2008-2009 学年《微积分A》第二学期期末考试 参考答案及评分标准

2009年6月26日

一、填空(每小题 4分, 共 28分)

1.
$$\frac{x-3}{1} = \frac{y-2}{\sqrt{2}} = \frac{z+1}{-1}$$

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 2. $12x-4y+3z-12=0$; $\frac{12}{13}$;

3.
$$gradu = \{x^{y-1}yz, x^{y}z \ln x, x^{y}\};$$

$$div(gradu) = y(y-1)x^{y-2}z + x^{y}z\ln^{2}x;$$

4.
$$2\pi$$
;

5.
$$\pi R^3$$
:

6.
$$I = \int_0^{\frac{\pi}{2}} d\theta \int_0^{2a\cos\theta} f(\rho\cos\theta, \rho\sin\theta) \rho d\rho$$

7.
$$p > \frac{1}{2}$$
; $-\frac{1}{2} .$

$$= \frac{\partial z}{\partial x} = 3x^2 - 3y = 0$$

$$\frac{\partial z}{\partial y} = 3y^2 - 3x = 0$$
 得驻点为 (0,0),(1,1) 2 分

在点(0,0)处:
$$A = \frac{\partial^2 z}{\partial x^2} = 0$$
, $B = \frac{\partial^2 z}{\partial x \partial y} = -3$, $C = \frac{\partial^2 z}{\partial y^2} = 0$

$$B^2 - AC = 9 > 0$$
,所以(0,0)点不是极值点.6分

在点 (1,1) 处:
$$A = \frac{\partial^2 z}{\partial x^2} = 6$$
, $B = \frac{\partial^2 z}{\partial x \partial y} = -3$, $C = \frac{\partial^2 z}{\partial y^2} = 6$

$$=2\pi a^4(3\pi-4)$$
 8 \hat{A}

(也可求出原函数后用牛顿-莱布尼茨公式或选择其他积分路径)

$$£. f(x) = \frac{1}{x(x-2)} = \frac{1}{2} \left(\frac{1}{x-2} - \frac{1}{x} \right) \dots 1 \cancel{3}$$

$$= \frac{1}{2} \left[\frac{1}{1+(x-3)} - \frac{1}{3} \cdot \frac{1}{1+\frac{x-3}{3}} \right] \dots 3 \cancel{3}$$

$$=\frac{1}{2}\left[\sum_{n=0}^{\infty}(-1)^{n}(x-3)^{n}-\sum_{n=0}^{\infty}(-1)^{n}\frac{(x-3)^{n}}{3^{n+1}}\right]$$
 5 \$\frac{\pi}{2}\$

$$=\frac{1}{2}\sum_{n=0}^{\infty}(-1)^n(1-\frac{1}{3^{n+1}})(x-3)^n$$
 6 \$\frac{\phi}{2}\$

收敛域为: 2<x<4. 8分

$$= -\frac{1}{R^2} \int_0^{2\pi} d\theta \int_{\frac{\pi}{2}}^{\pi} d\phi \int_0^R r^4 \sin\phi \, dr + \pi \quad (\text{ b} \text{ b} \text{ d} \text{ d} \text{ d} \text{ d}) \dots 8 \text{ } \hat{\textbf{ d}}$$

$$= -\frac{2\pi}{5}R^3 + \pi.$$
 10 $\%$

七、 $\lim_{n\to\infty} \left| \frac{a_{n+1}}{a_n} \right| = 1$,所以收敛半径R = 1. 又当 $x = \pm 1$ 时,级数发散,

所以幂级数的收敛域为: D=(-1,1). 3分

1+x

八、将f(x)进行偶延拓,由狄立克莱收敛定理知:

$$S(x) = \begin{cases} \pi + x & x \in (0, \pi] \\ \pi - x & x \in [-\pi, 0] \end{cases}$$
 2 \Re

由和函数的周期性,当 $x \in [\pi, 2\pi]$ 时, $x - 2\pi \in [-\pi, 0]$

$$S(x) = S(x - 2\pi) = 3\pi - x$$
 3 \Re

$$\mathcal{R} - 5 + 2\pi \in (0, \pi), \quad \therefore \quad S(-5) = S(-5 + 2\pi) = 3\pi - 5. \quad \dots \quad 5 \, \hat{\mathcal{S}}$$

$$b_n = 0, \qquad n = 1, 2, \cdots$$

$$a_0 = \frac{2}{\pi} \int_0^{\pi} f(x) dx = \frac{2}{\pi} \int_0^{\pi} (\pi + x) dx = 3\pi, \qquad 6 \, \Re$$

$$a_n = \frac{2}{\pi} \int_0^{\pi} f(x) \cos nx dx = \frac{2}{\pi} \int_0^{\pi} (\pi + x) \cos nx dx$$

$$= \frac{2}{\pi n^2} [(-1)^n - 1] = \begin{cases} 0 & n = 2k, k = 1, 2, \dots \\ -\frac{4}{n^2 \pi} & n = 2k - 1, k = 1, 2, \dots \end{cases}$$
 8 \$\frac{\partial}{\partial}\$

九、由球坐标与直角坐标的关系,有

$$x = r \sin \varphi \cos \theta$$
, $y = r \sin \varphi \sin \theta$, $z = r \cos \varphi$ 2 \Re

(1)
$$u = f(x, y, z) = f(r \sin \varphi \cos \theta, r \sin \varphi \sin \theta, r \cos \varphi)$$
...... 3 \Re

$$(2) \Leftrightarrow \frac{f'_x}{x} = \frac{f'_y}{y} = \frac{f'_z}{z} = t, \implies f'_x = tx, \quad f'_y = ty, \quad f'_z = tz.$$

$$\frac{\partial u}{\partial \theta} = f_x' \cdot x_\theta' + f_y' \cdot y_\theta' + f_z' \cdot z_\theta'$$

$$= f'_x \cdot r \sin \varphi(-\sin \theta) + f'_y \cdot r \sin \varphi \cos \theta + f'_z \cdot 0 \dots 4$$

$$= tx \cdot r \sin \varphi(-\sin \theta) + ty \cdot r \sin \varphi \cos \theta$$

$$= tr^2 \sin^2 \varphi(-\sin \theta) \cos \theta + tr^2 \sin^2 \varphi \cos \theta \sin \theta$$

$$= 0 \qquad ... 5$$

$$\frac{\partial u}{\partial \varphi} = f'_x \cdot x'_{\varphi} + f'_y \cdot y'_{\varphi} + f'_z \cdot z'_{\varphi}$$

$$= f'_x \cdot r \cos \varphi \cos \theta + f'_y \cdot r \cos \varphi \sin \theta - f'_z \cdot r \sin \varphi \dots 6$$

$$= tx \cdot r \cos \varphi \cos \theta + ty \cdot r \cos \varphi \sin \theta - tz \cdot r \sin \varphi$$

$$= tr^2 \sin \varphi \cos \varphi \cos^2 \theta + tr^2 \sin \varphi \cos \varphi \sin^2 \theta - tr^2 \sin \varphi \cos \varphi$$

$$= tr^2 \sin \varphi \cos \varphi - tr^2 \sin \varphi \cos \varphi$$

$$= tr^2 \sin \varphi \cos \varphi - tr^2 \sin \varphi \cos \varphi$$

$$= 0 \qquad ... 7$$
由此知 u 与 φ , θ 无关, Q 与 r 有关, Pu Q A r 的函数.