CSS 422 Hardware and Computer Organization

# Sequential Circuit

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The slides are re-produced by the courtesy of Dr. Arnie Berger and Dr. Wooyoung Kim



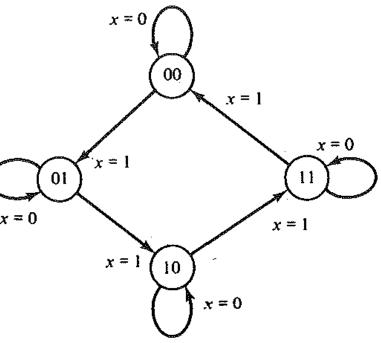
## **Topics**

- Sequential Circuit
  - Chapter 4, 5 by Berger
  - Chapter 3 by Null
  - Flip-Flop
  - Excitation table and K-maps
  - Design registers



### Example: 2-Binary Counter

- To design a 2-binary counter system with logic gates
- 2-binary counter system
  - Input: one control bit
  - Output: 2 bits that are stored in the system
  - If input is 0, then the 2 bits stay the x = 0 same
  - If input is 1, then the 2 bits are counted up and if they reach the maximum, then they are reset to 0



Can we make this with combinational logic gates?

What is missing in the combinational circuit to design this system?



## Combinational vs. Sequential

#### • **Combinational** circuit

- The current output state depends only on the input states
- It does not provide memory or state information, except ROM

#### Sequential circuits

- The current output depends on the current input and the past history of inputs/outputs
- The most common type of sequential circuit is the synchronous type
- Edge-triggered Flip-Flop: synchronous (clocked) sequential circuit
- Interconnection of flip-flops and gates



# Asynchronous vs. Synchronous

#### Asynchronous logic

The change in the state depends on the input variables

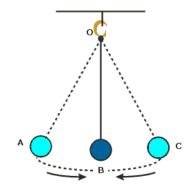
#### Synchronous logic

- With millions of logic gates, we need to synchronize the change of logic state with some master signal – clock
- Suppose we need to move data from memory to register to do arithmetic addition. How the computer will know the sequence of the work?
- We need a system that works according to the order of tasks as time goes → synchronous sequential circuit design



### Clocks and Time

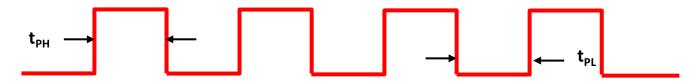
- The *clock* in a digital system is an electronic analog of the pendulum which synchronizes the circuits
  - Clock signal is the master control signal
  - Circuit output changes on the rising or falling edges of a clock pulse
- Frequencies are the inverse of time (speed)
  - Hz = the number of cycles per second: how to compute the time per each cycle?
  - -1 kilohertz (KHz) =  $10^3$  Hz (cycle per second)
  - -1 megahertz (MHz) =  $10^6$  Hz
  - 1 gigahertz (GHz) =  $10^9$  Hz
  - -1 terahertz (THz) =  $10^{12}$  Hz



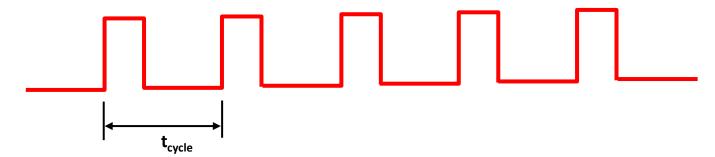


### Clocks and Pulses

Clocks are continuous streams of pulses



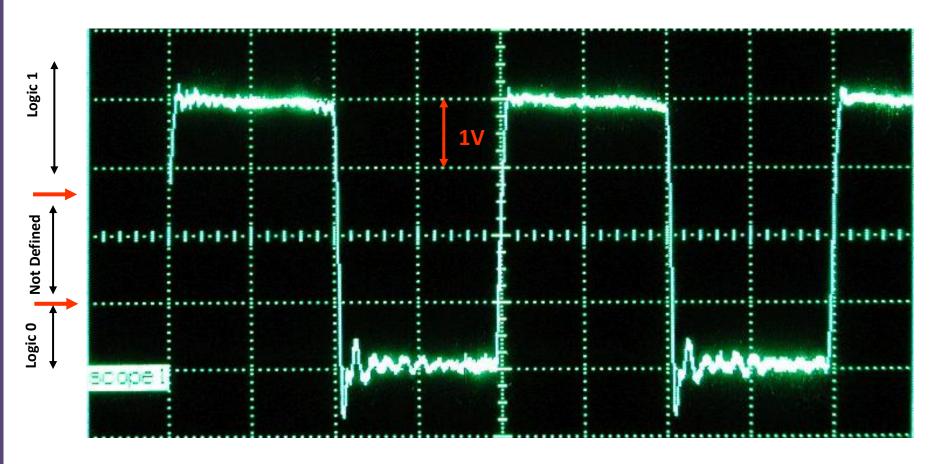
- Duty cycle =  $t_{PH} / (t_{PH} + t_{PL}) \times 100\%$ 
  - The clock signal shown above has a 50% duty cycle
  - The clock signal shown below has a 25% duty cycle
  - Period: The time to complete one clock cycle
    - Period = t<sub>cycle</sub>
  - Frequency: The inverse of the period, f = 1/period



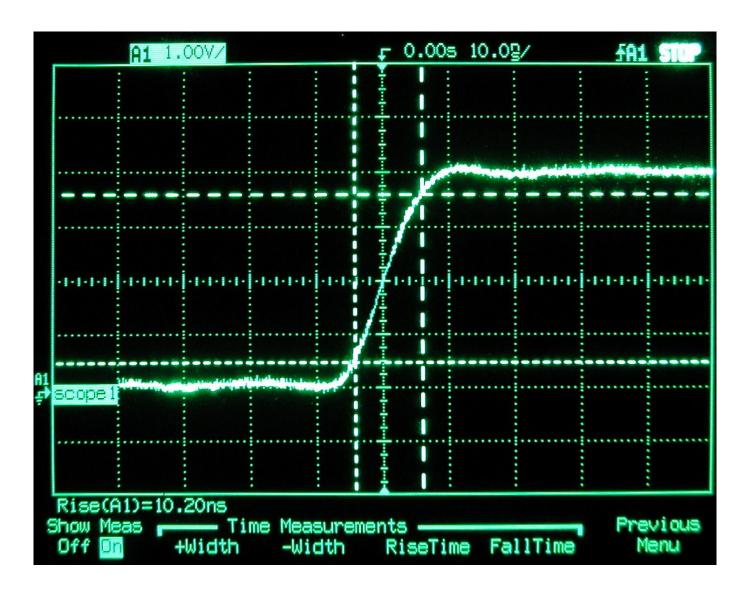


### A Real Clock

 Note that signal fidelity is not an issue. As long as the logic 1 is greater than 2.5 volts and logic 0 is less than 1 volt, the pulse will be properly interpreted



### Pulse Rise Time Measurement





## **Propagation Delay**

- Why can't we simply rev-up the clock on your PC to as higher as you want?
  - Answer: Gates require a finite amount of time to switch state when their inputs change
- Consider the inverter gate below

The propagation delay (time delay from input change to output

change) 類DO ょ 0.00s 10.0g/ FD1 SIU  $\Delta t = 12.60 \text{ns}$  $\Delta t = 12.60 ns$  $1/\Delta t = 79.37 MHz$ 



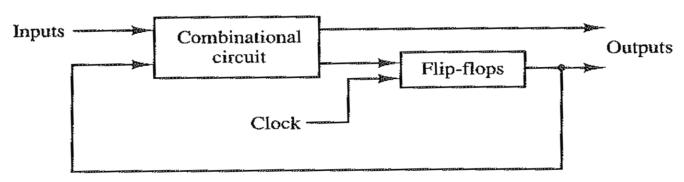
### Basic Units for Sequential Circuit

- Logic Gates: the building blocks of combinational circuit
- Flip-Flops: the building blocks of sequential circuit
  - Flip-flops are actually built with logical gates
- Before we study flip-flops, let's start with a latch
- Latch: Use the feedback functionality
  - Feedback: Bringing the output back to an input
  - Lock the gate pair into a new state
  - Transition is triggered by the application of the *input pulse*



### Sequential Circuit Design

 A sequential circuit can be a combination of combinational circuits and flipflops

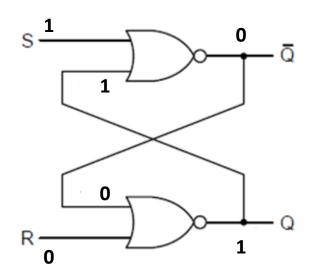


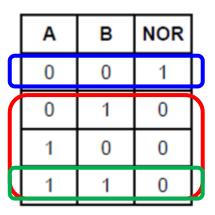
Block diagram of a sequential circuit

- Because the sequential circuit involves state transition, we have different types of tables for this circuit
- **State Table**: Based on the **input and current state**, give **the next state** information (similar to truth table)
- **Characteristic Table**: Give the state transition information based on inputs
- **Excitation Table**: Inputs are the current and next states, and outputs are input signals



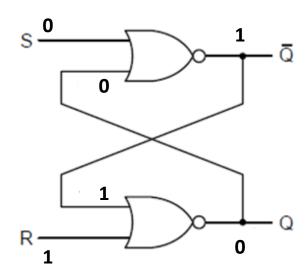
- A circuit that remembers previous input values states
- S-R Latch: two stable states Set and Reset
- Regardless of previous states,
  - When S = 1 and R = 0, Q becomes 1

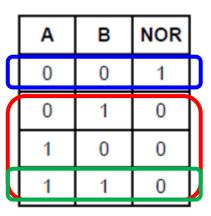






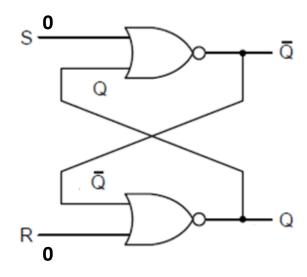
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- Regardless of previous states,
  - When S = 0 and R = 1, Q becomes 0







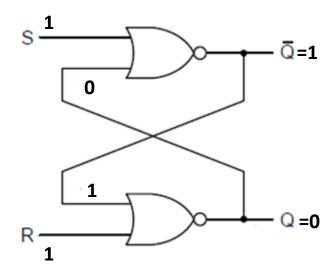
- A circuit that remembers previous input values states
- S-R Latch: two stable states Set and Reset
- Regardless of previous states,
  - When S = 0 and R = 0, the output will be "locked"



Α	В	NOR
0	0	1
0	1	0
1	0	0
1	1	0



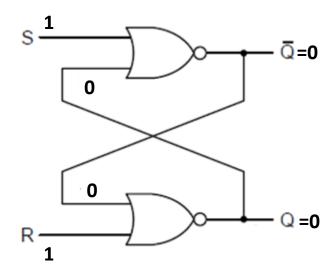
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- S-R Latch: two stable states Set and Reset
- Regardless of previous states,
  - What if S=1 and R=1, simultaneously?



Α	В	NOR	
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1	0	0	
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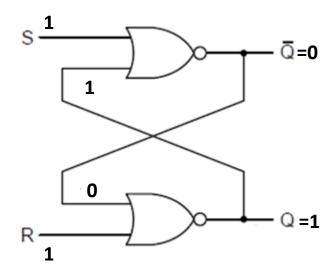
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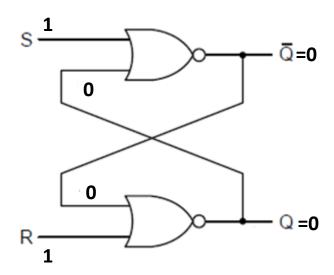
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- Regardless of previous states,
  - What if S=1 and R=1, simultaneously?



Α	В	NOR	
0	0	1	
0	1	0	
1	0	0	
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- A circuit that remembers previous input values states
- S-R Latch: two stable states Set and Reset
- Regardless of previous states,
  - What if S=1 and R=1, simultaneously?



Α	В	NOR	
0	0	1	
0	1	0	
1	0	0	
1	1	0	



- A circuit that remembers previous input values states
- S-R Latch: two stable states Set and Reset
- Regardless of previous states,
  - When S is 1 and R is 0, Q becomes 1
  - When S is 0 and R is 1, Q becomes 0
  - When S=R=0, the output will be "locked"
  - When S=R=1, the output will be in "race condition" (forbidden state)



# SR Latch

(a)	State	Table	e

Current Inputs SR	Current State Q <sub>n</sub>	Next State Q <sub>n+1</sub>
00	0	0
00	1	1
01	0	0
01	1	0
10	0	1
10	1	1
11	0	_
11	1	_

#### (b) Characteristic Table

S	R	$Q_{n+1}$
0	0	$Q_n$
0	1	0
1	0	1
1	1	_

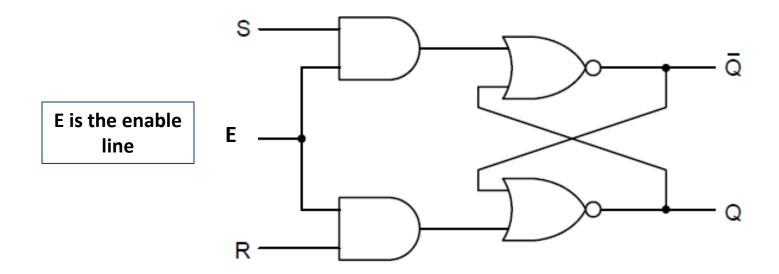
#### (c) Response to Series of Inputs

t	0	1	2	3	4	5	6	7	8	9
S	1	0	0	0	0	0	0	0	1	0
R	0	0	0	1	0	0	1	0	0	0
$Q_{n+1}$	1	1	1	0	0	0	0	0	1	1



### **Gated SR Latches**

- How to resolve the forbidden condition when S=R=1?
- Does this solve the forbidden condition problem?
  - When E is 0 (at logic low), the problem is solved



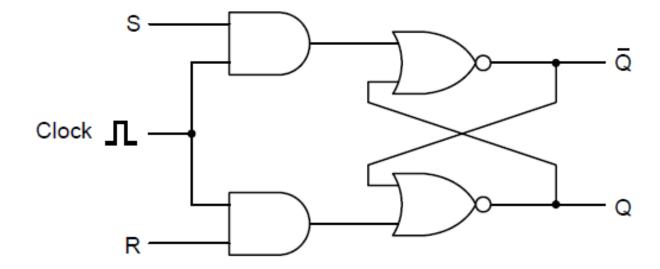


### Clocked SR Latches

- SR Latch is an asynchronous operation, yet
- Preventing the latch from changing state, except at

#### "certain specific time"

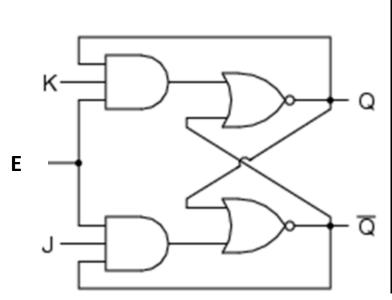
- Only when clock is up, the latch is sensitive to S or R
- How to resolve the forbidden condition when S=R=1?
  - When the clock is down, the problem is solved





### **Gated JK Latch**

- Avoid the SR latch's instability by preventing the inputs being 1 at the same time
  - "Toggle" does not cause the race condition, which is just OK but not perfect.
- In this case, all possible combinations of input values are valid

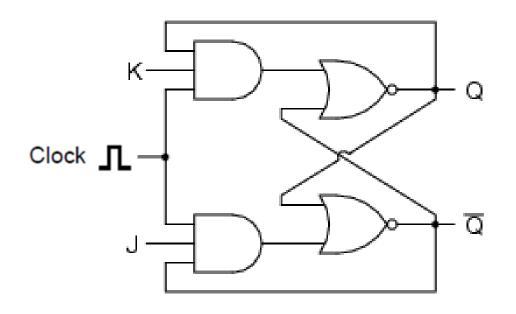


E	J	K	ď	Ισ
1	0	0	latch	latch
1	0	1	0	1
1	1	0	1	0
1	1	1	toggle	toggle
0	0	0	latch	latch
0	0	1	latch	latch
0	1	0	latch	latch
0	1	1	latch	latch



### **Clocked** JK Latch

- Avoid the SR latch's instability by preventing the inputs being 1 at the same time
- In this case, all possible combinations of input values are valid

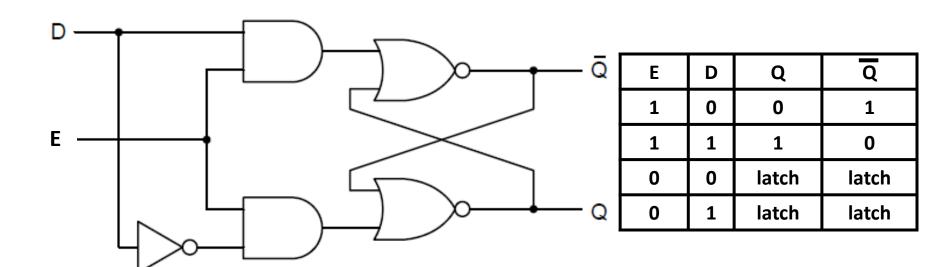


C	J	K	Q	Q
$\neg$	0	0	latch	latch
۲	0	1	0	1
7	1	0	1	0
$\vdash$	1	1	toggle	toggle
х	0	0	latch	latch
х	0	1	latch	latch
х	1	0	latch	latch
х	1	1	latch	latch



### **Gated** D Latches

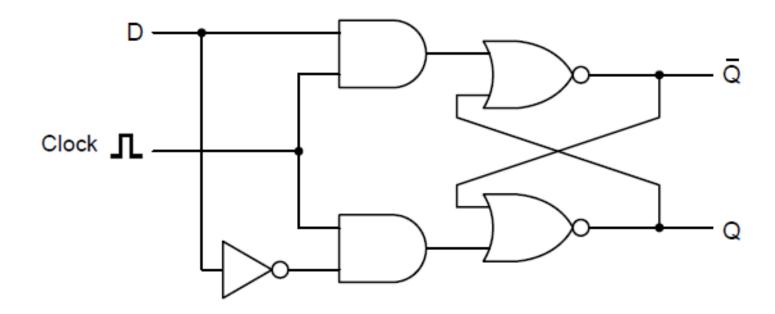
- Avoid the SR latch's instability by giving R as the inverse of S
- D: input the current data
- Q: output the stored value





### **Clocked** D Latches

- Avoid the SR latch's instability by giving R as the inverse of S
- D: input the current data
- Q: output the stored value
- To **load** the current value of D, just give a **positive pulse** on the clock line
- What if D changes while the clock stays in HIGH (active)?

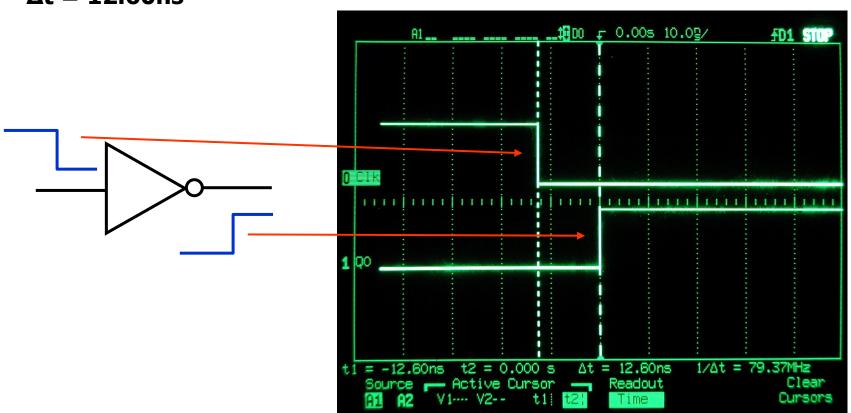




### **Propagation Delay**

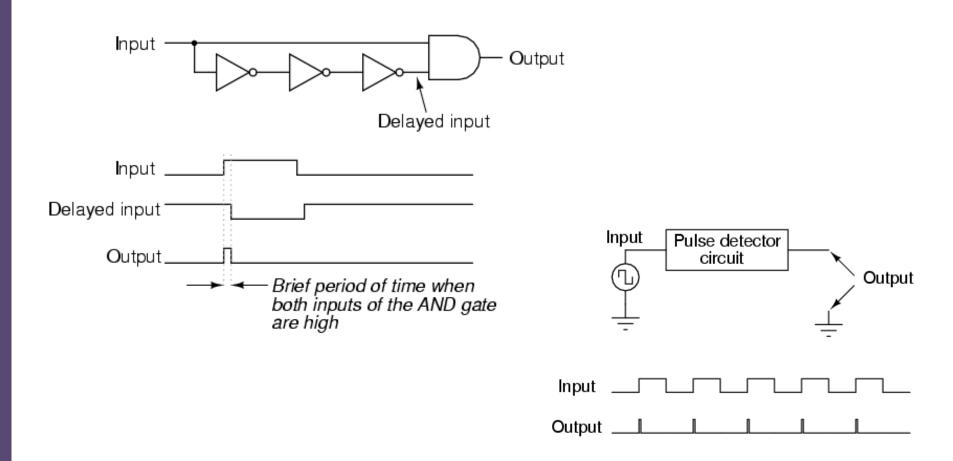
• The **propagation delay** (time delay from input change to output change)

$$\Delta t = 12.60 ns$$



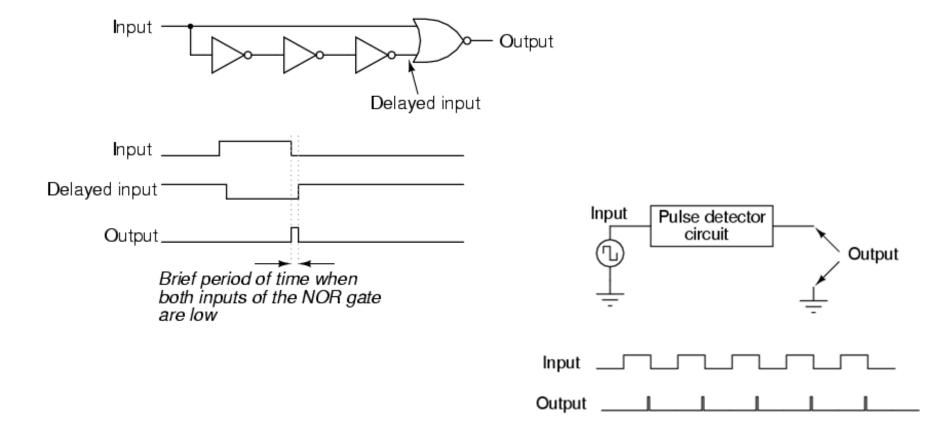


## Rising-Edge Pulse Detector





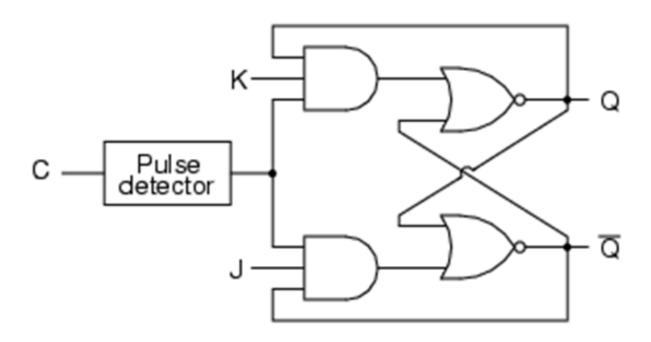
## Falling-Edge Pulse Detector





# J-K Flip-Flop

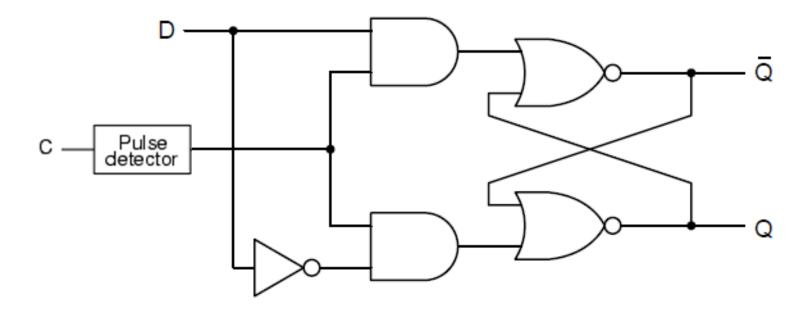
Only allow the output to change at a clock pulse





# D Flip-Flop

Only allow the output to change at a clock pulse





### Latches vs. Flip-Flops

- Latch lacks a mechanism to shift control to the clock edge
- The state changes when the clock is active

#### **Level-Triggered**

Flip-Flop: State transition occurs when the clock transitions
 from 0 to 1 (rising) or from 1 to 0 (falling)

#### **Edge Triggered**

- It's called a Flip-flop because output Q is flipped back and forth
- Sometimes Flip-Flops and latches are used as the same
- But in our class, we make the difference clear
- Without further specification, we use Rising Edge as a trigger in this class



### Characteristic Table for FF

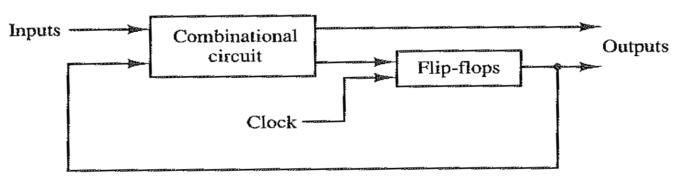
Name	Graphical Symbol	Characteristic Table
S-R	$S$ $Q$ $\rightarrow$ $Ck$ $R$ $\overline{Q}$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
J-K	J _ Q	$\begin{array}{c cccc} J & K & Q_{n+1} \\ \hline 0 & 0 & Q_n \\ 0 & 1 & 0 \\ 1 & 0 & \frac{1}{Q_n} \\ 1 & 1 & \overline{Q_n} \\ \end{array}$
D	D Q	$ \begin{array}{c cccc} D & Q_{n+1} \\ \hline 0 & 0 \\ 1 & 1 \end{array} $

**Basic Flip-Flops and the characteristic table** 



### Sequential Circuit Design

 A sequential circuit can be a combination of combinational circuits and flipflops



Block diagram of sequential circuit

- Because the sequential circuit involves state transition, we have different types of tables for this circuit
- **State Table**: Based on the input and current state, give the next state information (like truth table)
- **Characteristic Table**: Give the state transition information based on inputs
- Excitation Table: Inputs are the current and next states, and outputs are input signals (S, R, J, K) → why do we need this table?

# **Excitation Table for Flip-Flops**

SR flip-flop			•	D flip-flop			
Q(t)	Q(t+1)	s	R		Q(t)	Q(t+1)	D
0	0	0	×		0	0	0
0	1	1	0		0	1	1
1	0	0	1		1	0	0
1	1	×	0		1	1	1

JK mp-mop	JΚ	flip-flop
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Q(t)	Q(t+1)	J	K
0	0	0	×
0	1	1	×
1	0	×	1
1	1	×	0

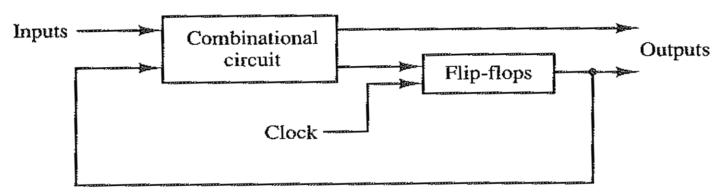
T flip-flop

Q(t)	Q(t+1)	T
0	0	0
0	1	1
1	0	1
1	1	0
		l



#### **Excitation Table**

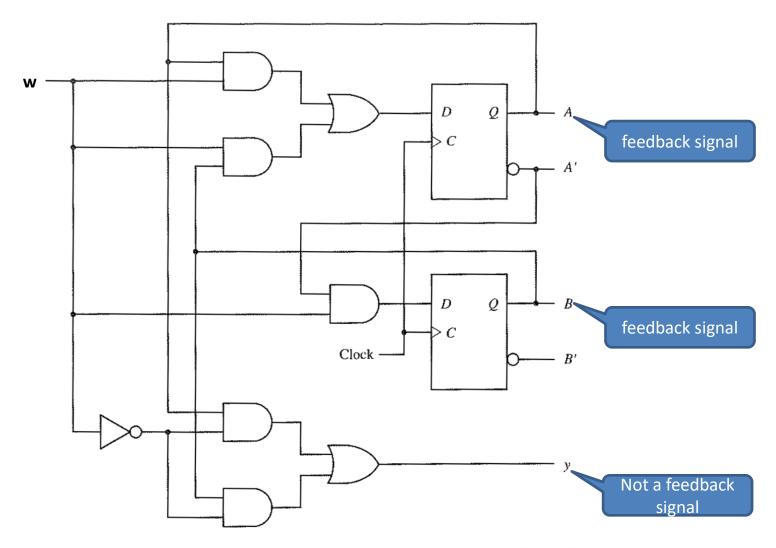
- Excitation table (inverted characteristic table)
  - Input: current state and next state
  - Output: S R or J K or D the control bit(s) of FF
- Necessity
  - FF is a feedback system
  - The transition information goes back to the states for inputs (S, R, etc.)
  - If you know the excitation table, you know how the sequential circuit can be built



Block diagram of a generic sequential circuit



## Example of a Sequential Circuit



What does this circuit do?



# Draw a state table to analyze a sequential circuit

How to draw a state table?



#### State Table

From the sequential circuit, can we build a state table?

A(t)	B(t)	(input) w	(output) Y	A(t+1)	B(t+1)
0	0	0	0	0	0
0	0	1	0	0	1
0	1	0	1	0	0
0	1	1	0	1	1
1	0	0	1	0	0
1	0	1	0	1	0
1	1	0	1	0	0
1	1	1	0	1	0



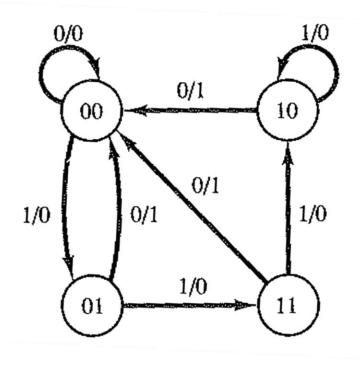
# How to draw a state machine from a state table?



# State Machine/Diagram

From the state table, can we build a state machine?

A(t)	B(t)	(input) w	(output) Y	A(t+1)	B(t+1)
0	0	0	0	0	0
0	0	1	0	0	1
0	1	0	1	0	0
0	1	1	0	1	1
1	0	0	1	0	0
1	0	1	0	1	0
1	1	0	1	0	0
1	1	1	0	1	0





# How to design a sequential circuit?



### Design a Sequential Circuit

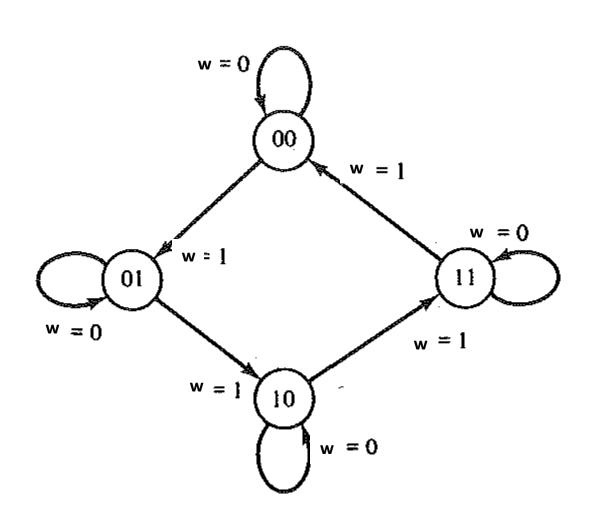
- Design a sequential circuit
- 1. Draw a **State Machine** (state diagram)
- 2. Figure out the *Inputs* and *Outputs*
- 3. Build a **State Table** and derive an **Excitation Table**
- 4. Derive a **Boolean Equation** using **K-map**
- 5. Build the **sequential circuit**

Let's design a 2-bit binary counter

 A sequence of repeated binary states 00, 01, 10, 11 whenever the input is 1.



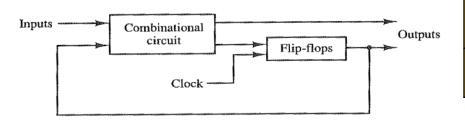
#### 2-bit Binary Counter – State Machine





### 2-bit Binary Counter – Input/Output

- Input (control signal): w
- Output (# of FF): 2 (2 bits)
- Suppose we are using JK FFs
- Then we need two J's and two K's
- In the state machine, you can build a state table
- The next states are connected to JK's
- We need an extended table → excitation table

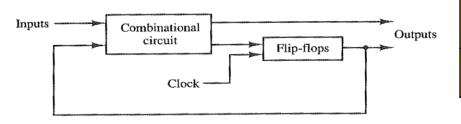


Present state (t)		Input	Next sta	nte (t+1)
А	В	W	Α	В
0	0	0		
0	0	1		
0	1	0		
0	1	1		
1	0	0		
1	0	1		
1	1	0		
1	1	1		



#### 2-bit Binary Counter – State Table

- Input (control signal): w
- Output (# of FF): 2 (2 bits)
- Suppose we are using JK FFs
- Then we need two J's and two K's
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Present state (t)		Input	Next sta	ite (t+1)
А	В	W	Α	В
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	0
1	0	0	1	0
1	0	1	1	1
1	1	0	1	1
1	1	1	0	0



#### 2-bit Binary Counter – Excitation Table 1

Q(t)	Q(t+1)	J	К
0	0	0	Χ
0	1	1	X
1	0	X	1
1	1	X	0

#### **Reference:**

JK FF's excitation Table

Presen (t		Input	Next (t+		Fl	lip-floր	o input	ts
Α	В	W	Α	В	J <sub>A</sub>	$K_A$	J <sub>B</sub>	K <sub>B</sub>
0	0	0	0	0				
0	0	1	0	1				
0	1	0	0	1				
0	1	1	1	0				
1	0	0	1	0				
1	0	1	1	1				
1	1	0	1	1				
1	1	1	0	0				

Extended table based on the state table



#### 2-bit Binary Counter – Excitation Table 2

Q(t)	Q(t+1)	J	K
0	0	0	X
0	1	1	X
1	0	X	1
1	1	X	0

**Reference:** 

JK FF's excitation Table

Presen	t state t)	Input	Next (t+		Fl	lip-flo <sub>l</sub>	o input	ts
А	В	W	А	В	J <sub>A</sub>	K <sub>A</sub>	J <sub>B</sub>	K <sub>B</sub>
0	0	0	0	0	0	X	0	X
0	0	1	0	1	0	X	1	X
0	1	0	0	1	0	X	X	0
0	1	1	1	0	1	X	X	1
1	0	0	1	0	X	0	0	X
1	0	1	1	1	X	0	1	X
1	1	0	1	1	X	0	X	0
1	1	1	0	0	X	1	X	1

**Excitation table with J and K inputs** 



#### 2-bit Binary Counter – Excitation Table 3

Q(t)	Q(t+1)	J	K
0	0	0	Χ
0	1	1	Χ
1	0	X	1
1	1	Χ	0

#### **Reference:**

JK FF's excitation Table

You cannot control the next state: So, not an input nor an output

Presen (1	t state	Input			Fl	lip-floլ	o input	ts
Α	В	W	А	В	J <sub>A</sub>	K <sub>A</sub>	J <sub>B</sub>	K <sub>B</sub>
0	0	0	0	0	0	X	0	X
0	0	1	0	1	0	X	1	X
0	1	0	0	1	0	X	X	0
0	1	1	1	0	1	X	X	1
1	0	0	1	0	X	0	0	X
1	0	1	1	1	X	0	1	X
1	1	0	1	1	X	0	X	0
1	1	1	0	0	Х	1	X	1

Excitation table with the "Next state" been removed



#### 2-bit Binary Counter – Boolean Equation



$$J_A = Bw$$

	~B~w	~Bw	Bw	B~w
~A	X	X	Х	X
Α			1	

$$K_A = Bw$$

	~B~w	~Bw	Bw	B~w
~A		1	Х	Х
Α		1	Х	Х
			•	•

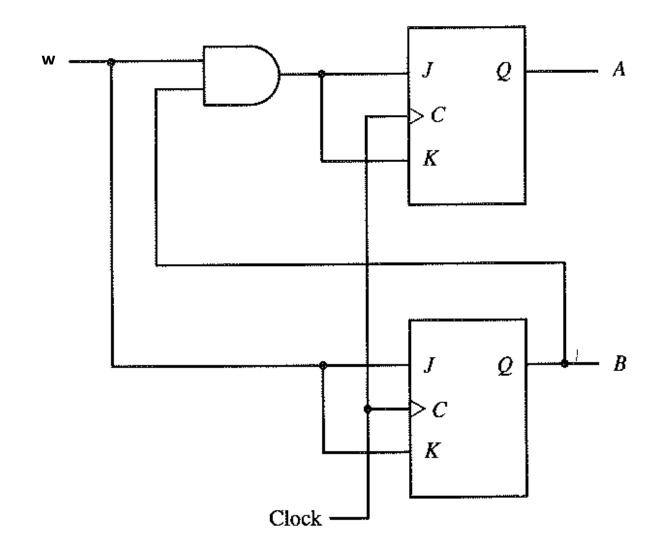
$$J_B = w$$

	~B~x	~Bw	Bw	B~w
<b>~</b> A	X	Х	1	
Α	X	Х	1	

$$K_B = w$$

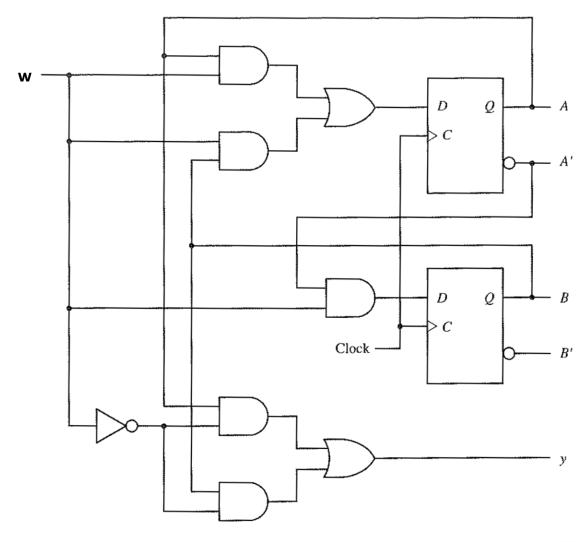


### 2-bit Binary Counter – Sequential Circuit





# Example of a Sequential Circuit



What does this circuit do?



# Draw a state table to analyze a sequential circuit

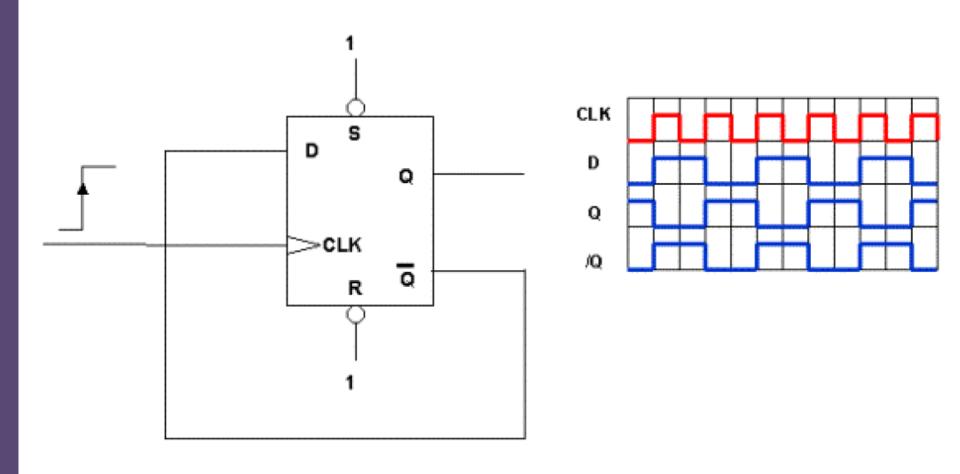
A(t)	B(t)	(input) w	(output) Y	A(t+1)	B(t+1)
0	0	0	0	0	0
0	0	1	0	0	1
0	1	0	1	0	0
0	1	1	0	1	1
1	0	0	1	0	0
1	0	1	0	1	0
1	1	0	1	0	0
1	1	1	0	1	0



# Examples of complicated sequential circuits



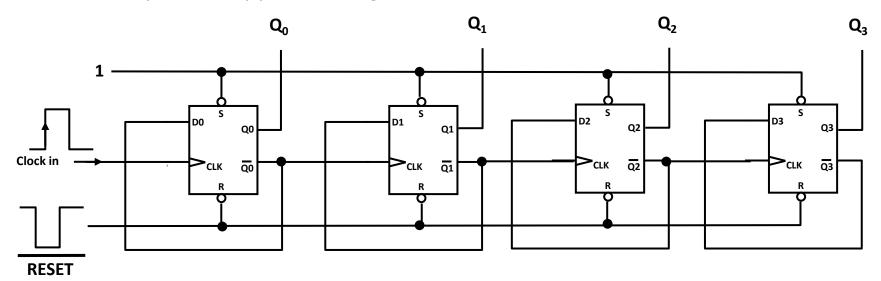
# D flip-flop connected in a divide-by-two configuration





#### The "D" FF as a Counting Element

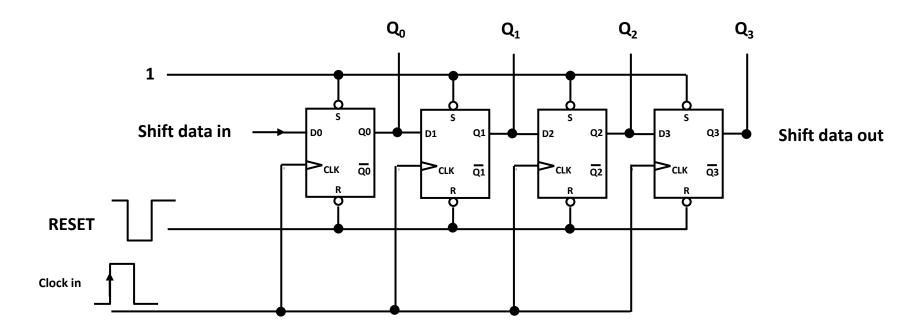
- A 4-bit binary *ripple counter* 
  - the pulses "ripple" through the circuit



- Each "D" FF divides the incoming clock frequency by 2
- RESET sets all Q output to 0 without a clock signal (asynchronous)
- Counts as fast as the first stage can toggle, but cannot be read until the count has rippled through to the last stage
- Can build counter/dividers of any length, any binary divisor
  - Clock frequency at output Q3 equals fclockin ÷ 16



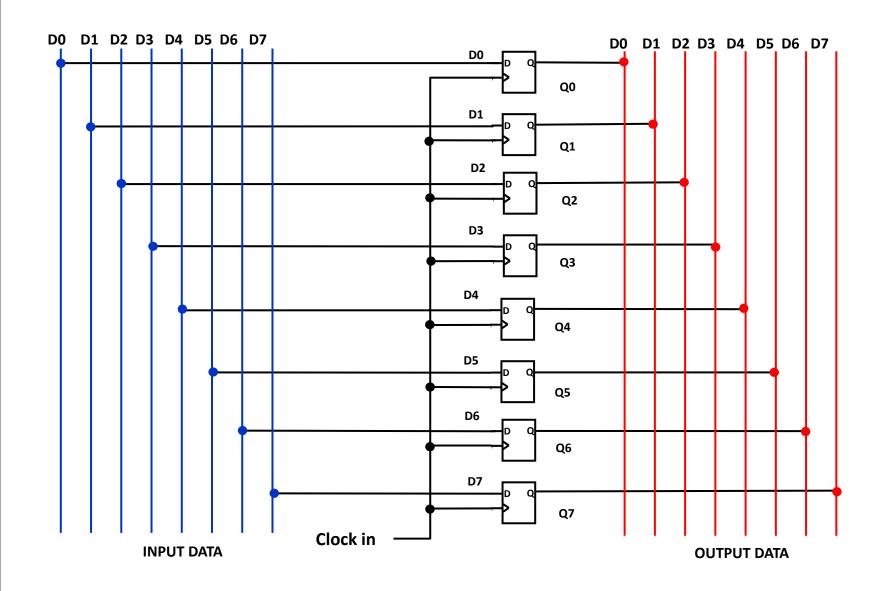
## "D" FF as a Shift Register



- Shift register moves data through successive stages on each clock pulse
- Used for serial data communications, multiplication, image processing
- Basis for UART (Universal Asynchronous Receiver/Transmitter)
- Data can be read in serial and then read out in parallel
- Serial data communications limit the number of signal wires needed to transmit byte-wide

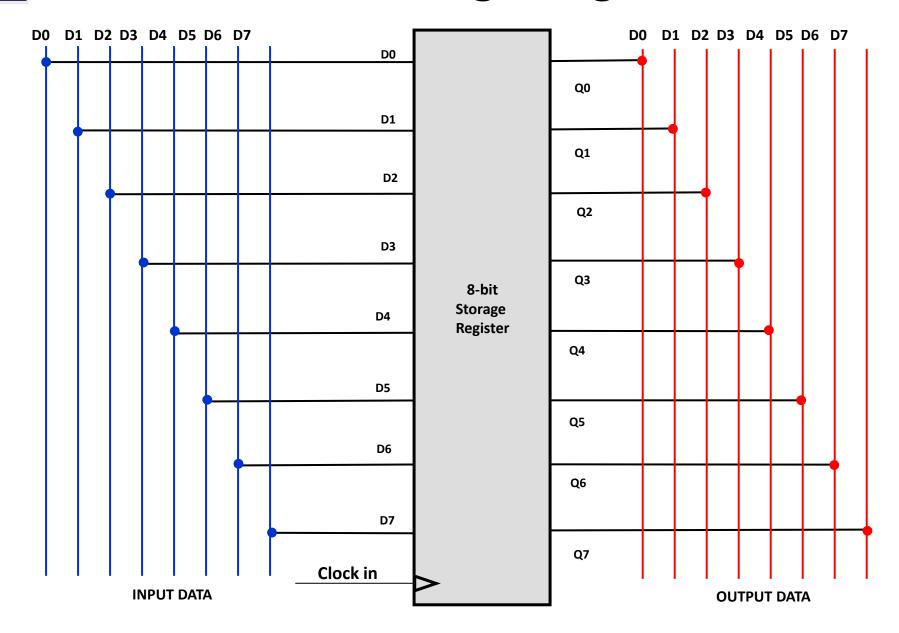


# "D" Flip-Flop as a Storage Register



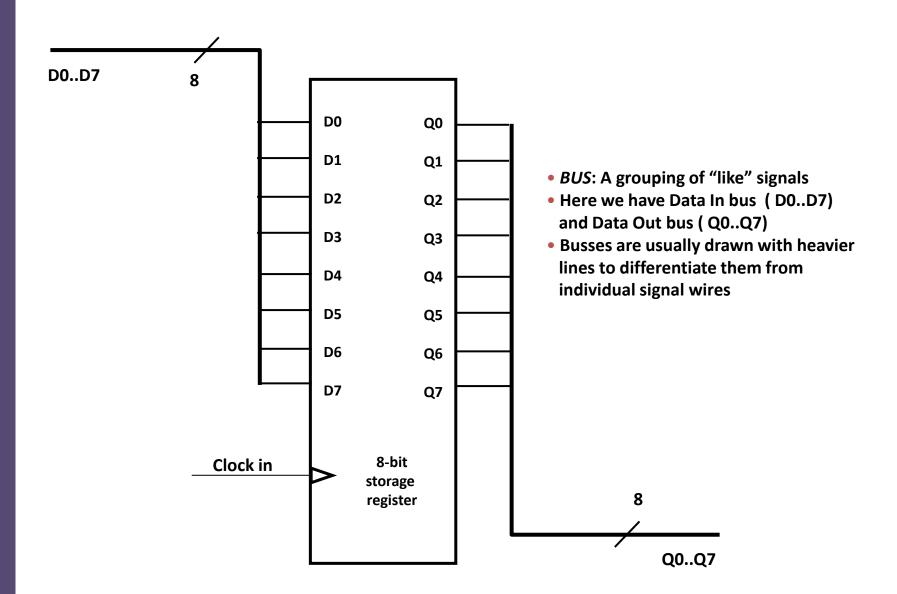


# An 8-bit Storage Register





#### The Storage Register with Busses



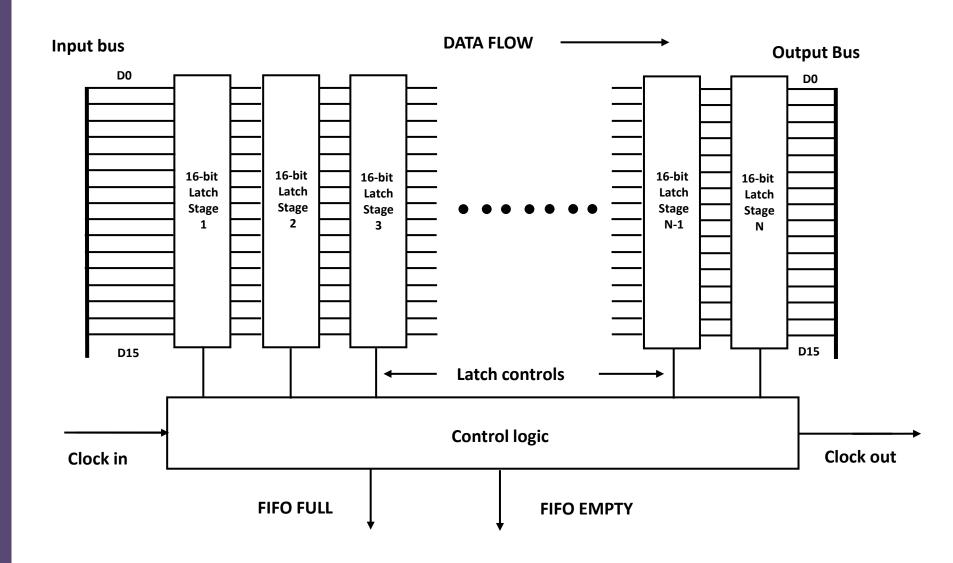


### More on Storage Registers

- The storage register provides a stable location to store data moving along buses
  - Data on buses are transitory
  - The width of a storage register typically matches the width of the data path
    - May be 4, 8, 16, 32, 64 or 128 bits wide
  - Registers interface data between a computer and the outside world
  - Registers are the key data holders in computers and microprocessors
    - A computer's architecture is often defined by organization of the storage registers
- Two variety of storage registers: "D" type and Latch



### First In First Out (FIFO) Data Storage





### Summary

- Gate is a fundamental building block of all digital systems
- Flip-flop is a basic unit for sequential circuit, which are built using gates and a clock
- Design a sequential circuit system
  - Draw a state diagram
  - Draw a state table
  - Build K-maps to derive Boolean equations
  - Draw a circuit diagram based on the equations