



Control Co-design: Achieving New Functionality and Performance via Integrated Physical and Control System Design

IDETC2020-19184

👤 Daniel R. Herber¹ 👤 James T. Allison²

¹  Colorado State University
Department of Systems Engineering
✉ daniel.herber@colostate.edu

²  University of Illinois at Urbana-Champaign
Department of Industrial and Enterprise Systems Engineering
✉ jtalliso@illinois.edu



①

What is Control Co-design?

→ What is Control Co-Design (CCD)?

- **Class of integrated engineering system design methods** that:
 - Consider the explicit relationship between **physical** and **control system** design decisions
 - Answer the question:
“How should the physical aspects of an actively controlled engineering system be designed such that passive and active properties interact synergistically for system-optimal performance?”
- Account explicitly for both **physics coupling** and **design coupling**
- Support discovery of **non-obvious** physical and control system design solutions that enable new levels of performance and functionality
- Subset of **Multidisciplinary Design Optimization** (MDO) methods where at least one discipline is control-system design¹

¹ Allison and Herber 2014

→ Design Optimization Across Two Disciplines

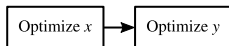
- Consider a general bi-discipline optimization problem with two sets of disciplinary design variables: x and y

$$\min_{x,y} f_x(x) + f_y(y) + f_{xy}(x,y)$$

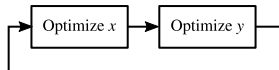
$$\text{subject to : } g_x(x) \leq 0, g_y(y) \leq 0 \\ g_{xy}(x,y) \leq 0$$

- System optimality requires **simultaneous optimization** of x and y
- Sequential design** does not produce system-optimal designs if cross terms exist¹ and is still largely used in practice
- Several formulations are mathematically equivalent* to simultaneous design²

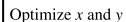
Sequential design



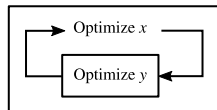
Iterated sequential design



Simultaneous design



Nested design

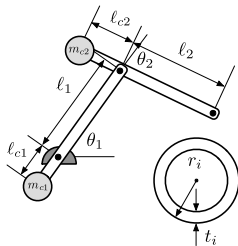


¹ Fathy et al. 2001; Allison, Guo, and Han 2014 ² Fathy et al. 2001

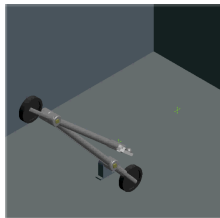
→ CCD Impact Examples

Robotic Manipulator Design

- **Passive dynamics** tailored to reduce control effort, complexity, and energy requirements for a pick-and-place task¹
- CCD can **exploit synergy** between passive dynamics and control system design



Sequential design result



(link lengths) (offsets) (masses)
 $\mathbf{x}_p = [1.0, 1.0, 0.3, 0.3, 10, 10]^T$
 $E(\mathbf{x}_p, \mathbf{x}_c) = 27.6 \text{ Joules}$

CCD design result



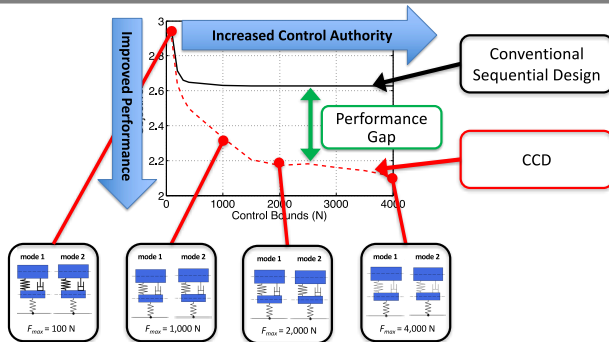
(link lengths) (offsets) (masses)
 $\mathbf{x}_p = [0.838, 0.711, 0.216, 0.885, 3.89, 20.7]^T$
 $E(\mathbf{x}_p, \mathbf{x}_c) = 5.86 \times 10^{-5} \text{ Joules}$

¹ Allison 2013

→ CCD Impact Examples (continued)

Active Vehicle Suspension using Direct Transcription

- Performance improvements with increasing control authority (but potential increases in cost)¹
- Large **performance gap** between sequential/simultaneous



¹ Allison, Guo, and Han 2014

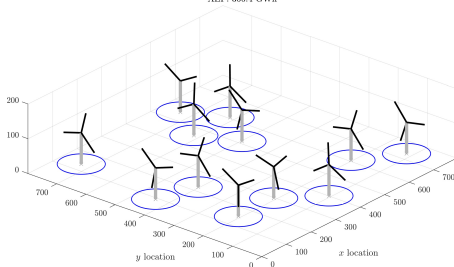
→ CCD Impact Examples (continued)

Combined Wind Turbine Layout and Hierarchical Control

- Layout and Control AEP increase of 17.7% over layout only¹

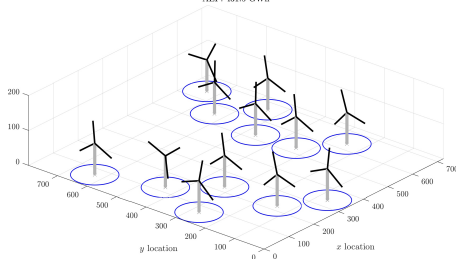
Layout only (AEP: 366.4 GWh)

AEP: 366.4 GWh



Layout only (AEP: 431.5 GWh)

AEP: 431.5 GWh



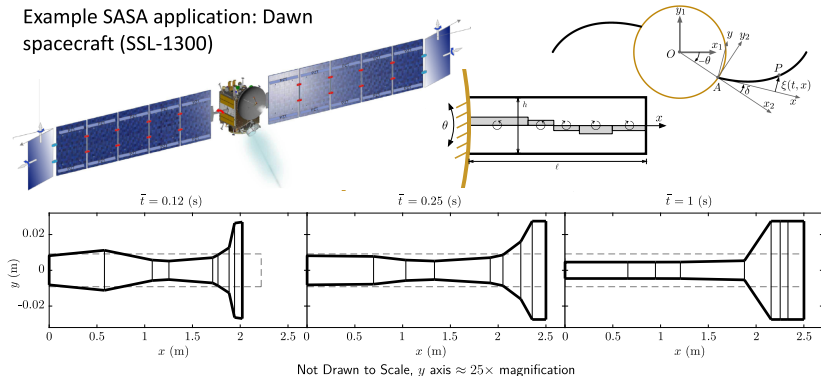
¹ Deshmukh and Allison 2017

→ CCD Impact Examples (continued)

Intelligent Structures for Spacecraft Attitude Control

- Tailored structural properties with distributed control¹
- Extracted **design rules** from CCD data²

Example SASA application: Dawn spacecraft (SSL-1300)



¹ Chilan et al. 2017; Vedant and Allison 2019 ² Herber and Allison 2017

②

Brief Overview of CCD Research

→ Historical CCD Development

Early Integrated Design Methods

- 1980's-1990's: Control Structure Interaction (CSI)¹
- 1980's-present: Multidisciplinary Design Optimization (MDO)²

Initial CCD Research

Breakthrough: Direct Optimal Control in CCD

CCD Method Maturation and Impact

¹ Crawley and Luis 1987; Manning 1991; Rao and Sunar 1994
Sobieski and Haftka 1997; Martins and Lambe 2013

² Sobieszczanski-

→ Historical CCD Development (continued)

Early Integrated Design Methods

Initial CCD Research

- Late 1990's/early 2000's: CCD theory and method development¹
- Primarily based on unidirectional design coupling, LQR/G
- Cannot account for plant design in a comprehensive manner² (e.g., state-dependent failure modes)

Breakthrough: Direct Optimal Control in CCD

CCD Method Maturation and Impact

¹ Fathy et al. 2001; Reyer et al. 2001
Han 2014; Herber and Allison 2018

² Allison and Herber 2014; Allison, Guo, and

→ Historical CCD Development (continued)

Early Integrated Design Methods

Initial CCD Research

Breakthrough: Direct Optimal Control in CCD

- 2011: First publication of CCD with direct transcription (DT) enabling comprehensive plant design while being generally efficient and scalable¹
- 2017: Revised CCD theory for bi-directional problems²

CCD Method Maturation and Impact

¹ Allison, Guo, and Han 2014 ² Herber and Allison 2018

→ Historical CCD Development (continued)

Early Integrated Design Methods

Initial CCD Research

Breakthrough: Direct Optimal Control in CCD

CCD Method Maturation and Impact

- Expanded applications, growing impact (key element of new research programs – NSF and ARPA-E)¹
- Labeled an engineering game changer²
- Still significant open questions³

¹ Slides 14 and 15 ² Garcia-Sanz 2019 ³ Slide 13

→ CCD State-of-the-Art

- Recent CCD methods account fully for **bi-directional** plant-control design coupling¹
- Requires **predictive models** that are appropriate for CCD studies² (different than models used for control design alone)
- Methods based on direct optimal control (direct transcription) are quite mature³
- Appropriate for **early-stage design** studies⁴ (what would the best possible passive dynamic properties be?)
- **General software tools** currently in development (supported by ARPA-E⁵)
- Many **open questions** exist for CCD, especially when supporting higher-TRL development efforts

¹ Allison, Guo, and Han 2014; Herber and Allison 2018

² Allison and Herber 2014

³ Herber 2017; Allison, Guo, and Han 2014; Chilan et al. 2017

⁴ Deshmukh, Herber,

and Allison 2015 ⁵ ARPA-E 2019a

③

CCD Open Questions and Impact

→ CCD Open Questions



- Deeper study and development of strategies to include **closed-loop control in CCD**¹, balancing design flexibility and implementability/stability/ robustness
- Account for **uncertainty** in the presence of design coupling² (some specific differences compared to existing RBDO or robust or stochastic control)
- Link with **physical experiments** (e.g., CCD method validation where HIL replaces simulation for part of the CCD optimization problem³)
- Extension to **large-scale systems**⁴ (distributed optimization)
- How do we maximize intellectual, practical, and societal **impacts** moving forward with CCD?

¹ Deshmukh, Herber, and Allison 2015; Nash and Jain 2020 ² Cui, Allison, and Wang 2020; Azad and Alexander-Ramos 2020 ³ Deodhar, Deese, and Vermillion 2017

⁴ Liu, Azarm, and Chopra 2020; Behtash and Alexander-Ramos 2020

→ CCD/Design Automation in New ARPA-E Programs

- DE-FOA-0002051: Aerodynamic Turbines, Lighter and Afloat, With Nautical Technologies and Integrated Servo-Control (ATLANTIS)¹
*“The program encourages the **application of control co-design (CCD)** methodologies . . . CCD methodologies enable designers to analyze . . . and propose solutions that **permit optimal FOWT designs not achievable otherwise.**”*
- DE-FOA-0002220: Flexible Carbon Capture and Storage (FLECCS)²
*“Applicants are thus encouraged to consider **advanced optimization techniques** that allow for a broader range of process configurations and **design and operational variables.** . . .”*
- DE-FOA-0002334: Submarine Hydrokinetic And Riverine Kilo-megawatt Systems (SHARKS)³
*“This Program is aimed at **applying Control Co-Design (CCD)**, Co-Design (CD) and Designing-for-OpEx (DFO) methodologies to HKT design.”*
- Takeaway: **Significant government resources committed, potential to realize substantial societal impact**

¹ ARPA-E 2019a ² ARPA-E 2019b ³ ARPA-E 2020

→ NSF Workshop on CCD

- Organized by James Allison (UIUC) and Chris Vermillion (North Carolina State University)
- Workshop on **Integrated Design of Active Dynamic Systems (IDADS)** supported by NSF (EDSE and DCSD programs)
- Focusing on bringing together a diverse set of viewpoints related to the topic of CCD
- **Online meeting was held March 26, 2020**
- In-person workshop will be held at a later date
- Workshop website: **<http://conferences.illinois.edu/idads2020>**



→ References



J. T. Allison and D. R. Herber (2014). “Multidisciplinary design optimization of dynamic engineering systems”. *AIAA Journal* 52.4. DOI: 10.2514/1.J052182



J. T. Allison (2013). “Plant-Limited Co-Design of an Energy-Efficient Counterbalanced Robotic Manipulator”. *Journal of Mechanical Design* 135.10. DOI: 10.1115/1.4024978



J. T. Allison, T. Guo, and Z. Han (2014). “Co-Design of an Active Suspension Using Simultaneous Dynamic Optimization”. *Journal of Mechanical Design* 136.8. DOI: 10.1115/1.4027335



ARPA-E (2019a). *DE-FOA-0002051: Aerodynamic Turbines, Lighter and Afloat, With Nautical Technologies and Integrated Servo-Control (AT-LANTIS)*. URL: <https://arpa-e-foa.energy.gov/FileContent.aspx?FileID=6621cfd3-8ac2-453d-b127-0725a3b5d8f1>



– (2019b). *DE-FOA-0002220: Flexible Carbon Capture and Storage (FLECCS)*. URL: <https://arpa-e-foa.energy.gov/FileContent.aspx?FileID=74dc63e5-16d7-4856-a043-36cc7b89e10a>

→ References (continued)



ARPA-E (2020). *DE-FOA-0002334: Submarine Hydrokinetic And Riverine Kilo-megawatt Systems (SHARKS)*. URL: <https://arpa-e-foa.energy.gov/FileContent.aspx?FileID=37c95808-b2ec-4e33-b000-2915bc8e2d13>



S. Azad and M. J. Alexander-Ramos (2020). “A Single-loop Reliability-based MDSDO Formulation for Combined Design and Control Optimization of Stochastic Dynamic Systems”. *Journal of Mechanical Design*. DOI: 10.1115/1.4047870



M. Behtash and M. J. Alexander-Ramos (2020). “A Decomposition-Based Optimization Algorithm for Combined Plant and Control Design of Inter-connected Dynamic Systems”. *Journal of Mechanical Design* 142.6. DOI: 10.1115/1.4046240



C. M. Chilan et al. (2017). “Co-Design of Strain-Actuated Solar Arrays for Spacecraft Precision Pointing and Jitter Reduction”. *AIAA Journal* 55.9. DOI: 10.2514/1.j055748



E. F. Crawley and J. de Luis (1987). “Use of piezoelectric actuators as elements of intelligent structures”. *AIAA Journal* 25.10. DOI: 10.2514/3.9792

→ References (continued)



T. Cui, J. T. Allison, and P. Wang (2020). “Reliability-based Co-Design of State-Constrained Stochastic Dynamical Systems”. *AIAA Scitech Forum*. DOI: 10.2514/6.2020-0413



N. Deodhar, J. Deese, and C. Vermillion (2017). “Experimentally Infused Plant and Controller Optimization Using Iterative Design of Experiments—Theoretical Framework and Airborne Wind Energy Case Study”. *Journal of Dynamic Systems, Measurement, and Control* 140.1. DOI: 10.1115/1.4037014



A. P. Deshmukh and J. T. Allison (2017). “Unrestricted Wind Farm Layout Design With Optimal Control Considerations”. *ASME International Design Engineering Technical Conferences*. DOI: 10.1115/detc2017-67480



A. P. Deshmukh, D. R. Herber, and J. T. Allison (2015). “Bridging the gap between open-loop and closed-loop control in co-design: A framework for complete optimal plant and control architecture design”. *2015 American Control Conference*. DOI: 10.1109/acc.2015.7172104



H. K. Fathy et al. (2001). “On the coupling between the plant and controller optimization problems”. *American Control Conference*. DOI: 10.1109/acc.2001.946008

→ References (continued)



M. Garcia-Sanz (2019). “Control Co-Design: An engineering game changer”. *Advanced Control for Applications: Engineering and Industrial Systems* 1.1. DOI: 10.1002/adcs.2.18



D. R. Herber (2017). “Advances in combined architecture, plant, and control design”. Ph.D. Dissertation. University of Illinois at Urbana-Champaign. URL: <http://hdl.handle.net/2142/99394>



D. R. Herber and J. T. Allison (2017). “Unified Scaling of Dynamic Optimization Design Formulations”. *ASME International Design Engineering Technical Conferences*. DOI: 10.1115/detc2017-67676



– (2018). “Nested and Simultaneous Solution Strategies for General Combined Plant and Control Design Problems”. *Journal of Mechanical Design* 141.1. DOI: 10.1115/1.4040705



T. Liu, S. Azarm, and N. Chopra (2020). “Decentralized Multisubsystem Co-Design Optimization Using Direct Collocation and Decomposition-Based Methods”. *Journal of Mechanical Design* 142.9. DOI: 10.1115/1.4046438



R. Manning (1991). “Optimum design of intelligent truss structures”. *Structures, Structural Dynamics, and Materials Conference*. DOI: 10.2514/6.1991-1158

→ References (continued)



J. R. R. A. Martins and A. B. Lambe (2013). “Multidisciplinary Design Optimization: A Survey of Architectures”. *AIAA Journal* 51.9. DOI: 10.2514/1.j051895



A. L. Nash and N. Jain (2020). “Hierarchical Control Co-design Using a Model Fidelity-Based Decomposition Framework”. *Journal of Mechanical Design*. DOI: 10.1115/1.4047691



S. S. Rao and M. Sunar (1994). “Piezoelectricity and Its Use in Disturbance Sensing and Control of Flexible Structures: A Survey”. *Applied Mechanics Reviews* 47.4. DOI: 10.1115/1.3111074



J. A. Reyer et al. (2001). “Comparison of Combined Embodiment Design and Control Optimization Strategies Using Optimality Conditions”. *ASME Design Engineering Technical Conference*. DETC2001/DAC-21119



J. Sobieszczanski-Sobieski and R. T. Haftka (1997). “Multidisciplinary aerospace design optimization: survey of recent developments”. *Structural Optimization* 14.1. DOI: 10.1007/bf01197554



Vedant and J. T. Allison (2019). “Multifunctional Structures for Attitude Control”. *ASME Smart Materials, Adaptive Structures and Intelligent Systems*. SMASIS2019-5565

Questions?

Control Co-design:
Achieving New Functionality and Performance via
Integrated Physical and Control System Design
IDETC2020-19184




 Daniel R. Herber

 Colorado State University

 daniel.herber@colostate.edu

 www.engr.colostate.edu/~drherber

 James T. Allison

 University of Illinois at Urbana-Champaign

 jtalliso@illinois.edu

 www.systemdesign.illinois.edu

