Recorded at time: 1757405581.2149608 new_map Broadcaster: default authority Average rate: $2\overline{0}.223$ Buffer length: 4.5 Most recent transform: 1757405581.065309 Oldest transform: 1757405576.565569 odom Broadcaster: default authority Average rate: $1\overline{0}.21$ Buffer length: 4.799 Most recent transform: 1757405579.620292 Oldest transform: 1757405574.821052 lidar_frame Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 livox_frame Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: default authority Average rate: $1\overline{0.206}$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $1\overline{0.206}$ Average rate: 10.206 Average rate: $1\overline{0.206}$ Buffer length: 4.899 Buffer length: 4.899 Buffer length: 4.899 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.899 Most recent transform: 1757405580.883498 Oldest transform: 1757405575.984459 Most recent transform: 1757405580.883498 Most recent transform: 1757405580.883498 Most recent transform: 1757405580.883498 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 1757405575.984459 Oldest transform: 1757405575.984459 Oldest transform: 1757405575.984459 Oldest transform: 0.0 Oldest transform: 0.0 fl_steering_wheel_link rl_steering_wheel_link fr_steering_wheel_link rr_steering_wheel_link base_footprint arm_base Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $1\overline{0.206}$ Average rate: $1\overline{0.206}$ Average rate: $1\overline{0.206}$ Average rate: $1\overline{0.206}$ Buffer length: 4.899
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Most recent transform: 1757405580.883498
Oldest transform: 1757405575.984459 link1 Broadcaster: default authority Average rate: 10.206 Buffer length: 4.899
Most recent transform: 1757405580.883498 Oldest transform: 1757405575.984459 link2 Broadcaster: default authority Average rate: $1\overline{0.206}$ Buffer length: 4.899 Most recent transform: 1757405580.883498 Oldest transform: 1757405575.984459 link3 Broadcaster: default authority Average rate: 10.206 Buffer length: 4.899 Most recent transform: 1757405580.883498 Oldest transform: 1757405575.984459 link4 Broadcaster: default authority Average rate: $1\overline{0.206}$ Buffer length: 4.899 Most recent transform: 1757405580.883498 Oldest transform: 1757405575.984459 link5 Broadcaster: default authority Average rate: 10.206 Buffer length: 4.899 Most recent transform: 1757405580.883498 Oldest transform: 1757405575.984459 link6 Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 link_eef Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera link Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 camera_accel_frame camera_gyro_frame camera_depth_frame camera_color_frame Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 camera_accel_optical_frame camera_gyro_optical_frame camera_depth_optical_frame camera_color_optical_frame

view frames Result