

Migrating to SDN for Mobile Core Networks : A Dynamic and Global Perspective

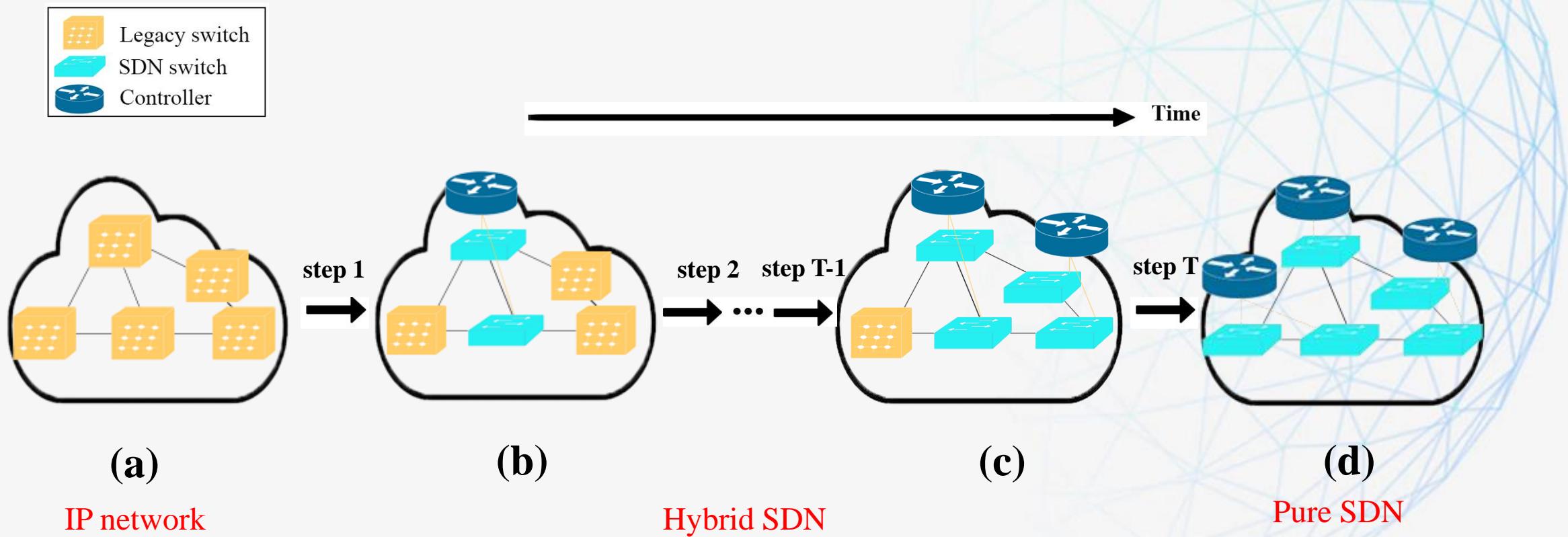
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Background

- Software-Defined Networking SDN
- Hybrid SDN

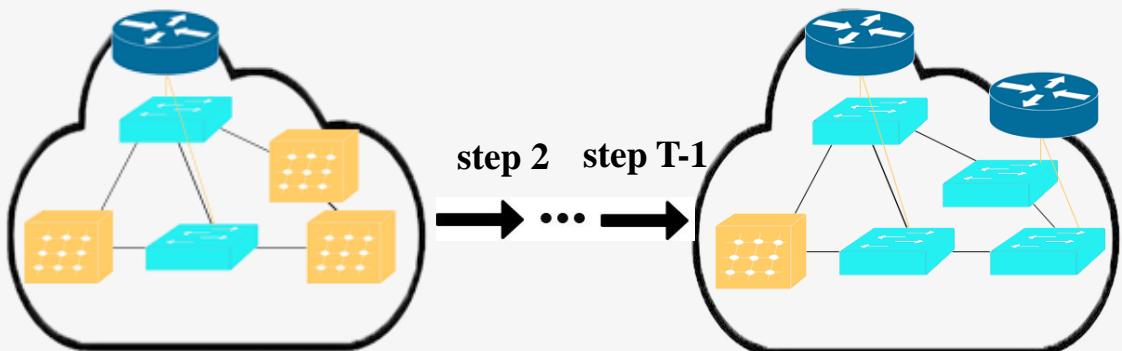


Migrating to SDN



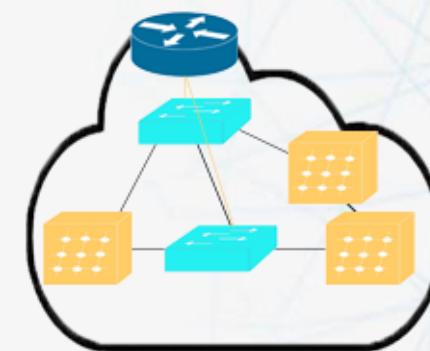
Dynamic

- Considering the entire migration trajectory as a whole
- Only considered switches upgrade



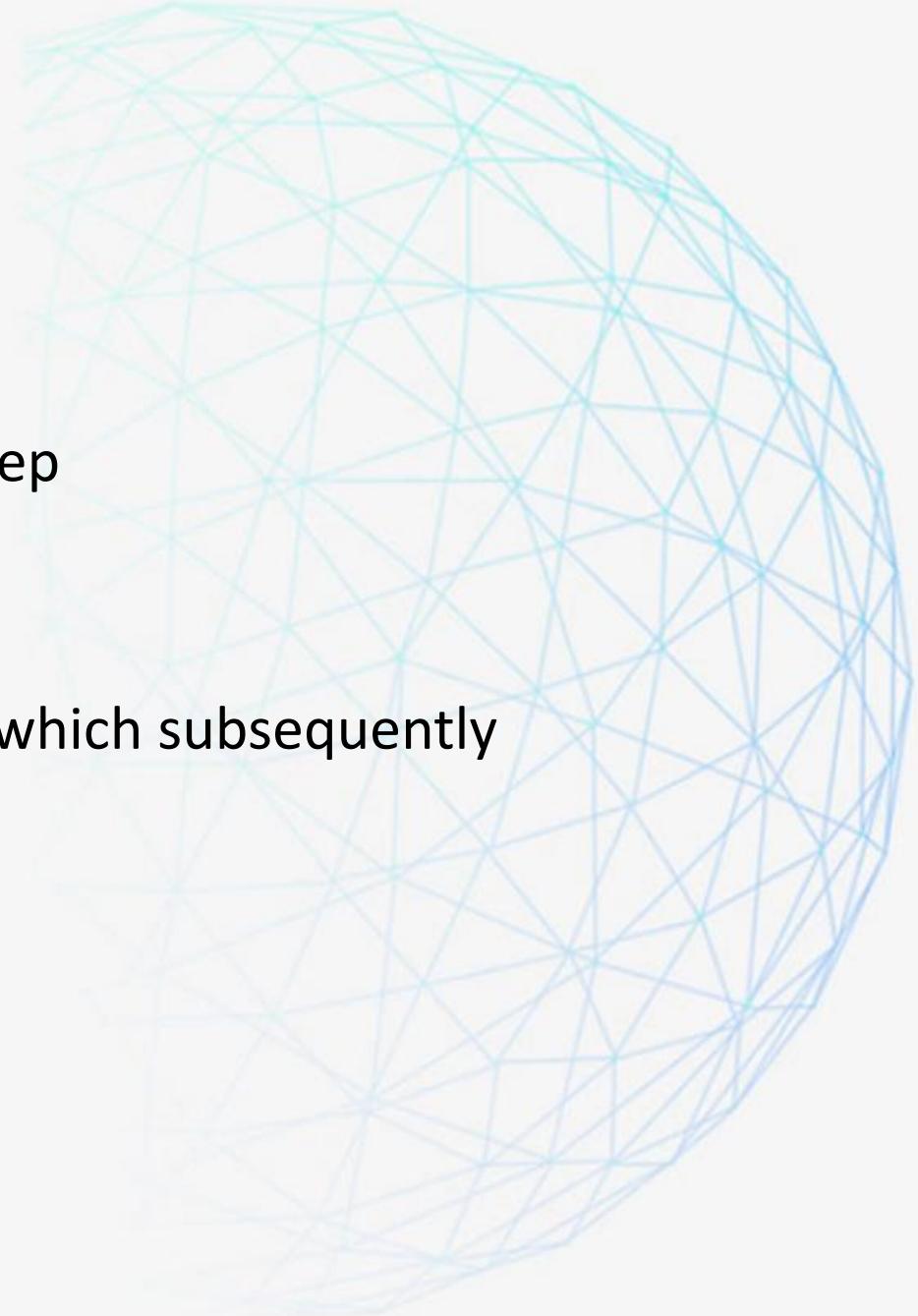
Static

- At a fixed point of time
- **Jointly deploy controllers and upgrade switches**



Problem

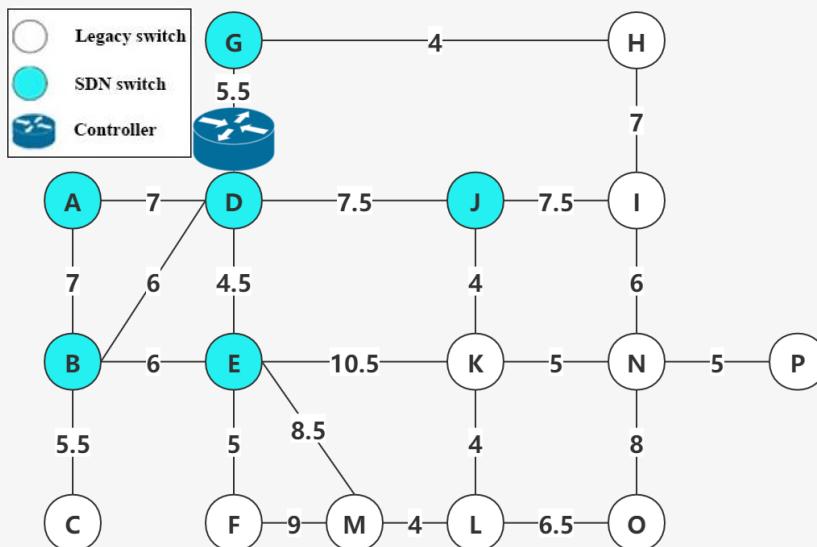
- **Which**
 - Which legacy devices should upgrade at each step
- **When**
 - Which legacy devices should upgrade first, and which subsequently
- **How**
 - Where to deploy controllers
 - Which controller controls which SDN switches



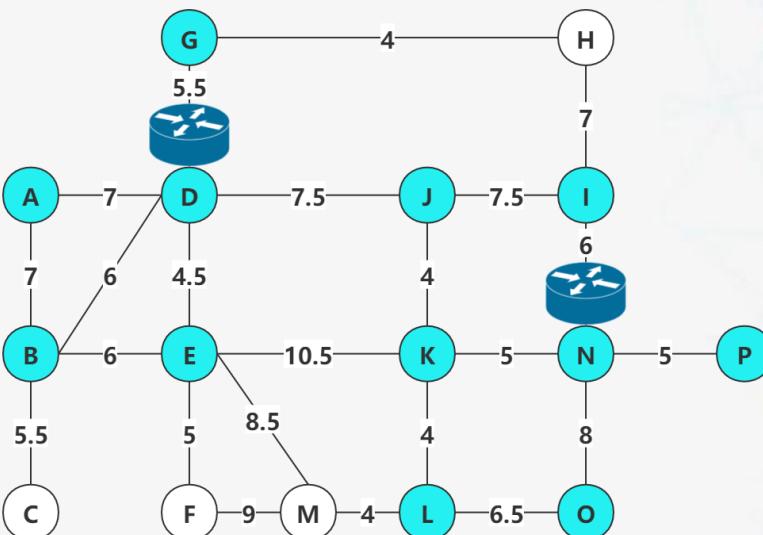
Motivation

Global controllers are on node B, I, L,
with the total delay of **83.5ms**.

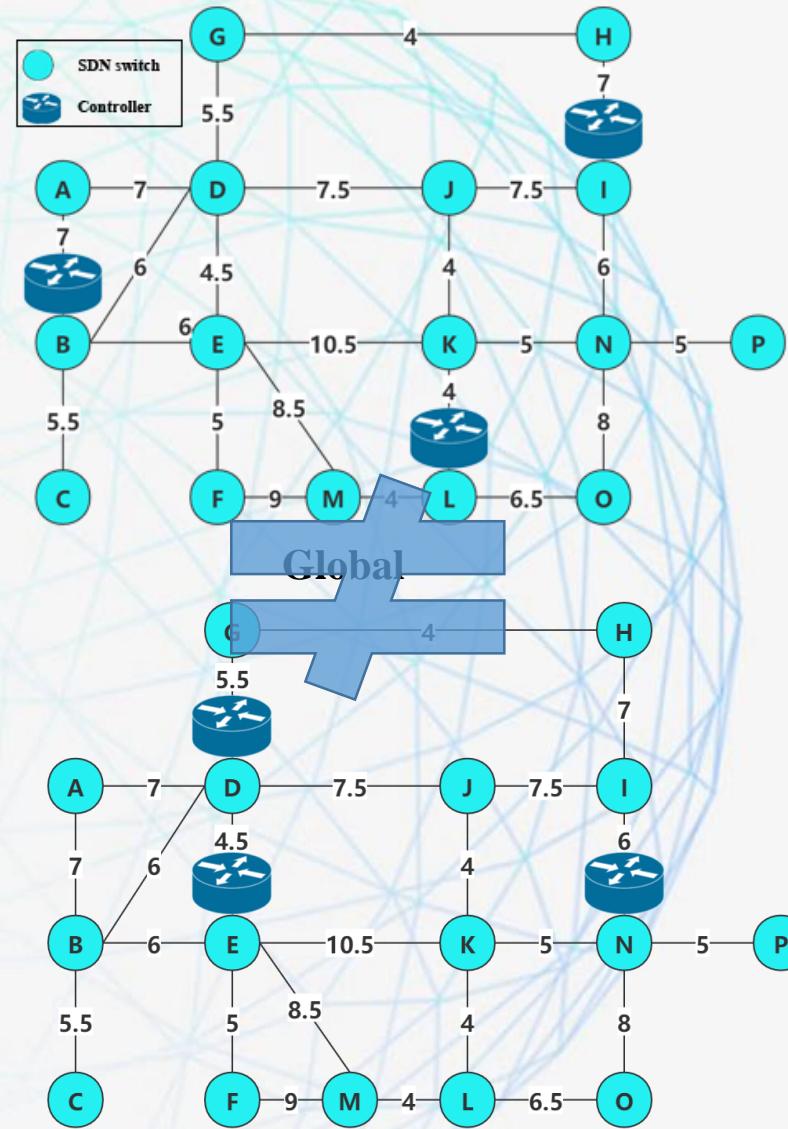
Migration controllers are on node D, E, N,
with the total delay of **93.5ms**.



step 1

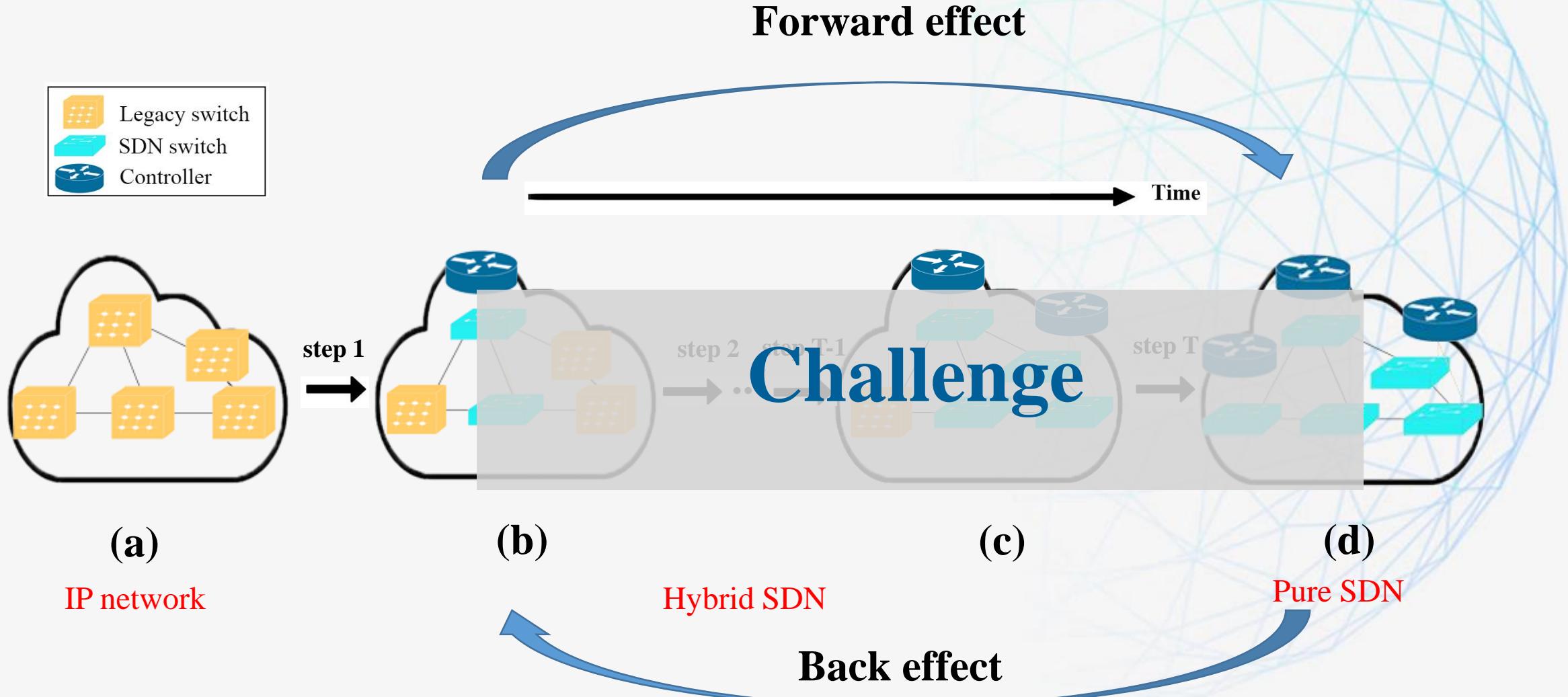


step 2
Local



step 3

Motivation



Model

$$\text{obj: } \max \sum_{i \in N} \beta^t * d_i * x_i^t \quad \text{Upgrade switches}$$

$$\min \sum_{i,j \in N} \omega_{ij} * z_{ij}^t \quad \text{Deploy controllers}$$

$$\text{s.t. } \sum_{i \in N} x_i^t = s^t, \sum_t s^t = n,$$

$$\sum_{i \in N} y_i^t = r^t, \sum_t r^t = m,$$

$$\sum_{j \in N} z_{ij}^t \leq c * y_i^t,$$

$$\sum_{i \in N} z_{ij}^t = x_j^t,$$

$$y_i^t \leq x_i^t,$$

$$x_i^{t-1} \leq x_i^t,$$

$$y_i^{t-1} \leq y_i^t,$$

$$x_i^t, y_i^t, z_{ij}^t \in \{0,1\},$$

x_i^t : Upgrade switch i at step t

y_i^t : Deploy controller i at step t

z_{ij}^t : Controller i controls switch j at step t

Maximizing network programmability (1)

Minimizing the delay (2)

$\forall t \in [1, T]$ (3)

$\forall t \in [1, T]$ (4)

$\forall i, \forall t \in [1, T]$ (5)

$\forall j, \forall t \in [1, T]$ (6)

$\forall i, \forall t \in [1, T]$ (7)

$\forall t \in [2, T]$ (8)

$\forall t \in [2, T]$ (9)

$i, j \in N$ (P_1)

Model

Middle steps

Hybrid SDN

- Maximizing network programmability
- Minimizing the delay



Hybrid SDN

Last step

Pure SDN

- Minimizing the delay

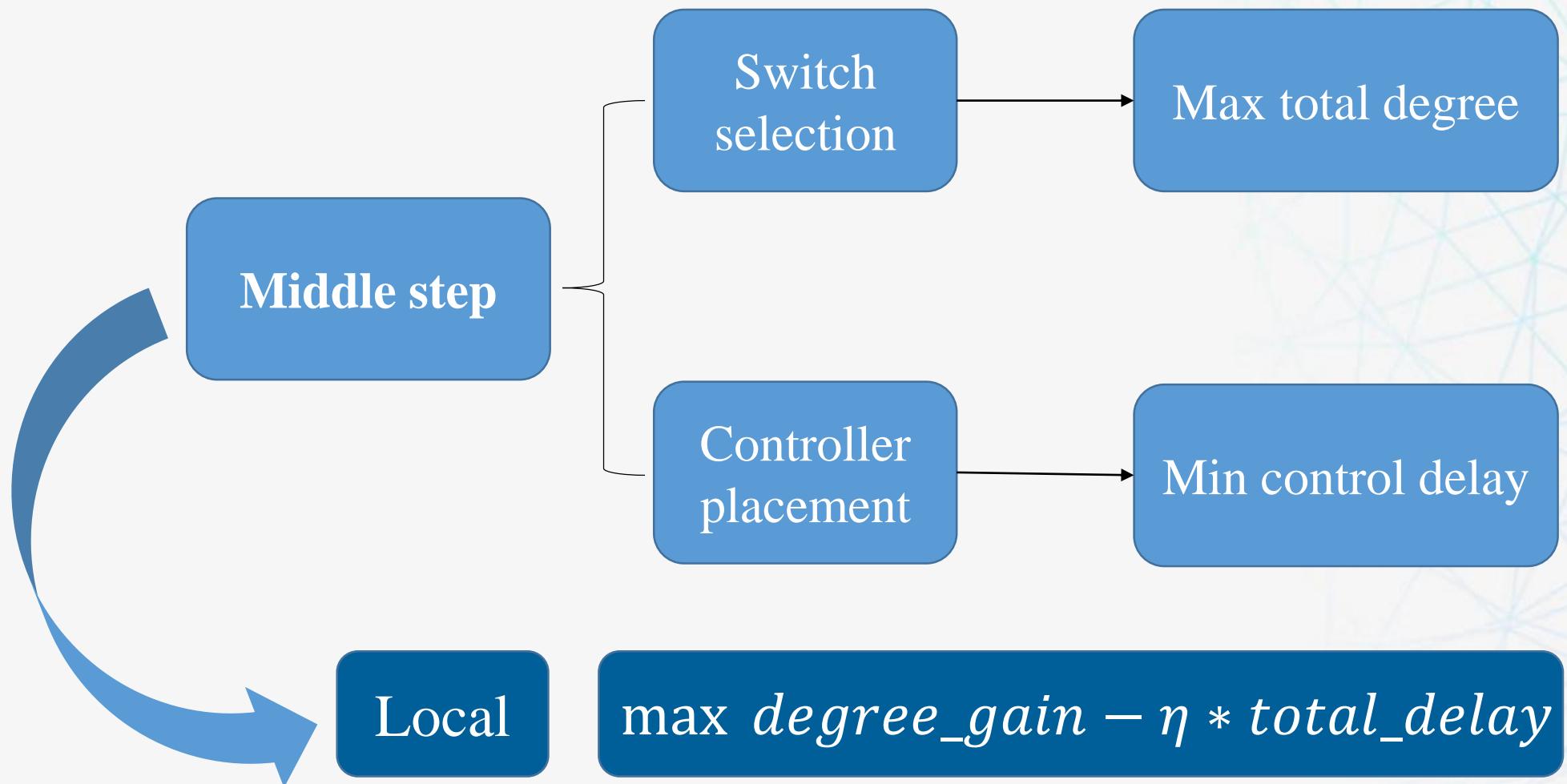


Accumulation of local optimum may not get the global optimum.



Pure SDN

Solution



Solution

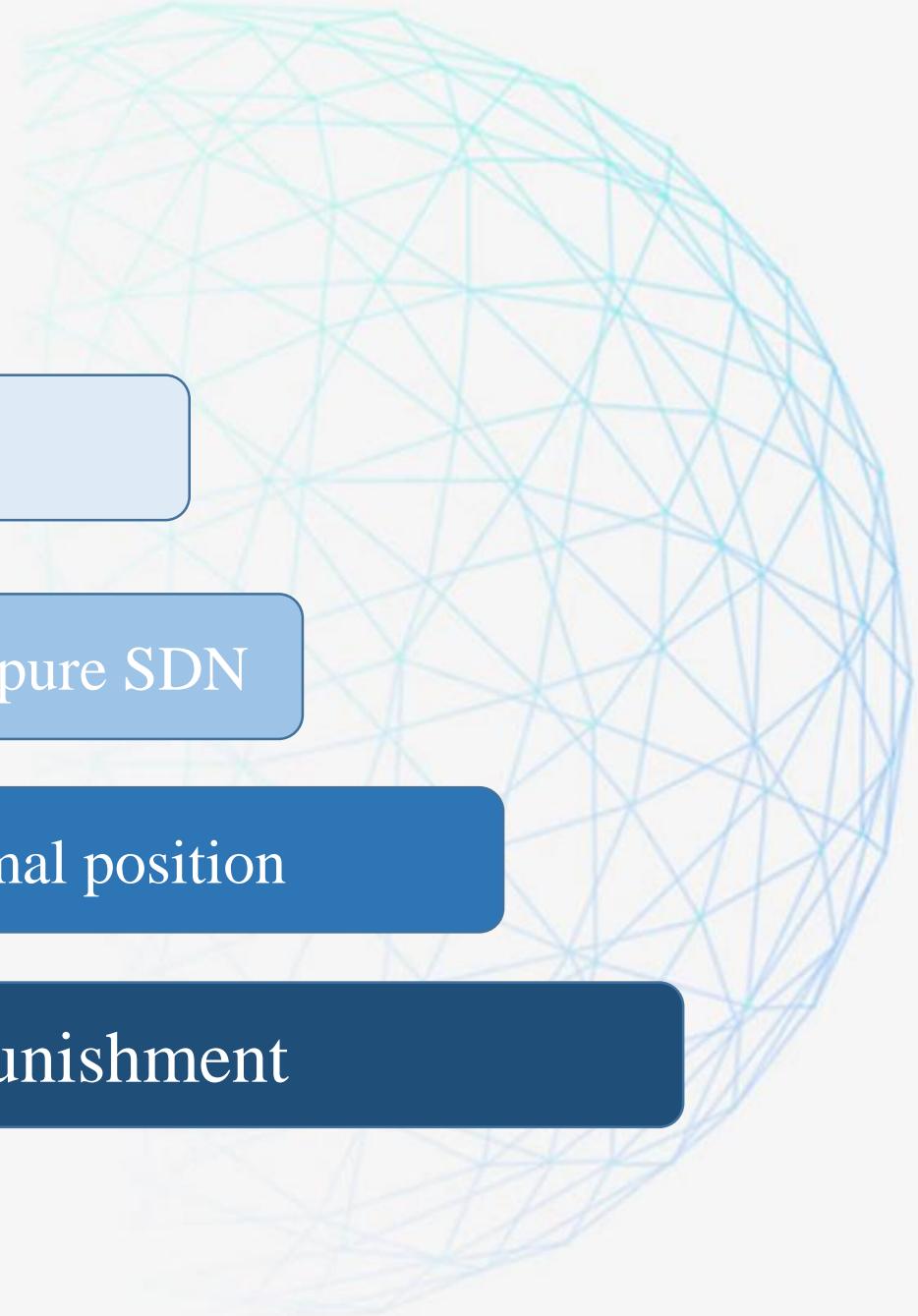
Last step: min total delay

Global optimal position for controllers in pure SDN

Punish the non-global optimal position

Global

min total punishment



Solution

Local:

max degree gain
min total delay



max *degree_gain* - $\eta * \text{total_delay}$



max *degree_gain* - $\eta * \text{total_delay} - \gamma * \text{punishment}$

Global:

min total delay



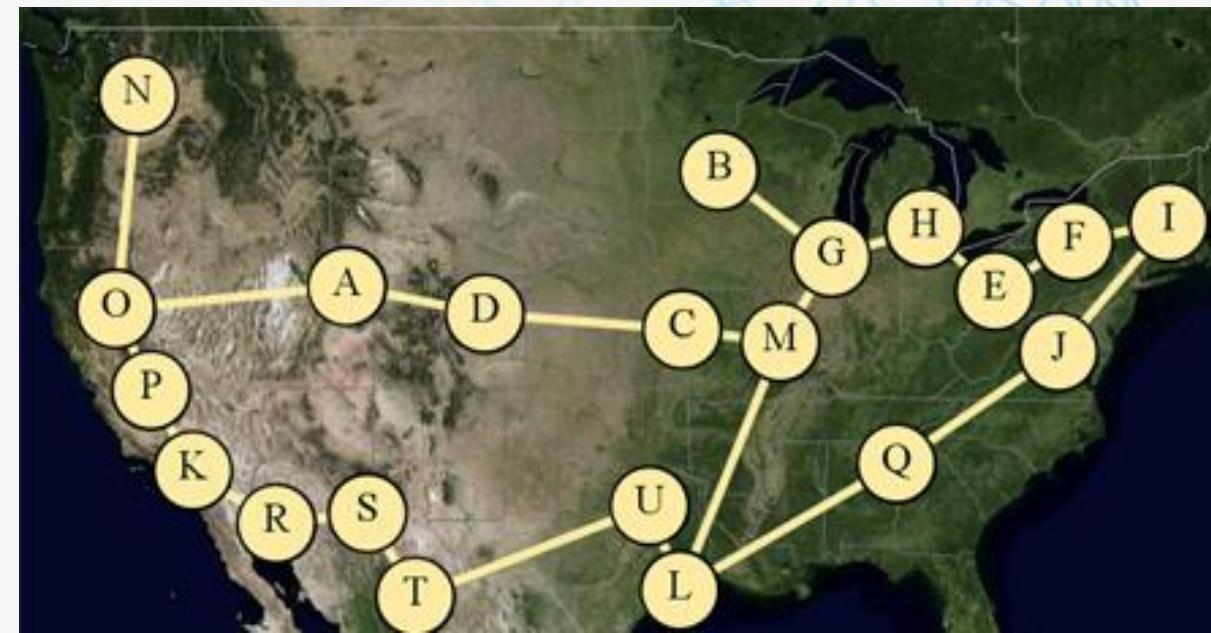
min total punishment



$$\max \sum_{i \in N} \beta^t * d_i * x_i^t - \eta * \sum_{i,j \in N} \omega_{ij} * z_{ij}^t - \sum_{i \in N} \gamma^t * q_i * y_i^t$$

Evaluation

- **Dataset**
 - Atmnet –Topology Zoo
 - 21 nodes and 22 edges
- **Compared methods**
 - **Naive deployment:**
First pick the switches in the degree descending order, then deploy the controllers in the sub SDN network to minimize control delay.
 - **Joint deployment:**
To maximize the degree gain and minimize the control delay simultaneously in each step.
 - **Global deployment:**
To maximize the degree gain, minimize control delay, and minimize the penalty simultaneously in each step.



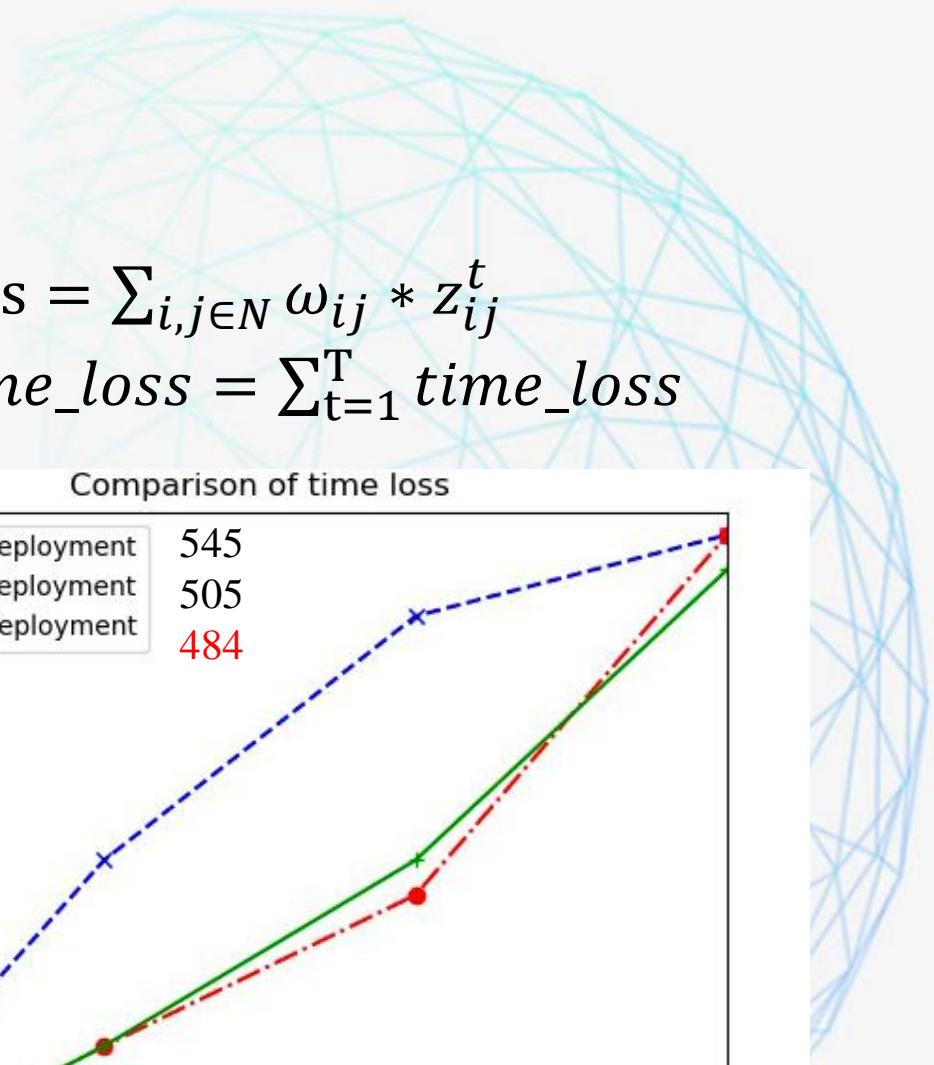
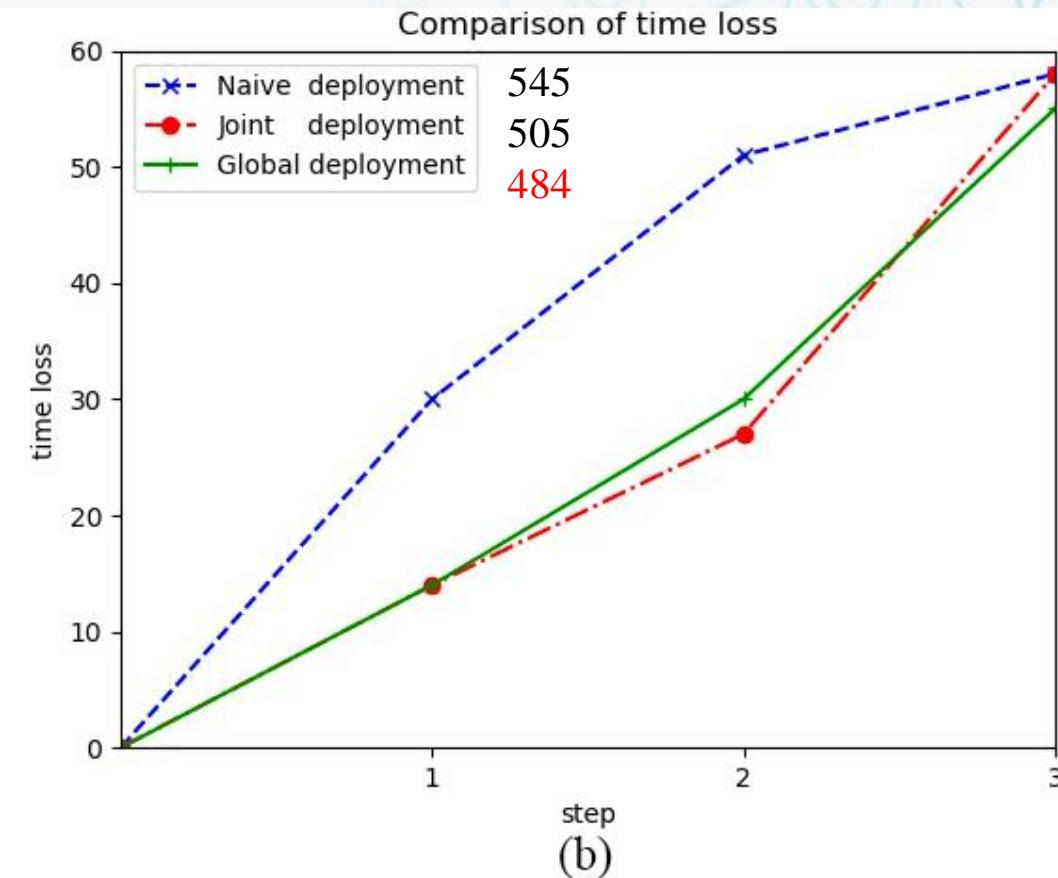
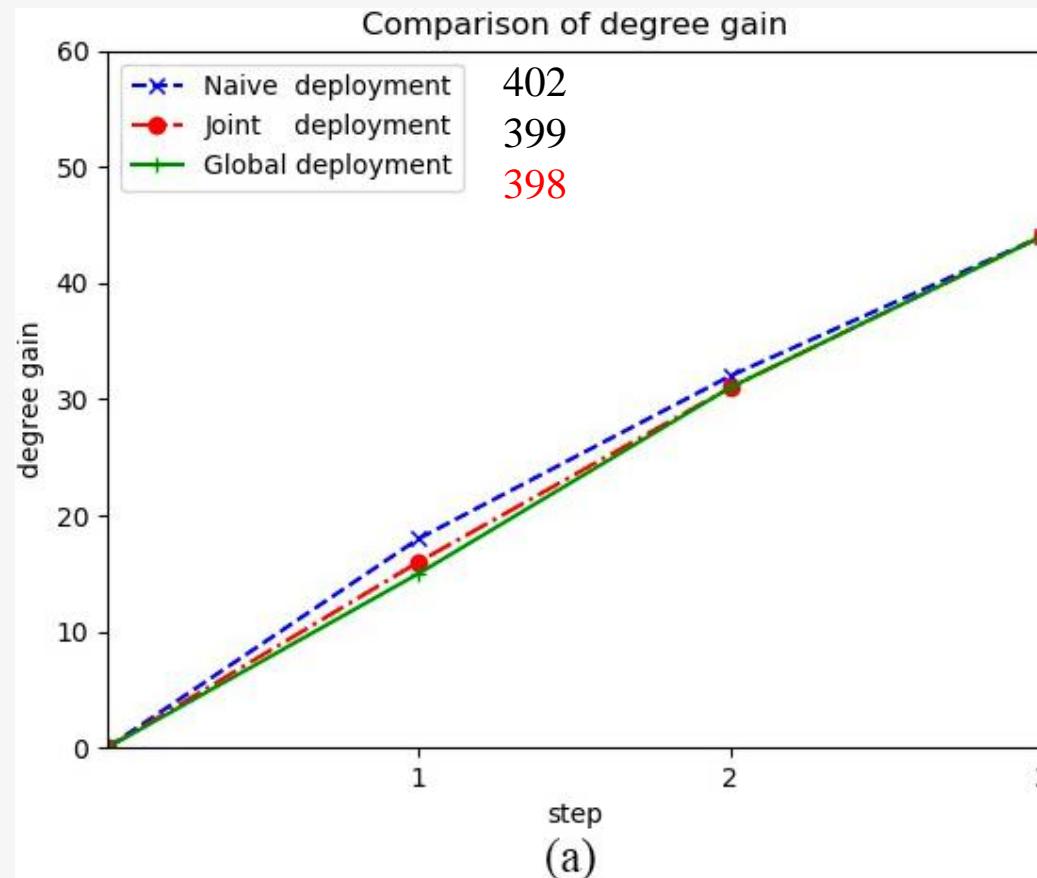
Evaluation

$$\text{degree_gain} = \sum_{i \in N} d_i * x_i^t$$

$$\text{total_degree_gain} = \sum_{t=1}^T \text{degree_gain}$$

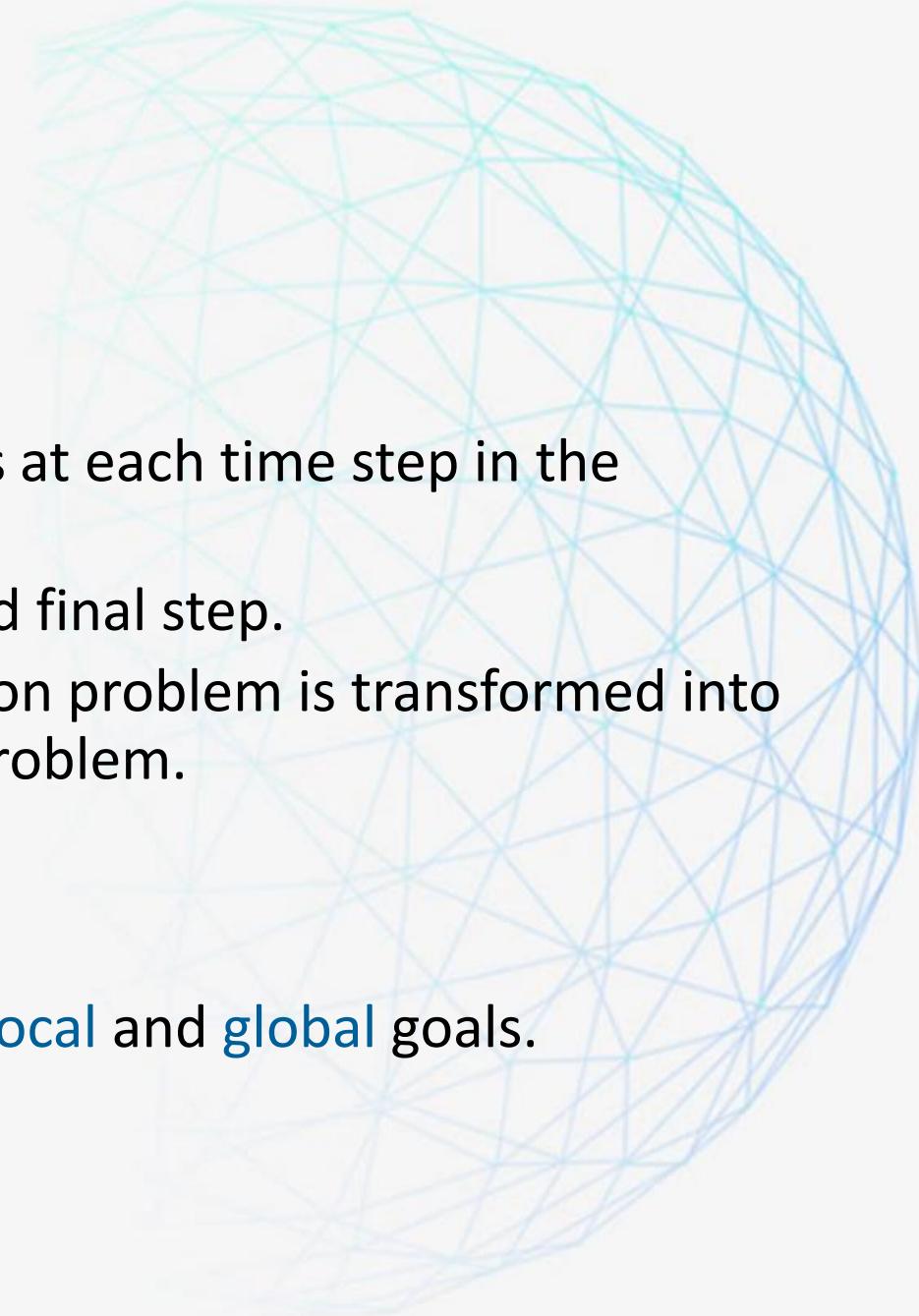
$$\text{time_loss} = \sum_{i,j \in N} \omega_{ij} * z_{ij}^t$$

$$\text{total_time_loss} = \sum_{t=1}^T \text{time_loss}$$



Conclusion

- Contribution
 - Jointly deploy controllers and upgrade switches at each time step in the whole migration process.
 - Considers the inconsistency of middle steps and final step.
 - By introducing the penalty item, the optimization problem is transformed into solvable single-objective linear programming problem.
- Results
 - Our method could get a tradeoff between the local and global goals.





Thanks for your listening