

# Homework 18

Brian Knotten, Brett Schreiber, Brian Falkenstein

October 7, 2018

## 27

A binary decision tree can be constructed which has the solution to this problem at the leaves. Let a node  $v$  at depth  $i$  of the decision tree represent a proposed solution for chapters  $x_1, x_2, \dots, x_i$ . Let the left child of  $v$  represent a proposed solution identical to  $v$ 's solution, but considering  $x_{i+1}$  in a new volume. Let the right child of  $v$  also represent a proposed solution identical to  $v$ 's solution, but which appends  $x_{i+1}$  into the same volume as  $x_i$ . The proposed solutions for all chapters  $x_1$  through  $x_n$  will be at the leaves, however, there are  $2^n$  leaves since it is a binary tree of depth  $n$ . So the tree must be pruned into a polynomial algorithm, and it also must be pruned for correctness.

The pruning rules are as follows:

1. If a vertex  $v$  proposes a solution with more than  $k$  volumes, then prune  $v$ , since the solution cannot use more than  $k$  volumes.

This pruning rule does not definitively reduce the input size, but it makes reasoning about the tree easier.

2. If two nodes  $u$  and  $v$  are on the same level, have the same number of volumes, and the difference between  $u$ 's longest and shortest volumes is less than or equal to the difference between  $v$ 's longest and shortest volumes, then prune  $v$ .  $v$ 's children can only decrease the difference between the longest and shortest volumes if they add to the shortest volume. And anything  $v$ 's children can add to the shortest volume,  $u$  can also add. So  $u$ 's children will always have an equal or better proposed solution than  $v$ 's children.

This pruning rule reduces the number of nodes at any given depth to  $k$ , since no two nodes at the same depth can use the same number of volumes, since one of them will be pruned. Therefore the tree is of size  $nk$ .

With these pruning rules, the tree can be turned into a 2-dimensional array  $A$ , where  $A[i, j]$  = the least difference in pages between the smallest and largest volumes of a partition of chapters  $x_1$  through  $x_i$  into  $j$  volumes.

The algorithm to populate  $A$  is as follows and runs in  $O(nk)$ :

```
for i = 1 to n do:
    A[i, 1]                # Base case: having only 1 volume implies 0 distance

for j = 1 to k do:
    A[0, j] = 0            # Base case: 0 pages implies 0 distance

for i = 1 to n do:        # For each chapter x[i]
    for j = 1 to k do:    # For every possible number of volumes:

        A[i, j] = min(    # Take the minimum of either:
            A[i - 1, j],  # appending to the previous volume
            A[i, j]       # or of what is already in the array cell
        )
```

```

if j < n:                # Only create a new volume if it's possible

A[i, j + 1] = min(       # Take the minimum of either:
    A [i - 1, j], # Adding it to its own volume
    A[i, j + 1]    # or of what is already in the array cell
)

```

Output A[n, k] # The solution is the minimum distance between the smallest and  
# largest volumes considering all n chapters and k volumes

## 28

### a

The decision tree for this problem can be constructed with the following rules:

- Nodes in the tree have  $n$  children, where the  $i$ 'th child for  $1 \leq i \leq n$  corresponds to choosing  $v_i$  to be a center point. Thus, the tree has height  $k$  and will contain all solutions at the leaves.
- The nodes will store the current aggregate distance, that is, the sum of all the distances from each  $v \in V$  to its closest center point  $c \in C$ .

The total size of the tree is  $n^k$ . This can then be pruned with the following rules:

1. If a node at depth  $i$  already exists in  $C$ , prune it. That is, if that vertex has already been added to  $C$ , remove that sub tree, as a valid solution contains  $k$  different vertices in  $C$ .
2. If two nodes  $u$  and  $v$  at depth  $i$  have the same  $c_1 \dots c_{i-1}$  center points, and  $D_u < D_v$ , prune  $v$  (where  $D_u$  is the total aggregate distance for  $u$ ).

The first pruning rule leaves the tree as still roughly  $n^k$ . However, under the second pruning rule, every depth  $i$  is limited to  $n$  nodes. This is because at depth  $i - 1$ , for some node  $v$ , all of  $v$ 's children have the same  $c_1 \dots c_{i-1}$ , and only one will not be pruned, that is the one with the shortest  $D$ . This brings the size of the tree down to  $nk$ . At each node  $v$ , a new aggregate distance must be calculated, which takes  $n$  calculations, which leaves this tree with a run time of  $O(n^2k)$ .

The dynamic algorithm is given as follows:

```

A = [k, n]                # Construct A to be an array of size k by n

A[0, :] = infinity        # Base case: having zero centers gives a
                           # distance of infinity

for i = 1 to k do         # For each row
    last_v = min(A[i-1, :]) # Retrieve the minimum distance vertex from the previous row,
                           # and use it for calculations on the current row.

    for j = 1 to no do     # For each row, check all possible center values
        if(last_v != V[j]) # Disregard already-used vertices
            A[i, j] = new_dist(last_v, V[j]) # Calculate new distance with V[j] as a new center

output min(A[k, :])        # Return the minimum value in the last row

```

Here, A[i, j] represents the minimum aggregate distance using  $i$  center points, where  $v_j$  is the last vertex to be chosen as a center.