

Homework 18

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The decision tree for this problem can be constructed with the following rules:

- Nodes in the tree have n children, where the i 'th child for $1 \leq i \leq n$ corresponds to choosing v_i to be a center point. Thus, the tree has height k and will contain all solutions at the leaves.
- The nodes will store the current aggregate distance, that is, the sum of all the distances from each $v \in V$ to its closest center point $c \in C$.

The total size of the tree is n^k . This can then be pruned with the following rules:

1. If a node at depth i already exists in C , prune it. That is, if that vertex has already been added to C , remove that sub tree, as a valid solution contains k different vertices in C .
2. If two nodes u and v at depth i have the same $c_1 \dots c_{i-1}$ center points, and $D_u < D_v$, prune v (where D_u is the total aggregate distance for u).

The first pruning rule leaves the tree as still roughly n^k . However, under the second pruning rule, every depth i is limited to n nodes. This is because at depth $i - 1$, for some node v , all of v 's children have the same $c_1 \dots c_{i-1}$, and only one will not be pruned, that is the one with the shortest D . This brings the size of the tree down to nk . At each node v , a new aggregate distance must be calculated, which takes n calculations, which leaves this tree with a run time of n^2k .

The dynamic algorithm is given as follows:

```
A = [k, n] %construct A to be an array of size k by n
A[0, :] = infinity %having zero centers gives a distance of infinity
for i = 1 to k do %loop over the rows
    last_v = min(A[i-1, :]) %grab the minimum D from the previous row. use this V for subsequent
    %calculations on the current row
    for j = 1 to no do %for each row, check all possible center values
        if(last_v != v[j]) %can't repeat a vertex in the solution
            A[i, j] = new_dist(last_v, V[j]) %calculate new distance with V[j] as a new center
output min(A[k, :]) %return the minimum value in the last row
```

Here, $A[i, j]$ represents the minimum aggregate distance using i center points, where v_j is the last vertex to be chosen as a center.