Aim?

Implement graph wing adjacency list or matrix
and perform DFS or. BFS.

Theory:

Algorithms => Creation of Adjacency 19st -> Declare array of pointers to a link 19st having a data field and forward pointers. The no. of array of pointers would point to 2 nodes one having the data 2 and other having data 3.

In this way construct the entire adjacency list. Depth First Search => The start vertex is visited. Next an unusited vertex wadjacent to vis selected and DFS from winitalated. When a vertex u is reached such that all its adjacents vertices have been visited. We both as unvisited vertex w adjacent to it and initiative a DFS from w. The search terminates when no unvisited vertex can be reached from any of the visited once

Breadth	First	Search	\Rightarrow

Starting at vertex v and marking it as visited differs from DFS in that all unvisited vertices adjacent to V are visited next.

Then unvisited vertex adjacent to these vertices are

A queue is used to store vertices as they are visited to that later search tree can be initalize from those vertices.

Test Condition >

(3,1) (4,8) (5,8) (6,8) (7,8)

The order of vertices visited by DFS is,

1,2,3,4,8,5,6,7

The order of vertices visited by BFS 95,

The no of vertices and the edge set of graph.

The order of vertices visited in both DFS & BFS.

Program Code:-

```
#include <bits/stdc++.h>
using namespace std;
class Graph {
 // Number of vertex
 int v;
 // Number of edges
 int e;
 // Adjacency matrix
 int ** adj;
 public:
  // To create the initial adjacency matrix
  Graph(int v, int e);
 // Function to insert a new edge
 void addEdge(int start, int e);
 // Function to display the BFS traversal
 void BFS(int start);
};
// Function to fill the empty adjacency matrix
Graph::Graph(int v, int e) {
 this \rightarrow v = v;
 this \rightarrow e = e;
 adj = new int * [v];
 for (int row = 0; row < v; row++) {
  adj[row] = new int[v];
  for (int column = 0; column < v; column++) {
   adi[row][column] = 0;
  }
}
// Function to add an edge to the graph
void Graph::addEdge(int start, int e) {
 // Considering a bidirectional edge
 adj[start][e] = 1;
 adj[e][start] = 1;
// Function to perform BFS on the graph
void Graph::BFS(int start) {
 // Visited vector to so that
```

```
// a vertex is not visited more than once
 // Initializing the vector to false as no
 // vertex is visited at the beginning
 vector < bool > visited(v, false);
 vector < int > q;
 q.push_back(start);
 // Set source as visited
 visited[start] = true;
 int vis;
 while (!q.empty()) {
  vis = q[0];
  // Print the current node
  cout << vis << " ";
  q.erase(q.begin());
  // For every adjacent vertex to the current vertex
  for (int i = 0; i < v; i++) {
   if (adj[vis][i] == 1 && (!visited[i])) {
     // Push the adjacent node to the queue
     q.push_back(i);
     // Set
     visited[i] = true;
// Driver code
int main() {
 int v = 5, e = 4;
 // Create the graph
 Graph G(v, e);
 G.addEdge(0, 1);
 G.addEdge(0, 2);
 G.addEdge(1, 3);
 G.BFS(0);
```

Program Output:

