

CS151 Intro to Data Structures

Hashmaps & Sorting

Announcements

HW06 due next Wednesday 11/29
Lab08 due next Wednesday too

No lab this week

HW07 due 12/05

Need to leave office hours around 3:15 today

Outline

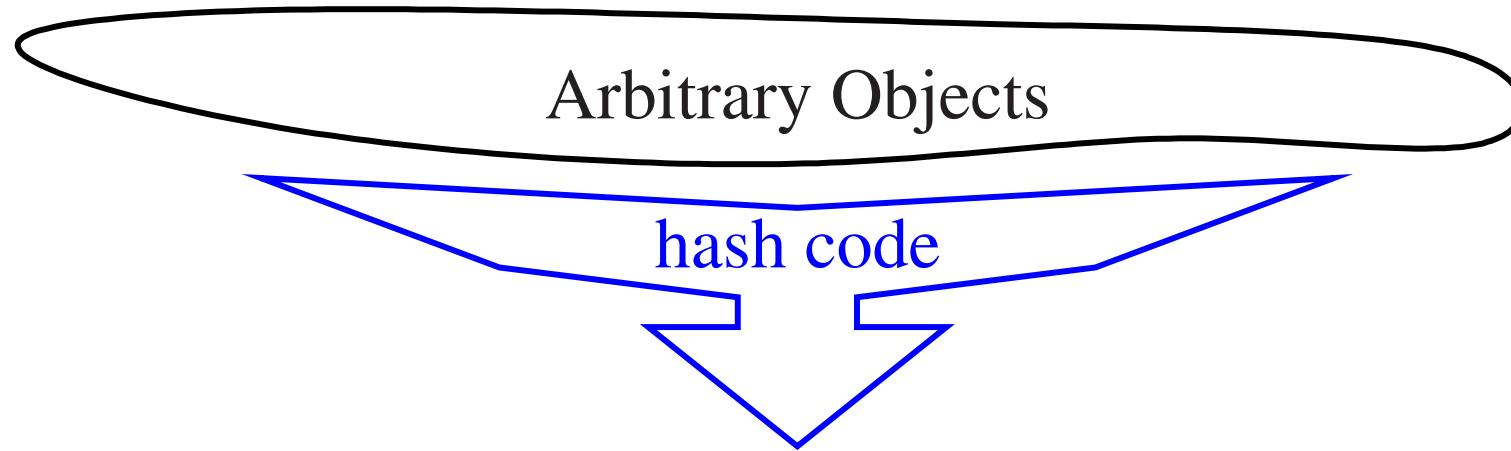
Review

MergeSort

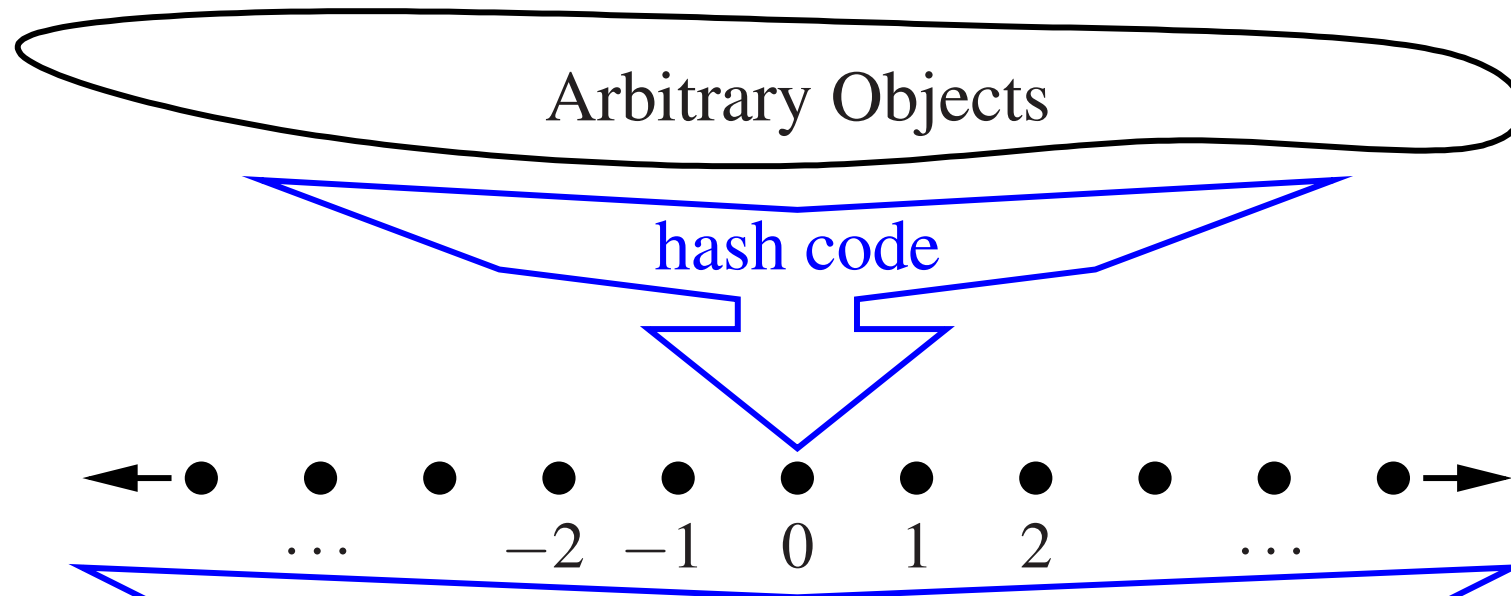
Hash Function Illustration



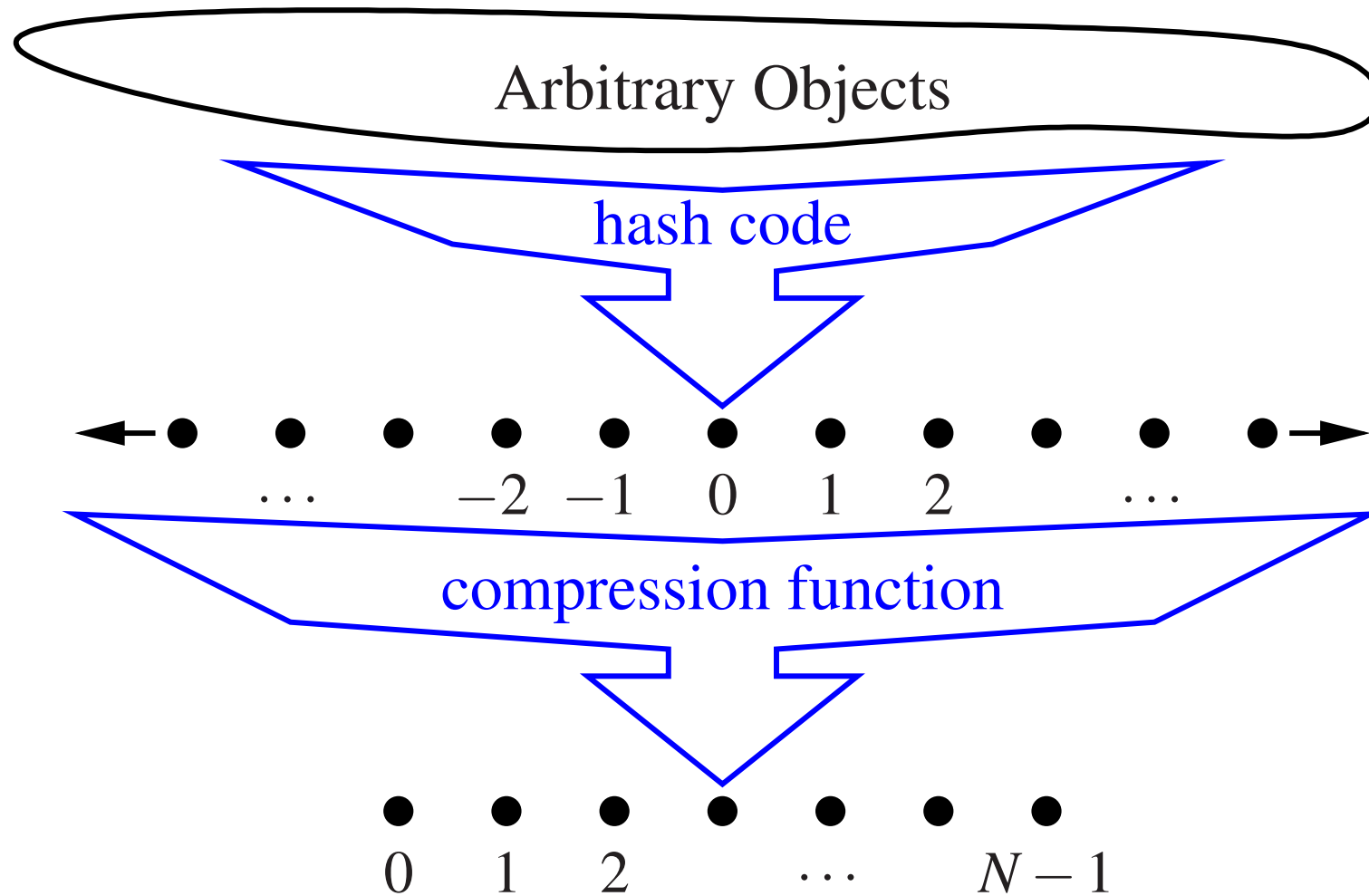
Hash Function Illustration



Hash Function Illustration



Hash Function Illustration



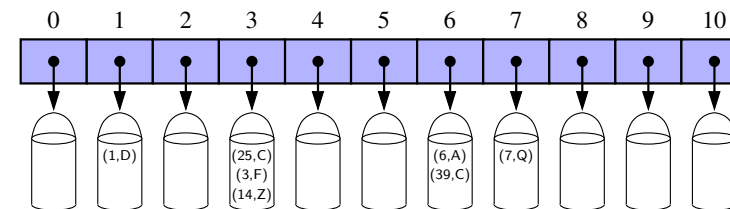
Collision Handling

Collision: keys mapped to same hash value

A hash function does not guarantee one-to-one mapping

no hash function does

Separate chaining: Each index holds a collection of entries



Open addressing

Linear/Quadratic probing

Double hasing

Open Addressing vs Chaining

- Probing is significantly faster in practice
- locality of references – much faster to access a series of elements in an array than to follow the same number of pointers in a linked list
- Efficient probing requires soft/lazy deletions – tombstoning, why?
- May require graveyard defragmenting

Performance Analysis

- In the worst case, searches, insertions and removals take $O(n)$ time
 - when all the keys collide
- The load factor $\alpha = n/N$ affects the performance of a hash table
 - expected number of probes for an insertion with open addressing is $\frac{1}{1-\alpha}$
- Expected time of all operations is $O(1)$ provided α is not close to 100%

Probing Tradeoffs

- Linear probing – best cache performance but most sensitive to clustering
- Double hashing – poor cache performance but exhibits virtually no clustering
- Quadratic – inbetween
- As load factor approaches 100%, number of probes rises dramatically
- Even with good hash functions, keep load factor 80% or below (50% is typical)
- Other open addressing methods besides probing

Performance of Hashtable

	Hash Expected	Hash Worst
search		
insert		
remove		
min/max		

	Unsorted array	Sorted array	Unsorted list	Sorted list	BST balanced	Hash Expected
search	$O(n)^*$	$O(\log n)$	$O(n)$	$O(n)$	$O(\log n)$	$O(1)$
insert	$O(1)^*$	$O(n)$	$O(1)$	$O(n)$	$O(\log n)$	$O(1)$
remove	$O(1)^*$	$O(n)$	$O(1)$	$O(1)$	$O(\log n)$	$O(1)$
min/max	$O(n)$	$O(1)$	$O(n)$	$O(1)$	$O(\log n)$	$O(n)$

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search	$O(n)^*$	$O(\log n)$	$O(n)$	$O(n)$	$O(\log n)$	$O(1)$
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remove	$O(1)^*$	$O(n)$	$O(1)$	$O(1)$	$O(\log n)$	$O(1)$
min/max	$O(n)$	$O(1)$	$O(n)$	$O(1)$	$O(\log n)$	$O(n)$

Hashtable vs Array

- A hashtable is an unsorted array with a fast search – $O(1)$ expected
- An array is more memory efficient, but slower for searching (without key-index pairing)
- If your data has natural indexing (a way to assign/associate an ID/unique integer to each entry), then you are better off using an array. You have a hash function with 1-to-1 mapping and guaranteed no collisions

Hashtable Size

Should be a prime

twice the size of max number of keys

- or 1.3 times if n is very large
- $1/1.333 = 75\%$ load factor

Keep track of load factor and expand (rehash) the hash table when necessary

Outline

Review

MergeSort

Divide-and-Conquer

Divide – the problem (input) into smaller pieces

Conquer – solve each piece individually, usually recursively

Combine – the piecewise solutions into a global solution

Usually involves recursion

Analysis usually involves solving recurrence relations

Merge Sort

Sort a sequence of numbers A , $|A| = n$

Base: $|A| = 1$, then it's already sorted

General

- divide: split A into two halves, each of size $\frac{n}{2}$ ($\lfloor \frac{n}{2} \rfloor$ and $\lceil \frac{n}{2} \rceil$)
- conquer: sort each half (by calling mergeSort recursively)
- combine: merge the two sorted halves into a single sorted list

Example

6	8	4	1	7	2	5	3
---	---	---	---	---	---	---	---

Example

6	8	4	1	7	2	5	3
---	---	---	---	---	---	---	---

6	8	4	1
---	---	---	---

7	2	5	3
---	---	---	---

Example

6	8	4	1	7	2	5	3
---	---	---	---	---	---	---	---

6	8	4	1
---	---	---	---

7	2	5	3
---	---	---	---

6	8	4	1
---	---	---	---

7	2
---	---

5	3
---	---

Example

6 8 4 1 7 2 5 3

6 8 4 1

7 2 5 3

6 8 4 1

7 2

5 3

6 8 4 1

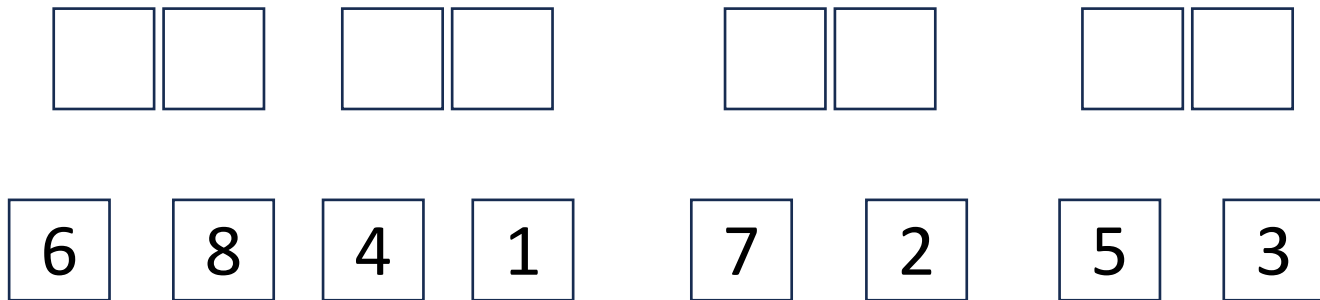
7 2

5 3

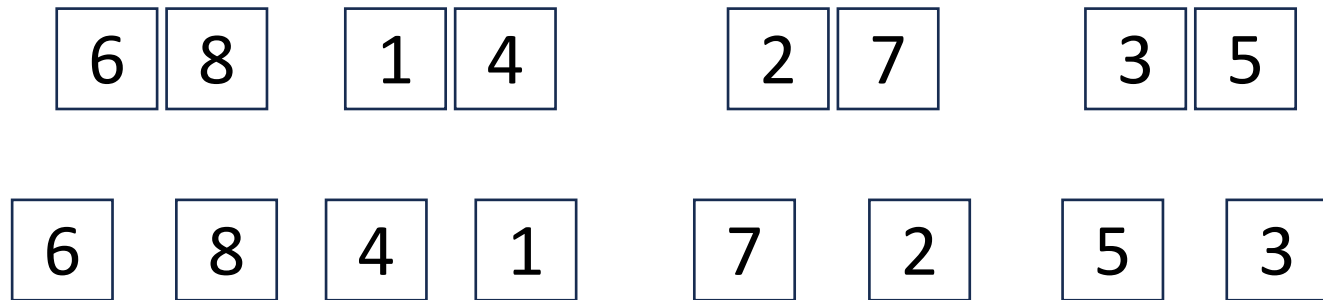
Example



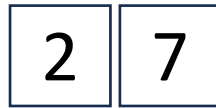
Example



Example



Example



Example

1 4 6 8

2 3 5 7

6 8 1 4

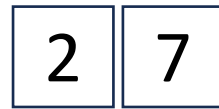
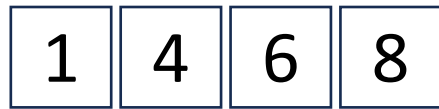
2 7

3 5

6 8 4 1

7 2 5 3

Example



Example

1	2	3	4	5	6	7	8
---	---	---	---	---	---	---	---

1	4	6	8
---	---	---	---

2	3	5	7
---	---	---	---

6	8	1	4
---	---	---	---

2	7
---	---

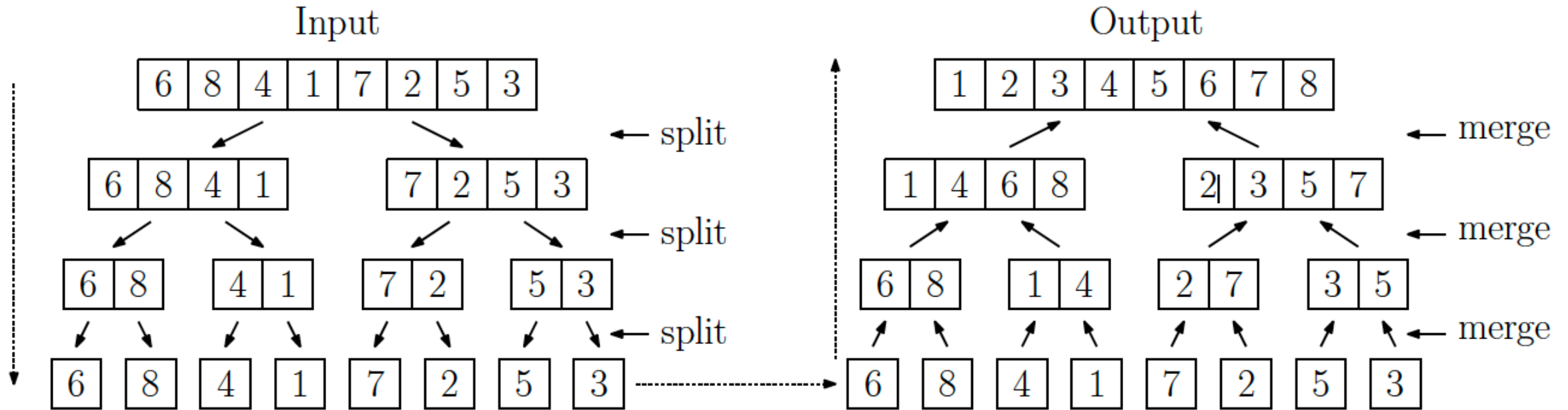
3	5
---	---

6	8	4	1
---	---	---	---

7	2
---	---

5	3
---	---

Example - summary



Merge Sort

Sort a sequence of numbers A , $|A| = n$

Base: $|A| = 1$, then it's already sorted

General

- divide: split A into two halves, each of size $\frac{n}{2}$ ($\lfloor \frac{n}{2} \rfloor$ and $\lceil \frac{n}{2} \rceil$)
- conquer: sort each half (by calling mergeSort recursively)
- combine: merge the two sorted halves into a single sorted list

Algorithm

```
mergeSort (S) :  
  if ...  
    ...  
  else  
    s1 = ...  
    s2 = ...  
    ...  
    S = ...
```


Algorithm

```
mergeSort(S) :  
    if S.size() <= 1  
        return  
    else  
        s1 = S[0, n/2]  
        s2 = S[n/2+1, n-1]  
        mergeSort(s1)  
        mergeSort(s2)  
        S = merge(s1, s2)
```

The Merge

The key is the merging process

How does one merge two sorted lists?

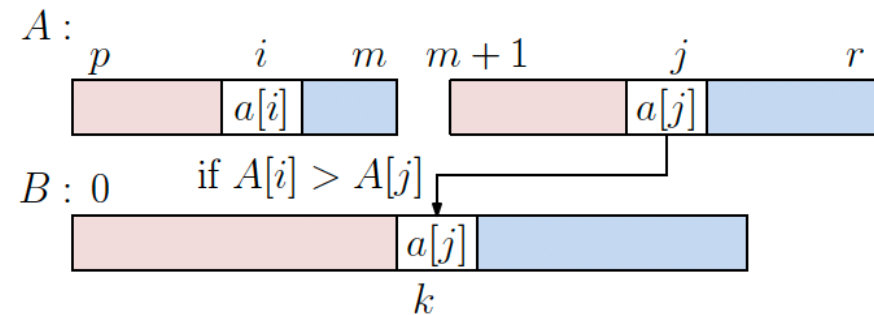
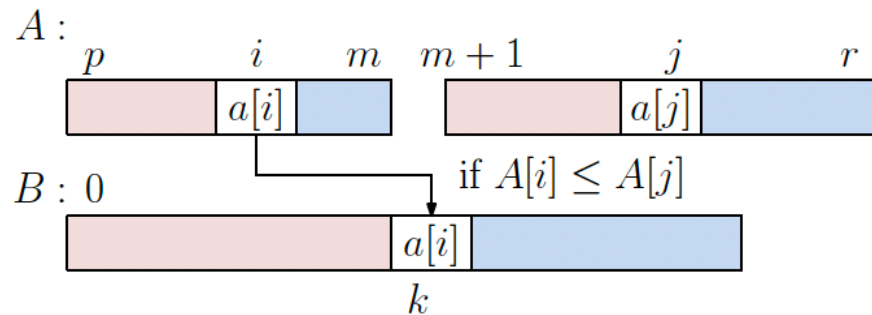
- Each element in $A \cup B$ is considered once
- $O(n)$

```
Algorithm merge(A, B)
  Input sorted A and B
  Output sorted  $A \cup B$ 
  S = empty sequence
  while (!A.isEmpty() and
        !B.isEmpty())
    if A.first() < B.first()
      S.addLast(A.removeFirst())
    else
      S.addLast(B.removeFirst())
  while (!A.isEmpty())
    S.addLast(A.removeFirst())
  while (!B.isEmpty())
    S.addLast(B.removeFirst())
  return S
```

In-place Merge

What if we don't want to use new lists?

How does one merge two sorted lists $A[p, \dots, m]$ and $A[m+1, \dots, r]$?



Use a temp array B and maintain two indices i and j , one for each subarray

Array mergeSort

```
mergeSort(A, p, r) {  
    if (p < r) {  
        m = (p+r) / 2  
        mergeSort(A, p, m)  
        mergeSort(A, m+1, r)  
        merge(A, p, m, r)  
    }  
}
```

Array mergeSort

```
merge(A, p, m, r) {  
    new B[0, r-p]
```

```
}
```

```
mergeSort(A, p, r) {  
    if (p < r) {  
        m = (p+r) / 2  
        mergeSort(A, p, m)  
        mergeSort(A, m+1, r)  
        merge(A, p, m, r)  
    }  
}
```

Array mergeSort

```
merge(A, p, m, r) {  
    new B[0, r-p]  
    i=p; j=m+1; k=0
```

```
}
```

```
mergeSort(A, p, r) {  
    if (p<r) {  
        m = (p+r) / 2  
        mergeSort(A, p, m)  
        mergeSort(A, m+1, r)  
        merge(A, p, m, r)  
    }  
}
```

Array mergeSort

```
merge(A, p, m, r) {
    new B[0, r-p]
    i=p; j=m+1; k=0
    while(i<=m and j<=r) {

    }
```

}

```
mergeSort(A, p, r) {
    if (p < r) {
        m = (p+r)/2
        mergeSort(A, p, m)
        mergeSort(A, m+1, r)
        merge(A, p, m, r)
    }
}
```

Array mergeSort

```
merge(A, p, m, r) {  
    new B[0, r-p]  
    i=p; j=m+1; k=0  
    while(i<=m and j<=r) {  
        if (A[i]<=A[j])  
  
        else  
  
    }  
  
}
```

```
mergeSort(A, p, r) {  
    if (p<r) {  
        m = (p+r)/2  
        mergeSort(A, p, m)  
        mergeSort(A, m+1, r)  
        merge(A, p, m, r)  
    }  
}
```


Array mergeSort

```
merge(A, p, m, r) {  
    new B[0, r-p]  
    i=p; j=m+1; k=0  
    while(i<=m and j<=r) {  
        if (A[i]<=A[j])  
            B[k++] = A[i++]  
        else  
            B[k++] = A[j++]  
    }  
}
```

```
mergeSort(A, p, r) {  
    if (p<r) {  
        m = (p+r)/2  
        mergeSort(A, p, m)  
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}
```

Array mergeSort

```
merge(A, p, m, r) {
    new B[0, r-p]
    i=p; j=m+1; k=0
    while(i<=m and j<=r) {
        if (A[i]<=A[j])
            B[k++] = A[i++]
        else
            B[k++] = A[j++]
    }
    while(i<=m) B[k++]=A[i++]
    while(j<=r) B[k++]=A[j++]
    copy B back to A[p, r]
}
```

```
mergeSort(A, p, r) {
    if (p<r) {
        m = (p+r)/2
        mergeSort(A, p, m)
        mergeSort(A, m+1, r)
        merge(A, p, m, r)
    }
}
```

Analysis

merge:

$$O(r - p + 1) \rightarrow O(n)$$

Let $T(n)$ denote the worse case running time of `mergeSort` on an input of size n

$$T(n) = \begin{cases} 1, & n = 1 \\ 2T\left(\frac{n}{2}\right) + n, & n > 1 \end{cases}$$

Solving the Recurrence

- $T(n) = 2T\left(\frac{n}{2}\right) + n$

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- $= \dots$
- $= 2^kT\left(\frac{n}{2^k}\right) + kn$

$$T(n) = 2^k T\left(\frac{n}{2^k}\right) + kn$$

What is the value of k ?

$$T(n) = 2^k T\left(\frac{n}{2^k}\right) + kn$$

What is the value of k ?

- $\frac{n}{2^k} = 1$
 - $n = 2^k$
 - $k = \log n$
-
- $T(n) = 2^{\log n} \cdot T(1) + \log n \times n$
 $= n + n \log n$
 - $= O(n \log n)$

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$T(n)$

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$$\begin{aligned} T(n) &= 2^{\log n} \cdot T(1) + \log n \times n \\ &= n + n \log n \end{aligned}$$

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$$\begin{aligned} T(n) &= 2^{\log n} \cdot T(1) + \log n \times n \\ &= n + n \log n \\ &= O(n \log n) \end{aligned}$$

Summary of Sorting Algorithms

Algorithm	Time	Notes
selection-sort	$O(n^2)$	<ul style="list-style-type: none">▪ slow▪ in-place▪ for small data sets (< 1K)
insertion-sort	$O(n^2)$	<ul style="list-style-type: none">▪ slow▪ in-place▪ for small data sets (< 1K)
heap-sort	$O(n \log n)$	<ul style="list-style-type: none">▪ fast▪ in-place▪ for large data sets (1K — 1M)
merge-sort	$O(n \log n)$	<ul style="list-style-type: none">▪ fast▪ sequential data access▪ for huge data sets (> 1M)