

CS151 Intro to Data Structures

Array-based Heaps

Outline

- Array Based Trees
- Breath First Traversal
- Array Based Heaps
- More efficient way to Construct Heaps

Announcements

HW05 due next Tuesday

Will be released very shortly (just fixing checkstyle in starter code)

Midterm & Grading

Array

Physical memory is one-dimensional

- an enormous array of bytes

All data structures (are in our heads)

- differ only in the organization of data
- how each element is accessed (search/traversal) in relationship with the next
- how insert/remove/update affects the organization

Organizational Types

Arrays

- Contiguous – next element is next in memory
- Directional

Linked List

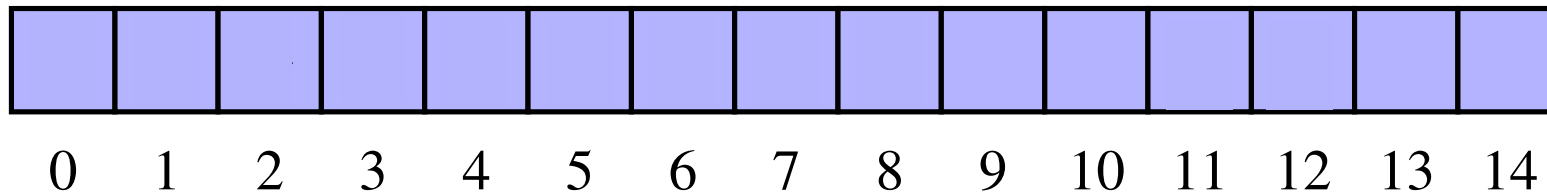
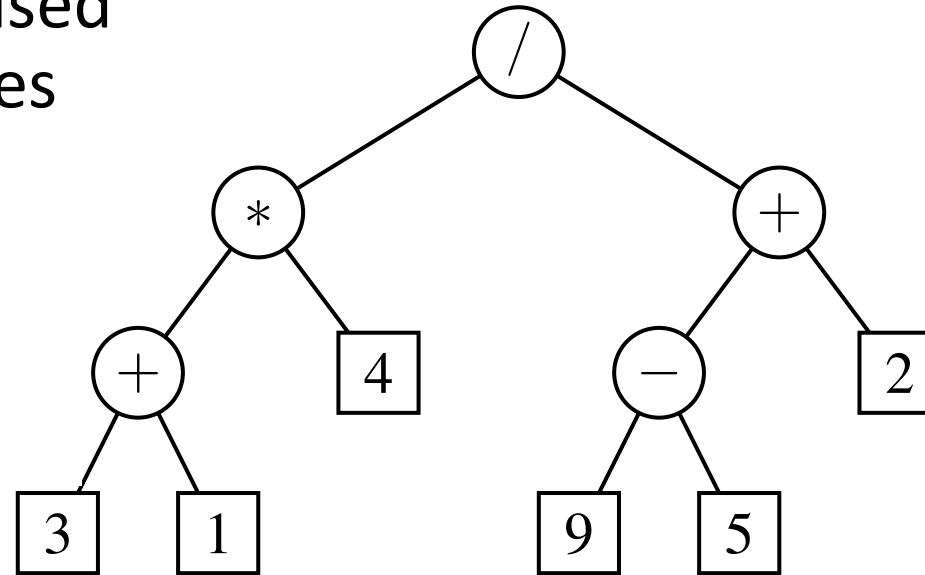
- Noncontiguous
- Directional

Tree

- Noncontiguous
- Multi-Directional

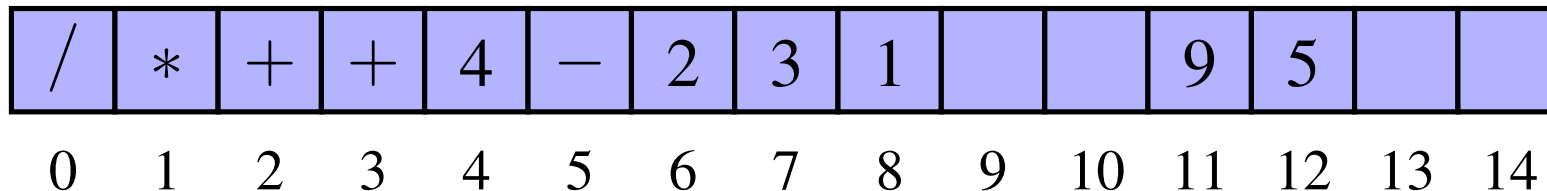
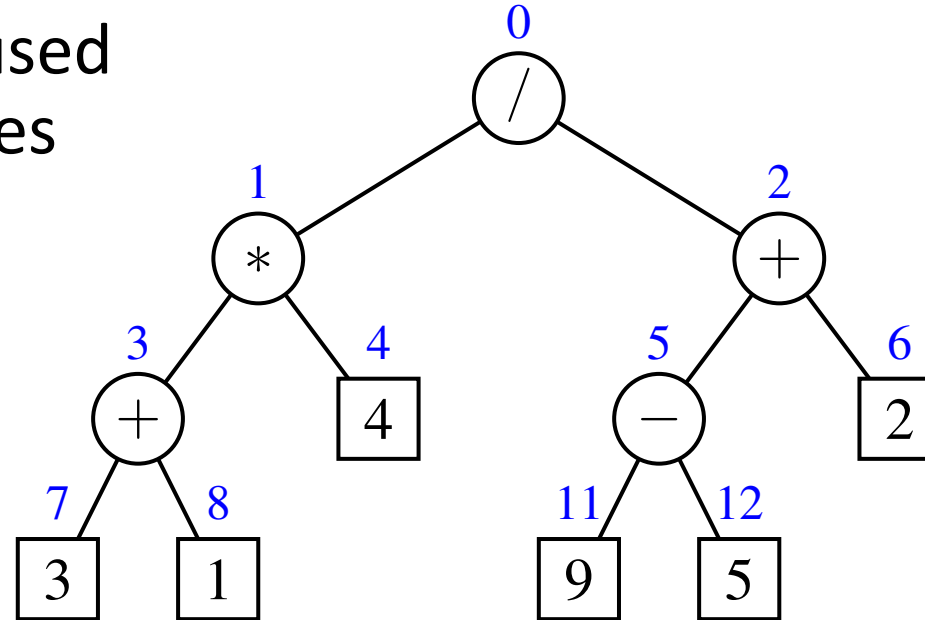
Array-based Binary Tree

- The numbering can then be used as indices for storing the nodes directly in an array
- $f(\text{root}) = 0$
- $f(l) = 2f(p) + 1$
- $f(r) = 2f(p) + 2$



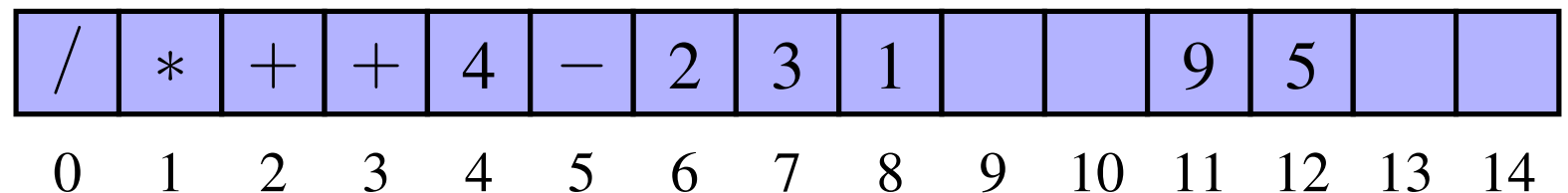
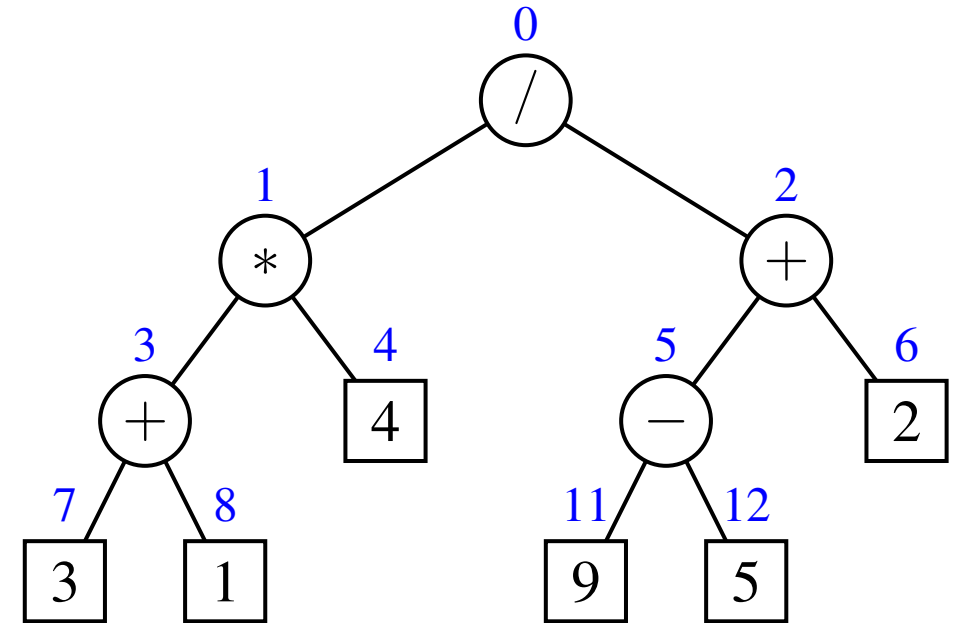
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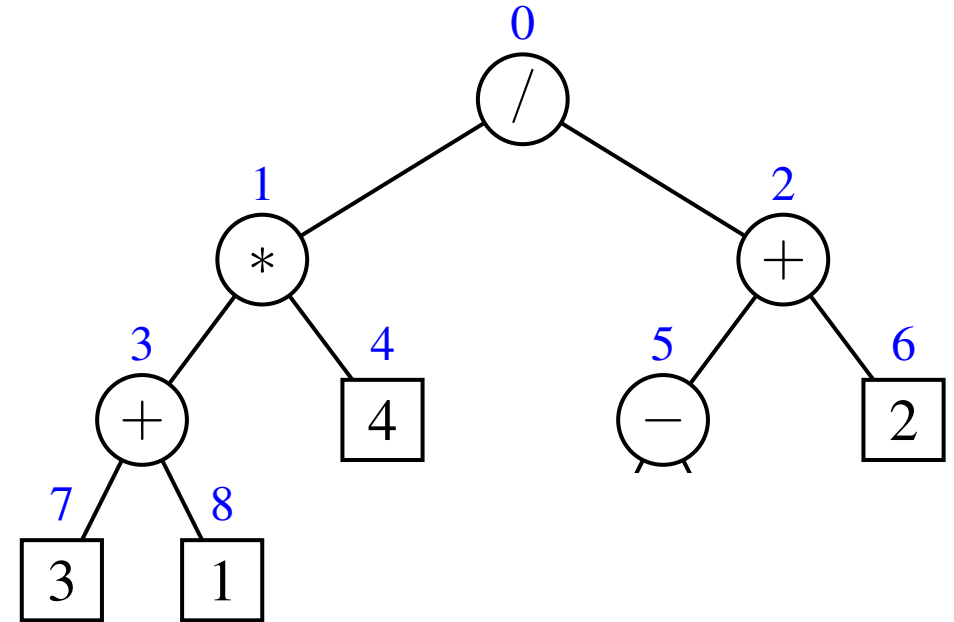
Array-based Binary Tree

- If we don't enforce any ordering properties, then we can ensure the tree is complete
- **Complete tree** – every level is full, except for the last and all nodes in the last level are as far left as possible



Array-based Binary Tree

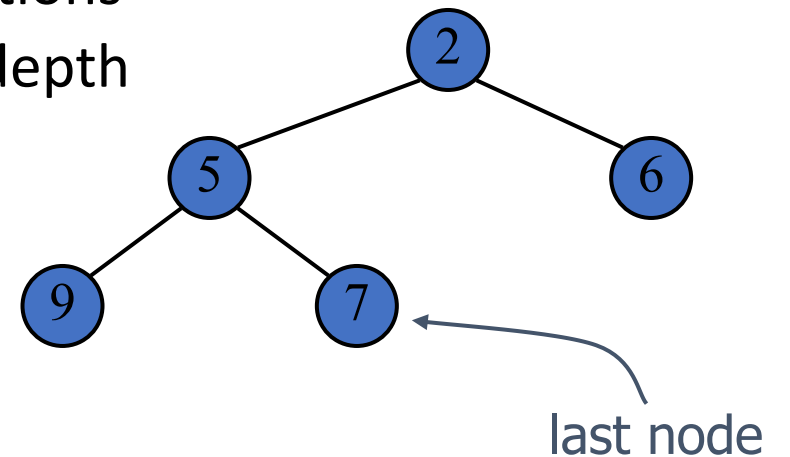
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Binary Heap

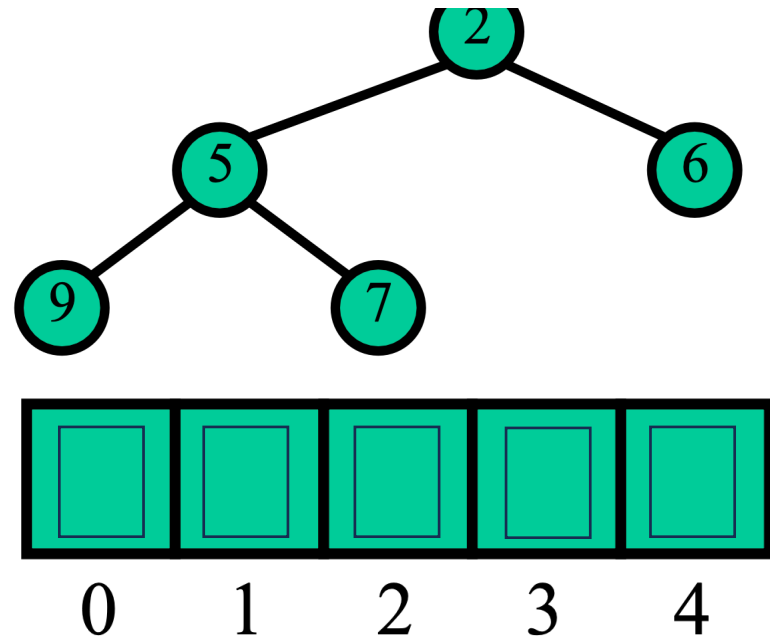
Binary tree storing keys at its nodes and satisfying:

1. heap-order: for every internal node v other than root, $key(v) \geq key(parent(v))$
2. complete binary tree: let h be the height of the heap
 - there are 2^i nodes of depth i , $0 \leq i \leq h - 1$
 - at depth h , the leaf nodes are in the leftmost positions
 - last node of a heap is the rightmost node of max depth



Array based heap

Array/ArrayList of length n
for heap with n keys

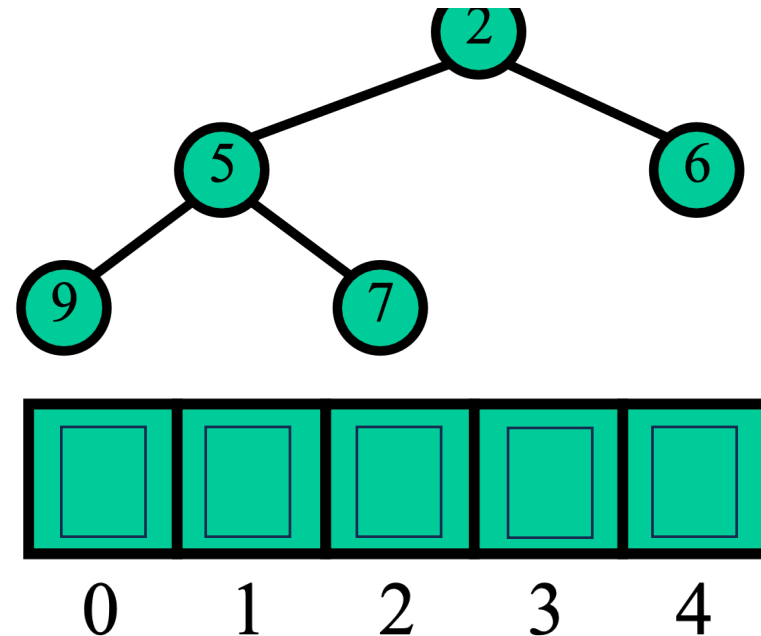


Array based heap

Array/ArrayList of length n
for heap with n keys

Node at index i

- Left child index:
 - $2i + 1$
- Right child index:
 - $2i + 2$



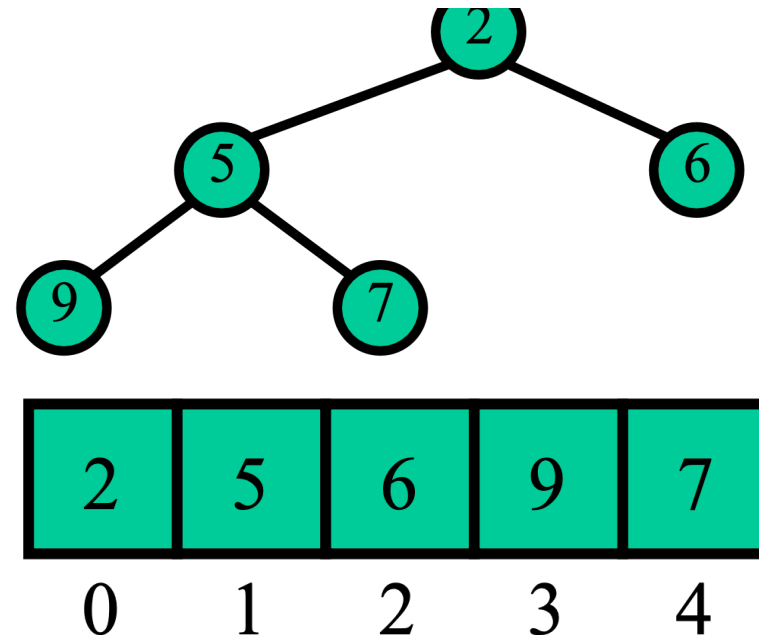
Array based heap

Array/ArrayList of length n
for heap with n keys

Node at index i

- Left child index:
 - $2i + 1$
- Right child index:
 - $2i + 2$

- Peek:
 - Get element at index 0
- Poll:
 - Remove element at index 0
- No need to store references/links



Binary Tree Interface

```
public interface BinaryTree<E extends Comparable<E>>
{
    E getRootElement();
    int size();
    boolean isEmpty();
    boolean contains(E element);
    void insert(E element);
    boolean remove(E element);
    String toStringInOrder();
    String toStringPreOrder();
    String toStringPostOrder();
}
```

Array Based Binary Tree

```
public class ArrayBinaryTree<E extends Comparable<E>>
implements BinaryTree<E>{
    public static final int CAPACITY=1000;
    //instance variables?
    private int size;
    private E[] data;
    public ArrayBinaryTree() {
        // what would our constructor look like?
    }
    //E getRootElement();
    //int size();
    //boolean isEmpty();
}
```

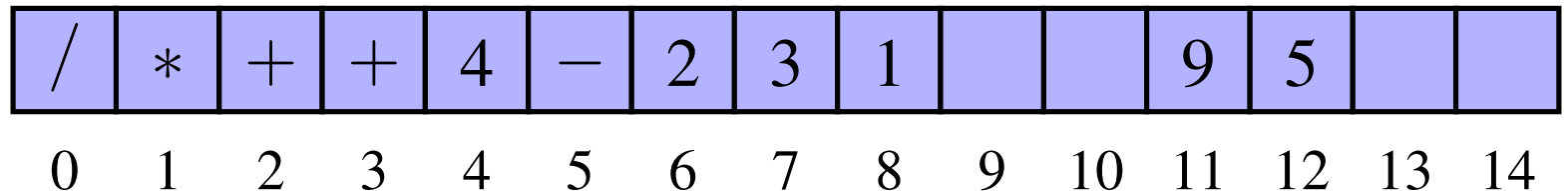
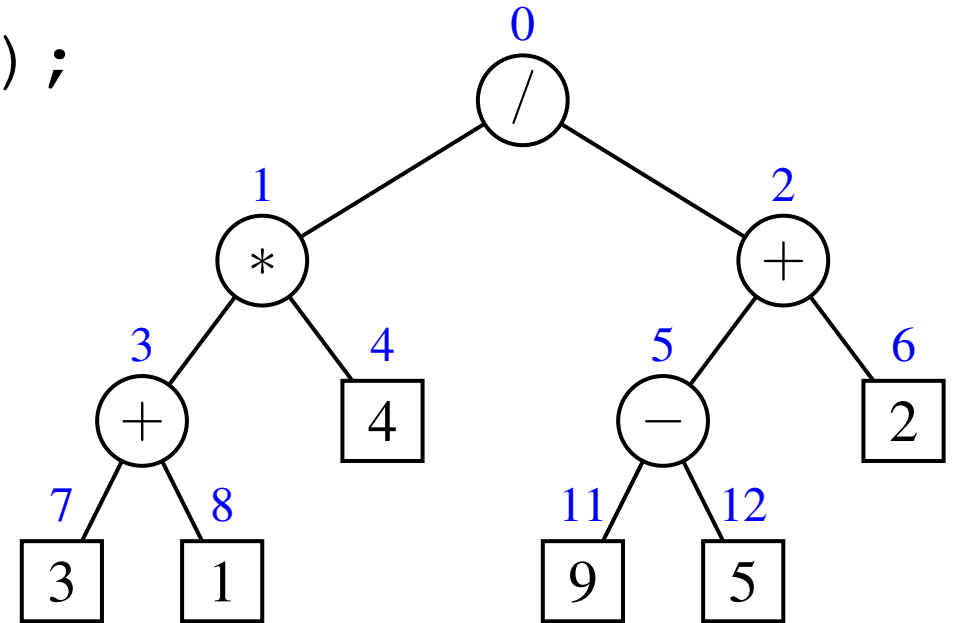
Array Based Binary Tree

```
public class ArrayBinaryTree<E extends Comparable<E>>
implements BinaryTree<E>{
    public static final int CAPACITY=1000;
    //instance variables?
    private int size;
    private E[] data;
    public ArrayBinaryTree(){
        data = (E[]) new Comparable[CAPACITY];
    }
    //E getRootElement();
    //int size();
    //boolean isEmpty();
}
```


Array Based Binary Tree Methods

- `boolean contains(E element);`
- `void insert(E element);`
- `boolean remove(E element);`

$$\begin{aligned}f(\text{root}) &= 0 \\f(l) &= 2f(p) + 1 \\f(r) &= 2f(p) + 2\end{aligned}$$



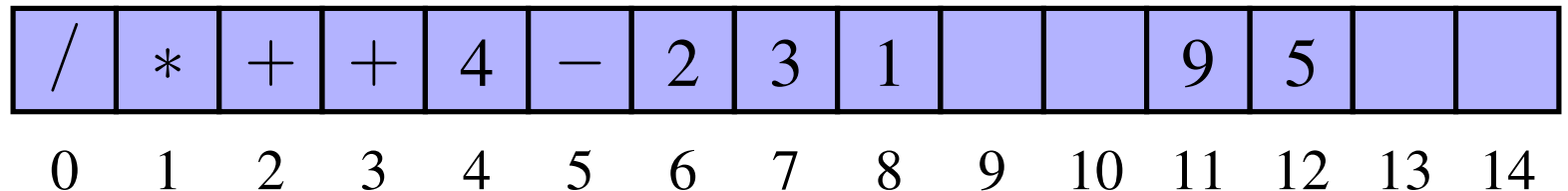
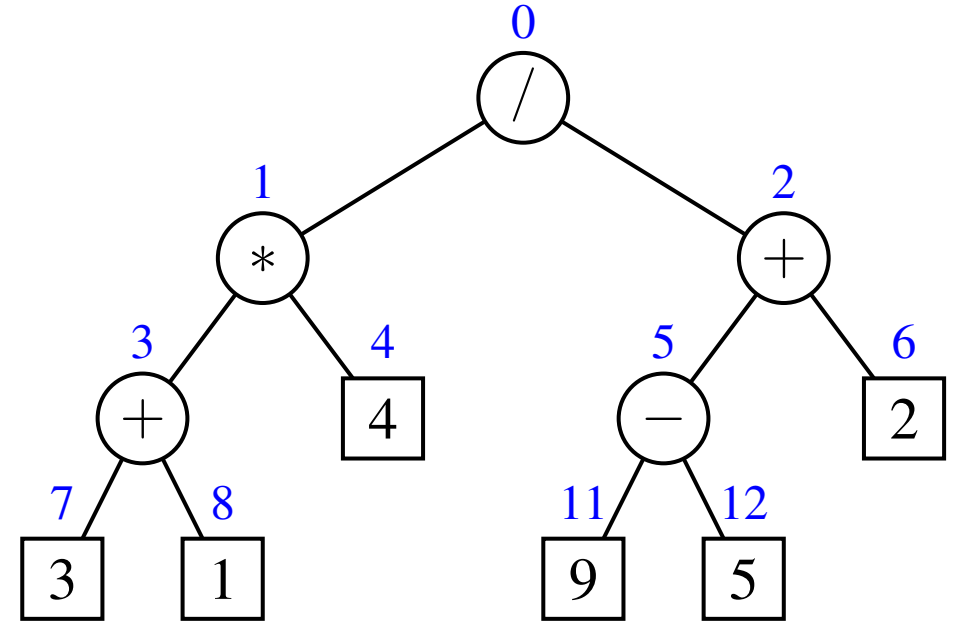
Traversals

`String toStringInorder();`

`String toStringPreorder();`

`String toStringPostorder();`

`String toStringBreadthFirst();`



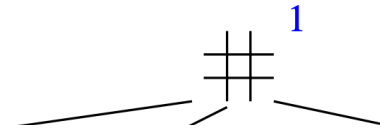
Outline

- Array Based Trees
- **Breath First Traversal**
- Array Based Heaps
- More efficient way to Construct Heaps

Breadth-First Traversal

Traverse the tree level-by-level

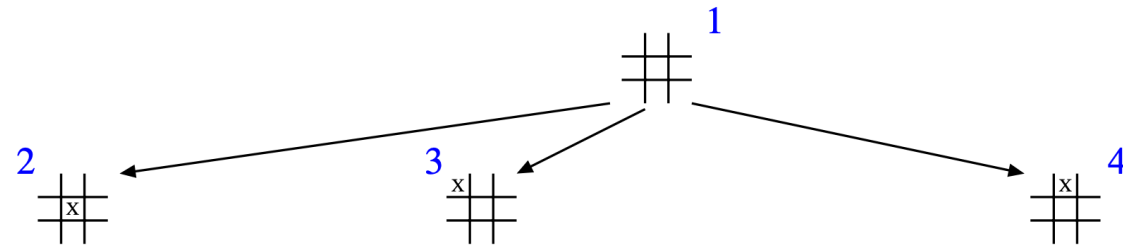
- Within a level go left-to-right



Breath-First Traversal

Traverse the tree level-by-level

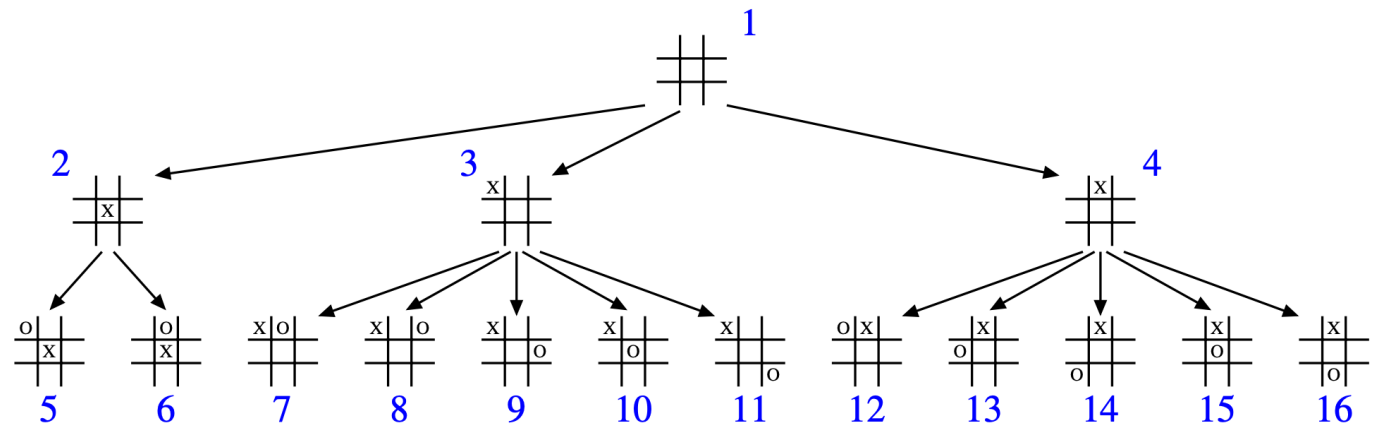
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Breath-First Traversal

Traverse the tree level-by-level

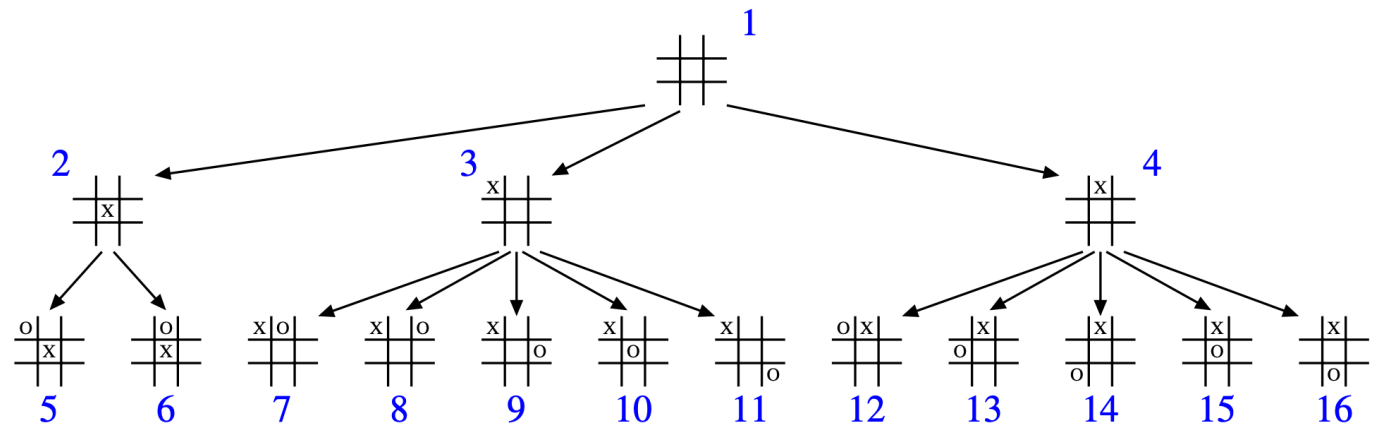
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Breath-First Traversal

Traverse the tree level-by-level

- Within a level go left-to-right

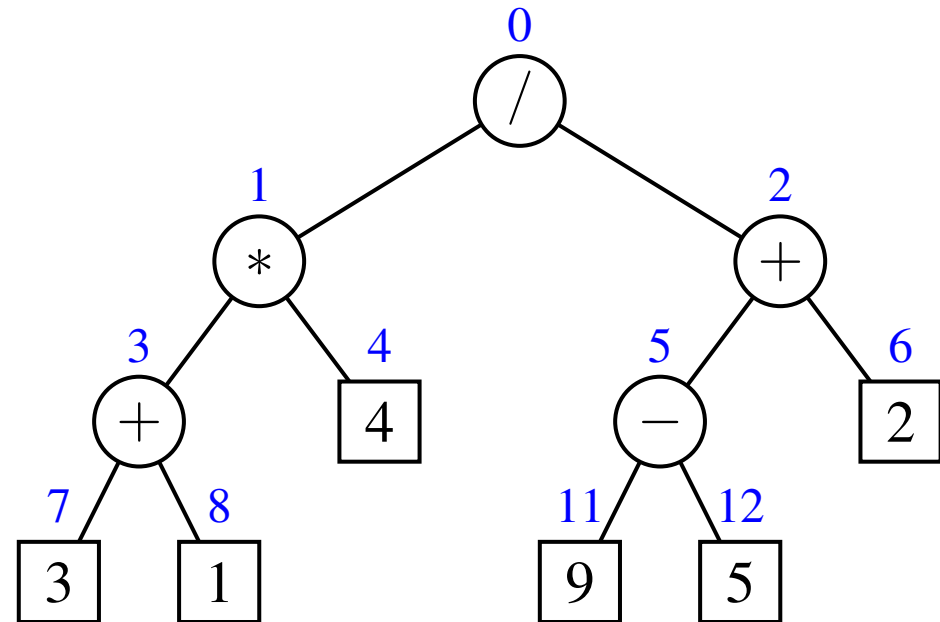


This is the array order of an array-based binary tree

Breath-First Traversal

Traverse the tree level-by-level

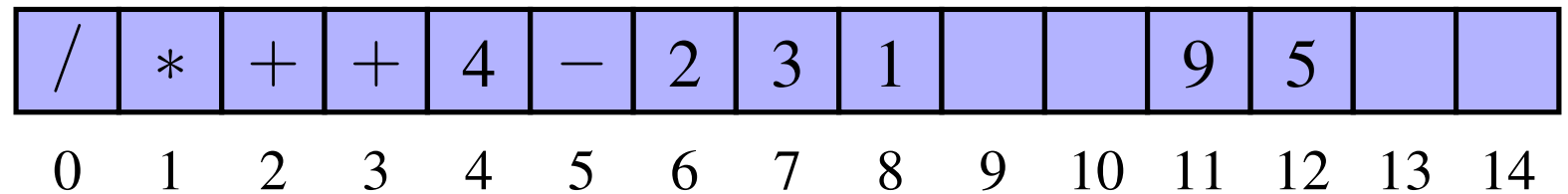
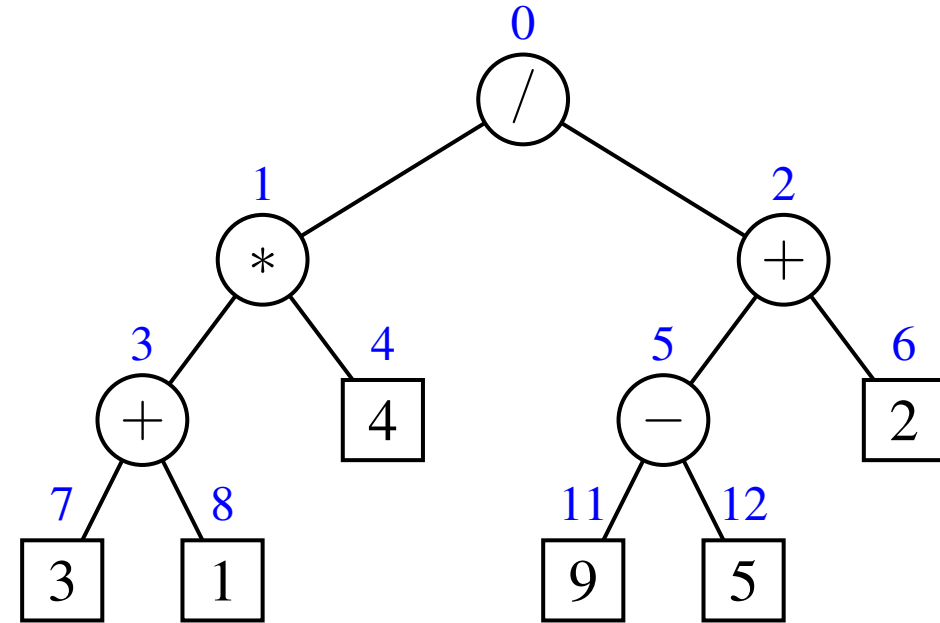
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Breath-First Traversal

Traverse the tree level-by-level

- Within a level go left-to-right



This is the array order of an array-based binary tree

Breath First Traversal Algorithms

Add root to queue

while queue is not empty:

 node n = deque()

 operate on n // in our case print or concat n

 for child c of n:

 enqueue(n)

Breath First Search Algorithm

Add root to queue

while queue is not empty:

 node n = deque()

 if n is the target:

 stop

 for child c of n:

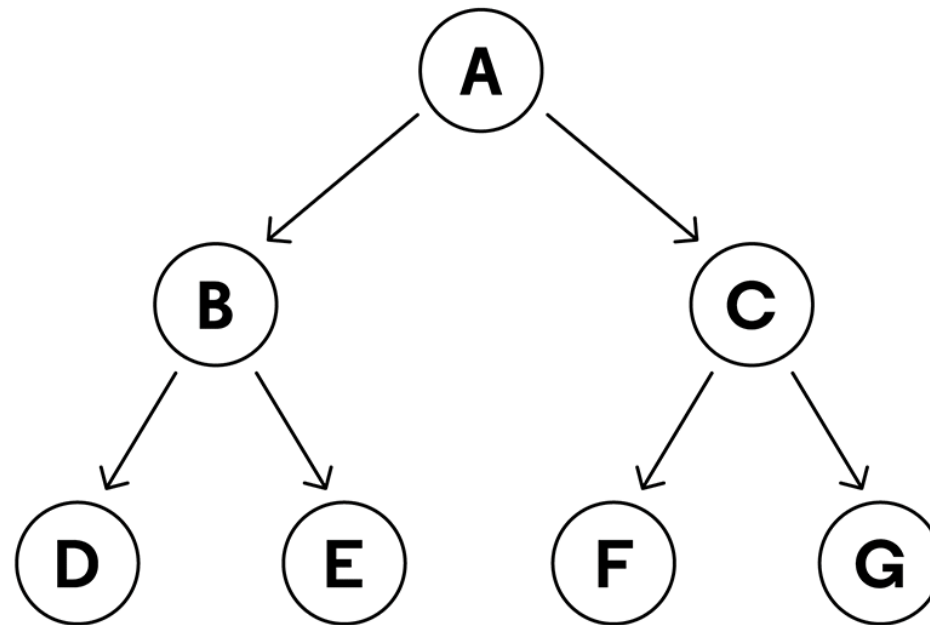
 enqueue(n)

Breath First Search in action



Frontier Queue
FIFO (First in First Out)

Tree with an Empty Queue



<https://www.codecademy.com/article/tree-traversal>

Outline

- Array Based Trees
- Breath First Traversal
- **Array Based Heaps**
- More efficient way to Construct Heaps

Helper methods for Array-based binary heap

```
int parent(int i);  
int leftChild(int i);  
int rightChild(int i);  
void swap(int i, int j);  
int containsIdx(E element);  
string toStringInOrderRec(int root);
```

PriorityQueue Interface

```
public interface PriorityQueue<E extends Comparable<E>>
    extends BinaryTree<E> {
    E getRootElement();
    int size();
    boolean isEmpty();
    boolean contains(E element);
    void insert(E element);
    boolean remove(E element);
    String toStringInOrder();
    String toStringPreOrder();
    String toStringPostOrder();
    E peek();
    E poll();
}
```

Heap-based Priority Queue

```
public class ArrayHeap<E> extends Comparable<E>>
    extends ArrayBinaryTree<E> implements
    PriorityQueue<E>{
    //instance variables?
    //constructor, getters, setters
    //inherited methods
    E peek();
    E poll();
}
```


Inherited Methods from ArrayBinaryTree

```
E getRootElement();  
int size();  
boolean isEmpty();  
boolean contains(E element);  
void insert(E element);  
boolean remove(E element);  
String toStringInOrder();  
String toStringPreOrder();  
String toStringPostOrder();
```

Inherited Methods from ArrayBinaryTree

```
E getRootElement();  
int size();  
boolean isEmpty();  
boolean contains(E element);  
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boolean remove(E element);  
String toStringInOrder();  
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String toStringPostOrder();
```

Updating Key (Priority of an element)

What should happen when you change the key of an existing element in a heap?

What are the cases?

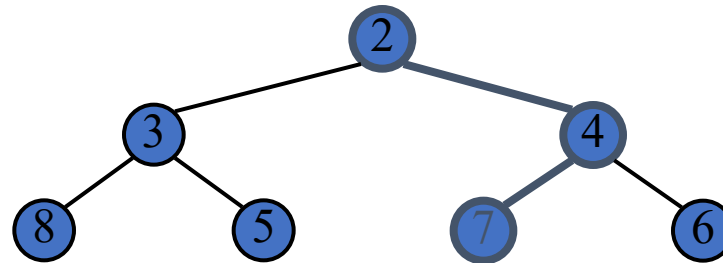
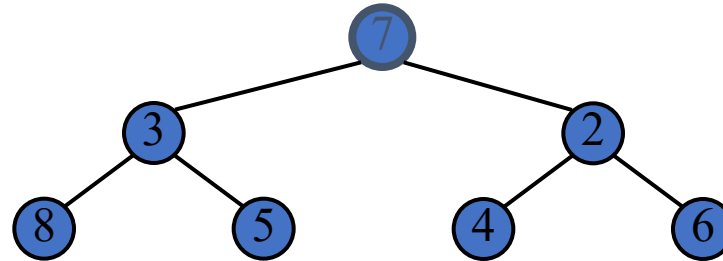
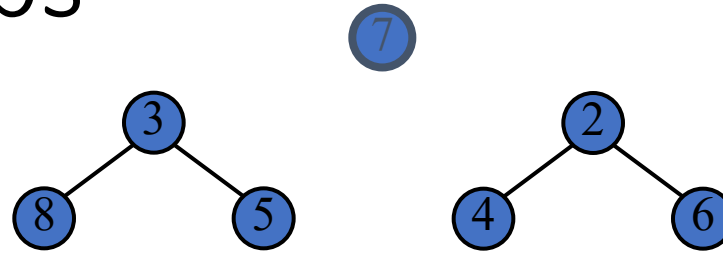
- increaseKey
- decreaseKey

Outline

- Array Based Trees
- Breath First Traversal
- Array Based Heaps
- **More efficient way to Construct Heaps**

Merging Two Heaps

- We are given two two heaps and a key k
- We create a new heap with the root node storing k and with the two heaps as subtrees
- We perform downheap to restore the heap-order property



Inserting n elements in a Heap (Construction)

Time complexity of making a heap with n elements:

- Call insert n times:
 - $O(n \log(n))$

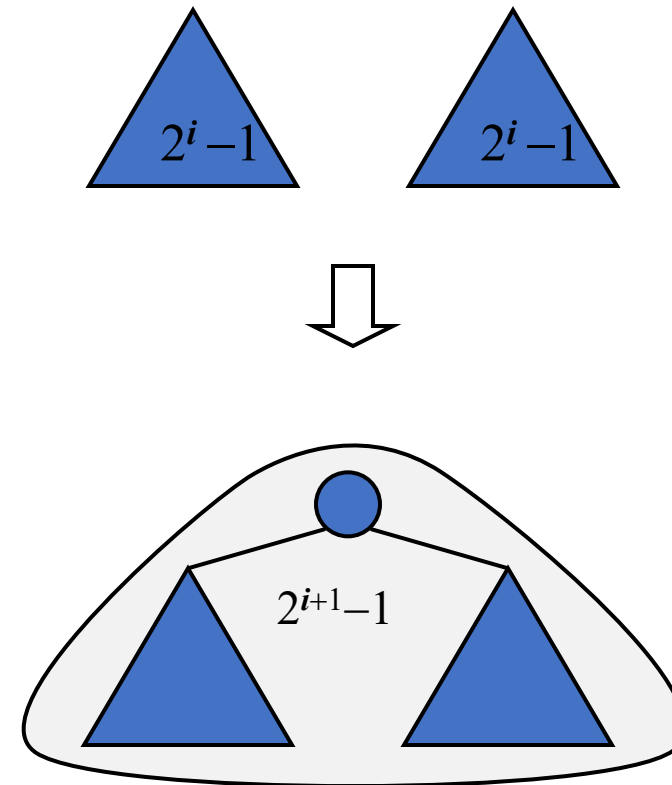
More efficient alternative:

- merge & conquer!
- Bottom-up approach
 1. construct $(n+1)/2$ elementary heaps storing one entry each
 2. merge pairwise into $(n+1)/4$ larger heaps

Bottom-up Heap Construction



- We can construct a heap storing n given keys using a bottom-up construction with $\log n$ phases
- In phase i , pairs of heaps with $2^i - 1$ keys are merged into heaps with $2^{i+1} - 1$ keys



Example

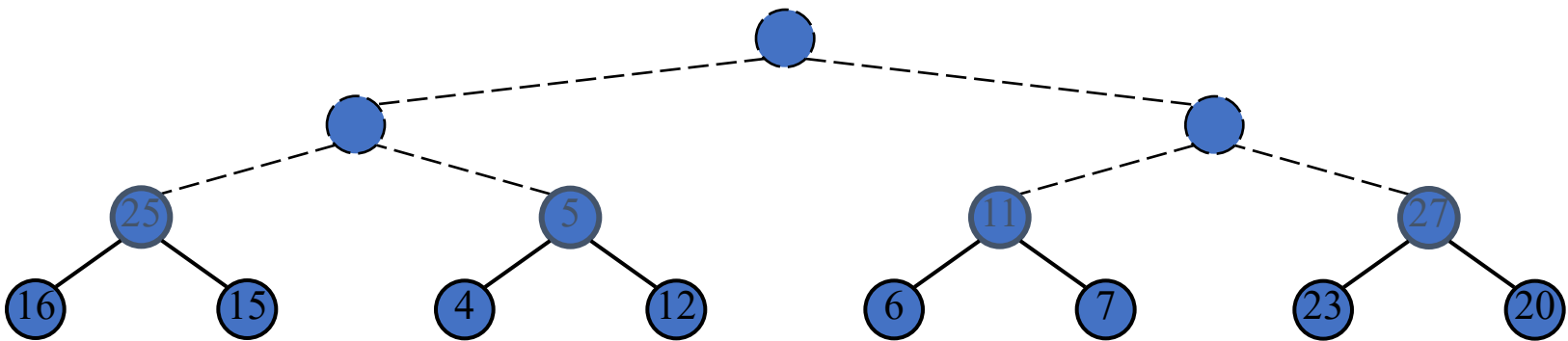
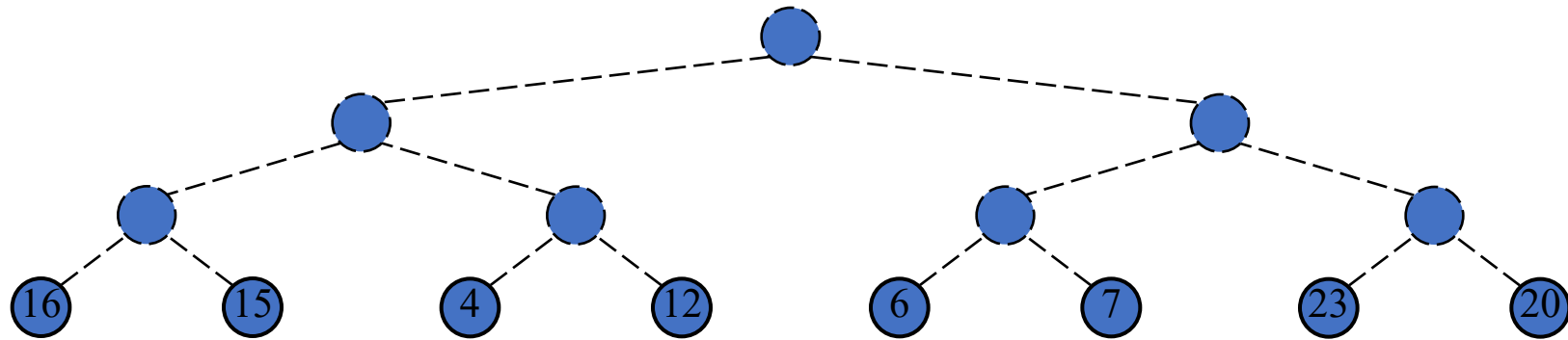
Lets insert 15 numbers: 4, 16, 25, 7, 15, 10, 12, 8, 11, 9, 6, 27, 23, 20, 5

What will the height of the tree be?

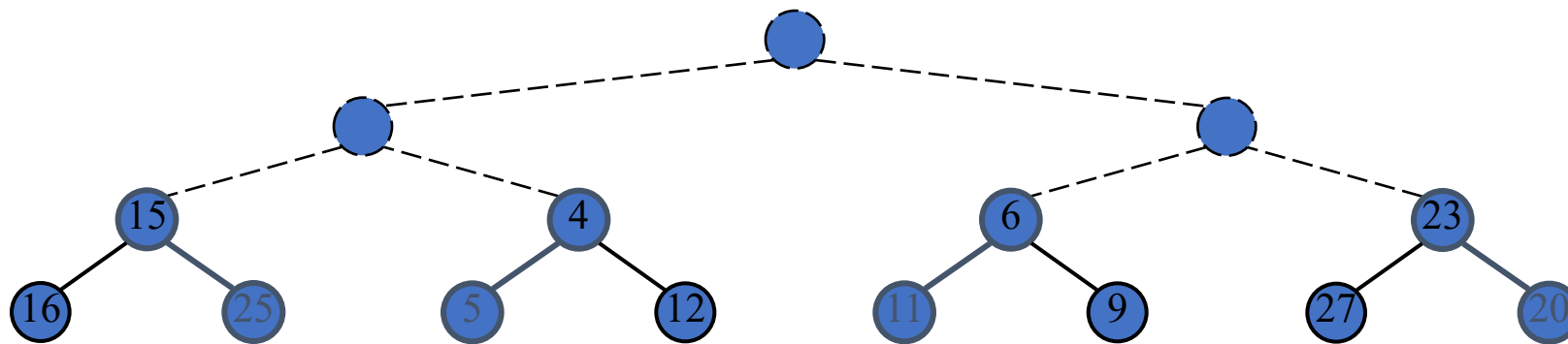
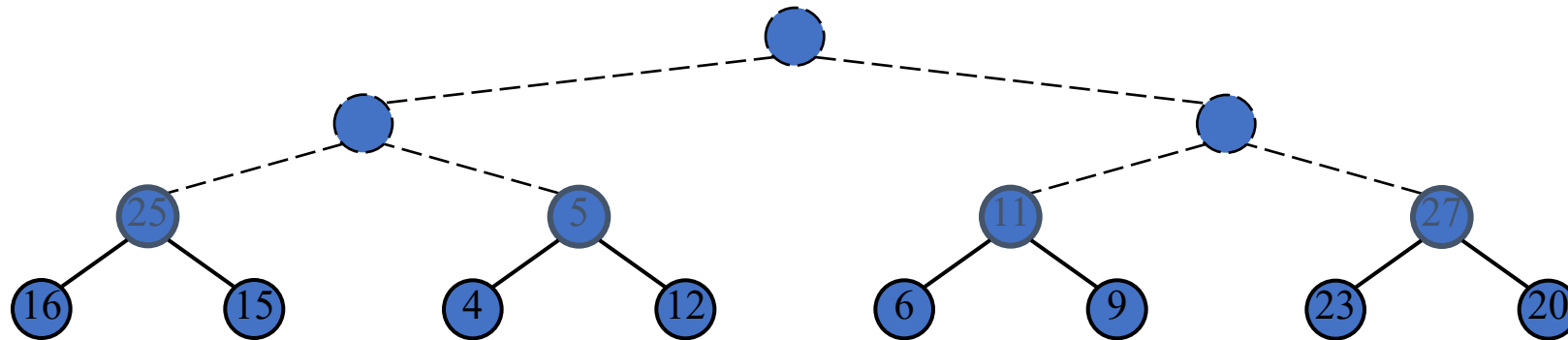
Whats the first step:

Bottom up:

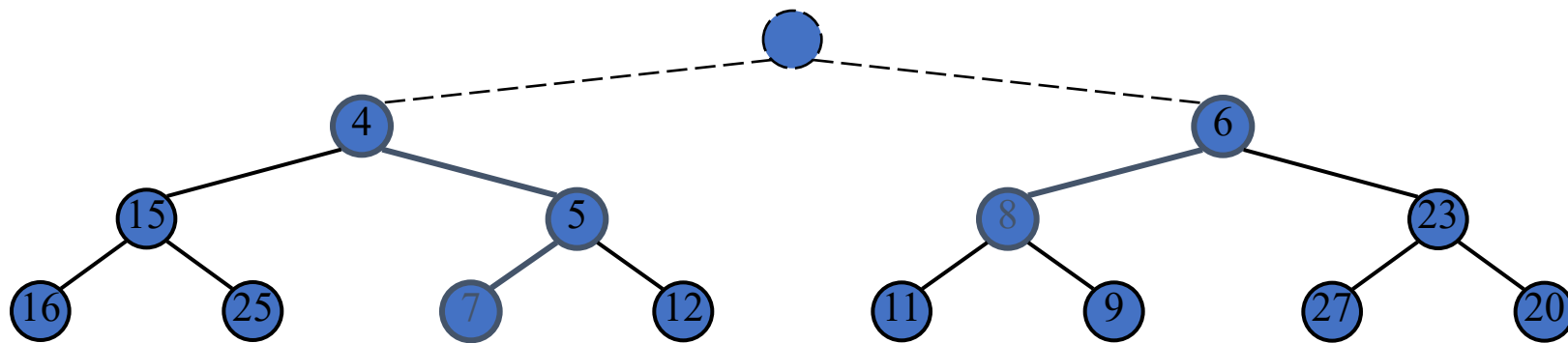
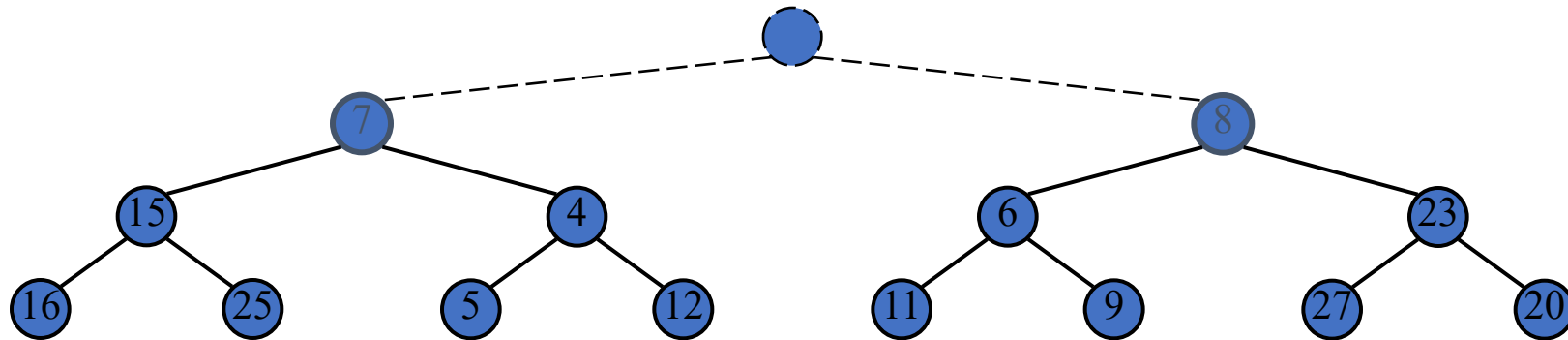
Example



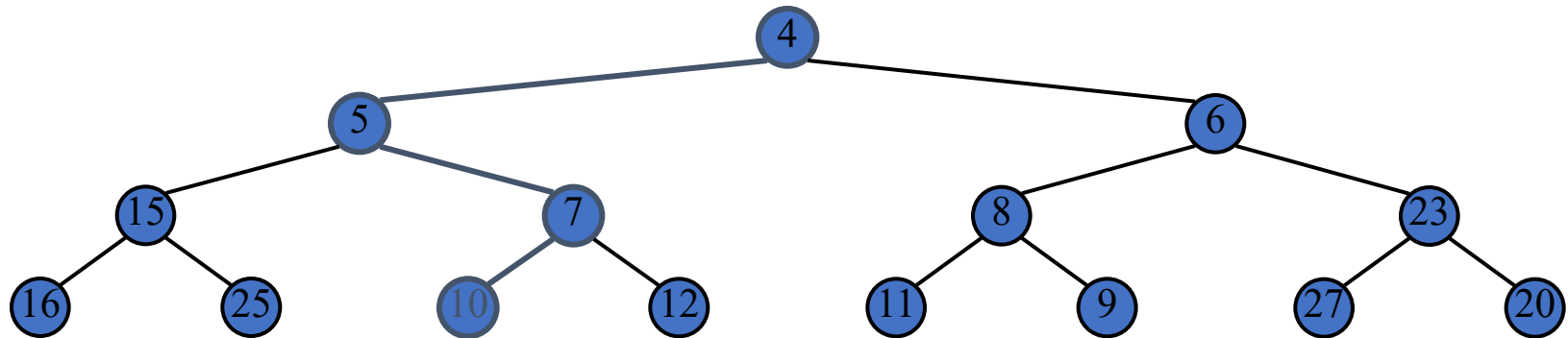
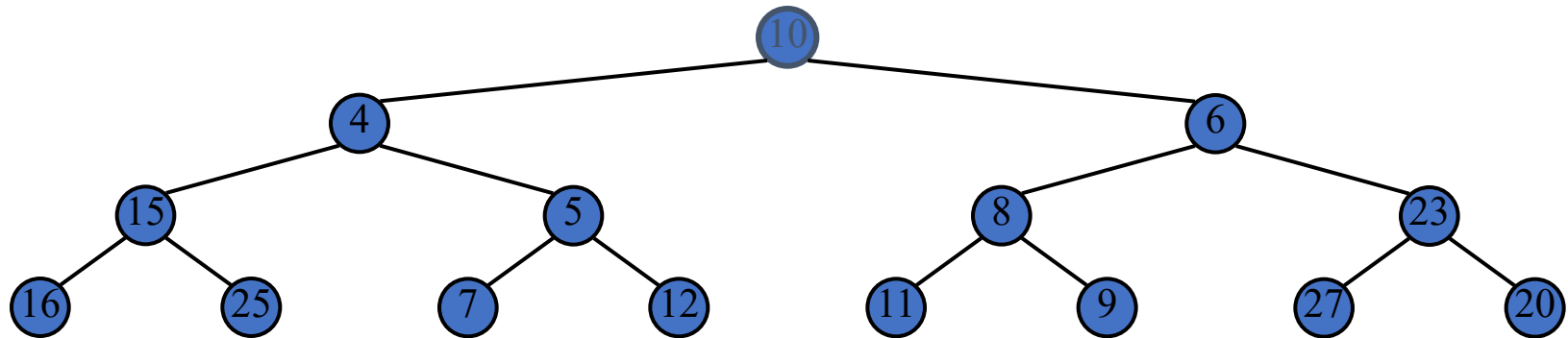
Example (contd.)



Example (contd.)



Example (end)



Runtime Analysis

$$n/4 + n/8 + n/16 + \dots +$$

$$1 = O(n) \text{ merges}$$

Each merge is $O(\log n)$ (because we need to fix heap order when merging)

Runtime Analysis

- Complexity of merge depends on the height of the tree - generally $O(\log(n))$
- height only reaches full $O(\log(n))$ on the last merge. All other heaps are shorter
- In fact, half of the heaps have height 0
- Tighter analysis (with a fair bit more math) shows $O(n)$