CS340 Analysis of Algorithms

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Sample description, pseudo code and proof of correctness for Dijkstra's shortest path algorithm. Please refer to lecture notes for details of the algorithm design and time analysis. Recall that given a directed graph G = (V, E), with associated edge weights w(u, v) for each edge $(u, v) \in E$, and a source vertex $s \in V$, we want to compute the shortest path from s to all vertices in V.

1 Description

The key idea of Dijstra's is to maintain an estimate of the shortest path length d[v] for each vertex v from s, stored in an array d indexed by the vertices. The algorithm updates these estimates as it processes more and more vertices, a process known as relaxation. Every iteration, the algorithm will select the unvisited vertex u with the smallest known distance from s, i.e. d[u] is minimum, mark it visited, and update the estimate of all of its neighbors, by comparing the existing estimate d[v] of a neighbor v (note that d[v] currently stores the best known shortest path from s to v without going through u) with the distance of going from s through u to v and update if necessary. A priority queue keyed by each d[u] is used to keep track of which vertex to process next.

2 Pseudocode

```
Function Dijkstra(G = (V, E), s)
for each u \in V do
 | d[u] = \infty
end
d[s] = 0
Q = priority queue of all vertices u keyed by d[u]
while Q is not empty do
   u = extractMin from Q
   for each v \in Adj[u] do
      // if going through u to v is shorter
       if d[u] + w(u, v) < d[v] then
          d[v] = d[u] + w(u, v)
          decrease v's key value in Q to d[v]
       end
   end
end
```

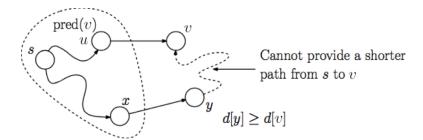
3 Correctness Proof

Termination is easily argued because the set Q is finite and we delete at least one vertex in each iteration of the while loop. The inner for loop also teriminates because G is finite.

We prove the optimality of Dijstra's by showing that the estimates are computed correctly for all processessed (visited) vertices. Let $\delta(s,v)$ denote the length of the true shortest path from s to v. Lemma: $d[v] = \delta(s,v)$, $\forall v \in S$, where S is the visited/processed set by Dijkstra's **Proof**: by induction.

- Base case: |S|=1, S consists of only the source vertex s. We set d[s] to 0 and $\delta(s,s)=0$.
- IH: assume that $d[v] = \delta(s,v)$, $\forall v \in S$, where |S| = k
- Want to show: lemma holds for |S| = k+1, that is, the d[v] of the next vertex added to S is also computed correctly.

Let v be the next vertex added to S, along with edge (u,v). Note that u must be a vertex already in S, because otherwise the shortest path will be disconnected. We argue that the true shortest path from s to v must be d[u]+w(u,v). Suppose this is not true, and let us consider any other $s \longrightarrow v$ path P. Note that no matter which edges P uses, because $v \notin S$, P must have an edge that goes across the cut from S to $V \setminus S$. Let (x,y) be the first edge taken by P where $x \in S$ and $y \in V \setminus S$. Note that it may be that x = s and/or y = v, but u and x must be distinct.



By the IH, u and x are both correctly processed and therefore $d[u] = \delta(s,u)$ and $d[x] = \delta(s,x)$ and in addition, because relaxations were applied when processing u and x, d[y] = d[x] + w(x,y) and d[v] = d[u] + w(u,v). By construction, because Dijkstra's selected u and not y as the next vertex to process, we must have $d[v] \le d[y]$. Therefore, we have

$$\delta(s,v) \le d[v] \le d[y] = \delta(s,y)$$

With a d[y] already greater than d[v], and we know that G does not contain any edges with negative weights, there is no way for us to construct a P that connects s to y then to v that can achieve a total length shorter than d[v]. Thus we have our contradiction.