CS340 - Analysis of Algorithms

Review: Discrete Math, Complexity, and Graphs

Logistics:

Office hours:

- Alternating Tuesday and Thursdays 7--9pm
- Cecilia will post each week on Piazza

Join the piazza and gradescope if you have not already

Make sure you have a goldengate account

- Email David Diaz ddiaz1@brynmawr.edu if you encounter issues

Upcoming deadlines:

Lab0 due tomorrow

HW1 due Monday (9/15)

Lab1 tomorrow

Quiz next class

Agenda

1. Stable matching algorithm review

2. Some math review

3. Complexity

4. Data structures

5. Graphs

Proof of Correctness:

For this algorithm to be correct, it must produce a perfect and stable matching.

A matching is perfect if every element of X and Y occurs in some pair.

Proof by contradiction:

suppose there is some employer e who was not matched.

```
Function findStableMatching (E, A)
   All e \in E and a \in A are unpaired
   while there is an e unpaired that hasn't made an offer to every a do
      choose such an e
      let a be the highest-ranked applicant in e's preference list who e has not
      made an offer to yet
      if a is unpaired then
          pair a and e
      end
      else
          a is currently paired with e'
          if a prefers e' to e then
             e remains unpaired
          end
          else
             a is paired with e and e' becomes unpaired
          end
      end
   end
   return the set of pairs
```

Proof of Correctness:

Proof of stability by contradiction: Suppose there exists some e and some a' such that e prefers a' to its match a and a' prefers e to its match e.

Either: (1) e never offered a job to a' or (2) a' rejected the offer

```
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Simplify the following equations:

1.
$$(3x^4y^2)(2x^3y^5)$$

2.
$$(6x^7y^5)/(2x^3y^2)$$

3.
$$((x^2y^3)/(z^4))^3$$

Exponent Rules For $a \neq 0, b \neq 0$				
Product Rule	$a^{x} \times a^{y} = a^{x+y}$			
Quotient Rule	$a^x \div a^y = a^{x-y}$			
Power Rule	$\left(a^{x}\right)^{y}=a^{xy}$			
Power of a Product Rule	$(ab)^x = a^x b^x$			
Power of a Fraction Rule	$\left(\frac{a}{b}\right)^x = \frac{a^x}{b^x}$			
Zero Exponent	$a^{0} = 1$			
Negative Exponent	$a^{-x} = \frac{1}{a^x}$			
Fractional Exponent	$a^{\frac{x}{y}} = \sqrt[y]{a^x}$			

Logarithms

1.
$$\log(5x) + \log(2y)$$

2.
$$\log(100) - \log(4)$$

3.
$$3 \cdot \log(x) - \frac{1}{2} \cdot \log(y)$$

Logarithmic Properties				
Product Rule	$\log_a(xy) = \log_a x + \log_a y$			
Quotient Rule	$\log_a \left(\frac{x}{y}\right) = \log_a x - \log_a y$			
Power Rule	$\log_a x^p = p \log_a x$			
Change of Base Rule	$\log_a x = \frac{\log_b x}{\log_b a}$			
Equality Rule	If $\log_a x = \log_a y$ then $x = y$			

Polynomials

$$f(n) = n^c$$

- C is a constant
- Adding polynomials: combine like terms and simplify coefficients
- Example 1: $(3x^2 + 5x + 2) + (4x^2 3x + 7)$
 - $= (3x^2 + 4x^2) + (5x 3x) + (2 + 7)$
 - \circ = $7x^2 + 2x + 9$
- Example 2: $(2x^2y + 3xy^2 + y) + (5x^2y 2xy^2 + 4y)$
 - $0 7x^2y + xy^2 + 5y$

Exponentials

$$f(n) = r^n$$

- Constant base r
- Grows *much faster* than polynomials (constant factor, variable base)

Summations

Constant series

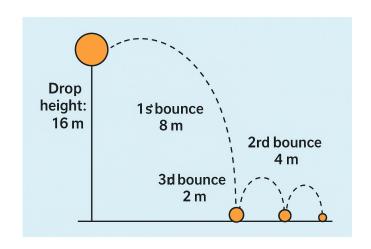
$$\sum_{i=a}^{b} 1 = \max(b - a + 1, 0)$$

Arithmetic series

$$\sum_{i=1}^{n} i = 1 + 2 + \dots + n = \frac{n(n+1)}{2} \quad O(n^2)$$

Geometric series

$$\sum_{i=0}^{n} c^{i} = 1 + c + c^{2} \dots + c^{n} = \frac{c^{n+1} - 1}{c - 1} \in \begin{cases} O(1), c < 1 \\ O(c^{n}), c > 1 \end{cases}$$



Summations

Quadratic series

$$\sum_{i=1}^{n} i^2 = 1^2 + 2^2 + \dots + n^2 = \frac{2n^3 + 3n^2 + n}{6}$$
 O(n³)

Linear-geometric series

$$\sum_{i=1}^{n} ic^{i} = c + 2c^{2} + \dots + nc^{n}$$

$$= \frac{(n-1)c^{n+1} - nc^{n} + c}{(c-1)^{2}}$$

Summations

Harmonic series

$$H_n = \sum_{i=1}^n \frac{1}{i} = 1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n} = \ln n + O(1)$$

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Now let's relate this to algorithms...

Basics of Algorithm Analysis

- Last class we discussed trade-offs between two algorithms
 - "How does algorithm 1's time and space usage grow with increasing input size?"

Table 2.1 The running times (rounded up) of different algorithms on inputs of increasing size, for a processor performing a million high-level instructions per second. In cases where the running time exceeds 10^{25} years, we simply record the algorithm as taking a very long time.

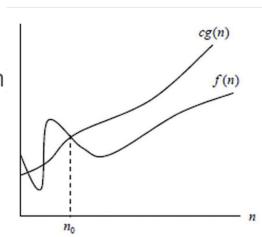
	n	$n \log_2 n$	n ²	n ³	1.5 ⁿ	2 ⁿ	n!
n = 10	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	4 sec
n = 30	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	18 min	10 ²⁵ years
n = 50	< 1 sec	< 1 sec	< 1 sec	< 1 sec	11 min	36 years	very long
n = 100	< 1 sec	< 1 sec	< 1 sec	1 sec	12,892 years	10 ¹⁷ years	very long
n = 1.000	< 1 sec	< 1 sec	1 sec	18 min	very long	very long	very long
n = 10,000	< 1 sec	< 1 sec	2 min	12 days	very long	very long	very long
n = 100,000	< 1 sec	2 sec	3 hours	32 years	very long	very long	very long
n = 1,000,000	1 sec	20 sec	12 days	31,710 years	very long	very long	very long

Big O

Big O notation expresses Asymptotic Upper Bounds

"If f(n) doesn't grow faster than g(n), up to a constant factor, for large enough n."

If $\exists n_0 \ge 0, c > 0 : f(n) \le c \cdot g(n) \ \forall n \ge n_0 \text{ then } O(f(n)) = g(n)$



Basics of Algorithm Analysis

- Q: Why do we simplify to only keep the dominant term in Big-O notation?
 - Worst case run time of 2n expressed as O(n)
 - Worst case run time of n² + 3n expressed as O(n²)
- A:
 - We'd like to classify run times at a coarse level of granularity so we can see similarities among different algorithms
 - Number of steps is arbitrary (language and machine dependant)

What is the Asymptotic Upper Bound of each of these functions? Write in Big-O notation

1.
$$f_2(x) = 15x^2 + 7x \log^3 x$$

= $O(x^2)$

2.
$$f_1(x) = 43x^2 \log^4 x + 12x^3 \log x + 52x \log x$$

= $O(x^3 \log x)$

3.
$$f_3(x) = 3x + 4 \log_5 x + 91x^2$$

= $O(x^2)$

4.
$$f_4(x) = 13 \cdot 3^{(2x+9)} + 4x^9$$

= $O(9^{x})$

5.
$$f_5(x) = \sum (\text{from } x=0 \text{ to } \infty) \frac{1}{2}x$$

= O(1)

Basics of Algorithm Analysis

- Sublinear time: O(logn) algorithms where we can throw away a constant fraction of the input with each step of the algorithm
 - Binary search
 - Queries in a balanced BST
- Linear Time Algorithms: O(n) run time is at most a constant factor times the input size
 - Process the input in a single pass spending constant time on each item
 - o min/max algorithm, linear search
- O(nlogn): Sorting algorithms
- Quadratic time: O(n²) nested loops
 - Processing all pairs in a list (every employer and every applicant
- Polynomial time: O(nk)
 - Consider all subsets of size k
- Exponential time: O(2ⁿ)
 - All subsets of a set of size n
- Factorial time: O(n!)
 - Number of ways to match n items with eachother

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Asymptotic Upper Bound of Common Operations

	Access	Search	Insertion	Deletion
Array				
Linked List				
Stack				
Queue				
BST				
AVL Tree				
Hash Map				

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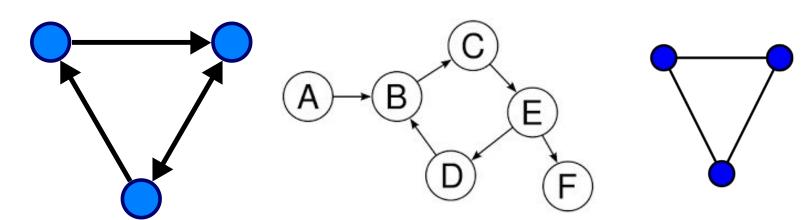
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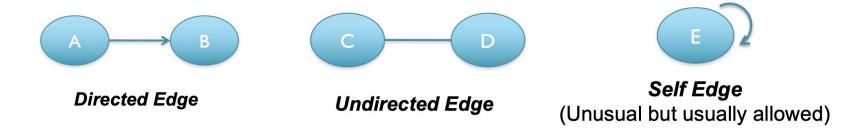
Graphs

- A way of representing relationships between pairs of objects
- Consist of Vertices (V) with pairwise connections between them
 Edges (E)
- A Graph G is a set of vertices and edges (V, E)

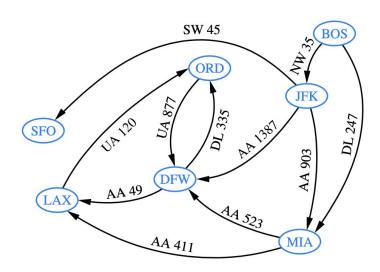


Edges

- An edge (u, v) connects vertices u and v
- Edges can be directed or undirected
- An edge is said to be incident to a vertex if the vertex is one of the endpoints
- The degree of a vertex deg(v) is
 - the number of incident edges on v if in an undirected graph
 the number of outgoing edges in a directed graph



Directed vs Undirected Graphs



Example of a directed graph representing a flight network.

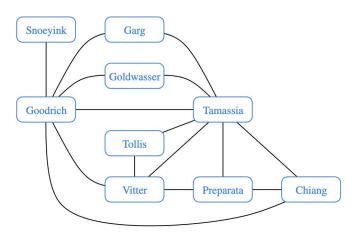
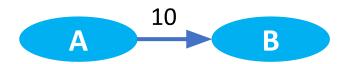


Figure 14.1: Graph of coauthorship among some authors.

Weighted Graphs

Edges have weights/costs



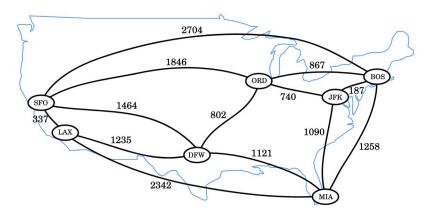
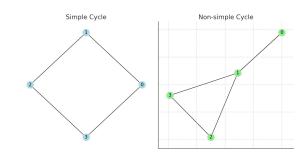


Figure 14.14: A weighted graph whose vertices represent major U.S. airports and whose edge weights represent distances in miles. This graph has a path from JFK to LAX of total weight 2,777 (going through ORD and DFW). This is the minimum-weight path in the graph from JFK to LAX.

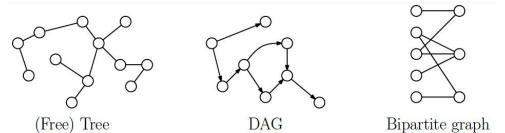
More terminology

- A path in a graph is a sequence of vertices $\langle v_0, ..., v_k \rangle$ such that (v_{i-1}, v_i) is an edge for i = 1, ..., k
- The *length* of a path is the number of edges, k.
- A *cycle* is a path containing at least one edge and for which $v_0 = v_k$
- A cycle is simple if its edges and vertices (except for v_0 and v_k) are distinct.



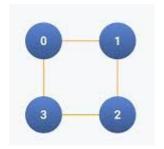
More terminology

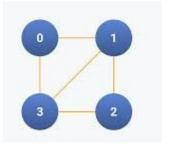
- An acyclic graph contains no simple cycles
- An acyclic connected graph is a tree
- The vertices of a *bipartite* graph can be partitioned into two disjoint subsets, V_1 and V_2 such that all edges have one endpoint in V_1 and the other one in V_2

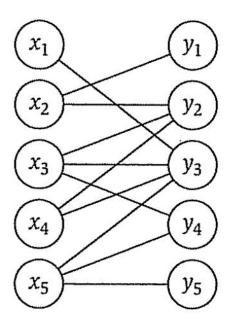


Bipartite Graphs

Is this graph bipartite?







Basic Graph Combinatorics

For an undirected graph:

•
$$|E| = 0 \le m \le \binom{n}{2}$$

$$\bullet = \frac{n(n-1)}{2} \in O(n^2)$$

•
$$\sum_{v \in V} \deg(v) = 2m$$

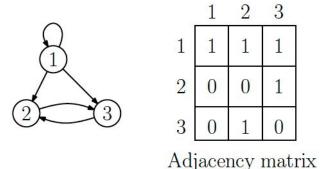
Basic Graph Combinatorics

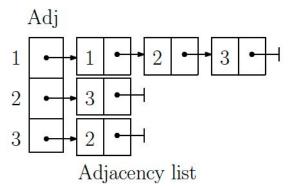
For a directed graph:

- $\bullet |E| = 0 \le m \le n^2 n$
- $\in O(n^2)$
- $\sum_{v \in V} \operatorname{indeg}(v) = m$
- $\sum_{v \in V} \text{outdeg}(v) = m$

Representing a graph

- Adjacency matrix: An $n \times n$ matrix defined for $1 \le (u, v) \le n$: A[u, v] = 1 if $(u, v) \in E$
- Adjacency list: An array of pointers where for $1 \le v \le n$, Adj[v] points to a list containing the vertices that are adjacent to v





Representing a graph - Adjacency List

Runtime Complexity: (In terms of V and E

- addVertex:
 - O(V)
- addEdge:
 - O(E)
- removeVertex:
 - O(V*E)
- removeEdge:O(E)

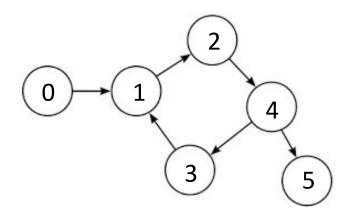
Representing a graph

Adjacency Matrix -

each index in the array is another array

Maintains an VxV matrix

where each slot (i,j) represents an outgoing edge from i to j



1				
	1			
			1	
1				
		1		1

Representing a graph - Adjacency Matrix

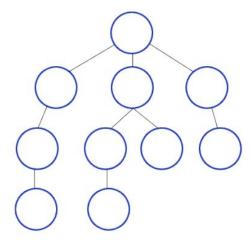
Runtime Complexity: (In terms of V and E)

- addVertex:
 - O(V^2) if we need to expand
- addEdge:
 - 0(1)
- removeVertex:
 - O(V^2)
- removeEdge:
 - O(1)

Graph Traversals

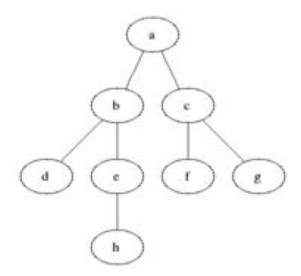
Depth First Search (DFS)

- start at root node and explore as far as possible along each branch
- Pre-order, in-order, and post-order traversals are DFS



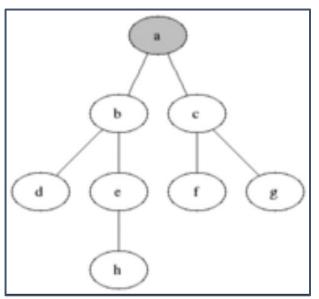
Breadth First Search (BFS)

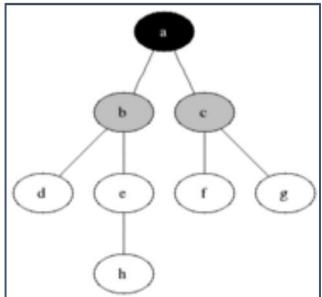
- Starts at the root and explores all nodes at the present "depth" before moving to nodes on the next level
- Extra memory is usually required to keep track of the nodes that have not yet been explored

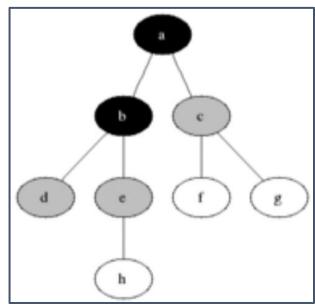


Breadth-First Traversal

pseudo-code?

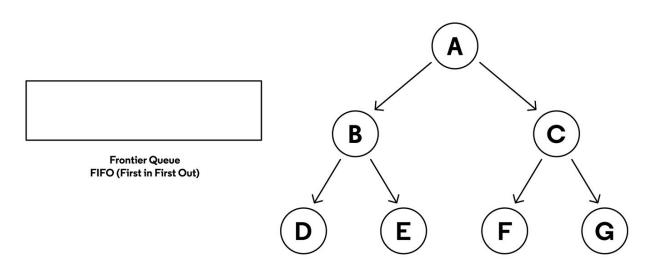






Breadth First Search (BFS)

Tree with an Empty Queue



https://www.codecademy.com/article/tree-traversal

Runtime Analysis of BFS

```
|V| = n, |E| = m
1. Initialization:
a. O(n)
```

- 2. Traversal
 - a. While-loop: we visit each vertex once
 - b. Nested for-loop: we visit each child of that vertex
 - i. Number of iterations depends on the degree

$$T(n) = n + \sum_{u \in V} (deg(u) + 1)$$

$$= n + (\sum_{u \in V} deg(u)) + n = 2n + \sum_{u \in V} deg(u)$$

$$= 2n + 2m$$

$$= O(n + m)$$

Summary

- 1. Know the following:
 - a. Exponent, logarithm, and summation rules and how to simplify equations
 - b. Growth rate of classes of algorithms (logn grows slower than n which grows slower than n^2...)
 - c. Asymptotic Upper Bound of functions (given a function write in Big-O notation)
 - d. Data structures asymptotic upper bound of basic operations
 - e. Graphs know terminology, basic rules, how to represent them, and traversal algorithms
- 2. Upcoming deadlines:
 - a. Lab 0 due tomorrow
 - b. HW1 due Sep 15th (next Monday)
 - c. Continue reading textbook

- 3. Next class: more basics of algorithmic analysis
 - a. Quiz on basic math rules, complexity, and DS review