

概率推理

重要公式

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Let \mathbf{X} be all the variables. Typically, we want the posterior joint distribution of the query variables \mathbf{Y} given specific values \mathbf{e} for the evidence variables \mathbf{E}

Let the hidden variables be $\mathbf{H} = \mathbf{X} - \mathbf{Y} - \mathbf{E}$

Then the required summation of joint entries is done by summing out the hidden variables:

$$P(\mathbf{Y}|\mathbf{E}=\mathbf{e}) = \alpha P(\mathbf{Y}, \mathbf{E}=\mathbf{e}) = \alpha \sum_{\mathbf{h}} P(\mathbf{Y}, \mathbf{E}=\mathbf{e}, \mathbf{H}=\mathbf{h})$$

条件独立性

Conditional independence

Write out full joint distribution using chain rule:

$$\begin{aligned}
 & \mathbf{P}(\textit{Toothache}, \textit{Catch}, \textit{Cavity}) \\
 &= \mathbf{P}(\textit{Toothache} | \textit{Catch}, \textit{Cavity}) \mathbf{P}(\textit{Catch}, \textit{Cavity}) \\
 &= \mathbf{P}(\textit{Toothache} | \textit{Catch}, \textit{Cavity}) \mathbf{P}(\textit{Catch} | \textit{Cavity}) \mathbf{P}(\textit{Cavity}) \\
 &= \mathbf{P}(\textit{Toothache} | \textit{Cavity}) \mathbf{P}(\textit{Catch} | \textit{Cavity}) \mathbf{P}(\textit{Cavity})
 \end{aligned}$$

I.e., $2 + 2 + 1 = 5$ independent numbers (equations 1 and 2 remove 2)

In most cases, the use of conditional independence reduces the size of the representation of the joint distribution from exponential in n to linear in n .

Conditional independence is our most basic and robust form of knowledge about uncertain environments.

有助于减少需要储存的参量

贝叶斯公式

Bayes' Rule

Product rule $P(a \wedge b) = P(a|b)P(b) = P(b|a)P(a)$

$$\Rightarrow \text{Bayes' rule } P(a|b) = \frac{P(b|a)P(a)}{P(b)}$$

or in distribution form

$$P(Y|X) = \frac{P(X|Y)P(Y)}{P(X)} = \alpha P(X|Y)P(Y)$$

Useful for assessing **diagnostic** probability from **causal** probability:

$$P(Cause|Effect) = \frac{P(Effect|Cause)P(Cause)}{P(Effect)}$$

贝叶斯公式 · 分析因果关系

全局语义

Global semantics

“Global” semantics defines the full joint distribution as the product of the local conditional distributions:

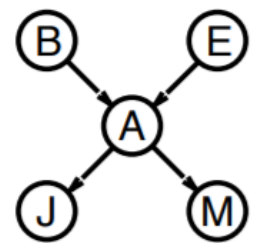
$$P(x_1, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$

e.g., $P(j \wedge m \wedge a \wedge \neg b \wedge \neg e)$

$$= P(j|a)P(m|a)P(a|\neg b, \neg e)P(\neg b)P(\neg e)$$

$$= 0.9 \times 0.7 \times 0.001 \times 0.999 \times 0.998$$

$$\approx 0.00063$$



- 构建贝叶斯网络

Need a method such that a series of locally testable assertions of conditional independence guarantees the required global semantics

1. Choose an ordering of variables X_1, \dots, X_n
2. For $i = 1$ to n
 add X_i to the network
 select parents from X_1, \dots, X_{i-1} such that
 $\mathbf{P}(X_i | \text{Parents}(X_i)) = \mathbf{P}(X_i | X_1, \dots, X_{i-1})$

This choice of parents guarantees the global semantics:

$$\begin{aligned}\mathbf{P}(X_1, \dots, X_n) &= \prod_{i=1}^n \mathbf{P}(X_i | X_1, \dots, X_{i-1}) \quad (\text{chain rule}) \\ &= \prod_{i=1}^n \mathbf{P}(X_i | \text{Parents}(X_i)) \quad (\text{by construction})\end{aligned}$$

- 由此可见，相比较原来的贝叶斯网络多了两条边。因此在构建贝叶斯网络时边的顺序非常重要
- 给定一个贝叶斯网络，每一个节点条件独立与所有除马尔可夫覆盖外的所有其他节点。这个性质在同一问题对应的不同网络版本下是保持不变的

贝叶斯网络推理

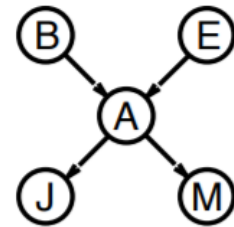
精确推理：所有节点的条件分布已知

Inference by enumeration

Slightly intelligent way to sum out variables from the joint without actually constructing its explicit representation

Simple query on the burglary network:

$$\begin{aligned} & \mathbf{P}(B|j, m) \\ &= \mathbf{P}(B, j, m) / P(j, m) \\ &= \alpha \mathbf{P}(B, j, m) \\ &= \alpha \sum_e \sum_a \mathbf{P}(B, e, a, j, m) \end{aligned}$$



Rewrite full joint entries using product of CPT entries:

$$\begin{aligned} & \mathbf{P}(B|j, m) \\ &= \alpha \sum_e \sum_a \mathbf{P}(B)P(e)\mathbf{P}(a|B, e)P(j|a)P(m|a) \\ &= \alpha \mathbf{P}(B) \sum_e P(e) \sum_a \mathbf{P}(a|B, e)P(j|a)P(m|a) \end{aligned}$$

Recursive depth-first enumeration: $O(n)$ space, $O(d^n)$ time

- 首先根据贝叶斯定理展开为全联合概率
- 然后使用全局语义结合已有的条件概率进行计算

枚举算法

Enumeration algorithm

function ENUMERATION-ASK(X, \mathbf{e}, bn) **returns** a distribution over X

inputs: X , the query variable

\mathbf{e} , observed values for variables \mathbf{E}

bn , a Bayesian network with variables $\{X\} \cup \mathbf{E} \cup \mathbf{Y}$

$Q(X) \leftarrow$ a distribution over X , initially empty

for each value x_i of X **do**

 extend \mathbf{e} with value x_i for X

$Q(x_i) \leftarrow$ ENUMERATE-ALL(VARS[bn], \mathbf{e})

return NORMALIZE($Q(X)$)

function ENUMERATE-ALL($vars, \mathbf{e}$) **returns** a real number

if EMPTY?($vars$) **then return** 1.0

$Y \leftarrow$ FIRST($vars$)

if Y has value y in \mathbf{e}

then return $P(y \mid Pa(Y)) \times$ ENUMERATE-ALL(REST($vars$), \mathbf{e})

else return $\sum_y P(y \mid Pa(Y)) \times$ ENUMERATE-ALL(REST($vars$), \mathbf{e}_y)

 where \mathbf{e}_y is \mathbf{e} extended with $Y = y$

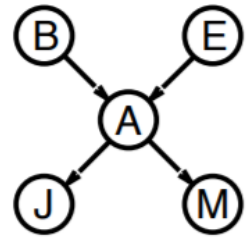
- 但是枚举算法是低效的
- 可以从右向左计算提高效率
- 也可以使用下面的定理，找出无关变量

Irrelevant variables

Consider the query $P(\text{JohnCalls} | \text{Burglary} = \text{true})$

$$P(J|b) = \alpha P(b) \sum_e P(e) \sum_a P(a|b, e) P(J|a) \sum_m P(m|a)$$

Sum over m is identically 1; M is **irrelevant** to the query



Thm 1: Y is irrelevant unless $Y \in \text{Ancestors}(\{X\} \cup \mathbf{E})$

Here, $X = \text{JohnCalls}$, $\mathbf{E} = \{\text{Burglary}\}$, and
 $\text{Ancestors}(\{X\} \cup \mathbf{E}) = \{\text{Alarm}, \text{Earthquake}\}$
so MaryCalls is irrelevant

模糊推理：部分节点的条件分布未知

- LM采样。给定证据变量，越能使得证据变量一致的样本权重应该越大
 - 对查询变量采样，
 - 证据变量固定。但是途径证据变量时，要根据他目前的父节点计算他满足给定值的条件概率，更新w
- MCMC采样

Approximate inference using MCMC



“State” of network = current assignment to all variables.

Generate next state by sampling one variable given Markov blanket

Sample each variable in turn, keeping evidence fixed

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function MCMC-Ask( $X, \mathbf{e}, bn, N$ ) returns an estimate of  $P(X|\mathbf{e})$ 
  local variables:  $\mathbf{N}[X]$ , a vector of counts over  $X$ , initially zero
                   $\mathbf{Z}$ , the nonevidence variables in  $bn$ 
                   $\mathbf{x}$ , the current state of the network, initially copied from  $\mathbf{e}$ 

  initialize  $\mathbf{x}$  with random values for the variables in  $\mathbf{Y}$ 
  for  $j = 1$  to  $N$  do
    for each  $Z_i$  in  $\mathbf{Z}$  do
      sample the value of  $Z_i$  in  $\mathbf{x}$  from  $\mathbf{P}(Z_i|mb(Z_i))$ 
        given the values of  $MB(Z_i)$  in  $\mathbf{x}$ 
       $\mathbf{N}[x] \leftarrow \mathbf{N}[x] + 1$  where  $x$  is the value of  $X$  in  $\mathbf{x}$ 
  return NORMALIZE( $\mathbf{N}[X]$ )
```

Can also choose a variable to sample at random each time

- 统计需要查询的变量为真和为假出现的次数。比例正则化后即为给定证据变量情况下需查询变量的条件分布