1

ASSIGNMENT 3

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Download all python codes from

https://github.com/BOJJAVOYINAANUSHA/ ASSIGNMENT_3/blob/main/ASSIGNMENT3 /assignment3.py

and latex-tikz codes from

https://github.com/BOJJAVOYINAANUSHA/ ASSIGNMENT_3/blob/main/ASSIGNMENT3 /ASSIGNMENT3.tex

1 Question No 2.57

Draw a circle of radius 3 units. Take two points P and Q on one its extended diameter each at a distance of 7 units from its centre. Draw tangents to the circle from these two points P and Q.

2 SOLUTION

The data from the question is in the table 2.1

	circle
Centre	$\mathbf{O} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$
Radius	r=3
Radius	d=7

TABLE 2.1: Input values

Lemma 2.1. The points of contact for the tangent drawn from a point

$$\mathbf{Q} = d\mathbf{e}_I, where \ \mathbf{e}_I = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
 (2.0.1)

to the circle are given by

$$\mathbf{x} = \frac{r^2}{d}\mathbf{e}_1 \pm r\sqrt{1 - \frac{r^2}{d^2}}\mathbf{e}_2, where \ \mathbf{e}_2 = \begin{pmatrix} 0\\1 \end{pmatrix} \quad (2.0.2)$$

Let the point at distance d from **O** be

$$\mathbf{Q} = d\mathbf{e}_I, where \ \mathbf{e}_I = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
 (2.0.3)

If \mathbf{x} be a point of contact for the tangent from \mathbf{Q} ,

$$QR \perp RO$$
 (2.0.4)

$$\implies (\mathbf{O} - \mathbf{x})^T (\mathbf{x} - \mathbf{Q}) = 0 \tag{2.0.5}$$

or,
$$\mathbf{Q}^T \mathbf{x} = \|\mathbf{x}^2\| = r^2$$
 (2.0.6)

$$\implies \mathbf{e}_I^{\mathbf{T}} \mathbf{x} = \frac{r^2}{d} \tag{2.0.7}$$

$$\mathbf{CO} = 0. \tag{2.0.8}$$

The above equation can be expressed in parametric form as

$$\mathbf{x} = \frac{r^2}{d}\mathbf{e}_1 + \lambda \mathbf{e}_2 \tag{2.0.9}$$

Substituting the above in

$$||\mathbf{x}||^2 = r^2, \tag{2.0.10}$$

yields

$$\left\| \frac{r^2}{d} \mathbf{e}_I + \lambda \mathbf{e}_2 \right\|^2 = r^2 \tag{2.0.11}$$

$$\implies \lambda^2 = r^2 \left[1 - \frac{r^2}{d^2} \right] \tag{2.0.12}$$

or,
$$\lambda = \pm r \sqrt{1 - \frac{r^2}{d^2}}$$
 (2.0.13)

Substitute r and d values in the above equation, we get

$$\lambda = \pm 2.71$$
 (2.0.14)

Now we can substitute r, d and λ in (2.0.9).

$$\mathbf{x} = \frac{3^2}{7} \begin{pmatrix} 1\\0 \end{pmatrix} + \pm 2.71 \begin{pmatrix} 0\\1 \end{pmatrix} \tag{2.0.15}$$

$$\mathbf{x} = \begin{pmatrix} 1.285 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ \pm 2.71 \end{pmatrix} \tag{2.0.16}$$

$$\implies \mathbf{C} = \begin{pmatrix} 1.285 \\ 2.71 \end{pmatrix}, \mathbf{D} = \begin{pmatrix} 1.285 \\ -2.71 \end{pmatrix} \tag{2.0.17}$$

From (2.0.1)

$$\mathbf{Q} = 7 \begin{pmatrix} 1 \\ 0 \end{pmatrix} \tag{2.0.18}$$

$$\mathbf{Q} = \begin{pmatrix} 7 \\ 0 \end{pmatrix} \tag{2.0.19}$$

Similarly, The points of contact for the tangent drawn from a point

$$\mathbf{P} = d\mathbf{e}_{I}, where \ \mathbf{e}_{I} = \begin{pmatrix} -1\\0 \end{pmatrix}$$
 (2.0.20)

Referencing (2.0.9), we have

$$\mathbf{y} = \frac{r^2}{d}\mathbf{e}_1 + \lambda\mathbf{e}_2 \tag{2.0.21}$$

Now we can substitute the r, d and λ values in the above equation, we get:

$$\mathbf{y} = \frac{3^2}{7} \begin{pmatrix} -1\\0 \end{pmatrix} + \pm 2.71 \begin{pmatrix} 0\\1 \end{pmatrix} \qquad (2.0.22)$$

$$\mathbf{y} = \begin{pmatrix} -1.285 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ \pm 2.71 \end{pmatrix} \tag{2.0.23}$$

$$\implies \mathbf{A} = \begin{pmatrix} -1.285 \\ 2.71 \end{pmatrix}, \mathbf{B} = \begin{pmatrix} -1.285 \\ -2.71 \end{pmatrix} \qquad (2.0.24)$$

From (2.0.20)

$$\mathbf{P} = 7 \begin{pmatrix} -1 \\ 0 \end{pmatrix} \tag{2.0.25}$$

$$\mathbf{P} = \begin{pmatrix} -7\\0 \end{pmatrix} \tag{2.0.26}$$

• Plot of Tangents PA, PB, QC and QD:

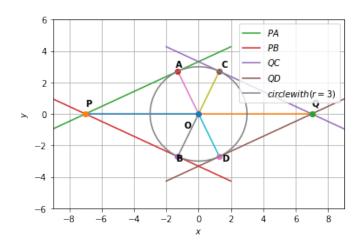


Fig. 2.1: Tangent lines to circle of radius 3 units.