

HW 1

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10:57

(a) associative:  $A(BC) = (AB)C$ set  $A_{n \times n} = (a_{ij})$   $B_{n \times n} = (b_{ij})$   $C_{n \times n} = (c_{ij})$ 

$$AB = (d_{ij}) \quad BC = (e_{ij})$$

$$ABC = (f_{ij}) \quad A(BC) = (g_{ij})$$

$$\Rightarrow d_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{in}b_{nj}, \quad i, j = 1, 2, \dots, n$$

$$e_{ij} = b_{1j}c_{1i} + b_{2j}c_{2i} + \dots + b_{nj}c_{ni}, \quad i, j = 1, 2, \dots, n$$

$$f_{ij} = d_{i1}c_{1j} + d_{i2}c_{2j} + \dots + d_{in}c_{nj}, \quad i, j = 1, 2, \dots, n$$

$$g_{ij} = a_{i1}e_{1j} + a_{i2}e_{2j} + \dots + a_{in}e_{nj}, \quad i, j = 1, 2, \dots, n$$

$$\Rightarrow \forall i, j = 1, 2, \dots, n$$

$$f_{ij} = d_{i1}c_{1j} + d_{i2}c_{2j} + \dots + d_{in}c_{nj}$$

$$= (a_{i1}b_{11} + a_{i2}b_{21} + \dots + a_{in}b_{n1})c_{1j} +$$

$$(a_{i1}b_{12} + a_{i2}b_{22} + \dots + a_{in}b_{n2})c_{2j} +$$

$$\dots (a_{i1}b_{1n} + a_{i2}b_{2n} + \dots + a_{in}b_{nn})c_{nj}$$

$$= a_{i1}(b_{11}c_{1j} + b_{12}c_{2j} + \dots + b_{1n}c_{nj}) +$$

$$a_{i2}(b_{21}c_{1j} + \dots + b_{2n}c_{nj}) + \dots$$

$$+ a_{in}(b_{n1}c_{1j} + \dots + b_{nn}c_{nj})$$

$$= a_{i1}e_{1j} + a_{i2}e_{2j} + \dots + a_{in}e_{nj}$$

$$= g_{ij}$$

$$\Rightarrow (AB)C = A(BC)$$

distributive:  $A(B+C) = AC+BC$

$$(A+B)C = AC+BC$$

$$[(A+B)C]_{ij} = \sum_k (A_{ik} + B_{ik}) C_{kj}$$

$$= \sum_k A_{ik} C_{kj} + \sum_k B_{ik} C_{kj}$$

$$= (AC)_{ij} + (BC)_{ij}$$

$$\Rightarrow (A+B)C = AC+BC$$

works similarly  $A(B+C) = AB+AC$

commutative:  $AB = BA$

set  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$   $B = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

$$AB = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad BA = \begin{bmatrix} 1 & 4 & 9 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$AB \neq BA$$

commutative is incorrect.

1b)  $A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 4 & 6 \\ 0 & 0 & 1 \end{bmatrix}$

$$[AE] = \begin{bmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 1 & 4 & 6 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{r_2 - r_1} \begin{bmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 2 & 3 & -1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_3} \begin{bmatrix} 1 & 0 & 0 & 2 & -1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 2 & 3 & -1 & 1 & 0 \end{bmatrix}$$

$$\xrightarrow{r_2 - r_1} \begin{bmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 2 & 3 & -1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_1 \leftrightarrow r_2} \begin{bmatrix} 1 & 0 & 0 & 2 & -1 & 0 \\ 0 & 2 & 3 & -1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{r_2 \times \frac{1}{2}} \begin{bmatrix} 1 & 0 & 0 & 2 & -1 & 0 \\ 0 & 2 & 0 & -1 & 1 & -3 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\frac{1}{2}r_2} \begin{bmatrix} 1 & 0 & 0 & 2 & -1 & 0 \\ 0 & 1 & 0 & -\frac{1}{2} & \frac{1}{2} & -\frac{3}{2} \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} 2 & -1 & 0 \\ -\frac{1}{2} & \frac{1}{2} & -\frac{3}{2} \\ 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 4 & 6 \\ 1 & 0 & 0 \end{bmatrix} \quad \det(A) = \begin{vmatrix} 1 & 2 & 3 \\ 1 & 4 & 6 \\ 1 & 0 & 0 \end{vmatrix}$$

$$= 1 \times 4 \times 0 + 2 \times 6 \times 1 + 3 \times 1 \times 0 \\ - 3 \times 4 \times 1 - 2 \times 1 \times 0 - 1 \times 6 \times 0 \\ = 12 - 12 = 0$$

$\Rightarrow A$  is a singular matrix  $\Rightarrow A$  is not invertible

1c)  $L = (A^T A)^{-1} A^T$

$$R = A^T (A A^T)^{-1}$$

$$Ax = I \\ A^T A x = A^T I \\ x = (A^T A)^{-1} A^T$$

$$xA = I$$

$$x A A^T = I A^T$$

$$x = A^T (A A^T)^{-1}$$

$$A^T \in \mathbb{R}^{2 \times 3}, (A^T A)^{-1} \in \mathbb{R}^{3 \times 3}$$

hence  $A^T$  can multiply  $(A^T A)^{-1}$

$(A^T A)^{-1} \in \mathbb{R}^{3 \times 3}, A^T \in \mathbb{R}^{2 \times 3}$ , hence the size of  $(A^T A)^{-1}$  can't multiply  $A^T$

$\therefore A$  has only right-Pseudo Inverse  
 $\Rightarrow$

$\therefore A$  has only Right-Pseudo Inverse

1d) see matrix  $W$  and vectors  $\vec{v}$

$$\text{if } W \times \vec{v} = \lambda \vec{v} \quad (\lambda \neq 0)$$

these vectors are called eigenvectors and  $\lambda$  is called eigenvalues

A squared symmetric matrix  $A = QDQ^T$ , where the columns of  $Q$  are the eigenvectors of  $A$  and  $D$  is a diagonal matrix where the entries are the corresponding eigenvalues.

This can help to reduce Dimension, so that we can use less data and the speed can be improved.