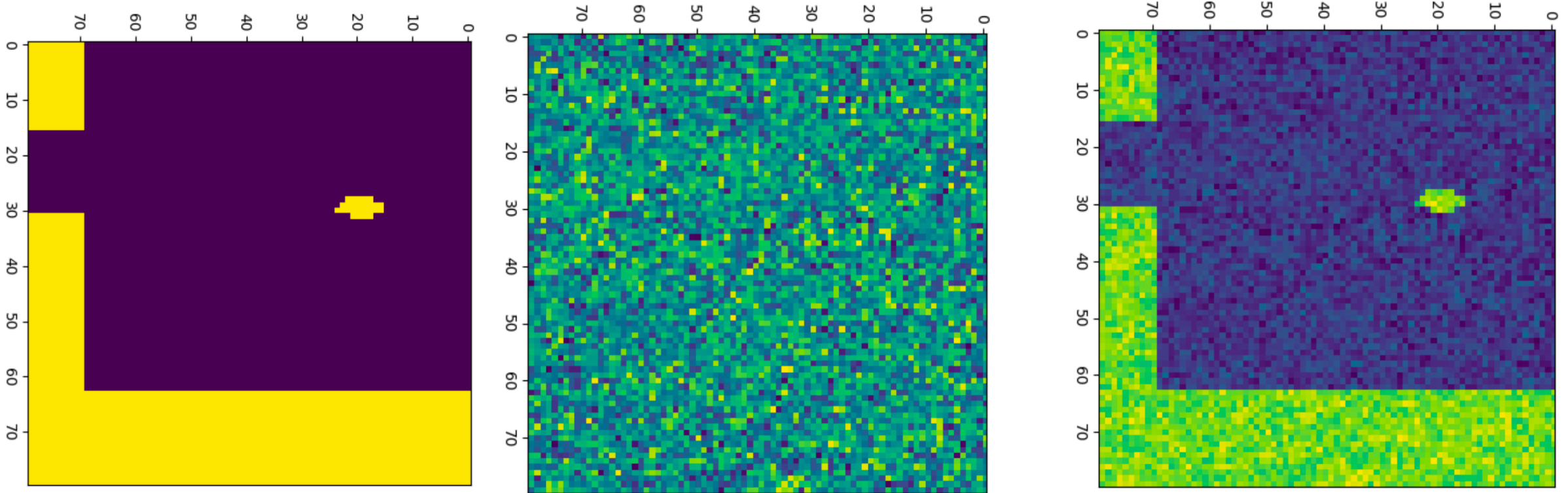


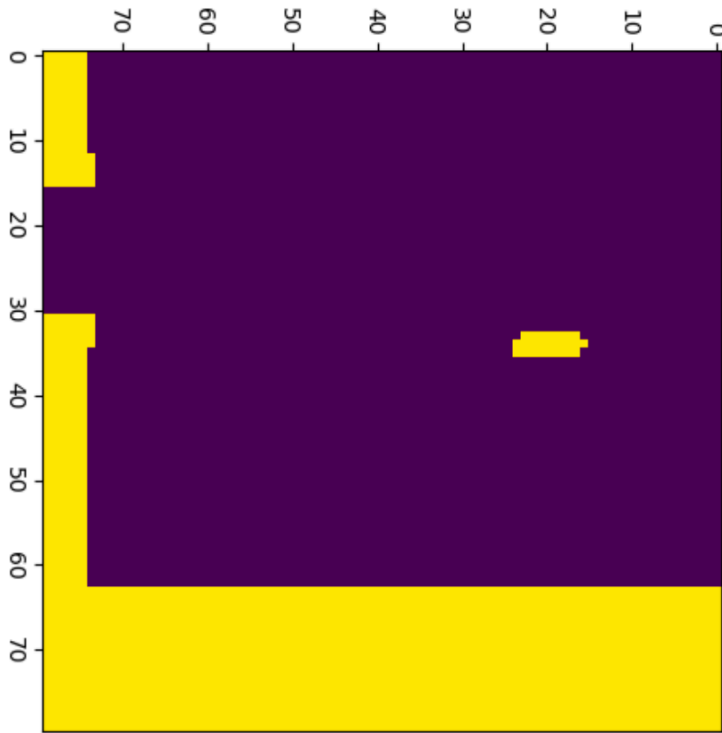


# Preliminary Results of Zero Level Attack

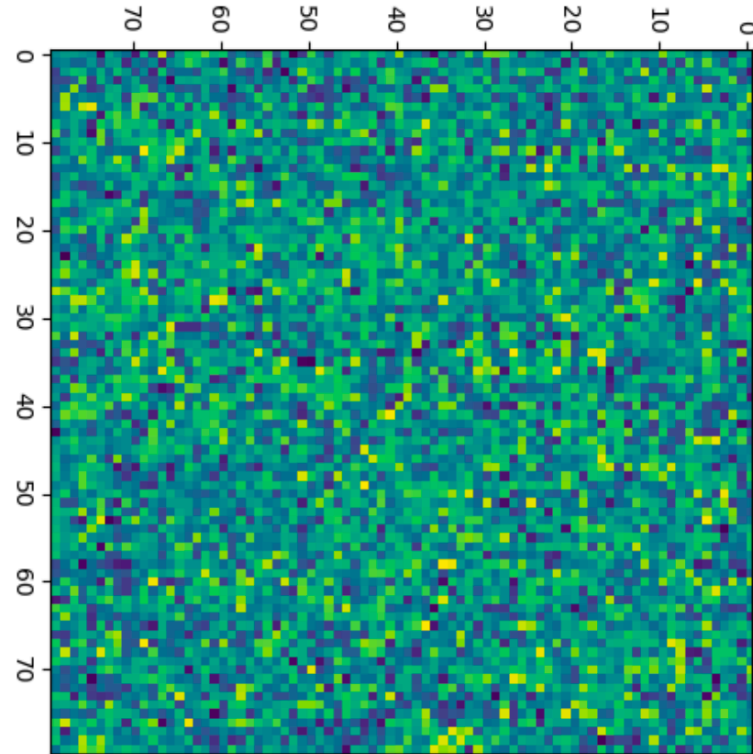


Batch 1

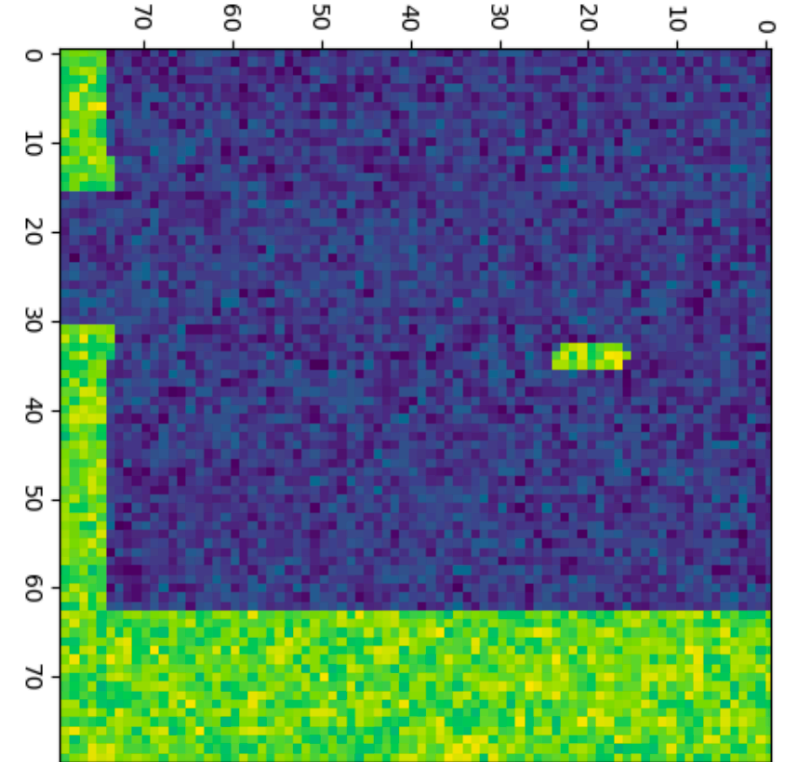
# Preliminary Results of Zero Level Attack



Batch 2

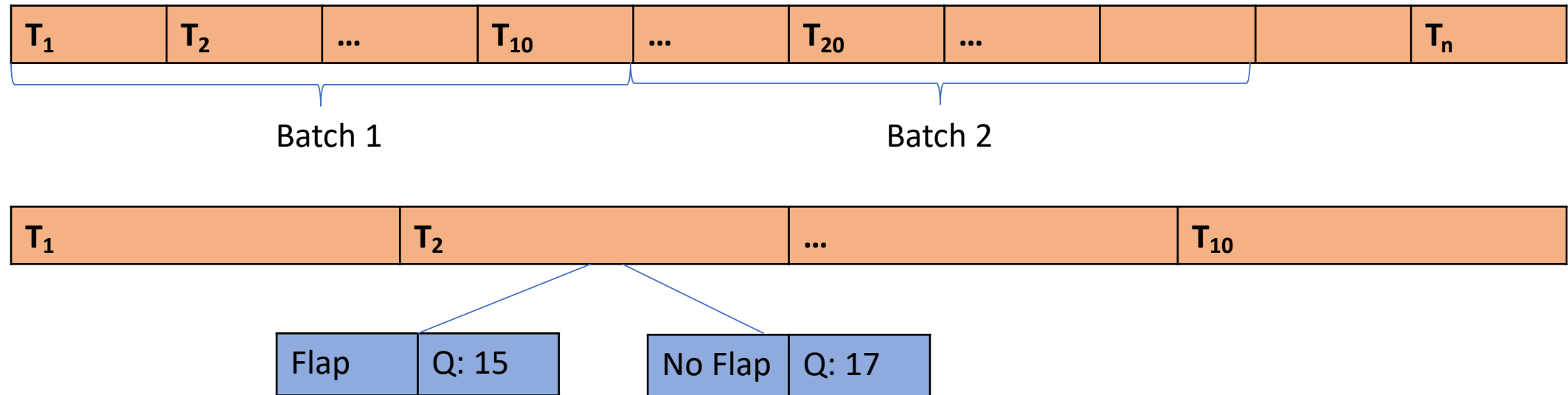


Very similar perturbation



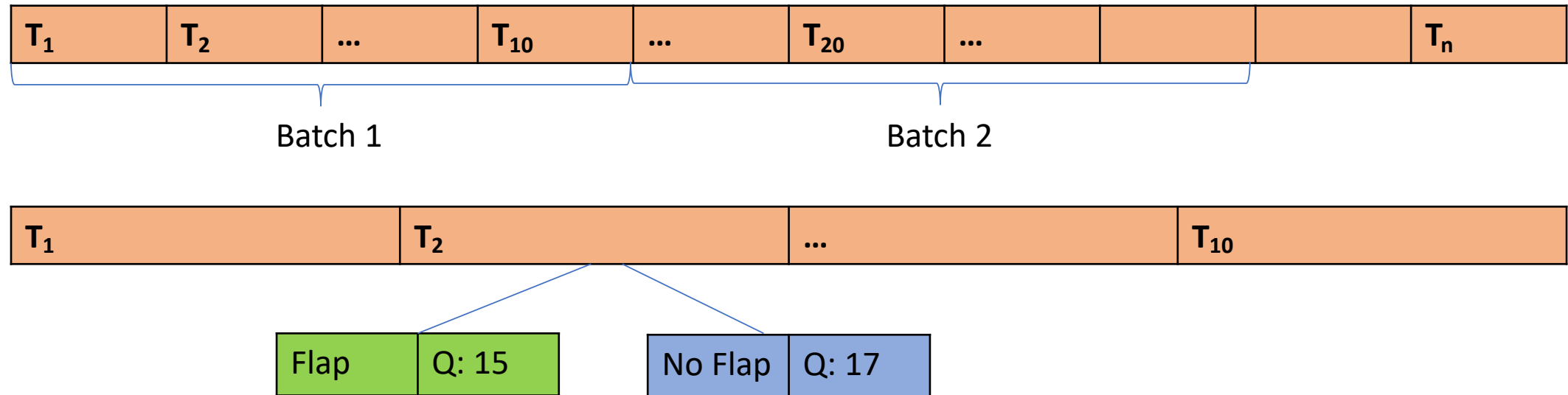
# What's going on?

Replay Memory,  $D : \{S, A, R, S', \gamma\}$



# What's going on?

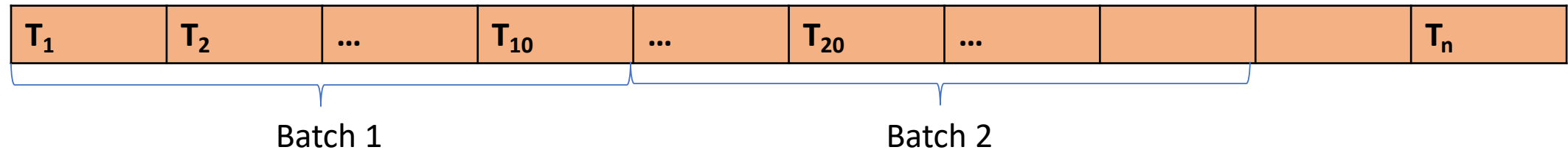
Replay Memory,  $D : \{S, A, R, S', \gamma\}$



Objective: Flap right now, even though we shouldn't

# What's going on?

Replay Memory,  $D : \{S, A, R, S', \gamma\}$



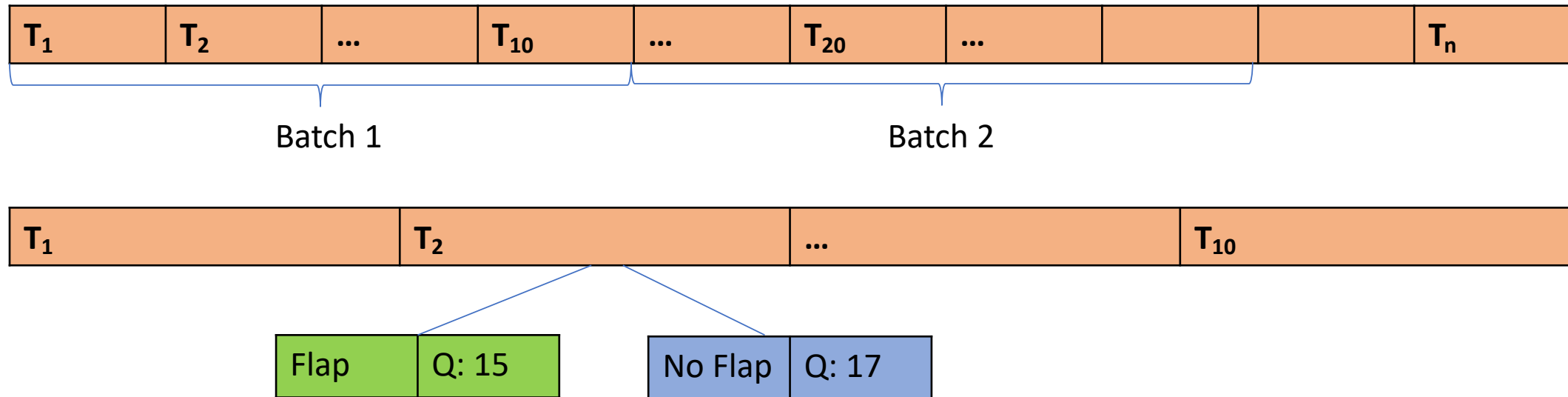
Flap Q: 19

No Flap Q: 17

Q Value for "Flap," is now higher than  
"No Flap"  $\rightarrow$  *objective met*

# How Did We Do This?

Replay Memory,  $D : \{S, A, R, S', \gamma\}$

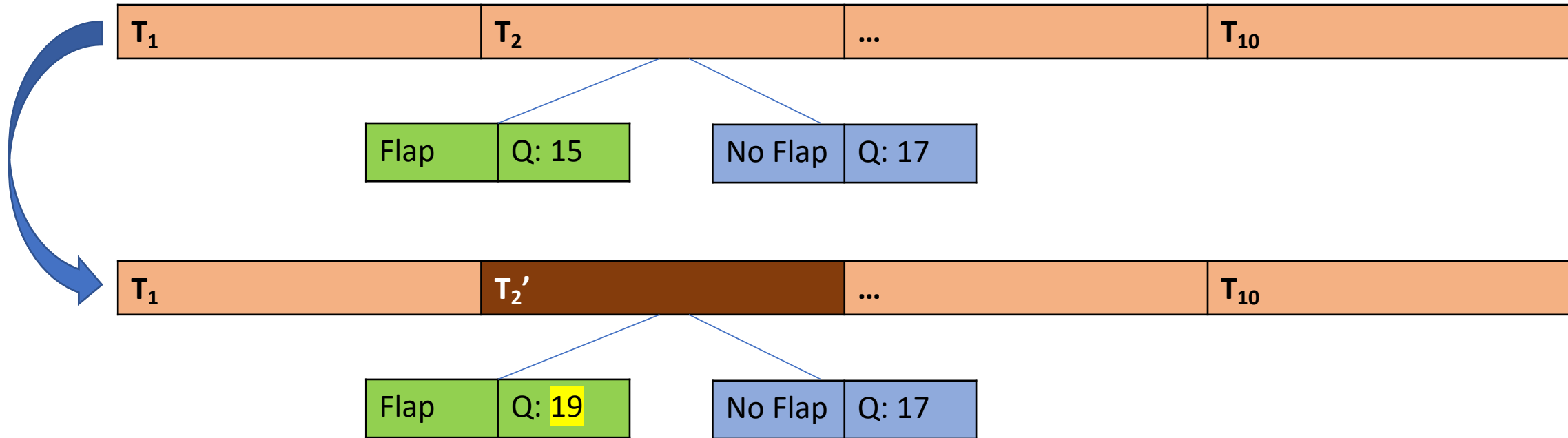


Enforce Loss:

$Q(\text{target}) > Q(\text{not Target})$

Minimize(dS)  $[Q(\text{target}) - Q(\text{not Target}) + \epsilon]$

# How Did We Do This?



Enforce Loss:

$Q(\text{target}) > Q(\text{not Target})$

Minimize(dS)  $[Q(\text{target}) - Q(\text{not Target}) + \epsilon]$

- > Fully functional agent
- > Freeze all weights
- > input + dS before layer 1 of NN (as first operation)
- > Collect Batch (10)
- > Loss over batch
- > Optimize entire NN graph == optimize dS