

R16

CAMERA 自动检测使用说明

文档履历

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前言

1.1. 编写目的

了解 CAMERA 自动检测注意事项。

1.2. 适用范围

介绍本模块设计适用 R16 平台。

1.3. 适用范围

客户

2. CAMERA 自动检测配置

R16 方案考虑到客户需要使用同一个固件支持多种不同 camera 模组的需求,重新定义了一套 camera detector 方案,如果需要使用该方案,需要在 sysconfig 中作出相应的配置:

- 1. 设置相应 csi 上的 vip_define_sensor_list = 1。
- 2. 明确定义出前后摄像头,例如 vip_dev0_pos = "rear", vip_dev1_pos = "front"; 使用该检测方案需使用一个 sensor_list_cfg. ini 配置文件, 驱动会从该文件中读取模组信息。

如果 csi0 或者 csi1 定义了 vip_define_sensor_list = 1, 则驱动就会去试图读取/system/etc/hawkview/sensor_list_cfg.ini,如果读取成功,则驱动会用 sensor_list_cfg.ini 中的相应信息替换掉原来从 sysconfig 中读取的信息,如果读取失败,则驱动会继续使用 sysconfig 中的配置。

3. 将 sensor list cfg. ini 配置文件放在 android/device/softwinner/xxx 方案目录下。

在 Android\device\softwinner\xxx\xxx. mk 文件中按如下方法增加配置:

```
# camera config for camera detector
PRODUCT_COPY_FILES += \
    device/softwinner/xxx/hawkview/sensor_list_cfg.ini:system/etc/hawkview/sensor_list_cfg.
ini
```

下面结合 sensor list cfg. ini 配置文件说明 camera detector 功能该如何使用:

- 1. sensor list cfg. ini 中整体上分为前置和后置两套 camera 配置。
- 2. 每套 camera 的配置分为 bus configs, power configs 和 sensor configs:
 - a) Bus configs: 考虑到客户已经习惯在 sysconfig 中配置相关的 bus, 在这里暂不配置。
 - b) Power configs: 该部分可以根据客户或者开发人员需要,通过 power_settings_enable 来选择使用 sysconfig 中配置还是 sensor_list_cfg. ini 中的配置,例如 power_settings_enable = 0:代表使用 sysconfig 中配置,power_settings_enable = 1代表使用 sensor_list_cfg. ini 中配置。
 - c) Sensor configs: 考虑到检测速度等方面原因,对前置和后置最大检测数量做出了限制,最大都为3。
 - d) 各个 sensor 实体配置比较灵活,可以 YUV sensor 也可以是 RAW sensor,也可以独立配置各自的 hflip 和 vflip。对于 RAW sensor 也可以独立配置 VCM。
- 3. 目前驱动不支持对供电电压要求不同的 sensor 列表做自动检测
- 4. 驱动也不能检测出相同的 sensor 使用不同的 VCM 的情况。

下面给出一个具体的使用例子:

该例子后置使用 ov5647, gc2035, ov5640。 前置使用 gc0328, gc2035, gc2015

```
#power settings enable: 0: enable the power settings in sysconfig.fex; 1: enable the power
settings in this file.
#iovdd: The name of iovdd for this camera;
#iovdd vol: The voltage value of iovdd in uV;
#detect_sensor_num: The number of sensors need be detected in this bus.
#sensor_name[x]: The sensor name in sensor driver.
#sensor twi addr[x]: The i2c address of this sensor.
#sensor_type[x]: The sensor type, 0: YUV, 1: RAW;
#sensor stby mode[x]: Not used;
#sensor_hflip[x]: Horizontal flip;
#sensor vflip[x]: Vertical flip;
#act_name[x]: The VCM name in vcm driver, only RAW sensor need be configured;
#act twi addr[x]: The VCM i2c address;
[rear_camera_cfg]
#bus configs
used
                    = 1
csi_sel
device sel
                    = 0
sensor_twi_id
                    = 2
#power configs
power_settings_enable
                    = 1
iovdd
                    = "axp22 d1do3"
                   = 2800000
iovdd_vol
                    = "axp22 d1do3"
avdd
avdd vol
                    = 2800000
                    = "axp22_e1do2"
dvdd
dvdd vol
                    = 1800000
                    = "axp22 d1do3"
afvdd
                    = 2800000
afvdd vol
#detect sensor configs
{\tt detect\_sensor\_num}
                    = 3
```

```
= "ov5647"
sensor_name0
sensor_twi_addr0
                        = 0x78
sensor_type0
                        = 0
sensor_stby_mode0
                        = 0
sensor_hflip0
                        = 0
sensor_vflip0
                        = ()
                        = "ad5820 act"
act_name0
act_twi_addr0
                        = 0x18
                        = "gc2035"
sensor_name1
                        = 0x78
sensor_twi_addr1
sensor_type1
                        = 2
sensor_stby_model
                       = 0
sensor_hflip1
                        = 1
sensor_vflip1
                        = 1
act_name1
act_twi_addr1
                        = "ov5640"
sensor\_name2
sensor_twi_addr2
                        = 0x78
sensor_type2
                        = 0
sensor_stby_mode2
                        = 0
                        = 0
sensor_hflip2
sensor_vflip2
                        = 0
act_name2
act_twi_addr2
[front_camera_cfg]
#bus configs
used
                        = 1
                        = 1
csi sel
device_sel
                        = 0
sensor_twi_id
                        = 2
#power configs
power_settings_enable = 1
                        = "axp22 d1do3"
iovdd
iovdd_vol
                        = 2800000
                        = "axp22_d1do3"
avdd
avdd vol
                        = 2800000
dvdd
                        = "axp22_e1do2"
                        = 1800000
dvdd vol
```

```
afvdd
                       = "axp22_d1do3"
afvdd vol
                       = 2800000
#detect sensor configs
                       = 3
detect_sensor_num
                       = "gc0328"
sensor_name0
sensor_twi_addr0
                      = 0x42
sensor_type0
                       = 2
                      = 0
sensor_stby_mode0
sensor_hflip0
                       = 1
sensor_vflip0
                       = 1
act\_name0
act_twi_addr0
                       = "gc2035"
sensor_name1
                       = 0x78
sensor_twi_addr1
sensor type1
                      = 0
sensor_stby_model
                      = 0
sensor_hflip1
                      = 0
sensor_vflip1
                       = 0
act_name1
act_twi_addr1
sensor_name2
                      = "gc2015"
                      = 0x60
sensor_twi_addr2
sensor_type2
                       = 0
sensor_stby_mode2
                       = 0
                       = 0
sensor_hflip2
sensor_vflip2
                       = 0
act_name2
act_twi_addr2
```

以上仅作参考,请根据 camera 使用情况进行相应配置。

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