



Department of Mechanical, Automotive, & Materials Engineering

401 Sunset Avenue, Windsor

Ontario, Canada N9B 3P4

519 253 3000 (2616)

www.uwindsor.ca

First Line of Title Here
Second Line of Title Here

John Smith: ID 12345678

Jane Smith: ID 87654321

September 15, 2015

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CHAPTER 1

INTRODUCTION

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1.1 System Description

The system properties are given in Tables 1.1 and 1.2.

Table 1.1: Body Location and Properties

| No. | Body Name | Location [m] | Mass [kg] | Inertia [kg·m ²] (I_{xx} , I_{yy} , I_{zz} ; I_{xy} , I_{yz} , I_{zx}) |
|-----|-----------|-----------------------|-----------|--|
| 1 | f-axle | 0.762, 0.000, 0.100 | 10.000 | 1.633, 0.000, 1.633; 0.000, 0.000, 0.000 |
| 2 | lf-axle | 0.762, 0.550, 0.229 | 0.000 | 0.000, 0.000, 0.000; 0.000, 0.000, 0.000 |
| 3 | rf-axle | 0.762, -0.550, 0.229 | 0.000 | 0.000, 0.000, 0.000; 0.000, 0.000, 0.000 |
| 4 | r-axle-t | -0.762, 0.000, 0.329 | 5.000 | 0.817, 0.000, 0.817; 0.000, 0.000, 0.000 |
| 5 | r-axle-b | -0.762, 0.000, 0.129 | 5.000 | 0.817, 0.000, 0.817; 0.000, 0.000, 0.000 |
| 6 | lr-axle | -0.762, 0.550, 0.229 | 0.000 | 0.000, 0.000, 0.000; 0.000, 0.000, 0.000 |
| 7 | rr-axle | -0.762, -0.550, 0.229 | 0.000 | 0.000, 0.000, 0.000; 0.000, 0.000, 0.000 |
| 8 | chassis | 0.000, 0.000, 0.300 | 300.000 | 50.000, 120.000, 180.000; 0.000, 0.000, 0.000 |
| 9 | lf-wheel | 0.762, 0.600, 0.229 | 10.000 | 0.500, 1.000, 0.500; 0.000, 0.000, 0.000 |
| 10 | rf-wheel | 0.762, -0.600, 0.229 | 10.000 | 0.500, 1.000, 0.500; 0.000, 0.000, 0.000 |
| 11 | lr-wheel | -0.762, 0.600, 0.229 | 10.000 | 0.500, 1.000, 0.500; 0.000, 0.000, 0.000 |
| 12 | rr-wheel | -0.762, -0.600, 0.229 | 10.000 | 0.500, 1.000, 0.500; 0.000, 0.000, 0.000 |

Note: inertias are defined as the positive integral over the body, e.g., $I_{xy} = +\int r_x r_y dm$.

Table 1.2: Connection Location and Properties

| No. | Connection Name | Location [m] | Unit Axis | Stiffness [N/m] | Damping [Ns/m] |
|-----|------------------|-----------------------|-----------------------|-----------------|----------------|
| 1 | lf-tire | 0.762, 0.600, 0.000 | 0.000, 0.000, 1.000 | – | – |
| 2 | rf-tire | 0.762, –0.600, 0.000 | 1.000, 0.000, 0.000 | – | – |
| 3 | rr-tire | –0.762, –0.600, 0.000 | 0.000, 0.000, 1.000 | – | – |
| 4 | lr-tire | –0.762, 0.600, 0.000 | 1.000, 0.000, 0.000 | – | – |
| 5 | lf-wb | 0.762, 0.600, 0.229 | 0.000, 1.000, 0.000 | – | – |
| 6 | rf-wb | 0.762, –0.600, 0.229 | 0.000, 1.000, 0.000 | – | – |
| 7 | lr-wb | –0.762, 0.600, 0.229 | 0.000, 1.000, 0.000 | – | – |
| 8 | rr-wb | –0.762, –0.600, 0.229 | 0.000, 1.000, 0.000 | – | – |
| 9 | lf | 0.762, 0.550, 0.229 | –0.170, –0.170, 0.970 | – | – |
| 10 | rf | 0.762, –0.550, 0.229 | –0.170, 0.170, 0.970 | – | – |
| 11 | lr | –0.762, 0.550, 0.329 | 1.000, 0.000, 0.000 | – | – |
| 12 | rr | –0.762, –0.550, 0.329 | 1.000, 0.000, 0.000 | – | – |
| 13 | lr | –0.762, 0.550, 0.129 | 1.000, 0.000, 0.000 | – | – |
| 14 | rr | –0.762, –0.550, 0.129 | 1.000, 0.000, 0.000 | – | – |
| 15 | lf-tire | 0.762, 0.600, 0.000 | 0.000, 0.000, 1.000 | 100,000 | 0 |
| 16 | rf-tire | 0.762, –0.600, 0.000 | 0.000, 0.000, 1.000 | 100,000 | 0 |
| 17 | rr-tire | –0.762, –0.600, 0.000 | 0.000, 0.000, 1.000 | 100,000 | 0 |
| 18 | lr-tire | –0.762, 0.600, 0.000 | 0.000, 0.000, 1.000 | 100,000 | 0 |
| 19 | front left | 0.800, 0.500, 0.100 | –, –, – | 5,000 | 200 |
| – | front left | 0.900, 0.400, 0.300 | –, –, – | – | – |
| 20 | front right | 0.800, –0.500, 0.100 | –, –, – | 5,000 | 200 |
| – | front right | 0.900, –0.400, 0.300 | –, –, – | – | – |
| 21 | rear left | –0.700, 0.500, 0.100 | –, –, – | 5,000 | 200 |
| – | rear left | –0.600, 0.400, 0.300 | –, –, – | – | – |
| 22 | rear right | –0.700, –0.500, 0.100 | –, –, – | 5,000 | 200 |
| – | rear right | –0.600, –0.400, 0.300 | –, –, – | – | – |
| 23 | right-b | 0.762, 0.000, 0.100 | –, –, – | – | – |
| – | right-b | 0.462, –0.400, 0.100 | –, –, – | – | – |
| 24 | left-b | 0.762, 0.000, 0.100 | –, –, – | – | – |
| – | left-b | 0.462, 0.400, 0.100 | –, –, – | – | – |
| 25 | right-b | 0.762, –0.500, 0.300 | –, –, – | – | – |
| – | right-b | 0.462, –0.500, 0.300 | –, –, – | – | – |
| 26 | left-b | 0.762, 0.500, 0.300 | –, –, – | – | – |
| – | left-b | 0.462, 0.500, 0.300 | –, –, – | – | – |
| 27 | lf-tie-rod | 0.662, 0.500, 0.150 | –, –, – | – | – |
| – | lf-tie-rod | 0.662, 0.100, 0.150 | –, –, – | – | – |
| 28 | rf-tie-rod | 0.662, –0.500, 0.150 | –, –, – | – | – |
| – | rf-tie-rod | 0.662, –0.100, 0.150 | –, –, – | – | – |
| 29 | right rear lower | –0.762, 0.000, 0.100 | –, –, – | – | – |
| – | right rear lower | –0.462, –0.500, 0.100 | –, –, – | – | – |
| 30 | left rear lower | –0.762, 0.000, 0.100 | –, –, – | – | – |
| – | left rear lower | –0.462, 0.500, 0.100 | –, –, – | – | – |
| 31 | right rear upper | –0.762, –0.500, 0.300 | –, –, – | – | – |
| – | right rear upper | –0.462, –0.500, 0.300 | –, –, – | – | – |
| 32 | left rear upper | –0.762, 0.500, 0.300 | –, –, – | – | – |
| – | left rear upper | –0.462, 0.500, 0.300 | –, –, – | – | – |
| 33 | left rear upper | –0.762, 0.500, 0.300 | –, –, – | – | – |
| – | left rear upper | –0.752, –0.500, 0.300 | –, –, – | – | – |

CHAPTER 2

ANALYSIS

Replace this text with the body of your report. Add sections or subsections as appropriate.

2.1 Eigenvalue Analysis

The eigenvalue properties are given in Tables 2.1 and 2.2.

Table 2.1: Eigenvalues

| No. | Real [rad/s] | Imaginary [rad/s] | Real [Hz] | Imaginary [Hz] |
|-----|-----------------------|-----------------------|--------------------------|--------------------------|
| 1 | -5.1043×10^0 | 8.7341×10^1 | -8.1237×10^{-1} | 1.3901×10^1 |
| 2 | -5.1043×10^0 | -8.7341×10^1 | -8.1237×10^{-1} | -1.3901×10^1 |
| 3 | -2.5054×10^0 | 7.2346×10^1 | -3.9875×10^{-1} | 1.1514×10^1 |
| 4 | -2.5054×10^0 | -7.2346×10^1 | -3.9875×10^{-1} | -1.1514×10^1 |
| 5 | -4.4638×10^0 | 8.1833×10^1 | -7.1044×10^{-1} | 1.3024×10^1 |
| 6 | -4.4638×10^0 | -8.1833×10^1 | -7.1044×10^{-1} | -1.3024×10^1 |
| 7 | -4.5110×10^0 | 8.2776×10^1 | -7.1795×10^{-1} | 1.3174×10^1 |
| 8 | -4.5110×10^0 | -8.2776×10^1 | -7.1795×10^{-1} | -1.3174×10^1 |
| 9 | -1.0715×10^0 | 7.1407×10^0 | -1.7053×10^{-1} | 1.1365×10^0 |
| 10 | -1.0715×10^0 | -7.1407×10^0 | -1.7053×10^{-1} | -1.1365×10^0 |
| 11 | -1.0574×10^0 | 5.4184×10^0 | -1.6829×10^{-1} | 8.6237×10^{-1} |
| 12 | -1.0574×10^0 | -5.4184×10^0 | -1.6829×10^{-1} | -8.6237×10^{-1} |
| 13 | -1.0126×10^0 | 3.7893×10^0 | -1.6116×10^{-1} | 6.0309×10^{-1} |
| 14 | -1.0126×10^0 | -3.7893×10^0 | -1.6116×10^{-1} | -6.0309×10^{-1} |
| 15 | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 |
| 16 | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 |

Note: oscillatory roots appear as complex conjugates.

There are 7 oscillatory modes, 7 damped modes, 0 unstable modes, and 2 rigid body modes.

Table 2.2: Eigenvalue Analysis

| No. | Frequency [Hz] | Damping Ratio | Time Constant [s] | Wavelength [s] |
|-----|-------------------------|-------------------------|-------------------------|-------------------------|
| 1 | 1.3924×10^1 | 5.8342×10^{-2} | 1.9591×10^{-1} | 7.1939×10^{-2} |
| 2 | 1.3924×10^1 | 5.8342×10^{-2} | 1.9591×10^{-1} | 7.1939×10^{-2} |
| 3 | 1.1521×10^1 | 3.4610×10^{-2} | 3.9914×10^{-1} | 8.6849×10^{-2} |
| 4 | 1.1521×10^1 | 3.4610×10^{-2} | 3.9914×10^{-1} | 8.6849×10^{-2} |
| 5 | 1.3043×10^1 | 5.4467×10^{-2} | 2.2402×10^{-1} | 7.6781×10^{-2} |
| 6 | 1.3043×10^1 | 5.4467×10^{-2} | 2.2402×10^{-1} | 7.6781×10^{-2} |
| 7 | 1.3194×10^1 | 5.4416×10^{-2} | 2.2168×10^{-1} | 7.5906×10^{-2} |
| 8 | 1.3194×10^1 | 5.4416×10^{-2} | 2.2168×10^{-1} | 7.5906×10^{-2} |
| 9 | 1.1492×10^0 | 1.4839×10^{-1} | 9.3327×10^{-1} | 8.7991×10^{-1} |
| 10 | 1.1492×10^0 | 1.4839×10^{-1} | 9.3327×10^{-1} | 8.7991×10^{-1} |
| 11 | 8.7863×10^{-1} | 1.9154×10^{-1} | 9.4572×10^{-1} | 1.1596×10^0 |
| 12 | 8.7863×10^{-1} | 1.9154×10^{-1} | 9.4572×10^{-1} | 1.1596×10^0 |
| 13 | 6.2425×10^{-1} | 2.5817×10^{-1} | 9.8756×10^{-1} | 1.6581×10^0 |
| 14 | 6.2425×10^{-1} | 2.5817×10^{-1} | 9.8756×10^{-1} | 1.6581×10^0 |
| 15 | – | – | – | – |
| 16 | – | – | – | – |

Notes: a) oscillatory roots are listed twice, b) negative time constants denote unstable roots.

2.2 Frequency Response Plots

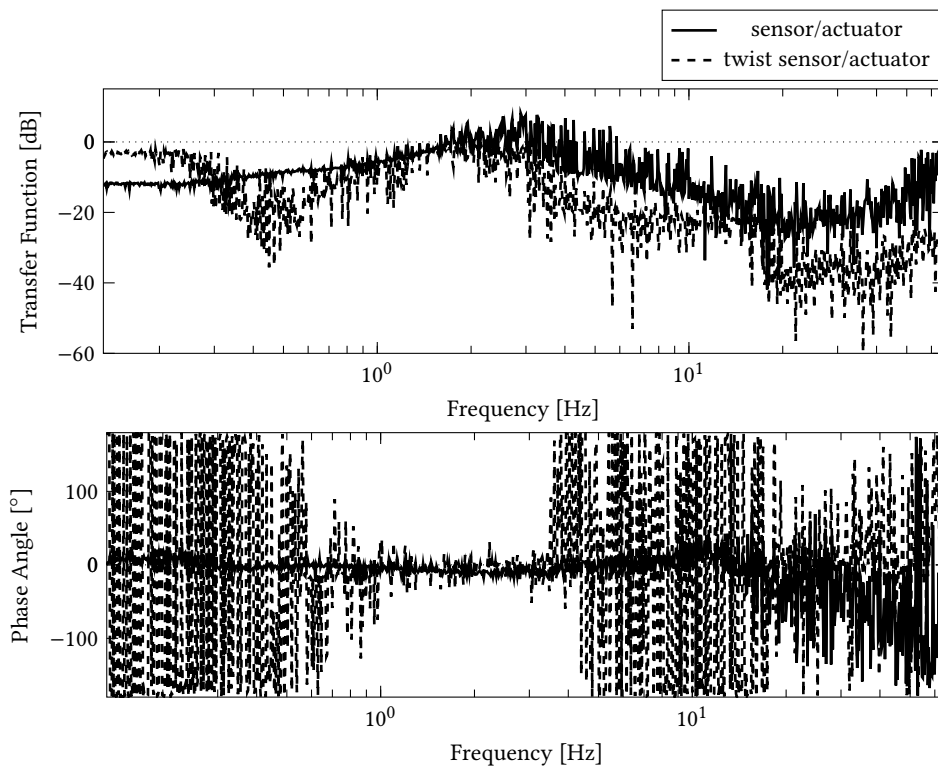


Figure 2.1: Frequency response: actuator

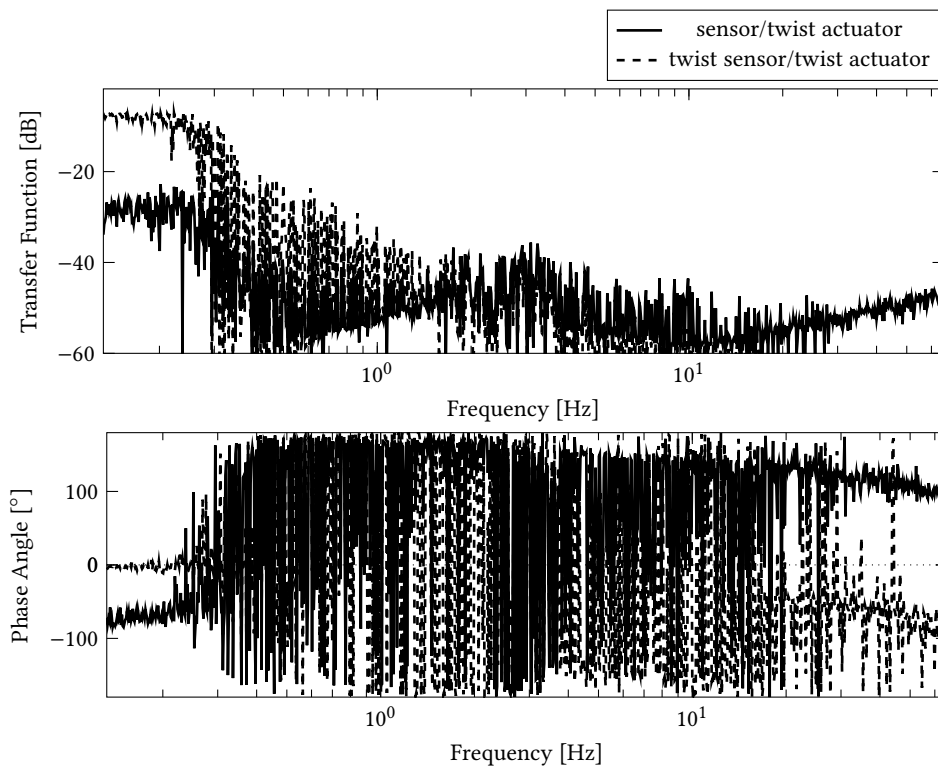


Figure 2.2: Frequency response: twist actuator

2.3 Steady State Gains

The steady state gains are given in Table 2.3.

Table 2.3: Steady State Gains

| Output/Input | Gain |
|-----------------------------|--------------------------|
| sensor/actuator | 2.5753×10^{-1} |
| sensor/twist actuator | 3.5000×10^{-7} |
| twist sensor/actuator | -7.2110×10^{-1} |
| twist sensor/twist actuator | 4.1710×10^{-1} |

2.4 Equilibrium Analysis

The results of the equilibrium load analysis are given in Tables 2.4 and 2.5.

Table 2.4: System Static Deflections

| No. | Body Name | Type | Deflection [m] or [rad] | | |
|-----|-----------|-------------|--------------------------|--------------------------|--------------------------|
| 1 | f-axle | translation | -2.0000×10^{-8} | 0.0000×10^0 | -8.8290×10^{-3} |
| – | – | rotation | 0.0000×10^0 | 1.0000×10^{-8} | -1.0000×10^{-8} |
| 2 | lf-axle | translation | -1.0000×10^{-8} | 0.0000×10^0 | -8.8290×10^{-3} |
| – | – | rotation | 0.0000×10^0 | 0.0000×10^0 | 1.0000×10^{-8} |
| 3 | rf-axle | translation | -2.0000×10^{-8} | 0.0000×10^0 | -8.8290×10^{-3} |
| – | – | rotation | -1.0000×10^{-7} | 1.1000×10^{-7} | 5.8000×10^{-7} |
| 4 | r-axle-t | translation | -1.0000×10^{-8} | 1.0000×10^{-8} | -8.8290×10^{-3} |
| – | – | rotation | 0.0000×10^0 | 1.0000×10^{-8} | -1.0000×10^{-8} |
| 5 | r-axle-b | translation | -1.0000×10^{-8} | 1.0000×10^{-8} | -8.8290×10^{-3} |
| – | – | rotation | 0.0000×10^0 | 1.0000×10^{-8} | -1.0000×10^{-8} |
| 6 | lr-axle | translation | -1.0000×10^{-8} | 1.0000×10^{-8} | -8.8290×10^{-3} |
| – | – | rotation | 0.0000×10^0 | 1.0000×10^{-8} | -1.0000×10^{-8} |
| 7 | rr-axle | translation | -2.0000×10^{-8} | 1.0000×10^{-8} | -8.8290×10^{-3} |
| – | – | rotation | 0.0000×10^0 | 1.0000×10^{-8} | -1.0000×10^{-8} |
| 8 | chassis | translation | -1.0000×10^{-8} | 0.0000×10^0 | -2.2955×10^{-1} |
| – | – | rotation | 0.0000×10^0 | 0.0000×10^0 | -1.0000×10^{-8} |
| 9 | lf-wheel | translation | -1.0000×10^{-8} | 0.0000×10^0 | -8.8290×10^{-3} |
| – | – | rotation | 0.0000×10^0 | -6.0000×10^{-8} | 1.0000×10^{-8} |
| 10 | rf-wheel | translation | 1.0000×10^{-8} | 0.0000×10^0 | -8.8290×10^{-3} |
| – | – | rotation | -1.0000×10^{-7} | 4.0000×10^{-8} | 5.8000×10^{-7} |
| 11 | lr-wheel | translation | -1.0000×10^{-8} | 0.0000×10^0 | -8.8290×10^{-3} |
| – | – | rotation | 1.0000×10^{-8} | -6.0000×10^{-8} | -1.0000×10^{-8} |
| 12 | rr-wheel | translation | -2.0000×10^{-8} | 1.0000×10^{-8} | -8.8290×10^{-3} |
| – | – | rotation | 0.0000×10^0 | -7.0000×10^{-8} | -1.0000×10^{-8} |

Table 2.5: System Preloads

| No. | Connector Name | Type | Load [N] or [Nm] (Components; Magnitude) | | | |
|-----|------------------|--------|--|-----------------------|-----------------------|-----------------------|
| 1 | lf-tire | force | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 |
| 2 | rf-tire | force | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 |
| 3 | rr-tire | force | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 |
| 4 | lr-tire | force | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 |
| 5 | lf-wb | force | 0.0000×10^0 | 0.0000×10^0 | -7.8480×10^2 | 7.8480×10^2 |
| 6 | rf-wb | force | 0.0000×10^0 | 0.0000×10^0 | -7.8480×10^2 | 7.8480×10^2 |
| 7 | lr-wb | force | 0.0000×10^0 | 0.0000×10^0 | -7.8480×10^2 | 7.8480×10^2 |
| 8 | rr-wb | force | 0.0000×10^0 | 0.0000×10^0 | -7.8480×10^2 | 7.8480×10^2 |
| 9 | lf | force | 0.0000×10^0 | -6.0445×10^1 | 7.8480×10^2 | 7.8712×10^2 |
| - | - | moment | 3.4489×10^1 | 0.0000×10^0 | 6.0445×10^0 | 3.5015×10^1 |
| 10 | rf | force | 0.0000×10^0 | 6.0445×10^1 | 7.8480×10^2 | 7.8712×10^2 |
| - | - | moment | -3.4489×10^1 | 0.0000×10^0 | -6.0445×10^0 | 3.5015×10^1 |
| 11 | lr | force | 0.0000×10^0 | -4.3274×10^2 | 2.4525×10^1 | 4.3344×10^2 |
| - | - | moment | 0.0000×10^0 | 0.0000×10^0 | -3.4948×10^0 | 3.4948×10^0 |
| 12 | rr | force | 0.0000×10^0 | 4.3274×10^2 | 2.4525×10^1 | 4.3344×10^2 |
| - | - | moment | 0.0000×10^0 | 0.0000×10^0 | 3.4948×10^0 | 3.4948×10^0 |
| 13 | lr | force | -5.9596×10^2 | 8.0062×10^2 | 2.4525×10^1 | 9.9838×10^2 |
| - | - | moment | 0.0000×10^0 | 1.7044×10^1 | -3.4948×10^0 | 1.7399×10^1 |
| 14 | rr | force | -5.9596×10^2 | -8.0062×10^2 | 2.4525×10^1 | 9.9838×10^2 |
| - | - | moment | 0.0000×10^0 | 1.7044×10^1 | 3.4948×10^0 | 1.7399×10^1 |
| 15 | lf-tire | force | 0.0000×10^0 | 0.0000×10^0 | 8.8290×10^2 | 8.8290×10^2 |
| 16 | rf-tire | force | 0.0000×10^0 | 0.0000×10^0 | 8.8290×10^2 | 8.8290×10^2 |
| 17 | rr-tire | force | 0.0000×10^0 | 0.0000×10^0 | 8.8290×10^2 | 8.8290×10^2 |
| 18 | lr-tire | force | 0.0000×10^0 | 0.0000×10^0 | 8.8290×10^2 | 8.8290×10^2 |
| 19 | front left | force | -3.6788×10^2 | 3.6788×10^2 | -7.3575×10^2 | -9.0111×10^2 |
| 20 | front right | force | -3.6788×10^2 | -3.6788×10^2 | -7.3575×10^2 | -9.0111×10^2 |
| 21 | rear left | force | -3.6788×10^2 | 3.6788×10^2 | -7.3575×10^2 | -9.0111×10^2 |
| 22 | rear right | force | -3.6788×10^2 | -3.6788×10^2 | -7.3575×10^2 | -9.0111×10^2 |
| 23 | right-b | force | 5.0767×10^2 | 6.7689×10^2 | 0.0000×10^0 | -8.4611×10^2 |
| 24 | left-b | force | 5.0767×10^2 | -6.7689×10^2 | 0.0000×10^0 | -8.4611×10^2 |
| 25 | right-b | force | -1.3979×10^2 | 0.0000×10^0 | 0.0000×10^0 | 1.3979×10^2 |
| 26 | left-b | force | -1.3979×10^2 | 0.0000×10^0 | 0.0000×10^0 | 1.3979×10^2 |
| 27 | lf-tie-rod | force | 0.0000×10^0 | -6.0445×10^1 | 0.0000×10^0 | 6.0445×10^1 |
| 28 | rf-tie-rod | force | 0.0000×10^0 | 6.0445×10^1 | 0.0000×10^0 | 6.0445×10^1 |
| 29 | right rear lower | force | 5.9596×10^2 | -9.9326×10^2 | 0.0000×10^0 | 1.1583×10^3 |
| 30 | left rear lower | force | 5.9596×10^2 | 9.9326×10^2 | 0.0000×10^0 | 1.1583×10^3 |
| 31 | right rear upper | force | -2.2808×10^2 | 0.0000×10^0 | 0.0000×10^0 | -2.2808×10^2 |
| 32 | left rear upper | force | -2.2808×10^2 | 0.0000×10^0 | 0.0000×10^0 | -2.2808×10^2 |
| 33 | left rear upper | force | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 | 0.0000×10^0 |

CHAPTER 3

CONCLUSION

Replace this text with the conclusion to your report.

APPENDIX A

EQUATIONS OF MOTION

The equations of motion are of the form

$$\begin{bmatrix} \mathbf{I} & \mathbf{0} \\ \mathbf{0} & \mathbf{M} \end{bmatrix} \begin{Bmatrix} \dot{\mathbf{p}} \\ \dot{\mathbf{w}} \end{Bmatrix} + \begin{bmatrix} \mathbf{V} & -\mathbf{I} \\ \mathbf{K} & \mathbf{C} \end{bmatrix} \begin{Bmatrix} \mathbf{p} \\ \mathbf{w} \end{Bmatrix} = \begin{Bmatrix} \mathbf{0} \\ \mathbf{f} \end{Bmatrix} + \begin{bmatrix} \mathbf{0} \\ \mathbf{F} \end{bmatrix} \{\mathbf{u}\}$$

The mass matrix of the system is

| Row | Column | Value | Row | Column | Value | Row | Column | Value |
|-----|--------|-------------------------|-----|--------|-------------------------|-----|--------|-------------------------|
| 1 | 1 | 1.0000×10^1 | 43 | 43 | 3.0000×10^2 | 58 | 58 | 5.0000×10^{-1} |
| 2 | 2 | 1.0000×10^1 | 44 | 44 | 3.0000×10^2 | 59 | 59 | 1.0000×10^0 |
| 3 | 3 | 1.0000×10^1 | 45 | 45 | 3.0000×10^2 | 60 | 60 | 5.0000×10^{-1} |
| 4 | 4 | 1.6333×10^0 | 46 | 46 | 5.0000×10^1 | 61 | 61 | 1.0000×10^1 |
| 6 | 6 | 1.6333×10^0 | 47 | 47 | 1.2000×10^2 | 62 | 62 | 1.0000×10^1 |
| 19 | 19 | 5.0000×10^0 | 48 | 48 | 1.8000×10^2 | 63 | 63 | 1.0000×10^1 |
| 20 | 20 | 5.0000×10^0 | 49 | 49 | 1.0000×10^1 | 64 | 64 | 5.0000×10^{-1} |
| 21 | 21 | 5.0000×10^0 | 50 | 50 | 1.0000×10^1 | 65 | 65 | 1.0000×10^0 |
| 22 | 22 | 8.1667×10^{-1} | 51 | 51 | 1.0000×10^1 | 66 | 66 | 5.0000×10^{-1} |
| 24 | 24 | 8.1667×10^{-1} | 52 | 52 | 5.0000×10^{-1} | 67 | 67 | 1.0000×10^1 |
| 25 | 25 | 5.0000×10^0 | 53 | 53 | 1.0000×10^0 | 68 | 68 | 1.0000×10^1 |
| 26 | 26 | 5.0000×10^0 | 54 | 54 | 5.0000×10^{-1} | 69 | 69 | 1.0000×10^1 |
| 27 | 27 | 5.0000×10^0 | 55 | 55 | 1.0000×10^1 | 70 | 70 | 5.0000×10^{-1} |
| 28 | 28 | 8.1667×10^{-1} | 56 | 56 | 1.0000×10^1 | 71 | 71 | 1.0000×10^0 |
| 30 | 30 | 8.1667×10^{-1} | 57 | 57 | 1.0000×10^1 | 72 | 72 | 5.0000×10^{-1} |

The damping matrix is

| Row | Column | Value | Row | Column | Value | Row | Column | Value |
|-----|--------|-----------------------|-----|--------|--------------------------|-----|--------|--------------------------|
| 1 | 1 | 6.6667×10^1 | 31 | 36 | -4.0000×10^{-1} | 40 | 43 | -7.6200×10^0 |
| 3 | 1 | 1.3333×10^2 | 32 | 36 | 4.0000×10^{-1} | 41 | 43 | 8.4200×10^0 |
| 5 | 1 | -5.0667×10^0 | 33 | 36 | -8.0000×10^{-1} | 42 | 43 | -4.0000×10^{-1} |
| 43 | 1 | -6.6667×10^1 | 34 | 36 | 9.1440×10^{-2} | 43 | 43 | 1.3333×10^2 |

A. EQUATIONS OF MOTION

| | | | | | | | | |
|----|----|--------------------------|----|----|--------------------------|----|----|--------------------------|
| 45 | 1 | -1.3333×10^2 | 35 | 36 | 1.0104×10^{-1} | 45 | 43 | 2.6667×10^2 |
| 47 | 1 | 1.2000×10^2 | 36 | 36 | 4.8000×10^{-3} | 47 | 43 | -4.0000×10^1 |
| 2 | 2 | 6.6667×10^1 | 43 | 36 | 4.0000×10^{-1} | 2 | 44 | -6.6667×10^1 |
| 4 | 2 | -6.6667×10^1 | 44 | 36 | -4.0000×10^{-1} | 4 | 44 | 6.6667×10^1 |
| 6 | 2 | 3.5867×10^1 | 45 | 36 | 8.0000×10^{-1} | 6 | 44 | -3.5867×10^1 |
| 44 | 2 | -6.6667×10^1 | 46 | 36 | 3.2000×10^{-1} | 31 | 44 | 3.3333×10^1 |
| 46 | 2 | 5.3333×10^1 | 47 | 36 | 4.8000×10^{-1} | 32 | 44 | -3.3333×10^1 |
| 48 | 2 | -8.6667×10^1 | 48 | 36 | 8.0000×10^{-2} | 33 | 44 | 6.6667×10^1 |
| 1 | 3 | 1.3333×10^2 | 37 | 37 | 3.3333×10^1 | 34 | 44 | -7.6200×10^0 |
| 3 | 3 | 2.6667×10^2 | 38 | 37 | 3.3333×10^1 | 35 | 44 | -8.4200×10^0 |
| 5 | 3 | -1.0133×10^1 | 39 | 37 | 6.6667×10^1 | 36 | 44 | -4.0000×10^{-1} |
| 43 | 3 | -1.3333×10^2 | 40 | 37 | 7.6200×10^0 | 37 | 44 | -3.3333×10^1 |
| 45 | 3 | -2.6667×10^2 | 41 | 37 | -8.4200×10^0 | 38 | 44 | -3.3333×10^1 |
| 47 | 3 | 2.4000×10^2 | 42 | 37 | 4.0000×10^{-1} | 39 | 44 | -6.6667×10^1 |
| 2 | 4 | -6.6667×10^1 | 43 | 37 | -3.3333×10^1 | 40 | 44 | -7.6200×10^0 |
| 4 | 4 | 6.6667×10^1 | 44 | 37 | -3.3333×10^1 | 41 | 44 | 8.4200×10^0 |
| 6 | 4 | -3.5867×10^1 | 45 | 37 | -6.6667×10^1 | 42 | 44 | -4.0000×10^{-1} |
| 44 | 4 | 6.6667×10^1 | 46 | 37 | 2.6667×10^1 | 44 | 44 | 1.3333×10^2 |
| 46 | 4 | -5.3333×10^1 | 47 | 37 | -4.0000×10^1 | 46 | 44 | -1.0667×10^2 |
| 48 | 4 | 8.6667×10^1 | 48 | 37 | 6.6667×10^0 | 48 | 44 | 7.3333×10^1 |
| 1 | 5 | -5.0667×10^0 | 37 | 38 | 3.3333×10^1 | 1 | 45 | -1.3333×10^2 |
| 3 | 5 | -1.0133×10^1 | 38 | 38 | 3.3333×10^1 | 3 | 45 | -2.6667×10^2 |
| 5 | 5 | 3.8507×10^{-1} | 39 | 38 | 6.6667×10^1 | 5 | 45 | 1.0133×10^1 |
| 43 | 5 | 5.0667×10^0 | 40 | 38 | 7.6200×10^0 | 31 | 45 | -6.6667×10^1 |
| 45 | 5 | 1.0133×10^1 | 41 | 38 | -8.4200×10^0 | 32 | 45 | 6.6667×10^1 |
| 47 | 5 | -9.1200×10^0 | 42 | 38 | 4.0000×10^{-1} | 33 | 45 | -1.3333×10^2 |
| 2 | 6 | 3.5867×10^1 | 43 | 38 | -3.3333×10^1 | 34 | 45 | 1.5240×10^1 |
| 4 | 6 | -3.5867×10^1 | 44 | 38 | -3.3333×10^1 | 35 | 45 | 1.6840×10^1 |
| 6 | 6 | 1.9296×10^1 | 45 | 38 | -6.6667×10^1 | 36 | 45 | 8.0000×10^{-1} |
| 44 | 6 | -3.5867×10^1 | 46 | 38 | 2.6667×10^1 | 37 | 45 | -6.6667×10^1 |
| 46 | 6 | 2.8693×10^1 | 47 | 38 | -4.0000×10^1 | 38 | 45 | -6.6667×10^1 |
| 48 | 6 | -4.6627×10^1 | 48 | 38 | 6.6667×10^0 | 39 | 45 | -1.3333×10^2 |
| 31 | 31 | 3.3333×10^1 | 37 | 39 | 6.6667×10^1 | 40 | 45 | -1.5240×10^1 |
| 32 | 31 | -3.3333×10^1 | 38 | 39 | 6.6667×10^1 | 41 | 45 | 1.6840×10^1 |
| 33 | 31 | 6.6667×10^1 | 39 | 39 | 1.3333×10^2 | 42 | 45 | -8.0000×10^{-1} |
| 34 | 31 | -7.6200×10^0 | 40 | 39 | 1.5240×10^1 | 43 | 45 | 2.6667×10^2 |
| 35 | 31 | -8.4200×10^0 | 41 | 39 | -1.6840×10^1 | 45 | 45 | 5.3333×10^2 |
| 36 | 31 | -4.0000×10^{-1} | 42 | 39 | 8.0000×10^{-1} | 47 | 45 | -8.0000×10^1 |
| 43 | 31 | -3.3333×10^1 | 43 | 39 | -6.6667×10^1 | 2 | 46 | 5.3333×10^1 |
| 44 | 31 | 3.3333×10^1 | 44 | 39 | -6.6667×10^1 | 4 | 46 | -5.3333×10^1 |
| 45 | 31 | -6.6667×10^1 | 45 | 39 | -1.3333×10^2 | 6 | 46 | 2.8693×10^1 |
| 46 | 31 | -2.6667×10^1 | 46 | 39 | 5.3333×10^1 | 31 | 46 | -2.6667×10^1 |
| 47 | 31 | -4.0000×10^1 | 47 | 39 | -8.0000×10^1 | 32 | 46 | 2.6667×10^1 |
| 48 | 31 | -6.6667×10^0 | 48 | 39 | 1.3333×10^1 | 33 | 46 | -5.3333×10^1 |
| 31 | 32 | -3.3333×10^1 | 37 | 40 | 7.6200×10^0 | 34 | 46 | 6.0960×10^0 |
| 32 | 32 | 3.3333×10^1 | 38 | 40 | 7.6200×10^0 | 35 | 46 | 6.7360×10^0 |
| 33 | 32 | -6.6667×10^1 | 39 | 40 | 1.5240×10^1 | 36 | 46 | 3.2000×10^{-1} |
| 34 | 32 | 7.6200×10^0 | 40 | 40 | 1.7419×10^0 | 37 | 46 | 2.6667×10^1 |
| 35 | 32 | 8.4200×10^0 | 41 | 40 | -1.9248×10^0 | 38 | 46 | 2.6667×10^1 |
| 36 | 32 | 4.0000×10^{-1} | 42 | 40 | 9.1440×10^{-2} | 39 | 46 | 5.3333×10^1 |
| 43 | 32 | 3.3333×10^1 | 43 | 40 | -7.6200×10^0 | 40 | 46 | 6.0960×10^0 |
| 44 | 32 | -3.3333×10^1 | 44 | 40 | -7.6200×10^0 | 41 | 46 | -6.7360×10^0 |
| 45 | 32 | 6.6667×10^1 | 45 | 40 | -1.5240×10^1 | 42 | 46 | 3.2000×10^{-1} |
| 46 | 32 | 2.6667×10^1 | 46 | 40 | 6.0960×10^0 | 44 | 46 | -1.0667×10^2 |
| 47 | 32 | 4.0000×10^1 | 47 | 40 | -9.1440×10^0 | 46 | 46 | 8.5333×10^1 |
| 48 | 32 | 6.6667×10^0 | 48 | 40 | 1.5240×10^0 | 48 | 46 | -5.8667×10^1 |
| 31 | 33 | 6.6667×10^1 | 37 | 41 | -8.4200×10^0 | 1 | 47 | 1.2000×10^2 |
| 32 | 33 | -6.6667×10^1 | 38 | 41 | -8.4200×10^0 | 3 | 47 | 2.4000×10^2 |

A. EQUATIONS OF MOTION

| | | | | | | | | |
|----|----|--------------------------|----|----|--------------------------|----|----|--------------------------|
| 33 | 33 | 1.3333×10^2 | 39 | 41 | -1.6840×10^1 | 5 | 47 | -9.1200×10^0 |
| 34 | 33 | -1.5240×10^1 | 40 | 41 | -1.9248×10^0 | 31 | 47 | -4.0000×10^1 |
| 35 | 33 | -1.6840×10^1 | 41 | 41 | 2.1269×10^0 | 32 | 47 | 4.0000×10^1 |
| 36 | 33 | -8.0000×10^{-1} | 42 | 41 | -1.0104×10^{-1} | 33 | 47 | -8.0000×10^1 |
| 43 | 33 | -6.6667×10^1 | 43 | 41 | 8.4200×10^0 | 34 | 47 | 9.1440×10^0 |
| 44 | 33 | 6.6667×10^1 | 44 | 41 | 8.4200×10^0 | 35 | 47 | 1.0104×10^1 |
| 45 | 33 | -1.3333×10^2 | 45 | 41 | 1.6840×10^1 | 36 | 47 | 4.8000×10^{-1} |
| 46 | 33 | -5.3333×10^1 | 46 | 41 | -6.7360×10^0 | 37 | 47 | -4.0000×10^1 |
| 47 | 33 | -8.0000×10^1 | 47 | 41 | 1.0104×10^1 | 38 | 47 | -4.0000×10^1 |
| 48 | 33 | -1.3333×10^1 | 48 | 41 | -1.6840×10^0 | 39 | 47 | -8.0000×10^1 |
| 31 | 34 | -7.6200×10^0 | 37 | 42 | 4.0000×10^{-1} | 40 | 47 | -9.1440×10^0 |
| 32 | 34 | 7.6200×10^0 | 38 | 42 | 4.0000×10^{-1} | 41 | 47 | 1.0104×10^1 |
| 33 | 34 | -1.5240×10^1 | 39 | 42 | 8.0000×10^{-1} | 42 | 47 | -4.8000×10^{-1} |
| 34 | 34 | 1.7419×10^0 | 40 | 42 | 9.1440×10^{-2} | 43 | 47 | -4.0000×10^1 |
| 35 | 34 | 1.9248×10^0 | 41 | 42 | -1.0104×10^{-1} | 45 | 47 | -8.0000×10^1 |
| 36 | 34 | 9.1440×10^{-2} | 42 | 42 | 4.8000×10^{-3} | 47 | 47 | 3.1200×10^2 |
| 43 | 34 | 7.6200×10^0 | 43 | 42 | -4.0000×10^{-1} | 2 | 48 | -8.6667×10^1 |
| 44 | 34 | -7.6200×10^0 | 44 | 42 | -4.0000×10^{-1} | 4 | 48 | 8.6667×10^1 |
| 45 | 34 | 1.5240×10^1 | 45 | 42 | -8.0000×10^{-1} | 6 | 48 | -4.6627×10^1 |
| 46 | 34 | 6.0960×10^0 | 46 | 42 | 3.2000×10^{-1} | 31 | 48 | -6.6667×10^0 |
| 47 | 34 | 9.1440×10^0 | 47 | 42 | -4.8000×10^{-1} | 32 | 48 | 6.6667×10^0 |
| 48 | 34 | 1.5240×10^0 | 48 | 42 | 8.0000×10^{-2} | 33 | 48 | -1.3333×10^1 |
| 31 | 35 | -8.4200×10^0 | 1 | 43 | -6.6667×10^1 | 34 | 48 | 1.5240×10^0 |
| 32 | 35 | 8.4200×10^0 | 3 | 43 | -1.3333×10^2 | 35 | 48 | 1.6840×10^0 |
| 33 | 35 | -1.6840×10^1 | 5 | 43 | 5.0667×10^0 | 36 | 48 | 8.0000×10^{-2} |
| 34 | 35 | 1.9248×10^0 | 31 | 43 | -3.3333×10^1 | 37 | 48 | 6.6667×10^0 |
| 35 | 35 | 2.1269×10^0 | 32 | 43 | 3.3333×10^1 | 38 | 48 | 6.6667×10^0 |
| 36 | 35 | 1.0104×10^{-1} | 33 | 43 | -6.6667×10^1 | 39 | 48 | 1.3333×10^1 |
| 43 | 35 | 8.4200×10^0 | 34 | 43 | 7.6200×10^0 | 40 | 48 | 1.5240×10^0 |
| 44 | 35 | -8.4200×10^0 | 35 | 43 | 8.4200×10^0 | 41 | 48 | -1.6840×10^0 |
| 45 | 35 | 1.6840×10^1 | 36 | 43 | 4.0000×10^{-1} | 42 | 48 | 8.0000×10^{-2} |
| 46 | 35 | 6.7360×10^0 | 37 | 43 | -3.3333×10^1 | 44 | 48 | 7.3333×10^1 |
| 47 | 35 | 1.0104×10^1 | 38 | 43 | -3.3333×10^1 | 46 | 48 | -5.8667×10^1 |
| 48 | 35 | 1.6840×10^0 | 39 | 43 | -6.6667×10^1 | 48 | 48 | 1.1533×10^2 |

The stiffness matrix is

| Row | Column | Value | Row | Column | Value | Row | Column | Value |
|-----|--------|--------------------------|-----|--------|---------------------------|-----|--------|--------------------------|
| 1 | 1 | -6.6306×10^3 | 44 | 26 | -1.0517×10^3 | 26 | 44 | -1.0517×10^3 |
| 2 | 1 | 5.2477×10^{-8} | 46 | 26 | -2.1034×10^2 | 28 | 44 | -3.0078×10^1 |
| 3 | 1 | 5.7858×10^3 | 47 | 26 | 5.3562×10^{-9} | 29 | 44 | 7.6593×10^{-10} |
| 4 | 1 | -2.9833×10^{-8} | 48 | 26 | -3.9053×10^2 | 31 | 44 | 1.4465×10^3 |
| 5 | 1 | -2.1986×10^2 | 27 | 27 | 3.9731×10^3 | 32 | 44 | 2.9926×10^3 |
| 6 | 1 | -7.3449×10^{-8} | 34 | 27 | -8.0062×10^2 | 33 | 44 | 2.8929×10^3 |
| 11 | 1 | -7.8480×10^2 | 35 | 27 | -5.9596×10^2 | 34 | 44 | 8.8143×10^1 |
| 12 | 1 | -6.0445×10^1 | 40 | 27 | 8.0062×10^2 | 35 | 44 | -3.6538×10^2 |
| 17 | 1 | -7.8480×10^2 | 41 | 27 | -5.9596×10^2 | 36 | 44 | 2.1073×10^2 |
| 18 | 1 | 6.0445×10^1 | 45 | 27 | -3.9731×10^3 | 37 | 44 | -1.4465×10^3 |
| 43 | 1 | 6.6306×10^3 | 46 | 27 | 3.0352×10^{-8} | 38 | 44 | 2.9926×10^3 |
| 44 | 1 | -5.2477×10^{-8} | 47 | 27 | -1.8355×10^3 | 39 | 44 | -2.8929×10^3 |
| 45 | 1 | -5.7858×10^3 | 25 | 28 | 7.6593×10^{-10} | 40 | 44 | 8.8143×10^1 |
| 46 | 1 | 1.9338×10^{-8} | 26 | 28 | 3.0078×10^1 | 41 | 44 | 3.6538×10^2 |
| 47 | 1 | 4.7740×10^3 | 27 | 28 | -6.0595×10^{-11} | 42 | 44 | 2.1073×10^2 |
| 48 | 1 | 3.4431×10^{-8} | 28 | 28 | 8.8154×10^2 | 43 | 44 | 5.5079×10^{-8} |
| 1 | 2 | 5.2477×10^{-8} | 29 | 28 | 9.1316×10^{-10} | 44 | 44 | -9.6845×10^3 |

| | | | | | | | | |
|----|---|---------------------------|----|----|---------------------------|----|----|--------------------------|
| 2 | 2 | -4.7510×10^3 | 30 | 28 | 3.4089×10^1 | 45 | 44 | 1.1672×10^{-8} |
| 3 | 2 | 5.9666×10^{-8} | 34 | 28 | -4.4034×10^2 | 46 | 44 | -4.6620×10^3 |
| 4 | 2 | -3.0793×10^3 | 35 | 28 | -3.2778×10^2 | 47 | 44 | -9.2380×10^{-8} |
| 5 | 2 | -2.2673×10^{-9} | 40 | 28 | -4.4034×10^2 | 48 | 44 | 2.5855×10^3 |
| 6 | 2 | 1.2768×10^3 | 41 | 28 | 3.2778×10^2 | 1 | 45 | -5.7858×10^3 |
| 10 | 2 | 7.8480×10^2 | 43 | 28 | -7.6593×10^{-10} | 2 | 45 | -5.9666×10^{-8} |
| 12 | 2 | -1.3971×10^{-9} | 44 | 28 | -3.0078×10^1 | 3 | 45 | -1.7617×10^3 |
| 16 | 2 | 7.8480×10^2 | 46 | 28 | -6.0157×10^0 | 4 | 45 | -6.4523×10^{-8} |
| 18 | 2 | 1.9140×10^{-10} | 47 | 28 | 1.5319×10^{-10} | 5 | 45 | 1.6014×10^2 |
| 43 | 2 | -5.2477×10^{-8} | 48 | 28 | -1.1169×10^1 | 6 | 45 | -3.2100×10^{-8} |
| 44 | 2 | 4.7510×10^3 | 25 | 29 | -8.3551×10^1 | 9 | 45 | -1.5111×10^2 |
| 45 | 2 | -5.9666×10^{-8} | 26 | 29 | -7.6593×10^{-10} | 10 | 45 | 7.5556×10^0 |
| 46 | 2 | 2.5580×10^3 | 27 | 29 | -2.0236×10^{-11} | 11 | 45 | -1.5111×10^1 |
| 47 | 2 | 5.8228×10^{-8} | 28 | 29 | 9.1288×10^{-10} | 15 | 45 | -1.5111×10^2 |
| 48 | 2 | 2.3435×10^3 | 29 | 29 | 2.3896×10^0 | 16 | 45 | -7.5556×10^0 |
| 1 | 3 | 5.7858×10^3 | 30 | 29 | -7.4883×10^{-10} | 17 | 45 | -1.5111×10^1 |
| 2 | 3 | 5.9666×10^{-8} | 43 | 29 | 8.3551×10^1 | 27 | 45 | -3.9731×10^3 |
| 3 | 3 | 1.7617×10^3 | 44 | 29 | 7.6593×10^{-10} | 31 | 45 | -2.8929×10^3 |
| 4 | 3 | 6.4523×10^{-8} | 46 | 29 | 1.5319×10^{-10} | 32 | 45 | 2.8929×10^3 |
| 5 | 3 | -1.6014×10^2 | 47 | 29 | -1.6710×10^1 | 33 | 45 | -1.3468×10^3 |
| 6 | 3 | 3.2100×10^{-8} | 48 | 29 | 2.8442×10^{-10} | 34 | 45 | 4.3937×10^2 |
| 10 | 3 | 6.0445×10^1 | 25 | 30 | 6.0595×10^{-11} | 35 | 45 | 5.0267×10^2 |
| 11 | 3 | 1.3971×10^{-9} | 26 | 30 | 2.0236×10^{-11} | 36 | 45 | 3.4715×10^1 |
| 16 | 3 | -6.0445×10^1 | 28 | 30 | 3.4089×10^1 | 37 | 45 | -2.8929×10^3 |
| 17 | 3 | -1.9140×10^{-10} | 29 | 30 | -8.6805×10^{-10} | 38 | 45 | -2.8929×10^3 |
| 43 | 3 | -5.7858×10^3 | 30 | 30 | 8.8068×10^2 | 39 | 45 | -1.3468×10^3 |
| 44 | 3 | -5.9666×10^{-8} | 35 | 30 | 1.3489×10^1 | 40 | 45 | -4.3937×10^2 |
| 45 | 3 | -1.7617×10^3 | 36 | 30 | -4.4034×10^2 | 41 | 45 | 5.0267×10^2 |
| 46 | 3 | -7.7427×10^{-8} | 41 | 30 | -1.3489×10^1 | 42 | 45 | -3.4715×10^1 |
| 47 | 3 | 2.6597×10^3 | 42 | 30 | -4.4034×10^2 | 43 | 45 | 1.1572×10^4 |
| 48 | 3 | -7.7565×10^{-8} | 31 | 31 | -2.2323×10^3 | 44 | 45 | 1.1672×10^{-8} |
| 1 | 4 | -2.9833×10^{-8} | 32 | 31 | -1.4465×10^3 | 45 | 45 | 8.7306×10^3 |
| 2 | 4 | -3.0793×10^3 | 33 | 31 | 2.8929×10^3 | 46 | 45 | 6.3581×10^{-8} |
| 3 | 4 | 6.3089×10^{-8} | 34 | 31 | -3.3066×10^2 | 47 | 45 | 8.0179×10^2 |
| 4 | 4 | 1.8274×10^3 | 35 | 31 | -6.2804×10^2 | 48 | 45 | 8.7164×10^{-8} |
| 5 | 4 | -2.9639×10^{-10} | 36 | 31 | -5.6917×10^2 | 1 | 46 | 1.9338×10^{-8} |
| 6 | 4 | -1.5025×10^3 | 43 | 31 | 2.2323×10^3 | 2 | 46 | 2.5580×10^3 |
| 10 | 4 | -6.7681×10^1 | 44 | 31 | 1.4465×10^3 | 3 | 46 | -7.7427×10^{-8} |
| 11 | 4 | 7.6840×10^{-10} | 45 | 31 | -2.8929×10^3 | 4 | 46 | -1.0758×10^3 |
| 12 | 4 | 1.7967×10^{-10} | 46 | 31 | -1.1572×10^3 | 5 | 46 | 9.0692×10^{-10} |
| 16 | 4 | -6.7681×10^1 | 47 | 31 | -1.7358×10^3 | 6 | 46 | 1.2451×10^3 |
| 17 | 4 | 1.0527×10^{-10} | 48 | 31 | -1.7608×10^3 | 9 | 46 | -1.5111×10^1 |
| 18 | 4 | -2.4615×10^{-11} | 31 | 32 | -1.4465×10^3 | 10 | 46 | 7.5556×10^{-1} |
| 43 | 4 | 2.9833×10^{-8} | 32 | 32 | -2.9926×10^3 | 11 | 46 | -1.5111×10^0 |
| 44 | 4 | 3.0793×10^3 | 33 | 32 | -2.8929×10^3 | 15 | 46 | 1.5111×10^1 |
| 45 | 4 | -6.4523×10^{-8} | 34 | 32 | 6.4761×10^2 | 16 | 46 | 7.5556×10^{-1} |
| 46 | 4 | -1.0758×10^3 | 35 | 32 | 3.6538×10^2 | 17 | 46 | 1.5111×10^0 |
| 47 | 4 | 4.2877×10^{-8} | 36 | 32 | -8.0668×10^2 | 25 | 46 | -5.3562×10^{-9} |
| 48 | 4 | 3.8469×10^3 | 43 | 32 | 1.4465×10^3 | 26 | 46 | -2.1034×10^2 |
| 1 | 5 | -2.1986×10^2 | 44 | 32 | 2.9926×10^3 | 27 | 46 | 3.0352×10^{-8} |
| 2 | 5 | -2.2673×10^{-9} | 45 | 32 | 2.8929×10^3 | 28 | 46 | -6.0157×10^0 |
| 3 | 5 | -1.6014×10^2 | 46 | 32 | 1.1572×10^3 | 29 | 46 | 1.5319×10^{-10} |
| 4 | 5 | -5.6316×10^{-10} | 47 | 32 | 1.7358×10^3 | 31 | 46 | -1.1572×10^3 |
| 5 | 5 | 1.6824×10^2 | 48 | 32 | -2.2692×10^3 | 32 | 46 | 1.1572×10^3 |
| 6 | 5 | -1.8595×10^{-9} | 31 | 33 | 2.8929×10^3 | 33 | 46 | -4.6270×10^2 |
| 11 | 5 | -1.0093×10^2 | 32 | 33 | -2.8929×10^3 | 34 | 46 | 1.7195×10^2 |
| 12 | 5 | -7.7732×10^0 | 33 | 33 | 1.3468×10^3 | 35 | 46 | 2.0107×10^2 |
| 17 | 5 | -1.0093×10^2 | 34 | 33 | -7.1495×10^1 | 36 | 46 | 1.3886×10^1 |

A. EQUATIONS OF MOTION

| | | | | | | | | |
|----|----|---------------------------|----|----|-----------------------|----|----|--------------------------|
| 18 | 5 | 7.7732×10^0 | 35 | 33 | 9.3289×10^1 | 37 | 46 | 1.1572×10^3 |
| 43 | 5 | 2.1986×10^2 | 36 | 33 | -3.4715×10^1 | 38 | 46 | 1.1572×10^3 |
| 44 | 5 | 2.2673×10^{-9} | 43 | 33 | -2.8929×10^3 | 39 | 46 | 4.6270×10^2 |
| 45 | 5 | 1.6014×10^2 | 44 | 33 | 2.8929×10^3 | 40 | 46 | 1.7195×10^2 |
| 46 | 5 | 9.0692×10^{-10} | 45 | 33 | -1.3468×10^3 | 41 | 46 | -2.0107×10^2 |
| 47 | 5 | -1.4412×10^2 | 46 | 33 | -4.6270×10^2 | 42 | 46 | 1.3886×10^1 |
| 48 | 5 | 2.9475×10^{-9} | 47 | 33 | -9.1300×10^2 | 43 | 46 | 5.2158×10^{-9} |
| 1 | 6 | -7.2014×10^{-8} | 48 | 33 | -5.7858×10^2 | 44 | 46 | -4.6620×10^3 |
| 2 | 6 | 1.2768×10^3 | 31 | 34 | -3.3066×10^2 | 45 | 46 | 6.4217×10^{-8} |
| 3 | 6 | 3.2100×10^{-8} | 32 | 34 | -8.8143×10^1 | 46 | 46 | 6.2123×10^2 |
| 4 | 6 | -1.5025×10^3 | 33 | 34 | -4.3937×10^2 | 47 | 46 | -7.3952×10^{-8} |
| 5 | 6 | -1.8068×10^{-9} | 34 | 34 | 7.6000×10^1 | 48 | 46 | -2.8917×10^3 |
| 6 | 6 | -7.2785×10^2 | 35 | 34 | 4.2323×10^1 | 1 | 47 | 4.7740×10^3 |
| 11 | 6 | 4.3164×10^2 | 36 | 34 | -5.6387×10^1 | 2 | 47 | 5.8228×10^{-8} |
| 12 | 6 | 3.3245×10^1 | 43 | 34 | 3.3066×10^2 | 3 | 47 | 2.6597×10^3 |
| 17 | 6 | -4.3164×10^2 | 44 | 34 | 8.8143×10^1 | 4 | 47 | 4.2877×10^{-8} |
| 18 | 6 | 3.3245×10^1 | 45 | 34 | 4.3937×10^2 | 5 | 47 | -1.4412×10^2 |
| 43 | 6 | 7.3449×10^{-8} | 46 | 34 | 1.7195×10^2 | 6 | 47 | 2.8890×10^{-8} |
| 44 | 6 | -1.2768×10^3 | 47 | 34 | 2.6887×10^2 | 7 | 47 | 2.2667×10^1 |
| 45 | 6 | -3.2100×10^{-8} | 48 | 34 | -1.9264×10^2 | 9 | 47 | 1.0004×10^2 |
| 46 | 6 | 1.2451×10^3 | 31 | 35 | 1.0771×10^2 | 10 | 47 | -5.0018×10^0 |
| 47 | 6 | 2.8890×10^{-8} | 32 | 35 | 3.6538×10^2 | 11 | 47 | 8.2220×10^0 |
| 48 | 6 | -3.0018×10^2 | 33 | 35 | -5.0267×10^2 | 12 | 47 | 1.1333×10^0 |
| 7 | 7 | 1.5111×10^2 | 34 | 35 | 4.2323×10^1 | 13 | 47 | 2.2667×10^1 |
| 11 | 7 | -1.1877×10^1 | 35 | 35 | 8.9123×10^1 | 15 | 47 | 1.0004×10^2 |
| 12 | 7 | 6.8000×10^1 | 36 | 35 | 7.5348×10^1 | 16 | 47 | 5.0018×10^0 |
| 43 | 7 | -1.5111×10^2 | 43 | 35 | -1.0771×10^2 | 17 | 47 | 8.2220×10^0 |
| 47 | 7 | 2.2667×10^1 | 44 | 35 | -3.6538×10^2 | 18 | 47 | -1.1333×10^0 |
| 48 | 7 | 1.5111×10^1 | 45 | 35 | 5.0267×10^2 | 25 | 47 | 5.8427×10^2 |
| 10 | 8 | -2.0327×10^{-10} | 46 | 35 | 2.0107×10^2 | 26 | 47 | 5.3562×10^{-9} |
| 12 | 8 | 1.5716×10^{-10} | 47 | 35 | 3.0160×10^2 | 27 | 47 | -1.8355×10^3 |
| 9 | 9 | 1.5111×10^2 | 48 | 35 | 2.6231×10^2 | 28 | 47 | 1.5319×10^{-10} |
| 10 | 9 | -6.8000×10^1 | 31 | 36 | -2.0130×10^2 | 29 | 47 | -1.6710×10^1 |
| 11 | 9 | 1.5111×10^1 | 32 | 36 | -2.1073×10^2 | 31 | 47 | -1.7358×10^3 |
| 45 | 9 | -1.5111×10^2 | 33 | 36 | -3.4715×10^1 | 32 | 47 | 1.7358×10^3 |
| 46 | 9 | -1.5111×10^1 | 34 | 36 | 3.2086×10^0 | 33 | 47 | -9.1300×10^2 |
| 47 | 9 | 1.0004×10^2 | 35 | 36 | -8.7486×10^0 | 34 | 47 | 2.6887×10^2 |
| 8 | 10 | 2.0327×10^{-10} | 36 | 36 | -6.4332×10^1 | 35 | 47 | 3.0160×10^2 |
| 9 | 10 | -7.5556×10^0 | 43 | 36 | 2.0130×10^2 | 36 | 47 | 2.0829×10^1 |
| 10 | 10 | 3.2251×10^0 | 44 | 36 | 2.1073×10^2 | 37 | 47 | -1.7358×10^3 |
| 11 | 10 | -9.3047×10^{-1} | 45 | 36 | 3.4715×10^1 | 38 | 47 | -1.7358×10^3 |
| 12 | 10 | 9.9803×10^{-1} | 46 | 36 | 1.3886×10^1 | 39 | 47 | -9.1300×10^2 |
| 45 | 10 | 7.5556×10^0 | 47 | 36 | 2.0829×10^1 | 40 | 47 | -2.6887×10^2 |
| 46 | 10 | 7.5556×10^{-1} | 48 | 36 | -2.0695×10^2 | 41 | 47 | 3.0160×10^2 |
| 47 | 10 | -5.0018×10^0 | 37 | 37 | -2.2323×10^3 | 42 | 47 | -2.0829×10^1 |
| 7 | 11 | -1.1877×10^1 | 38 | 37 | 1.4465×10^3 | 43 | 47 | -1.9321×10^3 |
| 9 | 11 | 1.5111×10^1 | 39 | 37 | 2.8929×10^3 | 44 | 47 | -9.2380×10^{-8} |
| 10 | 11 | -9.3047×10^{-1} | 40 | 37 | 3.3066×10^2 | 45 | 47 | 8.0179×10^2 |
| 11 | 11 | 8.3142×10^0 | 41 | 37 | -6.2804×10^2 | 46 | 47 | -7.1684×10^{-8} |
| 12 | 11 | -3.8836×10^1 | 42 | 37 | 5.6917×10^2 | 47 | 47 | 5.3208×10^3 |
| 43 | 11 | 1.1877×10^1 | 43 | 37 | 2.2323×10^3 | 48 | 47 | -6.2769×10^{-8} |
| 45 | 11 | -1.5111×10^1 | 44 | 37 | -1.4465×10^3 | 1 | 48 | 3.4431×10^{-8} |
| 46 | 11 | -1.5111×10^0 | 45 | 37 | -2.8929×10^3 | 2 | 48 | 2.3435×10^3 |
| 47 | 11 | 8.2220×10^0 | 46 | 37 | 1.1572×10^3 | 3 | 48 | -7.7565×10^{-8} |
| 48 | 11 | -1.1877×10^0 | 47 | 37 | -1.7358×10^3 | 4 | 48 | 3.8469×10^3 |
| 7 | 12 | 7.5556×10^0 | 48 | 37 | 1.7608×10^3 | 5 | 48 | 2.9475×10^{-9} |
| 8 | 12 | -1.5716×10^{-10} | 37 | 38 | 1.4465×10^3 | 6 | 48 | -3.0018×10^2 |
| 10 | 12 | 9.9803×10^{-1} | 38 | 38 | -2.9926×10^3 | 7 | 48 | 1.5111×10^1 |

A. EQUATIONS OF MOTION

| | | | | | | | | |
|----|----|---------------------------|----|----|-----------------------|----|----|---------------------------|
| 11 | 12 | 4.0416×10^{-1} | 39 | 38 | 2.8929×10^3 | 11 | 48 | -1.1877×10^0 |
| 12 | 12 | -2.2946×10^0 | 40 | 38 | 6.4761×10^2 | 12 | 48 | 7.5556×10^{-1} |
| 43 | 12 | -7.5556×10^0 | 41 | 38 | -3.6538×10^2 | 13 | 48 | -1.5111×10^1 |
| 47 | 12 | 1.1333×10^0 | 42 | 38 | -8.0668×10^2 | 17 | 48 | 1.1877×10^0 |
| 48 | 12 | 7.5556×10^{-1} | 43 | 38 | -1.4465×10^3 | 18 | 48 | 7.5556×10^{-1} |
| 13 | 13 | 1.5111×10^2 | 44 | 38 | 2.9926×10^3 | 25 | 48 | -9.9446×10^{-9} |
| 17 | 13 | -1.1877×10^1 | 45 | 38 | -2.8929×10^3 | 26 | 48 | -3.9053×10^2 |
| 18 | 13 | -6.8000×10^1 | 46 | 38 | 1.1572×10^3 | 28 | 48 | -1.1169×10^1 |
| 43 | 13 | -1.5111×10^2 | 47 | 38 | -1.7358×10^3 | 29 | 48 | 2.8442×10^{-10} |
| 47 | 13 | 2.2667×10^1 | 48 | 38 | -2.2692×10^3 | 31 | 48 | -1.7608×10^3 |
| 48 | 13 | -1.5111×10^1 | 37 | 39 | 2.8929×10^3 | 32 | 48 | -2.2692×10^3 |
| 16 | 14 | -1.5120×10^{-11} | 38 | 39 | 2.8929×10^3 | 33 | 48 | -5.7858×10^2 |
| 18 | 14 | -8.0947×10^{-11} | 39 | 39 | 1.3468×10^3 | 34 | 48 | -1.9264×10^2 |
| 15 | 15 | 1.5111×10^2 | 40 | 39 | 7.1495×10^1 | 35 | 48 | 2.6231×10^2 |
| 16 | 15 | 6.8000×10^1 | 41 | 39 | 9.3289×10^1 | 36 | 48 | -2.0695×10^2 |
| 17 | 15 | 1.5111×10^1 | 42 | 39 | 3.4715×10^1 | 37 | 48 | 1.7608×10^3 |
| 45 | 15 | -1.5111×10^2 | 43 | 39 | -2.8929×10^3 | 38 | 48 | -2.2692×10^3 |
| 46 | 15 | 1.5111×10^1 | 44 | 39 | -2.8929×10^3 | 39 | 48 | 5.7858×10^2 |
| 47 | 15 | 1.0004×10^2 | 45 | 39 | -1.3468×10^3 | 40 | 48 | -1.9264×10^2 |
| 14 | 16 | 1.5120×10^{-11} | 46 | 39 | 4.6270×10^2 | 41 | 48 | -2.6231×10^2 |
| 15 | 16 | 7.5556×10^0 | 47 | 39 | -9.1300×10^2 | 42 | 48 | -2.0695×10^2 |
| 16 | 16 | 3.2251×10^0 | 48 | 39 | 5.7858×10^2 | 43 | 48 | 2.7335×10^{-8} |
| 17 | 16 | 9.3047×10^{-1} | 37 | 40 | 3.3066×10^2 | 44 | 48 | 2.5855×10^3 |
| 18 | 16 | 9.9803×10^{-1} | 38 | 40 | -8.8143×10^1 | 45 | 48 | 8.7164×10^{-8} |
| 45 | 16 | -7.5556×10^0 | 39 | 40 | 4.3937×10^2 | 46 | 48 | -2.8917×10^3 |
| 46 | 16 | 7.5556×10^{-1} | 40 | 40 | 7.6000×10^1 | 47 | 48 | -6.2695×10^{-8} |
| 47 | 16 | 5.0018×10^0 | 41 | 40 | -4.2323×10^1 | 48 | 48 | -6.7493×10^3 |
| 13 | 17 | -1.1877×10^1 | 42 | 40 | -5.6387×10^1 | 11 | 49 | 7.8480×10^2 |
| 15 | 17 | 1.5111×10^1 | 43 | 40 | -3.3066×10^2 | 12 | 49 | -2.1081×10^{-9} |
| 16 | 17 | 9.3047×10^{-1} | 44 | 40 | 8.8143×10^1 | 10 | 50 | -7.8480×10^2 |
| 17 | 17 | 8.3142×10^0 | 45 | 40 | -4.3937×10^2 | 12 | 50 | 1.2399×10^{-9} |
| 18 | 17 | 3.8836×10^1 | 46 | 40 | 1.7195×10^2 | 10 | 51 | 2.1081×10^{-9} |
| 43 | 17 | 1.1877×10^1 | 47 | 40 | -2.6887×10^2 | 11 | 51 | -1.2399×10^{-9} |
| 45 | 17 | -1.5111×10^1 | 48 | 40 | -1.9264×10^2 | 51 | 51 | 1.0000×10^5 |
| 46 | 17 | 1.5111×10^0 | 37 | 41 | 1.0771×10^2 | 50 | 52 | -1.7888×10^{-9} |
| 47 | 17 | 8.2220×10^0 | 38 | 41 | -3.6538×10^2 | 51 | 52 | -1.2322×10^{-10} |
| 48 | 17 | 1.1877×10^0 | 39 | 41 | -5.0267×10^2 | 52 | 52 | -2.0183×10^2 |
| 13 | 18 | -7.5556×10^0 | 40 | 41 | -4.2323×10^1 | 49 | 53 | 1.7888×10^{-9} |
| 14 | 18 | 8.0947×10^{-11} | 41 | 41 | 8.9123×10^1 | 51 | 53 | -8.5876×10^{-11} |
| 16 | 18 | 9.9803×10^{-1} | 42 | 41 | -7.5348×10^1 | 52 | 53 | 1.1301×10^{-10} |
| 17 | 18 | -4.0416×10^{-1} | 43 | 41 | -1.0771×10^2 | 54 | 53 | 6.4395×10^{-10} |
| 18 | 18 | -2.2946×10^0 | 44 | 41 | 3.6538×10^2 | 49 | 54 | 1.2322×10^{-10} |
| 43 | 18 | 7.5556×10^0 | 45 | 41 | 5.0267×10^2 | 50 | 54 | 8.5876×10^{-11} |
| 47 | 18 | -1.1333×10^0 | 46 | 41 | -2.0107×10^2 | 52 | 54 | 3.0308×10^{-10} |
| 48 | 18 | 7.5556×10^{-1} | 47 | 41 | 3.0160×10^2 | 53 | 54 | 4.5374×10^{-10} |
| 35 | 19 | -2.4525×10^1 | 48 | 41 | -2.6231×10^2 | 17 | 55 | 7.8480×10^2 |
| 36 | 19 | -4.3274×10^2 | 37 | 42 | 2.0130×10^2 | 18 | 55 | 1.7061×10^{-10} |
| 41 | 19 | -2.4525×10^1 | 38 | 42 | -2.1073×10^2 | 16 | 56 | -7.8480×10^2 |
| 42 | 19 | 4.3274×10^2 | 39 | 42 | 3.4715×10^1 | 18 | 56 | -1.1046×10^{-10} |
| 34 | 20 | 2.4525×10^1 | 40 | 42 | 3.2086×10^0 | 16 | 57 | -1.7061×10^{-10} |
| 36 | 20 | -1.3375×10^{-9} | 41 | 42 | 8.7486×10^0 | 17 | 57 | 1.1046×10^{-10} |
| 40 | 20 | 2.4525×10^1 | 42 | 42 | -6.4332×10^1 | 57 | 57 | 1.0000×10^5 |
| 42 | 20 | 1.4781×10^{-9} | 43 | 42 | -2.0130×10^2 | 56 | 58 | -6.4933×10^{-8} |
| 34 | 21 | 4.3274×10^2 | 44 | 42 | 2.1073×10^2 | 57 | 58 | 1.7061×10^{-10} |
| 35 | 21 | 1.3375×10^{-9} | 45 | 42 | -3.4715×10^1 | 58 | 58 | -2.0183×10^2 |
| 40 | 21 | -4.3274×10^2 | 46 | 42 | 1.3886×10^1 | 55 | 59 | 6.4933×10^{-8} |
| 41 | 21 | -1.4781×10^{-9} | 47 | 42 | -2.0829×10^1 | 57 | 59 | -1.2048×10^{-10} |
| 20 | 22 | 2.8090×10^{-10} | 48 | 42 | -2.0695×10^2 | 58 | 59 | 1.2000×10^{-10} |

A. EQUATIONS OF MOTION

| | | | | | | | | |
|----|----|---------------------------|----|----|---------------------------|----|----|---------------------------|
| 21 | 22 | -2.5011×10^{-11} | 1 | 43 | 6.6306×10^3 | 60 | 59 | 1.1526×10^{-10} |
| 22 | 22 | -4.7602×10^2 | 2 | 43 | -5.2477×10^{-8} | 55 | 60 | -1.7061×10^{-10} |
| 23 | 22 | -1.4101×10^{-9} | 3 | 43 | -5.7858×10^3 | 56 | 60 | 1.2048×10^{-10} |
| 24 | 22 | 3.9736×10^{-11} | 4 | 43 | 2.9833×10^{-8} | 58 | 60 | 2.2906×10^{-12} |
| 34 | 22 | 2.3801×10^2 | 5 | 43 | 2.1986×10^2 | 35 | 61 | 7.8480×10^2 |
| 35 | 22 | 7.3564×10^{-10} | 6 | 43 | 7.3449×10^{-8} | 36 | 61 | 8.2514×10^{-10} |
| 40 | 22 | 2.3801×10^2 | 7 | 43 | -1.5111×10^2 | 34 | 62 | -7.8480×10^2 |
| 41 | 22 | 8.1294×10^{-10} | 11 | 43 | 1.1877×10^1 | 36 | 62 | -1.5617×10^{-9} |
| 19 | 23 | -2.8090×10^{-10} | 12 | 43 | -7.5556×10^0 | 34 | 63 | -8.2514×10^{-10} |
| 21 | 23 | 1.4055×10^{-10} | 13 | 43 | -1.5111×10^2 | 35 | 63 | 1.5617×10^{-9} |
| 22 | 23 | -1.5486×10^{-9} | 17 | 43 | 1.1877×10^1 | 63 | 63 | 1.0000×10^5 |
| 24 | 23 | -2.6061×10^{-11} | 18 | 43 | 7.5556×10^0 | 62 | 64 | -1.8117×10^{-9} |
| 19 | 24 | 2.5011×10^{-11} | 25 | 43 | -2.9214×10^3 | 63 | 64 | 8.2514×10^{-10} |
| 20 | 24 | -1.4055×10^{-10} | 26 | 43 | -2.6781×10^{-8} | 64 | 64 | -2.0183×10^2 |
| 24 | 24 | -4.7602×10^2 | 28 | 43 | -7.6593×10^{-10} | 61 | 65 | 1.8117×10^{-9} |
| 35 | 24 | 1.3489×10^1 | 29 | 43 | 8.3551×10^1 | 63 | 65 | -3.4078×10^{-11} |
| 36 | 24 | 2.3801×10^2 | 31 | 43 | 2.2323×10^3 | 64 | 65 | 1.2761×10^{-10} |
| 41 | 24 | -1.3489×10^1 | 32 | 43 | 1.4465×10^3 | 66 | 65 | -6.1313×10^{-11} |
| 42 | 24 | 2.3801×10^2 | 33 | 43 | -2.8929×10^3 | 61 | 66 | -8.2514×10^{-10} |
| 25 | 25 | 2.9214×10^3 | 34 | 43 | 3.3066×10^2 | 62 | 66 | 3.4078×10^{-11} |
| 26 | 25 | 2.6781×10^{-8} | 35 | 43 | -1.0771×10^2 | 64 | 66 | -3.4922×10^{-10} |
| 28 | 25 | 7.6593×10^{-10} | 36 | 43 | 2.0130×10^2 | 41 | 67 | 7.8480×10^2 |
| 29 | 25 | -8.3551×10^1 | 37 | 43 | 2.2323×10^3 | 42 | 67 | 1.3732×10^{-9} |
| 35 | 25 | -2.4525×10^1 | 38 | 43 | -1.4465×10^3 | 40 | 68 | -7.8480×10^2 |
| 36 | 25 | 8.0062×10^2 | 39 | 43 | -2.8929×10^3 | 42 | 68 | -8.0092×10^{-10} |
| 41 | 25 | -2.4525×10^1 | 40 | 43 | -3.3066×10^2 | 40 | 69 | -1.3732×10^{-9} |
| 42 | 25 | -8.0062×10^2 | 41 | 43 | -1.0771×10^2 | 41 | 69 | 8.0092×10^{-10} |
| 43 | 25 | -2.9214×10^3 | 42 | 43 | -2.0130×10^2 | 69 | 69 | 1.0000×10^5 |
| 44 | 25 | -2.6781×10^{-8} | 43 | 43 | -7.8716×10^3 | 68 | 70 | -2.9120×10^{-8} |
| 46 | 25 | -5.3562×10^{-9} | 44 | 43 | 5.5079×10^{-8} | 69 | 70 | -3.0911×10^{-10} |
| 47 | 25 | 5.8427×10^2 | 45 | 43 | 1.1572×10^4 | 70 | 70 | -2.0183×10^2 |
| 48 | 25 | -9.9446×10^{-9} | 46 | 43 | 5.2158×10^{-9} | 67 | 71 | 2.9120×10^{-8} |
| 25 | 26 | 2.6781×10^{-8} | 47 | 43 | -1.9321×10^3 | 69 | 71 | 1.0354×10^{-10} |
| 26 | 26 | 1.0517×10^3 | 48 | 43 | 2.7971×10^{-8} | 70 | 71 | 1.1356×10^{-10} |
| 28 | 26 | 3.0078×10^1 | 1 | 44 | -5.2477×10^{-8} | 72 | 71 | -2.3470×10^{-10} |
| 29 | 26 | -7.6593×10^{-10} | 2 | 44 | 4.7510×10^3 | 67 | 72 | 3.0911×10^{-10} |
| 34 | 26 | 2.4525×10^1 | 3 | 44 | -5.9666×10^{-8} | 68 | 72 | -1.0354×10^{-10} |
| 36 | 26 | 5.9596×10^2 | 4 | 44 | 3.0793×10^3 | 70 | 72 | -2.0676×10^{-10} |
| 40 | 26 | 2.4525×10^1 | 5 | 44 | 2.2673×10^{-9} | 71 | 72 | -3.8458×10^{-10} |
| 42 | 26 | 5.9596×10^2 | 6 | 44 | -1.2768×10^3 | - | - | - |
| 43 | 26 | -2.6781×10^{-8} | 25 | 44 | -2.6781×10^{-8} | - | - | - |

The velocity matrix is

| Row | Column | Value | Row | Column | Value | Row | Column | Value |
|-----|--------|----------------------|-----|--------|-------|-----|--------|-------|
| 1 | 1 | 0.0000×10^0 | - | - | - | - | - | - |

The input force matrix is

| Row | Column | Value | Row | Column | Value | Row | Column | Value |
|-----|--------|----------------------|-----|--------|----------------------|-----|--------|-----------------------|
| 3 | 1 | 1.0000×10^5 | 4 | 1 | 6.0000×10^4 | 46 | 2 | -1.0000×10^3 |

The system is subject to constraints

$$\begin{bmatrix} \mathbf{J}_h & \mathbf{0} \\ -\mathbf{J}_h \mathbf{V} & \mathbf{J}_h \\ \mathbf{0} & \mathbf{J}_{nh} \end{bmatrix} \begin{bmatrix} \dot{\mathbf{p}} & \mathbf{p} \\ \dot{\mathbf{w}} & \mathbf{w} \end{bmatrix} = \begin{bmatrix} \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}$$

| Row | Column | Value | Row | Column | Value | Row | Column | Value |
|-----|--------|--------------------------|-----|--------|--------------------------|-----|--------|--------------------------|
| 1 | 1 | -6.0000×10^{-1} | 63 | 41 | 1.0000×10^{-1} | 117 | 94 | 5.5000×10^{-1} |
| 2 | 1 | -6.0000×10^{-1} | 66 | 41 | -1.0000×10^0 | 122 | 94 | -5.5000×10^{-1} |
| 3 | 1 | -1.0000×10^0 | 9 | 42 | -5.0000×10^{-2} | 118 | 95 | 1.0000×10^0 |
| 4 | 1 | -1.0000×10^0 | 33 | 42 | -5.0000×10^{-2} | 123 | 95 | 1.0000×10^0 |
| 38 | 1 | 1.0000×10^0 | 37 | 42 | -1.0000×10^0 | 115 | 96 | -5.5000×10^{-1} |
| 43 | 1 | 1.0000×10^0 | 57 | 42 | -1.0000×10^0 | 119 | 96 | 1.0000×10^0 |
| 1 | 2 | -8.0000×10^{-1} | 67 | 42 | -1.0000×10^0 | 120 | 96 | 5.5000×10^{-1} |
| 2 | 2 | 8.0000×10^{-1} | 1 | 43 | 6.0000×10^{-1} | 124 | 96 | 1.0000×10^0 |
| 39 | 2 | 1.0000×10^0 | 2 | 43 | 6.0000×10^{-1} | 74 | 97 | 5.1450×10^{-1} |
| 44 | 2 | 1.0000×10^0 | 3 | 43 | 1.0000×10^0 | 75 | 97 | 5.1450×10^{-1} |
| 40 | 3 | 1.0000×10^0 | 4 | 43 | 1.0000×10^0 | 125 | 97 | 1.0000×10^0 |
| 45 | 3 | 1.0000×10^0 | 7 | 43 | -5.1450×10^{-1} | 130 | 97 | 1.0000×10^0 |
| 39 | 4 | -1.2860×10^{-1} | 8 | 43 | -5.1450×10^{-1} | 74 | 98 | -8.5749×10^{-1} |
| 40 | 4 | 5.5000×10^{-1} | 9 | 43 | -1.0000×10^0 | 75 | 98 | 8.5749×10^{-1} |
| 41 | 4 | 9.7063×10^{-1} | 10 | 43 | -1.0000×10^0 | 126 | 98 | 1.0000×10^0 |
| 42 | 4 | -1.7011×10^{-1} | 11 | 43 | -9.9995×10^{-3} | 131 | 98 | 1.0000×10^0 |
| 44 | 4 | -1.2860×10^{-1} | 1 | 44 | 8.0000×10^{-1} | 127 | 99 | 1.0000×10^0 |
| 45 | 4 | -5.5000×10^{-1} | 2 | 44 | -8.0000×10^{-1} | 132 | 99 | 1.0000×10^0 |
| 46 | 4 | 9.7063×10^{-1} | 5 | 44 | 1.0000×10^0 | 74 | 100 | -2.4524×10^{-2} |
| 47 | 4 | 1.7011×10^{-1} | 6 | 44 | -1.0000×10^0 | 75 | 100 | 2.4524×10^{-2} |
| 3 | 5 | -2.0000×10^{-1} | 7 | 44 | 8.5749×10^{-1} | 127 | 100 | 5.5000×10^{-1} |
| 4 | 5 | -2.0000×10^{-1} | 8 | 44 | -8.5749×10^{-1} | 132 | 100 | -5.5000×10^{-1} |
| 38 | 5 | 1.2860×10^{-1} | 11 | 44 | 9.9995×10^{-1} | 74 | 101 | -1.4715×10^{-2} |
| 41 | 5 | 1.4111×10^{-1} | 1 | 46 | 1.6000×10^{-1} | 75 | 101 | -1.4715×10^{-2} |
| 42 | 5 | 9.7527×10^{-1} | 2 | 46 | -1.6000×10^{-1} | 128 | 101 | 1.0000×10^0 |
| 43 | 5 | 1.2860×10^{-1} | 5 | 46 | 1.5000×10^{-1} | 133 | 101 | 1.0000×10^0 |
| 46 | 5 | -1.4111×10^{-1} | 6 | 46 | -1.5000×10^{-1} | 125 | 102 | -5.5000×10^{-1} |
| 47 | 5 | 9.7527×10^{-1} | 7 | 46 | 1.7150×10^{-1} | 129 | 102 | 1.0000×10^0 |
| 3 | 6 | -5.0000×10^{-1} | 8 | 46 | -1.7150×10^{-1} | 130 | 102 | 5.5000×10^{-1} |
| 4 | 6 | 5.0000×10^{-1} | 1 | 47 | -1.2000×10^{-1} | 134 | 102 | 1.0000×10^0 |
| 38 | 6 | -5.5000×10^{-1} | 2 | 47 | -1.2000×10^{-1} | 77 | 103 | 1.0000×10^0 |
| 41 | 6 | 1.9484×10^{-1} | 7 | 47 | 1.0290×10^{-1} | 78 | 103 | 9.9995×10^{-3} |
| 42 | 6 | 1.4111×10^{-1} | 8 | 47 | 1.0290×10^{-1} | 95 | 103 | -1.0000×10^0 |
| 43 | 6 | 5.5000×10^{-1} | 1 | 48 | 6.0960×10^{-1} | 115 | 103 | -1.0000×10^0 |
| 46 | 6 | 1.9484×10^{-1} | 2 | 48 | -6.0960×10^{-1} | 125 | 103 | -1.0000×10^0 |
| 47 | 6 | -1.4111×10^{-1} | 3 | 48 | 5.0000×10^{-1} | 78 | 104 | -9.9995×10^{-1} |
| 18 | 7 | -1.0000×10^0 | 4 | 48 | -5.0000×10^{-1} | 96 | 104 | -1.0000×10^0 |
| 38 | 7 | -1.0000×10^0 | 5 | 48 | 6.6200×10^{-1} | 116 | 104 | -1.0000×10^0 |
| 5 | 8 | -1.0000×10^0 | 6 | 48 | -6.6200×10^{-1} | 126 | 104 | -1.0000×10^0 |
| 19 | 8 | -1.0000×10^0 | 7 | 48 | -6.5341×10^{-1} | 97 | 105 | -1.0000×10^0 |
| 39 | 8 | -1.0000×10^0 | 8 | 48 | 6.5341×10^{-1} | 117 | 105 | -1.0000×10^0 |
| 20 | 9 | -1.0000×10^0 | 9 | 48 | -5.0000×10^{-1} | 127 | 105 | -1.0000×10^0 |
| 40 | 9 | -1.0000×10^0 | 10 | 48 | 5.0000×10^{-1} | 78 | 106 | 7.1396×10^{-2} |
| 5 | 10 | -7.8600×10^{-2} | 11 | 48 | -7.5696×10^{-1} | 97 | 106 | -5.0000×10^{-2} |
| 20 | 10 | -5.0000×10^{-2} | 13 | 49 | -1.0000×10^0 | 98 | 106 | 1.0000×10^0 |
| 21 | 10 | 1.0000×10^0 | 18 | 49 | 1.0000×10^0 | 116 | 106 | 1.0000×10^{-1} |

A. EQUATIONS OF MOTION

| | | | | | | | | |
|----|----|--------------------------|-----|----|--------------------------|-----|-----|--------------------------|
| 41 | 10 | -9.7063×10^{-1} | 12 | 50 | 1.0000×10^0 | 126 | 106 | -1.0000×10^{-1} |
| 42 | 10 | 1.7011×10^{-1} | 19 | 50 | 1.0000×10^0 | 77 | 107 | 7.1400×10^{-2} |
| 41 | 11 | -1.4111×10^{-1} | 20 | 51 | 1.0000×10^0 | 78 | 107 | 7.1396×10^{-4} |
| 42 | 11 | -9.7527×10^{-1} | 12 | 52 | 2.2860×10^{-1} | 115 | 107 | -1.0000×10^{-1} |
| 5 | 12 | 1.0000×10^{-1} | 21 | 52 | -1.0000×10^0 | 118 | 107 | -1.0000×10^0 |
| 18 | 12 | 5.0000×10^{-2} | 13 | 53 | 2.2860×10^{-1} | 125 | 107 | 1.0000×10^{-1} |
| 22 | 12 | -1.0000×10^0 | 22 | 54 | 1.0000×10^0 | 128 | 107 | -1.0000×10^0 |
| 41 | 12 | -1.9484×10^{-1} | 14 | 55 | 1.0000×10^0 | 77 | 108 | 5.0000×10^{-2} |
| 42 | 12 | -1.4111×10^{-1} | 23 | 55 | 1.0000×10^0 | 78 | 108 | 4.9998×10^{-4} |
| 23 | 13 | -1.0000×10^0 | 24 | 56 | 1.0000×10^0 | 95 | 108 | 5.0000×10^{-2} |
| 43 | 13 | -1.0000×10^0 | 25 | 57 | 1.0000×10^0 | 99 | 108 | -1.0000×10^0 |
| 6 | 14 | 1.0000×10^0 | 26 | 58 | -1.0000×10^0 | 119 | 108 | -1.0000×10^0 |
| 24 | 14 | -1.0000×10^0 | 14 | 59 | -2.2860×10^{-1} | 129 | 108 | -1.0000×10^0 |
| 44 | 14 | -1.0000×10^0 | 27 | 60 | 1.0000×10^0 | 76 | 109 | 1.0000×10^0 |
| 25 | 15 | -1.0000×10^0 | 17 | 61 | 1.0000×10^0 | 100 | 109 | -1.0000×10^0 |
| 45 | 15 | -1.0000×10^0 | 28 | 61 | 1.0000×10^0 | 120 | 109 | -1.0000×10^0 |
| 6 | 16 | 7.8600×10^{-2} | 29 | 62 | 1.0000×10^0 | 130 | 109 | -1.0000×10^0 |
| 25 | 16 | 5.0000×10^{-2} | 30 | 63 | 1.0000×10^0 | 101 | 110 | -1.0000×10^0 |
| 26 | 16 | 1.0000×10^0 | 31 | 64 | -1.0000×10^0 | 121 | 110 | -1.0000×10^0 |
| 46 | 16 | -9.7063×10^{-1} | 17 | 65 | -2.2860×10^{-1} | 131 | 110 | -1.0000×10^0 |
| 47 | 16 | -1.7011×10^{-1} | 32 | 66 | 1.0000×10^0 | 102 | 111 | -1.0000×10^0 |
| 46 | 17 | 1.4111×10^{-1} | 16 | 67 | -1.0000×10^0 | 122 | 111 | -1.0000×10^0 |
| 47 | 17 | -9.7527×10^{-1} | 33 | 67 | 1.0000×10^0 | 132 | 111 | -1.0000×10^0 |
| 6 | 18 | -1.0000×10^{-1} | 15 | 68 | 1.0000×10^0 | 102 | 112 | 5.0000×10^{-2} |
| 23 | 18 | -5.0000×10^{-2} | 34 | 68 | 1.0000×10^0 | 103 | 112 | 1.0000×10^0 |
| 27 | 18 | -1.0000×10^0 | 35 | 69 | 1.0000×10^0 | 121 | 112 | 1.0000×10^{-1} |
| 46 | 18 | -1.9484×10^{-1} | 15 | 70 | 2.2860×10^{-1} | 131 | 112 | -1.0000×10^{-1} |
| 47 | 18 | 1.4111×10^{-1} | 36 | 70 | -1.0000×10^0 | 76 | 113 | 7.1400×10^{-2} |
| 48 | 19 | 1.0000×10^0 | 16 | 71 | 2.2860×10^{-1} | 120 | 113 | -1.0000×10^{-1} |
| 53 | 19 | 1.0000×10^0 | 37 | 72 | 1.0000×10^0 | 123 | 113 | -1.0000×10^0 |
| 49 | 20 | 1.0000×10^0 | 68 | 73 | -6.0000×10^{-1} | 130 | 113 | 1.0000×10^{-1} |
| 54 | 20 | 1.0000×10^0 | 69 | 73 | -6.0000×10^{-1} | 133 | 113 | -1.0000×10^0 |
| 50 | 21 | 1.0000×10^0 | 70 | 73 | -1.0000×10^0 | 76 | 114 | -5.0000×10^{-2} |
| 55 | 21 | 1.0000×10^0 | 71 | 73 | -1.0000×10^0 | 100 | 114 | -5.0000×10^{-2} |
| 50 | 22 | 5.5000×10^{-1} | 105 | 73 | 1.0000×10^0 | 104 | 114 | -1.0000×10^0 |
| 55 | 22 | -5.5000×10^{-1} | 110 | 73 | 1.0000×10^0 | 124 | 114 | -1.0000×10^0 |
| 51 | 23 | 1.0000×10^0 | 68 | 74 | -8.0000×10^{-1} | 134 | 114 | -1.0000×10^0 |
| 56 | 23 | 1.0000×10^0 | 69 | 74 | 8.0000×10^{-1} | 68 | 115 | 6.0000×10^{-1} |
| 48 | 24 | -5.5000×10^{-1} | 106 | 74 | 1.0000×10^0 | 69 | 115 | 6.0000×10^{-1} |
| 52 | 24 | 1.0000×10^0 | 111 | 74 | 1.0000×10^0 | 70 | 115 | 1.0000×10^0 |
| 53 | 24 | 5.5000×10^{-1} | 107 | 75 | 1.0000×10^0 | 71 | 115 | 1.0000×10^0 |
| 57 | 24 | 1.0000×10^0 | 112 | 75 | 1.0000×10^0 | 74 | 115 | -5.1450×10^{-1} |
| 7 | 25 | 5.1450×10^{-1} | 106 | 76 | -1.2860×10^{-1} | 75 | 115 | -5.1450×10^{-1} |
| 8 | 25 | 5.1450×10^{-1} | 107 | 76 | 5.5000×10^{-1} | 76 | 115 | -1.0000×10^0 |
| 58 | 25 | 1.0000×10^0 | 108 | 76 | 9.7063×10^{-1} | 77 | 115 | -1.0000×10^0 |
| 63 | 25 | 1.0000×10^0 | 109 | 76 | -1.7011×10^{-1} | 78 | 115 | -9.9995×10^{-3} |
| 7 | 26 | -8.5749×10^{-1} | 111 | 76 | -1.2860×10^{-1} | 68 | 116 | 8.0000×10^{-1} |
| 8 | 26 | 8.5749×10^{-1} | 112 | 76 | -5.5000×10^{-1} | 69 | 116 | -8.0000×10^{-1} |
| 59 | 26 | 1.0000×10^0 | 113 | 76 | 9.7063×10^{-1} | 72 | 116 | 1.0000×10^0 |
| 64 | 26 | 1.0000×10^0 | 114 | 76 | 1.7011×10^{-1} | 73 | 116 | -1.0000×10^0 |
| 60 | 27 | 1.0000×10^0 | 70 | 77 | -2.0000×10^{-1} | 74 | 116 | 8.5749×10^{-1} |
| 65 | 27 | 1.0000×10^0 | 71 | 77 | -2.0000×10^{-1} | 75 | 116 | -8.5749×10^{-1} |
| 7 | 28 | -2.4524×10^{-2} | 105 | 77 | 1.2860×10^{-1} | 78 | 116 | 9.9995×10^{-1} |
| 8 | 28 | 2.4524×10^{-2} | 108 | 77 | 1.4111×10^{-1} | 68 | 118 | 1.6000×10^{-1} |
| 60 | 28 | 5.5000×10^{-1} | 109 | 77 | 9.7527×10^{-1} | 69 | 118 | -1.6000×10^{-1} |
| 65 | 28 | -5.5000×10^{-1} | 110 | 77 | 1.2860×10^{-1} | 72 | 118 | 1.5000×10^{-1} |
| 7 | 29 | -1.4715×10^{-2} | 113 | 77 | -1.4111×10^{-1} | 73 | 118 | -1.5000×10^{-1} |
| 8 | 29 | -1.4715×10^{-2} | 114 | 77 | 9.7527×10^{-1} | 74 | 118 | 1.7150×10^{-1} |

A. EQUATIONS OF MOTION

| | | | | | | | | |
|----|----|--------------------------|-----|----|--------------------------|-----|-----|--------------------------|
| 61 | 29 | 1.0000×10^0 | 70 | 78 | -5.0000×10^{-1} | 75 | 118 | -1.7150×10^{-1} |
| 66 | 29 | 1.0000×10^0 | 71 | 78 | 5.0000×10^{-1} | 68 | 119 | -1.2000×10^{-1} |
| 58 | 30 | -5.5000×10^{-1} | 105 | 78 | -5.5000×10^{-1} | 69 | 119 | -1.2000×10^{-1} |
| 62 | 30 | 1.0000×10^0 | 108 | 78 | 1.9484×10^{-1} | 74 | 119 | 1.0290×10^{-1} |
| 63 | 30 | 5.5000×10^{-1} | 109 | 78 | 1.4111×10^{-1} | 75 | 119 | 1.0290×10^{-1} |
| 67 | 30 | 1.0000×10^0 | 110 | 78 | 5.5000×10^{-1} | 68 | 120 | 6.0960×10^{-1} |
| 10 | 31 | 1.0000×10^0 | 113 | 78 | 1.9484×10^{-1} | 69 | 120 | -6.0960×10^{-1} |
| 11 | 31 | 9.9995×10^{-3} | 114 | 78 | -1.4111×10^{-1} | 70 | 120 | 5.0000×10^{-1} |
| 28 | 31 | -1.0000×10^0 | 85 | 79 | -1.0000×10^0 | 71 | 120 | -5.0000×10^{-1} |
| 48 | 31 | -1.0000×10^0 | 105 | 79 | -1.0000×10^0 | 72 | 120 | 6.6200×10^{-1} |
| 58 | 31 | -1.0000×10^0 | 72 | 80 | -1.0000×10^0 | 73 | 120 | -6.6200×10^{-1} |
| 11 | 32 | -9.9995×10^{-1} | 86 | 80 | -1.0000×10^0 | 74 | 120 | -6.5341×10^{-1} |
| 29 | 32 | -1.0000×10^0 | 106 | 80 | -1.0000×10^0 | 75 | 120 | 6.5341×10^{-1} |
| 49 | 32 | -1.0000×10^0 | 87 | 81 | -1.0000×10^0 | 76 | 120 | -5.0000×10^{-1} |
| 59 | 32 | -1.0000×10^0 | 107 | 81 | -1.0000×10^0 | 77 | 120 | 5.0000×10^{-1} |
| 30 | 33 | -1.0000×10^0 | 72 | 82 | -7.8600×10^{-2} | 78 | 120 | -7.5696×10^{-1} |
| 50 | 33 | -1.0000×10^0 | 87 | 82 | -5.0000×10^{-2} | 80 | 121 | -1.0000×10^0 |
| 60 | 33 | -1.0000×10^0 | 88 | 82 | 1.0000×10^0 | 85 | 121 | 1.0000×10^0 |
| 11 | 34 | 7.1396×10^{-2} | 108 | 82 | -9.7063×10^{-1} | 79 | 122 | 1.0000×10^0 |
| 30 | 34 | -5.0000×10^{-2} | 109 | 82 | 1.7011×10^{-1} | 86 | 122 | 1.0000×10^0 |
| 31 | 34 | 1.0000×10^0 | 108 | 83 | -1.4111×10^{-1} | 87 | 123 | 1.0000×10^0 |
| 49 | 34 | 1.0000×10^{-1} | 109 | 83 | -9.7527×10^{-1} | 79 | 124 | 2.2860×10^{-1} |
| 59 | 34 | -1.0000×10^{-1} | 72 | 84 | 1.0000×10^{-1} | 88 | 124 | -1.0000×10^0 |
| 10 | 35 | 7.1400×10^{-2} | 85 | 84 | 5.0000×10^{-2} | 80 | 125 | 2.2860×10^{-1} |
| 11 | 35 | 7.1396×10^{-4} | 89 | 84 | -1.0000×10^0 | 89 | 126 | 1.0000×10^0 |
| 48 | 35 | -1.0000×10^{-1} | 108 | 84 | -1.9484×10^{-1} | 81 | 127 | 1.0000×10^0 |
| 51 | 35 | -1.0000×10^0 | 109 | 84 | -1.4111×10^{-1} | 90 | 127 | 1.0000×10^0 |
| 58 | 35 | 1.0000×10^{-1} | 90 | 85 | -1.0000×10^0 | 91 | 128 | 1.0000×10^0 |
| 61 | 35 | -1.0000×10^0 | 110 | 85 | -1.0000×10^0 | 92 | 129 | 1.0000×10^0 |
| 10 | 36 | 5.0000×10^{-2} | 73 | 86 | 1.0000×10^0 | 93 | 130 | -1.0000×10^0 |
| 11 | 36 | 4.9998×10^{-4} | 91 | 86 | -1.0000×10^0 | 81 | 131 | -2.2860×10^{-1} |
| 28 | 36 | 5.0000×10^{-2} | 111 | 86 | -1.0000×10^0 | 94 | 132 | 1.0000×10^0 |
| 32 | 36 | -1.0000×10^0 | 92 | 87 | -1.0000×10^0 | 84 | 133 | 1.0000×10^0 |
| 52 | 36 | -1.0000×10^0 | 112 | 87 | -1.0000×10^0 | 95 | 133 | 1.0000×10^0 |
| 62 | 36 | -1.0000×10^0 | 73 | 88 | 7.8600×10^{-2} | 96 | 134 | 1.0000×10^0 |
| 9 | 37 | 1.0000×10^0 | 92 | 88 | 5.0000×10^{-2} | 97 | 135 | 1.0000×10^0 |
| 33 | 37 | -1.0000×10^0 | 93 | 88 | 1.0000×10^0 | 98 | 136 | -1.0000×10^0 |
| 53 | 37 | -1.0000×10^0 | 113 | 88 | -9.7063×10^{-1} | 84 | 137 | -2.2860×10^{-1} |
| 63 | 37 | -1.0000×10^0 | 114 | 88 | -1.7011×10^{-1} | 99 | 138 | 1.0000×10^0 |
| 34 | 38 | -1.0000×10^0 | 113 | 89 | 1.4111×10^{-1} | 83 | 139 | -1.0000×10^0 |
| 54 | 38 | -1.0000×10^0 | 114 | 89 | -9.7527×10^{-1} | 100 | 139 | 1.0000×10^0 |
| 64 | 38 | -1.0000×10^0 | 73 | 90 | -1.0000×10^{-1} | 82 | 140 | 1.0000×10^0 |
| 35 | 39 | -1.0000×10^0 | 90 | 90 | -5.0000×10^{-2} | 101 | 140 | 1.0000×10^0 |
| 55 | 39 | -1.0000×10^0 | 94 | 90 | -1.0000×10^0 | 102 | 141 | 1.0000×10^0 |
| 65 | 39 | -1.0000×10^0 | 113 | 90 | -1.9484×10^{-1} | 82 | 142 | 2.2860×10^{-1} |
| 35 | 40 | 5.0000×10^{-2} | 114 | 90 | 1.4111×10^{-1} | 103 | 142 | -1.0000×10^0 |
| 36 | 40 | 1.0000×10^0 | 115 | 91 | 1.0000×10^0 | 83 | 143 | 2.2860×10^{-1} |
| 54 | 40 | 1.0000×10^{-1} | 120 | 91 | 1.0000×10^0 | 104 | 144 | 1.0000×10^0 |
| 64 | 40 | -1.0000×10^{-1} | 116 | 92 | 1.0000×10^0 | - | - | - |
| 9 | 41 | 7.1400×10^{-2} | 121 | 92 | 1.0000×10^0 | - | - | - |
| 53 | 41 | -1.0000×10^{-1} | 117 | 93 | 1.0000×10^0 | - | - | - |
| 56 | 41 | -1.0000×10^0 | 122 | 93 | 1.0000×10^0 | - | - | - |

There are 8 degrees of freedom.

The full state space equations:

$$\begin{bmatrix} \mathbf{E} & \mathbf{0} \\ \mathbf{0} & \mathbf{I} \end{bmatrix} \begin{Bmatrix} \dot{\mathbf{x}} \\ \mathbf{y} \end{Bmatrix} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{bmatrix} \begin{Bmatrix} \mathbf{x} \\ \mathbf{u} \end{Bmatrix}$$

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{bmatrix} = \begin{bmatrix} -3624.3 & -5443.9 & 7224.6 & 3405.5 & 9222.7 & -5049.1 & -2830.2 & -1815.3 & 3958.2 & 611.82 & 3466.1 & -1948.3 & -542.22 \\ 4689.4 & 3003.8 & -2171.4 & -2323.7 & -1796 & -592.36 & 3274.1 & 1194.2 & -4443.5 & 931.76 & -323.9 & 1976.3 & 613.03 \\ -0.06215 & -0.04669 & -0 & -0.13768 & -0 & -0 & 0.20737 & -0.34521 & 0.12667 & -0.1949 & 0.3906 & 0.10476 & 0.42195 \\ 1189.8 & 1516 & 820.92 & 101.97 & -88.172 & 854.92 & -147.94 & -752.78 & -671.39 & 452.37 & -1984.4 & 1743.9 & 1621.9 \\ -0.63649 & -0.14613 & -0 & -0.13222 & -0 & -0 & 0.08304 & -0.082 & -0.44984 & 0.53161 & -0.16578 & 0.04728 & 0.11453 \\ 0.28401 & -0.07236 & -0 & -0.02132 & -0 & -0 & -0.51614 & 0.20974 & 0.09397 & 0.25795 & -0.18502 & -0.04127 & 0.45229 \\ -840.29 & 5674.1 & -7601.9 & -1877.2 & -9290.1 & 6925.4 & -808.89 & 136.82 & 289.71 & -1620.1 & -5810.4 & -624.72 & 700.36 \\ 2932.7 & 1907 & -2759.4 & -2012.1 & 1741.3 & -6502.2 & 2945.6 & 1391.3 & -3233.9 & 1163.4 & 2647 & -2389.1 & -1602.6 \\ 13055 & 6015.7 & 4856.8 & -2100.3 & 3618.8 & -4434.2 & 5911.6 & -609.67 & -10382 & 4654.1 & -2532.1 & 9714.1 & 5951.7 \\ 6659.2 & 3899.4 & -2736.1 & -1972.5 & -6581.9 & -3179.4 & 4457.3 & 3032.5 & -6962 & -553.7 & -3664.7 & 7351.5 & 1927.6 \\ 2917.9 & 2699.7 & -5433.2 & -3335.1 & -2172.8 & -548.01 & 3335.1 & 1750.1 & -3288.9 & 697.75 & 2085.9 & -2417 & -1838.2 \\ 6517.8 & 2528.1 & 410.9 & -1756.4 & -2125.5 & 30.708 & 3832.7 & 1217.8 & -5811.8 & 1097.3 & -1419.9 & 5955.4 & 2247.8 \\ -147.59 & 6463.9 & -11302 & -3335.5 & -4146 & -6361.2 & 1292.4 & 1517.3 & -1176.1 & -304.47 & -704.86 & -7188.8 & -2949 \\ -622.38 & -2458.1 & 4154.3 & 673.62 & 4021.8 & 4617.5 & -825.25 & -1662.3 & 1513 & 1255.1 & 2437.8 & -798.46 & 272.6 \\ -2659.3 & -167.17 & -5662.7 & -1286.9 & -4421.3 & 1191.5 & 124.3 & 1829.8 & 1238 & -1823.1 & 1136.7 & -3758.1 & -3025.7 \\ -9856.8 & -1770.6 & -10586 & -130.03 & -7548.1 & -1867.7 & -3002.5 & 3068.1 & 6286.9 & -5205 & 789.15 & -9138.8 & -6489 \\ -0.04211 & -0.43062 & 0.127 & 0.02971 & -0.32332 & 0.0146 & 0.17726 & 0.4016 & -0.13817 & -0.2568 & 0.14736 & 0.43017 & -0.2072 \\ 0.01987 & 0.01609 & 0.16777 & 0.12485 & -0.18075 & 0.09932 & -0.02387 & -0.02516 & -0.02335 & 0.06713 & 0.06354 & -0.1282 & -0.0105 \end{bmatrix}$$

$$\mathbf{E} = \begin{bmatrix} 6.6709 & -1.5133 & 0 & 4.7961 & -0 & -0 & 6.9095 & -0.726 & 5.6955 & -12.167 & -2.096 & -5.8914 & 8.9139 & 0.92396 & -5.0412 & -4.606 \\ -1.5133 & 10.368 & 0 & -4.7096 & -0 & 0 & -11.796 & 4.0445 & -6.7143 & 22.349 & 4.9233 & 12.76 & -23.932 & -1.922 & 9.3624 & 17.339 \\ 0 & 0 & 1 & -0 & 0 & 0 & 0 & -0 & -0 & 0 & -0 & -0 & 0 & 0 & 0 & -0 \\ 4.7961 & -4.7096 & -0 & 10.272 & 0 & -0 & 14.981 & -2.1922 & 9.681 & -24.538 & -4.8215 & -12.77 & 24.07 & 2.0376 & -12.581 & -15.039 \\ -0 & -0 & 0 & 0 & 1 & 0 & -0 & -0 & 0 & -0 & -0 & 0 & 0 & 0 & 0 & -0 \\ -0 & 0 & 0 & -0 & 0 & 1 & -0 & -0 & -0 & 0 & -0 & -0 & 0 & 0 & 0 & 0 \\ 6.9095 & -11.796 & 0 & 14.981 & -0 & -0 & 30.866 & -3.1091 & 17.581 & -44.377 & -9.2493 & -24.957 & 45.275 & 5.486 & -20.626 & -28.89 \\ -0.726 & 4.0445 & -0 & -2.1922 & -0 & -0 & -3.1091 & 6.8508 & -2.8678 & 11.743 & 1.3484 & 4.4964 & -12.316 & 2.4145 & 4.8687 & 8.337 \\ 5.6955 & -6.7143 & -0 & 9.681 & 0 & -0 & 17.581 & -2.8678 & 15.325 & -27.962 & -5.0324 & -14.266 & 28.444 & 1.8912 & -13.257 & -19.402 \\ -12.167 & 22.349 & 0 & -24.538 & -0 & 0 & -44.377 & 11.743 & -27.962 & 82.208 & 15.338 & 42.641 & -82 & -5.1117 & 37.631 & 53.446 \\ -2.096 & 4.9233 & -0 & -4.8215 & -0 & -0 & -9.2493 & 1.3484 & -5.0324 & 15.338 & 5.0953 & 9.0206 & -15.172 & -2.3871 & 7.7557 & 11.101 \\ -5.8914 & 12.76 & -0 & -12.77 & 0 & -0 & -24.957 & 4.4964 & -14.266 & 42.641 & 9.0206 & 24.851 & -43.446 & -4.5537 & 19.756 & 28.671 \\ 8.9139 & -23.932 & 0 & 24.07 & 0 & 0 & 45.275 & -12.316 & 28.444 & -82 & -15.172 & -43.446 & 88.994 & 3.9855 & -38.599 & -57.017 \\ 0.92396 & -1.922 & 0 & 2.0376 & 0 & 0 & 5.486 & 2.4145 & 1.8912 & -5.1117 & -2.3871 & -4.5537 & 3.9855 & 5.0113 & -2.6945 & -4.0802 \\ -5.0412 & 9.3624 & 0 & -12.581 & 0 & 0 & -20.626 & 4.8687 & -13.257 & 37.631 & 7.7557 & 19.756 & -38.599 & -2.6945 & 20.632 & 26.192 \\ -4.606 & 17.339 & -0 & -15.039 & -0 & 0 & -28.89 & 8.337 & -19.402 & 53.446 & 11.101 & 28.671 & -57.017 & -4.0802 & 26.192 & 42.701 \end{bmatrix}$$