



**Mechanical, Automotive, & Materials Engineering**

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EoM Analysis  
Full Car A-Arm Pushrod

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# CHAPTER 1

## INTRODUCTION

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### 1.1 System Description

The properties of the bodies are given in Tables 1.1 and 1.2. The properties of the connections are given in Tables 1.3, 1.4, and 1.5.

Table 1.1: Body CG Locations and Mass

No.	Body Name	Location [m]	Mass [kg]
1	Chassis	0.000, 0.000, 0.500	1,400.000
2	LF Upright	1.200, 0.800, 0.300	5.000
3	LF Lower A-arm	1.200, 0.600, 0.150	5.000
4	LF Upper A-arm	1.200, 0.600, 0.400	5.000
5	LF Bell-crank	1.140, 0.340, 0.460	1.000
6	LF Anti-roll arm	1.300, 0.300, 0.400	1.000
7	LF Push-rod	1.200, 0.550, 0.300	1.000
8	LF Tie-rod	1.040, 0.550, 0.280	1.000
9	LF Wheel+hub	1.200, 0.900, 0.300	10.000
10	LR Upright	-1.300, 0.800, 0.300	5.000
11	LR Lower A-arm	-1.300, 0.600, 0.150	5.000
12	LR Upper A-arm	-1.300, 0.600, 0.400	5.000
13	LR Bell-crank	-1.250, 0.350, 0.450	1.000
14	LR Push-rod	-1.300, 0.550, 0.300	1.000
15	LR Tie-rod	-1.140, 0.450, 0.125	1.000
16	LR Wheel+hub	-1.300, 0.900, 0.300	10.000
17	LF Contact patch	1.200, 0.900, 0.000	0.000
18	LR Contact patch	-1.300, 0.900, 0.000	0.000
19	RF Upright	1.200, -0.800, 0.300	5.000
20	RF Lower A-arm	1.200, -0.600, 0.150	5.000
21	RF Upper A-arm	1.200, -0.600, 0.400	5.000
22	RF Bell-crank	1.140, -0.340, 0.460	1.000
23	RF Anti-roll arm	1.300, -0.300, 0.400	1.000
24	RF Push-rod	1.200, -0.550, 0.300	1.000
25	RF Tie-rod	1.040, -0.550, 0.280	1.000

26	RF Wheel+hub	1.200, -0.900, 0.300	10.000
27	RR Upright	-1.300, -0.800, 0.300	5.000
28	RR Lower A-arm	-1.300, -0.600, 0.150	5.000
29	RR Upper A-arm	-1.300, -0.600, 0.400	5.000
30	RR Bell-crank	-1.250, -0.350, 0.450	1.000
31	RR Push-rod	-1.300, -0.550, 0.300	1.000
32	RR Tie-rod	-1.140, -0.450, 0.125	1.000
33	RR Wheel+hub	-1.300, -0.900, 0.300	10.000
34	RF Contact patch	1.200, -0.900, 0.000	0.000
35	RR Contact patch	-1.300, -0.900, 0.000	0.000

Table 1.2: Body Inertia Properties

No.	Body Name	Inertia <sup>†</sup> [kg m <sup>2</sup> ] ( $I_{xx}$ , $I_{yy}$ , $I_{zz}$ ; $I_{xy}$ , $I_{yz}$ , $I_{zx}$ )
1	Chassis	800.000, 2,000.000, 2,200.000; 0.000, 0.000, 0.000
2	LF Upright	0.100, 0.100, 0.100; 0.000, 0.000, 0.000
3	LF Lower A-arm	1.000, 1.000, 2.000; 0.000, 0.000, 0.000
4	LF Upper A-arm	1.000, 1.000, 2.000; 0.000, 0.000, 0.000
5	LF Bell-crank	0.050, 0.050, 0.050; 0.000, 0.000, 0.000
6	LF Anti-roll arm	0.050, 0.050, 0.050; 0.000, 0.000, 0.000
7	LF Push-rod	0.011, 0.003, 0.008; 0.000, -0.005, 0.000
8	LF Tie-rod	0.021, 0.003, 0.024; 0.008, 0.002, 0.001
9	LF Wheel+hub	2.000, 4.000, 2.000; 0.000, 0.000, 0.000
10	LR Upright	0.100, 0.100, 0.100; 0.000, 0.000, 0.000
11	LR Lower A-arm	1.000, 1.000, 2.000; 0.000, 0.000, 0.000
12	LR Upper A-arm	1.000, 1.000, 2.000; 0.000, 0.000, 0.000
13	LR Bell-crank	0.050, 0.050, 0.050; 0.000, 0.000, 0.000
14	LR Push-rod	0.011, 0.003, 0.008; 0.000, -0.005, 0.000
15	LR Tie-rod	0.041, 0.003, 0.044; -0.011, 0.003, -0.001
16	LR Wheel+hub	2.000, 4.000, 2.000; 0.000, 0.000, 0.000
17	LF Contact patch	0.000, 0.000, 0.000; 0.000, 0.000, 0.000
18	LR Contact patch	0.000, 0.000, 0.000; 0.000, 0.000, 0.000
19	RF Upright	0.100, 0.100, 0.100; 0.000, 0.000, 0.000
20	RF Lower A-arm	1.000, 1.000, 2.000; 0.000, 0.000, 0.000
21	RF Upper A-arm	1.000, 1.000, 2.000; 0.000, 0.000, 0.000
22	RF Bell-crank	0.050, 0.050, 0.050; 0.000, 0.000, 0.000
23	RF Anti-roll arm	0.050, 0.050, 0.050; 0.000, 0.000, 0.000
24	RF Push-rod	0.011, 0.003, 0.008; 0.000, 0.005, 0.000
25	RF Tie-rod	0.021, 0.003, 0.024; -0.008, -0.002, 0.001
26	RF Wheel+hub	2.000, 4.000, 2.000; 0.000, 0.000, 0.000
27	RR Upright	0.100, 0.100, 0.100; 0.000, 0.000, 0.000
28	RR Lower A-arm	1.000, 1.000, 2.000; 0.000, 0.000, 0.000
29	RR Upper A-arm	1.000, 1.000, 2.000; 0.000, 0.000, 0.000
30	RR Bell-crank	0.050, 0.050, 0.050; 0.000, 0.000, 0.000
31	RR Push-rod	0.011, 0.003, 0.008; 0.000, 0.005, 0.000
32	RR Tie-rod	0.041, 0.003, 0.044; 0.011, -0.003, -0.001
33	RR Wheel+hub	2.000, 4.000, 2.000; 0.000, 0.000, 0.000
34	RF Contact patch	0.000, 0.000, 0.000; 0.000, 0.000, 0.000
35	RR Contact patch	0.000, 0.000, 0.000; 0.000, 0.000, 0.000

<sup>†</sup>Inertias are defined as the positive integral over the body, e.g.,  $I_{xy} = + \int r_x r_y dm$ .

Table 1.3: Connection Location and Direction

No.	Connection Name	Location [m]			Unit Axis		
1	LF Wheel bearing	1.200,	0.900,	0.300	0.000,	1.000,	0.000
2	LF Lower ball joint	1.200,	0.800,	0.150	0.000,	1.000,	0.000
3	LF Lower A-arm pivot, rear	1.000,	0.100,	0.150	0.000,	1.000,	0.000
4	LF Lower A-arm pivot, front	1.400,	0.100,	0.100	1.000,	0.000,	0.000
5	LF Bell-crank pivot	1.100,	0.400,	0.400	0.000,	0.707,	0.707
6	LF Upper A-arm pivot, front	1.400,	0.300,	0.350	1.000,	0.000,	0.000
7	LF Upper A-arm pivot, rear	1.000,	0.300,	0.350	1.000,	0.000,	0.000
8	LF Upper ball joint	1.200,	0.750,	0.450	1.000,	0.000,	0.000
9	LF Lower push-rod end	1.200,	0.700,	0.200	0.000,	-0.832,	0.555
10	LF Upper push-rod end	1.200,	0.400,	0.400	0.000,	-0.832,	0.555
11	LF Inner tie-rod end	0.950,	0.300,	0.260	0.000,	-0.832,	0.555
12	LF Outer tie-rod end	1.130,	0.800,	0.300	0.338,	0.938,	0.075
13	LF Anti-roll mount	1.300,	0.300,	0.350	0.000,	1.000,	0.000
14	LR Wheel bearing	-1.300,	0.900,	0.300	0.000,	1.000,	0.000
15	LR Lower ball joint	-1.300,	0.800,	0.150	0.000,	1.000,	0.000
16	LR Lower A-arm pivot, front	-1.100,	0.100,	0.100	0.000,	1.000,	0.000
17	LR Lower A-arm pivot, rear	-1.500,	0.100,	0.100	1.000,	0.000,	0.000
18	LR Bell-crank pivot	-1.200,	0.400,	0.400	0.000,	0.707,	0.707
19	LR Upper A-arm pivot, rear	-1.500,	0.300,	0.350	1.000,	0.000,	0.000
20	LR Upper A-arm pivot, front	-1.100,	0.300,	0.350	1.000,	0.000,	0.000
21	LR Upper ball joint	-1.300,	0.750,	0.450	1.000,	0.000,	0.000
22	LR Lower push-rod end	-1.300,	0.700,	0.200	0.000,	-0.832,	0.555
23	LR Upper push-rod end	-1.300,	0.400,	0.400	0.000,	-0.832,	0.555
24	LR Inner tie-rod end	-1.050,	0.100,	0.100	0.000,	-0.832,	0.555
25	LR Outer tie-rod end	-1.230,	0.800,	0.150	-0.248,	0.966,	0.069
26	LF Contact patch constraint	1.200,	0.900,	0.000	0.000,	1.000,	0.000
27	LR Contact patch constraint	-1.300,	0.900,	0.000	0.000,	1.000,	0.000
28	RF Wheel bearing	1.200,	-0.900,	0.300	0.000,	-1.000,	0.000
29	RF Lower ball joint	1.200,	-0.800,	0.150	0.000,	-1.000,	0.000
30	RF Lower A-arm pivot, rear	1.000,	-0.100,	0.150	0.000,	-1.000,	0.000
31	RF Lower A-arm pivot, front	1.400,	-0.100,	0.100	1.000,	0.000,	0.000
32	RF Bell-crank pivot	1.100,	-0.400,	0.400	0.000,	-0.707,	0.707
33	RF Upper A-arm pivot, front	1.400,	-0.300,	0.350	1.000,	0.000,	0.000
34	RF Upper A-arm pivot, rear	1.000,	-0.300,	0.350	1.000,	0.000,	0.000
35	RF Upper ball joint	1.200,	-0.750,	0.450	1.000,	0.000,	0.000
36	RF Lower push-rod end	1.200,	-0.700,	0.200	0.000,	0.832,	0.555
37	RF Upper push-rod end	1.200,	-0.400,	0.400	0.000,	0.832,	0.555
38	RF Inner tie-rod end	0.950,	-0.300,	0.260	0.000,	0.832,	0.555
39	RF Outer tie-rod end	1.130,	-0.800,	0.300	0.338,	-0.938,	0.075
40	RF Anti-roll mount	1.300,	-0.300,	0.350	0.000,	-1.000,	0.000
41	RR Wheel bearing	-1.300,	-0.900,	0.300	0.000,	-1.000,	0.000
42	RR Lower ball joint	-1.300,	-0.800,	0.150	0.000,	-1.000,	0.000
43	RR Lower A-arm pivot, front	-1.100,	-0.100,	0.100	0.000,	-1.000,	0.000
44	RR Lower A-arm pivot, rear	-1.500,	-0.100,	0.100	1.000,	0.000,	0.000
45	RR Bell-crank pivot	-1.200,	-0.400,	0.400	0.000,	-0.707,	0.707
46	RR Upper A-arm pivot, rear	-1.500,	-0.300,	0.350	1.000,	0.000,	0.000
47	RR Upper A-arm pivot, front	-1.100,	-0.300,	0.350	1.000,	0.000,	0.000
48	RR Upper ball joint	-1.300,	-0.750,	0.450	1.000,	0.000,	0.000
49	RR Lower push-rod end	-1.300,	-0.700,	0.200	0.000,	0.832,	0.555
50	RR Upper push-rod end	-1.300,	-0.400,	0.400	0.000,	0.832,	0.555
51	RR Inner tie-rod end	-1.050,	-0.100,	0.100	0.000,	0.832,	0.555
52	RR Outer tie-rod end	-1.230,	-0.800,	0.150	-0.248,	-0.966,	0.069
53	RF Contact patch constraint	1.200,	-0.900,	0.000	0.000,	-1.000,	0.000
54	RR Contact patch constraint	-1.300,	-0.900,	0.000	0.000,	-1.000,	0.000
55	LF Tire, vertical	1.200,	0.900,	0.000	0.000,	0.000,	1.000

56	LR Tire, vertical	-1.300, 0.900, 0.000	0.000, 0.000, 1.000
57	LF Tire, sidewall	1.200, 0.900, 0.000	0.000, 1.000, 0.000
58	LR Tire, sidewall	-1.300, 0.900, 0.000	0.000, 1.000, 0.000
59	LF Tire, horizontal	1.200, 0.900, 0.000	0.000, 0.000, 1.000
60	LR Tire, horizontal	-1.300, 0.900, 0.000	0.000, 0.000, 1.000
61	RF Tire, vertical	1.200, -0.900, 0.000	0.000, 0.000, 1.000
62	RR Tire, vertical	-1.300, -0.900, 0.000	0.000, 0.000, 1.000
63	RF Tire, sidewall	1.200, -0.900, 0.000	0.000, -1.000, 0.000
64	RR Tire, sidewall	-1.300, -0.900, 0.000	0.000, -1.000, 0.000
65	RF Tire, horizontal	1.200, -0.900, 0.000	0.000, 0.000, 1.000
66	RR Tire, horizontal	-1.300, -0.900, 0.000	0.000, 0.000, 1.000

Table 1.4: Connection Locations

No.	Connection Name	Location [m]		Location [m]	
1	LF Suspension spring	1.100,	0.300, 0.500	0.700,	0.300, 0.500
2	LR Suspension spring	-1.200,	0.300, 0.500	-0.800,	0.300, 0.500
3	Anti-roll bar	1.300,	0.300, 0.350	1.300,	-0.300, 0.350
4	RF Suspension spring	1.100,	-0.300, 0.500	0.700,	-0.300, 0.500
5	RR Suspension spring	-1.200,	-0.300, 0.500	-0.800,	-0.300, 0.500
6	LF Drop link	1.140,	0.300, 0.500	1.300,	0.300, 0.500
7	RF Drop link	1.140,	-0.300, 0.500	1.300,	-0.300, 0.500

Table 1.5: Connection Properties

No.	Connection Name	Stiffness [N/m]	Damping [Ns/m]
1	LF Tire, vertical	150,000	0
2	LR Tire, vertical	150,000	0
3	LF Tire, sidewall	135,000	0
4	LR Tire, sidewall	135,000	0
5	LF Tire, horizontal	0	2,000
6	LR Tire, horizontal	0	2,000
7	RF Tire, vertical	150,000	0
8	RR Tire, vertical	150,000	0
9	RF Tire, sidewall	135,000	0
10	RR Tire, sidewall	135,000	0
11	RF Tire, horizontal	0	2,000
12	RR Tire, horizontal	0	2,000
1	LF Suspension spring	20,000	2,000
2	LR Suspension spring	20,000	2,000
3	Anti-roll bar	100	0
4	RF Suspension spring	20,000	2,000
5	RR Suspension spring	20,000	2,000



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## CHAPTER 2

# ANALYSIS

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### 2.1 Eigenvalue Analysis

The eigenvalue properties are given in Tables 2.1 and 2.2.

Table 2.1: Eigenvalues

No.	Real [rad/s]	Imaginary [rad/s]	Real [Hz]	Imaginary [Hz]
1	$-1.9946974394 \times 10^1$	$7.1626908222 \times 10^1$	$-3.1746595745 \times 10^0$	$1.1399776502 \times 10^1$
2	$-1.9946974394 \times 10^1$	$-7.1626908222 \times 10^1$	$-3.1746595745 \times 10^0$	$-1.1399776502 \times 10^1$
3	$-1.9617503256 \times 10^1$	$7.0244101281 \times 10^1$	$-3.1222226144 \times 10^0$	$1.1179695942 \times 10^1$
4	$-1.9617503256 \times 10^1$	$-7.0244101281 \times 10^1$	$-3.1222226144 \times 10^0$	$-1.1179695942 \times 10^1$
5	$-2.3209251356 \times 10^1$	$7.1608798939 \times 10^1$	$-3.6938670788 \times 10^0$	$1.1396894320 \times 10^1$
6	$-2.3209251356 \times 10^1$	$-7.1608798939 \times 10^1$	$-3.6938670788 \times 10^0$	$-1.1396894320 \times 10^1$
7	$-2.3042944844 \times 10^1$	$7.1215876379 \times 10^1$	$-3.6673985754 \times 10^0$	$1.1334358752 \times 10^1$
8	$-2.3042944844 \times 10^1$	$-7.1215876379 \times 10^1$	$-3.6673985754 \times 10^0$	$-1.1334358752 \times 10^1$
9	$-6.7367456050 \times 10^1$	$0.0000000000 \times 10^0$	$-1.0721863634 \times 10^1$	$0.0000000000 \times 10^0$
10	$-6.7499918828 \times 10^1$	$0.0000000000 \times 10^0$	$-1.0742945740 \times 10^1$	$0.0000000000 \times 10^0$
11	$-6.0749792877 \times 10^1$	$0.0000000000 \times 10^0$	$-9.6686298282 \times 10^0$	$0.0000000000 \times 10^0$
12	$-5.8879263207 \times 10^1$	$0.0000000000 \times 10^0$	$-9.3709257850 \times 10^0$	$0.0000000000 \times 10^0$
13	$-4.9325080292 \times 10^1$	$0.0000000000 \times 10^0$	$-7.8503303469 \times 10^0$	$0.0000000000 \times 10^0$
14	$-5.0487891009 \times 10^1$	$0.0000000000 \times 10^0$	$-8.0353974204 \times 10^0$	$0.0000000000 \times 10^0$
15	$-4.5148544470 \times 10^1$	$0.0000000000 \times 10^0$	$-7.1856140258 \times 10^0$	$0.0000000000 \times 10^0$
16	$-4.5137904498 \times 10^1$	$0.0000000000 \times 10^0$	$-7.1839206216 \times 10^0$	$0.0000000000 \times 10^0$
17	$-7.9421879648 \times 10^0$	$0.0000000000 \times 10^0$	$-1.2640384736 \times 10^0$	$0.0000000000 \times 10^0$
18	$-5.1152563711 \times 10^0$	$0.0000000000 \times 10^0$	$-8.1411833664 \times 10^{-1}$	$0.0000000000 \times 10^0$
19	$-2.4505439258 \times 10^0$	$5.5691811908 \times 10^0$	$-3.9001617906 \times 10^{-1}$	$8.8636271549 \times 10^{-1}$
20	$-2.4505439258 \times 10^0$	$-5.5691811908 \times 10^0$	$-3.9001617906 \times 10^{-1}$	$-8.8636271549 \times 10^{-1}$
21	$-1.4249822445 \times 10^0$	$5.3175149963 \times 10^0$	$-2.2679296803 \times 10^{-1}$	$8.4630879663 \times 10^{-1}$
22	$-1.4249822445 \times 10^0$	$-5.3175149963 \times 10^0$	$-2.2679296803 \times 10^{-1}$	$-8.4630879663 \times 10^{-1}$
23	$-1.7474333976 \times 10^0$	$5.9324407384 \times 10^0$	$-2.7811266295 \times 10^{-1}$	$9.4417726811 \times 10^{-1}$
24	$-1.7474333976 \times 10^0$	$-5.9324407384 \times 10^0$	$-2.7811266295 \times 10^{-1}$	$-9.4417726811 \times 10^{-1}$
25	$-1.6344445159 \times 10^{-5}$	$0.0000000000 \times 10^0$	$-2.6012992392 \times 10^{-6}$	$0.0000000000 \times 10^0$
26	$1.6344453575 \times 10^{-5}$	$0.0000000000 \times 10^0$	$2.6013005787 \times 10^{-6}$	$0.0000000000 \times 10^0$

27	$8.0555269999 \times 10^{-12}$	$0.0000000000 \times 10^0$	$1.2820769413 \times 10^{-12}$	$0.0000000000 \times 10^0$
28	$7.4419793112 \times 10^{-12}$	$0.0000000000 \times 10^0$	$1.1844277938 \times 10^{-12}$	$0.0000000000 \times 10^0$
29	$1.3962862844 \times 10^{-11}$	$0.0000000000 \times 10^0$	$2.2222586413 \times 10^{-12}$	$0.0000000000 \times 10^0$
30	$1.1062557531 \times 10^{-11}$	$0.0000000000 \times 10^0$	$1.7606607142 \times 10^{-12}$	$0.0000000000 \times 10^0$
31	$-6.6716242596 \times 10^{-12}$	$0.0000000000 \times 10^0$	$-1.0618219794 \times 10^{-12}$	$0.0000000000 \times 10^0$
32	$-5.3916400269 \times 10^{-12}$	$0.0000000000 \times 10^0$	$-8.5810616165 \times 10^{-13}$	$0.0000000000 \times 10^0$

Note: oscillatory roots appear as complex conjugates.

Table 2.2: Eigenvalue Analysis

No.	Frequency ( $\omega_n$ ) [Hz]	Damping Ratio ( $\zeta$ )	Time Constant ( $\tau$ ) [s]	Wavelength ( $\lambda$ ) [s]
1	$1.1833569525 \times 10^1$	$2.6827573605 \times 10^{-1}$	$5.0132916414 \times 10^{-2}$	$8.7721018025 \times 10^{-2}$
2	$1.1833569525 \times 10^1$	$2.6827573605 \times 10^{-1}$	$5.0132916414 \times 10^{-2}$	$8.7721018025 \times 10^{-2}$
3	$1.1607492210 \times 10^1$	$2.6898339089 \times 10^{-1}$	$5.0974886403 \times 10^{-2}$	$8.9447870961 \times 10^{-2}$
4	$1.1607492210 \times 10^1$	$2.6898339089 \times 10^{-1}$	$5.0974886403 \times 10^{-2}$	$8.9447870961 \times 10^{-2}$
5	$1.1980561512 \times 10^1$	$3.0832169888 \times 10^{-1}$	$4.3086266965 \times 10^{-2}$	$8.7743201956 \times 10^{-2}$
6	$1.1980561512 \times 10^1$	$3.0832169888 \times 10^{-1}$	$4.3086266965 \times 10^{-2}$	$8.7743201956 \times 10^{-2}$
7	$1.1912913189 \times 10^1$	$3.0785069255 \times 10^{-1}$	$4.3397230986 \times 10^{-2}$	$8.8227311474 \times 10^{-2}$
8	$1.1912913189 \times 10^1$	$3.0785069255 \times 10^{-1}$	$4.3397230986 \times 10^{-2}$	$8.8227311474 \times 10^{-2}$
9	—	—	$1.4843962629 \times 10^{-2}$	—
10	—	—	$1.4814832630 \times 10^{-2}$	—
11	—	—	$1.6460961472 \times 10^{-2}$	—
12	—	—	$1.6983908180 \times 10^{-2}$	—
13	—	—	$2.0273661879 \times 10^{-2}$	—
14	—	—	$1.9806729495 \times 10^{-2}$	—
15	—	—	$2.2149108277 \times 10^{-2}$	—
16	—	—	$2.2154329297 \times 10^{-2}$	—
17	—	—	$1.2590988836 \times 10^{-1}$	—
18	—	—	$1.9549362289 \times 10^{-1}$	—
19	$9.6837569328 \times 10^{-1}$	$4.0275296227 \times 10^{-1}$	$4.0807266887 \times 10^{-1}$	$1.1282063003 \times 10^0$
20	$9.6837569328 \times 10^{-1}$	$4.0275296227 \times 10^{-1}$	$4.0807266887 \times 10^{-1}$	$1.1282063003 \times 10^0$
21	$8.7616986344 \times 10^{-1}$	$2.5884588993 \times 10^{-1}$	$7.0176312992 \times 10^{-1}$	$1.1816018030 \times 10^0$
22	$8.7616986344 \times 10^{-1}$	$2.5884588993 \times 10^{-1}$	$7.0176312992 \times 10^{-1}$	$1.1816018030 \times 10^0$
23	$9.8428520608 \times 10^{-1}$	$2.8255292392 \times 10^{-1}$	$5.7226787663 \times 10^{-1}$	$1.0591231475 \times 10^0$
24	$9.8428520608 \times 10^{-1}$	$2.8255292392 \times 10^{-1}$	$5.7226787663 \times 10^{-1}$	$1.0591231475 \times 10^0$
25	—	—	$6.1182866120 \times 10^4$	—
26	—	—	$-6.1182834616 \times 10^4$	—
27	—	—	$-1.2413837108 \times 10^{11}$	—
28	—	—	$-1.3437285407 \times 10^{11}$	—
29	—	—	$-7.1618550664 \times 10^{10}$	—
30	—	—	$-9.0395010126 \times 10^{10}$	—
31	—	—	$1.4988853705 \times 10^{11}$	—
32	—	—	$1.8547232290 \times 10^{11}$	—

Notes: a) oscillatory roots are listed twice, b) negative time constants denote unstable roots.

There are 18 degrees of freedom. There are 7 oscillatory modes, 20 damped modes, 5 unstable modes, and 0 rigid body modes.

## 2.2 Frequency Response Plots

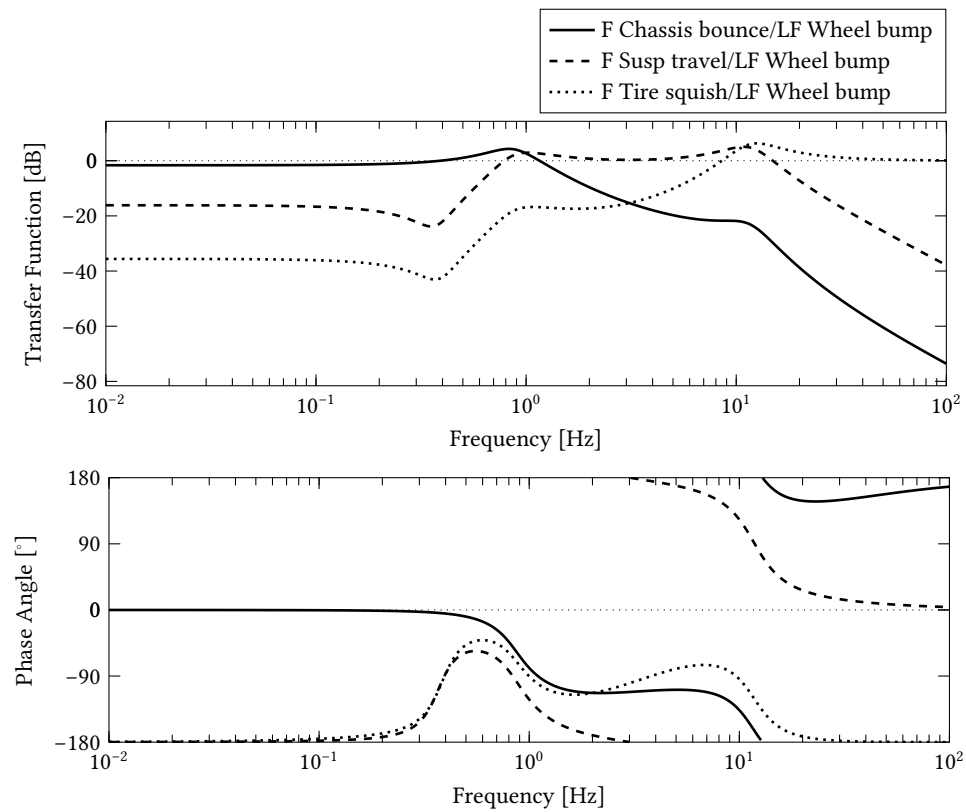


Figure 2.1: Frequency response: LF Wheel bump

## 2.3 Steady State Gains

The steady state gains are given in Table 2.3.

Table 2.3: Steady State Gains

No.	Output/Input	Gain
1	F Chassis bounce/LF Wheel bump	$8.2744599000 \times 10^{-1}$
2	F Susp travel/LF Wheel bump	$-1.5595645000 \times 10^{-1}$
3	F Tire squish/LF Wheel bump	$-1.6597560000 \times 10^{-2}$

## 2.4 Hankel Singular Value Analysis

The Hankel singular values are given in Table 2.4.

## 2.5 Equilibrium Analysis

The results of the equilibrium load analysis are given in Tables 2.5 and 2.6.

Table 2.5: System Static Deflections

No.	Body Name	Type	Deflection [m] or [rad]
1	Chassis	translation	$3.7738 \times 10^{-3}$ , $1.8000 \times 10^{-7}$ , $-3.0526 \times 10^{-1}$
–	–	rotation	$-3.3000 \times 10^{-7}$ , $2.3772 \times 10^{-2}$ , $5.0000 \times 10^{-8}$
2	LF Upright	translation	$1.9500 \times 10^{-2}$ , $-3.6517 \times 10^{-2}$ , $-4.3129 \times 10^{-2}$
–	–	rotation	$1.7425 \times 10^{-1}$ , $-8.1895 \times 10^{-2}$ , $-9.2622 \times 10^{-2}$
3	LF Lower A-arm	translation	$2.1404 \times 10^{-2}$ , $-1.0381 \times 10^{-2}$ , $-1.2617 \times 10^{-1}$
–	–	rotation	$4.1522 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $-5.1902 \times 10^{-2}$
4	LF Upper A-arm	translation	$1.3965 \times 10^{-3}$ , $-3.1327 \times 10^{-2}$ , $-1.4582 \times 10^{-1}$
–	–	rotation	$6.2654 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $1.9000 \times 10^{-7}$
5	LF Bell-crank	translation	$-1.3918 \times 10^{-1}$ , $-4.7336 \times 10^{-2}$ , $-2.8502 \times 10^{-1}$
–	–	rotation	$-3.2000 \times 10^{-7}$ , $-1.1596 \times 10^0$ , $-1.1834 \times 10^0$
6	LF Anti-roll arm	translation	$-7.7496 \times 10^{-2}$ , $2.1000 \times 10^{-7}$ , $-3.3616 \times 10^{-1}$
–	–	rotation	$-3.3000 \times 10^{-7}$ , $-1.5541 \times 10^0$ , $5.0000 \times 10^{-8}$
7	LF Push-rod	translation	$1.4590 \times 10^{-2}$ , $-7.4740 \times 10^{-2}$ , $-1.5005 \times 10^{-1}$
–	–	rotation	$4.3599 \times 10^{-1}$ , $-1.8146 \times 10^{-4}$ , $-8.7833 \times 10^{-2}$
8	LF Tie-rod	translation	$8.7844 \times 10^{-3}$ , $-1.5017 \times 10^{-2}$ , $-1.8835 \times 10^{-1}$
–	–	rotation	$4.8697 \times 10^{-1}$ , $-1.9720 \times 10^{-1}$ , $-5.8640 \times 10^{-2}$
9	LF Wheel+hub	translation	$2.8763 \times 10^{-2}$ , $-3.6517 \times 10^{-2}$ , $-2.5705 \times 10^{-2}$
–	–	rotation	$1.7425 \times 10^{-1}$ , $4.1286 \times 10^{-3}$ , $-9.2622 \times 10^{-2}$
10	LR Upright	translation	$-9.8073 \times 10^{-4}$ , $-3.4443 \times 10^{-2}$ , $-3.5386 \times 10^{-2}$
–	–	rotation	$1.1583 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $5.0000 \times 10^{-8}$
11	LR Lower A-arm	translation	$-4.5466 \times 10^{-3}$ , $-1.7069 \times 10^{-2}$ , $-1.0366 \times 10^{-1}$
–	–	rotation	$3.4138 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $5.0000 \times 10^{-8}$
12	LR Upper A-arm	translation	$1.3965 \times 10^{-3}$ , $-2.5909 \times 10^{-2}$ , $-1.1890 \times 10^{-1}$
–	–	rotation	$5.1817 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $5.0000 \times 10^{-8}$
13	LR Bell-crank	translation	$1.0500 \times 10^{-1}$ , $-5.1208 \times 10^{-2}$ , $-2.2434 \times 10^{-1}$
–	–	rotation	$-3.3000 \times 10^{-7}$ , $1.0479 \times 10^0$ , $1.0242 \times 10^0$
14	LR Push-rod	translation	$-9.8072 \times 10^{-4}$ , $-6.8277 \times 10^{-2}$ , $-1.2073 \times 10^{-1}$
–	–	rotation	$3.4138 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $5.0000 \times 10^{-8}$
15	LR Tie-rod	translation	$-5.1409 \times 10^{-3}$ , $-8.5346 \times 10^{-3}$ , $-1.5867 \times 10^{-1}$

–	–	rotation	$3.2746 \times 10^{-1}$ , $7.7917 \times 10^{-2}$ , $3.8675 \times 10^{-3}$
16	LR Wheel+hub	translation	$-9.8074 \times 10^{-4}$ , $-3.4443 \times 10^{-2}$ , $-2.3803 \times 10^{-2}$
–	–	rotation	$1.1583 \times 10^{-1}$ , $-1.4078 \times 10^{-4}$ , $5.0000 \times 10^{-8}$
17	LF Contact patch	translation	$2.7524 \times 10^{-2}$ , $1.5756 \times 10^{-2}$ , $-2.5705 \times 10^{-2}$
–	–	rotation	$1.7425 \times 10^{-1}$ , $4.1286 \times 10^{-3}$ , $-9.2622 \times 10^{-2}$
18	LR Contact patch	translation	$-9.3850 \times 10^{-4}$ , $3.0476 \times 10^{-4}$ , $-2.3803 \times 10^{-2}$
–	–	rotation	$1.1583 \times 10^{-1}$ , $-1.4078 \times 10^{-4}$ , $5.0000 \times 10^{-8}$
19	RF Upright	translation	$1.9501 \times 10^{-2}$ , $3.6518 \times 10^{-2}$ , $-4.3129 \times 10^{-2}$
–	–	rotation	$-1.7425 \times 10^{-1}$ , $-8.1898 \times 10^{-2}$ , $9.2619 \times 10^{-2}$
20	RF Lower A-arm	translation	$2.1405 \times 10^{-2}$ , $1.0381 \times 10^{-2}$ , $-1.2617 \times 10^{-1}$
–	–	rotation	$-4.1522 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $5.1903 \times 10^{-2}$
21	RF Upper A-arm	translation	$1.3966 \times 10^{-3}$ , $3.1327 \times 10^{-2}$ , $-1.4582 \times 10^{-1}$
–	–	rotation	$-6.2654 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $5.0000 \times 10^{-8}$
22	RF Bell-crank	translation	$-1.3918 \times 10^{-1}$ , $4.7336 \times 10^{-2}$ , $-2.8502 \times 10^{-1}$
–	–	rotation	$-3.3000 \times 10^{-7}$ , $-1.1596 \times 10^0$ , $1.1834 \times 10^0$
23	RF Anti-roll arm	translation	$-7.7496 \times 10^{-2}$ , $2.1000 \times 10^{-7}$ , $-3.3616 \times 10^{-1}$
–	–	rotation	$-3.3000 \times 10^{-7}$ , $-1.5541 \times 10^0$ , $5.0000 \times 10^{-8}$
24	RF Push-rod	translation	$1.4590 \times 10^{-2}$ , $7.4740 \times 10^{-2}$ , $-1.5005 \times 10^{-1}$
–	–	rotation	$-4.3599 \times 10^{-1}$ , $-1.8281 \times 10^{-4}$ , $8.7836 \times 10^{-2}$
25	RF Tie-rod	translation	$8.7847 \times 10^{-3}$ , $1.5017 \times 10^{-2}$ , $-1.8835 \times 10^{-1}$
–	–	rotation	$-4.8697 \times 10^{-1}$ , $-1.9720 \times 10^{-1}$ , $5.8641 \times 10^{-2}$
26	RF Wheel+hub	translation	$2.8763 \times 10^{-2}$ , $3.6518 \times 10^{-2}$ , $-2.5705 \times 10^{-2}$
–	–	rotation	$-1.7425 \times 10^{-1}$ , $4.1286 \times 10^{-3}$ , $9.2619 \times 10^{-2}$
27	RR Upright	translation	$-9.8065 \times 10^{-4}$ , $3.4443 \times 10^{-2}$ , $-3.5386 \times 10^{-2}$
–	–	rotation	$-1.1583 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $5.0000 \times 10^{-8}$
28	RR Lower A-arm	translation	$-4.5465 \times 10^{-3}$ , $1.7069 \times 10^{-2}$ , $-1.0366 \times 10^{-1}$
–	–	rotation	$-3.4138 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $5.0000 \times 10^{-8}$
29	RR Upper A-arm	translation	$1.3966 \times 10^{-3}$ , $2.5909 \times 10^{-2}$ , $-1.1890 \times 10^{-1}$
–	–	rotation	$-5.1817 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $5.0000 \times 10^{-8}$
30	RR Bell-crank	translation	$1.0500 \times 10^{-1}$ , $5.1208 \times 10^{-2}$ , $-2.2434 \times 10^{-1}$
–	–	rotation	$-3.3000 \times 10^{-7}$ , $1.0479 \times 10^0$ , $-1.0242 \times 10^0$
31	RR Push-rod	translation	$-9.8066 \times 10^{-4}$ , $6.8277 \times 10^{-2}$ , $-1.2073 \times 10^{-1}$
–	–	rotation	$-3.4138 \times 10^{-1}$ , $2.3772 \times 10^{-2}$ , $5.0000 \times 10^{-8}$
32	RR Tie-rod	translation	$-5.1408 \times 10^{-3}$ , $8.5346 \times 10^{-3}$ , $-1.5867 \times 10^{-1}$
–	–	rotation	$-3.2746 \times 10^{-1}$ , $7.7917 \times 10^{-2}$ , $-3.8674 \times 10^{-3}$
33	RR Wheel+hub	translation	$-9.8064 \times 10^{-4}$ , $3.4443 \times 10^{-2}$ , $-2.3803 \times 10^{-2}$
–	–	rotation	$-1.1583 \times 10^{-1}$ , $-1.4076 \times 10^{-4}$ , $5.0000 \times 10^{-8}$
34	RF Contact patch	translation	$2.7524 \times 10^{-2}$ , $-1.5756 \times 10^{-2}$ , $-2.5705 \times 10^{-2}$
–	–	rotation	$-1.7425 \times 10^{-1}$ , $4.1286 \times 10^{-3}$ , $9.2619 \times 10^{-2}$
35	RR Contact patch	translation	$-9.3842 \times 10^{-4}$ , $-3.0486 \times 10^{-4}$ , $-2.3803 \times 10^{-2}$
–	–	rotation	$-1.1583 \times 10^{-1}$ , $-1.4076 \times 10^{-4}$ , $5.0000 \times 10^{-8}$

Table 2.6: System Preloads

No.	Connector Name	Type	Load [N] or [Nm] (Components; Magnitude)
1	LF Wheel bearing	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $-3.7576 \times 10^3$ ; $3.7576 \times 10^3$
2	LF Lower ball joint	force	$-1.2600 \times 10^0$ , $-1.2134 \times 10^3$ , $-3.9405 \times 10^3$ ; $4.1231 \times 10^3$
3	LF Lower A-arm pivot, rear	force	$-1.2600 \times 10^0$ , $-3.4517 \times 10^3$ , $-4.8075 \times 10^1$ ; $3.4520 \times 10^3$
4	LF Lower A-arm pivot, front	force	$0.0000 \times 10^0$ , $-3.4473 \times 10^3$ , $-4.8075 \times 10^1$ ; $3.4476 \times 10^3$
5	LF Bell-crank pivot	force	$-4.7335 \times 10^3$ , $5.6856 \times 10^3$ , $-3.7757 \times 10^3$ ; $8.3059 \times 10^3$
–	–	moment	$-5.8860 \times 10^{-1}$ , $-9.5201 \times 10^1$ , $9.5201 \times 10^1$ ; $1.3464 \times 10^2$
6	LF Upper A-arm pivot, front	force	$0.0000 \times 10^0$ , $6.0522 \times 10^2$ , $1.4267 \times 10^2$ ; $6.2181 \times 10^2$
7	LF Upper A-arm pivot, rear	force	$1.0023 \times 10^0$ , $6.0748 \times 10^2$ , $1.4317 \times 10^2$ ; $6.2412 \times 10^2$
8	LF Upper ball joint	force	$-1.0023 \times 10^0$ , $-1.2127 \times 10^3$ , $-2.3679 \times 10^2$ ; $1.2356 \times 10^3$
9	LF Lower push-rod end	force	$0.0000 \times 10^0$ , $5.6856 \times 10^3$ , $-3.7953 \times 10^3$ ; $6.8359 \times 10^3$

10	LF Upper push-rod end	force	$0.0000 \times 10^0$ , $-5.6856 \times 10^3$ , $3.7855 \times 10^3$ ; $6.8305 \times 10^3$
11	LF Inner tie-rod end	force	$-2.5773 \times 10^{-1}$ , $-7.1591 \times 10^{-1}$ , $-4.9623 \times 10^0$ ; $5.0203 \times 10^0$
12	LF Outer tie-rod end	force	$2.5773 \times 10^{-1}$ , $7.1591 \times 10^{-1}$ , $-4.8477 \times 10^0$ ; $4.9071 \times 10^0$
13	LF Anti-roll mount	force	$-1.4500 \times 10^{-3}$ , $0.0000 \times 10^0$ , $9.8100 \times 10^0$ ; $9.8100 \times 10^0$
14	LR Wheel bearing	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $-3.4724 \times 10^3$ ; $3.4724 \times 10^3$
15	LR Lower ball joint	force	$1.3388 \times 10^0$ , $-1.1222 \times 10^3$ , $-3.6350 \times 10^3$ ; $3.8043 \times 10^3$
16	LR Lower A-arm pivot, front	force	$1.3388 \times 10^0$ , $-3.0244 \times 10^3$ , $-1.5007 \times 10^2$ ; $3.0281 \times 10^3$
17	LR Lower A-arm pivot, rear	force	$0.0000 \times 10^0$ , $-3.0197 \times 10^3$ , $-1.4974 \times 10^2$ ; $3.0234 \times 10^3$
18	LR Bell-crank pivot	force	$4.0966 \times 10^3$ , $4.9218 \times 10^3$ , $-3.2665 \times 10^3$ ; $7.1887 \times 10^3$
-	-	moment	$-4.9050 \times 10^{-1}$ , $8.2521 \times 10^1$ , $-8.2521 \times 10^1$ ; $1.1670 \times 10^2$
19	LR Upper A-arm pivot, rear	force	$0.0000 \times 10^0$ , $5.5942 \times 10^2$ , $1.3249 \times 10^2$ ; $5.7489 \times 10^2$
20	LR Upper A-arm pivot, front	force	$-1.1310 \times 10^0$ , $5.6196 \times 10^2$ , $1.3306 \times 10^2$ ; $5.7750 \times 10^2$
21	LR Upper ball joint	force	$1.1310 \times 10^0$ , $-1.1214 \times 10^3$ , $-2.1650 \times 10^2$ ; $1.1421 \times 10^3$
22	LR Lower push-rod end	force	$0.0000 \times 10^0$ , $4.9218 \times 10^3$ , $-3.2861 \times 10^3$ ; $5.9180 \times 10^3$
23	LR Upper push-rod end	force	$0.0000 \times 10^0$ , $-4.9218 \times 10^3$ , $3.2763 \times 10^3$ ; $5.9126 \times 10^3$
24	LR Inner tie-rod end	force	$2.0774 \times 10^{-1}$ , $-8.0788 \times 10^{-1}$ , $-4.9627 \times 10^0$ ; $5.0323 \times 10^0$
25	LR Outer tie-rod end	force	$-2.0774 \times 10^{-1}$ , $8.0788 \times 10^{-1}$ , $-4.8473 \times 10^0$ ; $4.9185 \times 10^0$
26	LF Contact patch constraint	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
27	LR Contact patch constraint	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
28	RF Wheel bearing	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $-3.7576 \times 10^3$ ; $3.7576 \times 10^3$
29	RF Lower ball joint	force	$-1.2600 \times 10^0$ , $1.2134 \times 10^3$ , $-3.9405 \times 10^3$ ; $4.1231 \times 10^3$
30	RF Lower A-arm pivot, rear	force	$-1.2600 \times 10^0$ , $3.4517 \times 10^3$ , $-4.8075 \times 10^1$ ; $3.4520 \times 10^3$
31	RF Lower A-arm pivot, front	force	$0.0000 \times 10^0$ , $3.4473 \times 10^3$ , $-4.8075 \times 10^1$ ; $3.4476 \times 10^3$
32	RF Bell-crank pivot	force	$-4.7336 \times 10^3$ , $-5.6856 \times 10^3$ , $-3.7757 \times 10^3$ ; $8.3059 \times 10^3$
-	-	moment	$5.8860 \times 10^{-1}$ , $-9.5201 \times 10^1$ , $-9.5201 \times 10^1$ ; $1.3464 \times 10^2$
33	RF Upper A-arm pivot, front	force	$0.0000 \times 10^0$ , $-6.0523 \times 10^2$ , $1.4267 \times 10^2$ ; $6.2181 \times 10^2$
34	RF Upper A-arm pivot, rear	force	$1.0023 \times 10^0$ , $-6.0748 \times 10^2$ , $1.4317 \times 10^2$ ; $6.2412 \times 10^2$
35	RF Upper ball joint	force	$-1.0023 \times 10^0$ , $1.2127 \times 10^3$ , $-2.3679 \times 10^2$ ; $1.2356 \times 10^3$
36	RF Lower push-rod end	force	$0.0000 \times 10^0$ , $-5.6856 \times 10^3$ , $-3.7953 \times 10^3$ ; $6.8359 \times 10^3$
37	RF Upper push-rod end	force	$0.0000 \times 10^0$ , $5.6856 \times 10^3$ , $3.7855 \times 10^3$ ; $6.8305 \times 10^3$
38	RF Inner tie-rod end	force	$-2.5773 \times 10^{-1}$ , $7.1591 \times 10^{-1}$ , $-4.9623 \times 10^0$ ; $5.0203 \times 10^0$
39	RF Outer tie-rod end	force	$2.5773 \times 10^{-1}$ , $-7.1591 \times 10^{-1}$ , $-4.8477 \times 10^0$ ; $4.9071 \times 10^0$
40	RF Anti-roll mount	force	$1.4500 \times 10^{-3}$ , $0.0000 \times 10^0$ , $9.8100 \times 10^0$ ; $9.8100 \times 10^0$
41	RR Wheel bearing	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $-3.4724 \times 10^3$ ; $3.4724 \times 10^3$
42	RR Lower ball joint	force	$1.3388 \times 10^0$ , $1.1222 \times 10^3$ , $-3.6350 \times 10^3$ ; $3.8043 \times 10^3$
43	RR Lower A-arm pivot, front	force	$1.3388 \times 10^0$ , $3.0243 \times 10^3$ , $-1.5007 \times 10^2$ ; $3.0281 \times 10^3$
44	RR Lower A-arm pivot, rear	force	$0.0000 \times 10^0$ , $3.0197 \times 10^3$ , $-1.4974 \times 10^2$ ; $3.0234 \times 10^3$
45	RR Bell-crank pivot	force	$4.0966 \times 10^3$ , $-4.9218 \times 10^3$ , $-3.2665 \times 10^3$ ; $7.1886 \times 10^3$
-	-	moment	$4.9050 \times 10^{-1}$ , $8.2521 \times 10^1$ , $8.2521 \times 10^1$ ; $1.1670 \times 10^2$
46	RR Upper A-arm pivot, rear	force	$0.0000 \times 10^0$ , $-5.5942 \times 10^2$ , $1.3249 \times 10^2$ ; $5.7489 \times 10^2$
47	RR Upper A-arm pivot, front	force	$-1.1310 \times 10^0$ , $-5.6196 \times 10^2$ , $1.3306 \times 10^2$ ; $5.7750 \times 10^2$
48	RR Upper ball joint	force	$1.1310 \times 10^0$ , $1.1214 \times 10^3$ , $-2.1650 \times 10^2$ ; $1.1421 \times 10^3$
49	RR Lower push-rod end	force	$0.0000 \times 10^0$ , $-4.9218 \times 10^3$ , $-3.2861 \times 10^3$ ; $5.9180 \times 10^3$
50	RR Upper push-rod end	force	$0.0000 \times 10^0$ , $4.9218 \times 10^3$ , $3.2763 \times 10^3$ ; $5.9126 \times 10^3$
51	RR Inner tie-rod end	force	$2.0774 \times 10^{-1}$ , $8.0788 \times 10^{-1}$ , $-4.9627 \times 10^0$ ; $5.0323 \times 10^0$
52	RR Outer tie-rod end	force	$-2.0774 \times 10^{-1}$ , $-8.0788 \times 10^{-1}$ , $-4.8473 \times 10^0$ ; $4.9185 \times 10^0$
53	RF Contact patch constraint	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
54	RR Contact patch constraint	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
55	LF Tire, vertical	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $3.8557 \times 10^3$ ; $3.8557 \times 10^3$
56	LR Tire, vertical	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $3.5705 \times 10^3$ ; $3.5705 \times 10^3$
57	LF Tire, sidewall	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
58	LR Tire, sidewall	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
59	LF Tire, horizontal	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
60	LR Tire, horizontal	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
61	RF Tire, vertical	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $3.8557 \times 10^3$ ; $3.8557 \times 10^3$
62	RR Tire, vertical	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $3.5705 \times 10^3$ ; $3.5705 \times 10^3$
63	RF Tire, sidewall	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
64	RR Tire, sidewall	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
65	RF Tire, horizontal	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$

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66	RR Tire, horizontal	force	$0.0000 \times 10^0$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $0.0000 \times 10^0$
67	LF Suspension spring	force	$4.7335 \times 10^3$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $-4.7335 \times 10^3$
68	LR Suspension spring	force	$-4.0966 \times 10^3$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $-4.0966 \times 10^3$
69	Anti-roll bar	moment	$0.0000 \times 10^0$ , $-2.2000 \times 10^{-4}$ , $0.0000 \times 10^0$ ; $2.2000 \times 10^{-4}$
70	RF Suspension spring	force	$4.7336 \times 10^3$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $-4.7336 \times 10^3$
71	RR Suspension spring	force	$-4.0966 \times 10^3$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $-4.0966 \times 10^3$
72	LF Drop link	force	$-1.4500 \times 10^{-3}$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $-1.4500 \times 10^{-3}$
73	RF Drop link	force	$1.4500 \times 10^{-3}$ , $0.0000 \times 10^0$ , $0.0000 \times 10^0$ ; $1.4500 \times 10^{-3}$

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Table 2.4: Hankel Singular Values

No.	Hankel SV
1	—
2	—
3	—
4	—
5	—
6	—
7	—
8	$1.6231316526 \times 10^0$
9	$1.2766885266 \times 10^0$
10	$8.9371716224 \times 10^{-1}$
11	$6.6864089737 \times 10^{-1}$
12	$1.3358992908 \times 10^{-2}$
13	$1.1692815448 \times 10^{-2}$
14	$1.9990616744 \times 10^{-3}$
15	$8.9283414651 \times 10^{-4}$
16	$3.8502854661 \times 10^{-4}$
17	$1.0475570377 \times 10^{-4}$
18	$1.3974419989 \times 10^{-5}$
19	$1.1026225267 \times 10^{-5}$
20	$5.0043380851 \times 10^{-6}$
21	$4.8880102047 \times 10^{-6}$
22	$2.6345082597 \times 10^{-6}$
23	$8.2549717760 \times 10^{-7}$
24	$1.9817843531 \times 10^{-8}$
25	$2.7837696082 \times 10^{-10}$
26	$9.3626576300 \times 10^{-13}$
27	$5.2393041340 \times 10^{-13}$
28	$3.0985981295 \times 10^{-13}$
29	$4.3810899733 \times 10^{-14}$
30	$3.2552864585 \times 10^{-15}$
31	$5.5675127928 \times 10^{-19}$
32	$6.9713344509 \times 10^{-25}$
33	$0.0000000000 \times 10^0$
34	$0.0000000000 \times 10^0$
35	$0.0000000000 \times 10^0$
36	$0.0000000000 \times 10^0$
37	$0.0000000000 \times 10^0$



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## CHAPTER 3

## CONCLUSION

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Replace this text with the conclusion to your report.

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## APPENDIX A

# EQUATIONS OF MOTION

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The equations of motion are of the form

$$\begin{bmatrix} \mathbf{I} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{M} & -\mathbf{G} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} \end{bmatrix} \begin{Bmatrix} \dot{\mathbf{p}} \\ \dot{\mathbf{w}} \\ \dot{\mathbf{u}} \end{Bmatrix} + \begin{bmatrix} \mathbf{V} & -\mathbf{I} & \mathbf{0} \\ \mathbf{K} & \mathbf{L} & -\mathbf{F} \\ \mathbf{0} & \mathbf{0} & \mathbf{I} \end{bmatrix} \begin{Bmatrix} \mathbf{p} \\ \mathbf{w} \\ \mathbf{u} \end{Bmatrix} = \begin{bmatrix} \mathbf{0} \\ \mathbf{0} \\ \mathbf{I} \end{bmatrix} \{ \mathbf{u} \}$$

The system is subject to constraints

$$\begin{bmatrix} \mathbf{J}_h & \mathbf{0} & \mathbf{0} \\ -\mathbf{J}_h \mathbf{V} & \mathbf{J}_h & \mathbf{0} \\ \mathbf{0} & \mathbf{J}_{nh} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \dot{\mathbf{p}} & \mathbf{p} \\ \dot{\mathbf{w}} & \mathbf{w} \\ \dot{\mathbf{u}} & \mathbf{u} \end{bmatrix} = \begin{bmatrix} \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}$$

The full state space equations:

$$\begin{bmatrix} \mathbf{E} & \mathbf{0} \\ \mathbf{0} & \mathbf{I} \end{bmatrix} \begin{Bmatrix} \dot{\mathbf{x}} \\ \mathbf{y} \end{Bmatrix} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{bmatrix} \begin{Bmatrix} \mathbf{x} \\ \mathbf{u} \end{Bmatrix}$$

# A. EQUATIONS OF MOTION

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{bmatrix} = \begin{bmatrix} -5.53013967 \times 10^3 & -4.07750499 \times 10^3 & -3.72017913 \times 10^3 & 6.66326815 \times 10^3 & 2.63160974 \times 10^3 & -8.10715489 \times 10^2 & -3.02002858 \times 10^3 & - \\ 2.57518804 \times 10^3 & 4.23923436 \times 10^3 & 7.96022610 \times 10^3 & -1.70055868 \times 10^3 & -6.03946561 \times 10^2 & 4.68164817 \times 10^2 & 1.02605854 \times 10^4 & - \\ 4.59861428 \times 10^3 & 2.01372315 \times 10^3 & 9.68744518 \times 10^2 & -3.30421364 \times 10^3 & -2.30259507 \times 10^3 & 8.77365229 \times 10^2 & -4.77978466 \times 10^3 & - \\ 2.02816041 \times 10^3 & 2.03032734 \times 10^3 & 5.96744268 \times 10^3 & 1.10647044 \times 10^2 & -5.25185456 \times 10^2 & -8.86183731 \times 10^2 & 8.08874251 \times 10^3 & - \\ -2.36641506 \times 10^3 & -1.15052403 \times 10^3 & 1.72708565 \times 10^3 & 3.06343127 \times 10^3 & 1.03628594 \times 10^3 & -3.66303915 \times 10^2 & 7.27078622 \times 10^2 & - \\ -1.90857828 \times 10^3 & -1.12419993 \times 10^3 & 7.64028047 \times 10^2 & 1.51248557 \times 10^2 & 2.63351189 \times 10^2 & -4.19077211 \times 10^2 & 2.18081325 \times 10^3 & - \\ 6.54266329 \times 10^2 & 3.36722137 \times 10^2 & 1.18805790 \times 10^3 & 5.41075228 \times 10^3 & 1.16862084 \times 10^3 & 9.81705740 \times 10^1 & 1.50665155 \times 10^3 & - \\ -4.78691914 \times 10^3 & -3.00188331 \times 10^3 & -5.02018598 \times 10^3 & 1.10547362 \times 10^2 & 2.00004968 \times 10^3 & 2.35500607 \times 10^3 & -5.51539485 \times 10^3 & - \\ -2.38565835 \times 10^3 & -6.90769428 \times 10^2 & -2.07334791 \times 10^3 & -6.79850025 \times 10^3 & -8.54014731 \times 10^2 & 1.33803500 \times 10^3 & -3.72069966 \times 10^3 & - \\ 4.81051958 \times 10^3 & 9.57169873 \times 10^3 & 1.20297421 \times 10^4 & -5.20220496 \times 10^3 & -3.12641209 \times 10^3 & -4.90378977 \times 10^1 & 1.41172023 \times 10^4 & - \\ -4.01874437 \times 10^3 & -3.21759095 \times 10^3 & 2.36037662 \times 10^3 & 2.73492365 \times 10^3 & 1.93484854 \times 10^3 & -7.11810517 \times 10^2 & 4.81073197 \times 10^3 & - \\ 1.97089136 \times 10^3 & 2.93769191 \times 10^3 & 1.37724708 \times 10^4 & -2.68406771 \times 10^3 & -1.12119985 \times 10^3 & -2.88493160 \times 10^3 & 2.02937216 \times 10^4 & - \\ 1.13828824 \times 10^3 & -6.65278193 \times 10^2 & -1.76407967 \times 10^3 & -4.93051790 \times 10^3 & -1.18512770 \times 10^3 & -4.78426321 \times 10^2 & -2.48875075 \times 10^3 & - \\ -4.29631498 \times 10^3 & 2.26586884 \times 10^3 & 9.68430329 \times 10^3 & 1.95743073 \times 10^3 & 6.82228554 \times 10^2 & -2.67644850 \times 10^3 & 1.59064881 \times 10^4 & - \\ -7.58404357 \times 10^2 & -2.92278449 \times 10^3 & -1.07861427 \times 10^4 & 3.39805963 \times 10^3 & 8.07502106 \times 10^2 & 1.24624571 \times 10^3 & -1.67888540 \times 10^4 & - \\ -1.83614320 \times 10^3 & -1.47773847 \times 10^3 & 7.35802722 \times 10^1 & 4.11345731 \times 10^3 & 1.21722958 \times 10^3 & 1.80966240 \times 10^0 & -6.18945190 \times 10^2 & - \\ -1.14978226 \times 10^3 & 4.12215211 \times 10^2 & 6.37728220 \times 10^3 & -2.51031696 \times 10^3 & -7.27675348 \times 10^2 & -2.63566742 \times 10^3 & 1.03955436 \times 10^4 & - \\ 2.90992981 \times 10^3 & 2.66423362 \times 10^3 & 3.54840927 \times 10^3 & 7.68068094 \times 10^2 & -6.30377037 \times 10^2 & -2.44297762 \times 10^2 & 3.51821469 \times 10^3 & - \\ 2.09104455 \times 10^3 & -1.74808106 \times 10^3 & -3.52705660 \times 10^3 & -8.07531293 \times 10^2 & -1.12283732 \times 10^2 & 1.21488368 \times 10^3 & -5.95478702 \times 10^3 & - \\ -3.45372051 \times 10^3 & -4.55455000 \times 10^2 & 3.16681824 \times 10^3 & 8.14904911 \times 10^2 & 1.48382393 \times 10^3 & -3.52931287 \times 10^2 & 7.28517737 \times 10^3 & - \\ 7.35425110 \times 10^3 & 8.58538647 \times 10^3 & 1.66718200 \times 10^4 & -9.51815431 \times 10^3 & -5.22502374 \times 10^3 & -2.44297762 \times 10^2 & 1.88063476 \times 10^4 & - \\ -1.64782272 \times 10^3 & 3.38487932 \times 10^3 & 9.22243070 \times 10^3 & -6.80211597 \times 10^2 & -2.73536683 \times 10^2 & -1.90273158 \times 10^3 & 1.50963316 \times 10^4 & - \\ 1.51122741 \times 10^3 & 3.79715098 \times 10^2 & 4.64299080 \times 10^3 & 4.81391360 \times 10^3 & 6.90858042 \times 10^2 & -1.29574750 \times 10^3 & 6.56045688 \times 10^3 & - \\ -4.09137313 \times 10^3 & -3.04586124 \times 10^3 & 1.33507976 \times 10^3 & 5.23048745 \times 10^3 & 2.87700110 \times 10^3 & -6.97243444 \times 10^2 & 4.91421557 \times 10^3 & - \\ 7.41648904 \times 10^2 & 5.19205707 \times 10^3 & 9.39965086 \times 10^3 & -1.05087245 \times 10^3 & -1.02411716 \times 10^3 & -5.76284117 \times 10^2 & 1.24175062 \times 10^4 & - \\ 6.56204971 \times 10^4 & 4.76391218 \times 10^4 & 5.35116470 \times 10^3 & -4.09121967 \times 10^2 & -2.10679124 \times 10^4 & 1.03811867 \times 10^4 & -3.56891006 \times 10^4 & - \\ 1.22069143 \times 10^3 & -2.93723142 \times 10^2 & -2.59662391 \times 10^3 & 9.90026366 \times 10^3 & 1.37310013 \times 10^3 & -4.10140859 \times 10^2 & -4.32754534 \times 10^3 & - \\ -7.02288075 \times 10^2 & -9.23872053 \times 10^2 & -5.73068668 \times 10^3 & 7.71910003 \times 10^3 & 7.44238562 \times 10^2 & -1.55945646 \times 10^3 & -7.35900889 \times 10^3 & - \\ 3.09018773 \times 10^3 & 3.00184244 \times 10^3 & 7.09120220 \times 10^3 & 3.29507784 \times 10^3 & -5.11161320 \times 10^2 & -1.40380231 \times 10^3 & 8.58928644 \times 10^3 & - \\ -1.90675321 \times 10^3 & -2.47231413 \times 10^3 & -5.07140216 \times 10^2 & 5.83120375 \times 10^3 & 1.33901291 \times 10^3 & -8.70697282 \times 10^2 & -2.06296778 \times 10^3 & - \\ 3.60318827 \times 10^3 & -3.13044323 \times 10^2 & 4.87212835 \times 10^3 & 4.51072159 \times 10^1 & 4.38772884 \times 10^2 & 5.23116119 \times 10^1 & 6.64483494 \times 10^3 & - \\ 1.40407953 \times 10^4 & -2.57672377 \times 10^4 & -7.19882689 \times 10^3 & -2.89544008 \times 10^3 & -5.36953256 \times 10^2 & -1.05897769 \times 10^4 & -3.80235896 \times 10^3 & - \\ 3.94548738 \times 10^2 & 1.29200136 \times 10^3 & 3.65821722 \times 10^3 & -5.89716877 \times 10^3 & -2.26176526 \times 10^3 & -2.05948753 \times 10^3 & 4.77848419 \times 10^3 & - \\ 2.94186907 \times 10^3 & 2.79373226 \times 10^3 & -1.52210510 \times 10^3 & -3.06147700 \times 10^3 & -1.82465789 \times 10^3 & 3.27297308 \times 10^1 & -1.94916118 \times 10^3 & - \\ -4.21543562 \times 10^3 & -5.08236866 \times 10^2 & -3.17688771 \times 10^3 & -4.80903025 \times 10^3 & -5.63734349 \times 10^2 & 1.32331225 \times 10^3 & -4.53829539 \times 10^3 & - \\ -1.02158679 \times 10^2 & -7.13434189 \times 10^2 & -3.40863399 \times 10^3 & -9.00285487 \times 10^3 & -1.37113359 \times 10^3 & 7.92116706 \times 10^2 & -3.15747665 \times 10^3 & - \\ 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & - \\ -9.81036670 \times 10^{-3} & -4.58963541 \times 10^{-2} & 4.55286254 \times 10^{-2} & -4.24253755 \times 10^{-2} & 3.85369328 \times 10^{-2} & 4.90916905 \times 10^{-2} & 3.64980491 \times 10^{-2} & - \\ 2.24531240 \times 10^{-2} & 2.19022161 \times 10^{-2} & -1.34133686 \times 10^{-2} & -2.18080321 \times 10^{-2} & 2.25237518 \times 10^{-2} & 3.36016391 \times 10^{-3} & 2.73398320 \times 10^{-3} & - \\ -3.22634907 \times 10^{-2} & -6.77985702 \times 10^{-2} & 5.89419940 \times 10^{-2} & -2.06173434 \times 10^{-2} & 1.60131810 \times 10^{-2} & 4.57315266 \times 10^{-2} & 3.37640659 \times 10^{-2} & - \end{bmatrix}$$

$$\mathbf{E} = \begin{bmatrix} -1.19976821 \times 10^1 & 1.75014539 \times 10^1 & -1.40295221 \times 10^1 & 3.40626380 \times 10^{-1} & -1.07129199 \times 10^1 & -1.07050792 \times 10^1 & 1.79718425 \times 10^1 & 8.909246 \\ 5.19332478 \times 10^0 & -2.49249397 \times 10^1 & 1.28739074 \times 10^1 & 8.35170447 \times 10^0 & 3.84796720 \times 10^0 & 5.09760197 \times 10^0 & -2.21983588 \times 10^1 & 4.350113 \\ -5.70350071 \times 10^0 & 2.37678759 \times 10^1 & -8.86960304 \times 10^0 & -7.32196346 \times 10^0 & 2.84708622 \times 10^0 & 3.64980030 \times 10^0 & 1.29907435 \times 10^1 & -7.305111 \\ 5.89904016 \times 10^0 & -6.62715235 \times 10^0 & 8.90021370 \times 10^0 & -3.74095793 \times 10^0 & 8.83925977 \times 10^0 & 8.50898504 \times 10^0 & -5.05654422 \times 10^0 & -7.870575 \\ -3.30843648 \times 10^0 & 1.70094297 \times 10^0 & 2.24825603 \times 10^{-1} & 8.81826095 \times 10^{-1} & -1.49112782 \times 10^{-1} & -9.25425784 \times 10^{-1} & 7.06469893 \times 10^{-1} & 2.299107 \\ -1.09057292 \times 10^1 & 6.28234307 \times 10^0 & -7.72066608 \times 10^0 & 4.99586200 \times 10^0 & -8.42997411 \times 10^0 & -5.89787076 \times 10^0 & 4.67746767 \times 10^0 & 1.010944 \\ 5.95727582 \times 10^0 & -9.68761070 \times 10^0 & 5.73436617 \times 10^0 & -1.81846552 \times 10^0 & 5.81566196 \times 10^0 & 7.40619779 \times 10^0 & -3.57916534 \times 10^0 & -3.641935 \\ -4.78596397 \times 10^0 & -2.90992069 \times 10^1 & 8.68759017 \times 10^0 & 1.62880412 \times 10^1 & -4.65302990 \times 10^0 & -2.23109950 \times 10^0 & 2.02954005 \times 10^1 & 1.980710 \\ -1.10500295 \times 10^1 & -1.97267527 \times 10^0 & -5.40946493 \times 10^0 & 9.13846940 \times 10^0 & -9.18479838 \times 10^0 & -7.42055691 \times 10^0 & -1.03415695 \times 10^0 & 1.539555 \\ -7.16351227 \times 10^0 & -5.15198701 \times 10^0 & -5.92374881 \times 10^{-1} & 6.56094824 \times 10^0 & -1.86445445 \times 10^0 & -1.55846913 \times 10^0 & -2.03750157 \times 10^0 & 1.275481 \\ -3.55903343 \times 10^0 & -1.88460773 \times 10^1 & 3.12090456 \times 10^0 & 8.57305011 \times 10^0 & -4.82383311 \times 10^0 & -4.80957132 \times 10^{-1} & -6.05253313 \times 10^0 & 1.255054 \\ 1.28856976 \times 10^0 & 1.03742062 \times 10^1 & -3.40683561 \times 10^0 & -4.33479902 \times 10^0 & -1.91012478 \times 10^0 & -4.26426834 \times 10^0 & 5.62762007 \times 10^0 & -6.347900 \\ -2.24660153 \times 10^0 & 1.69012455 \times 10^1 & -8.08940648 \times 10^0 & -8.22717082 \times 10^0 & -5.10633657 \times 10^{-1} & 3.59968435 \times 10^{-1} & 1.91266662 \times 10^1 & -5.333922 \\ -2.02067157 \times 10^1 & 2.73160581 \times 10^0 & -1.08710416 \times 10^1 & 1.37824647 \times 10^1 & 1.74575417 \times 10^1 & -1.67917766 \times 10^1 & 5.10084539 \times 10^0 & 2.681458 \\ -7.39767929 \times 10^0 & 3.37429148 \times 10^1 & -1.46658523 \times 10^1 & -9.39150000 \times 10^0 & -1.67698149 \times 10^0 & -3.18910681 \times 10^0 & 2.27613870 \times 10^1 & -7.026058 \\ -6.80901922 \times 10^0 & -5.77078242 \times 10^0 & -1.43755386 \times 10^0 & 4.14874376 \times 10^0 & -2.43824431 \times 10^0 & 2.22624690 \times 10^0 & 1.47909341 \times 10^0 & 9.206695 \\ -2.44000512 \times 10^0 & -3.52025952 \times 10^0 & -4.47119880 \times 10^{-1} & 2.22582855 \times 10^0 & -4.05714505 \times 10^0 & -2.53864735 \times 10^0 & 1.21970000 \times 10^0 & 4.357357 \\ 2.45779625 \times 10^0 & 3.37961496 \times 10^0 & 8.49715703 \times 10^{-1} & -4.35713898 \times 10^0 & 4.58753568 \times 10^0 & 4.16787473 \times 10^0 & 3.11630050 \times 10^0 & -5.577548 \\ 1.34010892 \times 10^1 & -2.45753955 \times 10^1 & 1.62052981 \times 10^1 & -3.53605290 \times 10^0 & 1.40520617 \times 10^1 & 1.83432281 \times 10^1 & -1.19614092 \times 10^1 & -1.026959 \\ -3.44275625 \times 10^0 & -2.32764900 \times 10^1 & 5.54018348 \times 10^0 & 1.50499280 \times 10^1 & -7.89648103 \times 10^0 & -7.24482717 \times 10^0 & -1.94412683 \times 10^1 & 1.643830 \\ -4.08624130 \times 10^0 & 1.82024036 \times 10^1 & -9.86586445 \times 10^0 & -3.87435762 \times 10^0 & -2.96679603 \times 10^0 & -2.96884330 \times 10^0 & 1.09995385 \times 10^1 & -3.060963 \\ -9.71680675 \times 10^0 & -1.75130741 \times 10^0 & -4.31435265 \times 10^0 & 9.37315489 \times 10^0 & -1.02004442 \times 10^1 & -1.12468958 \times 10^1 & -1.03130416 \times 10^0 & 1.585459 \\ 6.40605052 \times 10^0 & 6.57329767 \times 10^0 & 2.82374952 \times 10^0 & -8.91078937 \times 10^0 & 7.16954698 \times 10^0 & 5.76407722 \times 10^0 & 4.27856552 \times 10^0 & -1.316558 \\ -2.43754906 \times 10^0 & -8.63964288 \times 10^0 & 4.59883358 \times 10^{-1} & 5.11530715 \times 10^0 & -5.62417509 \times 10^0 & -3.84602421 \times 10^0 & -3.43354612 \times 10^0 & 7.198393 \\ -7.39738461 \times 10^0 & -1.72882299 \times 10^1 & 4.30983617 \times 10^{-1} & 1.22434078 \times 10^1 & -6.71311658 \times 10^0 & -2.93496745 \times 10^0 & -6.18168066 \times 10^0 & 1.864026 \\ 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.000000 \\ 5.91787342 \times 10^0 & 1.65027146 \times 10^1 & -4.78944654 \times 10^0 & -8.47364028 \times 10^0 & 3.25427064 \times 10^0 & 5.74234230 \times 10^{-1} & 6.63857409 \times 10^0 & -1.329830 \\ -6.56033432 \times 10^0 & 3.95995418 \times 10^1 & -1.56515433 \times 10^1 & -1.09172479 \times 10^1 & -3.11281483 \times 10^0 & -8.76245639 \times 10^0 & 2.38803514 \times 10^1 & -8.193333 \\ 3.27634113 \times 10^0 & 3.65217722 \times 10^0 & -1.16912164 \times 10^0 & -4.12792681 \times 10^0 & 2.63042657 \times 10^0 & 3.26670095 \times 10^0 & 3.52534934 \times 10^0 & -6.114341 \\ -6.72047277 \times 10^0 & 8.41789881 \times 10^0 & -7.13902064 \times 10^0 & -8.12790788 \times 10^{-1} & -3.41080793 \times 10^0 & 6.44245999 \times 10^{-1} & 1.00878128 \times 10^1 & 2.235968 \\ 2.25560605 \times 10^1 & -3.30153987 \times 10^1 & 2.54722609 \times 10^1 & -7.85188110 \times 10^0 & 2.11764552 \times 10^1 & 2.46126984 \times 10^1 & -1.88817459 \times 10^1 & -1.918905 \\ 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.000000 \\ -1.20659635 \times 10^1 & 3.24120097 \times 10^1 & -1.80818194 \times 10^1 & -4.48765376 \times 10^0 & -1.03405570 \times 10^1 & -1.26174680 \times 10^1 & 2.41352449 \times 10^1 & 2.676777 \\ 4.71493349 \times 10^0 & 1.30164907 \times 10^1 & 3.93802481 \times 10^{-1} & -1.04271305 \times 10^1 & 7.21003073 \times 10^0 & 3.53310786 \times 10^0 & 1.00834191 \times 10^1 & -1.152844 \\ 3.69494981 \times 10^{-1} & -1.65125258 \times 10^1 & 4.82239334 \times 10^0 & 6.54657623 \times 10^0 & -8.21118585 \times 10^{-1} & 1.63160357 \times 10^0 & -9.91437830 \times 10^0 & 7.411212 \\ -4.42477165 \times 10^0 & -1.76914411 \times 10^0 & -1.00877006 \times 10^0 & 3.66163879 \times 10^0 & -4.29780356 \times 10^0 & -4.88487798 \times 10^0 & 5.71426571 \times 10^{-1} & 7.054761 \\ 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.00000000 \times 10^0 & 0.000000 \end{bmatrix}$$

The reduced state space equations:

$$\begin{Bmatrix} \dot{x} \\ y \end{Bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{Bmatrix} x \\ u \end{Bmatrix}$$

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} -1.03935745 \times 10^2 & -4.15043235 \times 10^2 & -1.18255207 \times 10^2 & -1.66966760 \times 10^2 & 3.72898600 \times 10^1 & -1.06306375 \times 10^2 & -8.76364759 \times 10^1 \\ 1.01880130 \times 10^1 & -3.55176173 \times 10^0 & -2.63722372 \times 10^1 & 9.99837813 \times 10^0 & -2.23300805 \times 10^0 & 6.36588582 \times 10^0 & 5.24788660 \times 10^0 \\ 2.93562933 \times 10^1 & -1.06314119 \times 10^1 & -4.86137853 \times 10^1 & 2.33833375 \times 10^1 & 1.01009905 \times 10^0 & -2.87960233 \times 10^0 & -2.37387646 \times 10^0 \\ 1.44824284 \times 10^2 & 4.43011314 \times 10^2 & -1.74863731 \times 10^1 & 8.84155189 \times 10^1 & 4.24315233 \times 10^1 & 1.03576345 \times 10^2 & 8.53859034 \times 10^1 \\ 1.82343771 \times 10^2 & 5.98005613 \times 10^2 & 4.74610962 \times 10^1 & 2.25870784 \times 10^2 & -2.51784528 \times 10^1 & 1.67094644 \times 10^2 & 1.16093785 \times 10^2 \\ -1.64173819 \times 10^2 & -2.35899235 \times 10^2 & 2.61934502 \times 10^2 & -3.76834437 \times 10^1 & -1.07558890 \times 10^2 & -6.70693821 \times 10^1 & -4.14844304 \times 10^1 \\ -1.24688516 \times 10^2 & -3.72778524 \times 10^2 & 6.18788973 \times 10^1 & -1.04541437 \times 10^2 & -3.13674566 \times 10^1 & -9.01606628 \times 10^1 & -6.70988071 \times 10^1 \\ -2.85365576 \times 10^2 & -1.85988971 \times 10^3 & -3.97111178 \times 10^2 & -4.85058368 \times 10^2 & 1.04193183 \times 10^2 & -6.18380987 \times 10^2 & -3.78016724 \times 10^2 \\ -8.09211801 \times 10^2 & -1.20642420 \times 10^3 & 2.59455287 \times 10^3 & 5.22525975 \times 10^1 & -1.25249846 \times 10^3 & 8.27395478 \times 10^1 & -7.62107038 \times 10^1 \\ -3.30746536 \times 10^2 & 4.62066127 \times 10^2 & 2.69922230 \times 10^3 & 4.38839081 \times 10^2 & -1.23152431 \times 10^3 & 6.02359159 \times 10^2 & 2.66499415 \times 10^2 \\ -1.46135567 \times 10^2 & -3.00558166 \times 10^2 & 1.91254430 \times 10^3 & 1.58907101 \times 10^2 & -8.95207045 \times 10^2 & 2.43999520 \times 10^2 & 8.45970630 \times 10^1 \\ -9.03986970 \times 10^2 & -8.81865228 \times 10^2 & -2.25373140 \times 10^2 & -1.56648858 \times 10^3 & 8.97027723 \times 10^1 & 5.63515618 \times 10^2 & -1.95990871 \times 10^2 \\ -4.43299496 \times 10^3 & 1.12822594 \times 10^3 & -1.21966480 \times 10^3 & 1.71361596 \times 10^3 & 4.60983243 \times 10^2 & -9.89083201 \times 10^2 & -3.27649385 \times 10^2 \\ 7.56551121 \times 10^2 & 1.17816773 \times 10^3 & 1.86531173 \times 10^3 & 4.13413012 \times 10^3 & -9.59633398 \times 10^2 & -1.73027696 \times 10^3 & 2.74923573 \times 10^2 \\ -6.13510165 \times 10^3 & -1.08608706 \times 10^3 & -2.75088874 \times 10^3 & -1.57166576 \times 10^2 & 1.09747503 \times 10^3 & -1.14217640 \times 10^3 & -9.39499149 \times 10^2 \\ 3.94067853 \times 10^3 & 1.22185325 \times 10^3 & -7.01883805 \times 10^2 & 5.69454600 \times 10^2 & 4.40760046 \times 10^2 & 2.16260174 \times 10^1 & 4.99029973 \times 10^2 \\ -2.32311313 \times 10^2 & -7.61545070 \times 10^2 & -1.11729388 \times 10^3 & -3.94636793 \times 10^2 & 4.88825498 \times 10^2 & -3.66844380 \times 10^2 & -2.27807564 \times 10^2 \\ 9.90561134 \times 10^2 & -8.36295397 \times 10^2 & -7.08450115 \times 10^2 & -2.41341215 \times 10^2 & 3.17011132 \times 10^2 & -3.91475104 \times 10^2 & -1.13485652 \times 10^2 \\ -3.72670905 \times 10^3 & 1.55686170 \times 10^2 & 3.00517625 \times 10^3 & 1.56521108 \times 10^3 & -1.50257990 \times 10^3 & -2.22730684 \times 10^2 & -1.09398844 \times 10^2 \\ 7.23501752 \times 10^2 & -4.39794492 \times 10^2 & -2.63020149 \times 10^3 & -1.75516711 \times 10^3 & 1.26156382 \times 10^3 & 2.97628471 \times 10^2 & -1.59727164 \times 10^2 \\ -2.21435045 \times 10^3 & -1.20050399 \times 10^3 & -4.95255261 \times 10^3 & -5.60338104 \times 10^3 & 2.40409722 \times 10^3 & 1.90416629 \times 10^3 & -5.84239217 \times 10^2 \\ -4.58181461 \times 10^2 & -5.34572996 \times 10^2 & -1.52043438 \times 10^3 & -7.11073992 \times 10^2 & 6.77132867 \times 10^2 & -1.71601635 \times 10^2 & -2.32537043 \times 10^2 \\ 9.61029177 \times 10^2 & -1.54614804 \times 10^2 & -1.01855206 \times 10^3 & 1.04594813 \times 10^1 & 4.52932420 \times 10^2 & -3.30349217 \times 10^2 & -2.00291200 \times 10^1 \\ -1.07897401 \times 10^{-1} & -1.03044812 \times 10^{-2} & -1.69058741 \times 10^{-2} & -1.66279879 \times 10^{-2} & 1.92665093 \times 10^{-2} & 3.18919643 \times 10^{-3} & 1.77525426 \times 10^{-2} \\ 3.29134703 \times 10^{-4} & -2.06158735 \times 10^{-3} & -5.40593010 \times 10^{-3} & 3.88704971 \times 10^{-2} & 1.20614973 \times 10^{-2} & -2.61079085 \times 10^{-2} & 2.41274104 \times 10^{-2} \\ -1.08226535 \times 10^{-1} & -8.24289384 \times 10^{-3} & -1.14999440 \times 10^{-2} & -5.54984850 \times 10^{-2} & 7.20501202 \times 10^{-3} & 2.92971049 \times 10^{-2} & -6.37486783 \times 10^{-3} \end{bmatrix}$$