Chapter Summary

- 1. A transformation is a one-to-one mapping from the whole plane to the whole plane. If the transformation S maps P to P', we write $S:P \to P'$ or S(P) = P'.
- 2. The word "mapping" is used in geometry as the word "function" is used in algebra. If the function f maps every number to its square we write $f: x \to x^2$ or $f(x) = x^2$.
- 3. An isometry is a transformation that preserves distance. An isometry maps any figure to a congruent figure.
- 4. Some basic isometries are:

Reflection in a line. R_i is a reflection in line j.

Translation or glide. $T:(x, y) \rightarrow (x + a, y + b)$ is a translation.

Rotation about a point. $\mathcal{R}_{O, x}$ is a rotation counterclockwise about O through x° . H_{O} is a half-turn about O.

Glide reflection. A glide followed by a reflection in a line parallel to the glide yields a glide reflection.

- 5. A dilation maps any figure to a similar figure. $D_{O,k}$ is a dilation with center O and nonzero scale factor k. A dilation is an isometry if |k| = 1.
- **6.** Properties of figures that are preserved by a transformation are said to be invariant under that transformation. Invariant properties are checked in the table below.

- 7. The combination of one mapping followed by another is called a composite or product of mappings. The mapping A followed by B is written $B \circ A$.
- 8. A composite of isometries is an isometry.

A composite of reflections in two parallel lines is a translation.

A composite of reflections in two intersecting lines is a rotation.

A composite of reflections in two perpendicular lines is a half-turn.

- 9. The identity transformation I keeps all points fixed. A transformation S followed by its inverse S^{-1} is equal to the identity.
- 10. A symmetry of a figure is an isometry that maps the figure onto itself. Figures can have line symmetry, point symmetry, and rotational symmetry. A tessellation, or covering of the plane with congruent figures, may also have translational and glide reflection symmetry. Solid figures in space can have planes of symmetry and rotational symmetry about an axis.