

Translational Mechanics Symbols Used in This Book

Symbols that are **boldfaced** refer to vector quantities that have both a magnitude and a direction. Symbols that are *italicized* refer to quantities with only a magnitude. Symbols that are neither are usually units.

Symbol	Quantity
a , <i>a</i>	acceleration
a_g	free-fall acceleration (acceleration due to gravity)
d , <i>d</i>	displacement
F Δt	impulse
F_g , <i>F_g</i>	gravitational force (weight)
F_k , <i>F_k</i>	force of kinetic friction
F_n , <i>F_n</i>	normal force
F_{net} , <i>F_{net}</i>	net force
F_R , <i>F_R</i>	force of air resistance
F_s , <i>F_s</i>	force of static friction
F_{s,max} , <i>F_{s,max}</i>	maximum force of static friction
<i>h</i>	height
<i>k</i>	spring constant
<i>KE</i>	kinetic energy
<i>KE_{trans}</i>	translational kinetic energy
<i>MA</i>	mechanical advantage
<i>ME</i>	mechanical energy (sum of all kinetic and potential energies)
μ_k	(Greek <i>mu</i>) coefficient of kinetic friction
μ_s	(Greek <i>mu</i>) coefficient of static friction
<i>P</i>	power
p , <i>p</i>	momentum
<i>PE</i>	potential energy
<i>PE_{elastic}</i>	elastic potential energy
<i>PE_g</i>	gravitational potential energy
<i>r</i>	separation between point masses
v , <i>v</i>	velocity or speed
<i>W</i>	work
<i>W_{friction}</i>	work done by a frictional force (or work required to overcome a frictional force)
<i>W_{net}</i>	net work done
$\Delta \mathbf{x}$, Δx	displacement in the <i>x</i> direction
$\Delta \mathbf{y}$, Δy	displacement in the <i>y</i> direction