# MA201: Partial Differential Equations Lecture - 6

 A second-order PDE in two independent variables x and y in its most general form is given by

$$F(x, y, u, u_x, u_y, u_{xy}, u_{xx}, u_{yy}) = 0.$$
 (1)

• The linear form of a second-order PDE in two independent variables is the following when the unknown function u(x, y) satisfies

$$Au_{xx} + Bu_{xy} + Cu_{yy} + Du_x + Eu_y + Fu + G = 0.$$
 (2)

where A, B, C, D, E, F and G are, in general, functions of x and y. Facts:

- The expression  $Lu \equiv Au_{xx} + Bu_{xy} + Cu_{yy}$ , containing the second-order partial derivatives, is called the Principal part of equation (2).
- Classification of such PDEs is based on this principal part. We will discuss it later.
- Second-order PDEs have immense importance in all branches of science and engineering.

### Second-order Linear Equations

• Consider the second-order linear equation in two independent variables x and y given by (2) in the following form:

$$(Au_{xx} + Bu_{xy} + Cu_{yy} + Du_x + Eu_y + Fu)(x, y) = -G(x, y).$$
 (3)

In operator notation,

$$(T(u))(x,y) = -G(x,y) = f(x,y)$$
(say), (4)

with

$$T(u) = Au_{xx} + Bu_{xy} + Cu_{yy} + Du_x + Eu_y + Fu.$$

• Since T is linear, we have

$$T(u_1 + u_2) = T(u_1) + T(u_2) \& T(cu) = cT(u) \forall c \in \mathbb{R}.$$
 (5)

#### Remark:

• Equation (4) is called homogeneous, if  $f \equiv 0$ , otherwise it is called non-homogeneous.

### The Principle of Superposition

#### Theorem

Suppose  $u_1$  solves linear PDE  $T(u) = f_1$  and  $u_2$  solves  $T(u) = f_2$ , then  $u = c_1u_1 + c_2u_2$  solves  $T(u) = c_1f_1 + c_2f_2$ . In particular, if  $u_1$  and  $u_2$  both solve the same homogeneous linear PDE T(u) = 0, so does  $u = c_1u_1 + c_2u_2$ .

### Remark:

- Any linear combination of solutions of a linear homogeneous PDE is also a solution.
- A solution u = u(x, y) to a homogeneous equation T(u) = 0 is called the *general solution* if it contains two arbitrary functions.
- If u is a general solution to homogeneous PDE T(u)=0 and  $u_p$  is a particular solution to non-homogeneous PDE T(w)=f, then  $u+u_p$  is also a solution to the non-homogeneous equation and it is called the general solution to the PDE T(w)=f.

### Linear Equations with Constant Coefficients

►With the notations  $D = \partial/\partial x$  and  $D' = \partial/\partial y$ , a PDE with constant coefficients can be written as

$$F(D, D')u = f. (6)$$

- ► We classify PDE (6) into two main types (with respect to the appearance of the operators):
  - **Reducible:** Equation (6) is called reducible if it can be written as the product of linear factors of the form aD + bD' + c, with constants a, b, c. For example, consider the equation

$$u_{xx}-u_{yy}=0.$$

In this case

$$F(D, D') = D^2 - (D')^2 = (D + D')(D - D').$$

• Irreducible: Equation (6) is called irreducible if it is not reducible. For example, when we consider  $F(D, D') = D^2 - D'$ .

## Linear Equations with Constant Coefficients: Reducible Equation

An *n*-th order reducible PDE can be written as

$$F(D, D')u = \left(\prod_{r=1}^{n} (a_r D + b_r D' + c_r)\right) u = f.$$
 (7)

#### Theorem 1

If  $(a_rD + b_rD' + c_r)$  is a factor of F(D, D'),  $a_r \neq 0$ , then

$$u_r = \exp\left\{-\frac{c_r x}{a_r}\right\} \phi_r (b_r x - a_r y)$$

is a solution of the equation F(D, D')u = 0. Here,  $\phi_r$  is an arbitrary real-valued function.

#### Theorem 2

If  $(b_rD'+c_r)$  is a factor of F(D,D') and  $\phi_r$  is an arbitrary real-valued single variable function, then

$$u_r = \exp\left\{-\frac{c_r y}{b_r}\right\} \phi_r(b_r x)$$

is a solution of the equation F(D, D')u = 0.

# Linear Equations with Constant Coefficients: Reducible Equation

### Theorem 3

If  $(aD + bD' + c)^m$   $(m \le n, a \ne 0)$  is a factor of F(D, D') and  $\phi_1, \phi_2, \ldots, \phi_m$  are arbitrary real-valued functions, then

$$\exp\left\{-\frac{cx}{a}\right\}\sum_{i=1}^{m}x^{i-1}\phi_i(bx-ay)$$

is a solution of the equation F(D, D')u = 0.

#### Theorem 4

If  $(bD'+c)^m$   $(m \le n)$  is a factor of F(D,D') and  $\phi_1, \phi_2, \ldots, \phi_m$  are real-valued single variable functions, then

$$\exp\left\{-\frac{cy}{b}\right\}\sum_{i=1}^{m}x^{i-1}\phi_i(bx)$$

is a solution of the equation F(D, D')u = 0.

NOTE: *n* is the order of the PDE.

### Reducible Equations: Examples

# Example

General solution of

$$u_{xx} - u_{yy} = 0$$

is given by

$$u = \phi_1(x + y) + \phi_2(x - y),$$

 $\phi_1$  and  $\phi_2$  are arbitrary real-valued single functions.

- By Theorem 1,  $D^2 D^2 = (D D^2)(D + D^2)$  and  $a_1 = 1, b_1 = -1, a_2 = 1, b_2 = 1$  and  $c_1 = 0 = c_2$ .
- Hence the solution.

# Reducible Equations: Examples

# Example

General solution of

$$\frac{\partial^4 u}{\partial x^4} + \frac{\partial^4 u}{\partial y^4} = 2 \frac{\partial^4 u}{\partial x^2 \partial y^2}$$

is given by

$$u = x\phi_1(x - y) + \phi_2(x - y) + x\psi_1(x + y) + \psi_2(x + y).$$

- We have  $D^4 + D^{'4} 2D^2D^{'2} = (D^2 D^{'2})^2 = (D + D')^2(D D')^2$ .
- By using Theorem 3, m=2. Also, n=2 for both expressions. For  $(D+D')^2$  part, a=1,b=1 whereas for the  $(D-D')^2$  part, a=1,b=-1.
- Hence the solution.

# Classification

Consider

$$Au_{xx} + Bu_{xy} + Cu_{yy} + Du_x + Eu_y + Fu + G = 0.$$
 (8)

• At a point (x, y), equation (8) is said to be

► Hyperbolic if 
$$B^2(x,y) - 4A(x,y)C(x,y) > 0$$

► Parabolic if  $B^2(x,y) - 4A(x,y)C(x,y) = 0$ 

► Elliptic if  $B^2(x,y) - 4A(x,y)C(x,y) < 0$ 

- Each category relates to specific problems such as
  - 1 Wave Equation:  $\mathbf{u}_{tt} \mathbf{c}^2 \mathbf{u}_{xx} = \mathbf{0}$ . (Hyperbolic)
  - 2 Laplace's Equation:  $\mathbf{u}_{xx} + \mathbf{u}_{yy} = \mathbf{0}$ . (Elliptic)
  - 3 Heat (or Diffusion) Equation:  $\mathbf{u_t} = \alpha \mathbf{u_{xx}}$ . (Parabolic)

### Methods and Techniques for Solving PDEs

- Change of coordinates: A PDE can be converted to ODEs or to an easier PDE by changing the coordinates of the problem.
- Separation of variables: A PDE in n independent variables is reduced to n ODEs.
- Integral transforms: A PDE in n independent variables is reduced to a PDE in (n-1) independent variables. Hence, a PDE in two variables gets reduced to an ODE.
- Numerical Methods

Our immediate focus will be on a method in which we will use transformation of the independent variables x and y to another set, say  $\xi$  and  $\beta$ .

The aim is to transform the PDE to an easier one so that the solution can be obtained by simple integration only.