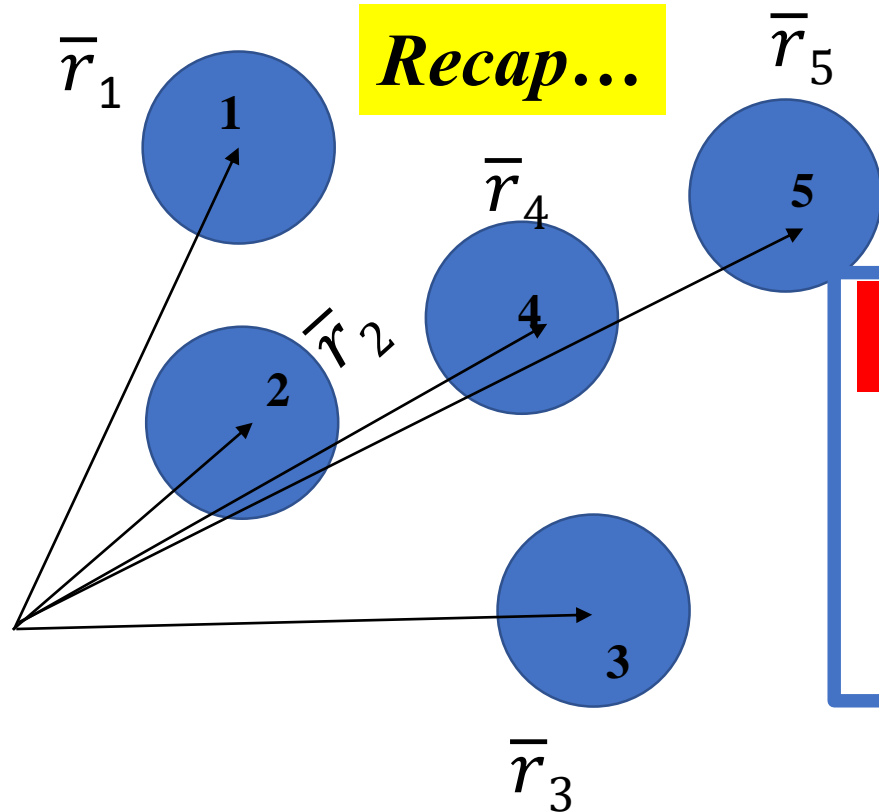


Molecular Dynamics

Numerical Integration and Position/Velocity update

P. SATPATI, BSBE

Recap...



MD cycle (**Four Steps**)

1

$$\begin{aligned} &\{\vec{r}_i\}(0) \quad \{\vec{r}_i\}(dt) \\ &\{\vec{v}_i\}(0) \quad \{\vec{v}_i\}(dt) \\ &i \in [1, N] \end{aligned}$$

2

$$\begin{aligned} &U_{ij}(r_{ij}) \\ &U_{total} = \sum_{i > j} U_{ij}(r_{ij}) \end{aligned}$$

3

$$\begin{aligned} &\vec{F}_{j \rightarrow i} = - \frac{\partial U_{ij}}{\partial r_{ij}} \vec{r} \\ &\vec{F}_i = \sum_{i \neq j} \vec{F}_{j \rightarrow i} \end{aligned}$$

4

Newtons Law

$$a_i = \frac{\vec{F}_i}{m_i}$$

Numerical integration
Time Step = dt

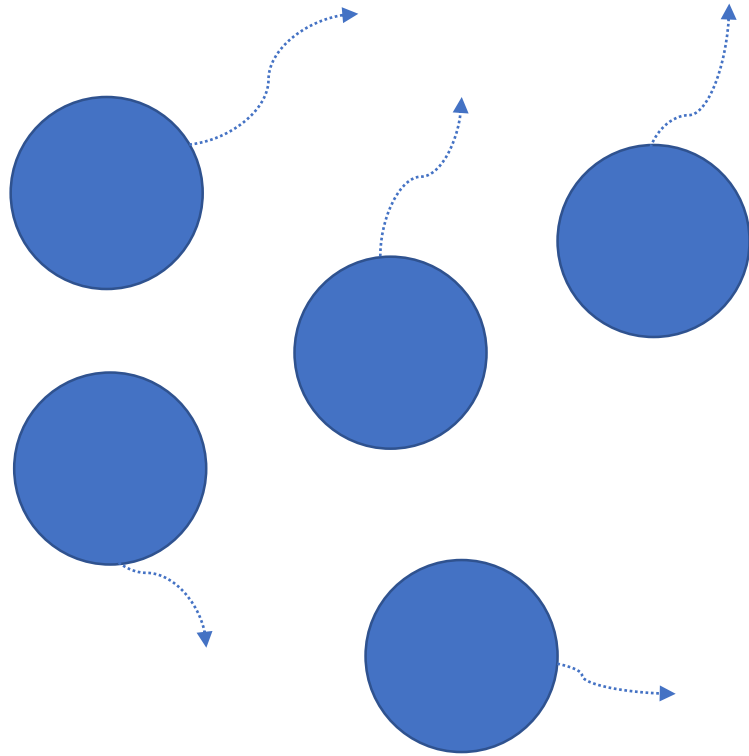
acceleration

Mass of "i" particle

Recap...

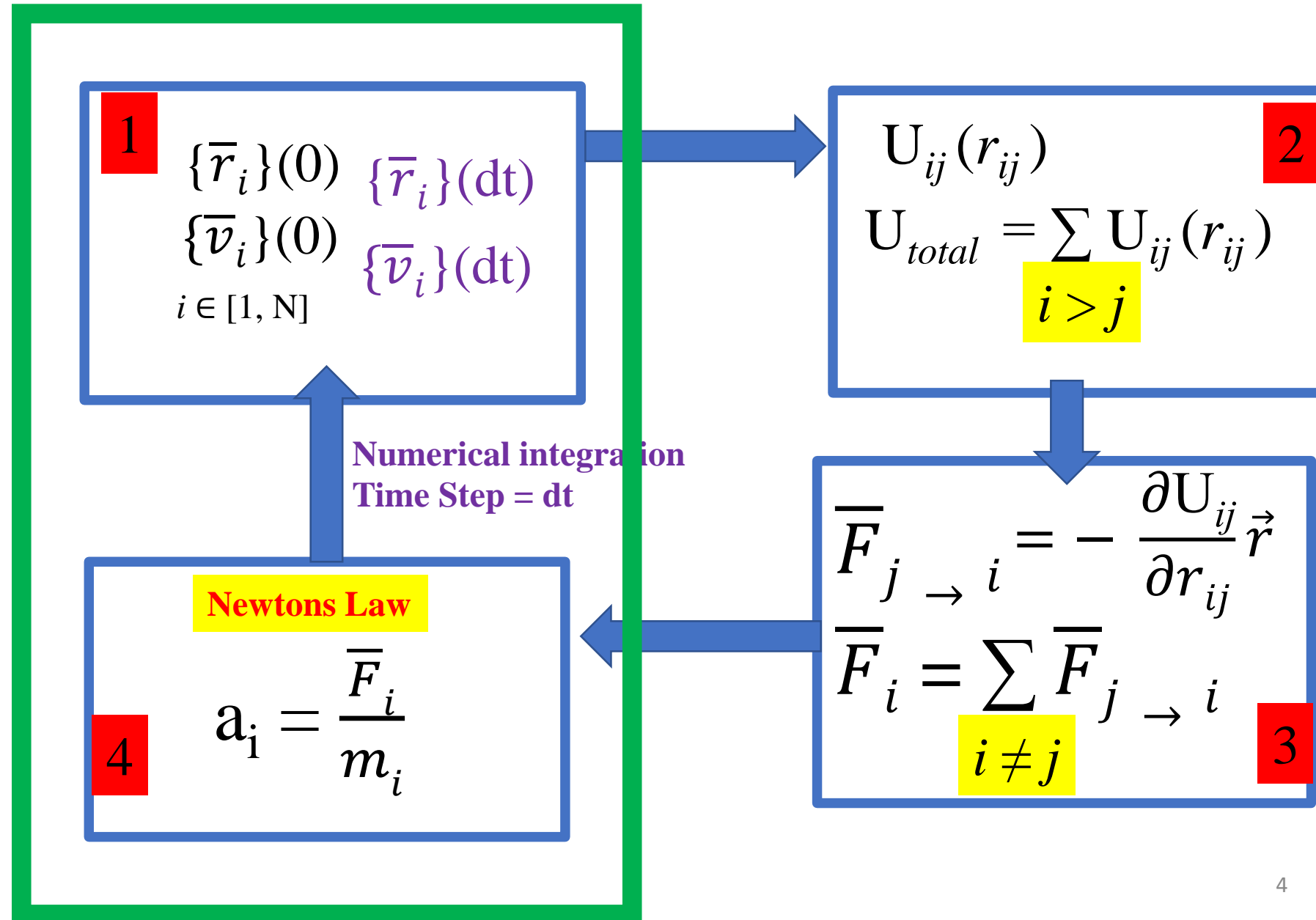
MD cycle (**Four Steps**)

$0 \rightarrow dt \rightarrow 2 dt \rightarrow 3dt \dots$



Outcome = Trajectory

We will discuss the Green box



Newton's Law

$$F_i = m_i a_i = m_i \frac{dv_i}{dt} = \frac{d(m_i v_i)}{dt} = \frac{d\mathbf{p}_i}{dt} \dots (1)$$

F = Force, m = Mass, a = Acceleration
v = velocity, t = Time, P = mv = momentum
i = level of the particle

$$F_i = - \frac{dU}{dq_i} \dots (2)$$

U = Energy, q = position of the particle

Equating above two equations:

$$\frac{d\mathbf{p}_i}{dt} = - \frac{dU}{dq_i}$$

Kinetic Energy

$$KE_i = \frac{1}{2} m_i v_i^2 = \frac{1}{2} \frac{m_i^2 v_i^2}{m_i} = \frac{P_i^2}{2 m_i}$$

KE = Kinetic Energy

Differentiating with respect to time

$$\frac{d KE_i}{d P_i} = \frac{2 \cdot P_i}{2 m_i} = \frac{P_i}{m_i} = \frac{m_i v_i}{m_i} = v_i = \frac{dq_i}{dt}$$



$$\frac{d KE_i}{d P_i} = \frac{dq_i}{dt}$$

Hamilton's Equation of motion

$$\frac{dp_i}{dt} = - \frac{dU}{dq_i} \dots (1)$$

$$\frac{dq_i}{dt} = \frac{d KE_i}{d P_i} \dots (2)$$

- No exact solutions of equation (1) and (2)
- SOLVED NUMERICALLY

How ?

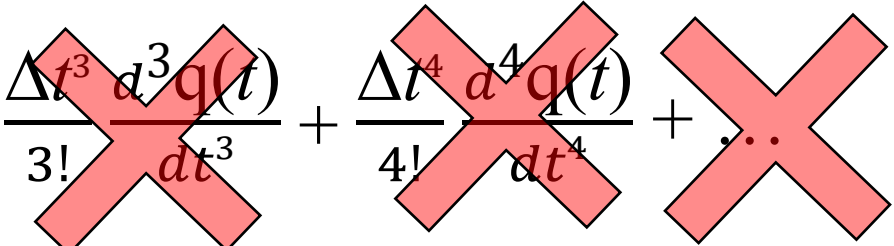
Taylor Series expansion in 'position'

$$q(t+\Delta t) = q(t) + \Delta t \frac{dq(t)}{dt} + \frac{\Delta t^2}{2!} \frac{d^2q(t)}{dt^2} + \frac{\Delta t^3}{3!} \frac{d^3q(t)}{dt^3} + \frac{\Delta t^4}{4!} \frac{d^4q(t)}{dt^4} + \dots$$

Difficulty:

- All the derivatives at q_i are known (Infinite number).
- The function and all its derivatives are continuous and well defined.

Neglecting the higher order terms.

$$q(t+\Delta t) = q(t) + \Delta t \frac{dq(t)}{dt} + \frac{\Delta t^2}{2!} \frac{d^2q(t)}{dt^2} + \frac{\Delta t^3}{3!} \frac{d^3q(t)}{dt^3} + \frac{\Delta t^4}{4!} \frac{d^4q(t)}{dt^4} + \dots$$


$$q(t+\Delta t) = q(t) + \Delta t \frac{dq(t)}{dt} + \frac{\Delta t^2}{2!} \frac{d^2q(t)}{dt^2}$$

$v = \text{velocity}$

$a = \text{Acceleration}$

$$q(t+\Delta t) = q(t) + \Delta t \frac{dq(t)}{dt} + \frac{\Delta t^2}{2!} \frac{d^2q(t)}{dt^2}$$

$$\Rightarrow q(t+\Delta t) = q(t) + \Delta t v(t) + \frac{\Delta t^2}{2!} a(t)$$

$$\Rightarrow q(t+\Delta t) = q(t) + \Delta t v(t) + \frac{\Delta t^2}{2!} \frac{F(t)}{m}$$

Newton's Law:
 $a(t) = \frac{F(t)}{m}$

$$\Rightarrow q(t+\Delta t) = q(t) + \Delta t v(t) + \frac{\Delta t^2}{2 m} \left(- \frac{dU}{dq} \right)$$

$F = - \frac{dU}{dq}$

$$q(t+\Delta t) = q(t) + \Delta t v(t) - \frac{\Delta t^2}{2 m} \frac{dU}{dq} \dots (3)$$

Taylor Series expansion in ‘velocity’

$$v(t+\Delta t) = v(t) + \Delta t \frac{dv(t)}{dt} + \frac{\Delta t^2}{2!} \frac{d^2 v(t)}{dt^2} + \frac{\Delta t^3}{3!} \frac{d^3 v(t)}{dt^3} + \frac{\Delta t^4}{4!} \frac{d^4 v(t)}{dt^4} + \dots$$

If the “ Δt ” is small then I can neglect the higher order terms.

$$v(t+\Delta t) = v(t) + \Delta t \frac{dv(t)}{dt} + \frac{\Delta t^2}{2!} \frac{d^2 v(t)}{dt^2}$$

a = Acceleration

What is this term ?

I need to replace this **RED** term with known !

Lets do a Taylor Series expansion in $\frac{dV(t)}{dt}$,

$$\frac{dV(t+\Delta t)}{dt} = \frac{dV(t)}{dt} + \Delta t \frac{d}{dt} \frac{dV(t)}{dt} + \frac{\Delta t^2}{2!} \frac{d^2}{dt^2} \frac{dV(t)}{dt} + \frac{\Delta t^3}{3!} \frac{d^3}{dt^3} \frac{dV(t)}{dt} + \frac{\Delta t^4}{4!} \frac{d^4}{dt^4} \frac{dV(t)}{dt} + \dots$$

If the “ Δt ” is small then I can neglect the higher order terms.

$$\Rightarrow \frac{dV(t+\Delta t)}{dt} = \frac{dV(t)}{dt} + \Delta t \frac{d^2 V(t)}{dt^2} + \frac{\Delta t^2}{2!} \frac{d^3 V(t)}{dt^3} + \frac{\Delta t^3}{3!} \frac{d^4 V(t)}{dt^4} + \frac{\Delta t^4}{4!} \frac{d^5 V(t)}{dt^5} + \dots$$

$$\Rightarrow \frac{dV(t+\Delta t)}{dt} = \frac{dV(t)}{dt} + \Delta t \frac{d^2 V(t)}{dt^2}$$

Multiple $\frac{\Delta t}{2}$ both sides: $\frac{\Delta t}{2} \frac{dV(t+\Delta t)}{dt} = \frac{\Delta t}{2} \frac{dV(t)}{dt} + \frac{\Delta t}{2} \cdot \Delta t \frac{d^2 V(t)}{dt^2}$

$$\Rightarrow \frac{\Delta t}{2} \frac{dV(t+\Delta t)}{dt} = \frac{\Delta t}{2} \frac{dV(t)}{dt} + \frac{\Delta t^2}{2} \frac{d^2 V(t)}{dt^2}$$

Term needs to be replaced

$$\frac{\Delta t^2}{2} \frac{d^2 v(t)}{dt^2} = \frac{\Delta t}{2} \frac{dv(t+\Delta t)}{dt} - \frac{\Delta t}{2} \frac{dv(t)}{dt}$$

Substituting the above term in “Equation 3”

$$v(t+\Delta t) = v(t) + \Delta t \frac{dv(t)}{dt} + \frac{\Delta t^2}{2!} \frac{d^2 v(t)}{dt^2}$$

$$\Rightarrow v(t+\Delta t) = v(t) + \Delta t \frac{dv(t)}{dt} + \frac{\Delta t}{2} \frac{dv(t+\Delta t)}{dt} - \frac{\Delta t}{2} \frac{dv(t)}{dt}$$

$$\Rightarrow v(t+\Delta t) = v(t) + \frac{\Delta t}{2} \frac{dv(t)}{dt} + \frac{\Delta t}{2} \frac{dv(t+\Delta t)}{dt}$$

$a(t) = \text{Acceleration}$

$a(t+\Delta t) = \text{Acceleration}$

$$\Rightarrow v(t+\Delta t) = v(t) + \frac{\Delta t}{2} a(t) + \frac{\Delta t}{2} a(t + \Delta t)$$

$$\Rightarrow v(t+\Delta t) = v(t) + \frac{\Delta t}{2} [a(t) + a(t + \Delta t)]$$

$$\Rightarrow v(t+\Delta t) = v(t) + \frac{\Delta t}{2} \left[\frac{F(t)}{m} + \frac{F(t+\Delta t)}{m} \right]$$

Newtons Law:
 $a(t) = \frac{F(t)}{m}$

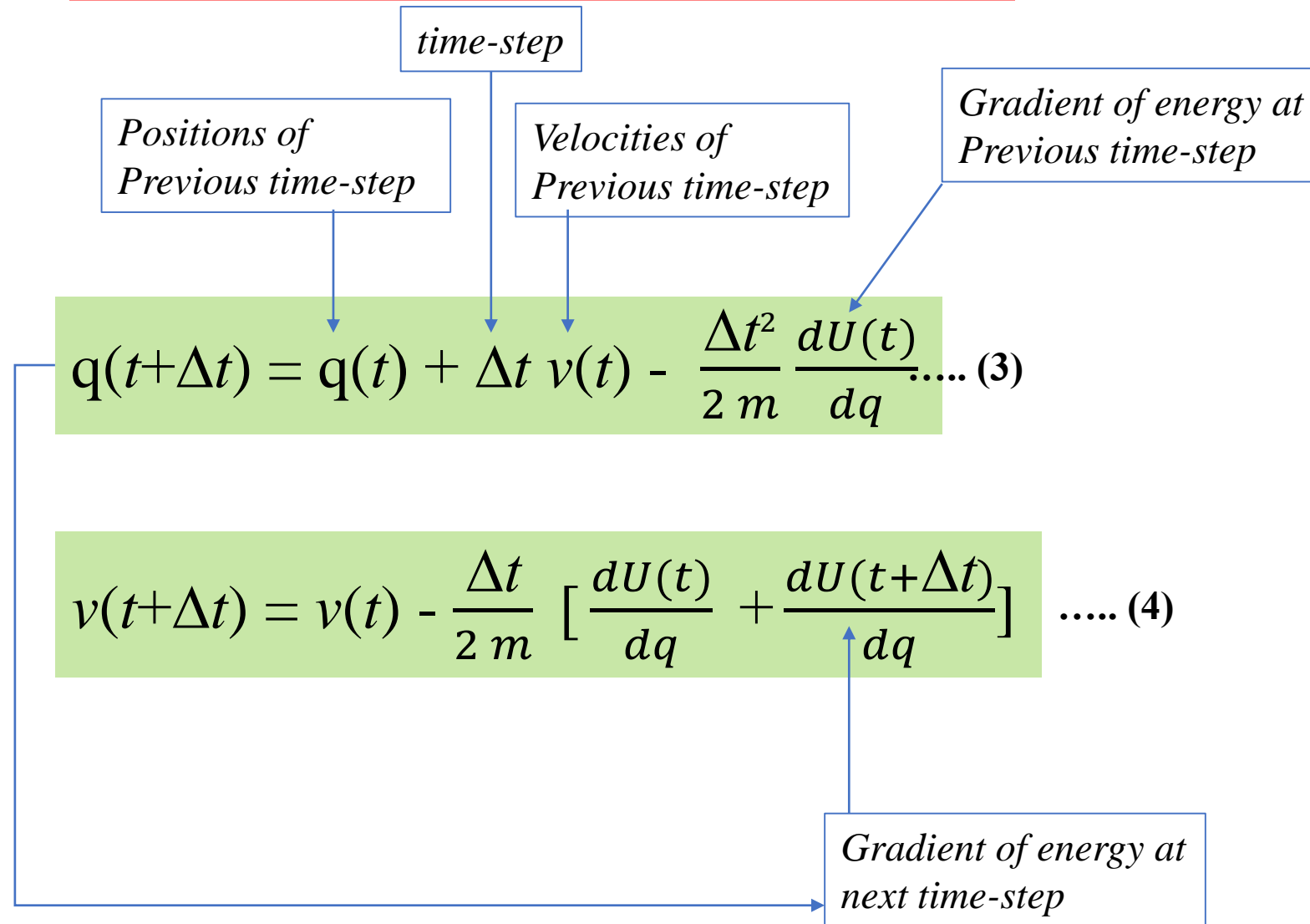
$$\Rightarrow v(t+\Delta t) = v(t) + \frac{\Delta t}{2} \left[\frac{F(t)}{m} + \frac{F(t+\Delta t)}{m} \right]$$

$F = - \frac{dU}{dq}$

$$\Rightarrow v(t+\Delta t) = v(t) + \frac{\Delta t}{2 m} \left[- \frac{dU(t)}{dq} - \frac{dU(t+\Delta t)}{dq} \right]$$

$$\Rightarrow v(t+\Delta t) = v(t) - \frac{\Delta t}{2 m} \left[\frac{dU(t)}{dq} + \frac{dU(t+\Delta t)}{dq} \right] \dots (4)$$

Velocity Verlet algorithm



Velocity Verlet algorithm

$$q(t+\Delta t) = q(t) + \Delta t v(t) - \frac{\Delta t^2}{2m} \frac{dU(t)}{dq} \dots(3)$$

$$v(t+\Delta t) = v(t) - \frac{\Delta t}{2m} \left[\frac{dU(t)}{dq} + \frac{dU(t+\Delta t)}{dq} \right] \dots(4)$$

1. Given initial positions [$q(t)$] and velocities [$v(t)$] at time 't'

2. Calculate $\frac{dU(t)}{dq}$

3. Calculate $q(t+\Delta t)$ from equation 3

4. Calculate $\frac{dU(t+\Delta t)}{dq}$

5. Calculate $v(t+\Delta t)$ from equation 4.

6. Repeat (2 \rightarrow 5)

Molecular Dynamics

Velocity Verlet algorithm

1. Given initial positions [$q(t)$] and velocities [$v(t)$] at time 't'

2. Calculate $\frac{dU(t)}{dq}$

3. Calculate $q(t+\Delta t)$ from equation 3

4. Calculate $\frac{dU(t+\Delta t)}{dq}$

5. Calculate $v(t+\Delta t)$ from equation 4.

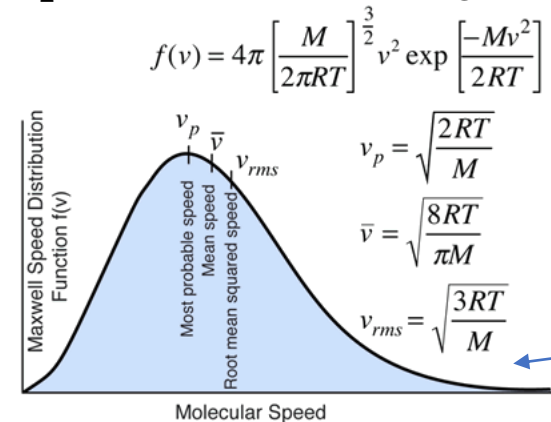
6. Repeat (2 \rightarrow 5)

➤ **Initial coordinates $q(t=0)$:**

PDB, Theoretical Model (e.g, Homology Model).

➤ **Initial velocities $v(t=0)$:**

**Maxwell-Boltzmann distribution at a given temperature
(Require THERMAL EQUILIBRIUM)**



Box of Gas.
Particle mass $\doteq M$
Temperature. $\doteq T$

Molecular Dynamics (MD)

CALCULATION OF Energy Gradient $\frac{dU}{dq}$

➤ Using Classical Force-field → Classical MD

CHARMM Potential Function

$$U(\vec{R}) = \underbrace{\sum_{bonds} k_i^{bond} (r_i - r_0)^2}_{U_{bond}} + \underbrace{\sum_{angles} k_i^{angle} (\theta_i - \theta_0)^2}_{U_{angle}} + \underbrace{\sum_{dihedrals} k_i^{dihe} [1 + \cos(n_i \phi_i + \delta_i)]}_{U_{dihedral}} + \underbrace{\sum_i \sum_{j \neq i} 4\epsilon_{ij} \left[\left(\frac{\sigma_{ij}}{r_{ij}} \right)^{12} - \left(\frac{\sigma_{ij}}{r_{ij}} \right)^6 \right] + \sum_i \sum_{j \neq i} \frac{q_i q_j}{\epsilon r_{ij}}}_{U_{nonbond}}$$

Diagram illustrating the components of the CHARMM Potential Function and their associated data sources:

- PDB file** (geometry) → $\sum_{bonds} k_i^{bond} (r_i - r_0)^2$
- Topology** (PSF file) → $\sum_{angles} k_i^{angle} (\theta_i - \theta_0)^2$
- Parameters** (Parameter file) → $\sum_{dihedrals} k_i^{dihe} [1 + \cos(n_i \phi_i + \delta_i)]$
- Parameters** (Parameter file) → $\sum_i \sum_{j \neq i} 4\epsilon_{ij} \left[\left(\frac{\sigma_{ij}}{r_{ij}} \right)^{12} - \left(\frac{\sigma_{ij}}{r_{ij}} \right)^6 \right] + \sum_i \sum_{j \neq i} \frac{q_i q_j}{\epsilon r_{ij}}$

➤ Using Quantum Mechanics “Schrodinger equation” → Abinitio MD

➤ Combining Quantum Mechanics & Classical Force-field → QM/MM MD

What Time – Step “ Δt ” one should use ?

- ❖ No hard and fast rule.
- ❖ “ Δt ” too small \rightarrow Limited Sampling
- ❖ “ Δt ” too Large \rightarrow error in Velocity-verlet algorithm (Taylor series truncation)

➤ Appropriate time-step “ Δt ” \rightarrow Efficient Sampling + Collision occur smoothly

➤ Liquid Simulations: “ Δt ” should be small compared to <collision time>

➤ Biomolecules: Δt should be (1/10th) of the fastest motion

e.g, C-H bond vibrate with 10 fs repeat period
Thus, use $\Delta t = 1$ fs

High frequency motions are usually of relatively less interest and have a minimal effect on the overall behavior of the system

(Solution: Constrain covalent bonds involving hydrogens)

$\Delta t = 2$ fs (**SHAKE algorithm, LINCS algorithm**)

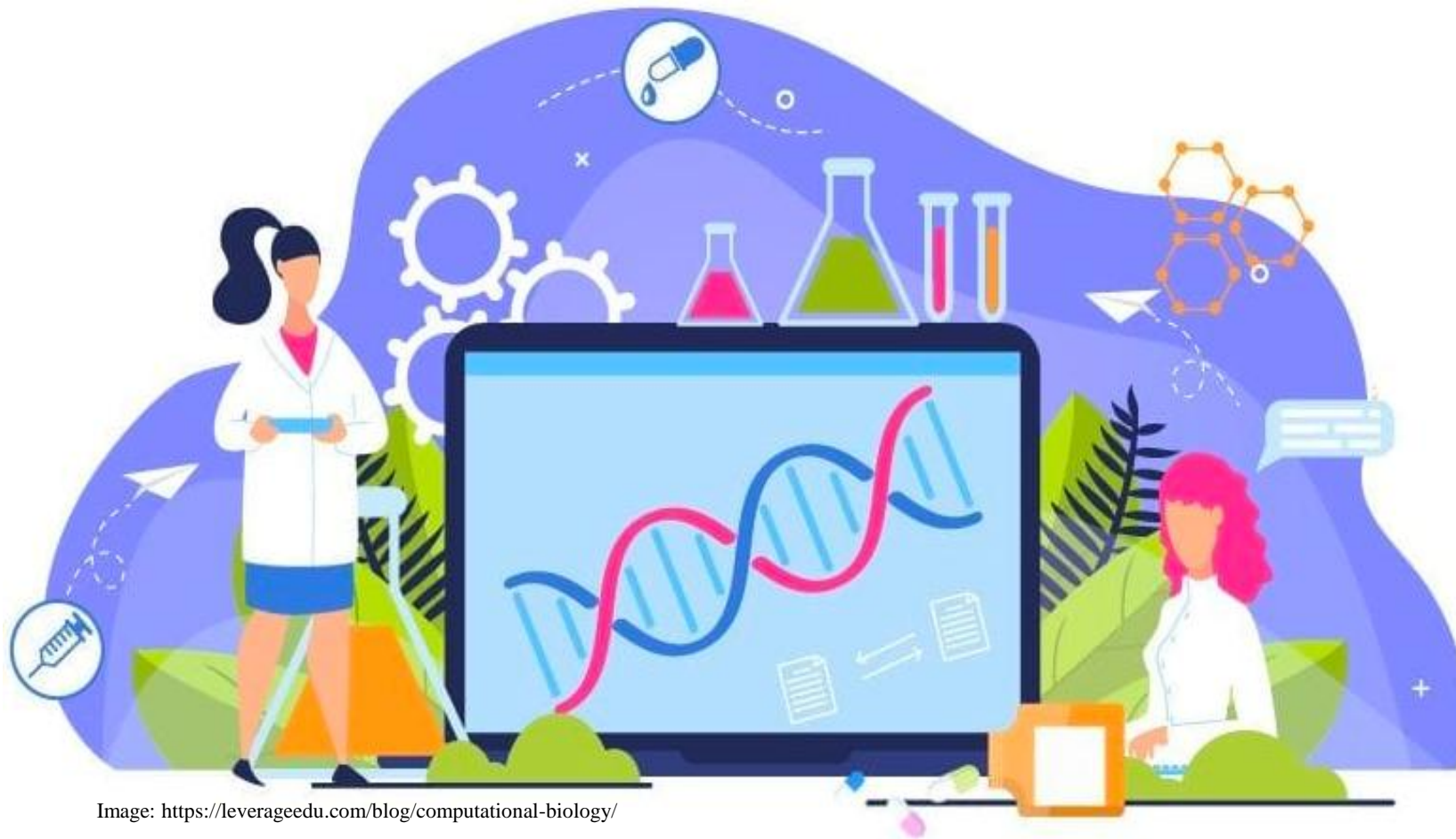


Image: <https://leverageedu.com/blog/computational-biology/>

Next :Boundary Conditions, Cut-off, Temperature and Pressure control