

Méthode de séparation de sources

Modèles et algorithmes

Applications en Astrophysique

Statistical approaches - take II
from linear to non-linear models

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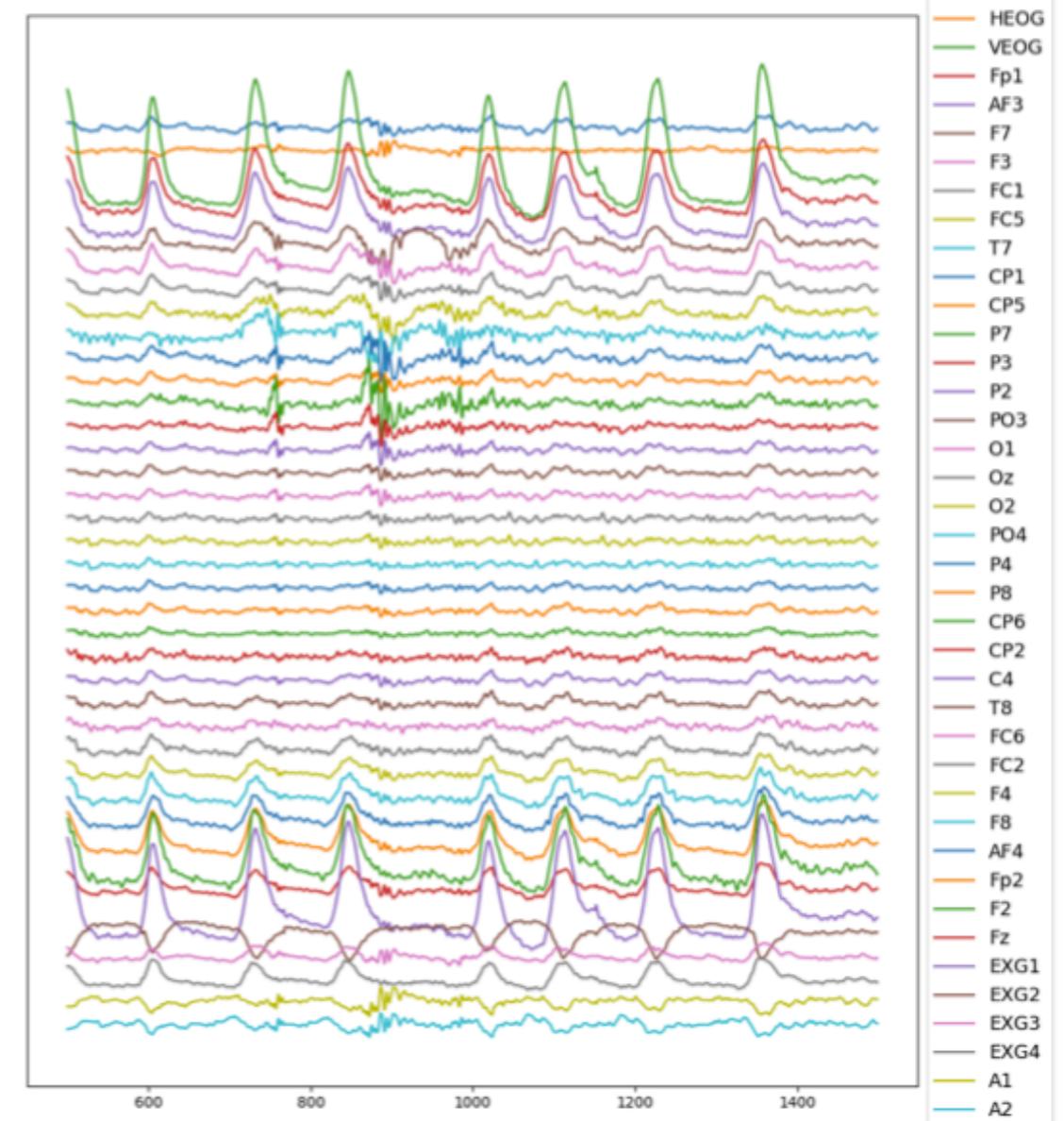
From linear to non-linear mixture models

General principles

Context

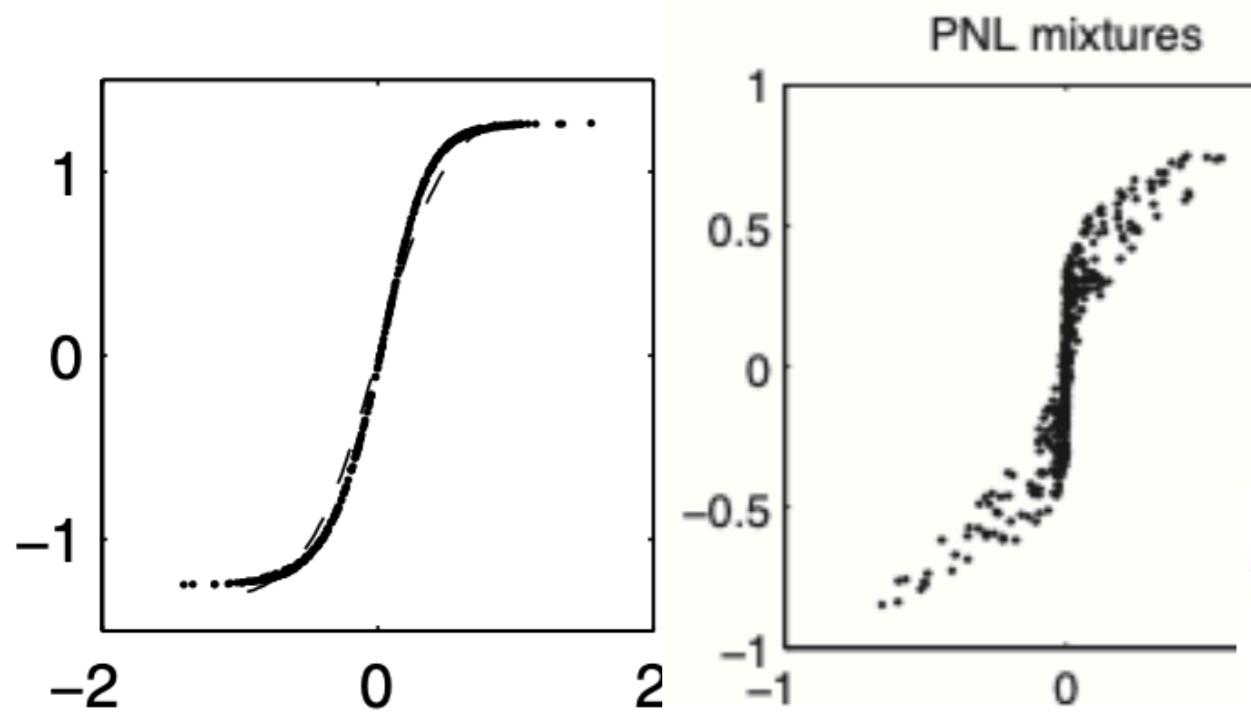


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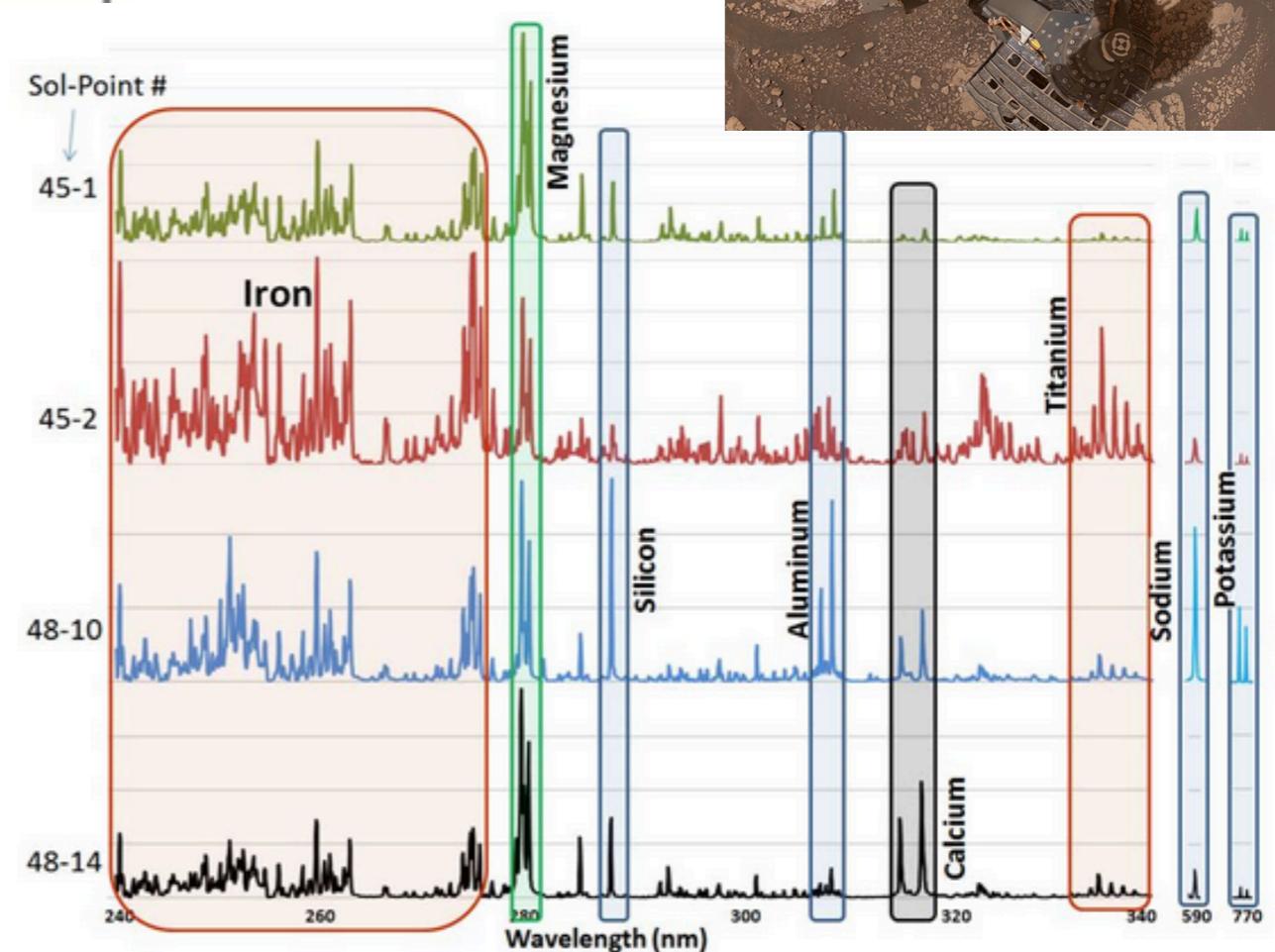
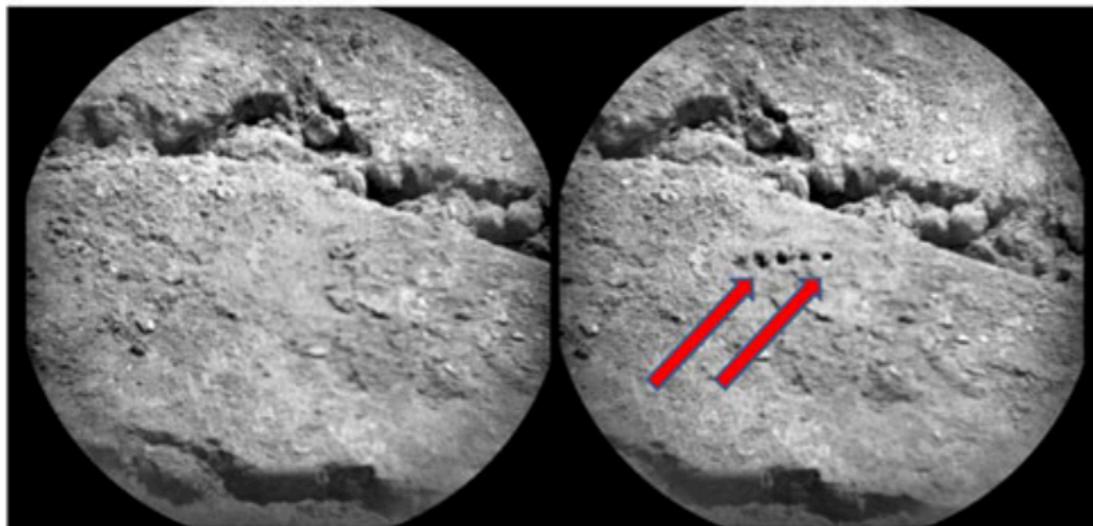


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Context

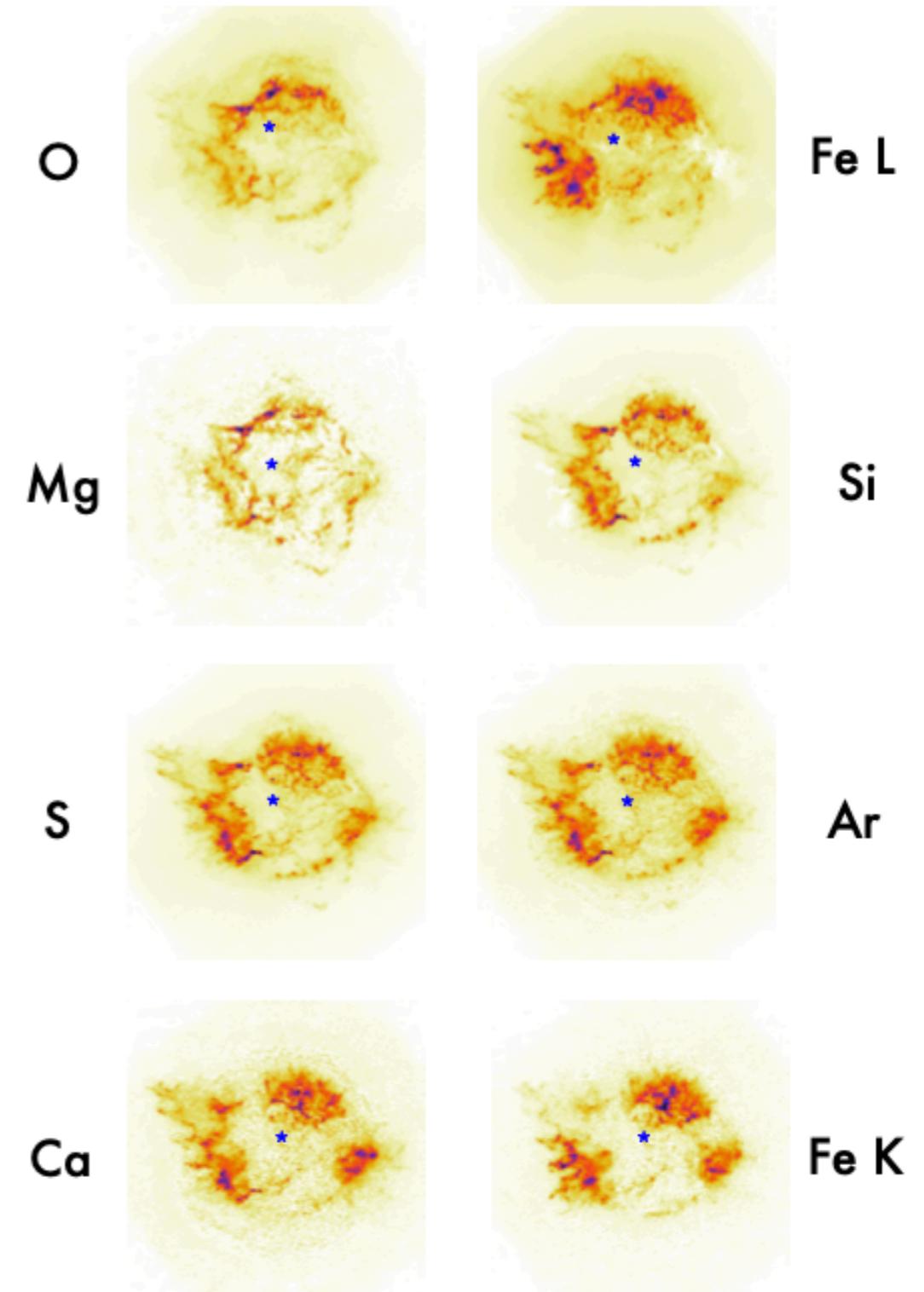
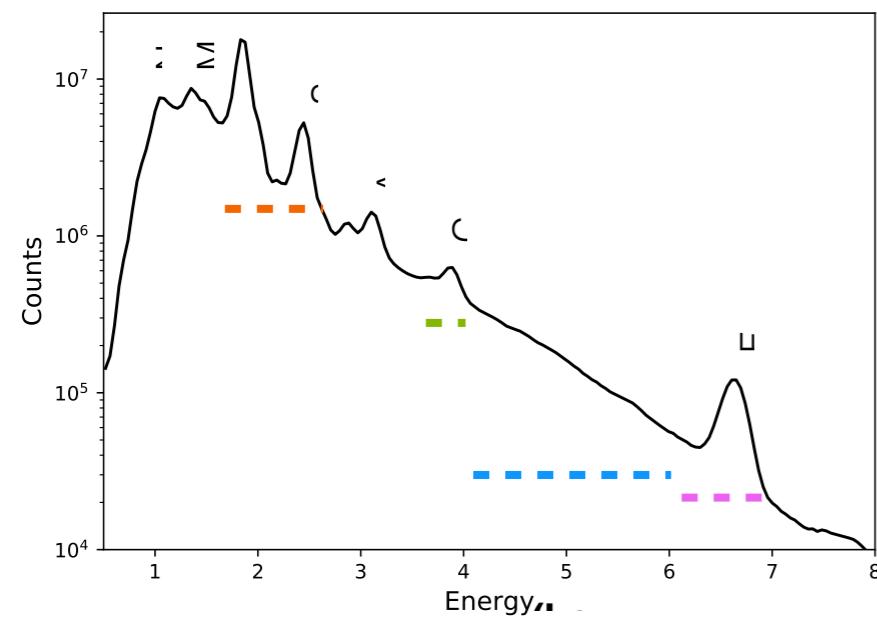
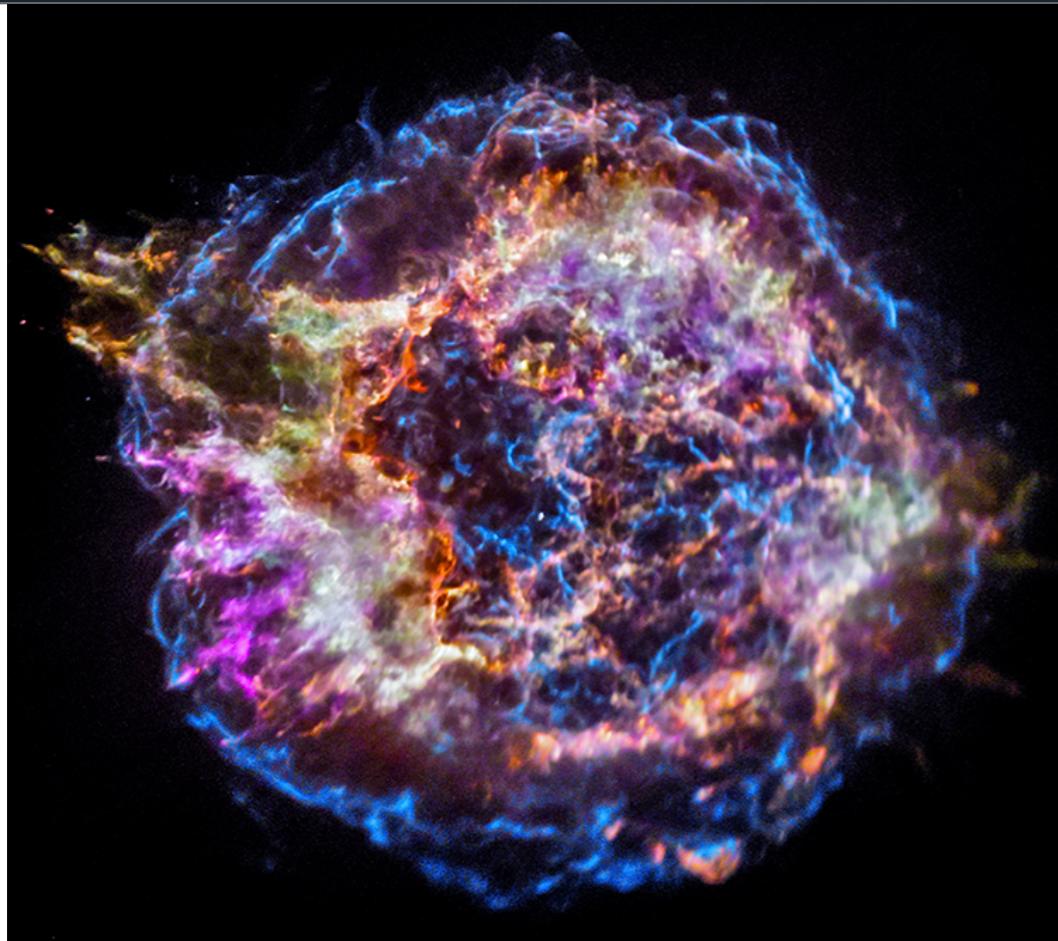


Non-linear sensor response



LIBS data from the mars rover curiosity

Context



Special types of non-stationary mixture models

Post non-linear mixture models

$$\mathbf{X} = f(\mathbf{AS}) + \mathbf{N}$$

*Composition of a non-linearity with a linear mixture model
e.g. non-linear sensor response*

General mixture models

$$\mathbf{X} = f(s_1, \dots, s_n) + \mathbf{N}$$

*General non-linear mixture model
... but f is assumed to be invertible*

Post-non linear mixture models

Post non-linear mixture model

Post non-linear mixture models

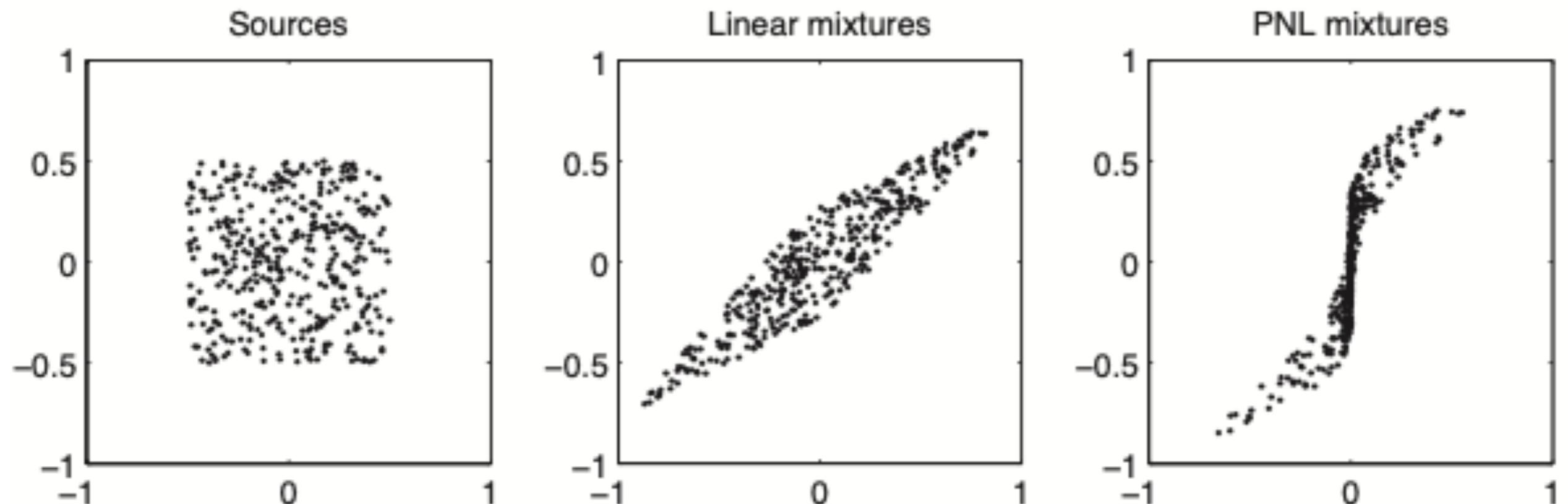
$$x_i^t = f_i \left(\sum_j a_{ij} s_j^t \right) + n_i^t$$

f is invertible and applies to each entry independently

$$\mathbf{X} = (f \circ \mathbf{A})(\mathbf{S}) + \mathbf{N}$$

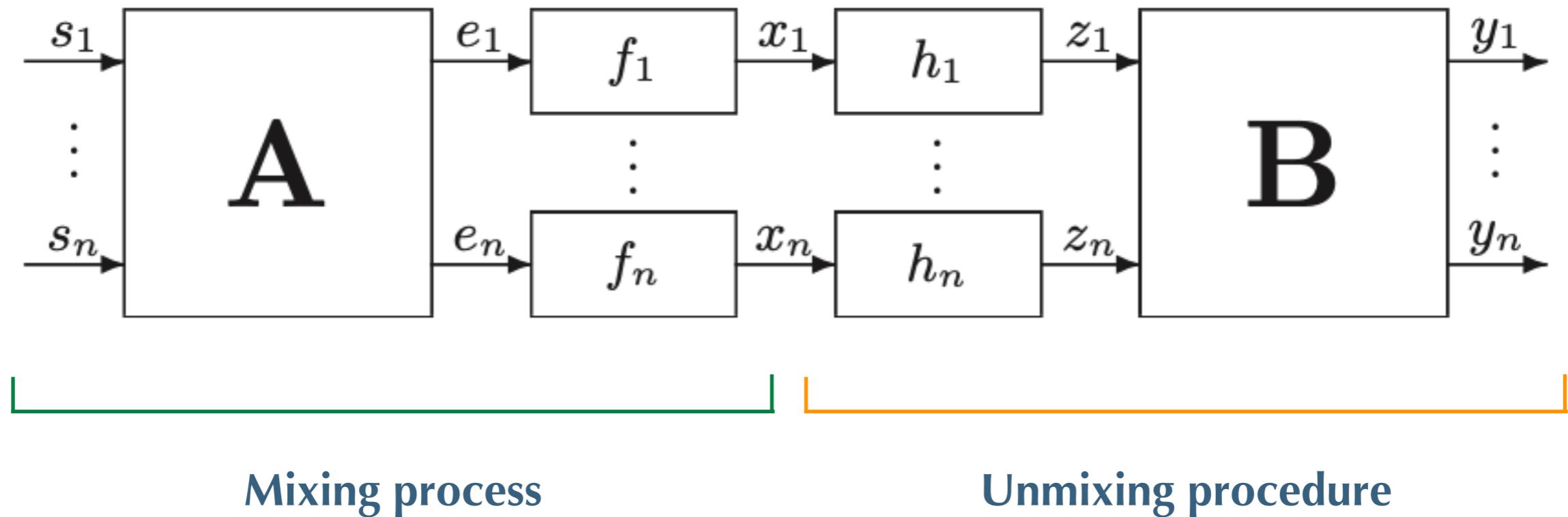
obtained as the composition of a linear mixture with a non-linearity

Example



Courtesy of Jutten et al. 2010

Theoretical results



- **h** corrects for the PNL
- **B** is an unmixing matrix as in standard ICA

Can we identify an unmixing structure (h,B**) based on independence ?**

Theoretical results

An equivalent of the Darmois theorem for PNL (Achard and Jutten 2005):

i. **A is invertible and “sufficiently mixing”**

i.e. $\forall i, j \text{ s.t. } a_{ij} \neq 0,$

$\exists k \neq j \text{ such that } a_{ik} \neq 0$

Or

$\exists l \neq i \text{ such that } a_{lj} \neq 0$

ii. **h is composed of differentiable and invertible functions**

iii. **S has i.i.d. entries, and at most one is Gaussian**

iv. **The pdf of the sources are differentiable and their derivatives are continuous**

Algorithms for PNL mixture models

$\mathbf{Y} = (B \circ h)(\mathbf{X})$ has independent sources iif

$f \circ h$ are linear and $\mathbf{BA} = \boldsymbol{\Pi}\boldsymbol{\Delta}$

Sources from PNL are identifiable using standard ICA !

General non-linear mixture models

General mixture models

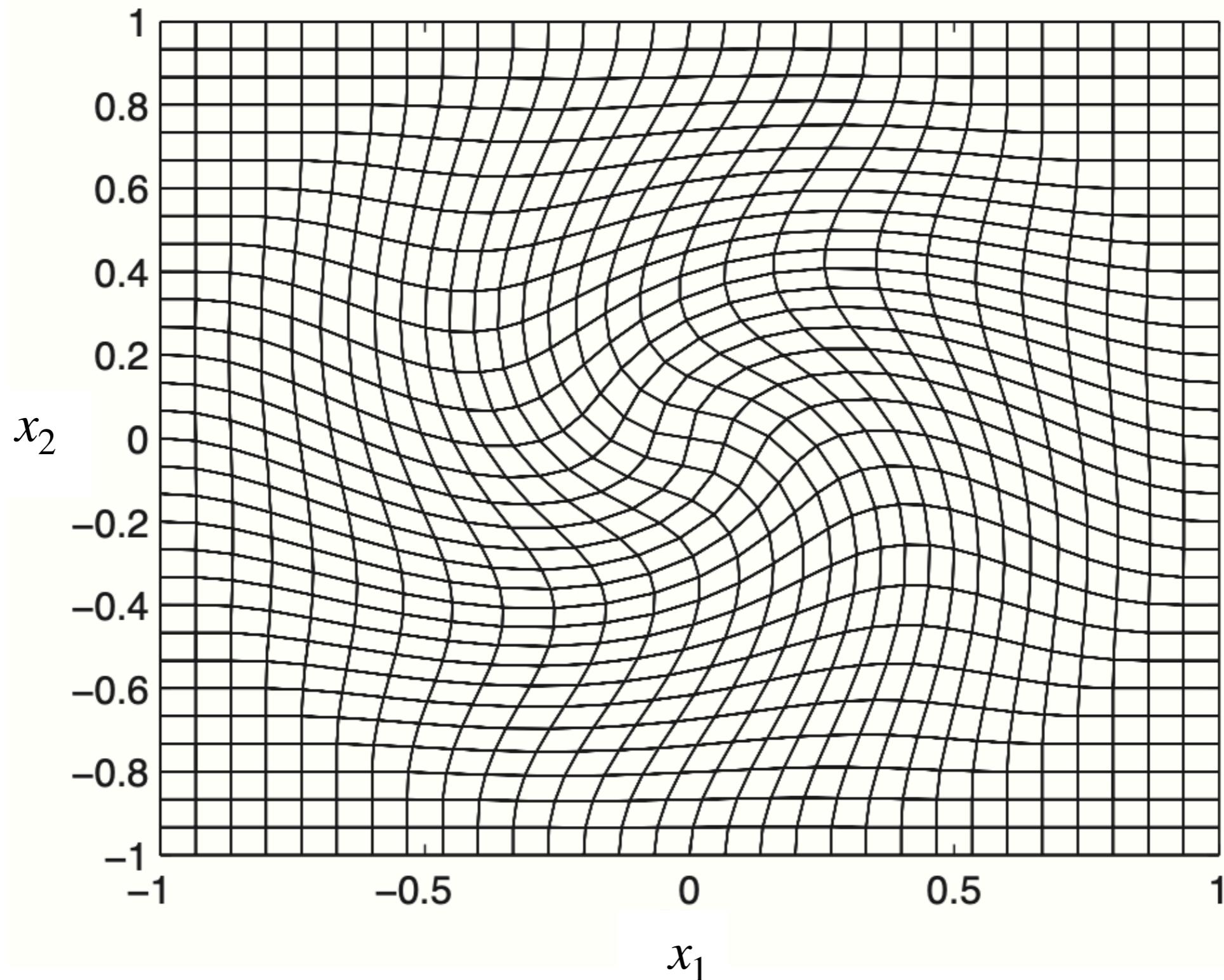
$$\mathbf{X} = f(s_1, \dots, s_n) + \mathbf{N}$$

General non-linear mixture model

$$\mathbf{X}^t = f(s_1^t, \dots, s_n^t) + \mathbf{N}^t$$

General instantaneous non-linear mixture model

Context



Sketch of a smooth non-linear mixture

Are there extensions of the Darmois-Linnik theorem for general NL mixtures?

Take I - Kagan, Linnik, Rao (1973!) and later by koivunen et al. (2002)

Identifiability limited to non-linearities admitting some mapping \mathcal{F} so that:

$$f(s_1 + s_2) = \mathcal{F}[f(s_1), f(s_2)]$$

$$s_1 + s_2 = f^{-1}(\mathcal{F}[f(s_1), f(s_2)])$$

This allows to go back to the standard case

Take II - Hyvarinen et al. (2020)

More general result ... see later in this course

ICA for NL mixtures

A quick recall on InfoMAX - minimises the mutual information (MI) of the sources:

$$\min_{\mathbf{B}} \mathcal{D} \left(f_{\mathbf{S}}, \prod_i f_{s_i} \right) \quad \mathbf{S} = \mathbf{B}\mathbf{X}$$

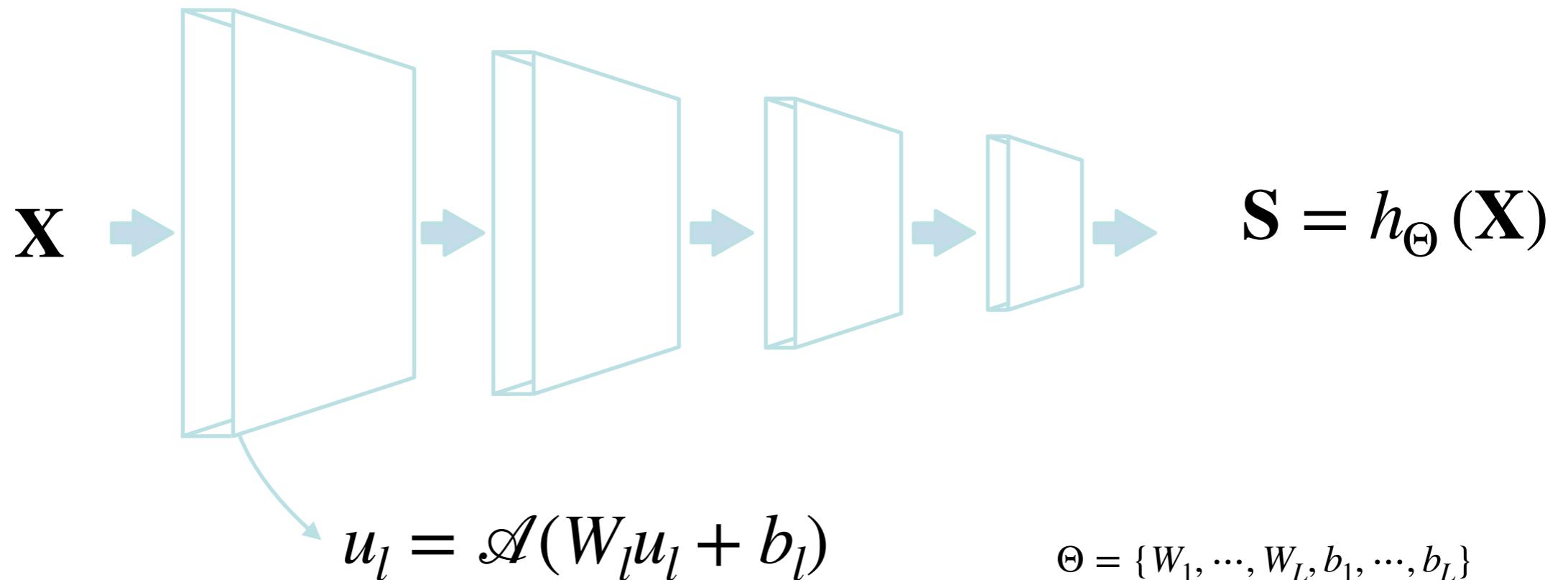
Extension of the InfoMax algorithm to NL mixtures (Almeida 2004)

- i. The unmixing process is a non-linear mapping \mathbf{h}
- ii. Estimate \mathbf{h} so that $\mathbf{h}(\mathbf{X})$ minimises the MI

$$\min_{\mathbf{h}} \mathcal{D} \left(f_{\mathbf{S}}, \prod_i f_{s_i} \right) \quad \mathbf{S} = h(\mathbf{X})$$

Extension of the InfoMax algorithm to NL mixtures (*MISEP - Almeida 2004*)

Modelling of the unmixing mapping with a multilayer perceptron (MLP)

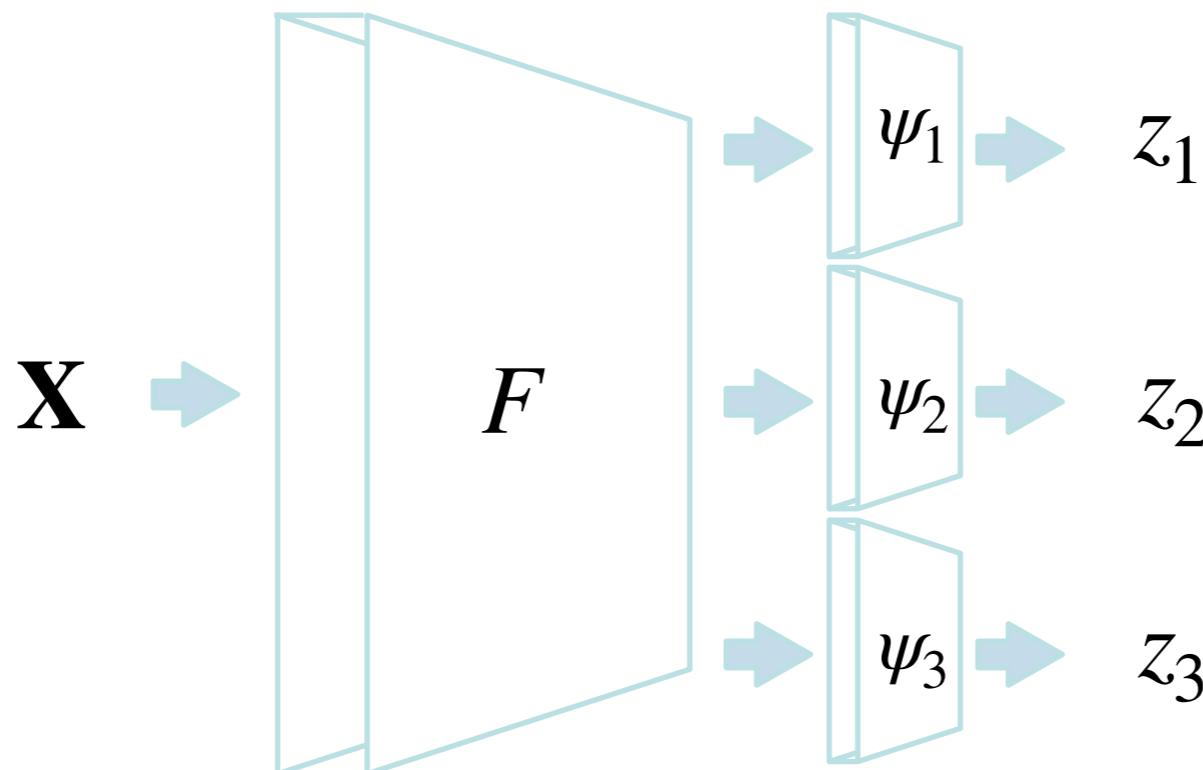


$$\min_{\Theta} \mathcal{D} \left(f_{\mathbf{S}}, \prod_i f_{S_i} \right) \quad \mathbf{S} = h_{\Theta}(\mathbf{X})$$

MISEP algorithm

- Pre-DL methods, does make use of standard ML coding frameworks

- A simple 2-layers network

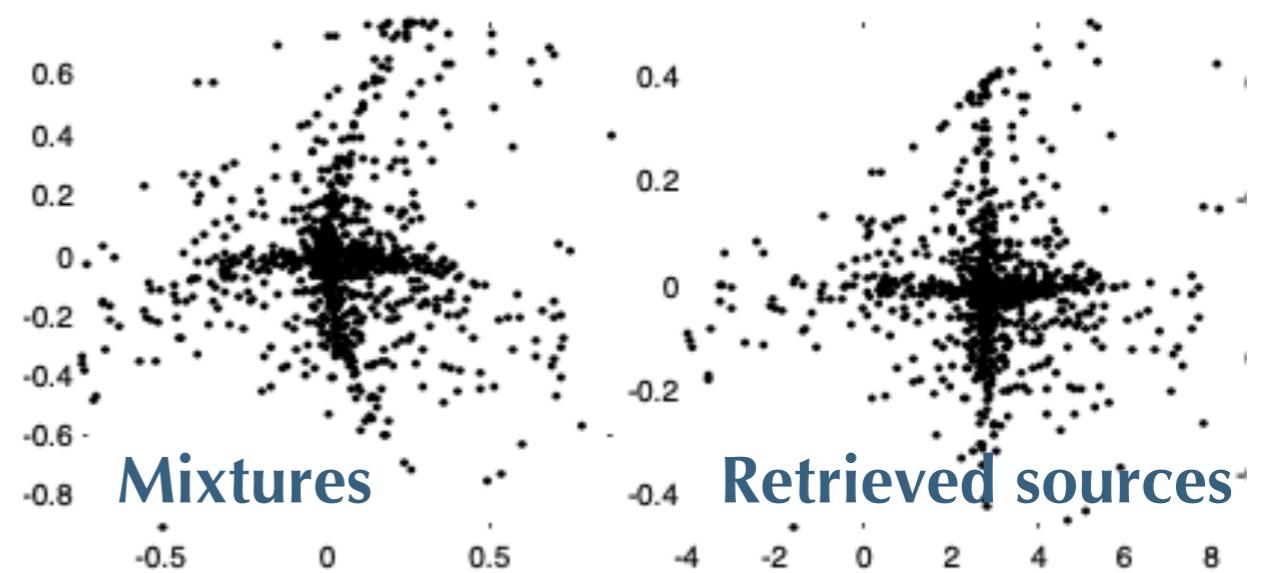


- F is a linear mapping or MLP (trained)

- ψ is a non-linear mapping (trained)

- e.g. $\arctan + \text{linear units}$

- Loss: MI of the outputs



Models for NLMM



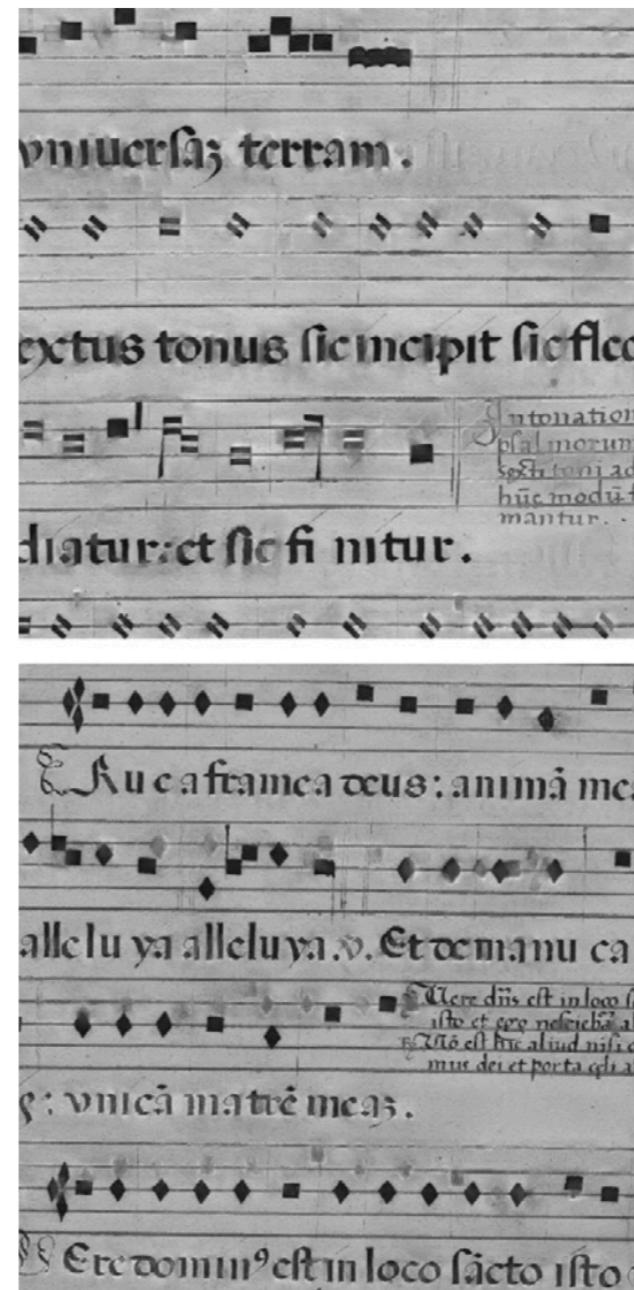
Partiture
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Measurements

Results on show-through data

Retrieved sources



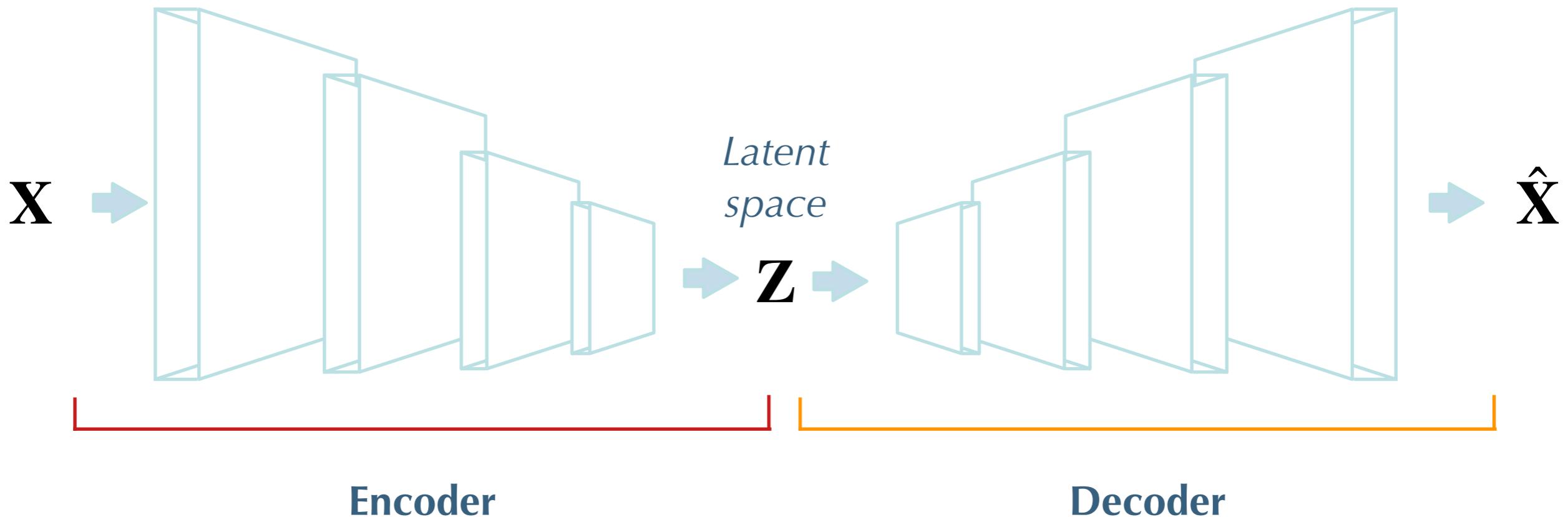
Encoder/decoder-based approaches

Beyond NL-ICA, from 2004 to 2020:

- i) **Applicability: improving the modelling of the sources/non-linearity**
- ii) **Reconstructing more than an unmixing process ?**
- iii) **Identifiability ? make use of modern-day statistical models**

It's time to switch to encoder-decoder (autoencoder) models

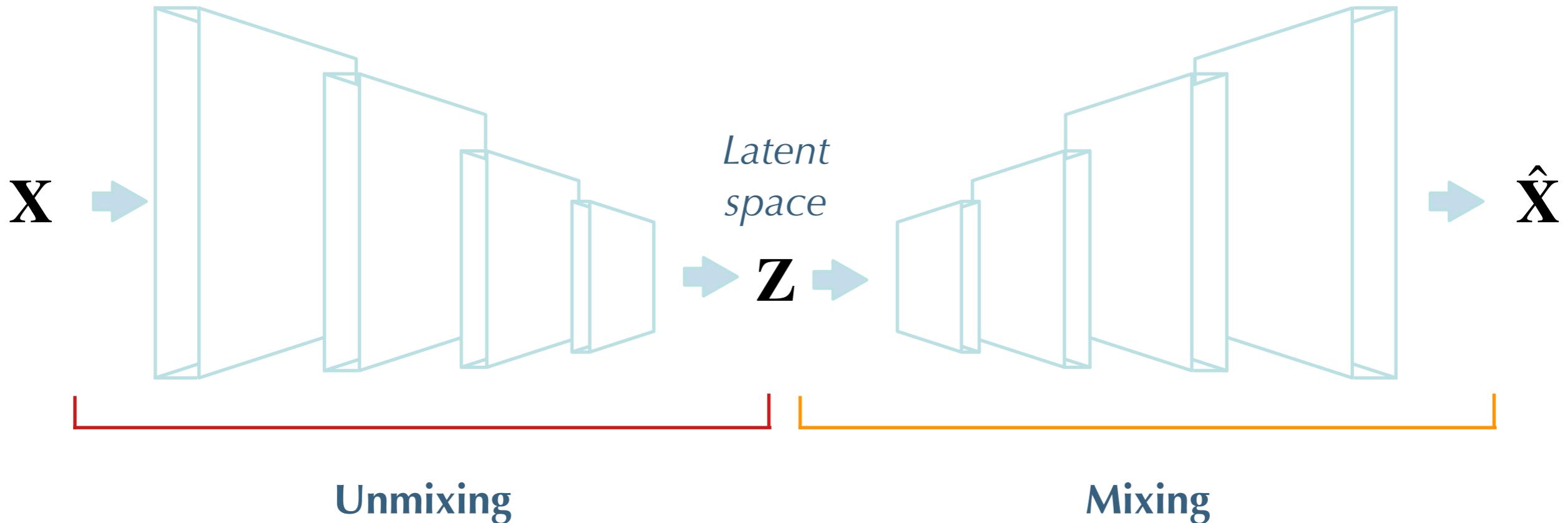
Encoder/decoder-based approaches



The Autoencoder (AE) is a very popular model for:

- (unsupervised) representation learning
- unsupervised/self-supervised learning
- manifold learning
- Building a non-linear low-dimensional approximation
- Generative models
- ...etc

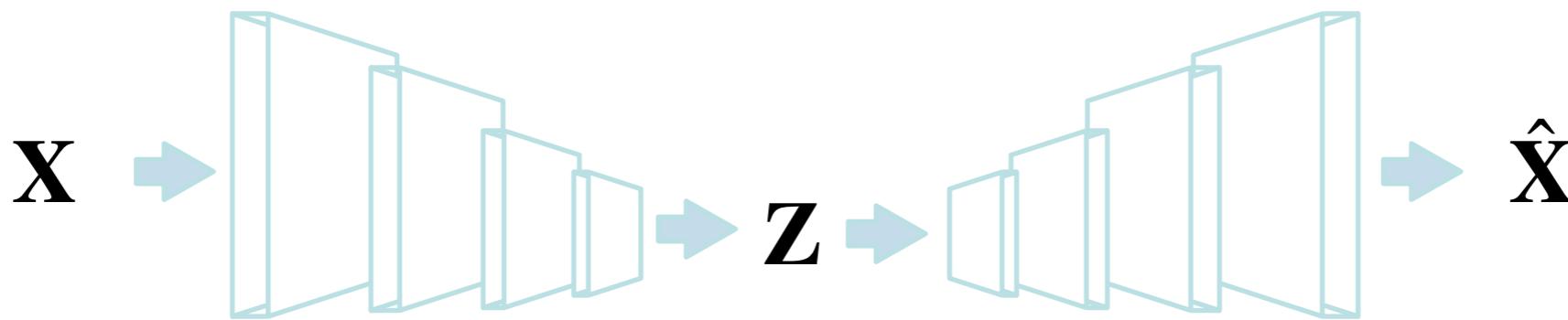
Towards non-linear ICA



Making use of AE for non-linear ICA is virtually simple:

Learning an unmixing/mixing model that enforces independence in the latent space

But how to do it efficiently ?



Back to the mutual information:

For simplicity, let's pick two sources:

$$I(z_1, z_2) = \iint p(z_1, z_2) \log \frac{p(z_1, z_2)}{p(z_1)p(z_2)} dz_1 dz_2$$

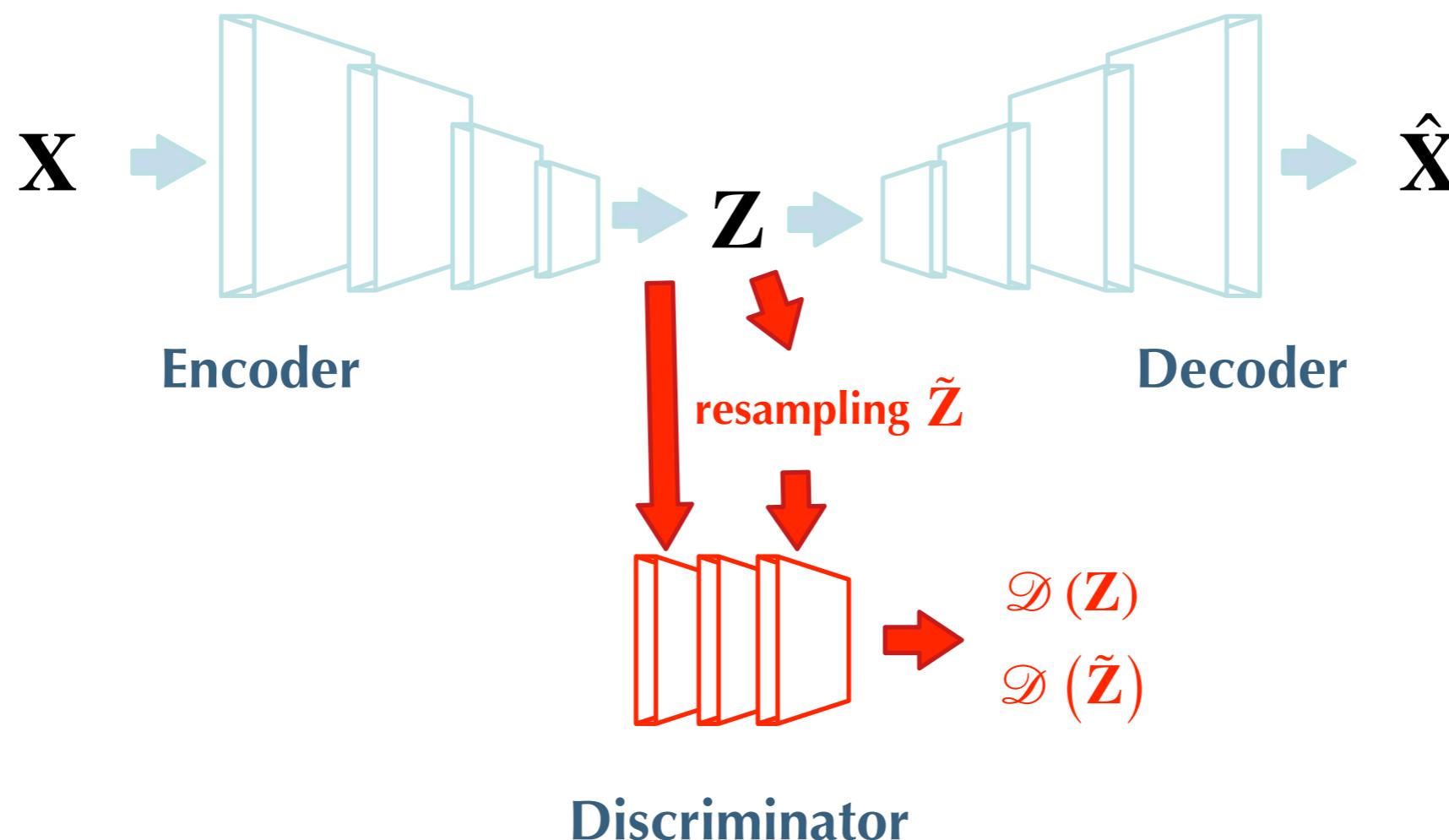
When p is unknown, how to compute/minimise the mutual information ?

Solution: use a proxy to favour independent latent space variables thanks to adversarial training

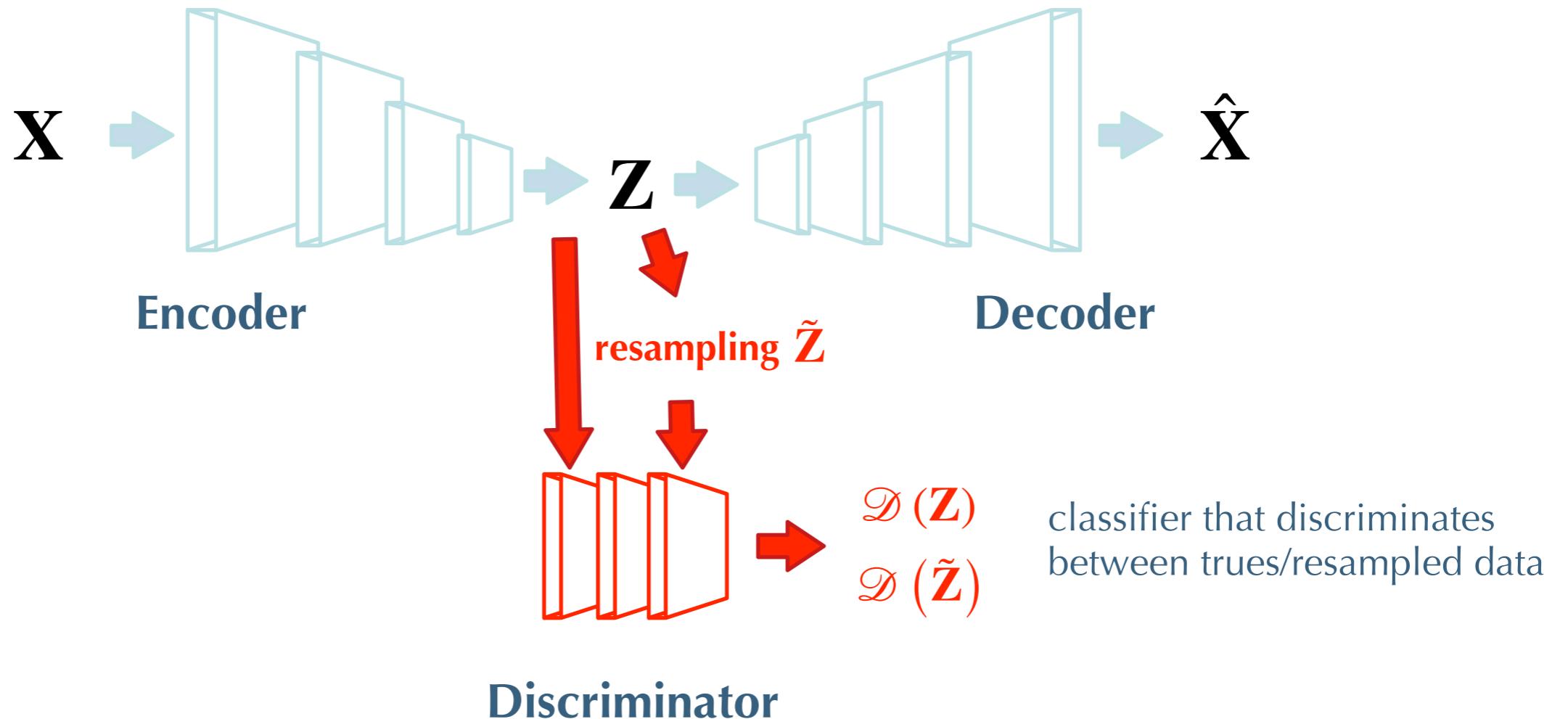
Adversarial regularisation for NL ICA

Gist of the approach:

- i) Add a regularisation to the latent space variable based on a generator/discriminator model
- ii) Generative Adversarial Network (*GAN - Goodfellow 2014*) allows to model and discriminate dependent/independent sources



Adversarial regularisation for NL ICA



Updated loss:

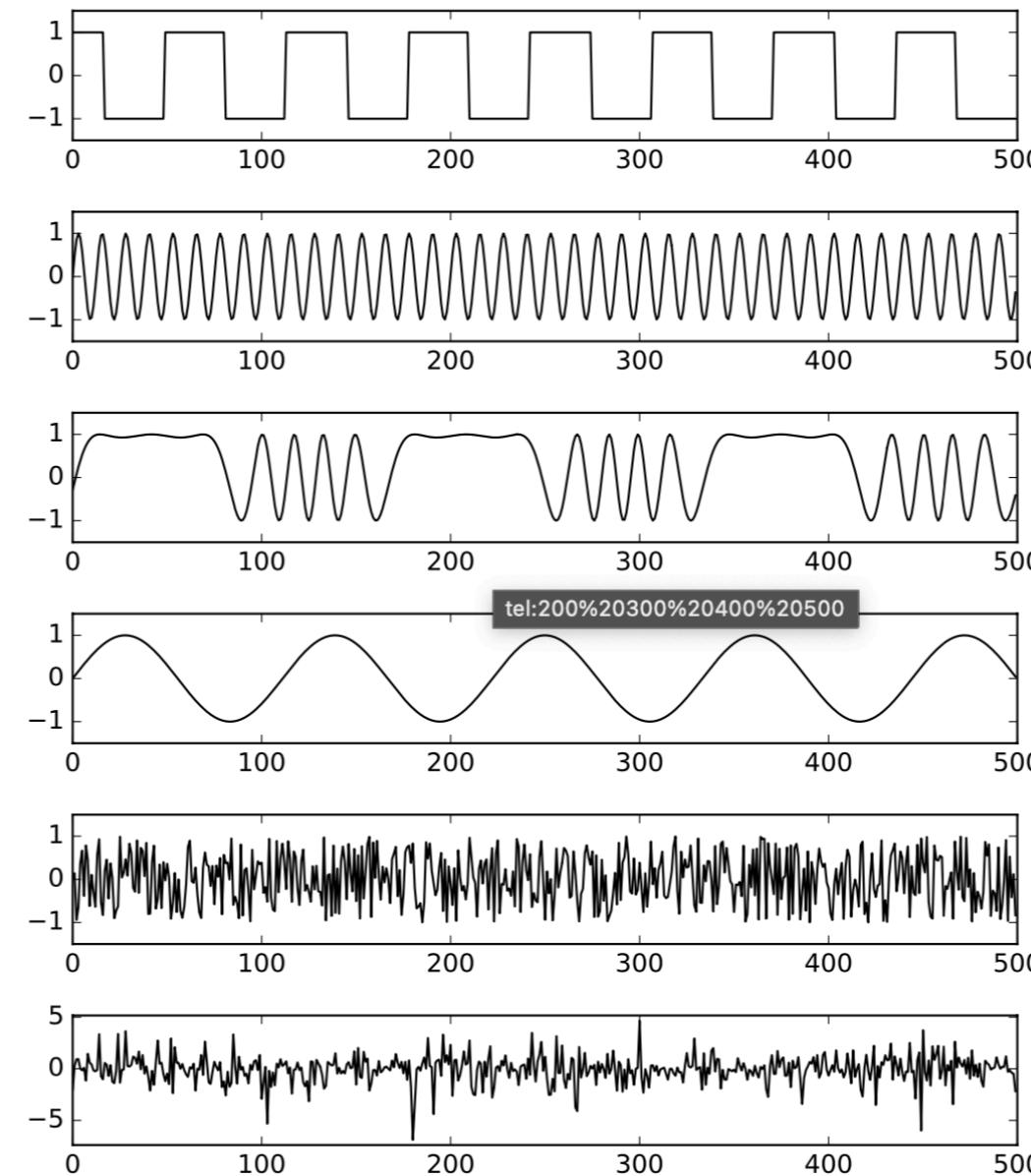
$$\mathcal{L} = \|\mathbf{X} - \hat{\mathbf{X}}\|_2 + \lambda [\log \mathcal{D}(\mathbf{Z}) + \log(1 - \mathcal{D}(\mathbf{Z}))]$$

Reconstruction error

Discrimination loss

Adversarial regularisation for NL ICA

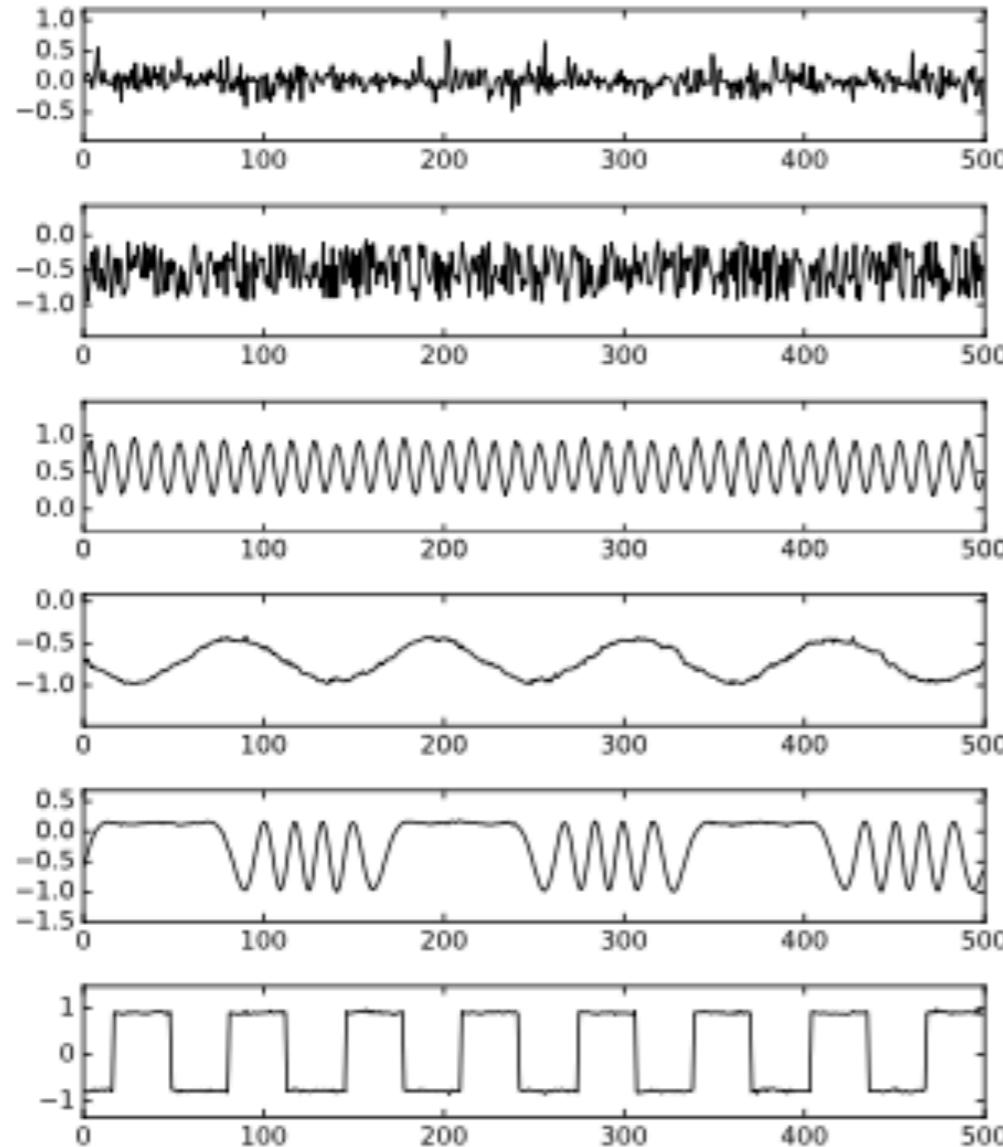
Examples of reconstructions (audio signals) in case of a PNL



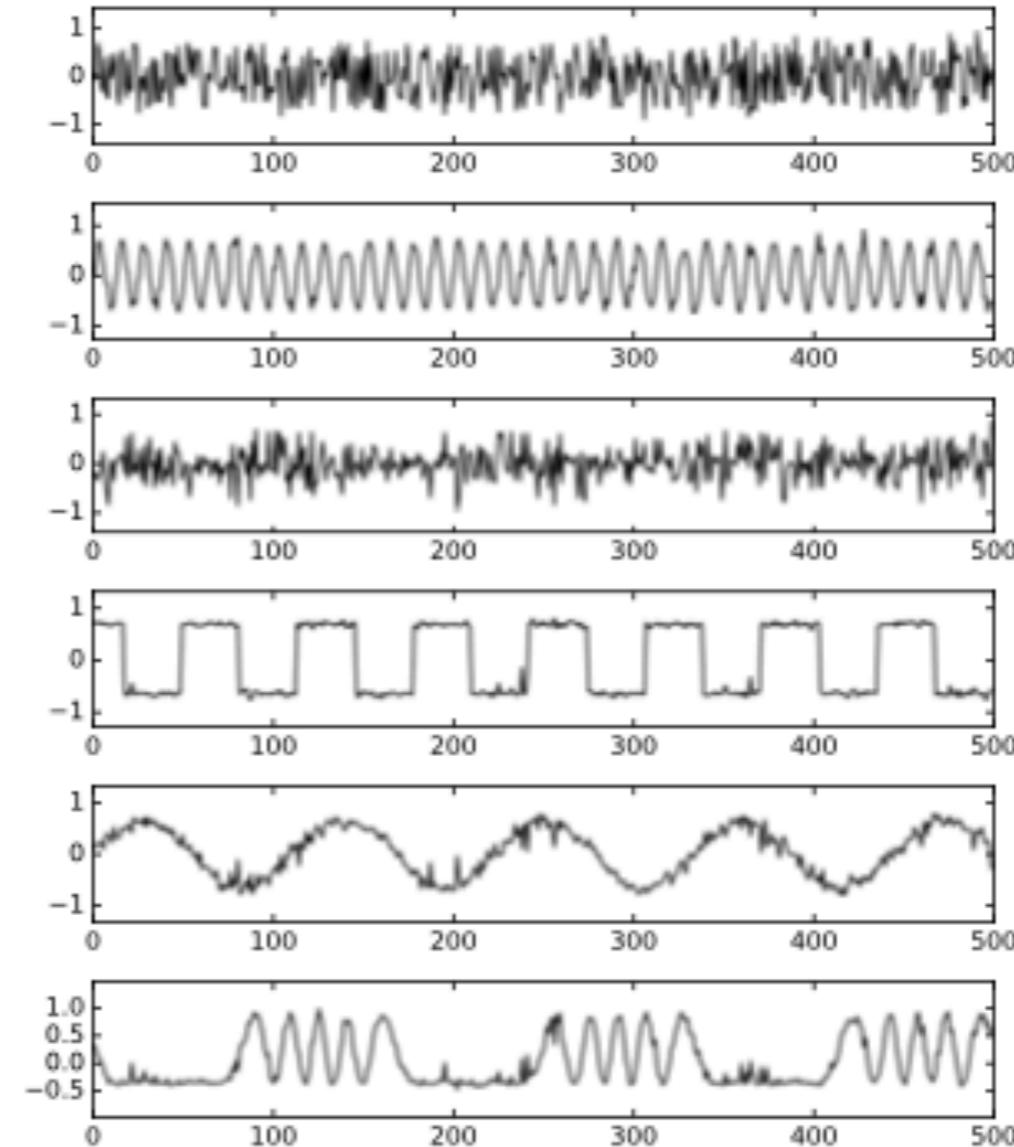
Test with NL and PNL mixtures

Adversarial regularisation for NL ICA

Examples of reconstructions (audio signals) in case of a PNL



(a) Anica PNL reconstructions $\rho_{\max} = .997$.



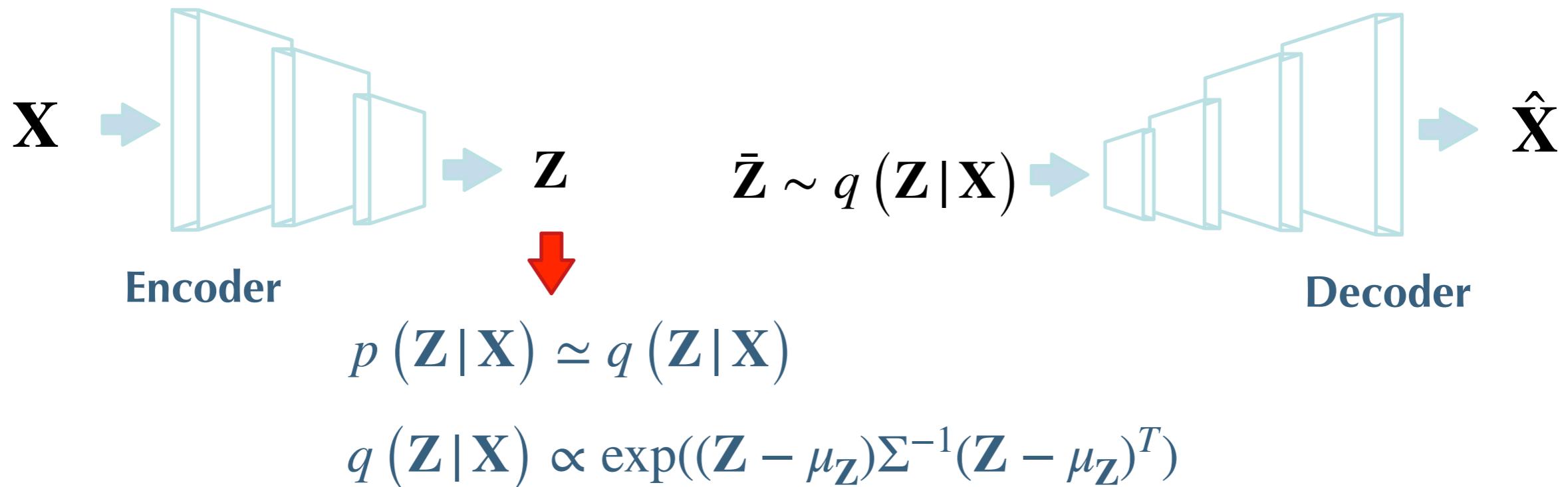
(b) Anica MLP reconstructions $\rho_{\max} = .968$.

$$X = \tanh(B \tanh(AS)) \quad x_1 = \tanh(x), x_2 = (x + x^3)/2, x = \exp(x)$$

Gist of the approach:

- i) better constrain the latent space
- ii) statistical model of the latent variables

Solution: make use of a **variational autoencoder model**



Variational autoencoders

Learn the marginal likelihood of the data (as a generative model):

$$\min_{\phi, \psi} \mathbb{E}_{q(\mathbf{Z}|\mathbf{X})} \left[-\log p_\psi(\mathbf{X}|\mathbf{Z}) \right] \quad \phi : \text{encoder}, \psi : \text{decoder}$$

Reformulation:

$$\log p_\psi(\mathbf{X}|\mathbf{Z}) = \mathcal{D}_{KL} \left(q \left(\mathbf{Z} | \mathbf{X} \right), p(\mathbf{X}) \right) + \mathcal{L} \left(\phi, \psi; \mathbf{X}, \mathbf{Z} \right)$$

*approximation error
of the posterior*

β -VAE loss (Higgins 2017 - Burgess 2018):

$$\mathcal{L} \left(\phi, \psi; \mathbf{X}, \mathbf{Z} \right) = \beta \mathcal{D}_{KL} \left(q \left(\mathbf{Z} | \mathbf{X} \right), p(\mathbf{X}) \right) - \log p_\psi(\mathbf{X}|\mathbf{Z})$$

Factor VAE (Kim, Mnih 2019)

$$\mathcal{L}(\phi, \psi; \mathbf{X}, \mathbf{Z}) = \beta \mathcal{D}_{KL}(q(\mathbf{Z}|\mathbf{X}), p(\mathbf{Z})) - \log p_\psi(\mathbf{X}|\mathbf{Z})$$

→

$$\mathcal{L}(\phi, \psi; \mathbf{X}, \mathbf{Z}) = \beta \mathcal{D}_{KL}(q(\mathbf{Z}|\mathbf{X}), p(\mathbf{Z})) + \boxed{\gamma \mathcal{D}_{KL}\left(q(\mathbf{Z}), \prod_i q(z_i)\right)} - \log p_\psi(\mathbf{X}|\mathbf{Z})$$

“Total correlation” :

$$\mathcal{D}_{KL}\left(q(\mathbf{Z}), \prod_i q(z_i)\right) = \mathbb{E}_{q(\mathbf{Z})} \left[\log \frac{q(\mathbf{Z})}{\prod_i q(z_i)} \right]$$

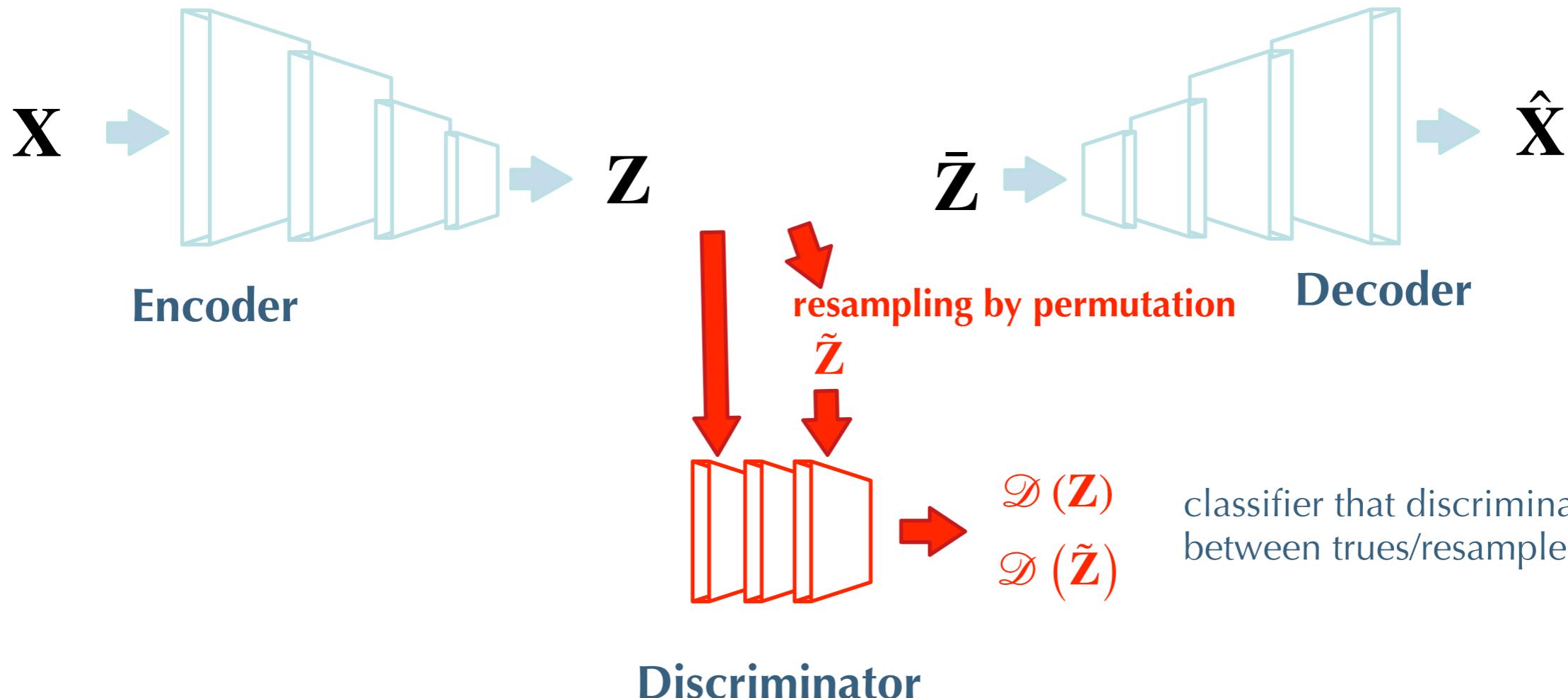
$$\simeq \mathbb{E}_{q(\mathbf{Z})} \left[\log \frac{\mathcal{D}(\mathbf{Z})}{1 - \mathcal{D}(\mathbf{Z})} \right] \quad (Sugiyama 2012)$$

$$\mathcal{L}(\phi, \psi; \mathbf{X}, \mathbf{Z}) = \beta \mathcal{D}_{KL}(q(\mathbf{Z}|\mathbf{X}), p(\mathbf{Z})) + \boxed{\gamma \frac{\log(\mathcal{D}(\mathbf{Z}))}{\log(1 - \mathcal{D}(\tilde{\mathbf{Z}}))}} - \log p_\psi(\mathbf{X}|\mathbf{Z})$$

Factor VAE (Kim, Mnih 2019)

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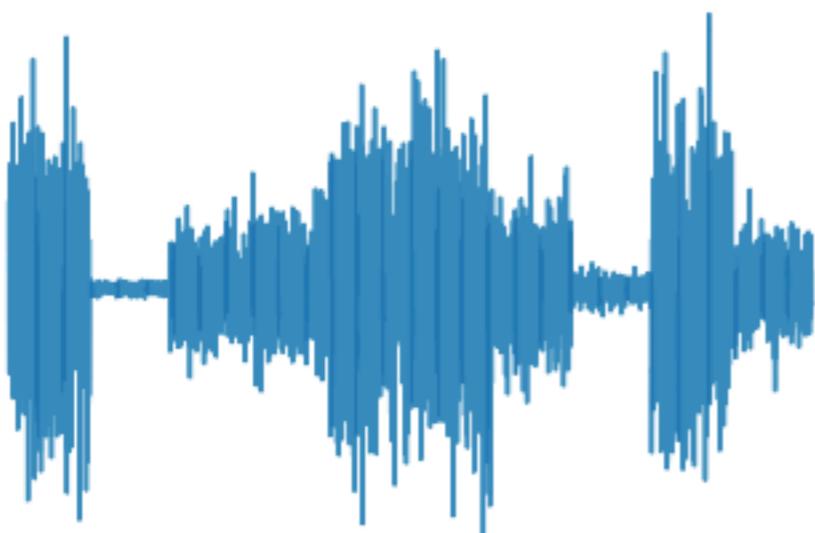
Towards identifiability: a unified framework

Some good and bad news (*Khemakhem 2020*):

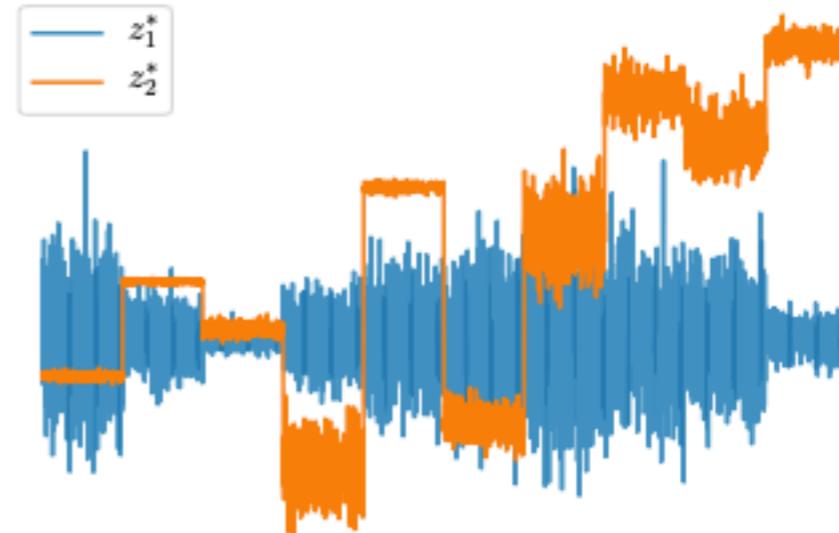
- i) we generally don't have identifiability .. unless
- ii) prior information is known about the sought-after sources

$$q(\mathbf{Z}|\mathbf{X}), p(\mathbf{Z}) \rightarrow q(\mathbf{Z}|\mathbf{X}, \mathbf{U}), p(\mathbf{Z}|\mathbf{U})$$

Where \mathbf{U} is an auxiliary variable describing the sources
e.g. time-dependent sources, class labels, etc



(a)



(b)

(Temporary conclusion)

- VAE-based architectures provide a powerful and general framework to tackle NL-ICA
- Identifiability results have quickly emerged during the past 3 years
- Applicability and extensions to tackle real problems are fully open !

