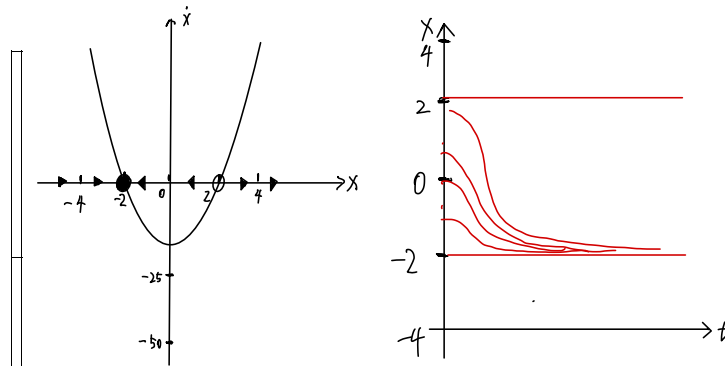


2.2.1  $\dot{x} = 4x^2 - 16$



$\therefore x^* = -2$  (stable)

$x^* = 2$  (unstable)

$\dot{x} = 4x^2 - 16$

$\frac{dx}{dt} = 4x^2 - 16$

$dt = \frac{1}{4x^2 - 16} dx$

$\int dt = \int \frac{1}{4x^2 - 16} dx$

$t + c_1 = \frac{1}{16} \log\left(\frac{2-x}{x+2}\right)$

modify:

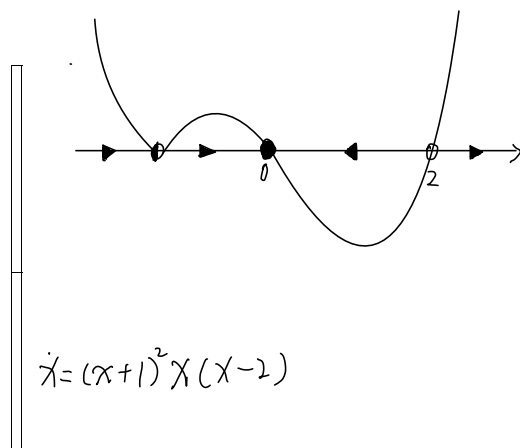
$x(t) = \frac{-2(e^{4c_1 + 16t} - 1)}{e^{4c_1 + 16t} + 1}$

$x \in [-2, 2]$

$t = \frac{1}{16} \ln\left(\frac{2-x}{x+2}\right)$

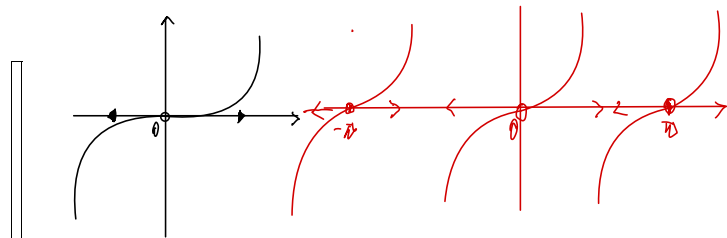
(a) 2.2.1

2.2.8



(b) 2.2.8

2.4.3



from the graph  $x^* = 0$  (unstable).

let  $y = \tan(x) = 0$ .

get  $x^* = 0$ .

Due to  $f'(x^*) = \sec^2(x) = 1$ .

$\therefore x^* = 0$  is unstable.

modify:

$x = \tan(x) = 0$ .

$x = 0$  or  $x = \pi n$   $n \in \mathbb{Z}$

Due to  $f'(x) = \sec^2(x)$

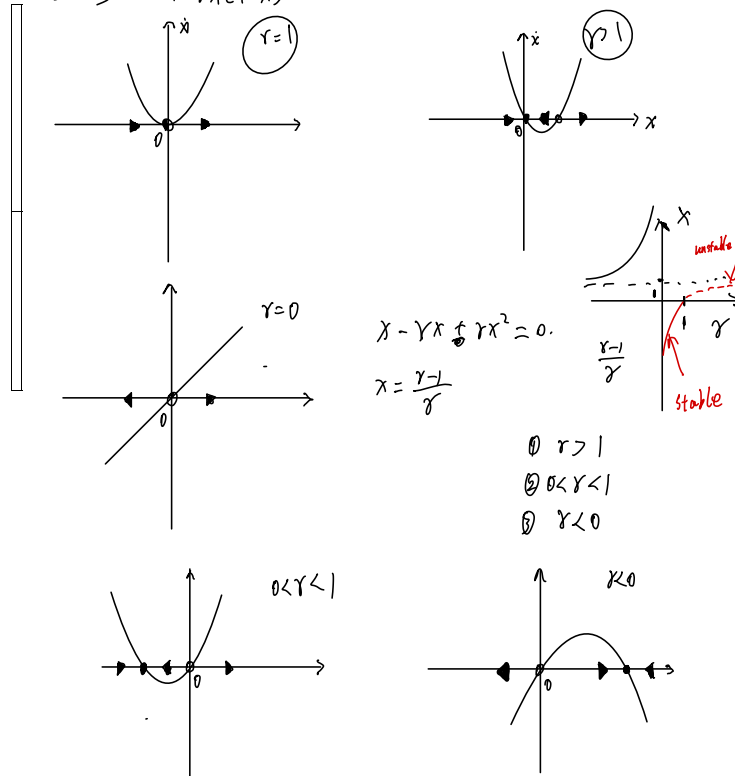
$\therefore x^* = 0$   $f'(x) = 1$ .

$x^* = \pi n$   $f'(x) = 1$

(c) 2.4.3

3.2.3

3.2.3  $\dot{x} = x - r x (1 - x)$



$r$  gradual coincidence of stability points. from  $-\infty$  to  $1$  then exchange stability after  $1$

(d) 3.2.3

3.4.6

3.4.6.  $\dot{x} = rx - \frac{x}{1+x}$

this curve is supercritical pitchfork.

let  $rx - \frac{x}{1+x} = 0$ .

$x(r - \frac{1}{1+x}) = 0$ .

$r - \frac{1}{1+x} = 0$ .

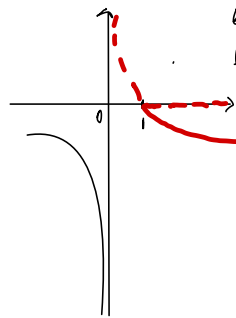
$\frac{1}{1+x} = r$ .

$x = \frac{1}{r} - 1$  ①  $r = 1$

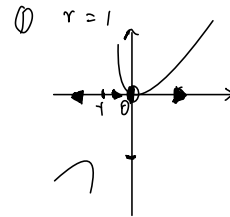
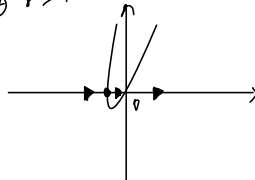
②  $0 < r < 1$

③  $r < 0$

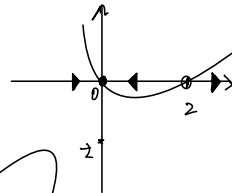
④  $r > 1$



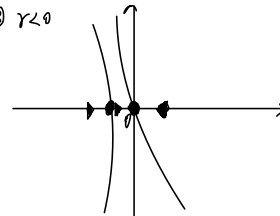
⑤  $r > 1$



⑥  $0 < r < 1$



⑦  $r < 0$



(e) 3.4.6

5.1.7

5.1.7

$$\dot{x} = x$$

$$\dot{y} = x + y$$

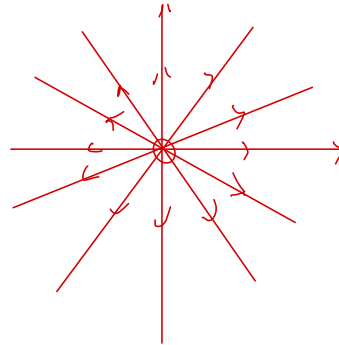
$$A = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$$

$$T = a + d = 2.$$

$$\Delta = 1 - 0 = 1$$

$$c^2 - 4\Delta = 0.$$

$$\lambda_{1,2} = \frac{2}{2} = 1.$$



(f) 5.1.7

5.2.3

5.2.3.  $\dot{x} = y$

$\dot{y} = -2x - 3y$

$A_x = \begin{pmatrix} 0 & 1 \\ -2 & -3 \end{pmatrix}$

$\tau = -3$

$\Delta = 2$

$\lambda_{1,2} = \frac{-3 \pm \sqrt{(-3)^2 - 4(-2)}}{2}$

$= \frac{-3 \pm 1}{2}$

$\lambda_2 = -2 \quad \lambda_1 = -1$

$\therefore \lambda_1 = -1 \quad \lambda_2 = -2 \quad \lambda_2 < \lambda_1 < 0$   
when  $\lambda_1 = -1$

$\begin{pmatrix} 1 & 1 \\ -2 & -2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$v_1 = 1$

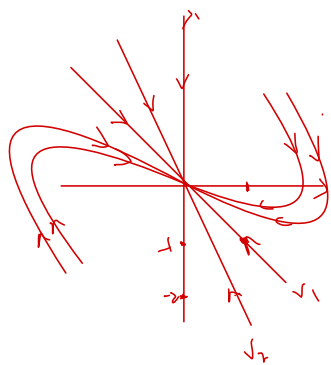
$v_2 = -1 \quad \vec{v} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

when  $\lambda_2 = -2$

$\begin{pmatrix} 2 & 1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$v_1 = 1$

$v_2 = -2 \quad \vec{v} = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$



(g) 5.2.3

5.2.5

5.2.5.

$$\dot{x} = 3x - 4y$$

$$\dot{y} = x - y$$

$$A = \begin{pmatrix} 3 & -4 \\ 1 & -1 \end{pmatrix}$$

$$\text{Tr} = 2$$

$$\Delta = -3 - (-4) = 1$$

$$\lambda_{1,2} = \frac{2 \pm \sqrt{4 - 1 \times 4}}{2}$$

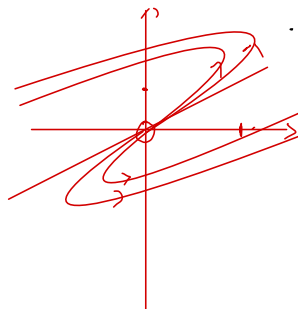
$$= 1$$

$$\lambda_1 = \lambda_2 = 1$$

$$\begin{pmatrix} 3-\lambda & b \\ c & d-\lambda \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\text{eigenvector } v = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$A = \begin{pmatrix} 2 & -4 \\ 1 & -2 \end{pmatrix}$$



(h) 5.2.5

5.3.4



5.3.4 Analyze  $\dot{x} = ax$   $\dot{y} = by$ .

$$\dot{x} = ax$$

$$\dot{y} = by$$

$$A = \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix}$$

$$\tau = 0$$

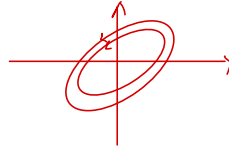
$$\Delta = -ab$$

$$\tau^2 - 4\Delta = -4ab$$

$$\lambda_{1,2} = \frac{0 \pm \sqrt{0^2 - 4ab}}{2} = \pm \sqrt{ab}$$

Case 1  
when  $ab > 0$ ,

$$\Delta < 0.$$

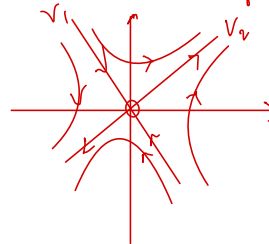


Case 2  $ab < 0$ ,

$$\Delta > 0.$$

$$\begin{pmatrix} \sqrt{ab} & a \\ b & \sqrt{ab} \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$v_1 = \begin{pmatrix} -\frac{\sqrt{a}}{\sqrt{b}} \\ 1 \end{pmatrix} \quad v_2 = \begin{pmatrix} \frac{\sqrt{a}}{\sqrt{b}} \\ 1 \end{pmatrix}$$



(i) 5.3.4

6.3.1

6.3.1  $\dot{x} = x - y$   $\dot{y} = x^2 - 4$  when  $x = -2, y = -2$ .  
 at  $\dot{x} = 0$  set  $y = x \pm 2$ . when  $x = 2, y = 2$ ,  
 $\dot{y} = 0$

$A = \begin{pmatrix} 1 & -1 \\ 2x & 0 \end{pmatrix}$

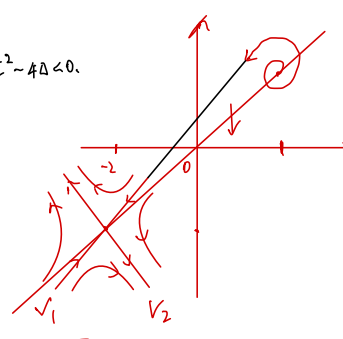
(2.2)  $A_1 = \begin{pmatrix} 1 & -1 \\ 4 & 0 \end{pmatrix}$   $\Delta = 4$   $\tau^2 - 4\Delta < 0$ ,  
 $\tau = 1$

$(-2, -2) A_2 = \begin{pmatrix} 1 & -1 \\ -4 & 0 \end{pmatrix}$   $\Delta = -4$   
 $\tau = 1$

$\lambda_{1,2} = \frac{1 \pm \sqrt{1+16}}{2}$

$\therefore \lambda_2 < 0 < \lambda_1, \therefore$

$V_2 = \begin{pmatrix} \frac{-1 - \sqrt{17}}{8} \\ 1 \end{pmatrix}$   $V_1 = \begin{pmatrix} \frac{-1 + \sqrt{17}}{8} \\ 1 \end{pmatrix}$



(j) 6.3.1

6.3.3

6.3.3.  $\dot{x} = 1 + y - e^{-x}, \dot{y} = x^3 - y$

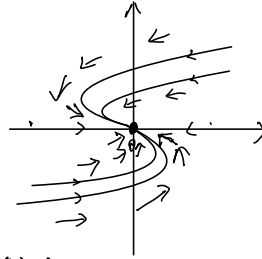
$$\dot{x} = 1 + y - e^{-x} = 0$$

$$\dot{y} = x^3 - y = 0$$

$$\therefore y = x = 0$$

$$A = \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}$$

$$A \hat{r} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{matrix} \tau = 2 \\ \Delta = 1 \end{matrix} \quad \tau^2 - 4\Delta = 0$$



(k) 6.3.3

6.4.2

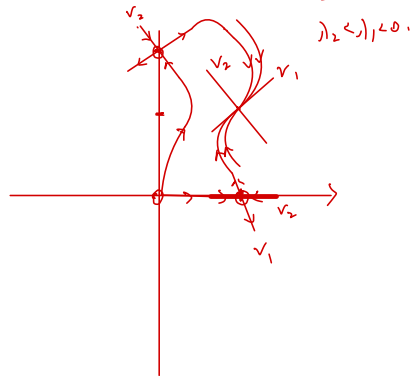
6.4.2.  $\dot{x} = x(3-2x-y) = 0$ ,  $\dot{y} = y(2-x-y) = 0$ , get  $(0,2), (1,1), (\frac{3}{2},0), (0,0)$ ,

$$A = \begin{pmatrix} -4x-y+3 & -x \\ -y & -x-2y+2 \end{pmatrix} \quad (0,0) A = \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix}$$

$$(0,2) A = \begin{pmatrix} 1 & 0 \\ -2 & -2 \end{pmatrix} \quad \lambda = 1, -2$$

$$(1,1) A = \begin{pmatrix} -2 & -1 \\ -1 & -1 \end{pmatrix} \quad \begin{matrix} \tau = -3 \\ \Delta = 1 \end{matrix} \quad \lambda = \frac{-3 \pm \sqrt{5}}{2}$$

$$(\frac{3}{2},0) A = \begin{pmatrix} 3 & -\frac{3}{2} \\ 0 & \frac{1}{2} \end{pmatrix} \quad \begin{matrix} \tau = -\frac{5}{2} \\ \Delta = -\frac{3}{2} \end{matrix} \quad \lambda = \frac{-5 \pm \sqrt{(\frac{5}{2})^2 - \frac{3}{2}}}{2}$$



(1) 6.4.2