

MACHINE LEARNING

Probabilistic classification - discriminative models

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In the cases considered above, the posterior class distributions $p(C_k|\mathbf{x})$ are sigmoidal or softmax with argument given by a linear combination of features in \mathbf{x} , i.e., they are instances of **generalized linear models**

A **generalized linear model** (GLM) is a function

$$y(\mathbf{x}) = f(\mathbf{w}^T \mathbf{x} + w_0)$$

where f (usually called the *response function*) is in general a non linear function.

Each iso-surface of $y(\mathbf{x})$, such that by definition $y(\mathbf{x}) = c$ (for some constant c), is such that

$$f(\mathbf{w}^T \mathbf{x} + w_0) = c$$

and

$$\mathbf{w}^T \mathbf{x} + w_0 = f^{-1}(y) = c'$$

(c' constant).

Hence, iso-surfaces of a GLM are hyper-planes, thus implying that boundaries are hyperplanes themselves.

Exponential families and GLM

Otteniamo modelli regressivi dalle stesse ip!

↙ o la distribuzione di probabilità

Let us assume we wish to predict a random variable y as a function of a different set of random variables \mathbf{x} . By definition, a prediction model for this task is a GLM if the following hypotheses hold:

1. the conditional distribution of y given \mathbf{x} , $p(y|\mathbf{x})$ belongs to the exponential family: that is, we may write it as

$$p(y|\mathbf{x}) = \frac{1}{s} g(\boldsymbol{\theta}(\mathbf{x})) f\left(\frac{y}{s}\right) e^{\frac{1}{s} \boldsymbol{\theta}(\mathbf{x})^T \mathbf{u}(y)}$$

$\boldsymbol{\theta}(\mathbf{x})$ sono i coefficienti del modello, $\mathbf{u}(y)$ è come rappresentiamo l'output.

for suitable $g, \boldsymbol{\theta}, \mathbf{u}$

2. for any \mathbf{x} , we wish to predict the expected value of $\mathbf{u}(y)$ given \mathbf{x} , that is $E[\mathbf{u}(y)|\mathbf{x}]$
3. $\boldsymbol{\theta}(\mathbf{x})$ (the **natural parameter**) is a linear combination of the features, $\boldsymbol{\theta}(\mathbf{x}) = \mathbf{w}^T \bar{\mathbf{x}}$

I GLM hanno tutte le stesse caratteristiche

$\boldsymbol{\theta}$ è una funzione generica:

$$\begin{pmatrix} \theta_1 \\ \vdots \\ \theta_k \end{pmatrix} [u_1(\theta) \dots u_k(\theta)]$$

Sia per la regressione lineare che per quella logistica siamo partiti da ipotesi:

- lineare: media derivata da una Gaussiana, varianza qualunque
- logistica: dobbiamo predire 0/1, allora riconduciamo ad una Bernoulli. Facciamo dipendere il valore di probabilità da x

Facciamo sempre l'ipotesi di come è fatto y data la x :

$$p(y|x)$$

otterremo sempre una combinazione lineare delle feature a cui viene applicata una funzione non lineare.

1. $y \in \mathbb{R}$, and $p(y|\mathbf{x}) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(y-\mu(\mathbf{x}))^2}{2\sigma^2}}$ is a normal distribution with mean $\mu(\mathbf{x})$ and constant variance σ^2 : it is easy to verify that

$$\boldsymbol{\theta}(\mathbf{x}) = \begin{pmatrix} \theta_1(\mathbf{x}) \\ \theta_2 \end{pmatrix} = \begin{pmatrix} \mu(\mathbf{x})/\sigma^2 \\ -1/2\sigma^2 \end{pmatrix}$$

and $\mathbf{u}(y) = y$

2. we wish to predict the value of $E[\mathbf{u}(y)|\mathbf{x}]$ as $y(\mathbf{x}) = E[y|\mathbf{x}]$, then

$$y(\mathbf{x}) = \mu(\mathbf{x}) = \sigma^2 \theta_1(\mathbf{x})$$

3. we assume there exists \mathbf{w} such that $\theta_1(\mathbf{x}) = \mathbf{w}_1^T \bar{\mathbf{x}}$

Then, a linear regression results

$$y(\mathbf{x}) = \mathbf{w}_1^T \bar{\mathbf{x}}$$

$$\Rightarrow y(\mathbf{x}) = \sigma^2 \theta(\mathbf{x}) = \sigma^2 \mathbf{w}^T \mathbf{x}$$

1. $y \in \{0, 1\}$, and $p(y|\mathbf{x}) = \pi(\mathbf{x})^y(1 - \pi(\mathbf{x}))^{1-y}$ is a Bernoulli distribution with parameter $\pi(\mathbf{x})$: then, the natural parameter $\theta(\mathbf{x})$ is

$$\theta(\mathbf{x}) = \log \frac{\pi(\mathbf{x})}{1 - \pi(\mathbf{x})}$$

↳ sostituisce nell'espressione generale.

and $\mathbf{u}(y) = y$

2. we wish to predict the value of $E[\mathbf{u}(y)|\mathbf{x}]$ as $y(\mathbf{x}) = E[y|\mathbf{x}] = p(y = 1|\mathbf{x})$, then

$$p(y = 1|\mathbf{x}) = \pi(\mathbf{x}) = \frac{1}{1 + e^{-\theta(\mathbf{x})}}$$

3. we assume there exists \mathbf{w} such that $\theta(\mathbf{x}) = \mathbf{w}^T \bar{\mathbf{x}}$

Then, a logistic regression derives

$$y(\mathbf{x}) = \frac{1}{1 + e^{-\mathbf{w}^T \bar{\mathbf{x}}}}$$

GLM and categorical distribution

1. $y \in \{1, \dots, K\}$, and $p(y|\mathbf{x}) = \prod_{i=1}^K \pi_i(\mathbf{x})^{y_i}$ (where $y_i = 1$ if $y = i$ and $y = 0$ otherwise) is a categorical distribution with probabilities $\pi_1(\mathbf{x}), \dots, \pi_K(\mathbf{x})$ (where $\sum_{i=1}^K \pi_i(\mathbf{x}) = 1$): the natural parameter is then $\boldsymbol{\theta}(\mathbf{x}) = (\theta_1(\mathbf{x}), \dots, \theta_K(\mathbf{x}))^T$, with

$$\theta_i(\mathbf{x}) = \log \frac{\pi_i(\mathbf{x})}{\pi_K(\mathbf{x})} = \log \frac{\pi_i(\mathbf{x})}{1 - \sum_{j=1}^{K-1} \pi_j(\mathbf{x})}$$

Classifier for one multi-class.

and $\mathbf{u}(y) = (y_1, \dots, y_K)^T$ is the 1-to- K representation of y

2. we wish to predict the expectations $y_i(\mathbf{x}) = E[u_i(y)|\mathbf{x}] = p(y = i|\mathbf{x})$ as

$$p(y = i|\mathbf{x}) = E[u_i(y)|\mathbf{x}] = \pi_i(\mathbf{x}) = \pi_K(\mathbf{x})e^{\theta_i(\mathbf{x})}$$

Since $1 = \sum_{i=1}^K \pi_i(\mathbf{x}) = \pi_K(\mathbf{x}) \sum_{i=1}^K e^{\theta_i(\mathbf{x})}$, it derives

$$\pi_K(\mathbf{x}) = \frac{1}{\sum_{i=1}^K e^{\theta_i(\mathbf{x})}} \quad \text{and} \quad \pi_i(\mathbf{x}) = \frac{e^{\theta_i(\mathbf{x})}}{\sum_{i=1}^K e^{\theta_i(\mathbf{x})}}$$

3. we assume there exist $\mathbf{w}_1, \dots, \mathbf{w}_K$ such that $\theta_i(\mathbf{x}) = \mathbf{w}_i^T \bar{\mathbf{x}}$

Partendo da un ipotesi diversa della distribuzione del target rispetto alle feature ottengo tutte le regressioni.

Then, a softmax regression results, with

$$y_i(\mathbf{x}) = \frac{e^{\mathbf{w}_i^T \bar{\mathbf{x}}}}{\sum_{j=1}^K e^{\mathbf{w}_j^T \bar{\mathbf{x}}}} \quad \text{if } i \neq K$$
$$y_K(\mathbf{x}) = \frac{1}{\sum_{j=1}^K e^{\mathbf{w}_j^T \bar{\mathbf{x}}}}$$

Other regression types can be defined by considering different models for $p(y|\mathbf{x})$. For example,

1. Assume $y \in \{0, \dots, \}$ is a non negative integer (for example we are interested to count data), and $p(y|\mathbf{x}) = \frac{\lambda(\mathbf{x})^y}{y!} e^{-\lambda(\mathbf{x})}$ is a Poisson distribution with parameter $\lambda(\mathbf{x})$: then, the natural parameter $\theta(\mathbf{x})$ is

$$\theta(\mathbf{x}) = \log \lambda(\mathbf{x}) \rightarrow \text{stress argument to d. prime.}$$

and $\mathbf{u}(y) = y$

2. we wish to predict the value of $E[\mathbf{u}(y)|\mathbf{x}]$ as $y(\mathbf{x}) = E[y|\mathbf{x}]$, then

$$y(\mathbf{x}) = \lambda(\mathbf{x}) = e^{\theta(\mathbf{x})}$$

3. we assume there exists \mathbf{w} such that $\theta(\mathbf{x}) = \mathbf{w}^T \bar{\mathbf{x}}$

Then, a Poisson regression derives

$$y(\mathbf{x}) = e^{\mathbf{w}^T \bar{\mathbf{x}}}$$

1. Assume $y \in [0, \infty)$ is a non negative real (for example we are interested to time intervals), and $p(y|\mathbf{x}) = \lambda(\mathbf{x})e^{-\lambda(\mathbf{x})y}$ is an exponential distribution with parameter $\lambda(\mathbf{x})$: then, the natural parameter $\theta(\mathbf{x})$ is

$$\theta(\mathbf{x}) = -\lambda(\mathbf{x})$$

and $\mathbf{u}(y) = y$

2. we wish to predict the value of $E[\mathbf{u}(y)|\mathbf{x}]$ as $y(\mathbf{x}) = E[y|\mathbf{x}]$, then

$$y(\mathbf{x}) = \frac{1}{\lambda(\mathbf{x})} = -\frac{1}{\theta(\mathbf{x})}$$

3. we assume there exists \mathbf{w} such that $\theta(\mathbf{x}) = \mathbf{w}^T \bar{\mathbf{x}}$

Then, an exponential regression derives

$$y(\mathbf{x}) = -\frac{1}{\mathbf{w}^T \bar{\mathbf{x}}}$$

Discriminative approach

We could directly assume that $p(C_k|\mathbf{x})$ is a GLM and derive its coefficients (for example through ML estimation).

Comparison wrt the generative approach:

- ⊙ Less information derived (we do not know $p(\mathbf{x}|C_k)$, thus we are not able to generate new data)
- ⊙ Simpler method, usually a smaller set of parameters to be derived
- ⊙ Better predictions, if the assumptions done with respect to $p(\mathbf{x}|C_k)$ are poor.

→ Algorithms non parametric, la predizione è effettuata guardando ai dati (che snobbano i parametri).

$$p(C_1|\mathbf{x}) = \sigma(\mathbf{w}^T \mathbf{x}) \quad \Bigg| \quad p(C_k|\mathbf{x}) = S(\mathbf{w}_k^T \mathbf{x})$$

Nel caso generativo dobbiamo apprendere più cose, tutti i parametri per le diverse classi. Può essere uno svantaggio, ma così apprendiamo più cose sulla classe e quindi possiamo:

- generare sinteticamente degli elementi della classe (se necessari);
- poter scartare degli outlayer se li individuiamo

Nell'approccio discriminativo, che forse lo fa preferire, è che si fanno diverse ipotesi: nel caso generativo supponiamo che le classi siano distribuite secondo Gaussiane ma magari non lo sono e quindi apprendo dei parametri che non vanno bene perché i dati non sono distribuiti Gaussianamente.

Nel caso discriminativo andiamo "più dritti" all'obiettivo senza fare ipotesi, a parte che il modello sia lineare generalizzato

Logistic regression is a GLM deriving from the hypothesis of a Bernoulli distribution of y , which results into

$$p(C_1|\mathbf{x}) = \underbrace{\sigma(\mathbf{w}^T \mathbf{x})}_{\text{sigmoide}} = \frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}}}$$

where base functions could also be applied.

The model is equivalent, for the binary classification case, to linear regression for the regression case.

Ottengono la superficie di separazione lineare, ma stimare la probabilità è utile se ci portiamo dietro più informazioni, e non solo discriminare a che classe appartenga in base al dato della superficie

- ⊙ In the case of d features, logistic regression requires $d + 1$ coefficients w_0, \dots, w_d to be derived from a training set
- ⊙ A generative approach with gaussian distributions requires:
 - $2d$ coefficients for the means μ_1, μ_2 ,
 - for each covariance matrix

$$\sum_{i=1}^d i = d(d+1)/2 \quad \text{coefficients}$$

- one prior cla probability $p(C_1)$
- ⊙ As a total, it results into $d(d+1) + 2d + 1 = d(d+3) + 1$ coefficients (if a unique covariance matrix is assumed $d(d+1)/2 + 2d + 1 = d(d+5)/2 + 1$ coefficients)

Maximum likelihood estimation

Let us assume that targets of elements of the training set can be conditionally (with respect to model coefficients) modeled through a Bernoulli distribution. That is, assume

stimata dal modello $p(t_i|\mathbf{x}_i, \mathbf{w}) = p_i^{t_i}(1 - p_i)^{1-t_i}$ $t_i = (0,1)$

where $p_i = p(C_1|\mathbf{x}_i) = \sigma(\mathbf{w}^T \mathbf{x}_i)$.

Then, the likelihood of the training set targets \mathbf{t} given \mathbf{X} is

assumo di generare elementi con relativo target \Rightarrow $p(\mathbf{t}|\mathbf{X}, \mathbf{w}) = L(\mathbf{w}|\mathbf{X}, \mathbf{t}) = \prod_{i=1}^n p(t_i|\mathbf{x}_i, \mathbf{w})$ *assumo indipendenza fra gli elementi* $= \prod_{i=1}^n p_i^{t_i}(1 - p_i)^{1-t_i}$

and the log-likelihood is

$l(\mathbf{w}|\mathbf{X}, \mathbf{t}) = \log L(\mathbf{w}|\mathbf{X}, \mathbf{t}) = \sum_{i=1}^n (t_i \log p_i + (1 - t_i) \log(1 - p_i))$

$\begin{cases} p_i & 1 \\ 1-p_i & 0 \end{cases} \Rightarrow p_i^{t_i} (1-p_i)^{1-t_i} \Rightarrow \sigma(\mathbf{w}^T \mathbf{x}_i)^{t_i} (1 - \sigma(\mathbf{w}^T \mathbf{x}_i))^{1-t_i}$

Ho più coefficienti da apprendere: cerco i valori di w che massimizza la prob. stimata di appartenere alla classe + elemento.

Genero n coppie (x_i, t_i) , stimo la prob. di aver generato queste coppie:

x_i e' scelto a caso

t_i dipende da x_i

$$p(x_i, t_i) = p(t_i | x_i) \cancel{p(x_i)} \text{ e' uniforme, non m. } \\ \text{impart.}$$

$$p(t_i | x_i) \text{ dipende da } w, \text{ quindi } p(t, x) = \prod p(x_i, t_i) = \prod (p(t_i | x_i) \cancel{p(x_i)}) \\ = \prod p(t_i | x_i, w)$$

$$\text{otteniamo } \sum_{i=1}^n t_i \log(\sigma(w^T x_i)) + (1-t_i) \log(1 - \sigma(w^T x_i))$$

cerchiamo w che ci dia il valore più alto dell'espressione.

⊙ It results

Qui $p_i = \sigma(w^T x + w_0)$
e σ è non lineare quindi
non abbiamo un sistema
lineare.

$$\frac{\partial l(\mathbf{w}|\mathbf{X}, \mathbf{t})}{\partial \mathbf{w}} = \left[\sum_{i=1}^n (t_i - p_i) \bar{\mathbf{x}}_i \right] = \sum_{i=1}^n (t_i - \sigma(\mathbf{w}^T \bar{\mathbf{x}}_i)) \bar{\mathbf{x}}_i$$

$$\sum_{i=1}^n (t_i - p_i) x_i$$

↑
valore corretto
del target

è quello che avevamo anche nella regressione
lineare, dove $p_i = w^T x + w_0$ ⇒

$$\sum_i (t_i - w^T x_i + w_0) x_i$$

È lineare. (1 solution)

To maximize the likelihood, we could apply a gradient ascent algorithm, where at each iteration the following update of the currently estimated \mathbf{w} is performed

Approssimazione del metodo
del gradiente
"standard"
(in forma semplice).

$$\begin{aligned}\mathbf{w}^{(j+1)} &= \mathbf{w}^{(j)} + \alpha \frac{\partial l(\mathbf{w} | \mathbf{X}, \mathbf{t})}{\partial \mathbf{w}} \Big|_{\mathbf{w}^{(j)}} \\ &= \mathbf{w}^{(j)} + \alpha \sum_{i=1}^n (t_i - \sigma((\mathbf{w}^{(j)})^T \bar{\mathbf{x}}_i)) \bar{\mathbf{x}}_i \\ &= \mathbf{w}^{(j)} + \alpha \sum_{i=1}^n (t_i - y(\mathbf{x}_i)) \bar{\mathbf{x}}_i\end{aligned}$$

calcolato in $\mathbf{w}^{(j)}$ che poi mi trovo nella predizione

As a possible alternative, at each iteration only one coefficient in \mathbf{w} is updated

$$\begin{aligned}w_k^{(j+1)} &= w_k^{(j)} + \alpha \frac{\partial l(\mathbf{w}|\mathbf{X}, \mathbf{t})}{\partial w_k} \Big|_{\mathbf{w}^{(j)}} \\&= w_k^{(j+1)} + \alpha \sum_{i=1}^n (t_i - \sigma((\mathbf{w}^{(j)})^T \bar{\mathbf{x}}_i)) x_{ik} \\&= w_k^{(j+1)} + \alpha \sum_{i=1}^n (t_i - y(\mathbf{x}_i)) x_{ik}\end{aligned}$$

Vi si incardina il discorso della regolarizzazione, quindi avviene che in realtà posso dire che: volendo massimizzare la log verosimiglianza:

$$\max \sum t_i \log(\sigma(w^T x_i)) + (1-t_i) \log(1 - \sigma(w^T x_i))$$

questo ci può portare in overfitting, quindi ci aggiungiamo una componente di regolarizzazione:

$$-\lambda \|w\|^2$$

Softmax regression

Abbiamo insieme di parametri $(D^{+1} \times K)$
dimensione $d+1$ \hookrightarrow n° classi

apprendiamo sempre per massima verosimiglianza.

- ⊙ In order to extend the logistic regression approach to the case $K > 2$, let us consider the matrix $\mathbf{W} = (\mathbf{w}_1, \dots, \mathbf{w}_K)$ of model coefficients, of size $(d+1) \times K$, where \mathbf{w}_j is the $d+1$ -dimensional vector of coefficients for class C_j .
- ⊙ In this case, the likelihood is defined as

$$p(\mathbf{T}|\mathbf{X}, \mathbf{W}) = \prod_{i=1}^n \prod_{k=1}^K p(C_k|\mathbf{x}_i)^{t_{ik}} = \prod_{i=1}^n \prod_{k=1}^K \left(\frac{e^{\mathbf{w}_k^T \bar{\mathbf{x}}_i}}{\sum_{r=1}^K e^{\mathbf{w}_r^T \bar{\mathbf{x}}_i}} \right)^{t_{ik}}$$

prob se la
classe scelta
è la i -esima

where \mathbf{X} is the usual matrix of features and \mathbf{T} is the $n \times K$ matrix where row i is the 1-to- K coding of t_i .
That is, if $\mathbf{x}_i \in C_k$ then $t_{ik} = 1$ and $t_{ir} = 0$ for $r \neq k$.

Assumiamo che $t_i = [0, 0, \dots, 1, \dots, 0]$ (su K)

The log-likelihood is then defined as

$$l(\mathbf{W}) = \sum_{i=1}^n \sum_{k=1}^K t_{ik} \log \left(\frac{e^{\mathbf{w}_k^T \bar{\mathbf{x}}_i}}{\sum_{r=1}^K e^{\mathbf{w}_r^T \bar{\mathbf{x}}_i}} \right)$$

And the gradient is defined as

$$\frac{\partial l(\mathbf{W})}{\partial \mathbf{W}} = \left(\frac{\partial l(\mathbf{W})}{\partial \mathbf{w}_1}, \dots, \frac{\partial l(\mathbf{W})}{\partial \mathbf{w}_K} \right)$$

\mathbf{W} : c'è una matrice di coefficienti, K righe e $D+1$ colonne.

- ⊙ It is possible to show that

$$\frac{\partial l(\mathbf{W})}{\partial \mathbf{w}_j} = \sum_{i=1}^n (t_{ij} - y_{ij}) \bar{\mathbf{x}}_i$$

- ⊙ Observe that the gradient has the same structure than in the case of linear regression and logistic regression

Se consideriamo il valore del gradiente nella reg. lineare: $\sum_{i=1}^n (t_i - y_i) \mathbf{x}_i$

Nella reg. logistica $\sum (t_i - \sigma(\mathbf{w}^T \mathbf{x}_i)) \mathbf{x}_i$.

Nei 3 casi il gradiente si esprime sempre nello stesso modo: errore \cdot valore dell'elemento
È ricorrente sulle reti neurali.