Concepts of Programming Languages Lecture 23

Outline

- » Demo an implementation of unification
- » Discuss principle types and specialization

Practice Problem

$$\cdot \vdash \lambda x \cdot xx : \tau \dashv \mathscr{C}$$

Determine the type τ and constraints $\mathscr C$ such that the above judgment is derivable

Answer

 $C \quad \cdot \vdash \lambda x . xx : \tau \dashv \mathscr{C}$

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LX: Z3 LXX: B-1 X= X->B

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Recap

Recall: Unification

$$a \doteq d \rightarrow e$$

$$c \doteq \operatorname{int} \rightarrow d$$

$$\operatorname{int} \rightarrow \operatorname{int} \rightarrow \operatorname{int} \doteq b \rightarrow c$$

Unification is the process of solving a system of equations over *symbolic* expressions

It's kind of like solving a system of linear equations, but instead of working over real numbers and addition, we work over *uninterpreted* operators

Recall: ADT Unification Problem

A unification problem is a collection of equations of the form

$$s_1 \doteq t_1$$
 $s_2 \doteq t_2$
 \vdots
 $s_k \doteq t_k$

where $s_1,...,s_k$ and $t_1,...,t_k$ are **terms** (values of an ADT with variables)

Example: List Unification

```
type int list =
  | Cons of int * int list
             Nil

Cons (2, 1) = Cons(2, 1)
           Cons (2, Nil)
```

Example: Type Unification

```
type ty =
    | TInt
    | TBool
    | TFun of ty * ty
    | TVar of string
```

Type unification is the unification problem for an ADT of types (with type variables acting as variables in the unification problem)

Recall: Unifiers

A **unifier** is a sequence of substitutions to variables, typically written

$$S = \{x_1 \mapsto t_1, x_2 \mapsto t_2, ..., x_n \mapsto t_n\}$$

We write St for $[t_n/x_n]...[t_1/x_1]t$. A solution must have the property that it **satisfies** every equation

$$St_1 = Ss_1$$

$$Ss_2 = St_2$$

$$\vdots$$

$$Ss_k = St_k$$

Recall: Most General Unifiers

A most general unifier of a unification problem is a solution S such that, for any solution S', there is another solution S'' such that S' = SS''

In other words, S' is S with more substitutions

$$S = \{ \times \mapsto \text{int} \}$$

$$S_2 = \{ \times \mapsto \text{bool} \}$$

$$S_3 = \{ \times \mapsto \text{as} \}$$

```
<u>input:</u> type unification problem \mathcal{U} <u>output:</u> most general unifier to \mathcal{U}
```

```
<u>input:</u> type unification problem \mathcal{U} <u>output:</u> most general unifier to \mathcal{U} \mathcal{S} \leftarrow \text{empty solution}
```

```
input: type unification problem \mathscr{U} output: most general unifier to \mathscr{U} \mathscr{S} \leftarrow \text{empty} solution   \text{WHILE } eq \in \mathscr{U} \text{: } // \mathscr{U} \text{ is not empty}
```

<u>input:</u> type unification problem \mathcal{U}

```
input: type unification problem \mathscr{U} output: most general unifier to \mathscr{U} \mathscr{S} \leftarrow \text{empty} solution WHILE eq \in \mathscr{U}: // \mathscr{U} is not empty MATCH eq:
```

```
t_1 \doteq t_2 where t_1 = t_2 \implies \mathcal{U} \leftarrow \mathcal{U} \setminus \{eq\} // if t_1 and t_2 are syntactically equal then remove eq s_1 \rightarrow t_1 \doteq s_2 \rightarrow t_2 \implies \mathcal{U} \leftarrow \mathcal{U} \setminus \{eq\} \cup \{s_1 \doteq s_2, t_1 \doteq t_2\} // remove eq and add s_1 \doteq s_2 and t_1 \doteq t_2
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input: type unification problem \mathscr{U} output: most general unifier to \mathscr{U} \mathscr{S} ← empty solution WHILE eq \in \mathscr{U}: // \mathscr{U} is not empty MATCH eq:
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```

<u>input:</u> type unification problem \mathcal{U}

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<u>output:</u> most general unifier to \mathscr{U}
\mathcal{S} \leftarrow \text{empty solution}
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       t_1 \doteq t_2 where t_1 = t_2 \implies \mathcal{U} \leftarrow \mathcal{U} \setminus \{eq\} // if t_1 and t_2 are syntactically equal then remove eq
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           \mathcal{S} \leftarrow \mathcal{S} \cup \{\alpha \mapsto t\} // add \alpha \mapsto t to \mathcal{S}
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<u>input:</u> type unification problem \mathcal{U}
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S \leftarrow \text{empty solution}
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      s_1 \rightarrow t_1 \doteq s_2 \rightarrow t_2 \implies \mathcal{U} \leftarrow \mathcal{U} \setminus \{eq\} \cup \{s_1 \doteq s_2, t_1 \doteq t_2\} // remove eq and add s_1 \doteq s_2 and t_1 \doteq t_2
      \alpha \doteq t or t \doteq \alpha where \alpha \notin FV(t) \Longrightarrow // type variable \alpha does not appear free in t
          \mathcal{S} \leftarrow \mathcal{S} \cup \{\alpha \mapsto t\} // add \alpha \mapsto t to \mathcal{S}
          \mathcal{U} \leftarrow \mathcal{U} \setminus \{eq\}
          perform the substitution \alpha \mapsto t to every equation in \mathcal{U}
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          perform the substitution \alpha \mapsto t to every equation in \mathcal{U}
      OTHERWISE \Longrightarrow FAIL
```

RETURN S

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<u>input:</u> type unification problem \mathcal{U}
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S \leftarrow \text{empty solution}
WHILE eq \in \mathcal{U}: // \mathcal{U} is not empty
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          \mathcal{S} \leftarrow \mathcal{S} \cup \{\alpha \mapsto t\} // add \alpha \mapsto t to \mathcal{S}
          \mathcal{U} \leftarrow \mathcal{U} \setminus \{eq\}
          perform the substitution \alpha \mapsto t to every equation in \mathcal{U}
      OTHERWISE \Longrightarrow FAIL
```

Example

Another Practice Problem

$$\beta \doteq \eta$$

$$\alpha \rightarrow \beta \doteq \alpha \rightarrow \gamma$$

$$\alpha \rightarrow \beta \doteq \gamma \rightarrow \eta$$

$$\alpha \rightarrow \beta \doteq \inf \rightarrow \eta$$

$$\alpha \rightarrow \beta \doteq \inf \rightarrow \eta$$

Determine a most general unifier to the above type unification problem using the algorithm we just gave

Answer

$$\beta \stackrel{!}{=} \eta \qquad var = ty$$

$$\alpha \rightarrow \beta \stackrel{!}{=} \alpha \rightarrow \gamma \qquad \text{funty} = \text{funty}$$

$$\alpha \rightarrow \beta \stackrel{!}{=} \gamma \rightarrow \eta \qquad \text{funty} = \text{funty}$$

$$\alpha \rightarrow \beta \stackrel{!}{=} \text{int} \rightarrow \eta \qquad \text{funty} = \text{funty}$$

$$\alpha \rightarrow \beta \stackrel{!}{=} \text{int} \rightarrow \eta \qquad \text{funty} = \text{funty}$$

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demo (unification)

$$Sa = a > \beta \neq (a > \beta) > \beta = S(a > \beta)$$

$$\Gamma \vdash e : \tau \vdash \mathscr{C}$$

$$\Gamma \vdash e : \tau \dashv \mathscr{C}$$

The constraints $\mathscr C$ defined a *unification problem*. Given a most general unifier $\mathscr S$ we can get the "actual" type of e:

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principle $(\tau, \mathscr{C}) = \forall \alpha_1 ... \forall \alpha_k . \mathcal{S}\tau$ where $FV(\mathcal{S}\tau) = \{\alpha_1, ..., \alpha_k\}$

$$\Gamma \vdash e : \tau \vdash \mathscr{C}$$

The constraints $\mathscr C$ defined a *unification problem*. Given a most general unifier $\mathscr S$ we can get the "actual" type of e:

principle
$$(\tau, \mathscr{C}) = \forall \alpha_1 ... \forall \alpha_k . \mathcal{S}\tau$$
 where $FV(\mathcal{S}\tau) = \{\alpha_1, ..., \alpha_k\}$

i.e, the **principle type** of e (<u>note:</u> it may not exist). Every type we could give e is a specialization of $\forall \alpha_1, ..., \alpha_k. \mathcal{S}\tau$

Example

Determine the principle type of $\lambda f \cdot \lambda x \cdot f(x+1)$

Example

Show that $let f = \lambda x \cdot x$ in f(f = 2) has no principle type

<u>input</u>: program P (sequence of top-level let-expressions)

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$$\Gamma \leftarrow \emptyset$$

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$$\Gamma \leftarrow \emptyset$$

FOR EACH top-level let-expression let x = e in P:

1. Constraint-based inference: Determine τ and $\mathscr C$ such that $\Gamma \vdash e : \tau \dashv \mathscr C$ is derivable

<u>input</u>: program P (sequence of top-level let-expressions)

$$\Gamma \leftarrow \emptyset$$

- 1. Constraint-based inference: Determine τ and $\mathscr C$ such that $\Gamma \vdash e : \tau \dashv \mathscr C$ is derivable
- 2. Unification: Solve $\mathscr C$ to get a most general unifier $\mathscr S$ (TYPE ERROR if this fails)

<u>input</u>: program P (sequence of top-level let-expressions)

$$\Gamma \leftarrow \emptyset$$

- 1. Constraint-based inference: Determine τ and $\mathscr C$ such that $\Gamma \vdash e : \tau \dashv \mathscr C$ is derivable
- 2. Unification: Solve $\mathscr C$ to get a most general unifier $\mathscr S$ (TYPE ERROR if this fails)
- *3. Generalization:* Quantify over the free variables in $\mathcal{S}\tau$ to get the principle type $\forall \alpha_1 ... \forall \alpha_k . \mathcal{S}\tau$ of e

<u>input</u>: program P (sequence of top-level let-expressions)

$$\Gamma \leftarrow \emptyset$$

- 1. Constraint-based inference: Determine τ and $\mathscr C$ such that $\Gamma \vdash e : \tau \dashv \mathscr C$ is derivable
- 2. Unification: Solve $\mathscr C$ to get a most general unifier $\mathscr S$ (TYPE ERROR if this fails)
- 3. Generalization: Quantify over the free variables in $\mathcal{S}\tau$ to get the principle type $\forall \alpha_1 ... \forall \alpha_k . \mathcal{S}\tau$ of e
- 4. Add $(x: \forall \alpha_1 ... \forall \alpha_k . \mathcal{S}\tau)$ to Γ

```
let id = fun x \rightarrow x
let = id (id 2 = 2)
T = Ø
 letid=fnx>x
[ = { id: 42.2 = 25
```

Specialization

Recall: HM⁻ (Syntax)

$$e::= \lambda x \cdot e \mid ee$$

$$| \text{ let } x = e \text{ in } e$$

$$| \text{ if } e \text{ then } e \text{ else } e$$

$$| e + e \mid e = e$$

$$| n \mid x$$

$$\sigma::= \text{ int } | \text{ bool } | \alpha | \sigma \rightarrow \sigma$$

$$\tau::= \sigma | \forall \alpha \cdot \tau$$

Recall: HM⁻ (Typing)

$$\frac{n \text{ is an integer}}{\Gamma \vdash n : \text{int} \dashv \emptyset} \text{ (int)}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathscr{C}_1 \qquad \Gamma \vdash e_2 : \tau_2 \dashv \mathscr{C}_2 \qquad \Gamma \vdash e_3 : \tau_3 \dashv \mathscr{C}_3}{\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : \tau_3 \dashv \tau_1 \doteq \text{bool}, \tau_2 \doteq \tau_3, \mathscr{C}_1, \mathscr{C}_2, \mathscr{C}_3} \qquad \text{(if)}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathscr{C}_1 \qquad \Gamma \vdash e_2 : \tau_2 \dashv \mathscr{C}_2}{\Gamma \vdash e_1 = e_2 : \mathsf{bool} \dashv \tau_1 \doteq \tau_2, \mathscr{C}_1, \mathscr{C}_2} \quad (eq)$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathscr{C}_1 \qquad \Gamma \vdash e_2 : \tau_2 \dashv \mathscr{C}_2}{\Gamma \vdash e_1 + e_2 : \text{int} \dashv \tau_1 \doteq \text{int}, \tau_2 \doteq \text{int}, \mathscr{C}_1, \mathscr{C}_2} \quad (\text{add})$$

$$\frac{\alpha \text{ is fresh}}{\Gamma \vdash \lambda x. e : \alpha \rightarrow \tau \dashv \mathscr{C}} \text{ (fun)}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathscr{C}_1 \quad \Gamma \vdash e_2 : \tau_2 \dashv \mathscr{C}_2 \quad \alpha \text{ is fresh}}{\Gamma \vdash e_1 e_2 : \alpha \dashv \tau_1 \doteq \tau_2 \rightarrow \alpha, \mathscr{C}_1, \mathscr{C}_2} \quad \text{(app)}$$

Recall: HM⁻ (Typing Variables)

$$\frac{(x: \forall \alpha_1. \forall \alpha_2... \forall \alpha_k. \tau) \in \Gamma \qquad \beta_1, ..., \beta_k \text{ are fresh}}{\Gamma \vdash x: [\beta_1/\alpha_1]...[\beta_k/\alpha_k]\tau \dashv \varnothing} \quad (var)$$

If x is declared in Γ , then x can be given the type τ with all free variables replaced by **fresh** variables

This is where the polymorphism magic happens

Fresh variables can be unified with anything

An Alternative Formulation

$$\Gamma \vdash e : \tau$$

It's possible to give a type system for HM-without constraints

It's very similar to our 320Caml system, but with some rules for dealing with quantification and specialization

HM⁻ (Alternative Typing)

$$\frac{n \text{ is an integer}}{\Gamma \vdash n : \text{int}} \text{ (int)} \qquad \frac{\Gamma \vdash e_1 : \text{bool}}{\Gamma \vdash e_1 : \text{then } e_2 \text{ else } e_3 : \tau} \text{ (if)}$$

$$\frac{\Gamma \vdash e_1 : \tau}{\Gamma \vdash e_1 = e_2 : \text{bool (eq)}} \qquad \frac{\Gamma \vdash e_1 : \text{int}}{\Gamma \vdash e_1 + e_2 : \text{int}} \text{ (add)}$$

$$\frac{\Gamma, x : \tau_1 \vdash e : \tau_2 \dashv \mathscr{C}}{\Gamma \vdash \lambda x . e : \tau_1 \to \tau_2 \dashv \mathscr{C}} \text{ (fun)} \qquad \frac{\Gamma \vdash e_1 : \tau_2 \to \tau}{\Gamma \vdash e_1 e_2 : \tau} \text{ (app)}$$

is a monotype
$$\Gamma \vdash e_1 : \tau_1 \qquad \Gamma, x : \tau_1 \vdash e_2 : \tau_2$$
 (let)
$$\Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau_2 \dashv \mathscr{C}_1, \mathscr{C}_2$$

HM⁻ (Alternative Typing)

```
familiar rules
   \frac{n \text{ is an integer}}{\Gamma \vdash n : \text{int}} \text{ (int)} \qquad \frac{\Gamma \vdash e_1 : \text{bool}}{\Gamma \vdash e_1 \text{ then } e_2 \text{ else } e_3 : \tau} \text{ (if)}
  \Gamma \vdash e_1 : \tau \qquad \Gamma \vdash e_2 : \tau
                                                                                                                         \frac{\Gamma \vdash e_1 : \text{int} \qquad \Gamma \vdash e_2 : \text{int}}{\Gamma \vdash e_1 + e_2 : \text{int}} \quad (\text{add})
  \Gamma \vdash e_1 = e_2 : \text{bool (eq)}
\frac{\Gamma, x : \tau_1 \vdash e : \tau_2 \dashv \mathscr{C}}{\Gamma \vdash \lambda x . e : \tau_1 \rightarrow \tau_2 \dashv \mathscr{C}} \quad (fun)
                                                                                                                       \frac{\Gamma \vdash e_1 : \tau_2 \to \tau \qquad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash e_1 e_2 : \tau} \quad \text{(app)}
```

is a monotype
$$\Gamma \vdash e_1 : \tau_1 \qquad \Gamma, x : \tau_1 \vdash e_2 : \tau_2$$
 (let)
$$\Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau_2 \dashv \mathscr{C}_1, \mathscr{C}_2$$

$$\frac{\Gamma \vdash e : \tau \qquad \alpha \text{ not free in } \Gamma}{\Gamma \vdash e : \forall \alpha . \tau} \text{ (gen)} \quad \frac{(x : \tau) \in \Gamma \qquad \tau \sqsubseteq \tau'}{\Gamma \vdash x : \tau'} \text{ (var)}$$

$$\frac{\Gamma \vdash e : \tau \quad \alpha \text{ not free in } \Gamma}{\Gamma \vdash e : \forall \alpha . \tau} \text{ (gen)} \quad \frac{(x : \tau) \in \Gamma \quad \tau \sqsubseteq \tau'}{\Gamma \vdash x : \tau'} \text{ (var)}$$

The generalization rule is like the one from System F

$$\frac{\Gamma \vdash e : \tau \qquad \alpha \text{ not free in } \Gamma}{\Gamma \vdash e : \forall \alpha . \tau} \text{ (gen)} \quad \frac{(x : \tau) \in \Gamma \qquad \tau \sqsubseteq \tau'}{\Gamma \vdash x : \tau'} \text{ (var)}$$

The generalization rule is like the one from System F

<u>The main difference:</u> we introduce a notion of **specialization** which allows us to *instantiate* polymorphic functions at particular types

$$\frac{\Gamma \vdash e : \tau \qquad \alpha \text{ not free in } \Gamma}{\Gamma \vdash e : \forall \alpha . \tau} \text{ (gen)} \quad \frac{(x : \tau) \in \Gamma \qquad \tau \sqsubseteq \tau'}{\Gamma \vdash x : \tau'} \text{ (var)}$$

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<u>The main difference:</u> we introduce a notion of **specialization** which allows us to *instantiate* polymorphic functions at particular types

"⊑" defined a *partial order* on type schemes

Specialization (Informal)

$$\forall \alpha_1 \dots \forall \alpha_m \cdot \tau \sqsubseteq \forall \beta_1 \dots \forall \beta_n \cdot \tau'$$

A type scheme T_2 **specializes** T_1 , written $T_1 \sqsubseteq T_2$ if T_2 the result of instantiating the bound variables of T_1 and generalizing over some of the variables introduced by the instantiation

Specialization (Formal)

$$au_1, \ldots, au_m$$
 are monotypes $au' = [au_m/lpha_m] \ldots [au_1/lpha_1] au$ $eta_1, \ldots, eta_n
otin \mathsf{FV}(au) ackslash \{lpha_1, \ldots, lpha_m\}$ $au lpha_1 \ldots au lpha_m \cdot au \sqsubseteq au eta_1 \ldots au eta_n \cdot au'$

A specialization of a type scheme is an instantiation of its bound variable, together with some generalizations over remaining free variables

$$\forall \alpha . \forall \beta . \alpha \to \beta \to \alpha \sqsubseteq \forall \eta . \eta \to \mathsf{bool} \to \eta$$

 $\sqsubseteq \mathsf{int} \to \mathsf{bool} \to \mathsf{int}$

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$$\forall \alpha . \forall \beta . \alpha \rightarrow \beta \rightarrow \alpha \sqsubseteq \forall \gamma . \text{bool} \rightarrow (\gamma \rightarrow \gamma) \rightarrow \text{bool}$$

$$\sqsubseteq \text{bool} \rightarrow (\text{int} \rightarrow \text{int}) \rightarrow \text{bool}$$

$$\forall \alpha . \forall \beta . \alpha \to \beta \to \alpha \sqsubseteq \forall \eta . \eta \to \mathsf{bool} \to \eta$$

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$$\sqsubseteq \text{bool} \to (\text{int} \to \text{int}) \to \text{bool}$$

$$\forall \alpha . \forall \beta . \alpha \to \beta \to \alpha \sqsubseteq \text{bool} \to (\gamma \to \gamma) \to \text{bool}$$

$$\not\sqsubseteq \text{bool} \to (\text{int} \to \text{int}) \to \text{bool}$$

<u>Theorem.</u> If $\Gamma \vdash e : \tau'$ then there is a type τ and constraints $\mathscr C$ such that $\Gamma \vdash e : \tau \dashv \mathscr C$ and principle $(\tau,\mathscr C) \sqsubseteq \tau'$

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<u>Theorem.</u> If $\Gamma \vdash e : \tau \dashv \mathscr{C}$ and $principle(\tau, \mathscr{C}) \sqsubseteq \tau'$ then $\Gamma \vdash e : \tau'$

The principle type is the most general "lowest" type with respect to specialization

$$\{f \colon \forall \alpha . \alpha \to \alpha\} \vdash f(f 2 = 2) : bool$$

$$\frac{(x:\tau) \in \Gamma \quad \tau \sqsubseteq \tau'}{\Gamma \vdash x:\tau'} \quad \text{(var)} \quad \frac{(x:\forall \alpha_1. \forall \alpha_2... \forall \alpha_k. \tau) \in \Gamma \quad \beta_1, ..., \beta_k \text{ are fresh}}{\Gamma \vdash x: [\beta_1/\alpha_1]...[\beta_k/\alpha_k]\tau \dashv \varnothing} \quad \text{(var)}$$

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The alternative type rules are theoretically nice but not algorithmic

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How do I choose which specialization to use in a derivation?

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How do I choose which specialization to use in a derivation?

Constraints allow us to determine which specializations we should use after the fact

Summary

The **principle type** of an expression is the most general type we could give it

Specialization defines a partial ordering on type schemes from most to least general

Our unification algorithm gives us a most general unifier, which will always give us the principle type of an expression