CS460: Intro to Database Systems

Class 14: Log-Structured-Merge Trees

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https://midas.bu.edu/classes/CS460/

Useful when?

- Massive dataset
- Rapid updates/insertions
- Fast lookups

LSM-trees are for you.

Why now?

Patrick O'Neil UMass Boston



Invented in 1996





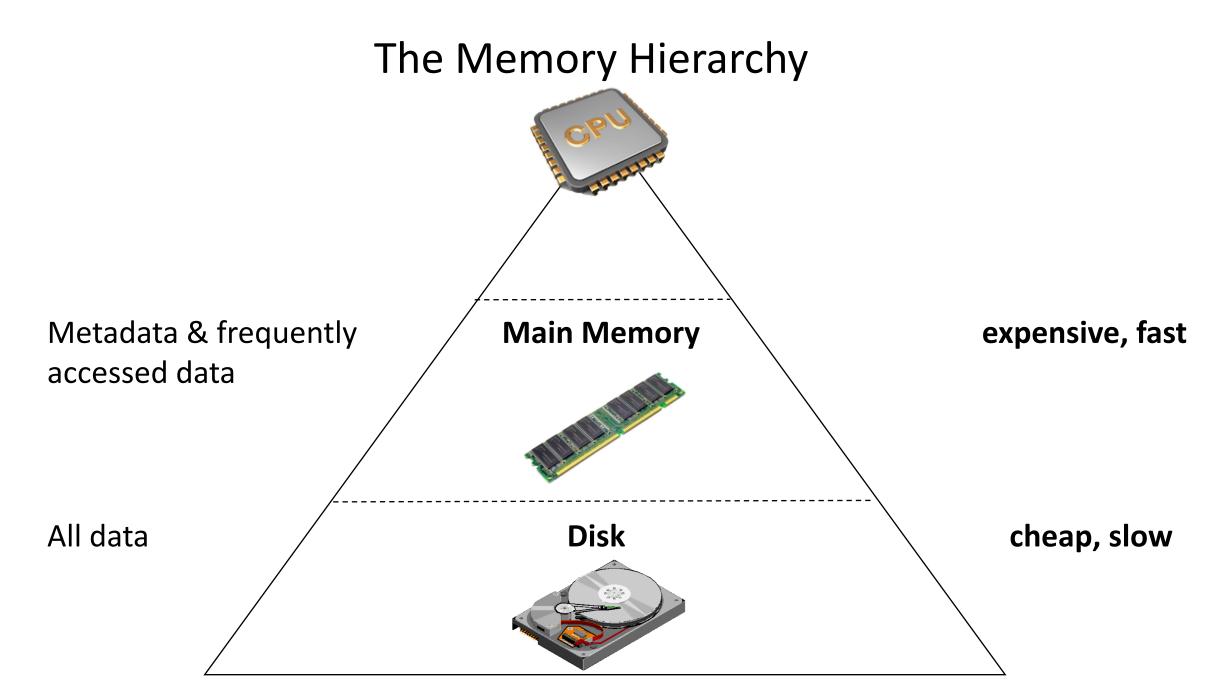
1980 1990 2000 2010

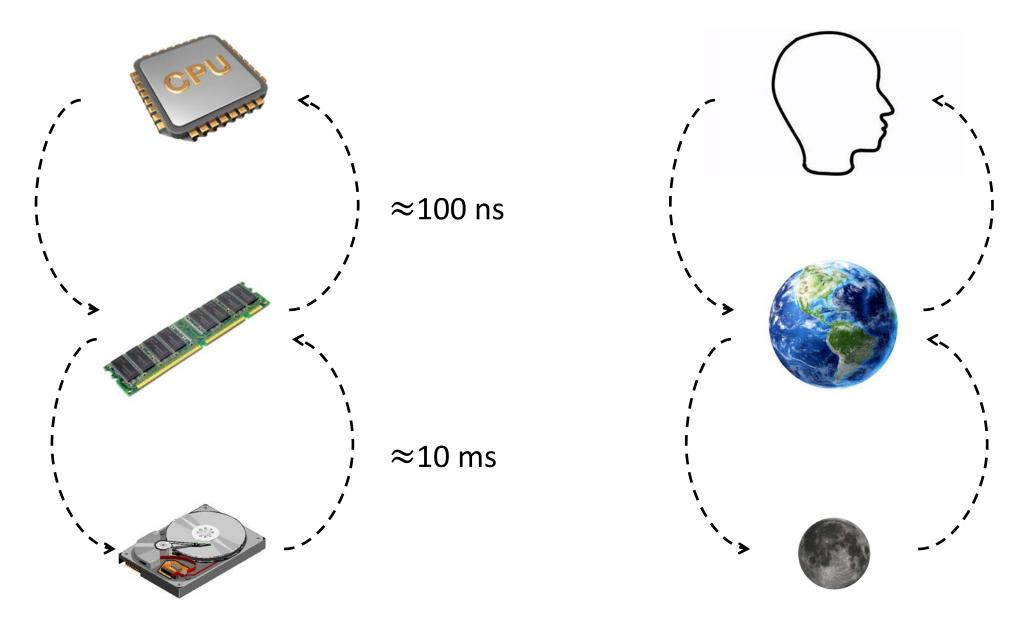
Time

Outline

- 1. Storage devices
- 2. Indexing problem & basic solutions
- 3. Basic LSM-trees
- 4. Leveled LSM-trees
- 5. Tiered LSM-trees
- 6. Bloom filters

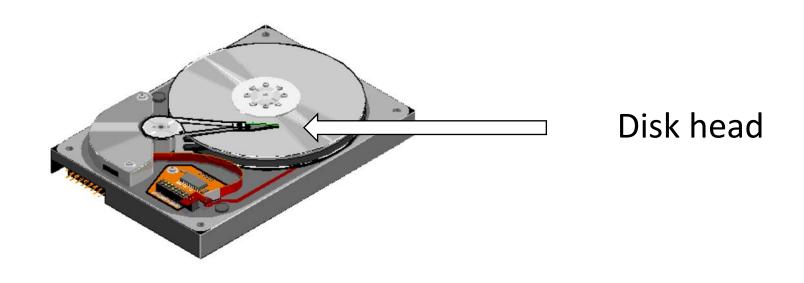
Storage devices





≈5-6 order of magnitude difference

Why is disk slow?



Random access is slow

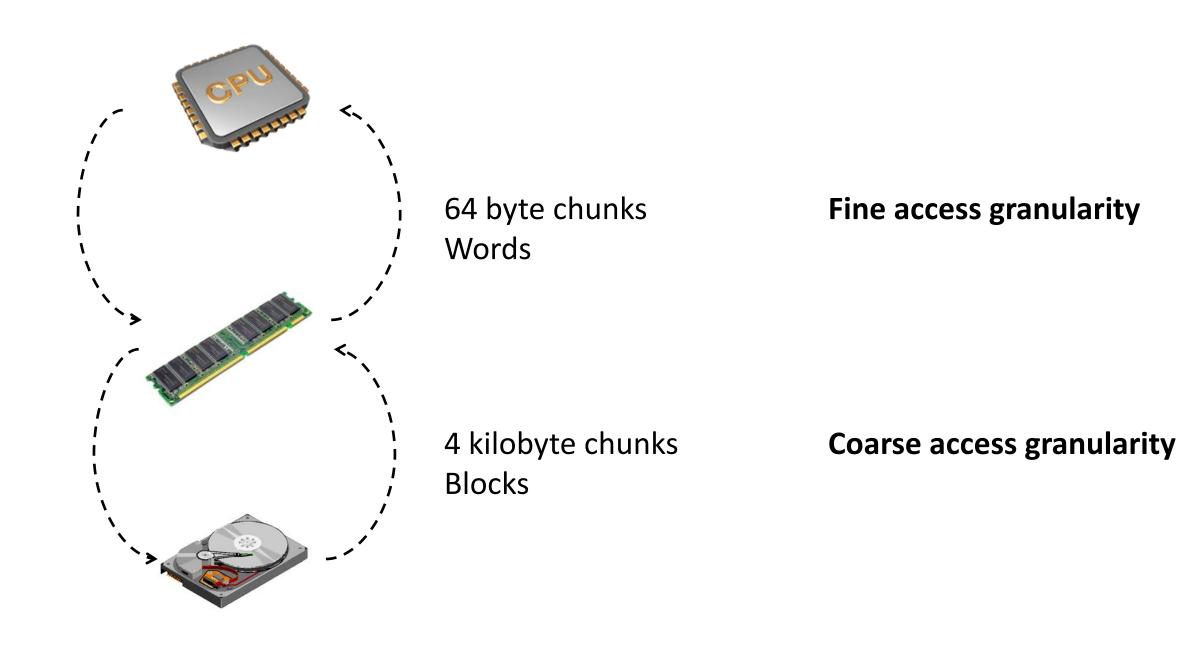
Sequential access is faster

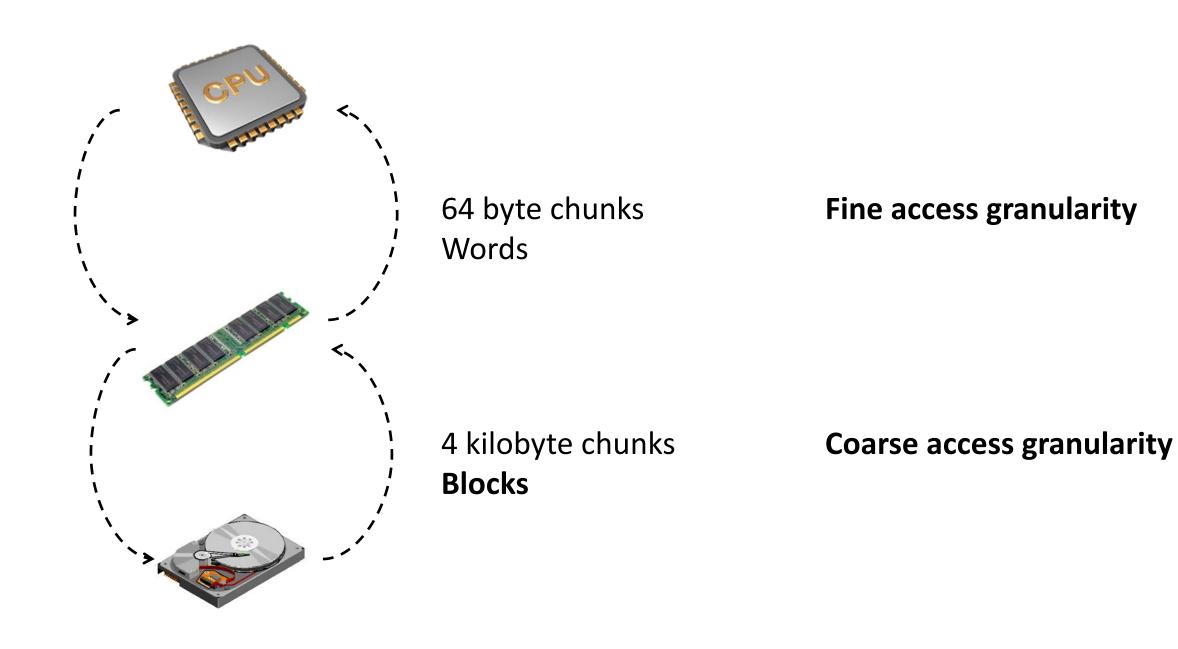
 \Rightarrow

move disk head



let disk spin





Outline

- 1. Storage devices
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- 3. Basic LSM-trees
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Indexing Problem & Basic Solutions

Indexing Problem



names phone numbers

Structure on disk?

Lookup cost?

Insertion cost?



Compare and contrast data structures.

What to use when?

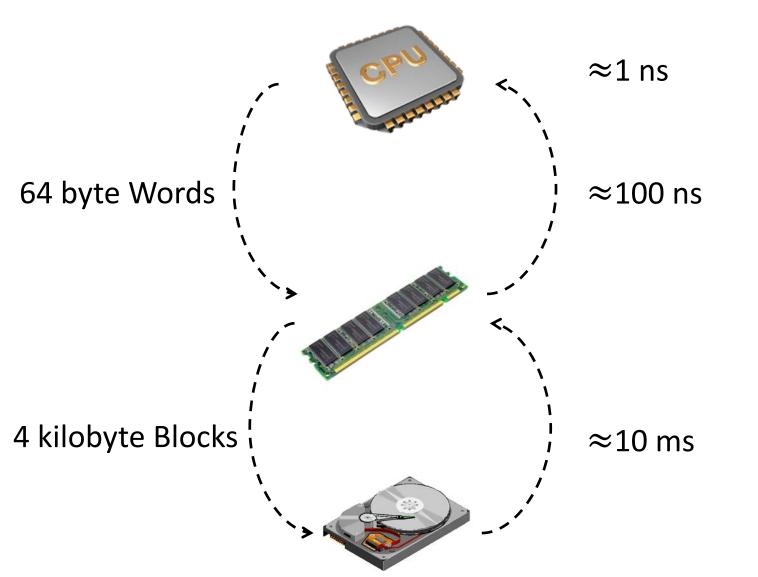
Data Structure	Lookup cost	Insertion cost
Sorted array		
Log		
B-tree		
Basic LSM-tree		
Leveled LSM-tree		
Tiered LSM-tree		

Compare and contrast data structures.

What to use when?

Data Structure	Lookup cost	Insertion cost
Sorted array		
Log		
B-tree		
Basic LSM-tree		
Leveled LSM-tree		
Tiered LSM-tree		

Modeling Performance



Measure bottleneck:

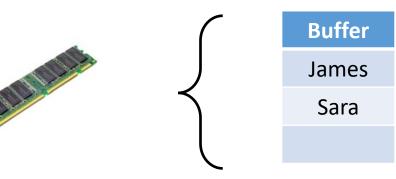
Number of block reads/writes (I/O)

Sorted Array

N entries

B entries fit into a disk block

Array spans **N/B** disk blocks



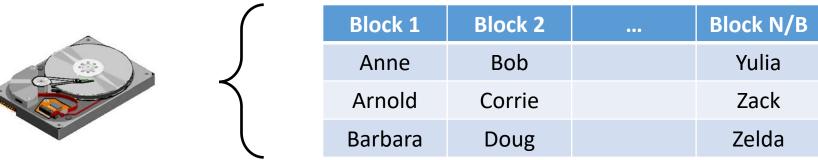
Lookup method & cost?

Binary search: $O\left(\log_2\left(\frac{N}{R}\right)\right)$

Insertion cost?

Push entries: $O\left(\frac{1}{B} \cdot \frac{N}{B}\right)$ I/Os

Array size	Pointer



	Lookup cost	Insertion cost
Sorted array	$O(\log_2(N/B))$	$O(N/B^2)$
Log		
B-tree		
Basic LSM-tree		
Leveled LSM-tree		
Tiered LSM-tree		

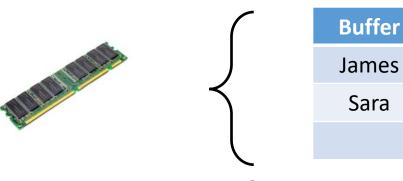
	Lookup cost	Insertion cost
Sorted array	$O(\log_2(N/B))$	$O(N/B^2)$
Log		
B-tree		
Basic LSM-tree		
Leveled LSM-tree		
Tiered LSM-tree		

Log (append-only array)

N entries

B entries fit into a disk block

Array spans **N/B** disk blocks



Lookup method & cost?

Scan: $O\left(\frac{N}{B}\right)$

Insertion cost?

Append: $O\left(\frac{1}{B}\right)$

Array size	Pointer
	ı

Block 1	Block 2	•••	Block N/B
Doug	Yulia		Anne
Zelda	Zack		Bob
Arnold	Barbara		Corrie



	Lookup cost	Insertion cost
Sorted array	$O(\log_2(N/B))$	$O(N/B^2)$
Log	O(N/B)	O(1/B)
B-tree		
Basic LSM-tree		
Leveled LSM-tree		
Tiered LSM-tree		

	Lookup cost	Insertion cost
Sorted array	$O(\log_2(N/B))$	$O(N/B^2)$
Log	O(N/B)	O(1/B)
B-tree		
Basic LSM-tree		
Leveled LSM-tree		
Tiered LSM-tree		

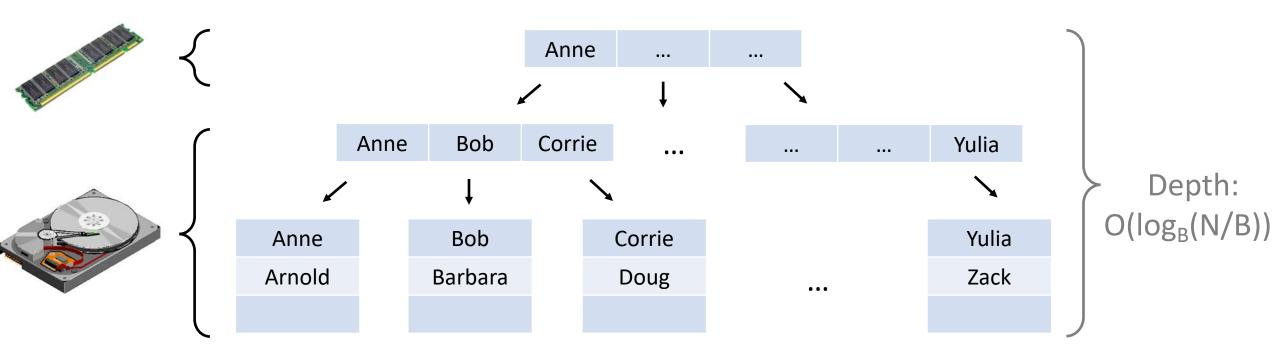
B-tree

Lookup method & cost?

Tree search: $O\left(\log_B\left(\frac{N}{B}\right)\right)$

Insertion method & cost?

Tree search & append: $O\left(\log_B\left(\frac{N}{B}\right)\right)$



	Lookup cost	Insertion cost
Sorted array	$O(\log_2(N/B))$	$O(N/B^2)$
Log	O(N/B)	O(1/B)
B-tree	$O(\log_B(N/B))$	$O(\log_B(N/B))$
Basic LSM-tree		
Leveled LSM-tree		
Tiered LSM-tree		

B-trees

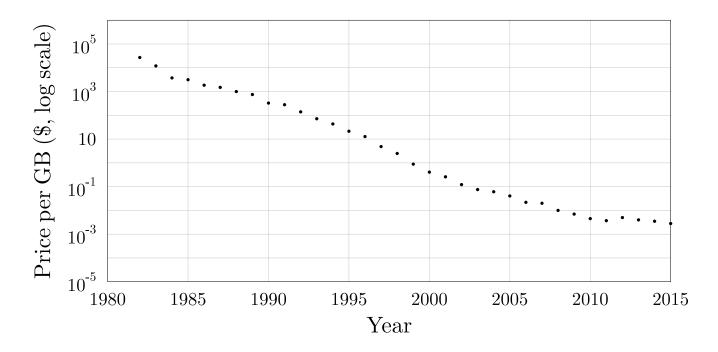


"It could be said that the world's information is at our fingertips because of B-trees"

Goetz Graefe Microsoft, HP Fellow, now Google ACM Software System Award

B-trees are no longer sufficient

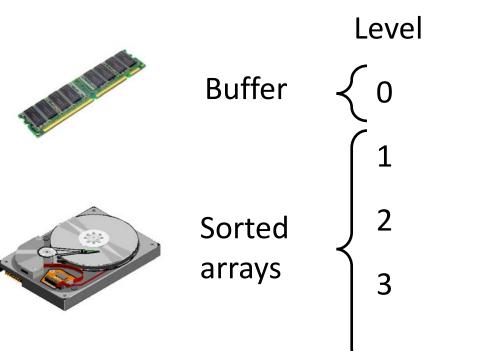
Cheaper to store data
Workloads more insert-intensive
We need better insert-performance.



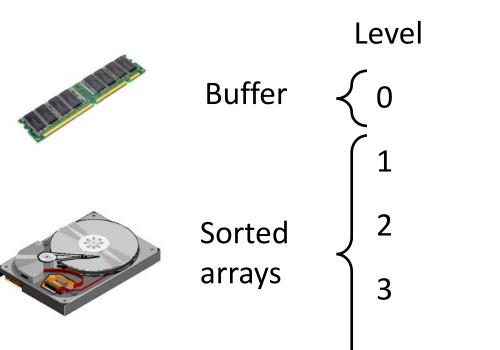
Goal to combine

sub-constant insertion cost logarithmic lookup cost

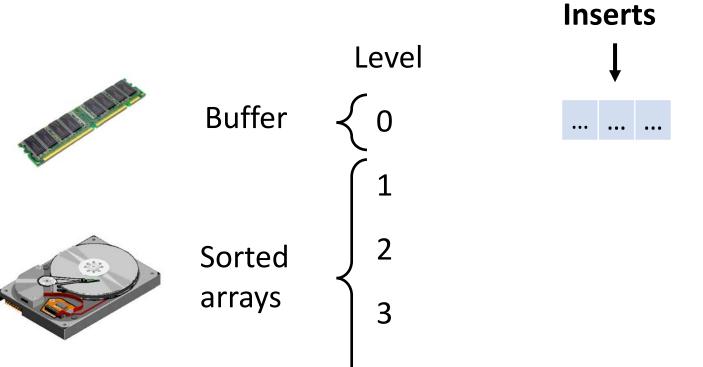
	Lookup cost	Insertion cost
Sorted array	$O(\log_2(N/B))$	O(N/B ²)
Log	O(N/B)	O(1/B)
B-tree	O(log _B (N/B))	$O(log_B(N/B))$
Basic LSM-tree		
Leveled LSM-tree		
Tiered LSM-tree		



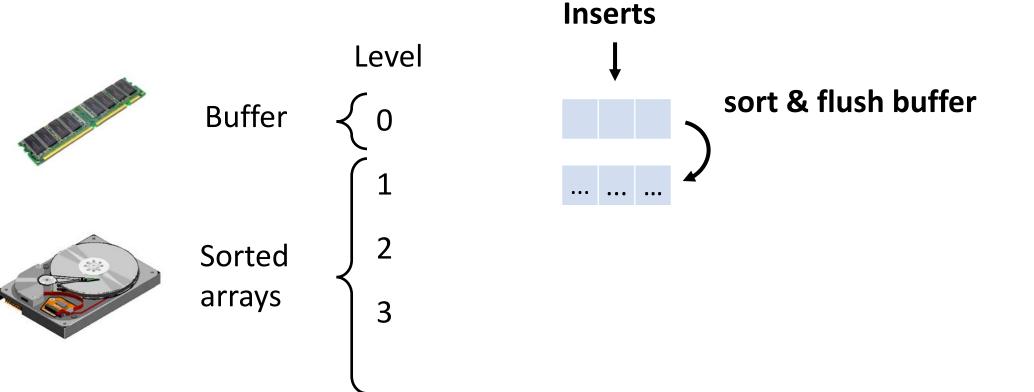
Design principle #1:



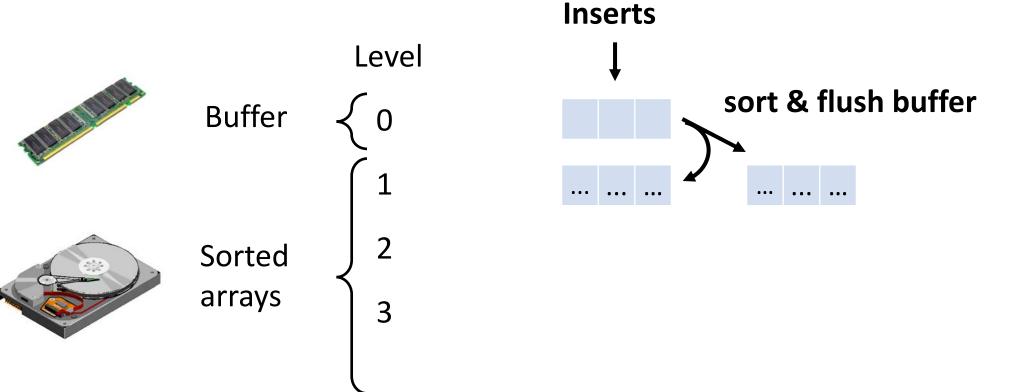
Design principle #1:



Design principle #1:



Design principle #1:

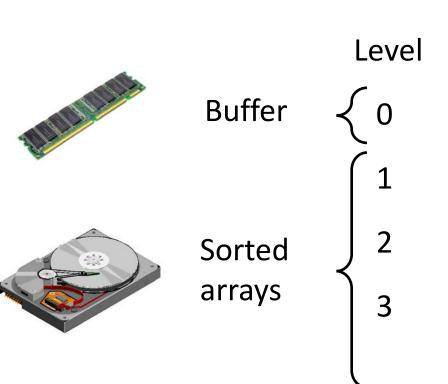


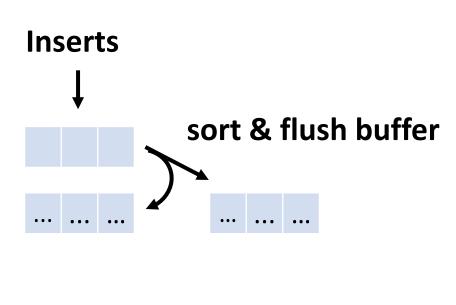
Design principle #1:

optimize for insertions by buffering

Design principle #2:

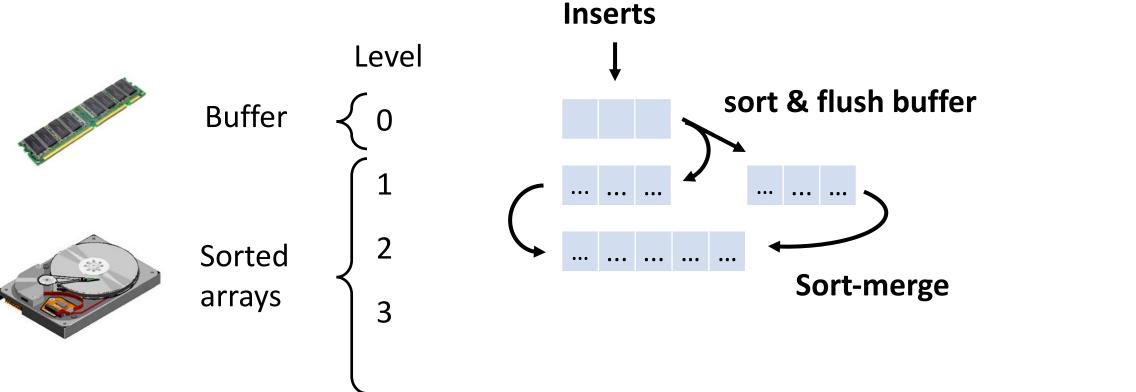
optimize for lookups by sort-merging arrays





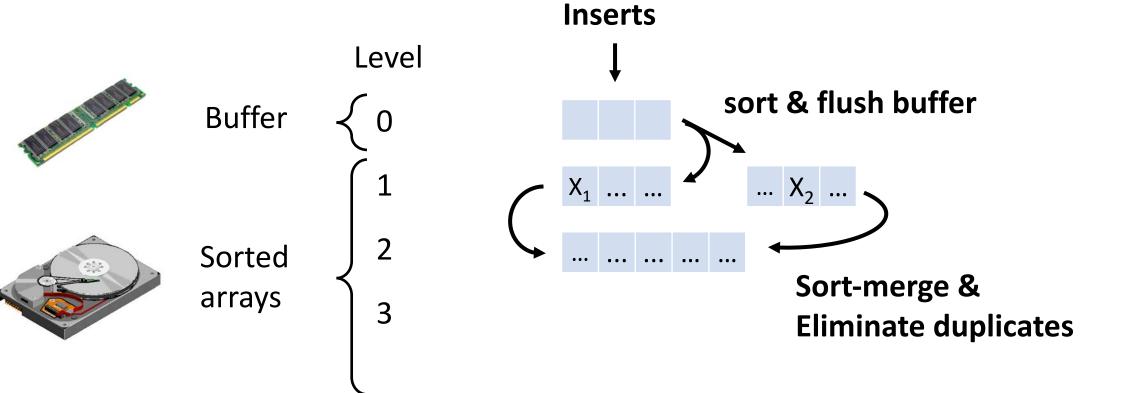
Design principle #1: optimize for insertions by buffering

Design principle #2: optimize for lookups by sort-merging arrays



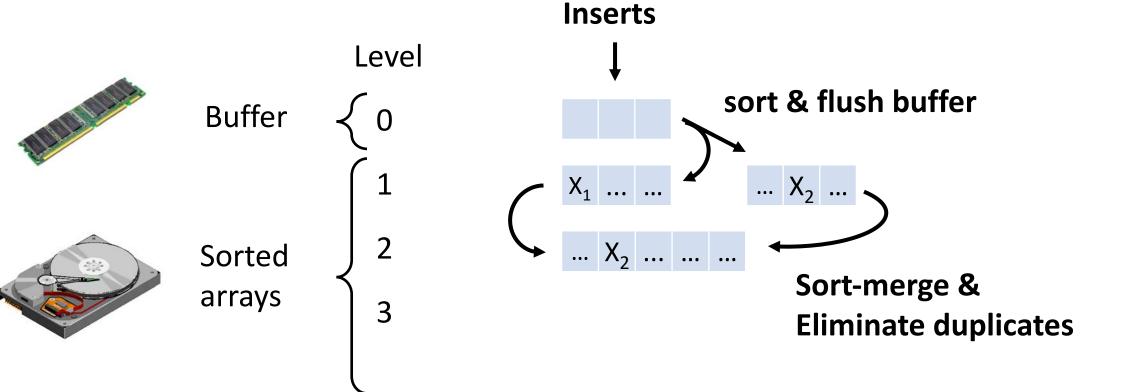
Design principle #1: optimize for insertions by buffering

Design principle #2: optimize for lookups by sort-merging arrays



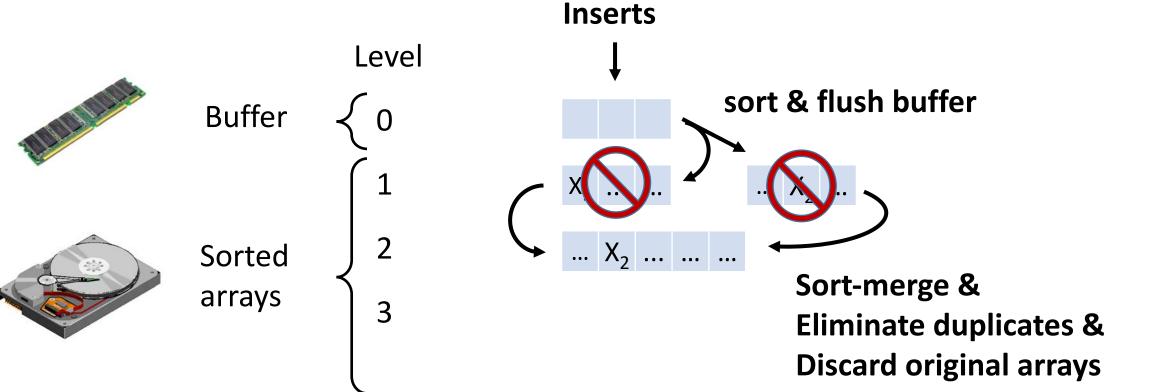
Design principle #1: optimize for insertions by buffering

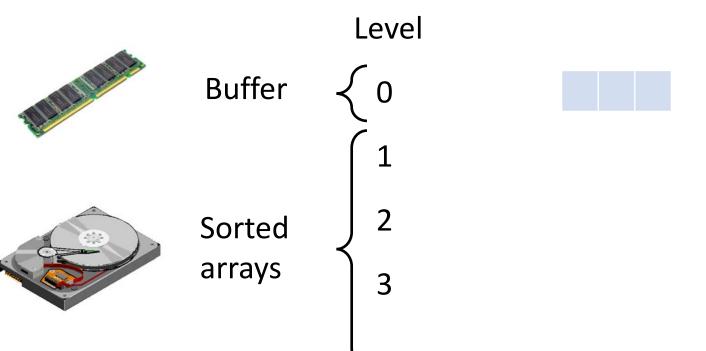
Design principle #2: optimize for lookups by sort-merging arrays

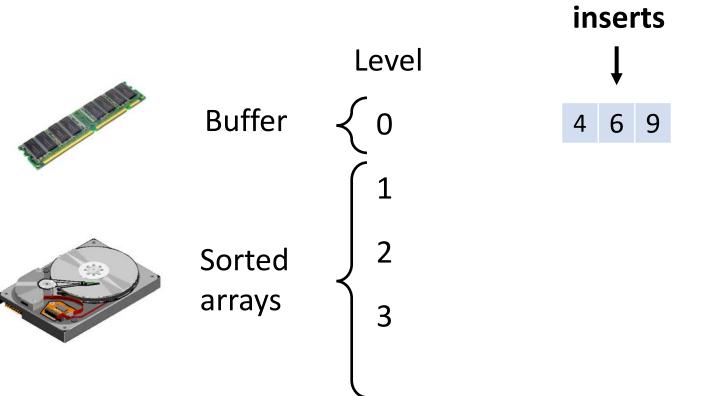


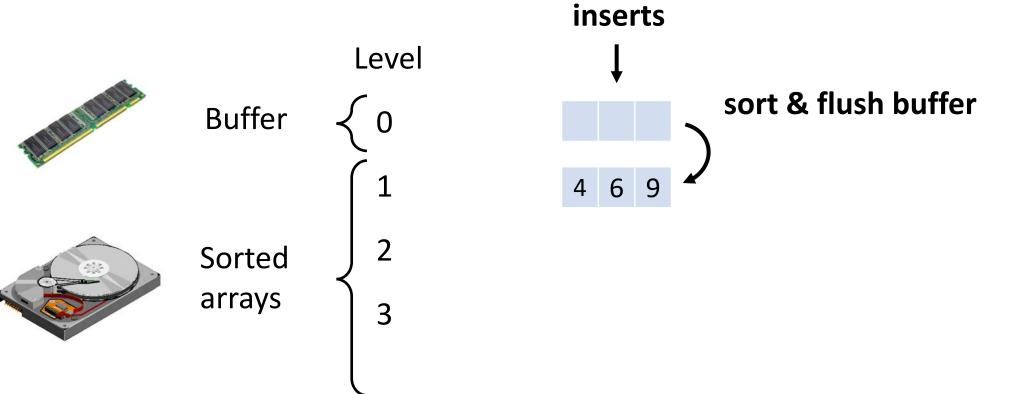
Design principle #1: optimize for insertions by buffering

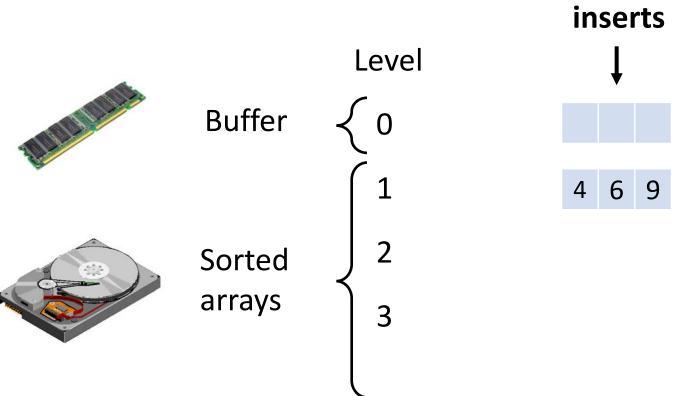
Design principle #2: optimize for lookups by sort-merging arrays

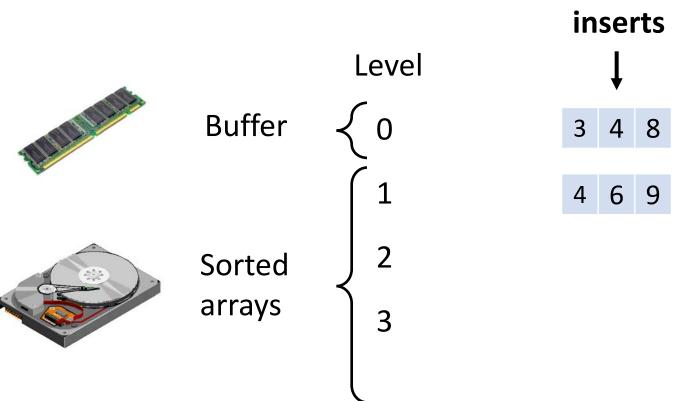


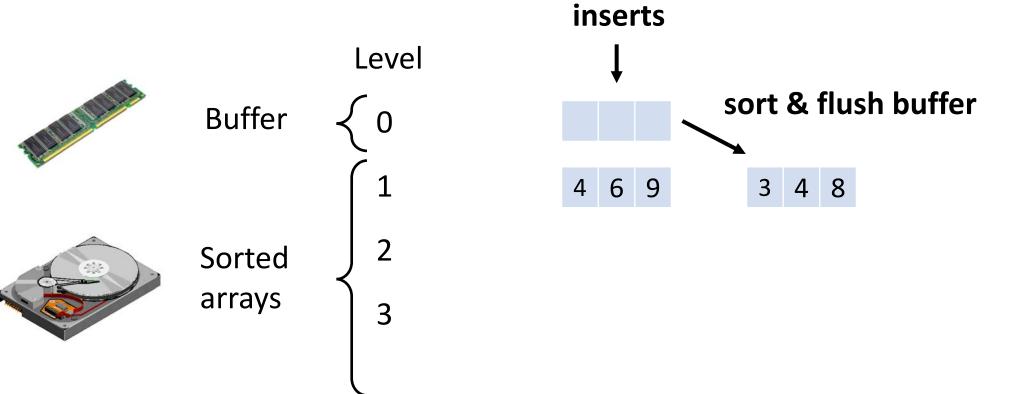


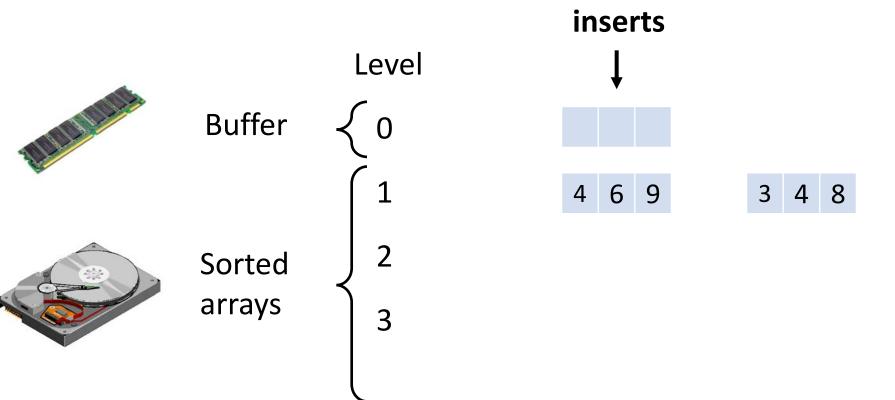


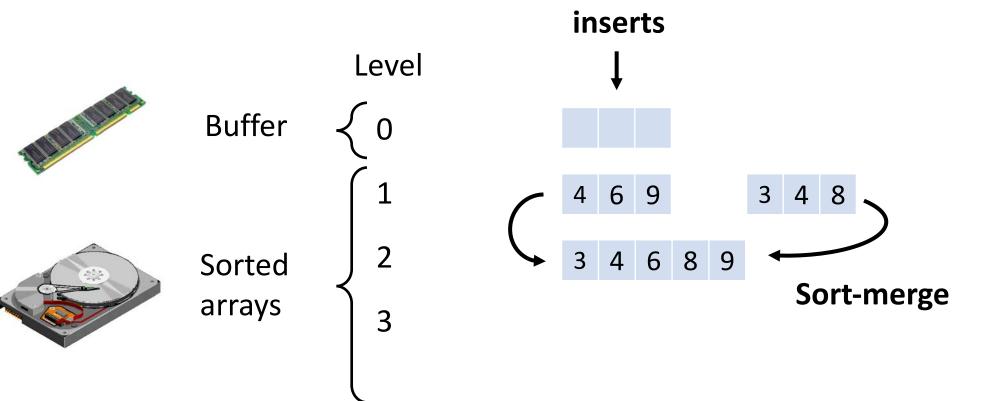


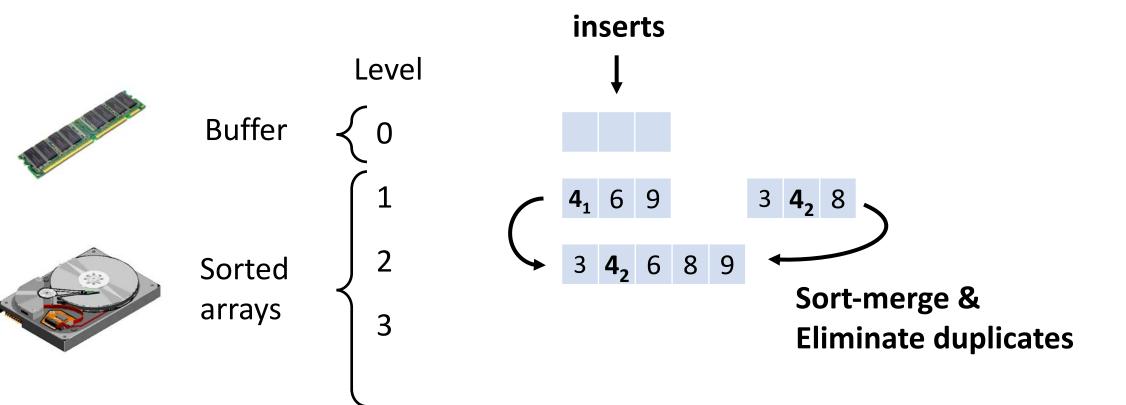


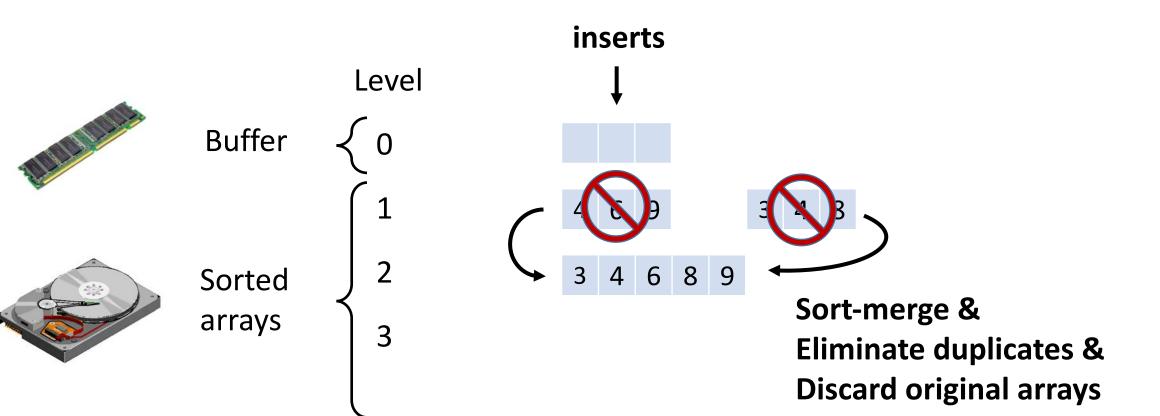






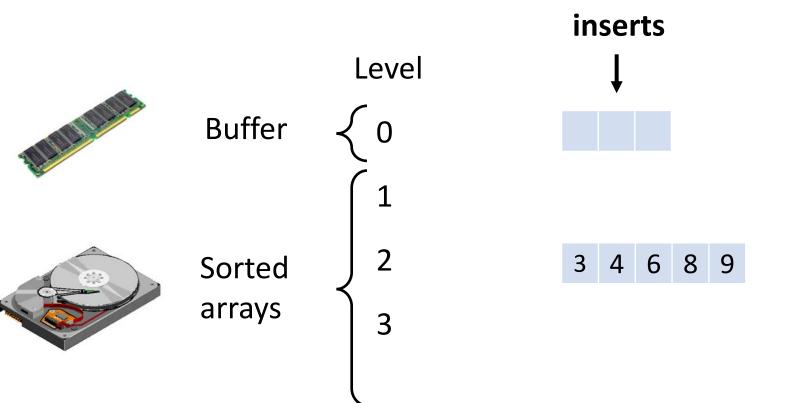


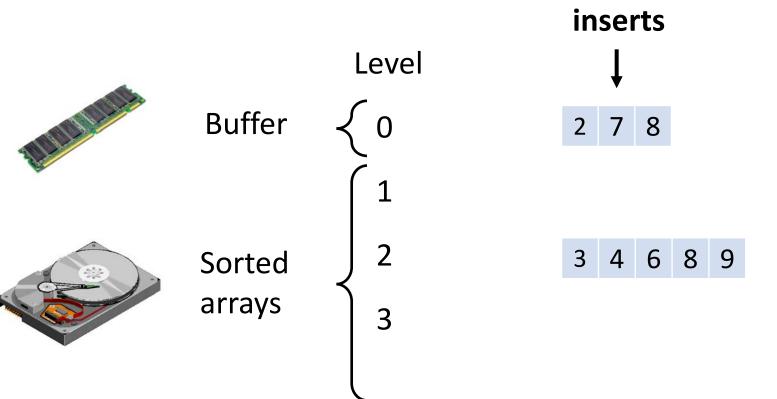


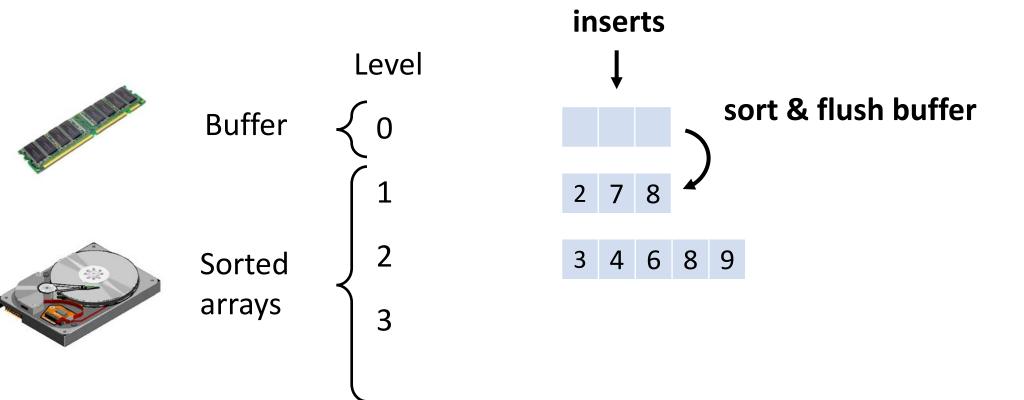


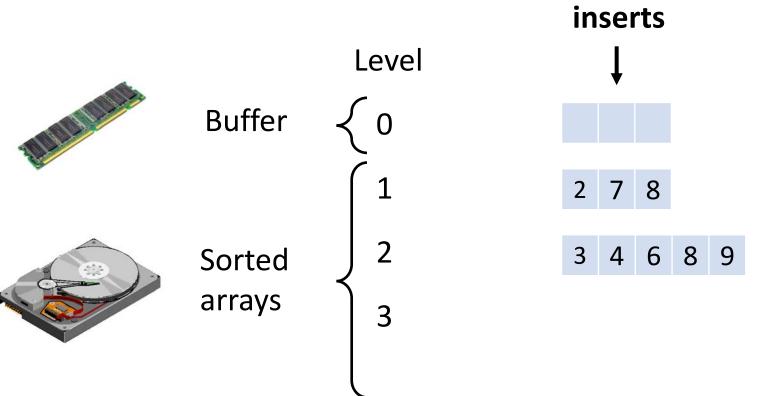




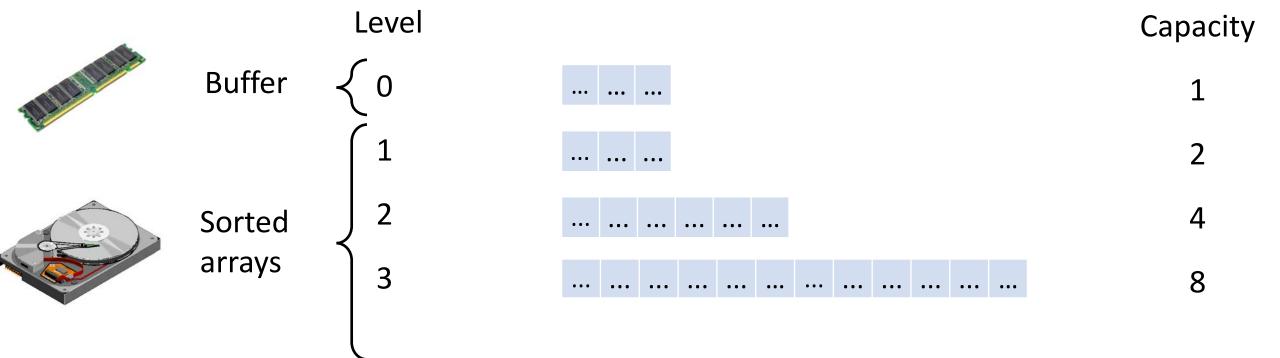








Levels have exponentially increasing capacities.



Basic LSM-tree – Lookup cost

Lookup method?

How?

Lookup cost?

Search youngest to oldest.

Binary search.

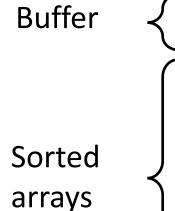
$$O\left(\log_2\left(\frac{N}{B}\right)\right)$$

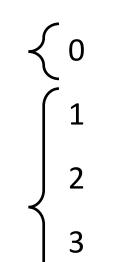
$$O\left(\log_2\left(\frac{N}{B}\right)\right)$$

$$O\left(\log_2\left(\frac{N}{B}\right)^2\right)$$

Capacity







Level



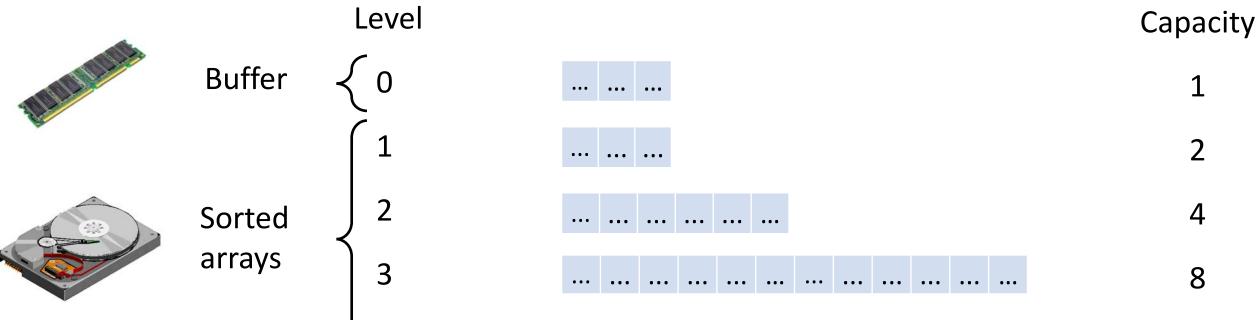
Basic LSM-tree – Insertion cost

How many times is each entry copied?

What is the price of each copy?

Total insert cost?

$O\left(\log_2\right)$	$\left(\frac{N}{B}\right)$
$O\left(\frac{1}{B}\right)$	· · ·
$O\left(\frac{1}{R} \cdot \log \frac{1}{R}\right)$	$\log_2\left(\frac{N}{R}\right)$



Results Catalogue

	Lookup cost	Insertion cost
Sorted array	$O(\log_2(N/B))$	O(N/B)
Log	O(N/B)	O(1/B)
B-tree	$O(log_B(N/B))$	$O(log_B(N/B))$
Basic LSM-tree	$O(\log_2(N/B)^2)$	$O(1/B \cdot \log_2(N/B))$
Leveled LSM-tree		
Tiered LSM-tree		

Results Catalogue

Better insert cost and worst lookup cost compared with B-trees

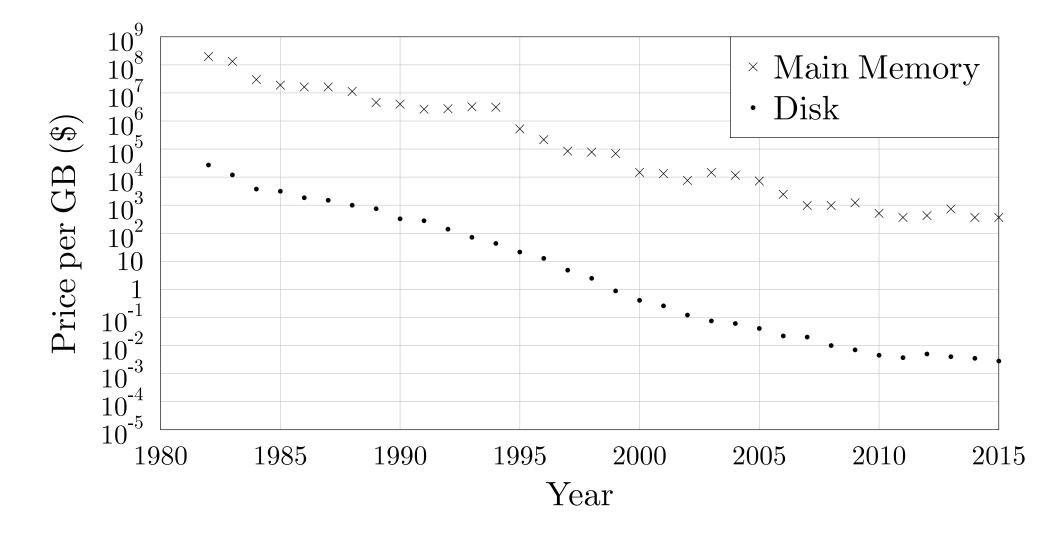
	Lookup cost	Insertion cost
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Log	O(N/B)	O(1/B)
B-tree	$O(\log_B(N/B))$	$O(\log_B(N/B))$
Basic LSM-tree	$O(\log_2(N/B)^2)$	$O(1/B \cdot \log_2(N/B))$
Leveled LSM-tree		
Tiered LSM-tree		

Results Catalogue

Better insert cost and worst lookup cost compared with B-trees Can we improve lookup cost?

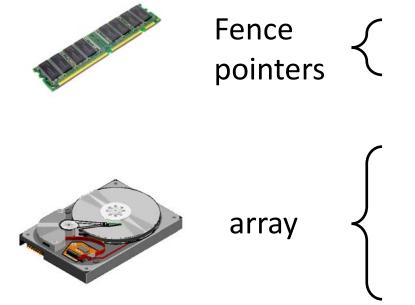
	Lookup cost	Insertion cost
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Log	O(N/B)	O(1/B)
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Leveled LSM-tree		
Tiered LSM-tree		

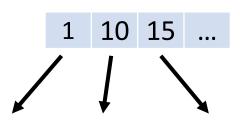
Declining Main Memory Cost



Declining Main Memory Cost

Store a fence pointer for every block in main memory





Block 1	Block 2	Block 3	•••
1	10	15	•••
3	11	16	
6	13	18	•••

	Lookup cost	Insertion cost
Sorted array	$O(\log_2(N/B))$	O(N/B)
Log	O(N/B)	O(1/B)
B-tree	$O(log_B(N/B))$	$O(log_B(N/B))$
Basic LSM-tree	$O(\log_2(N/B)^2)$	$O(1/B \cdot \log_2(N/B))$
Leveled LSM-tree		
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Log	O(N/B)	O(1/B)
B-tree	$O(log_B(N/B))$	$O(log_B(N/B))$
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Leveled LSM-tree		
Tiered LSM-tree		

	Lookup cost	Insertion cost
Sorted array	O(1)	O(N/B)
Log	O(N/B)	O(1/B)
B-tree	$O(log_B(N/B))$	$O(log_B(N/B))$
Basic LSM-tree	$O(\log_2(N/B)^2)$	$O(1/B \cdot log_2(N/B))$
Leveled LSM-tree		
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	Lookup cost	Insertion cost
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Lookup cost	Insertion cost
O(1)	O(N/B)
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O(1)	O(1)
$O(\log_2(N/B)^2)$	$O(1/B \cdot \log_2(N/B))$
	O(1) O(N/B) O(1)

Lookup cost	Insertion cost
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Lookup cost	Insertion cost
O(1)	O(N/B)
O(N/B)	O(1/B)
O(1)	O(1)
$O(log_2(N/B))$	$O(1/B \cdot \log_2(N/B))$
	O(1) O(N/B) O(1)

Quick sanity check:

suppose $N = 2^{42}$

 $B = 2^{10}$

and

	Lookup cost	Insertion cost
Sorted array	O(1)	O(N/B)
Log	O(N/B)	O(1/B)
B-tree	O(1)	O(1)
Basic LSM-tree	$O(log_2(N/B))$	$O(1/B \cdot \log_2(N/B))$
Leveled LSM-tree		
Tiered LSM-tree		

Quick sanity check:

suppose $N = 2^{42}$

and

 $B = 2^{10}$

	Lookup cost	Insertion cost
Sorted array	O(1)	O(2 ³²)
Log	O(2 ³²)	O(2 ⁻¹⁰)
B-tree	O(1)	O(1)
Basic LSM-tree	O(5)	O(2 ⁻¹⁰ · 5)
Leveled LSM-tree		
Tiered LSM-tree		

Leveled LSM-tree



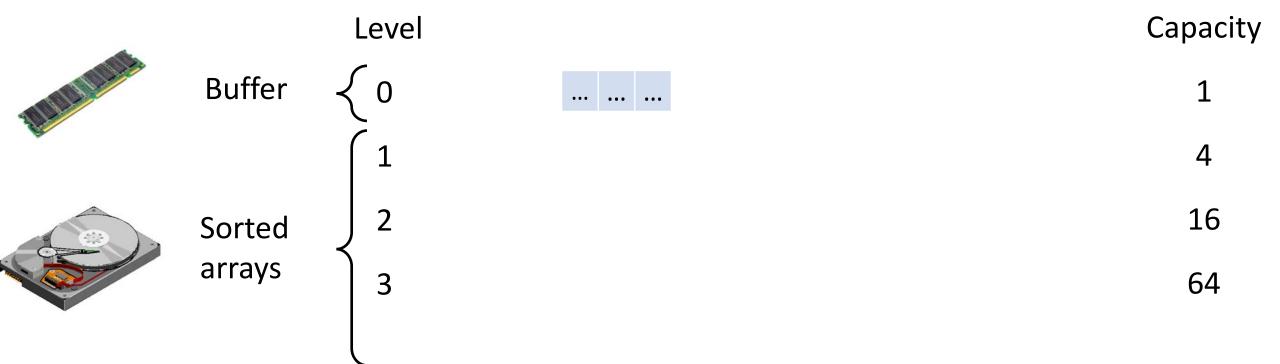


Lookup cost depends on number of levels How to reduce it?



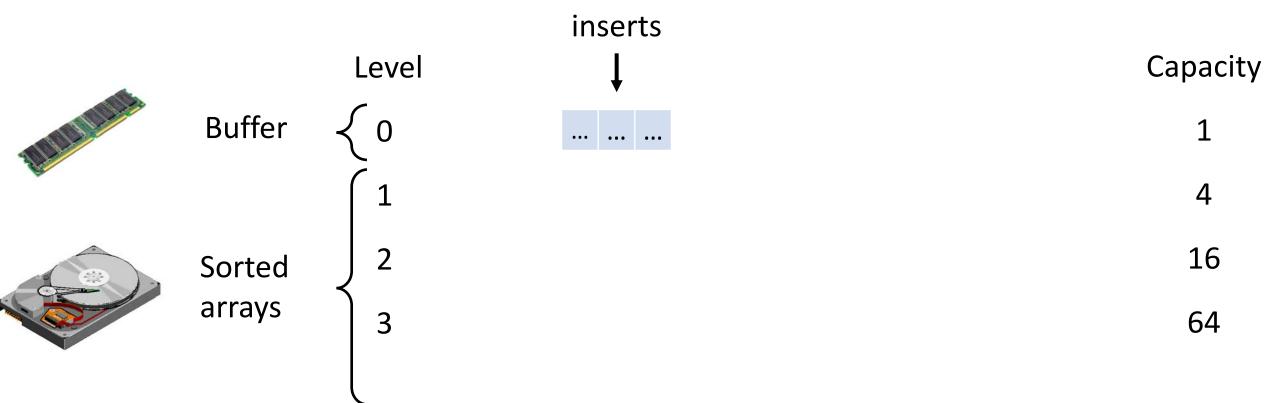
Lookup cost depends on number of levels How to reduce it?

E.g. size ratio of 4



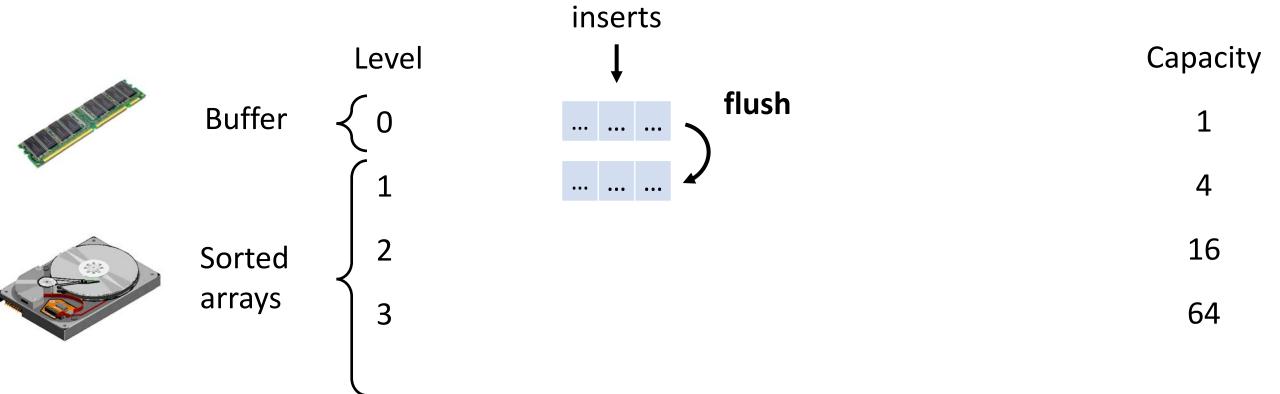
Lookup cost depends on number of levels How to reduce it?

E.g. size ratio of 4



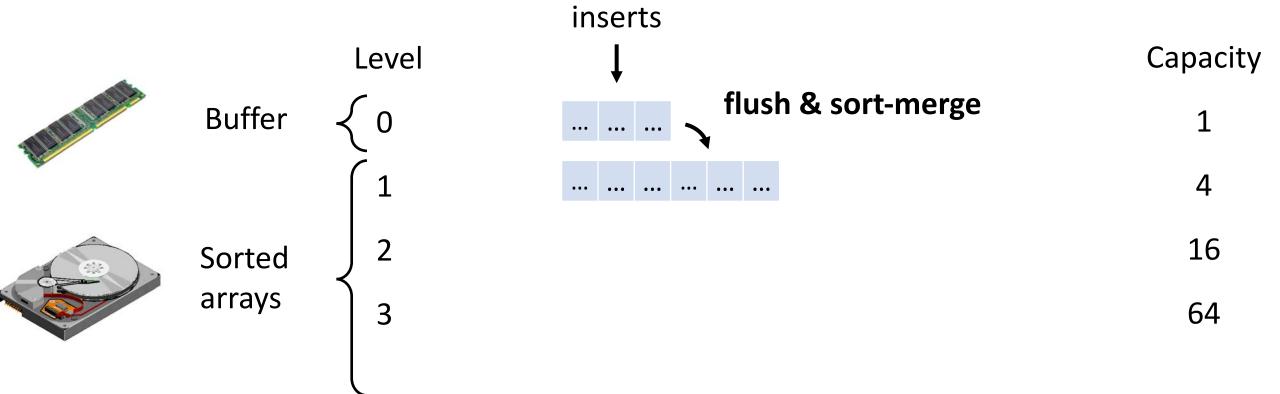
Lookup cost depends on number of levels How to reduce it?

E.g. size ratio of 4



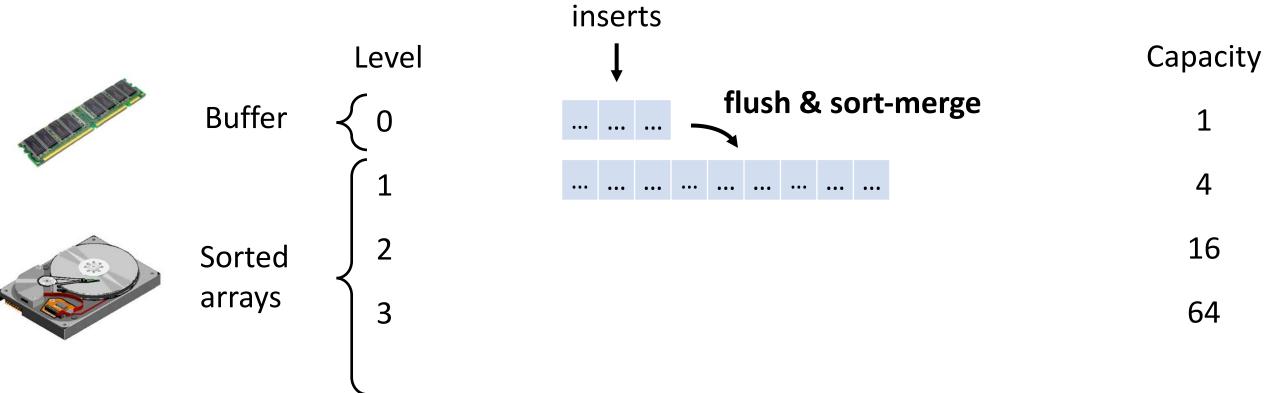
Lookup cost depends on number of levels How to reduce it?

E.g. size ratio of 4



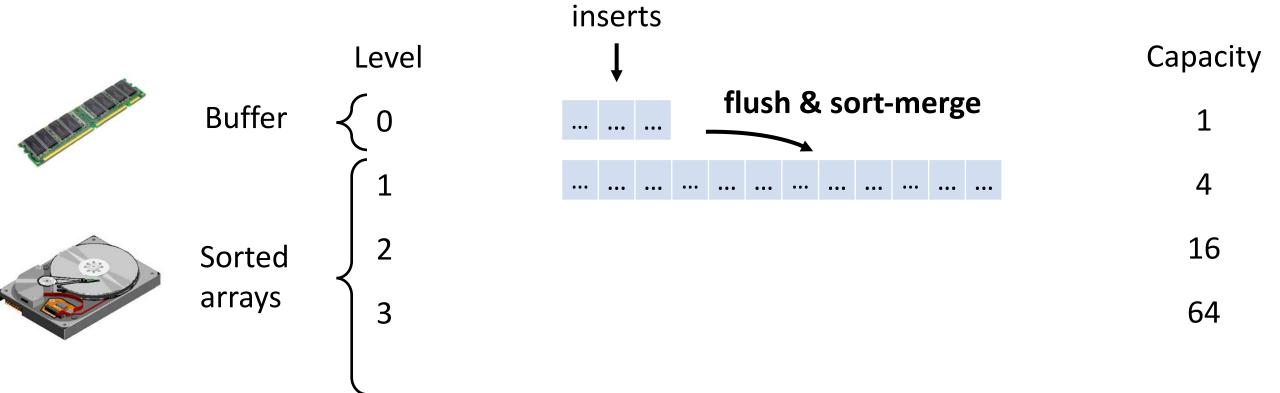
Lookup cost depends on number of levels How to reduce it?

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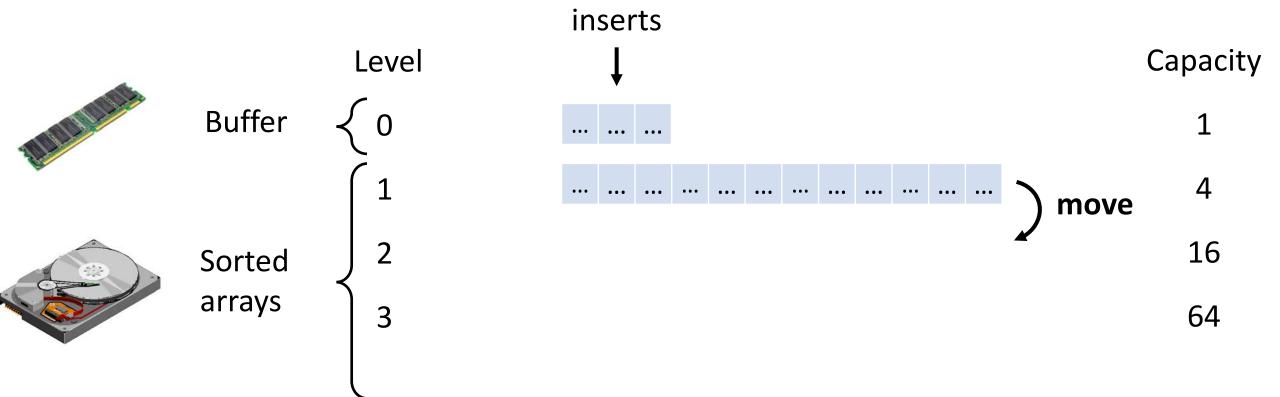
Lookup cost depends on number of levels How to reduce it?

E.g. size ratio of 4



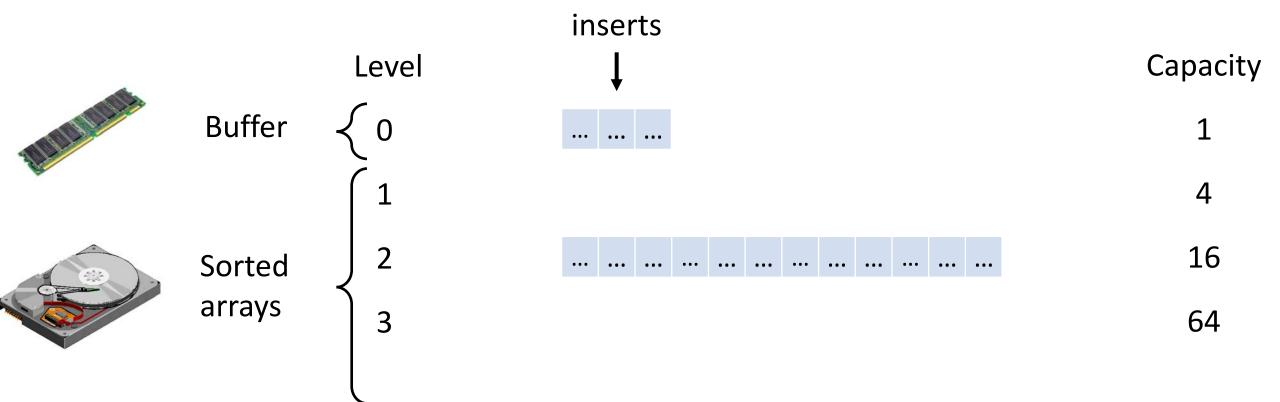
Lookup cost depends on number of levels How to reduce it?

E.g. size ratio of 4



Lookup cost depends on number of levels How to reduce it?

E.g. size ratio of 4

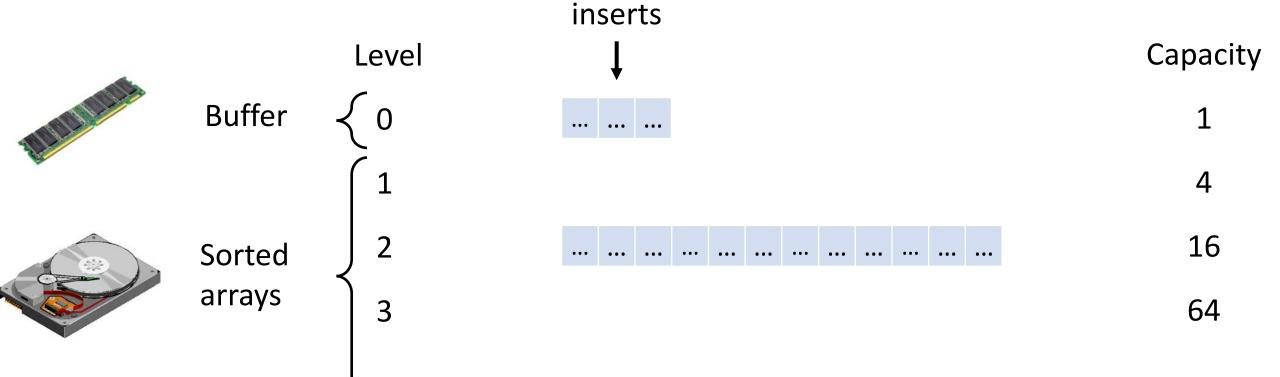


Lookup cost?

$$O\left(\log_T\left(\frac{N}{B}\right)\right)$$

Insertion cost?

$$O\left(\frac{T}{B} \cdot \log_T\left(\frac{N}{B}\right)\right)$$





Lookup cost?
$$O\left(\log_T\left(\frac{N}{B}\right)\right)$$

Insertion cost?

O
$$\left(\frac{T}{B} \cdot \log_T\left(\frac{N}{B}\right)\right)$$



What happens as we increase the size ratio T?

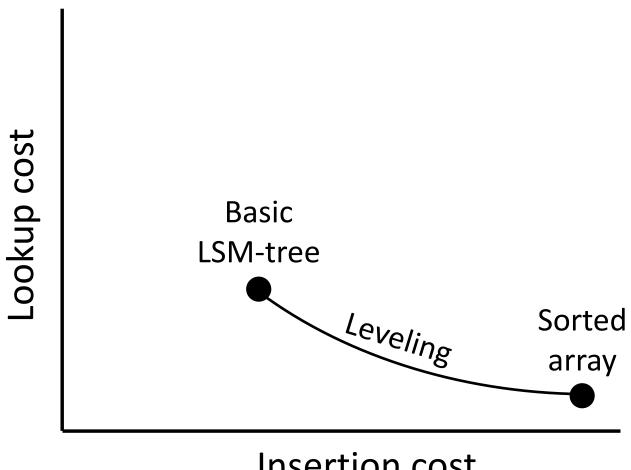
What happens when size ratio T is set to be N/B?

Lookup cost becomes:

Insert cost becomes:

$$O(N/B^2)$$

The LSM-tree becomes a sorted array!



Insertion cost

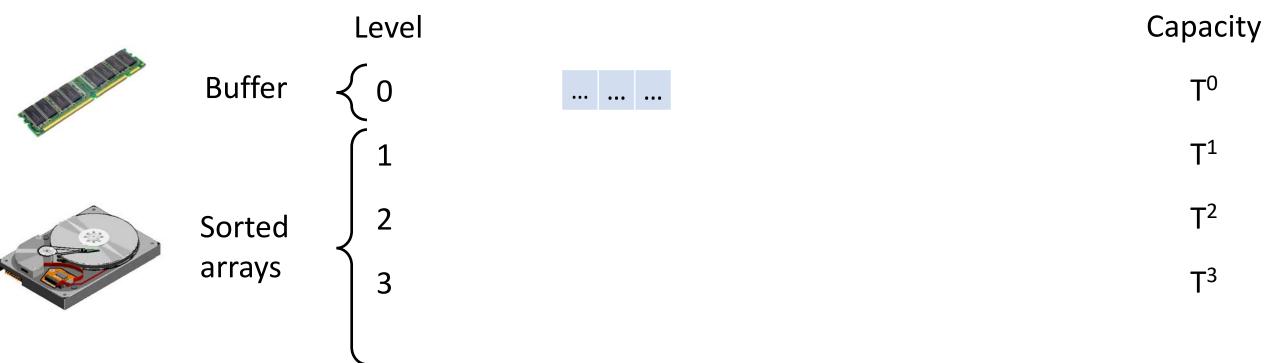
Results Catalogue – with fence pointers

	Lookup cost	Insertion cost
Sorted array	O(1)	O(N/B)
Log	O(N/B)	O(1/B)
B-tree	O(1)	O(1)
Basic LSM-tree	$O(\log_2(N/B))$	$O(1/B \cdot \log_2(N/B))$
Leveled LSM-tree	$O(log_T(N/B))$	$O(T/B \cdot log_T(N/B))$
Tiered LSM-tree		



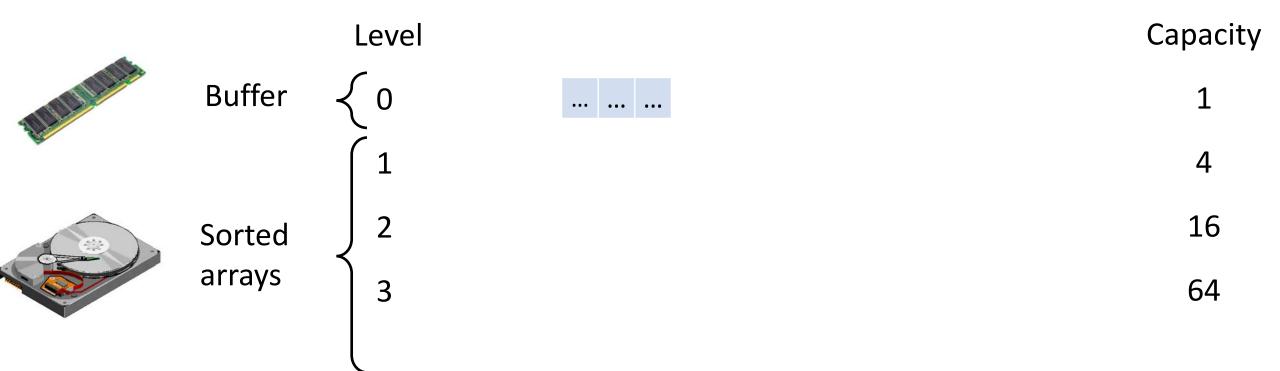


Reduce the number of levels by increasing the size ratio. Do not merge within a level.



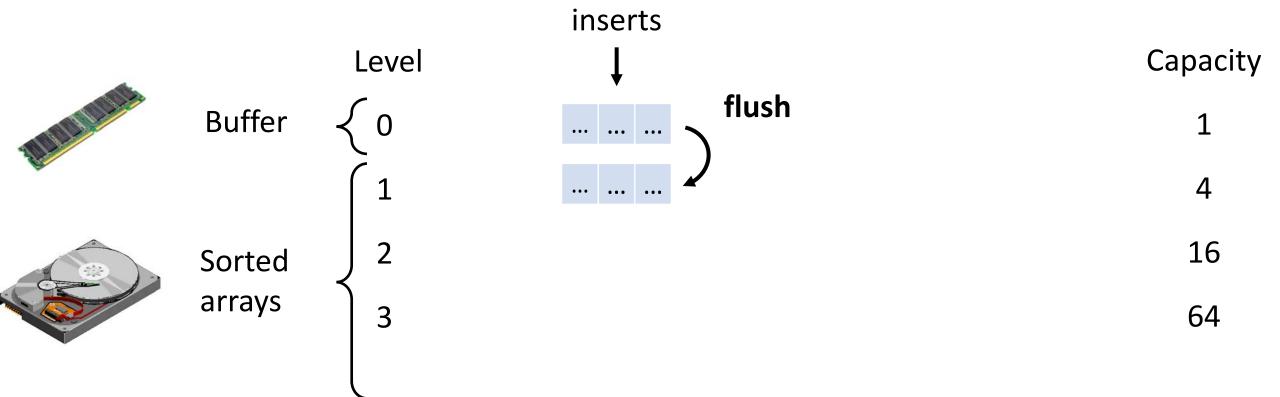
Reduce the number of levels by increasing the size ratio.

Do not merge within a level.



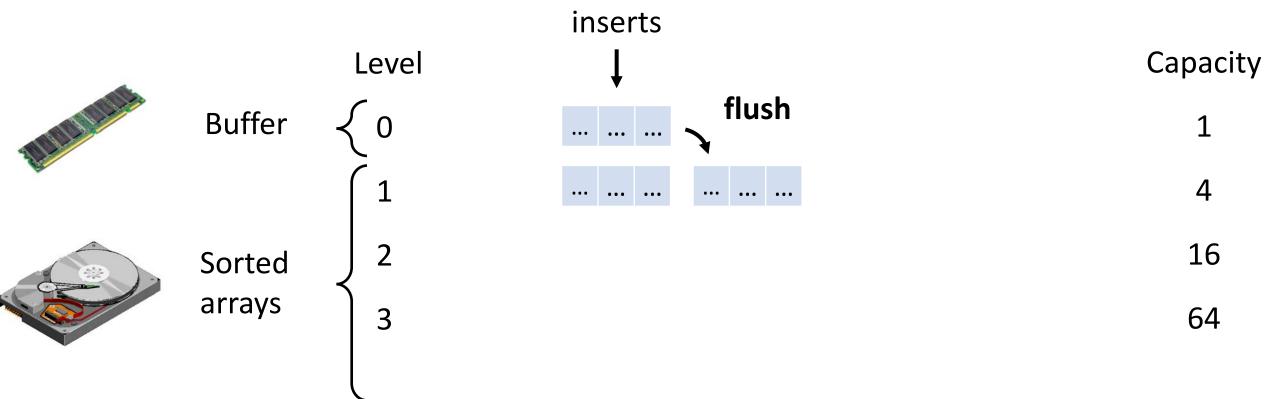
Reduce the number of levels by increasing the size ratio.

Do not merge within a level.



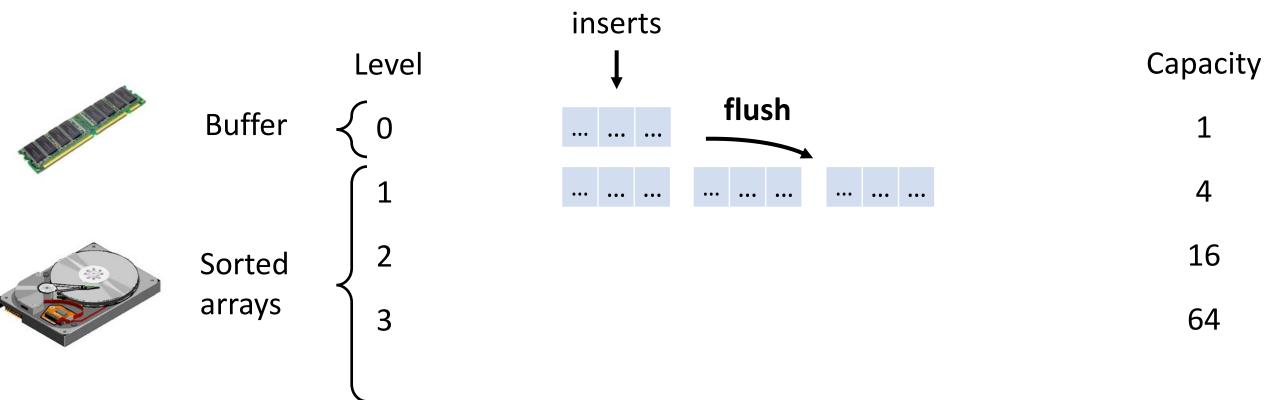
Reduce the number of levels by increasing the size ratio.

Do not merge within a level.



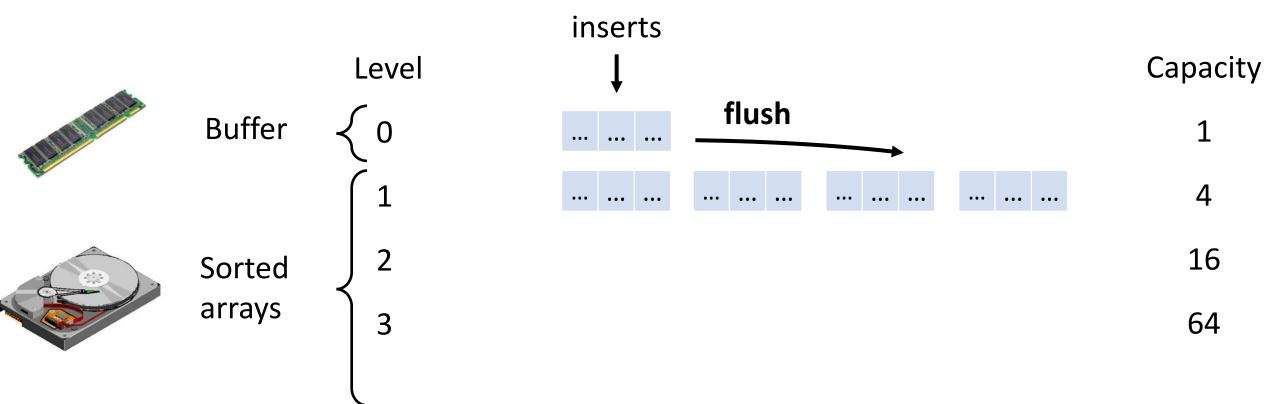
Reduce the number of levels by increasing the size ratio.

Do not merge within a level.



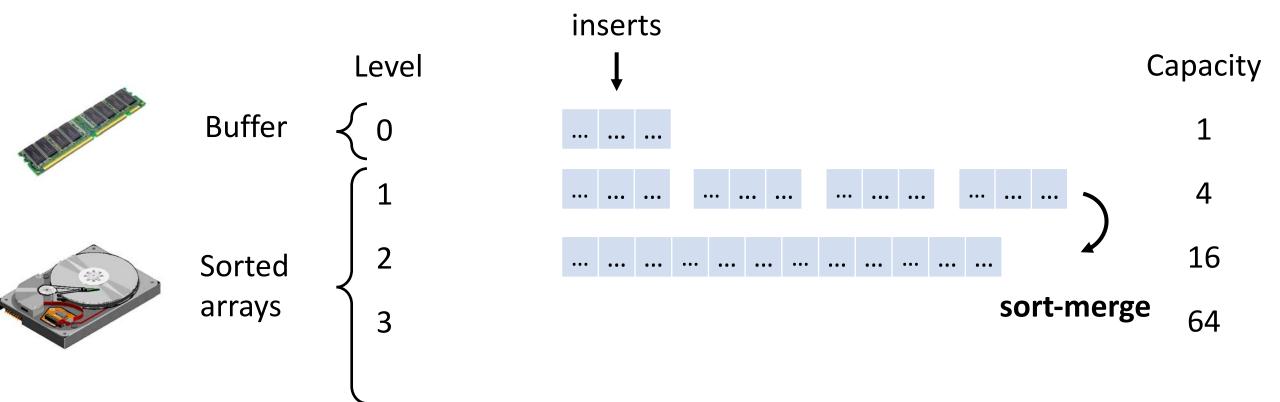
Reduce the number of levels by increasing the size ratio.

Do not merge within a level.



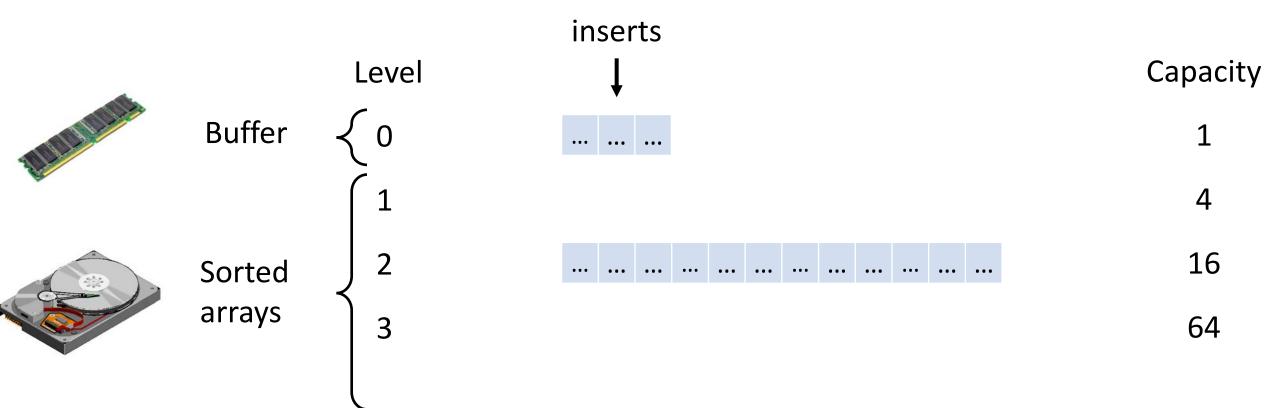
Reduce the number of levels by increasing the size ratio.

Do not merge within a level.



Reduce the number of levels by increasing the size ratio.

Do not merge within a level.

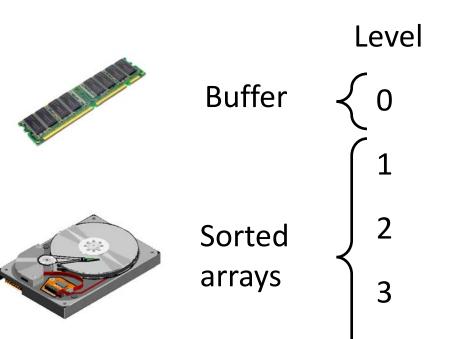


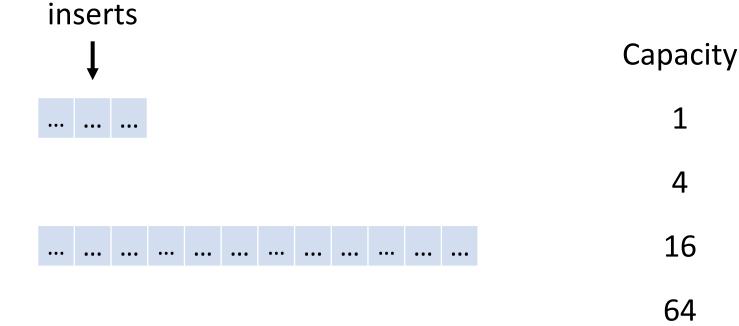
Lookup cost?

$$O\left(T \cdot \log_T\left(\frac{N}{B}\right)\right)$$

Insertion cost?

$$O\left(\frac{1}{B} \cdot \log_T\left(\frac{N}{B}\right)\right)$$





Lookup cost?
$$0\left(T \cdot \log_T\left(\frac{N}{B}\right)\right)$$

Insertion cost?

$$O\left(\frac{1}{B} \cdot \log_T\left(\frac{N}{B}\right)\right)$$



What happens as we increase the size ratio T?

What happens when size ratio T is set to be N/B?

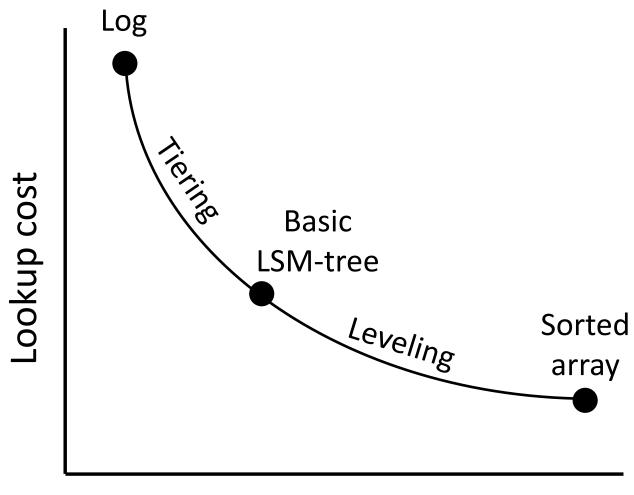
Lookup cost becomes:

O(N/B)

Insert cost becomes:

O(1/B)

The tiered LSM-tree becomes a log!

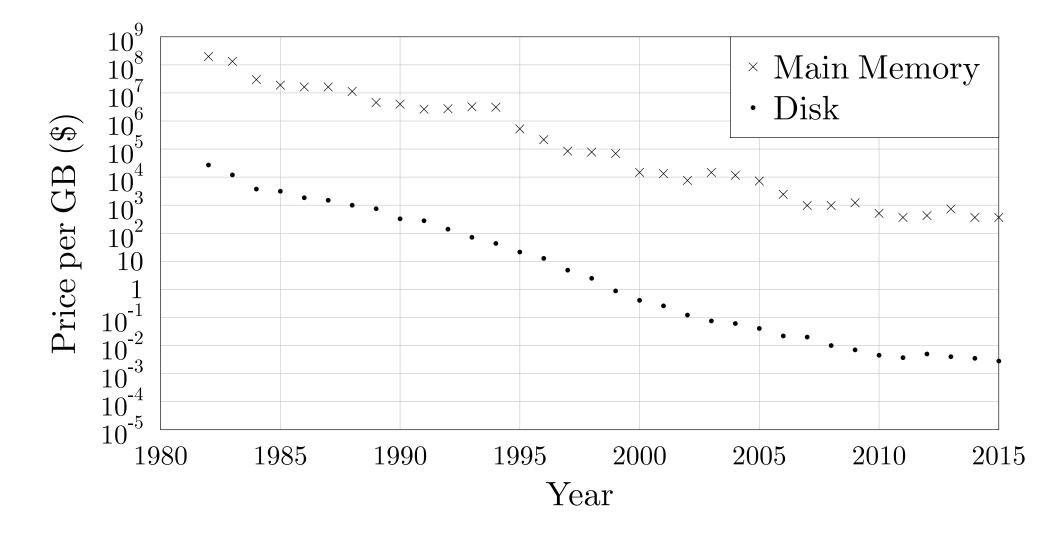


Insertion cost

Results Catalogue – with fence pointers

	Lookup cost	Insertion cost
Sorted array	O(1)	O(N/B)
Log	O(N/B)	O(1/B)
B-tree	O(1)	O(1)
Basic LSM-tree	$O(\log_2(N/B))$	$O(1/B \cdot \log_2(N/B))$
Leveled LSM-tree	$O(log_T(N/B))$	$O(T/B \cdot log_T(N/B))$
Tiered LSM-tree	$O(T \cdot log_T(N/B))$	$O(1/B \cdot log_T(N/B))$

Declining Main Memory Cost



Answers set-membership queries

Smaller than array, and stored in main memory

Purpose: avoid accessing disk if entry is not in array

Subtlety: may return false positives.

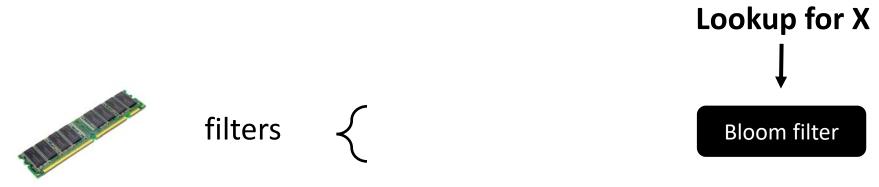


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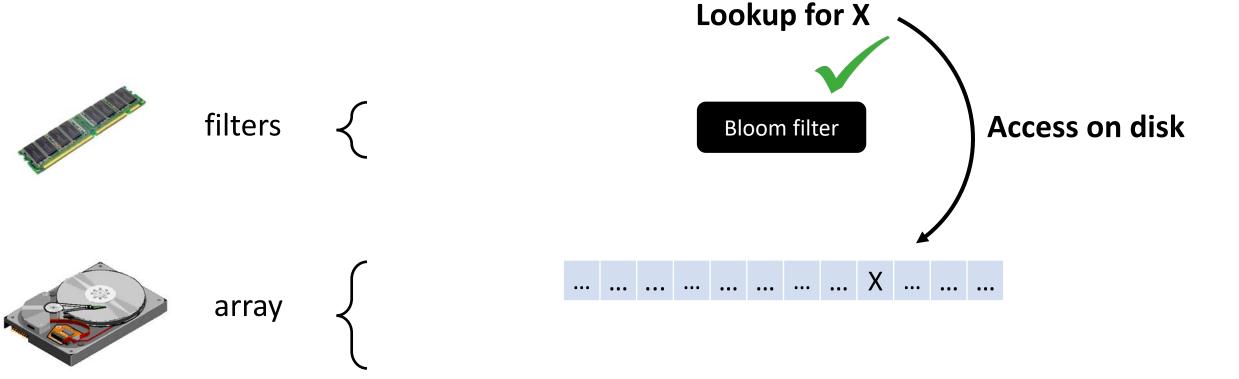


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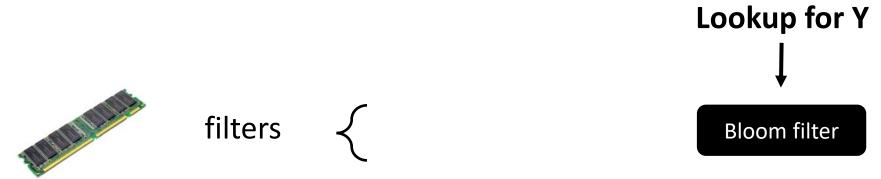


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Subtlety: may return false positives.

Lookup for Y



filters



Bloom filter







Answers set-membership queries

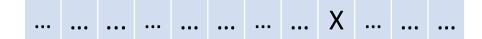
Smaller than array, and stored in main memory

Purpose: avoid accessing disk if entry is not in array

Subtlety: may return false positives.





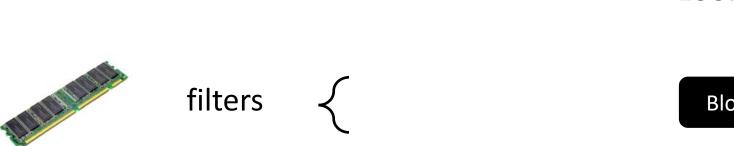


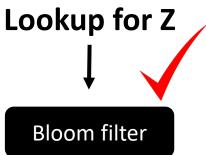
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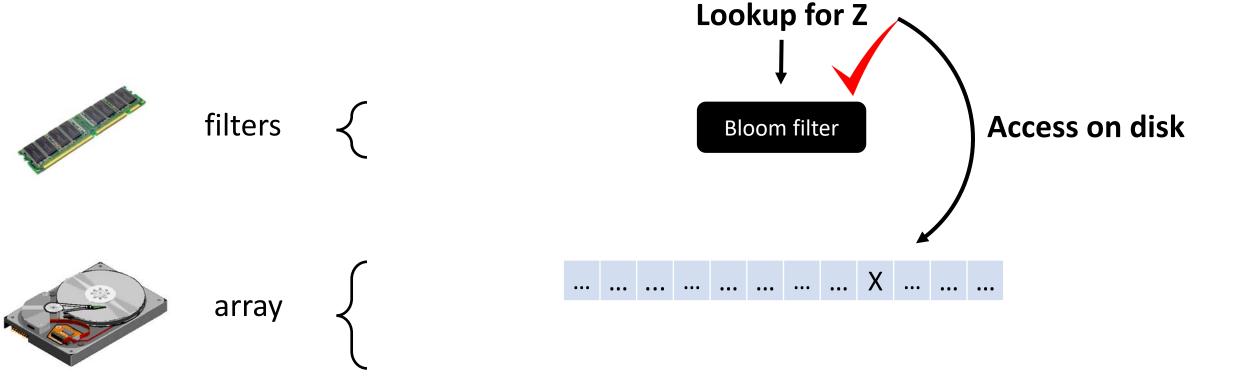


Answers set-membership queries

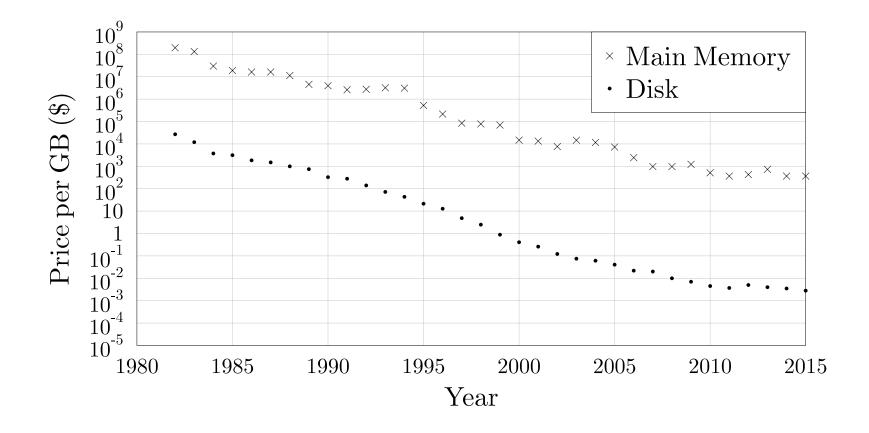
Smaller than array, and stored in main memory

Purpose: avoid accessing disk if entry is not in array

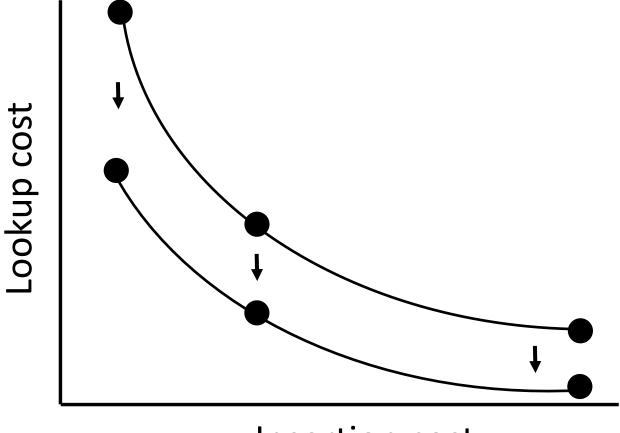
Subtlety: may return false positives.



The more main memory, the fewer false positives _____ cheaper lookups



The more main memory, the fewer false positives _____ cheaper lookups



Insertion cost

Conclusions

Write-optimized

Highly tunable

Backbone of many modern systems

Trade-off between lookup and insert cost (tiering/leveling, size ratio)

Trade main memory for lookup cost (fence pointers, Bloom filters)

Thank you!