

CS 561: Data Systems Architectures

class 7

Design Tradeoffs in Key-Value Stores

Prof. Manos Athanassoulis

https://bu-disc.github.io/CS561/

Do we have a quiz today ... ?

No!



what to do now?

- A) read the syllabus and the website
- B) register to Piazza + Gradescope
- C) finish project 0
- D) finish project 1 (due 2/14)
- E) register for the student-presentations (by 2/17)
- F) start working on project proposal (due 2/23)



Fast Scans on Key-Value Stores (KVS)

Key-Value Stores are designed for *transactional* workloads (put and get operations)











Analytical workloads require efficient scans and aggregations (typically offered by column-store systems)







Can we do both in one system?

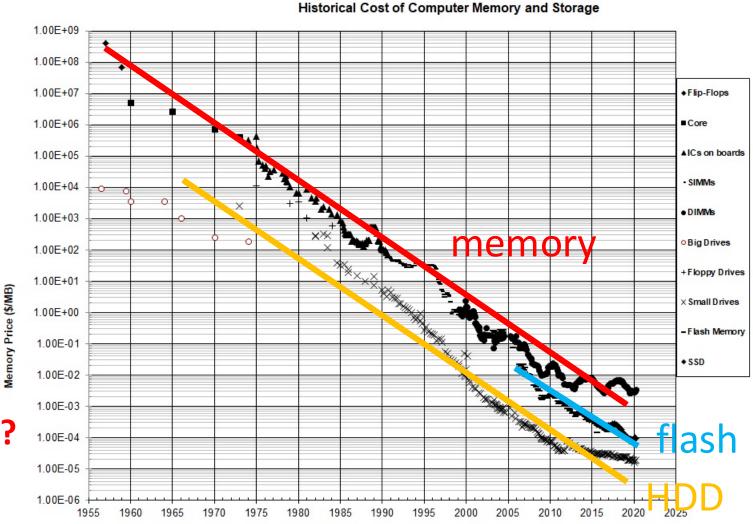
Why combine KVS and analytical systems?

cheaper and cheaper storage

more data ingestion

need for write-optimized data structures

what about analytical queries?



Year



Both transactional and analytical systems

Most organizations maintain both

- transactional systems (often as key-value stores)
- analytical systems (often as column-stores)

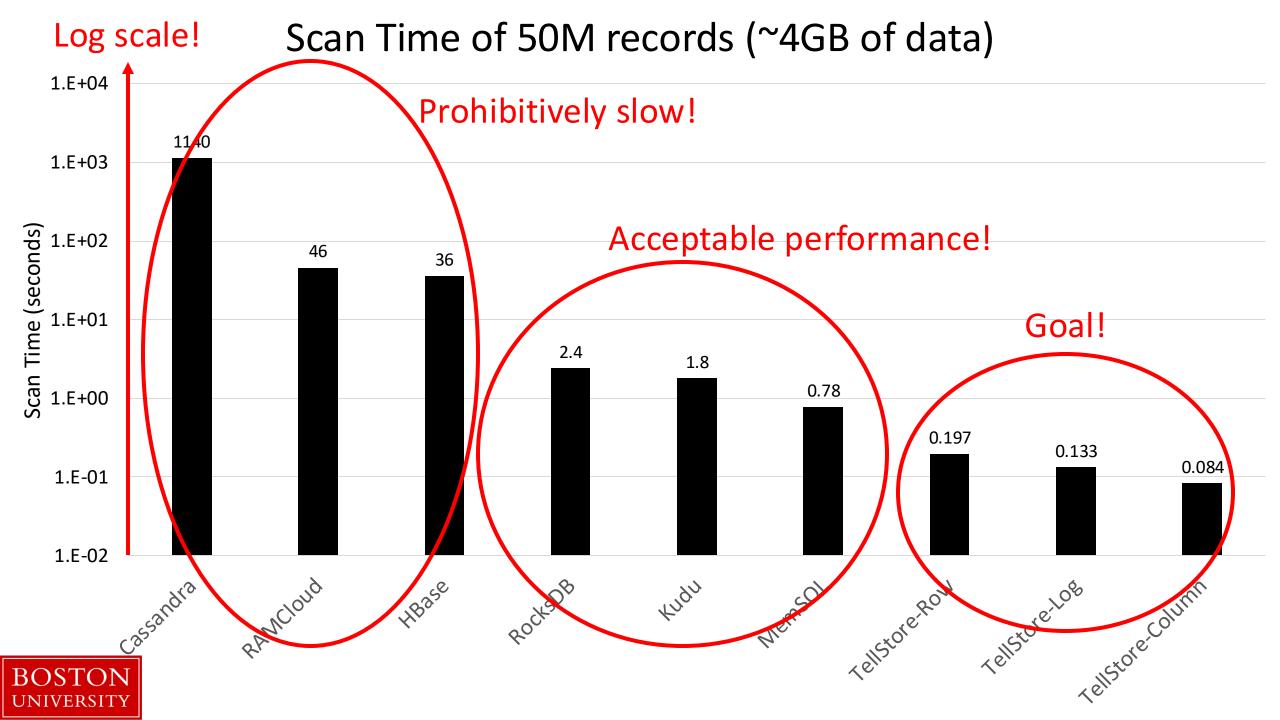


requires additional expertise and management (e.g., two DBAs)

harder to maintain (more systems, more code)

time consuming data integration/transfer





Goals of this paper

Bridge the conflicting goals of *get/put* and *scan* operations

get/put operations need sparse data structures → locality is not required, access one object scans require locality (relevant data to be packed together)

we will discuss how to compromise, via the design of *Tellstore*

how to amend the **SQL-over-NoSQL** architecture for mixed workloads



SQL over NoSQL

Elasticity

Snapshot Isolation

Processing Layer

e.g., MVCC, no locking, timestamp based

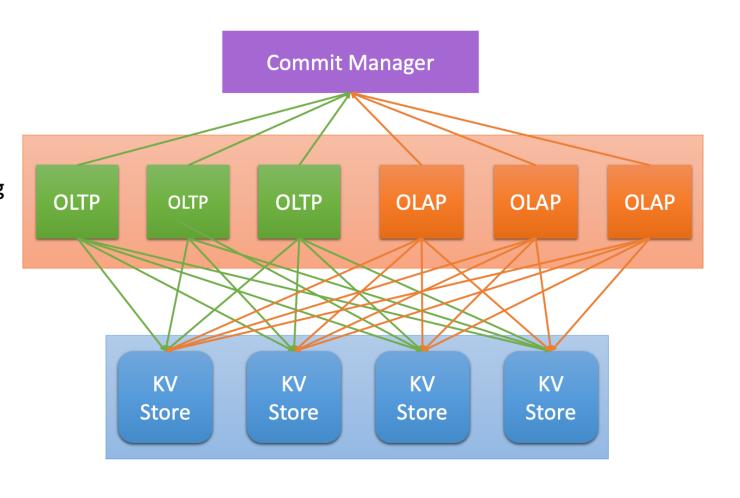
Support for:

Scans

Versioning

Batching

Storage Layer





Scans

Versioning

Batching

selection

projection

(simple) aggregates

shared scans

remember them?

multiple versions through timestamps

garbage collection

discarding old versions during scans might be costly

batch several requests to the storage layer

amortize the network time

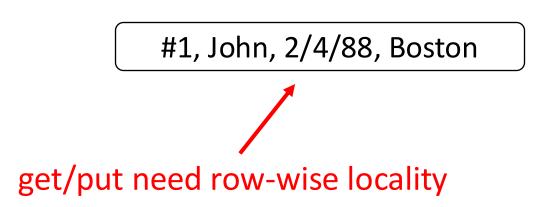




Challenges

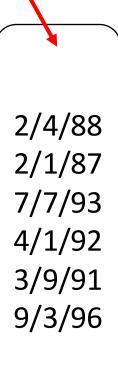
scans vs. get/put

Scans need columnar locality



why?







Challenges

scans vs. get/put

scans vs. versioning

#1, John, 2/4/88, Boston, v1

#1, John, 2/4/88, Cambridge, v2

versioning reduces locality in scans

checking for the latest version in scans needs CPU time



Challenges

scans vs. get/put

scans vs. versioning

scans vs. batching

batching multiple scans or multiple put/get requests is ok

but ...

batching scans and puts/gets is a bad idea!

why?





puts/gets need fast predictable performance

scans inherently have high and variable latency



Key design decisions

(A) Updates

(B) Layout

(C) Versioning



Key design decisions

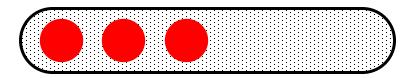
(A) Updates *in-place*





Key design decisions

(A) Updates in-place log-structured





Key design decisions

(A) Updates in-place log-structured delta-main

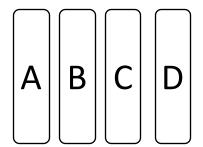


Key design decisions

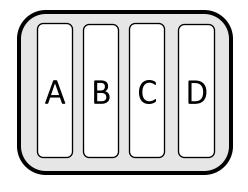
(A) Updates in-place log-structured delta-main

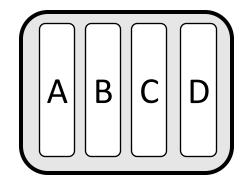
(B) Layout *column*





PAX (columnar per page)

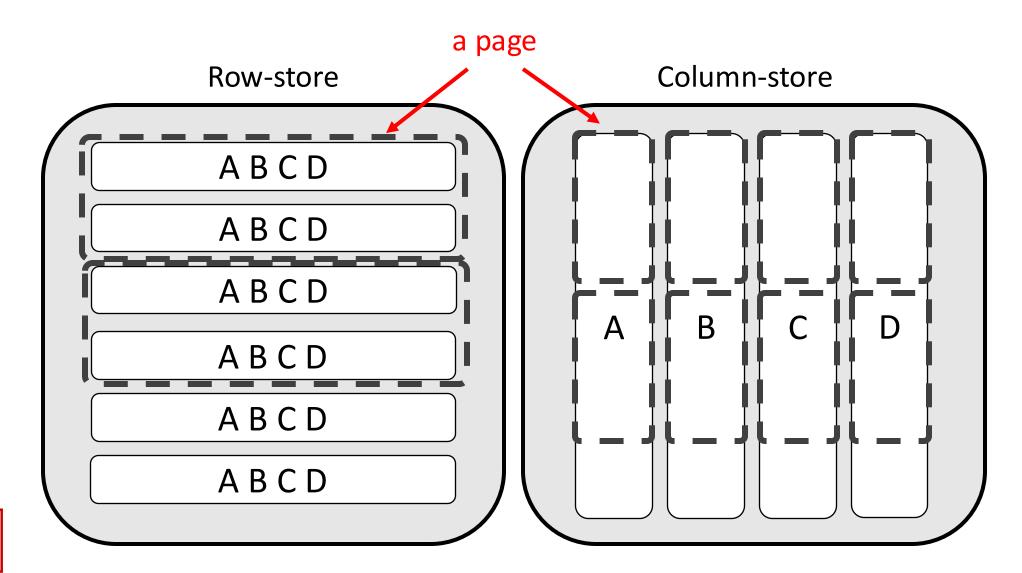




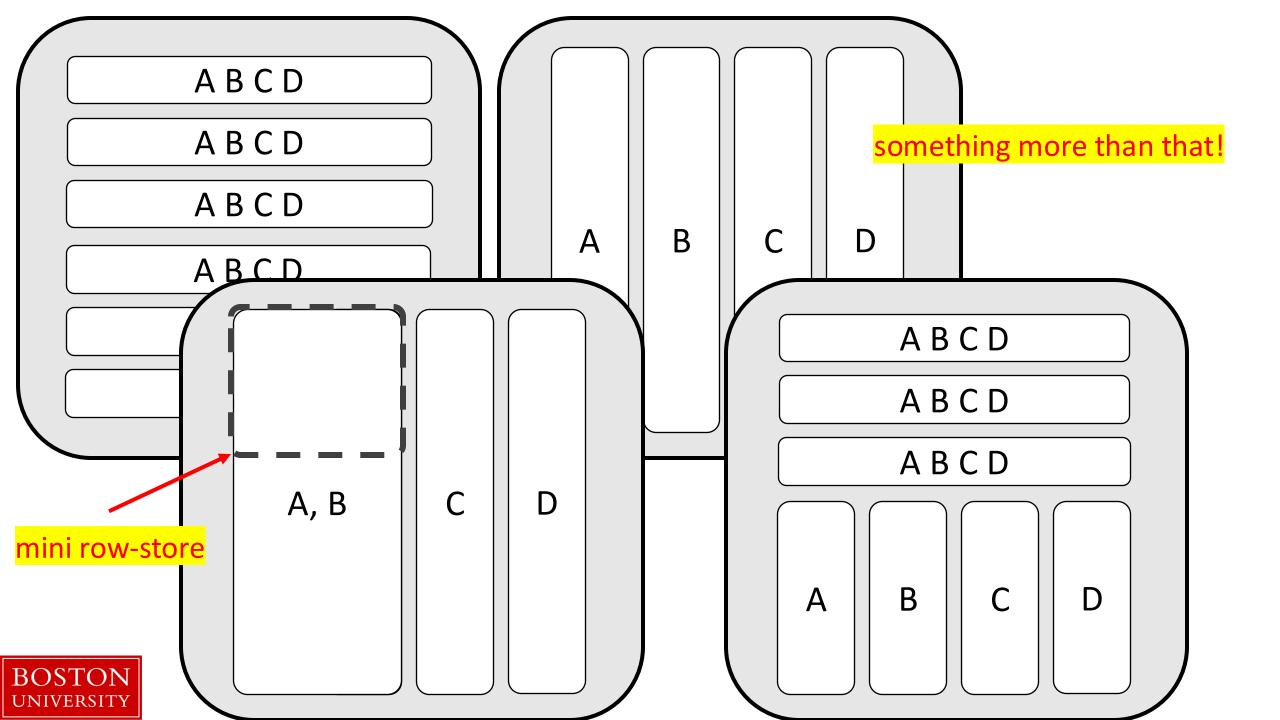


Small detour: page layouts

middle ground?







Partition Attributes Across (PAX)

Middle ground?

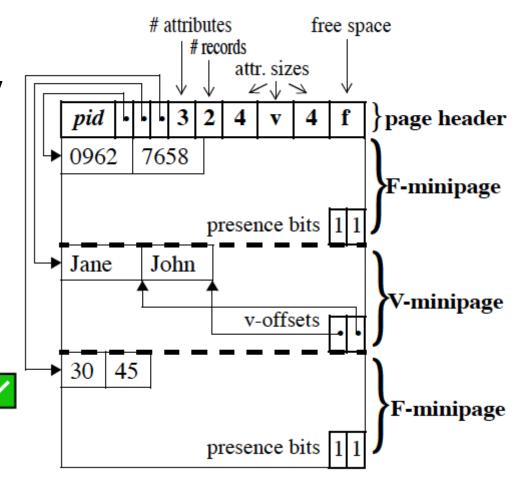


Decompose a slotted-page internally in mini-pages per attribute

- ✓ Cache-friendly
 - > Brings only relevant attributes to cache



- Compatible with slotted-pages?
- Same update abstraction?
 - (insert in a page)

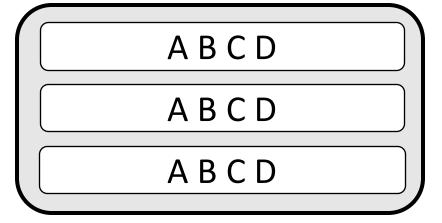




Key design decisions

(A) Updates in-place log-structured delta-main

(B) Layout column (PAX) row





Key design decisions

(A) Updates in-place log-structured delta-main

(B) Layout column (PAX) row

(C) Versioning clustered

A B C D (v1)

A B C D (v2)

A B C D



any other options?

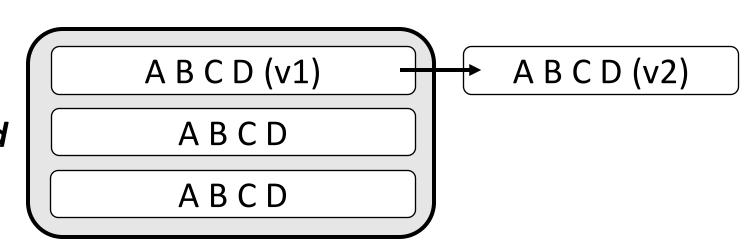


Key design decisions

(A) Updates in-place log-structured delta-main

(B) Layout column (PAX) row

(C) Versioning *clustered chained*





Key design decisions

(A) Updates in-place log-structured delta-main

(B) Layout column (PAX) row

(C) Versioning clustered chained



Garbage Collection (GC)

(A) Periodic separate dedicated thread(s)

(B) Piggy-backed GC during scans

increases scan time but frequently read tables benefit avoids re-reading for GC (since data is already accessed)



Updates

X

Layout



Versioning



GC

in-place

log-structured

delta-main

column (PAX)

row

clustered

chained

periodic piggy-backed

?

hybrid designs are also valid! should we consider all possible designs?



Updates X Layout X Versioning X GC

in-place column (PAX) clustered periodic

log-structured row chained piggy-backed

delta-main

some combinations can be discarded:

log-structured & column worse than delta-main & column log-structured & clustered worse than log-structured & chained



| Dimension | Approach | Advantages | Disadvantages |
|-----------|---------------------|-------------------------|-------------------------|
| | update-in- place | storage | versioning, concurrency |
| Update | log- structured | storage, concurrency | GC |
| | delta-main | compromise | |
| Layout | column (PAX) | scan | get/put |
| Luyoui | row | get/put | scan |
| Versions | clustered | get/put | GC |
| | chained | GC | scan |

Table 2: Design Tradeoffs



Updates X Layout X Versioning X GC

in-place column (PAX) clustered periodic

log-structured row chained piggy-backed

focus on two extremes: *TellStore-Log* (1) log-structured & row & chained



delta-main

focus on two extremes:

TellStore-Log

- (1) log-structured & row & chained
- (2) delta-main & column & clustered

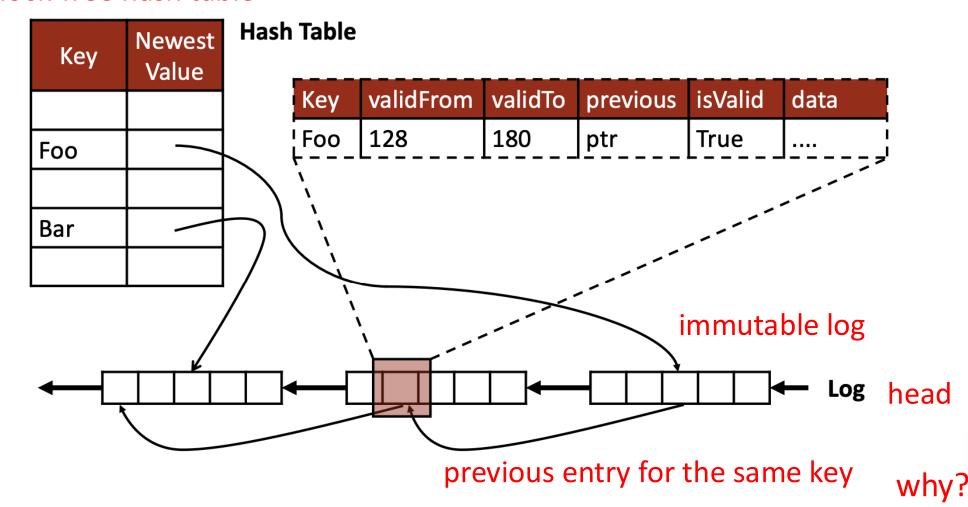
TellStore-Col



TellStore-Log

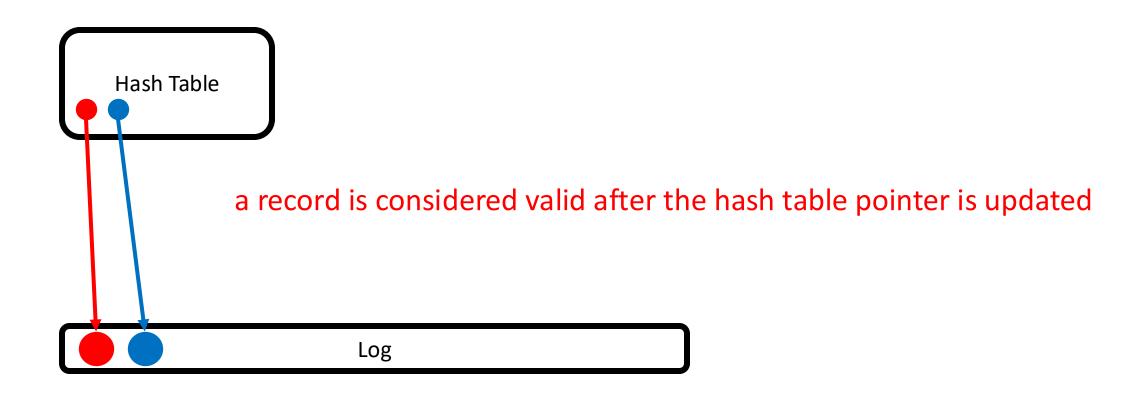
one log per table (locality for scans) inserts, updates, and deletes are all logged

lock-free hash table



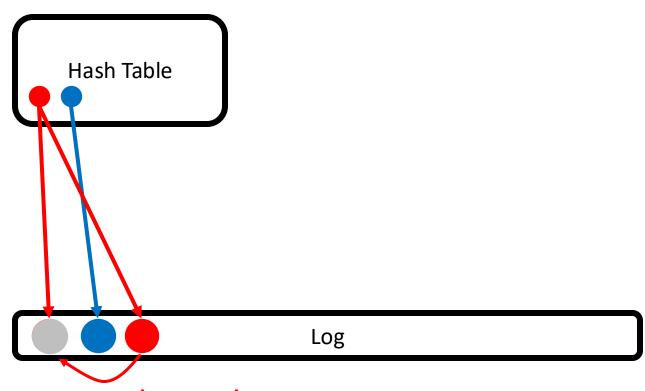


TellStore-Log Insertion





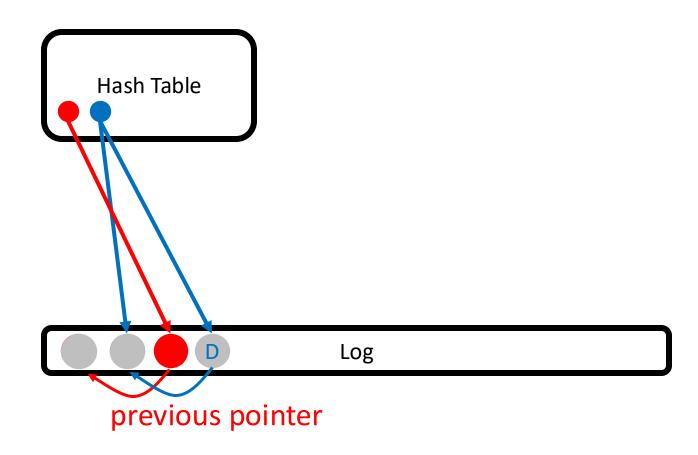
TellStore-Log Update



previous pointer

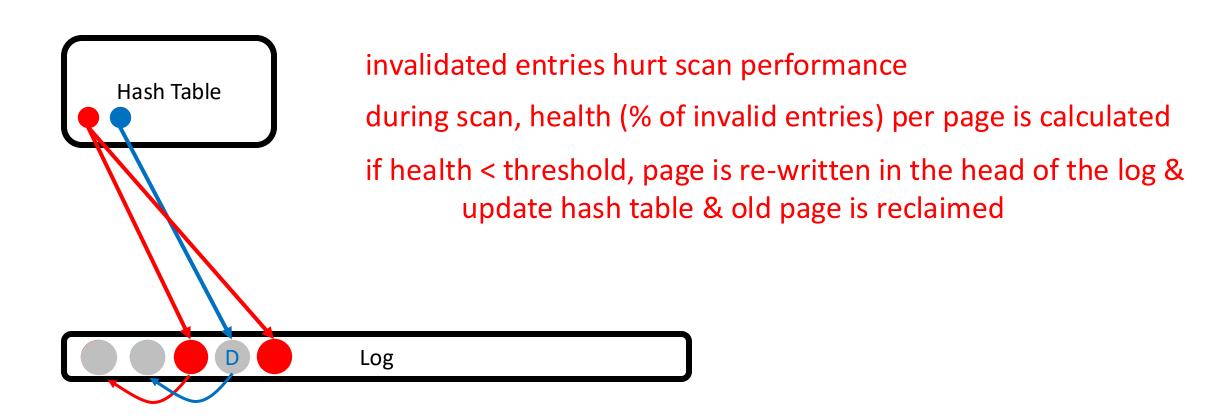


TellStore-Log Delete





TellStore-Log Garbage Collection





TellStore-Log in a nutshell

log-structure: efficient puts

hash-table: efficient gets (always points to the latest entry)

snapshot Isolation: high throughput, no locks needed

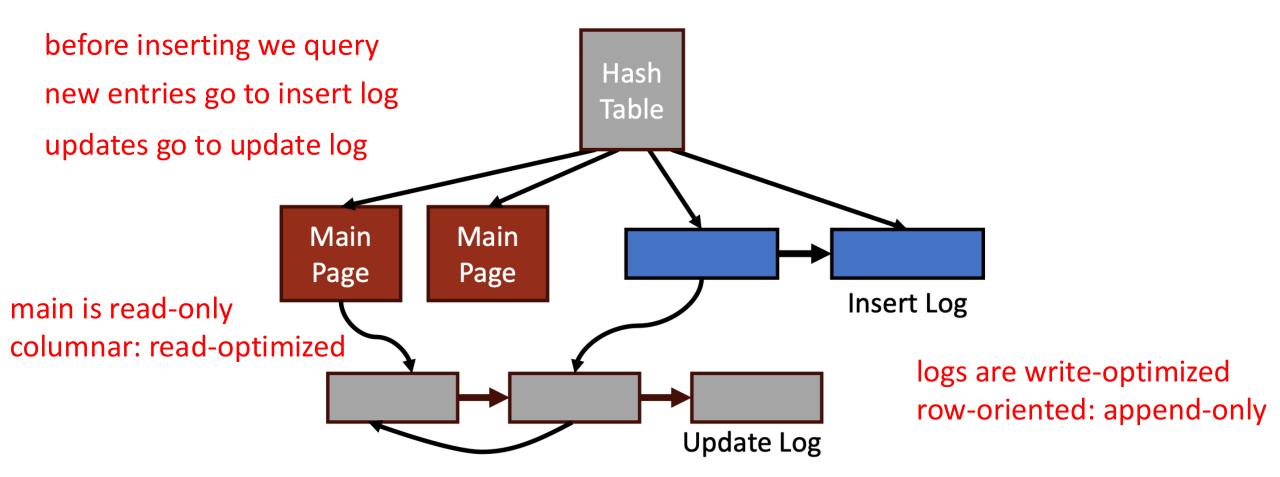
self-contained log: efficient scans (valid from/to needed)

lazy GC: Optimize tables that are scanned

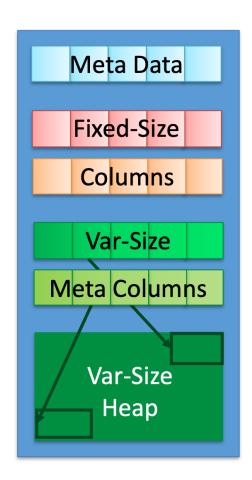


four data structures

TellStore-Col



TellStore-Col Layout



fixed-size data is stored in columnar format

variable-size data is indexed in columnar format but stored in row-wise format

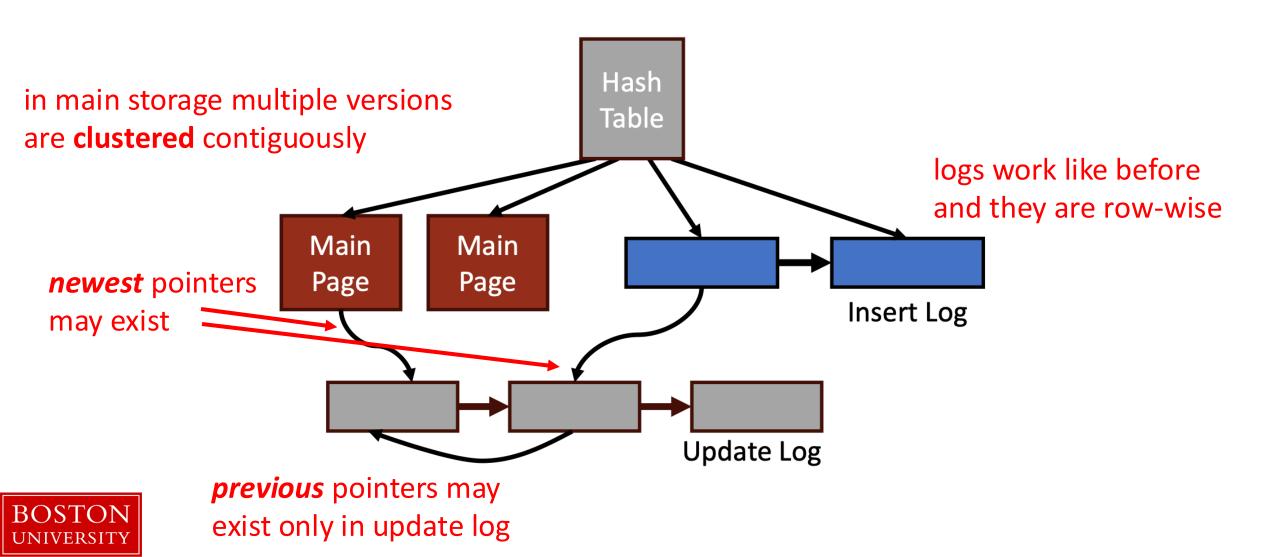
why row-wise?



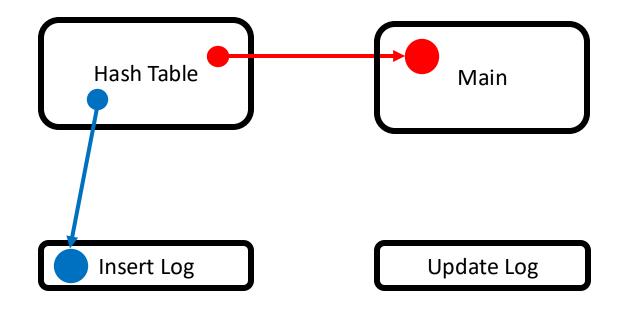
- (1) faster materialization (contiguous copying)
- (2) less metadata (one offset for many columns)



TellStore-Col Versioning

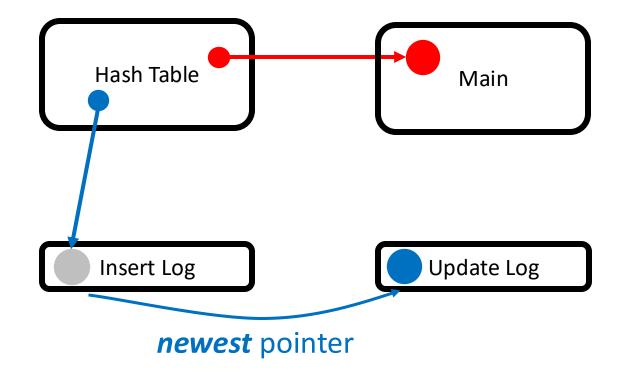


TellStore-Col Insertion



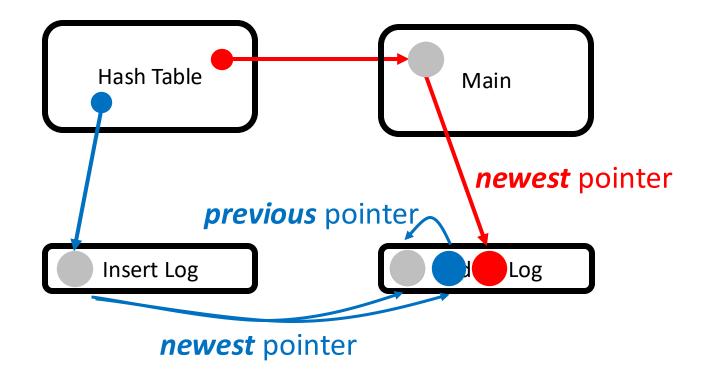


TellStore-Col Update



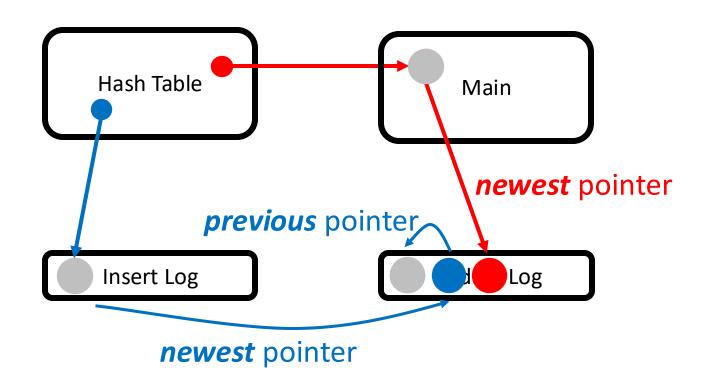


TellStore-Col Update





TellStore-Col Garbage Collection



dedicated thread (conversion from row to column)

all main pages with invalid entries

all pages from insert log + update to main

run GC frequently + truncate logs



TellStore-Col in a nutshell

delta-main: compromise between puts and scans

hash-table: efficient gets (always points to the latest entry, may need one more pointer to follow)

PAX layout: minimize disk I/O, maintain locality for scans

separate insert/update logs: efficient GC

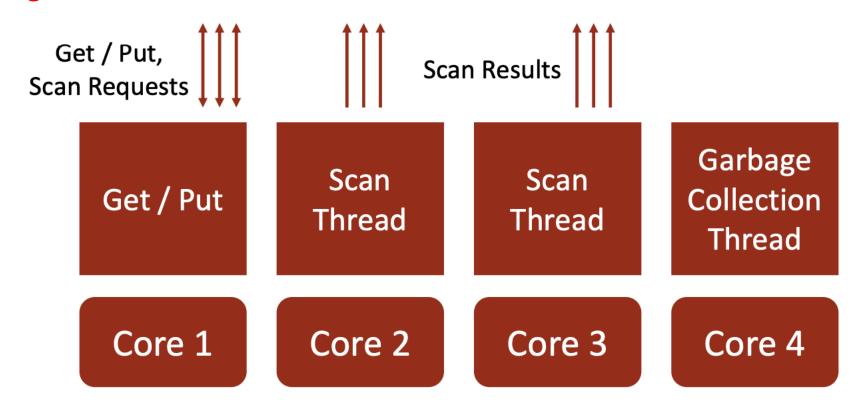
eager GC: improve scans



Implementation Details

scans are assigned to dedicated threads

scan coordinator for shared scans



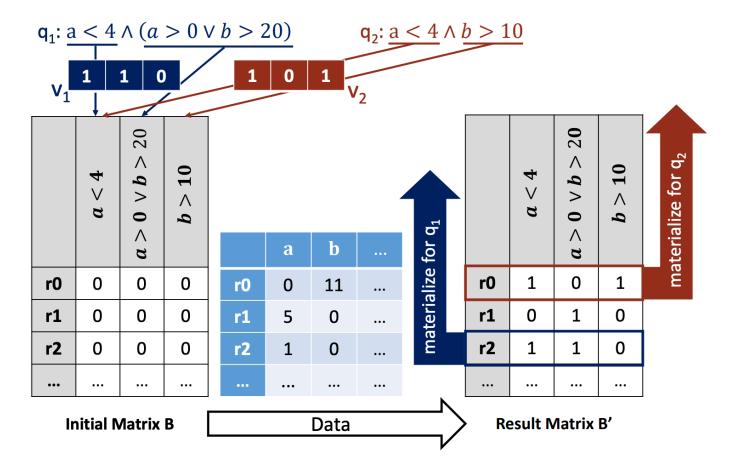


Implementation Details

efficient predicate evaluation via code generation and predicate pushdown

all queries in CNF

reuse work





Yahoo! Cloud Serving Benchmark# (YCSB#)

based on YSCB, a put/get benchmark

main_table (P, A, B, C, D, E, F, G, H, I, J) P: 8-byte ley | A-H: 2-bytes, 4-bytes, 8-bytes | I-J: strings 12-16 bytes

• Query 1: A simple aggregation on the first floating point column to calculate the maximum value:

```
SELECT max(B) FROM main_table
```

• Query 2: The same aggregation as Query 1, but with an additional selection on a second floating point column and selectivity of about 50%:

```
SELECT max(B) FROM main_table WHERE H > 0 and H < 0.5
```

• Query 3: A selection with approximately 10% selectivity:

```
SELECT * FROM main_table WHERE F > 0 and F < 26
```



Experiments: Transactional Workload

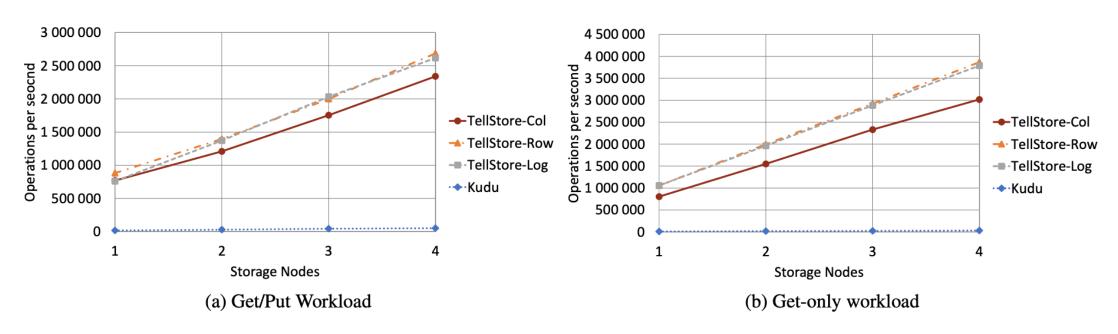


Figure 8: Exp 1, Throughput: YCSB, TellStore Variants and Kudu, Vary Storage Nodes

Kudu is used as it was the most competitive to begin with



All TellStore approaches are not that far!

Experiments: Scans

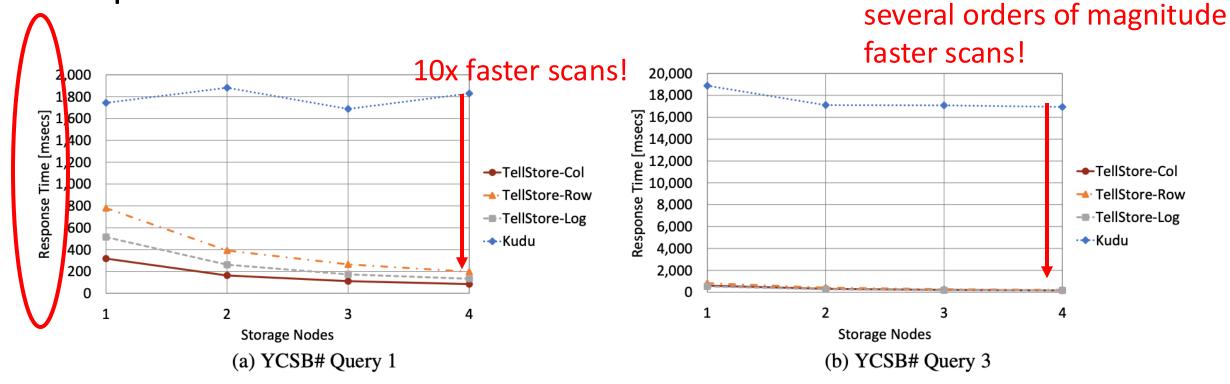


Figure 10: Exp 3, Response Time: YCSB#, Vary Storage Nodes

Q3 does not have projections, so no benefit from columnar



Experiments: Mixed Workload

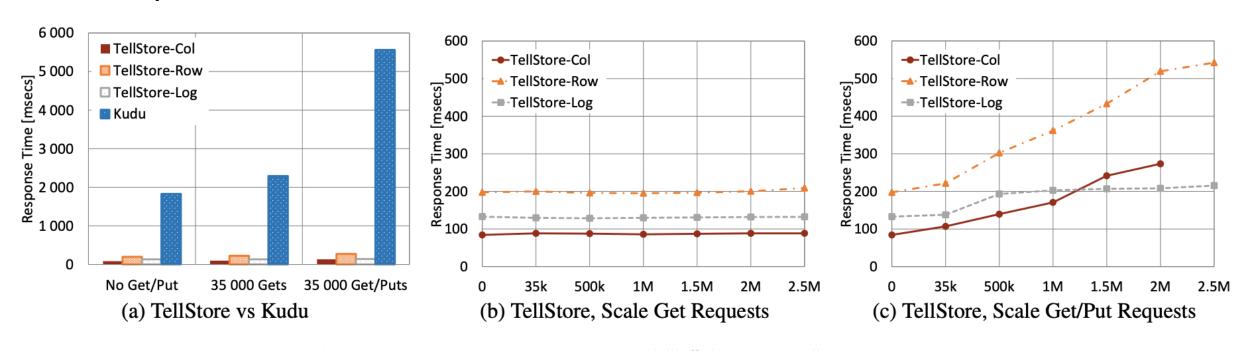


Figure 11: Exp 4, Response Time: YCSB# Query 1, 4 Storage Nodes

Contrary to competition, scan perf. is stable with more gets/puts

In the absence of updates
TellStore scales perfectly:
scans+gets go to different
cores

With 50% updates eventually logging wins



Things to remember

KVS vs. Scans: how to compromise, navigate the design space

- ✓ delta-main vs. log-structure
- ✓ chained vs. clustered versions
- ✓ row-major vs. column-major
- ✓ lazy vs. eager GC



F2: Designing a Key-Value Store for Large Skewed Workloads

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Shivaram Venkataraman University of Wisconsin-Madison shivaram@cs.wisc.edu

A new set of requirements:

point put/get operations (need for high throughput, ideally full in-memory for hot data)

larger-than-memory working set (so full in-memory not possible)

high skew in access patterns (reads/writes)

The target application has **no scans**!



which design should they follow?

Key-value stores

Log-structured Merge (LSM) Trees

- Handle larger-than-memory workloads
- Organized in levels; first is in-memory
- Support both point & range queries
- Avoid I/O by employing (Bloom) filters
- Judicious use of main memory





Point-optimized Stores

- Focus on use-cases like web caching
- Large in-memory index structures
- Latch-free concurrent designs
- Saturate I/O (even for NVMe SSDs)
- Very high throughput (>1M ops/sec)



KVell: the Design and Implementation of a Fast Persistent Key-Value Store

Baptiste Lepers University of Sydney

Karan Gupta

Abstract

Modern block-addressable NVMe SSDs provide much higher bandwidth and similar performance for random and sequential access. Persistent key-value stores (RVs) designed for earlier storage devices, using either Log-Structured Merge (LSM) or B trees, do not take full advantage of these new devices. Logic to avoid random accesses, expensive operations for keeping data sorted on disk, and synchronization

FASTER: A Concurrent Key-Value Store with In-Place Updates

Badrish Chandramouli † , Guna Prasaad $^{\dagger *}$, Donald Kossmann † , Justin Levandoski † , James Hunter † , Mike Barnett †

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ABSTRACT

Over the last decade, there has been a tremendous growth in dataintensive applications and services in the cloud. Data is created on a variety of edge sources, e.g., devices, browsers, and servers, and processed by cloud applications to gain insights or take decisions. Applications and services either work on collected dats, or monitor and process data in real time. These applications are typically update intensive and involve a large amount of state beyond what can fit in main memory. However, they display significant temporal locality

1.1 Challenges and Existing Solutions

State management is an important problem for all these applications and services. It exhibits several unique characteristics:

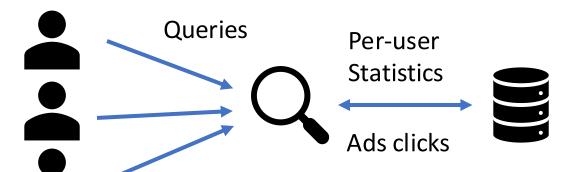
Large State: The amount of state accessed by some applications
can be very large, far exceeding the capacity of main memory. For
example, a targeted search ads provider may maintain persuer,
per-ad and clickthrough-rate statistics for billions of suers. Also, it
is often chapter to retain state that is infequently accessed on
secondary storage [18], even when it fits in memory.



Real-world, large skewed workloads

- Point queries and high throughput paramount
- Working sets larger than main-memory most data rarely accessed or updated
- Total indexed data order of magnitude larger than main-memory
- Natural skew in key access pattern both for reads and writes
- Memory resources scarce disk wear is a practical concern

Search Engine Workload



Insert / Update statistics (e.g., clicks, statistics)

Millions of active users at any time – critical path

Many more *inactive*, but we still need to keep data!

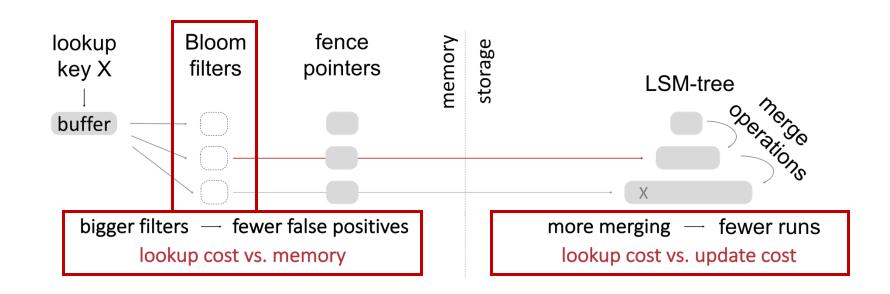
We fetch clicks for active users (during browsing) We count viewed ads, from active users

Limitations of Existing Systems (1)

Log-structured Merge (LSM) Trees

- + Enable and tune (Bloom) filters
- + Use hash indices
- + Efficient compaction policies

- Filters may no longer fit in memory
- CPU overhead (10s of filters / query)
- Need tuning





Limitations of Existing Systems (2)

KVell

- Adjust page-cache size
- Large in-memory B-tree (19B per key)
- B-tree continuously paged out to disk

FASTER

- Tune record log in-memory size / hash index
- Reducing index size increases I/O ops
- Log compaction "pollutes" in-memory log



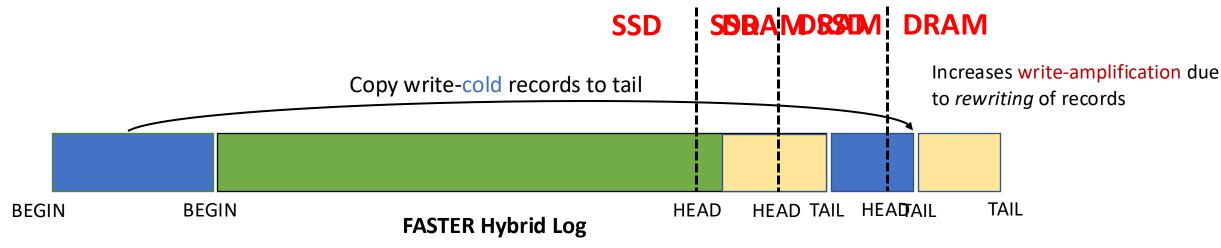
Limitations of Existing Systems (2)

KVell

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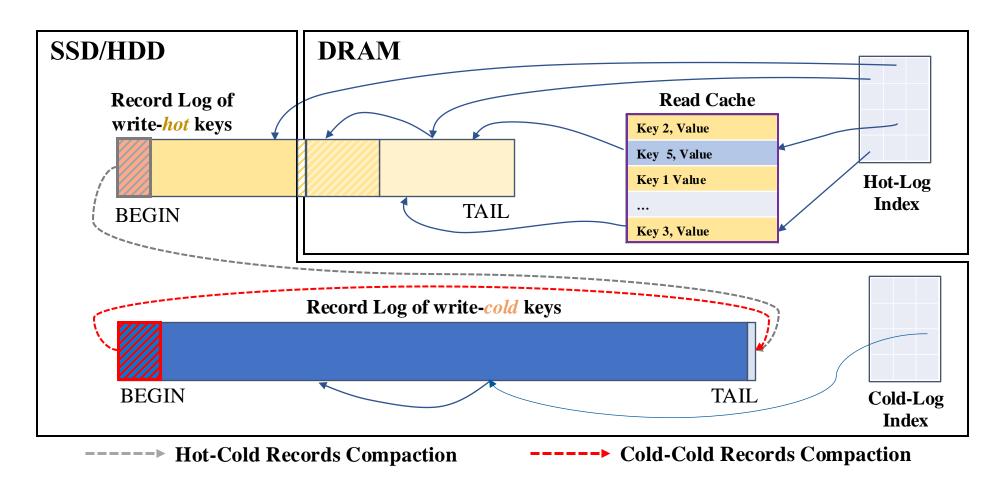




New records compete with old compacted records for a spot at *in-memory* regions

Introducing *F2*

Key Idea: separate management of records across both read/write and hot/cold domains





Design Space

Updates X Layout X Versioning X GC

in-place column (PAX) clustered periodic
log-structured row chained piggy-backed
delta-main

similar to TellStore-Log, but with **periodic compaction**

compaction aggressively optimized



F2 – Read Cache

Contains read-hot records of both hot log and cold log

• Hash index entries can point to *either* read cache entries or (hot) record log (single bit in address)

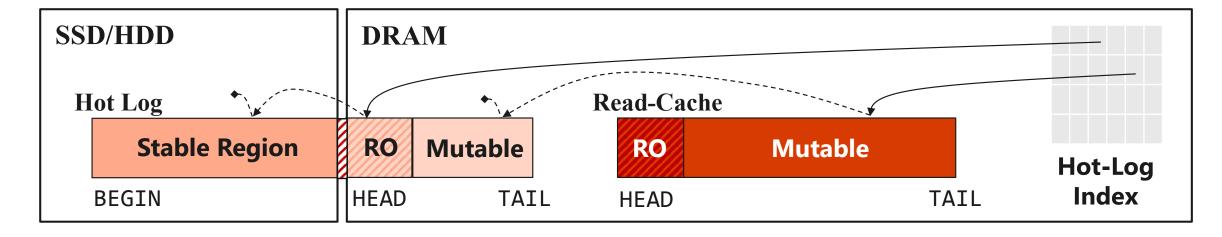
Reads go from hot-log index \rightarrow (optionally) read cache \rightarrow hot log

Reads from **cold**-log are *always* inserted at the tail of the read cache

Upserts and **RMWs** write *directly* to **hot** log tail, eliminating read cache chain

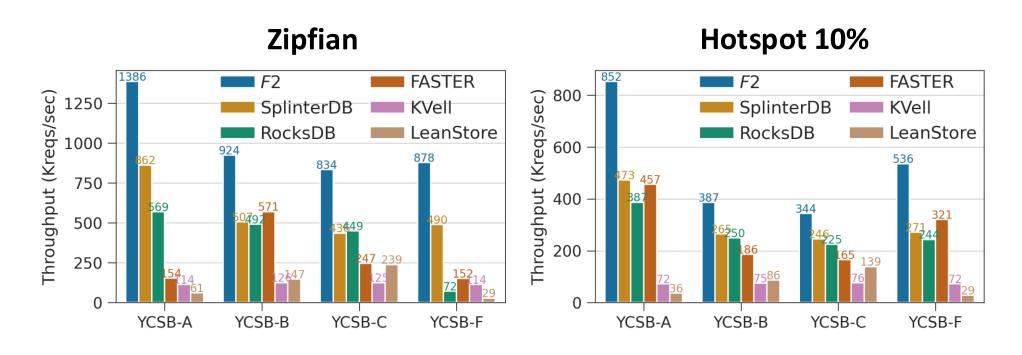
If record with same key in read cache, it's invalidated!

Periodically, read cache is evicting in-memory records (HEAD), by altering the hash chains



F2 – Performance Comparison

YCSB: 250M keys, 8B keys, 100B values; **3GiB** mem budget (**10%** of dataset size); 24 threads, NVMe SSD

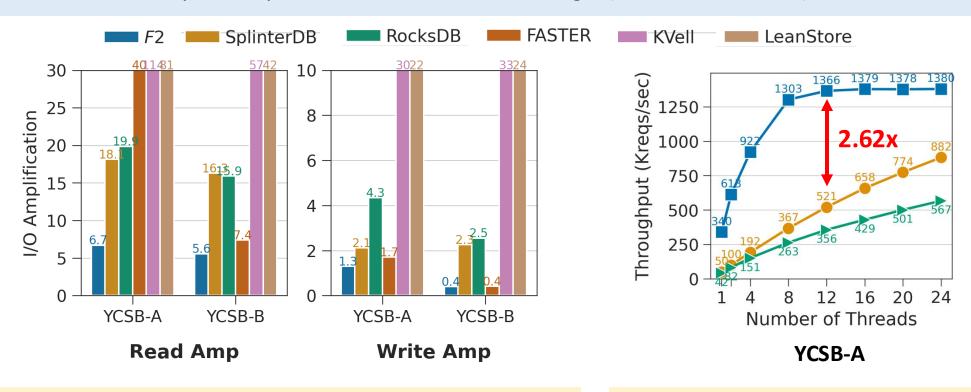


Zipfian: SplinterDB (1.78x), RocksDB (4.61x), FASTER (4.94x)

Hotspot 10%: SplinterDB (1.66x), RocksDB (1.88x), FASTER (1.92x)

F2 – I/O Amplification & Scalability Comparison

YCSB: 250M keys, 8B keys, 100B values; **3GiB** mem budget (**10%** of dataset size); 24 threads, NVMe SSD



F2 achieve less WA than Baselines

F2 saturates at 8-12 threads



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