



# LSM-Trees Under Memory Pressure

Presenter: Zichen Zhu



Widely adopted because they balance read performance and ingestion







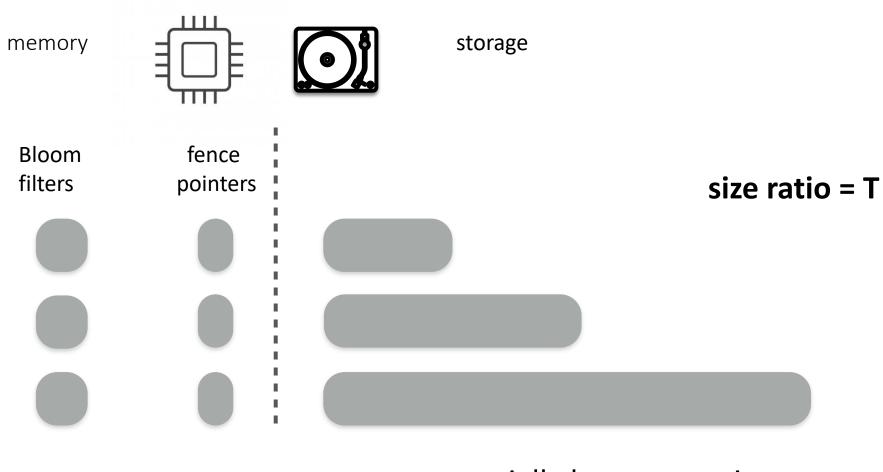








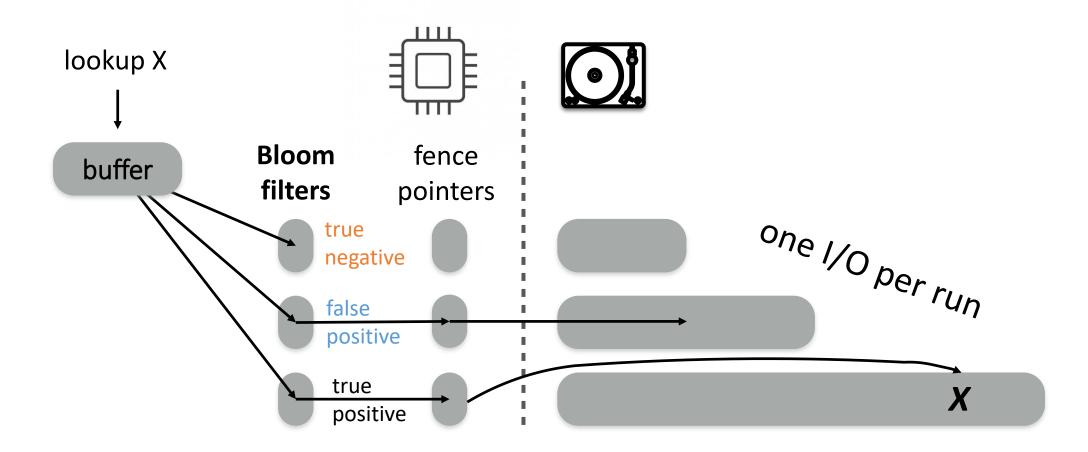




exponentially larger capacity



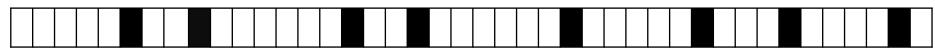






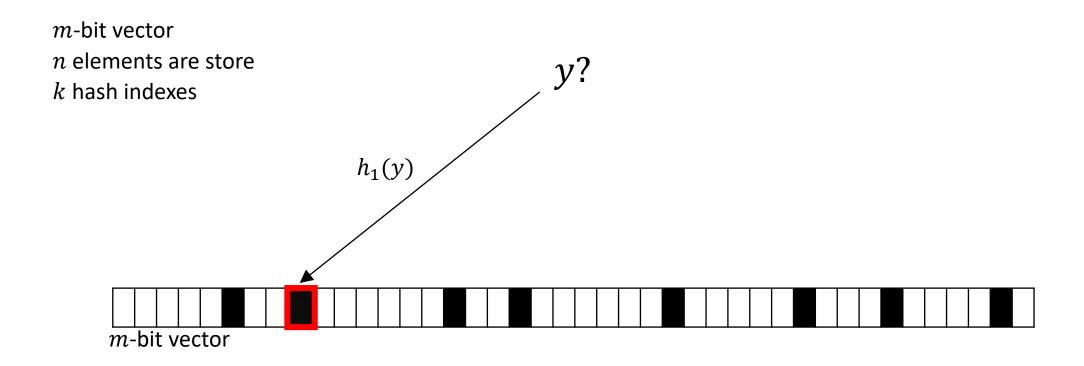
m-bit vector n elements are store k hash indexes

*y*?



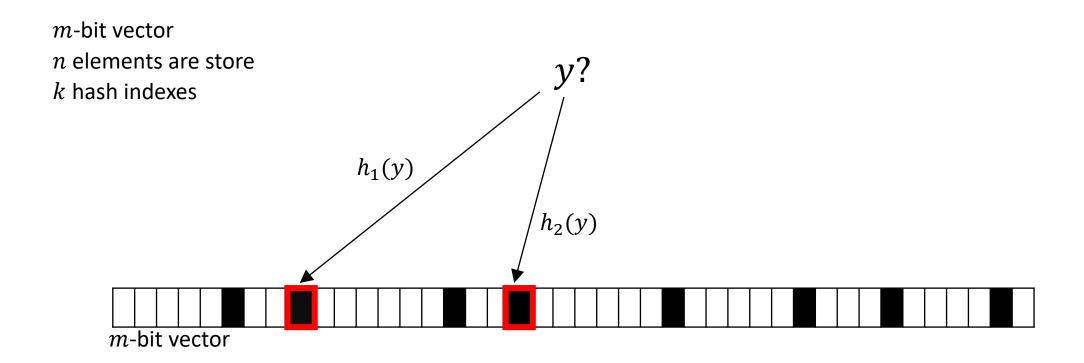
*m*-bit vector



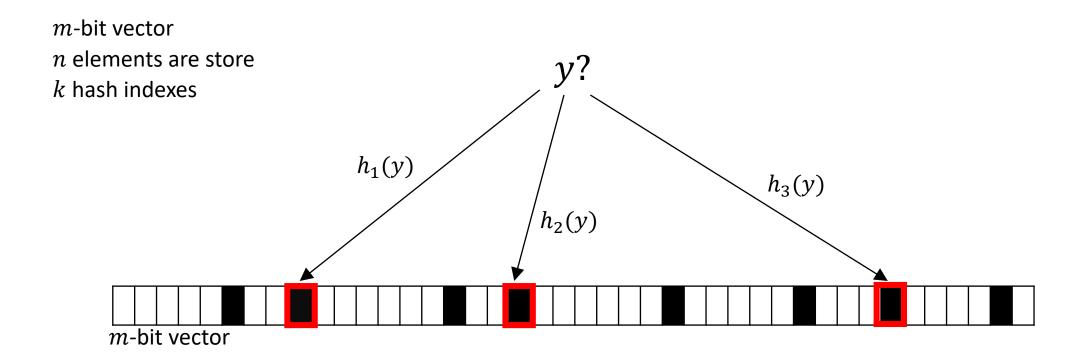




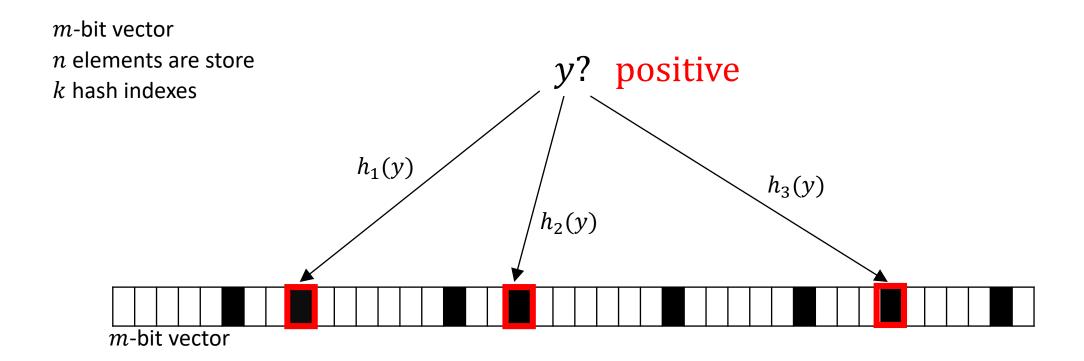








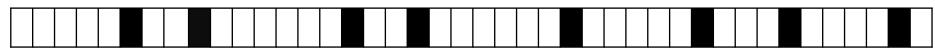






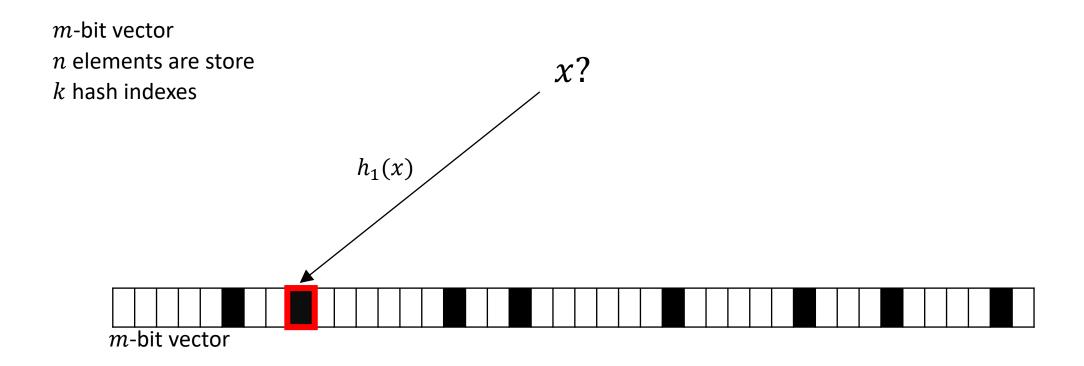
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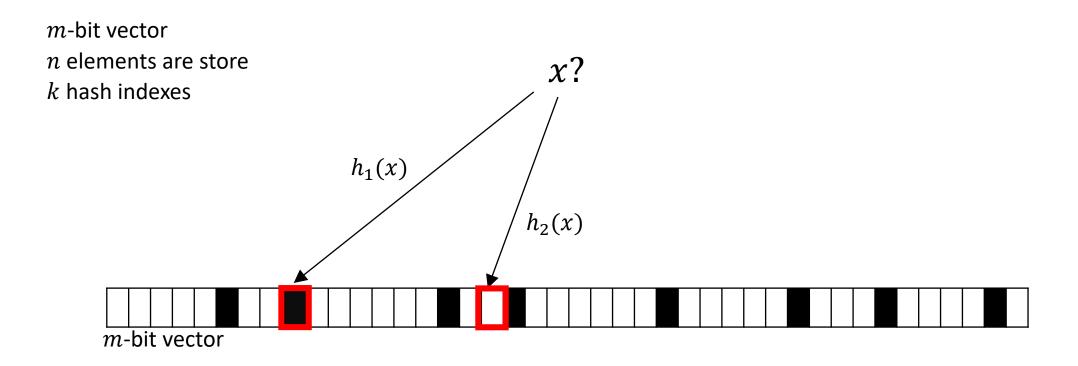
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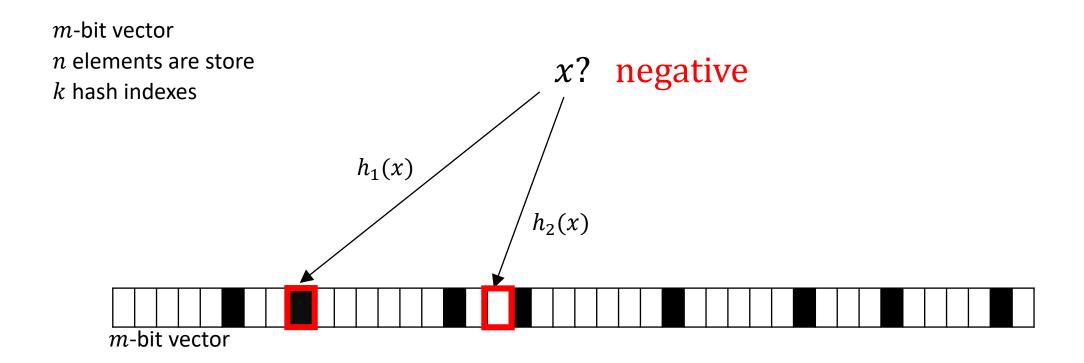










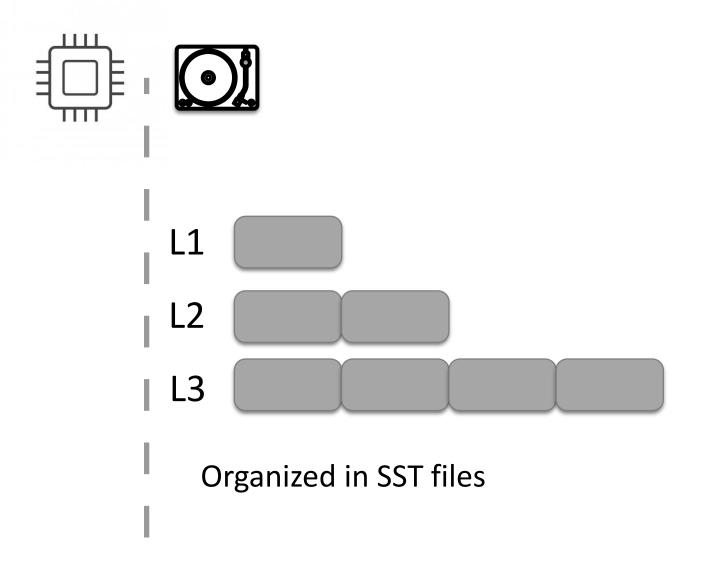


false positive 
$$p = e^{-\frac{\text{bits } M}{\text{entries } N} \cdot ln(2)^2}$$





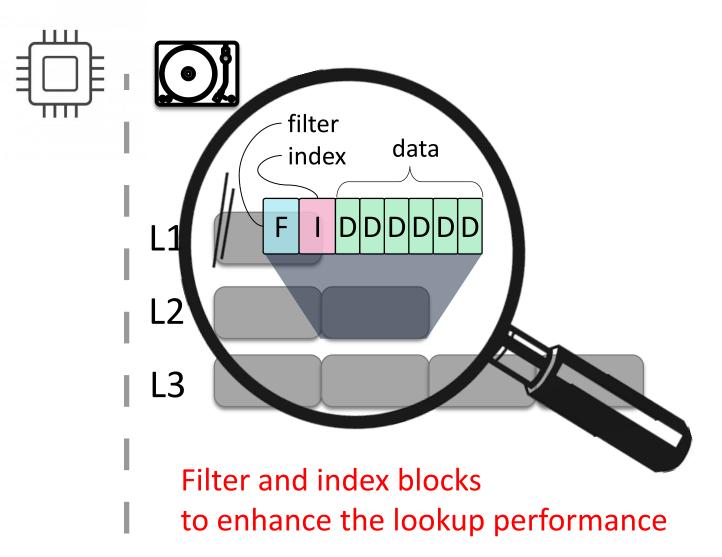
buffer







buffer









# Memory vs. Storage

Metric	DRAM				2	HDD				SATAFlash SSD	
	1987	1997	2007	2018	1987	1997	2007	2018	2007	2018	
Unit price(\$)	5k	15k	48	80	30k	2k	80	49	1k	415	
Unit capacity	1MB	1GB	1GB	16GB	180MB	9GB	250GB	2TB	32GB	800GB	
\$/MB	5k	14.6	0.05	0.005	83.33	0.22	0.0003	0.00002	0.03	0.0005	
Random IOPS	-	-	-	-	5	64	83	200	6.2k	67k (r)/20k (w)	
Sequential b/w (MB/s)	_	-	<del>57</del> 8	<del></del>	1	10	300	200	66	500 (r)/460 (w)	

The Five-Minute Rule 30 Years Later and Its Impact on the Storage Hierarchy, Communications of the ACM, 2019

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The price drop in memory has been slower than storage



# Memory vs. Storage

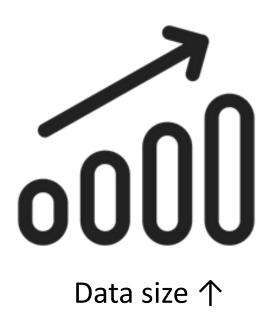
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The Five-Minute Rule 30 Years Later and Its Impact on the Storage Hierarchy, Communications of the ACM, 2019

The price drop in memory has been slower than storage making it hard to maintain the same memory-to-data ratio









Data size ↑

For 1TB data, 1.3GB filter &17.2GB index

> 11% space amplification, 1KB entry, 64B key, bpk 10

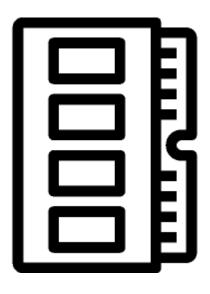




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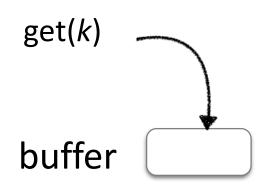


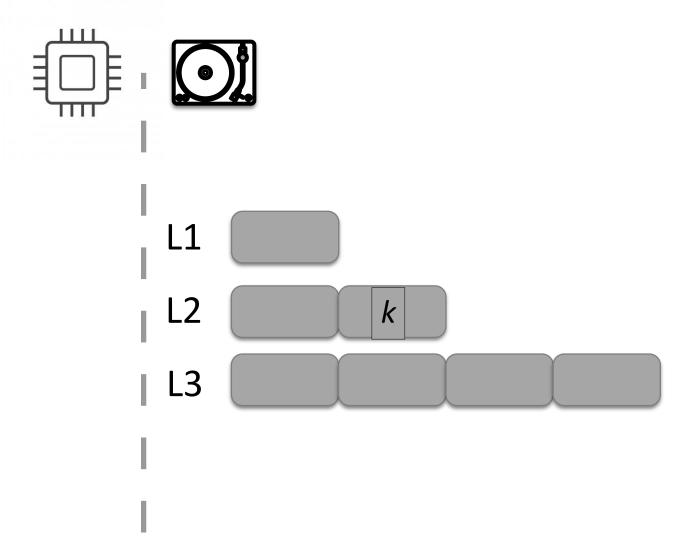
memory-to-data ratio 🗸

Memory pressure



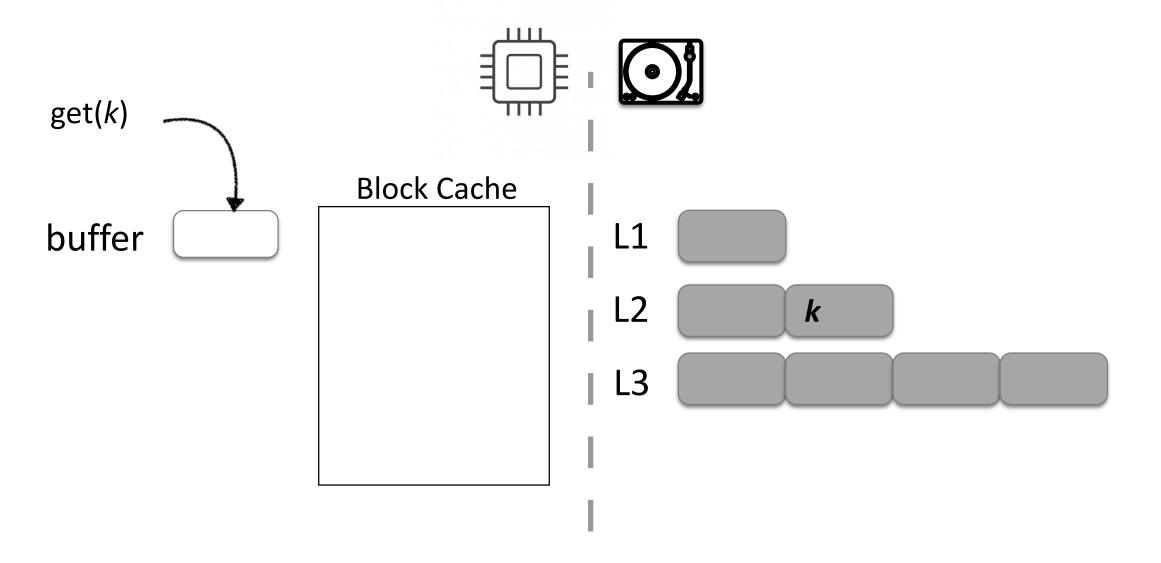






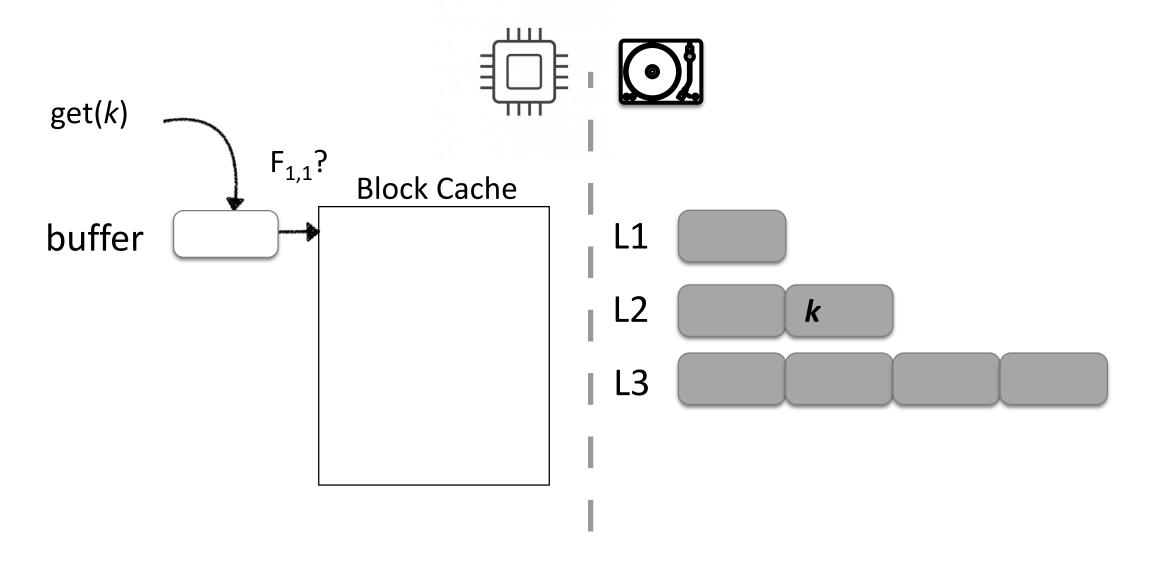






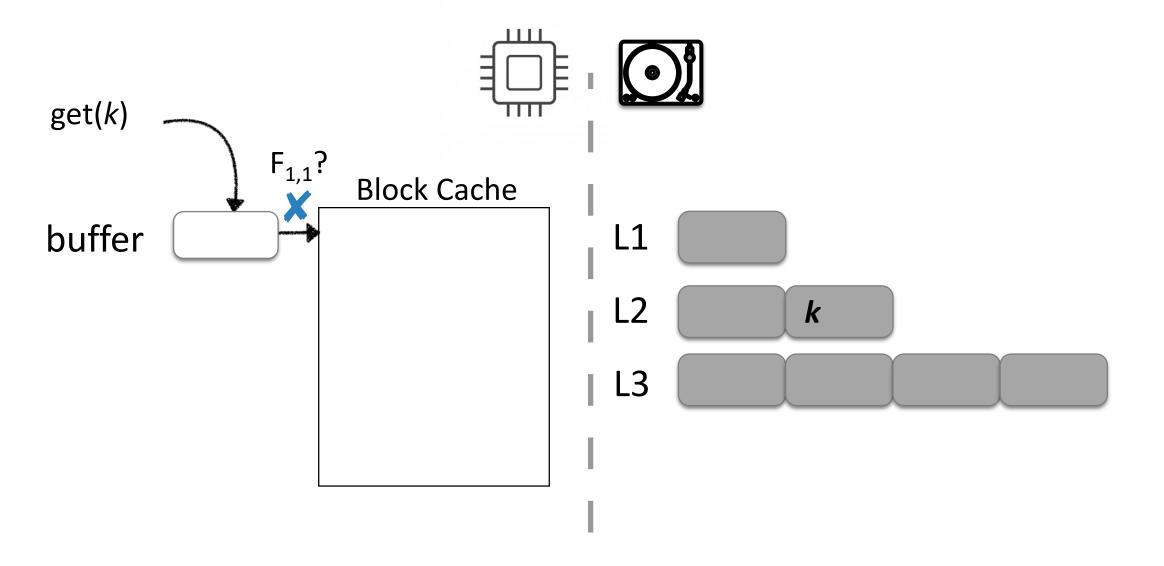






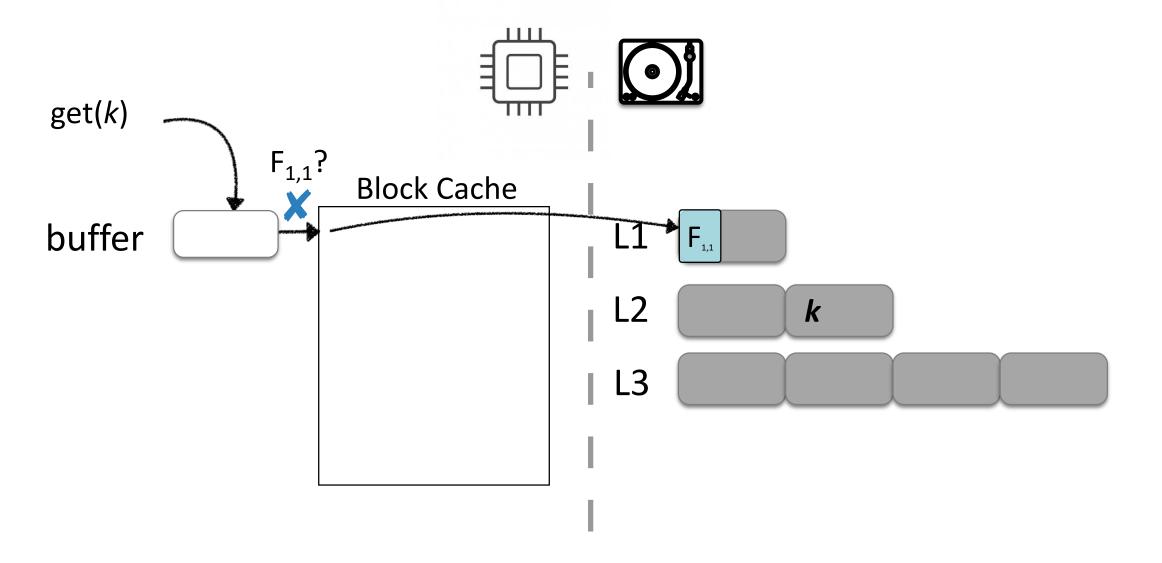






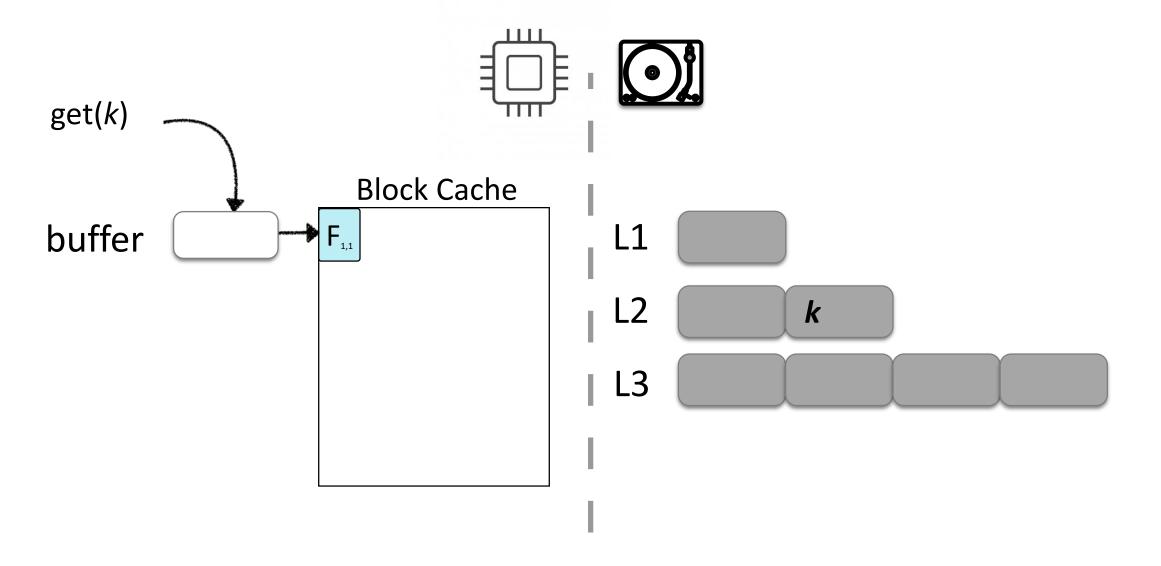






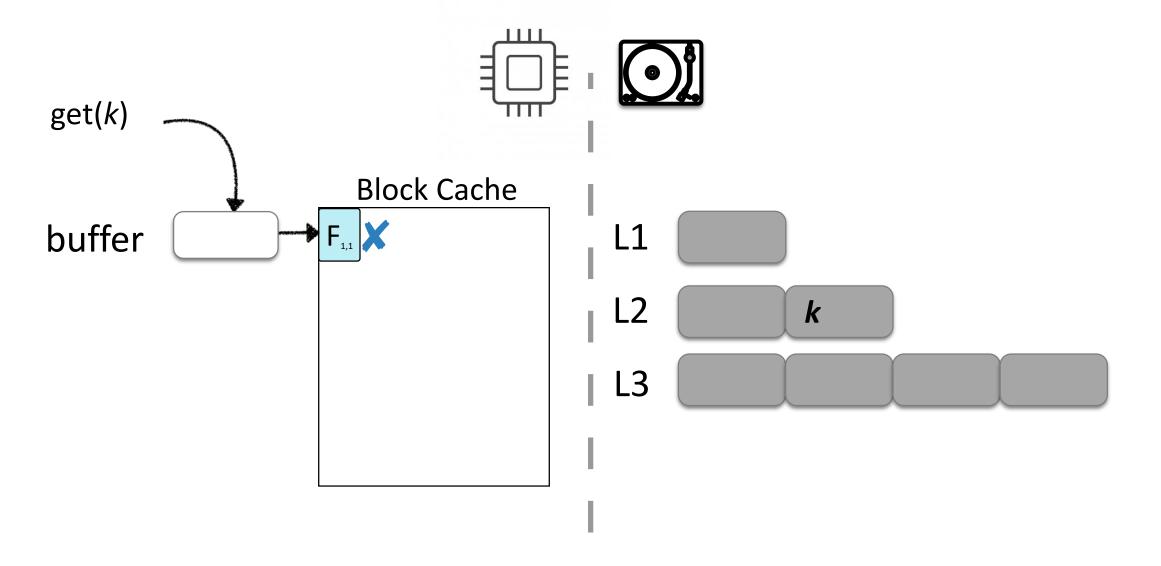






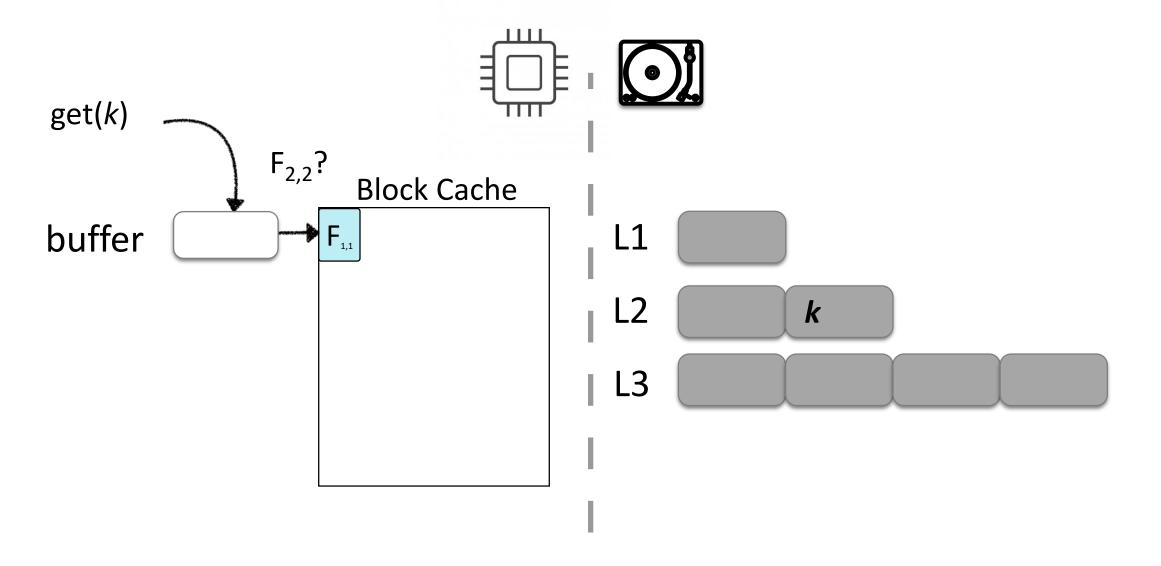






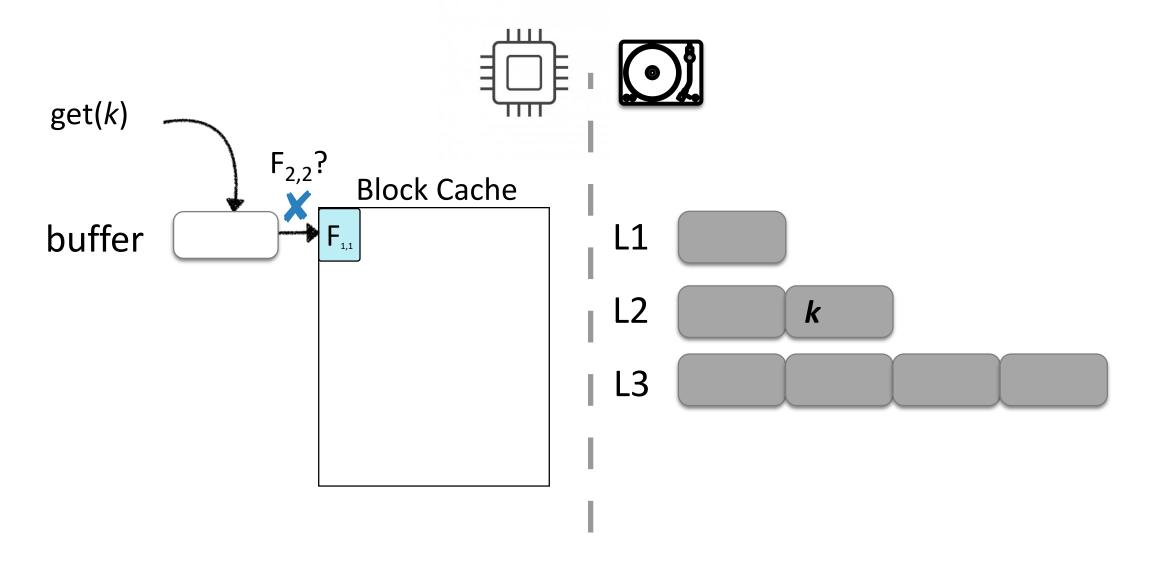






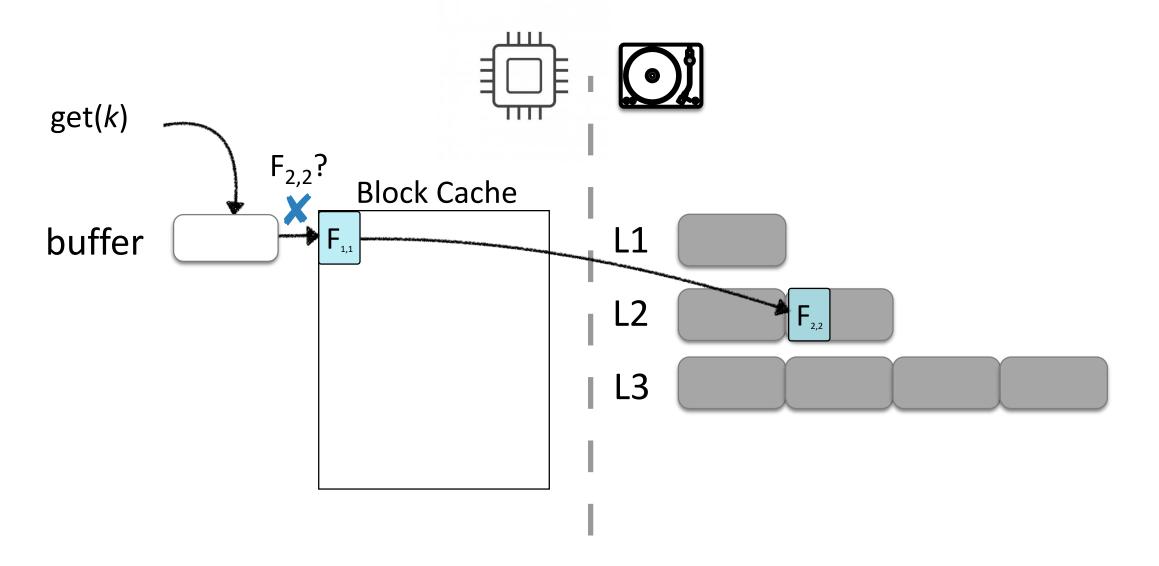






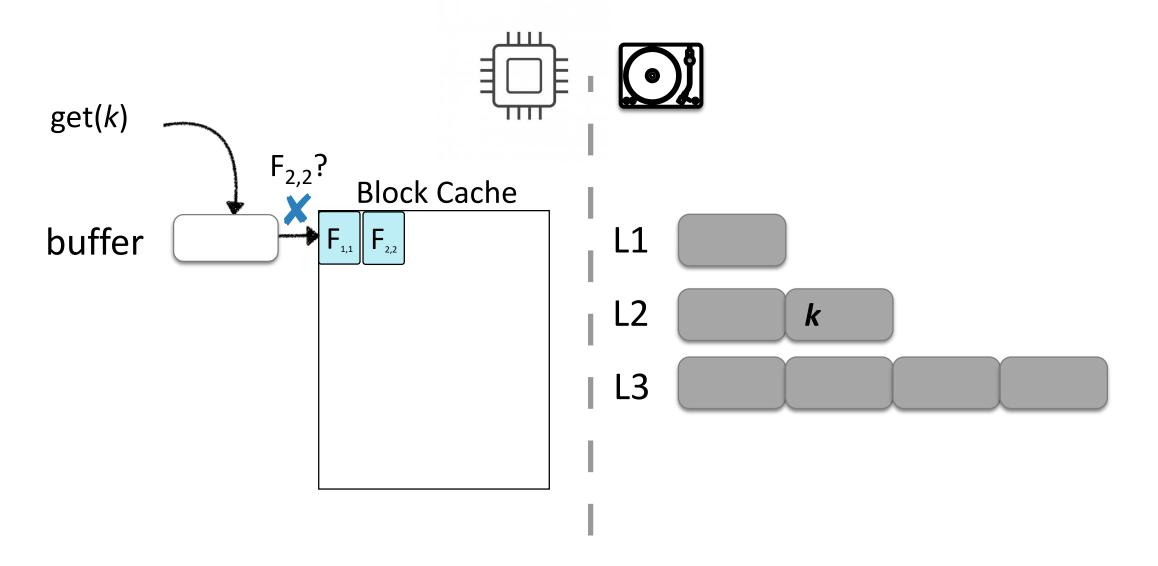






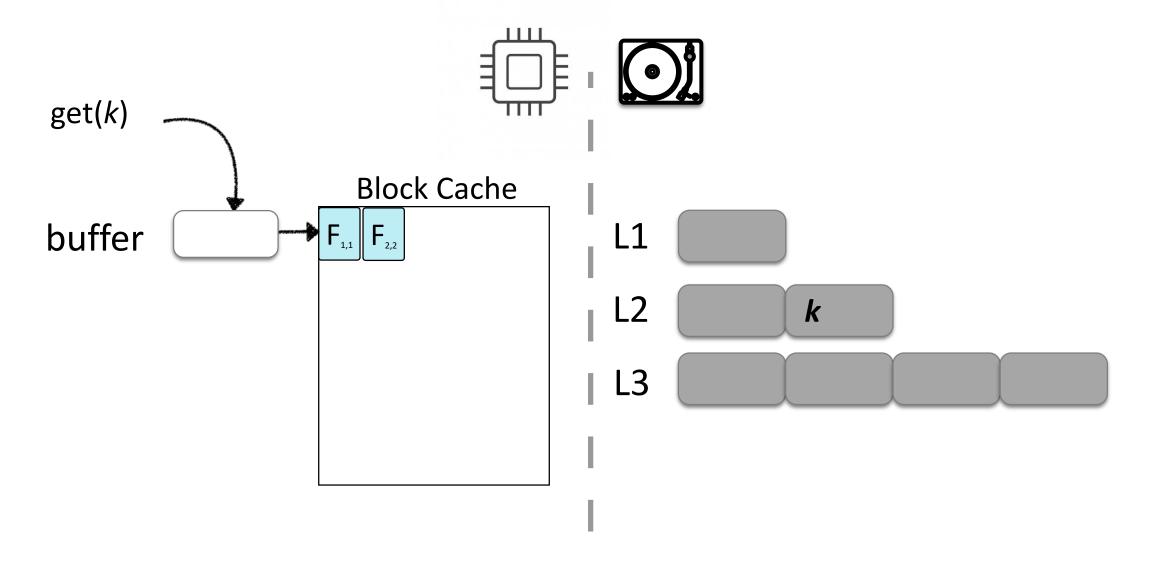






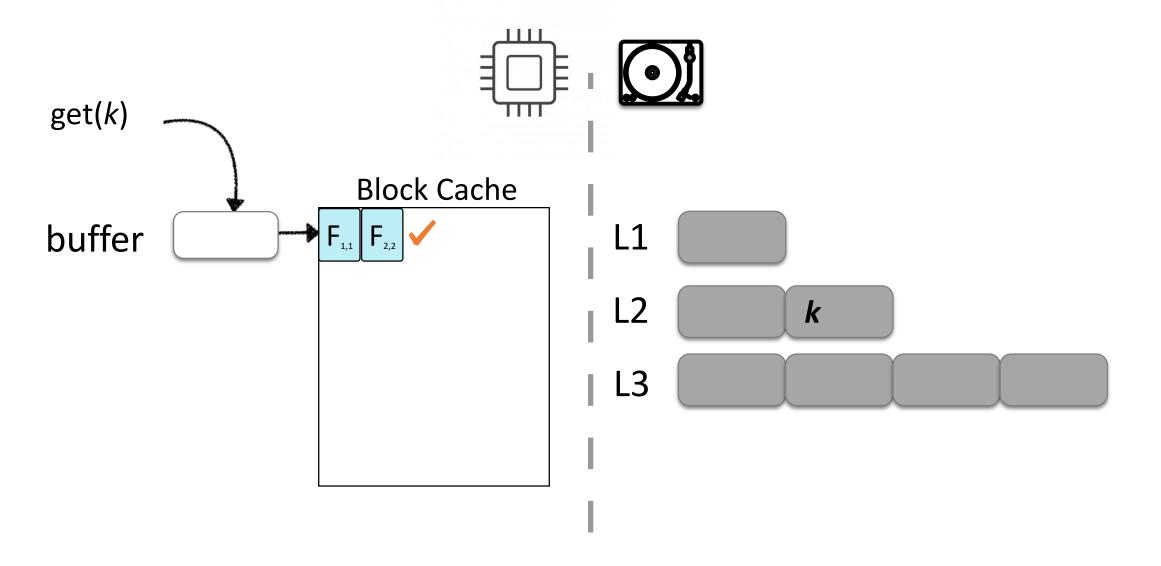






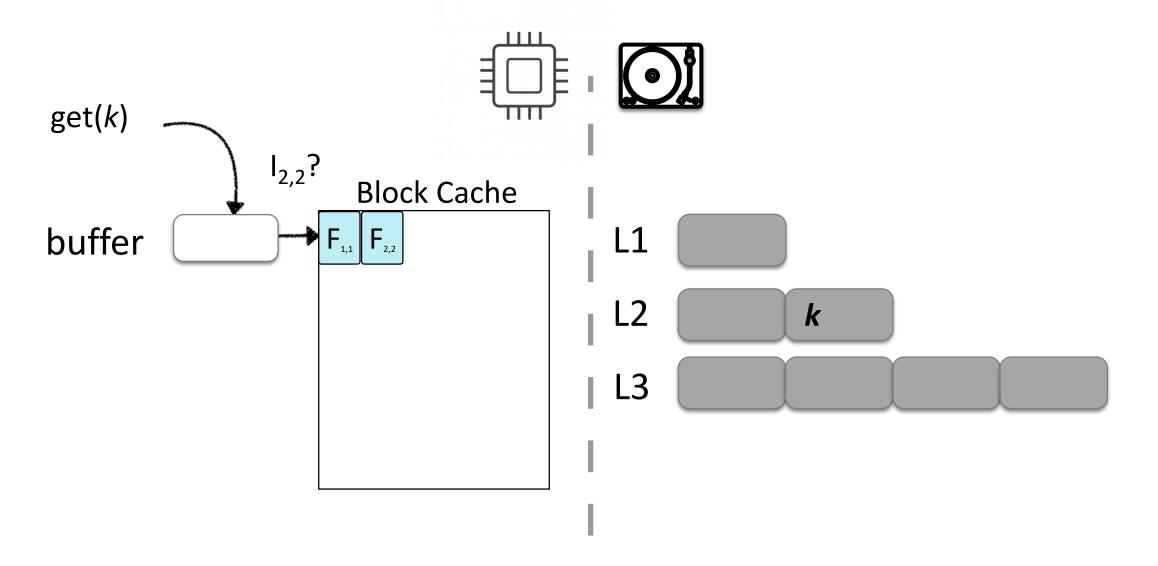






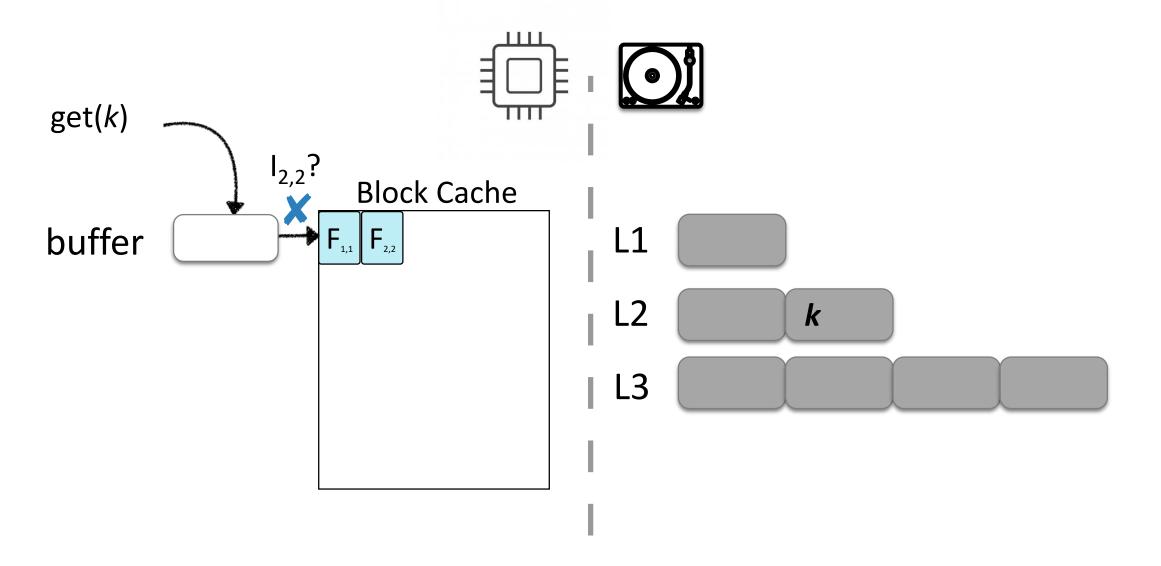






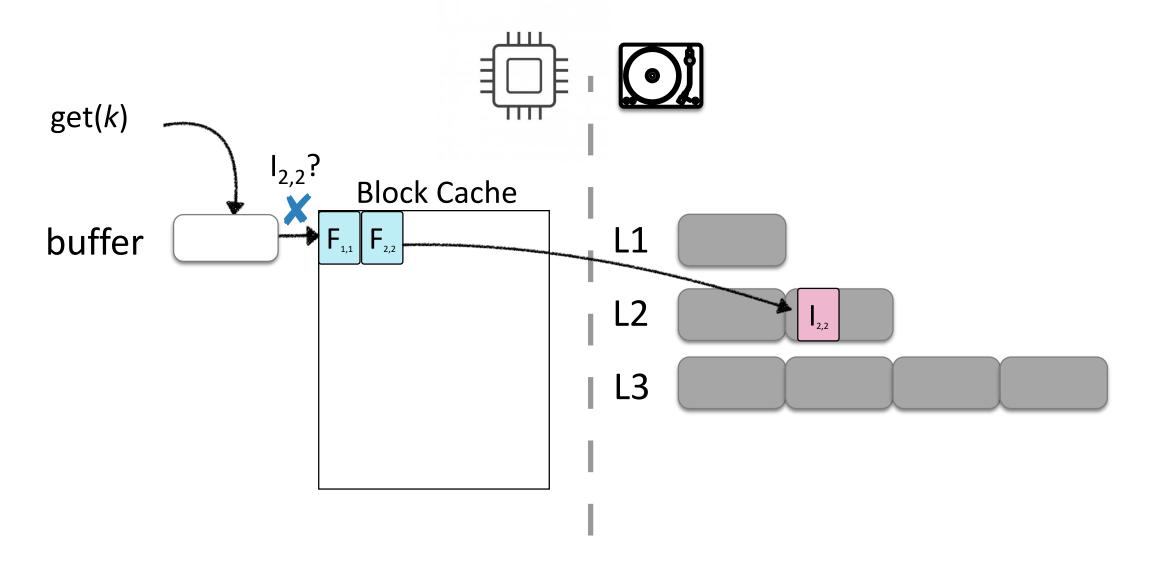






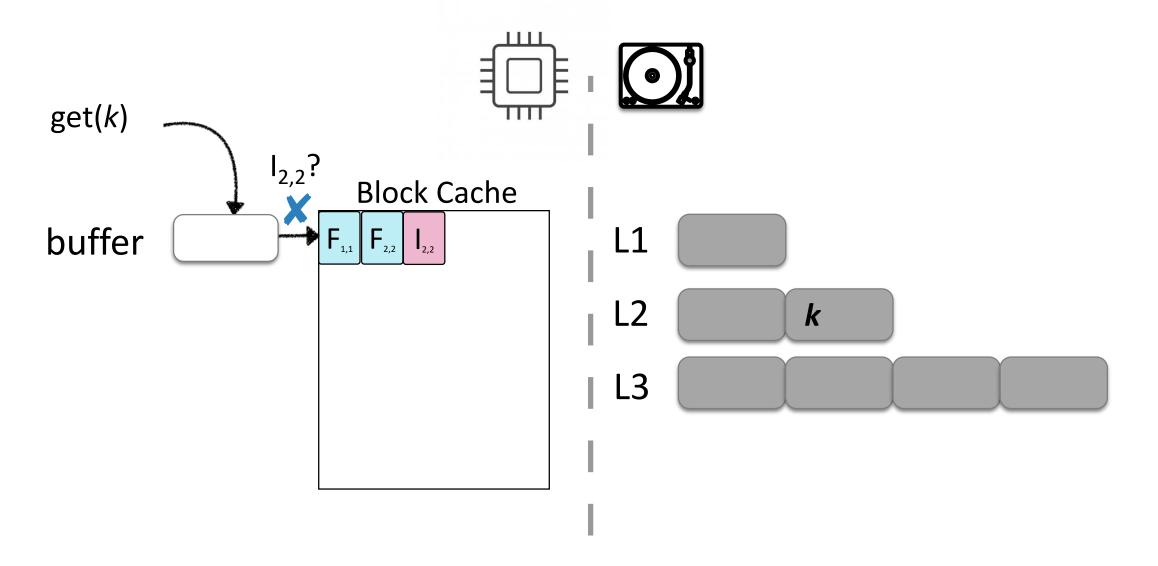






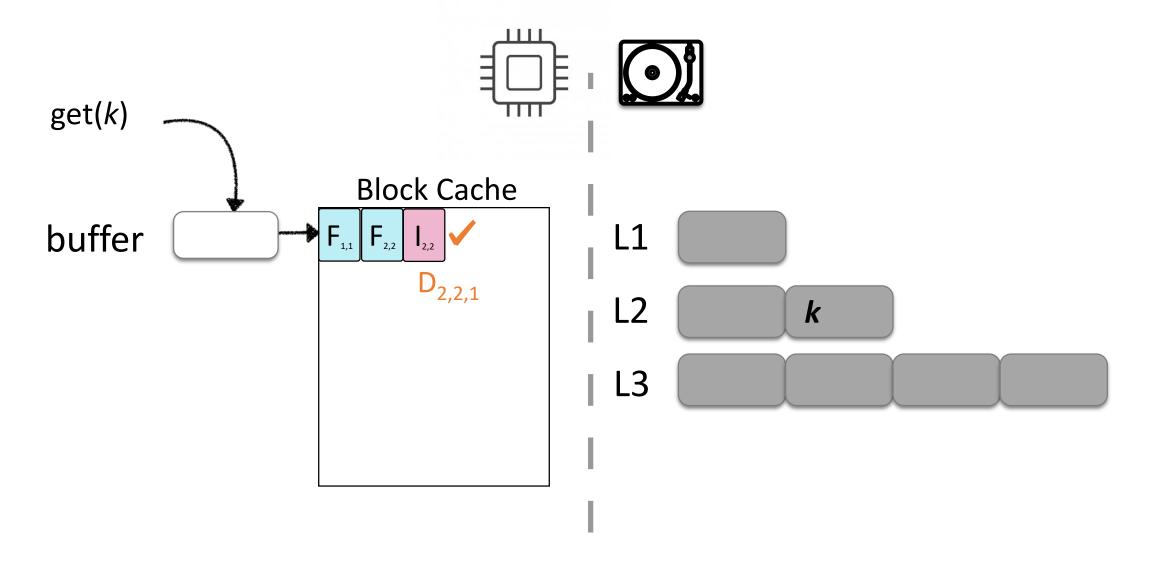






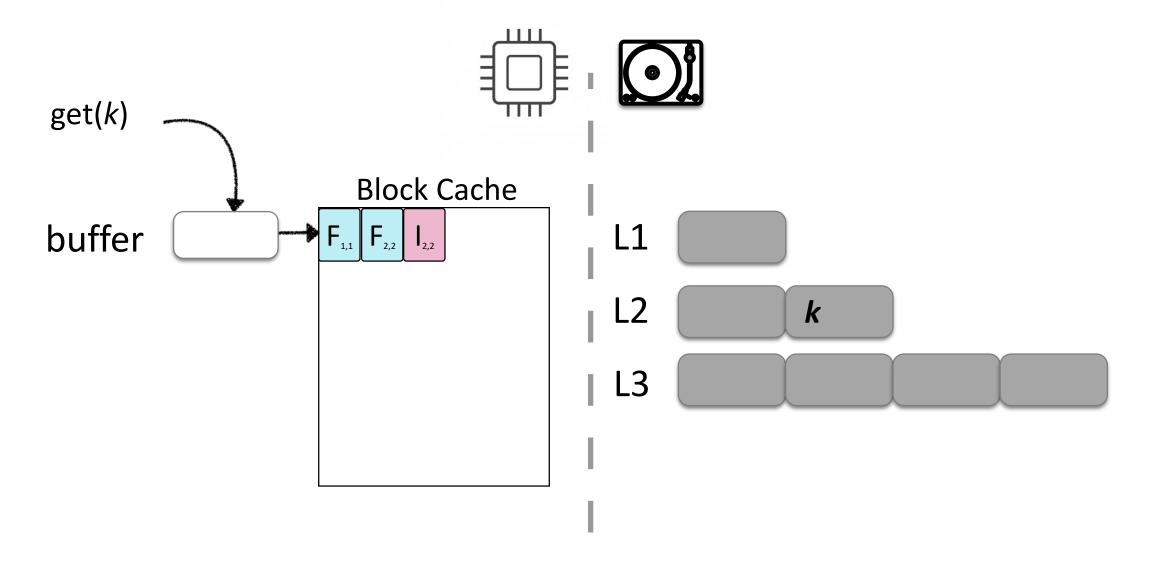






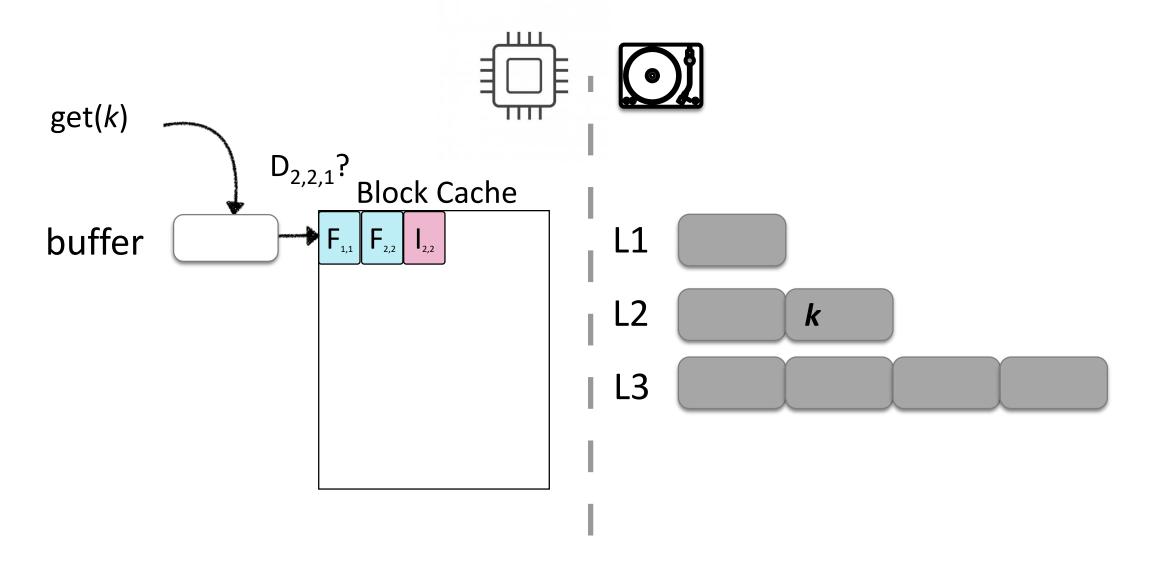






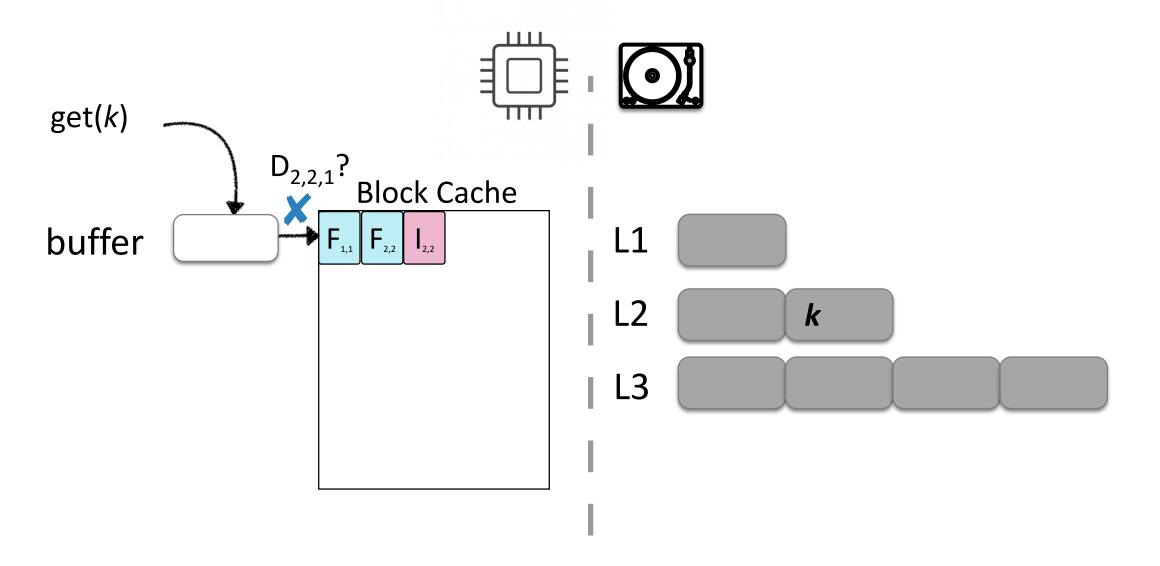






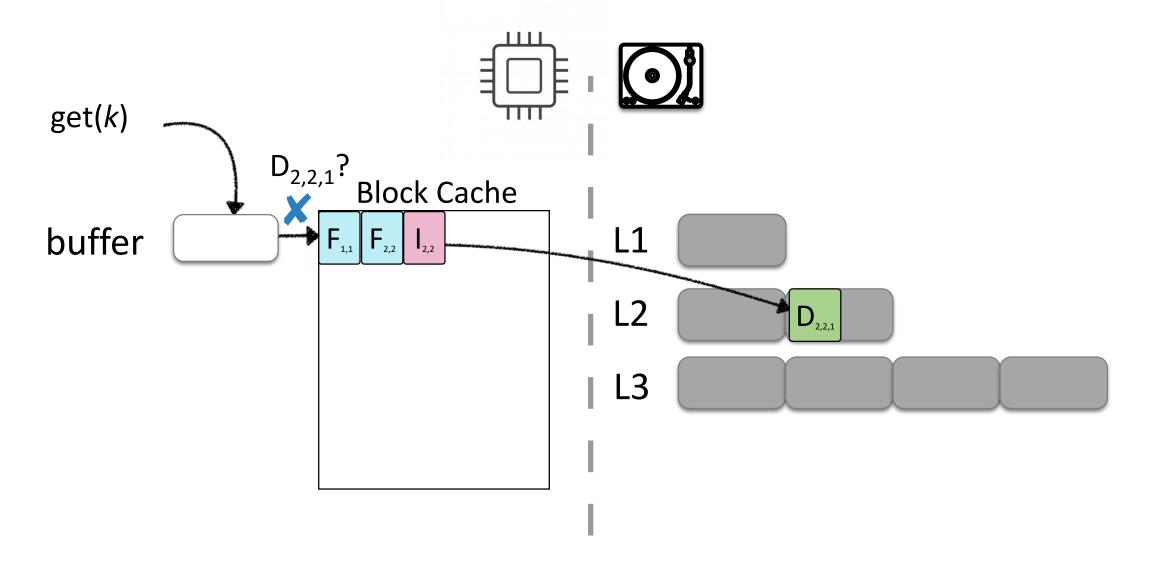






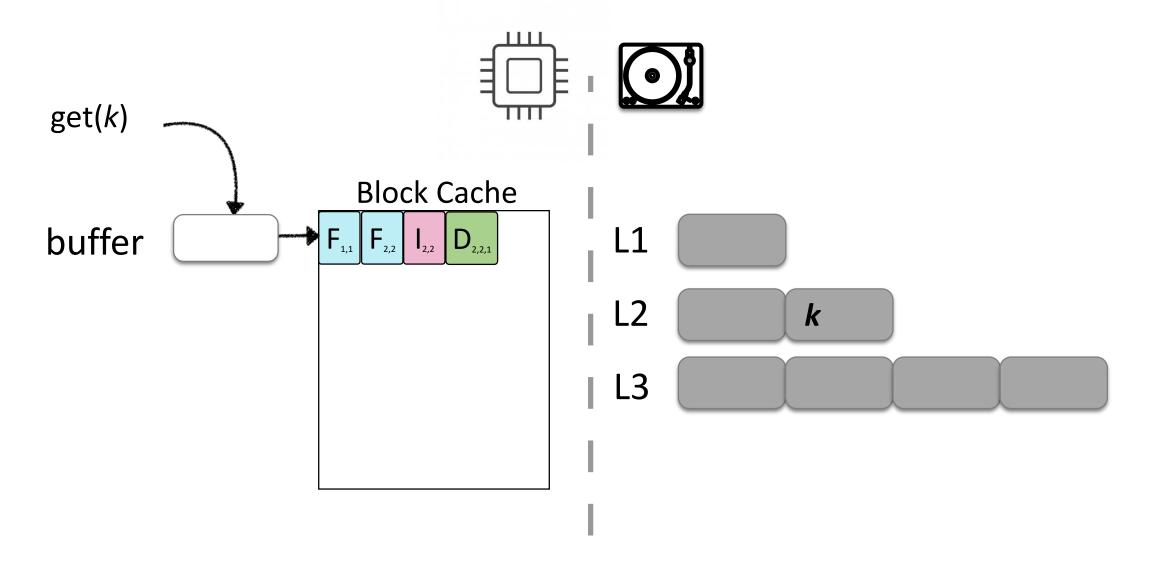






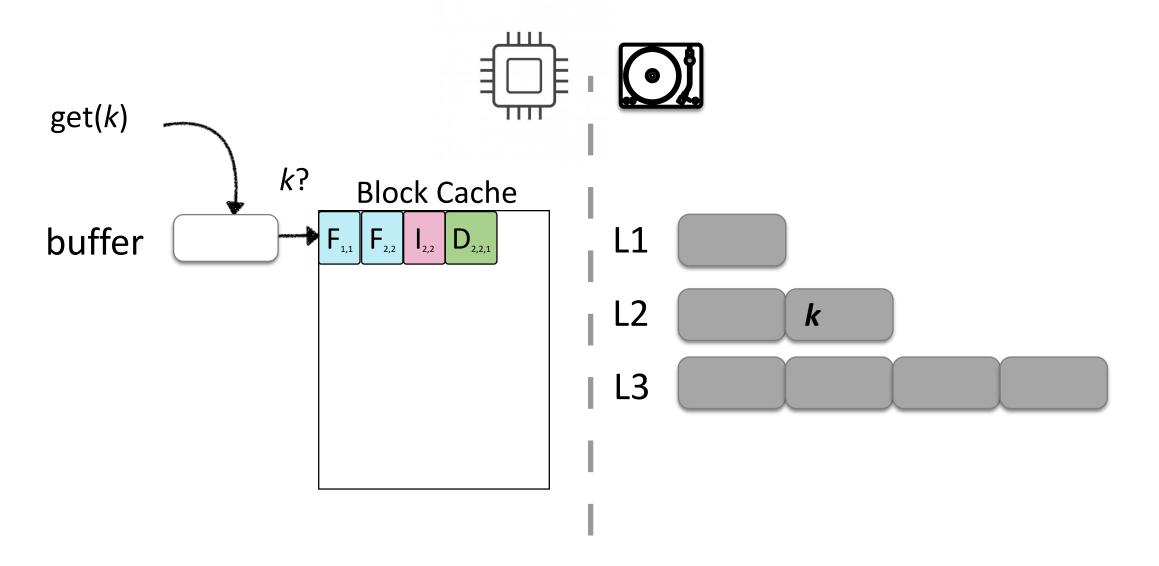






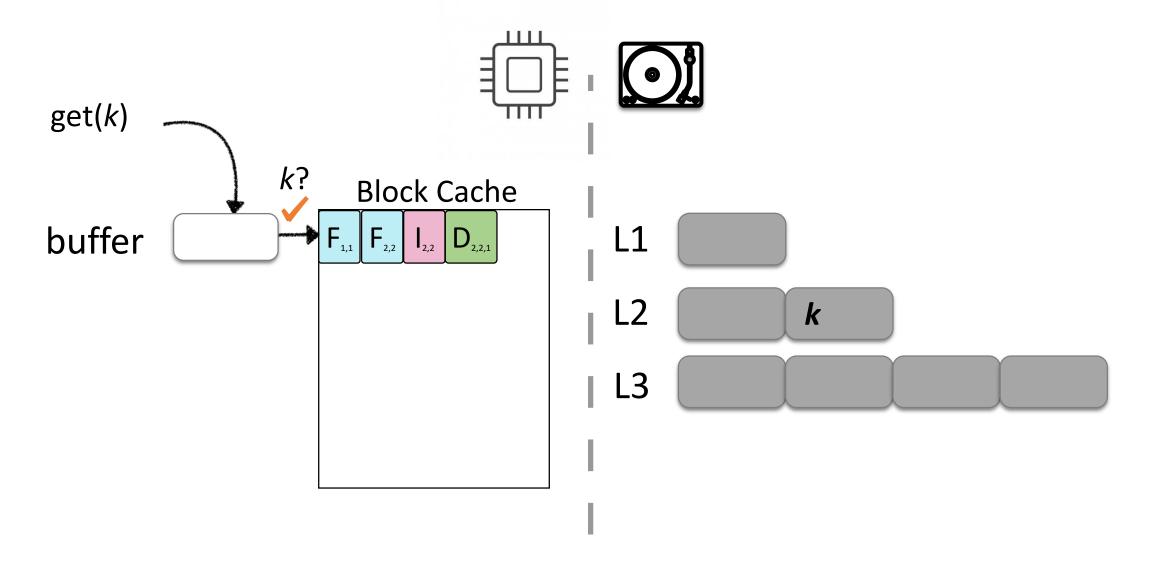






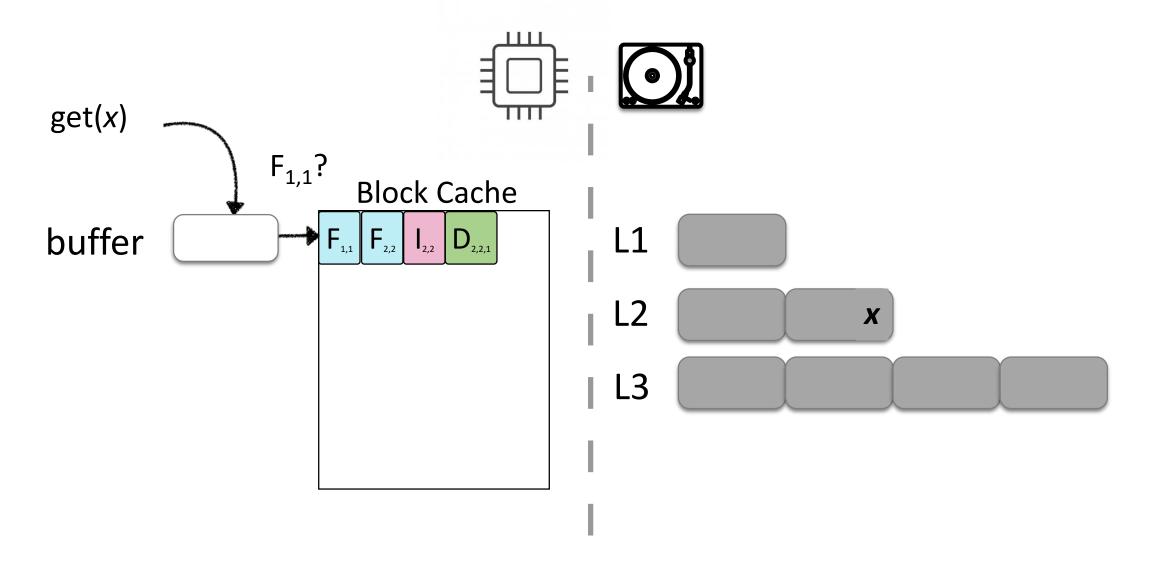






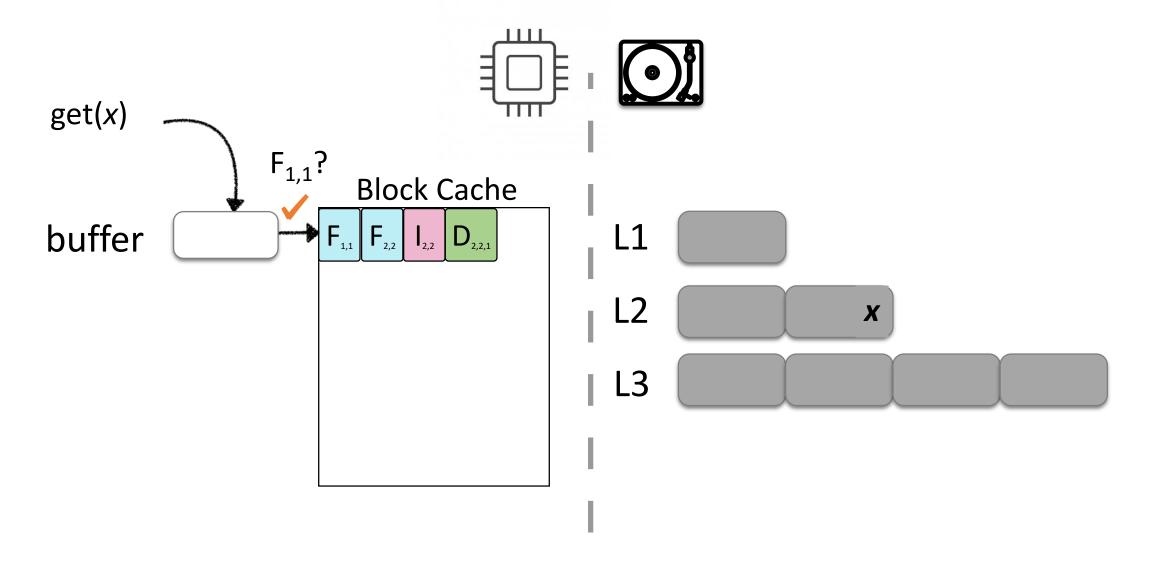






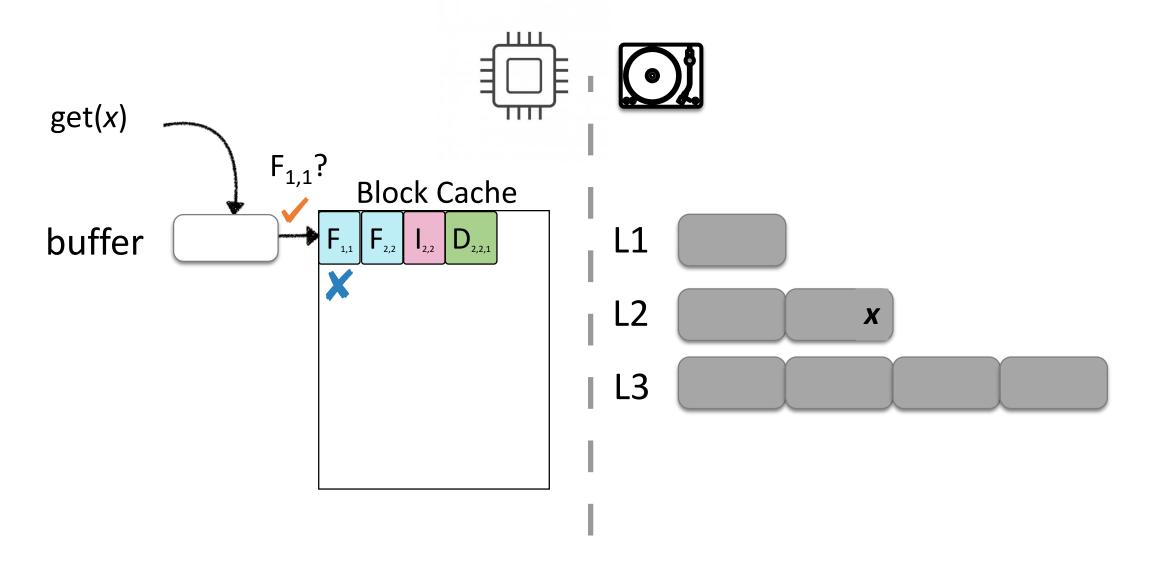






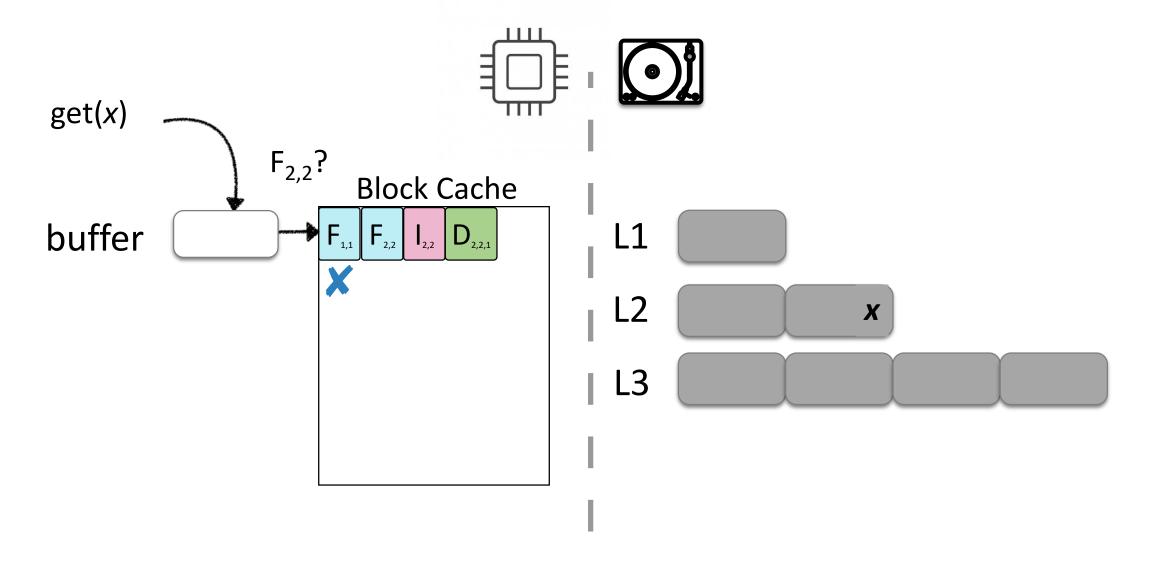






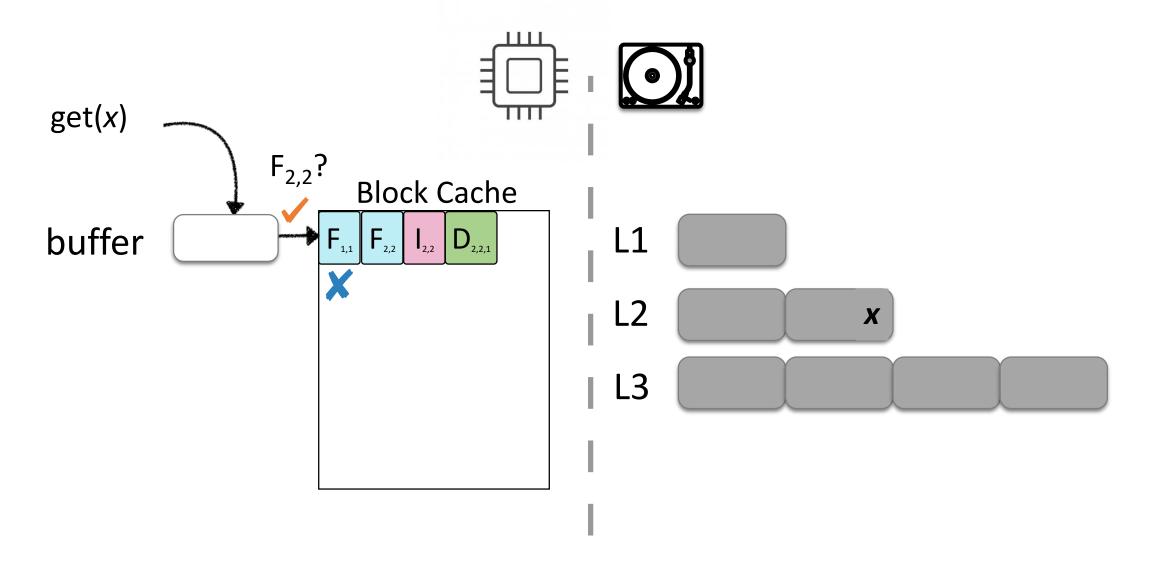






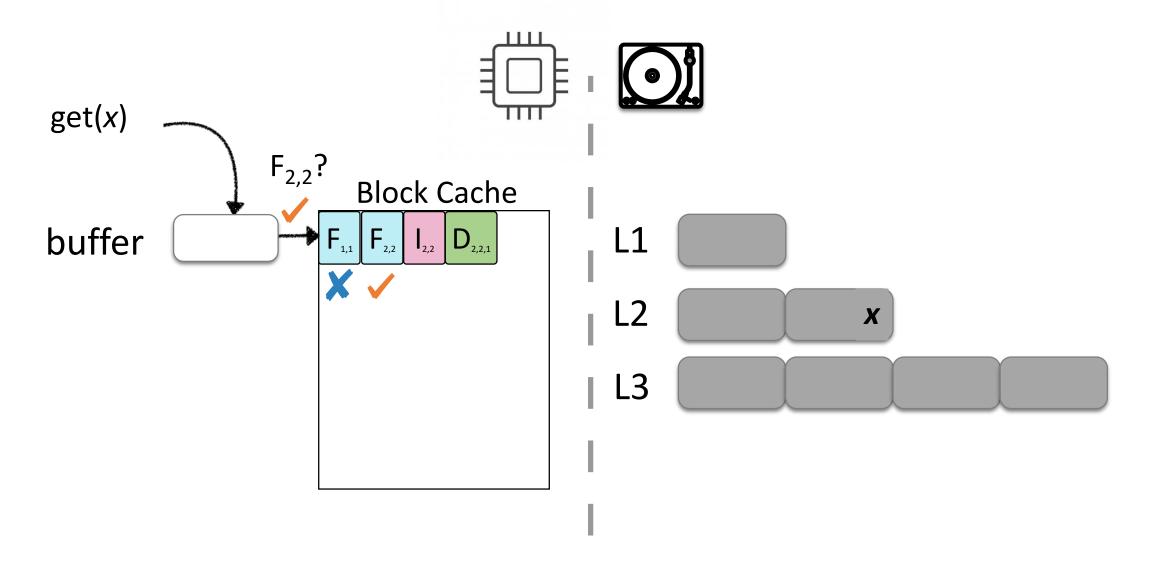






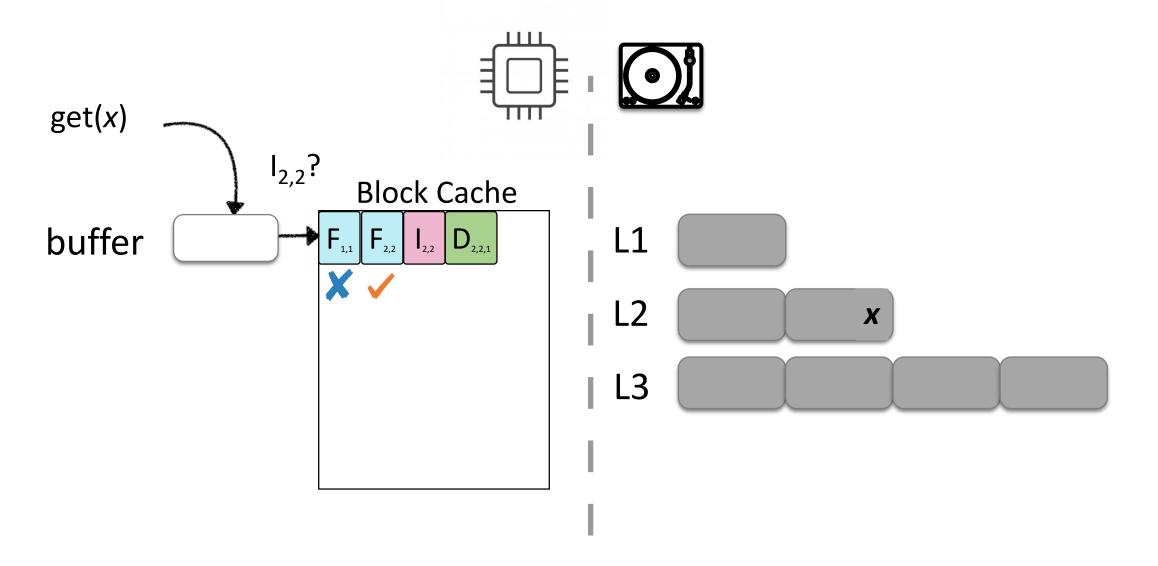






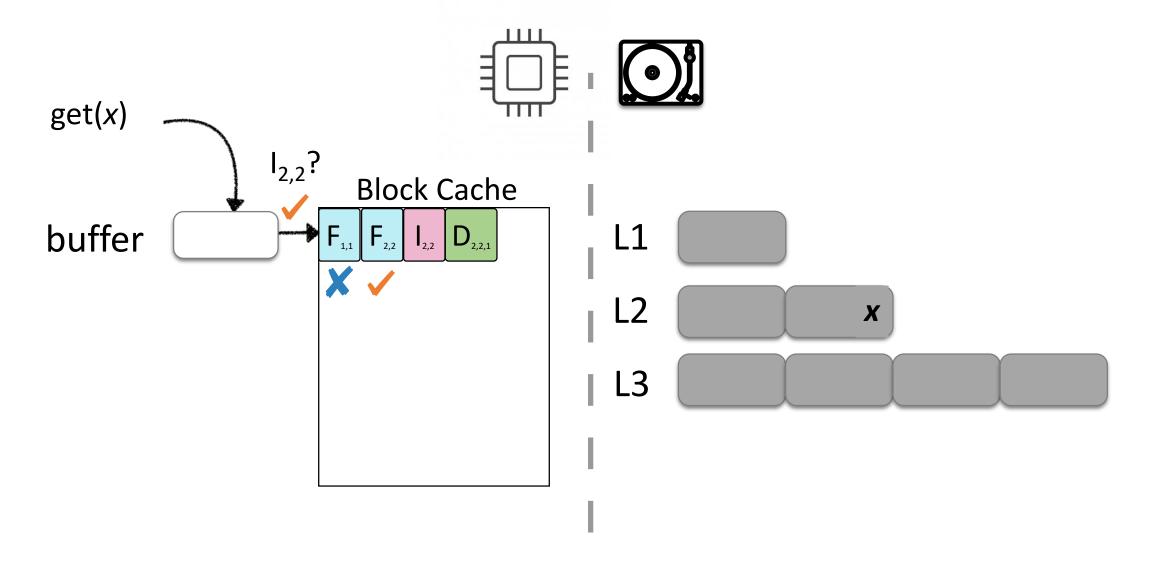






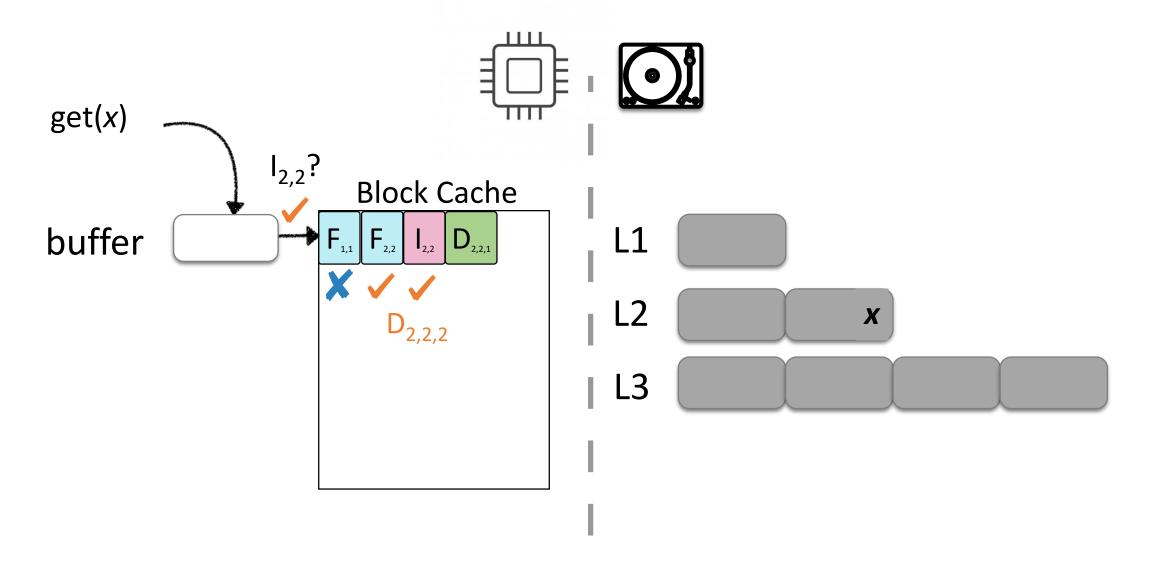






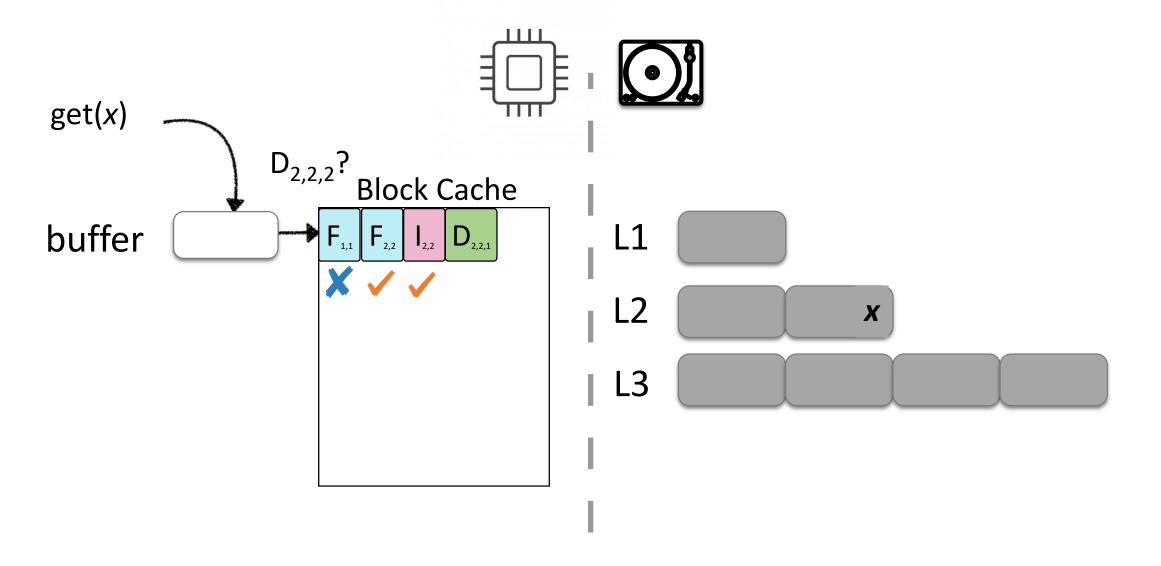






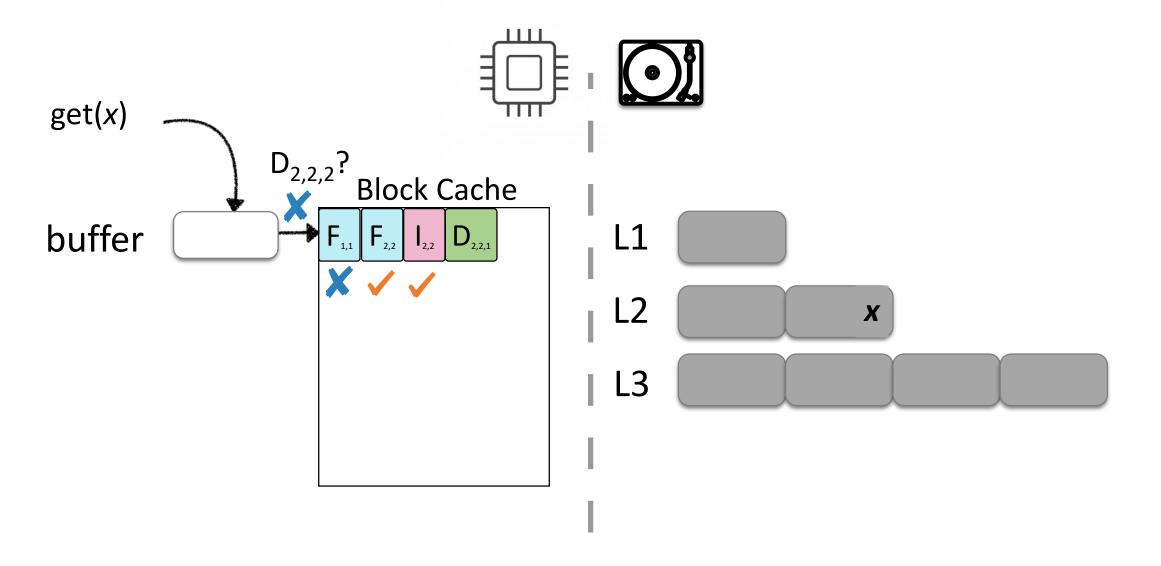






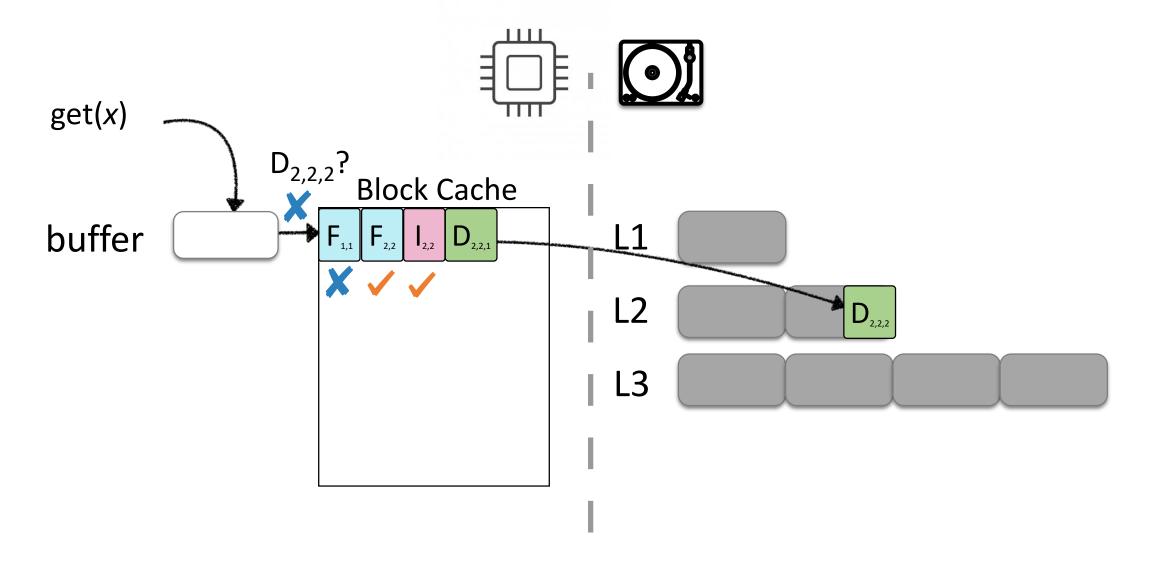






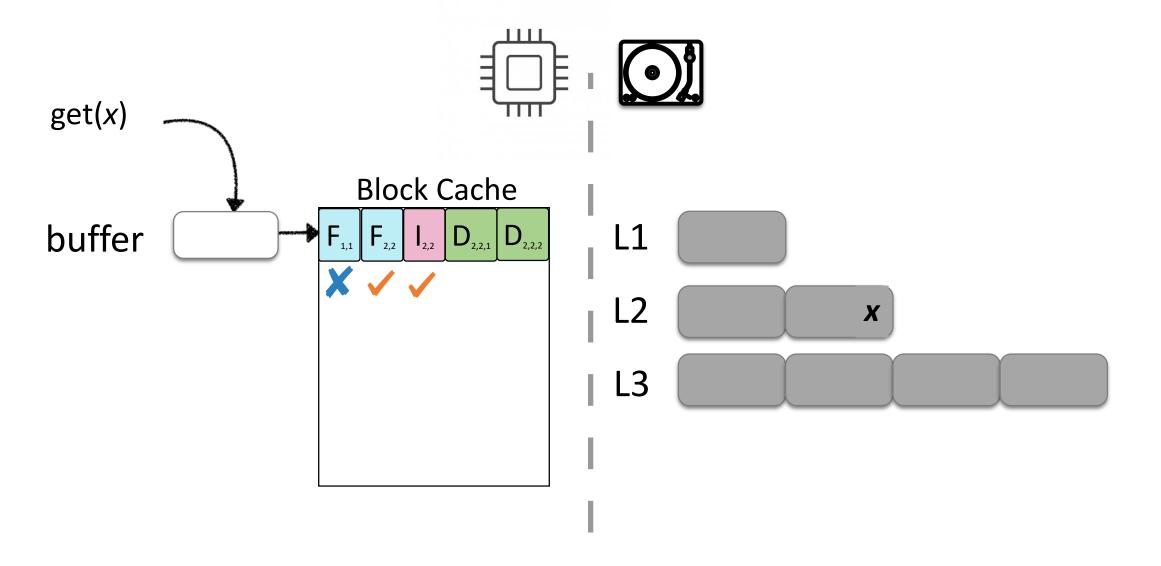






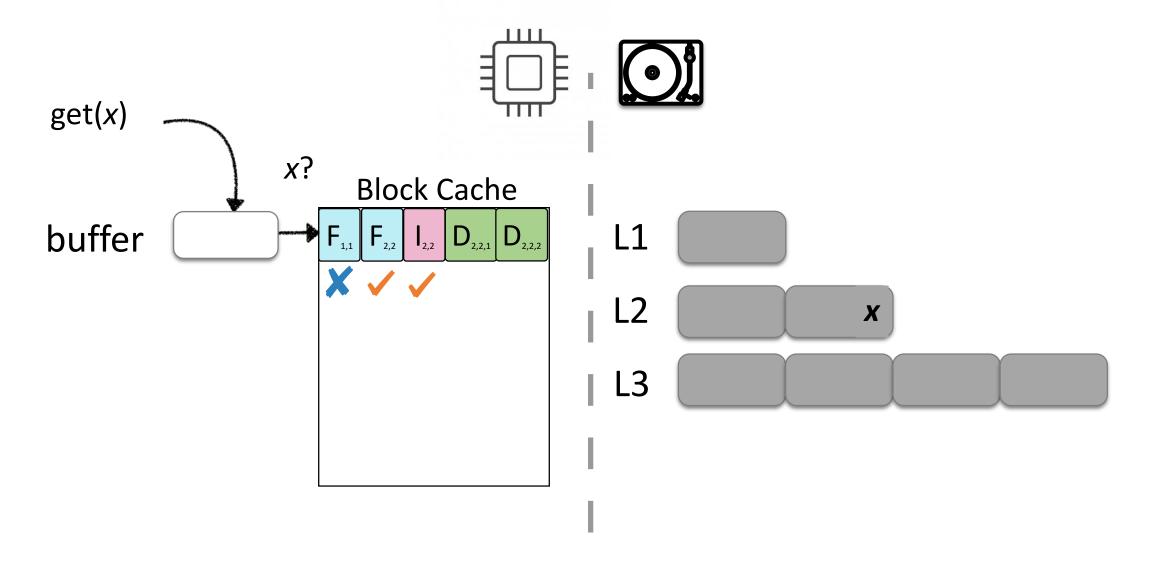






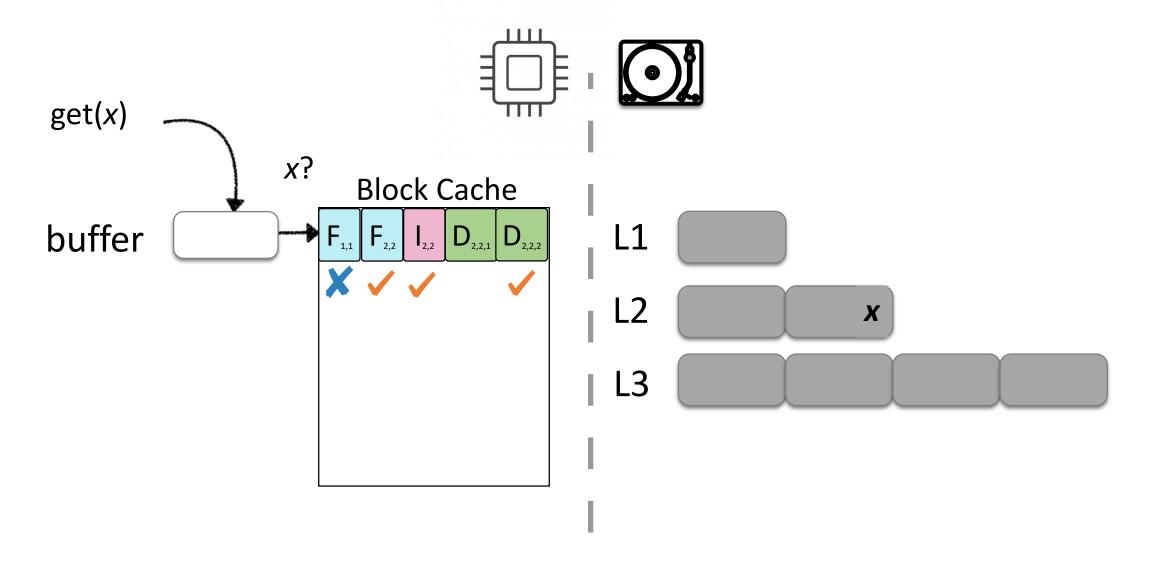






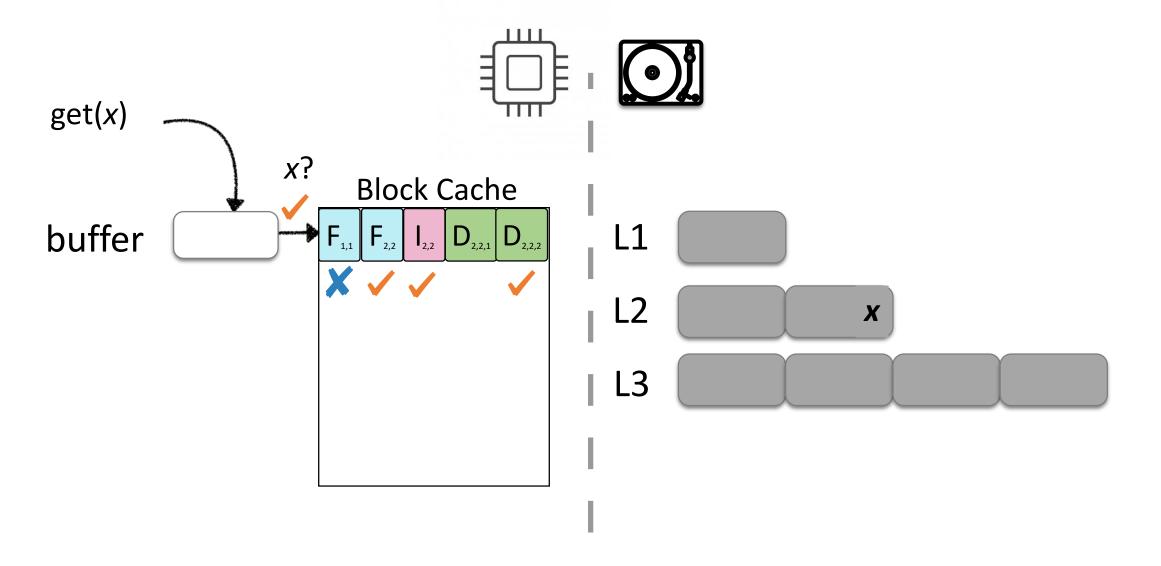
















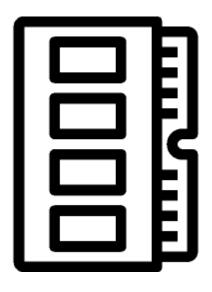
## Memory Pressure in LSM-trees



Data size ↑

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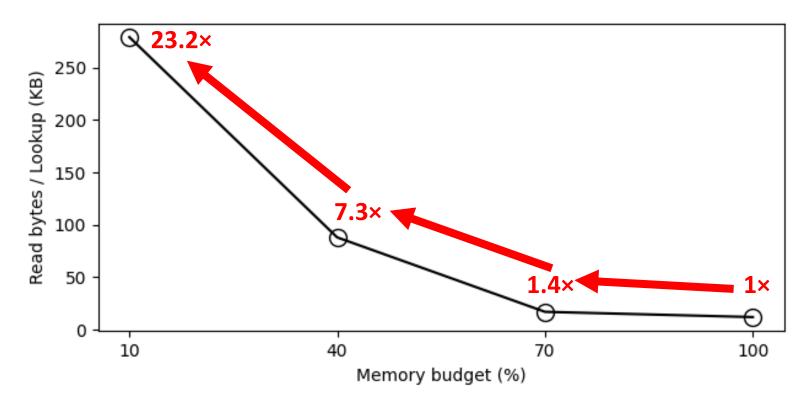


memory-to-data ratio ↓

Memory pressure



#### Lookup cost under memory pressure



As the available memory decreases, the read bytes per query increase rapidly.





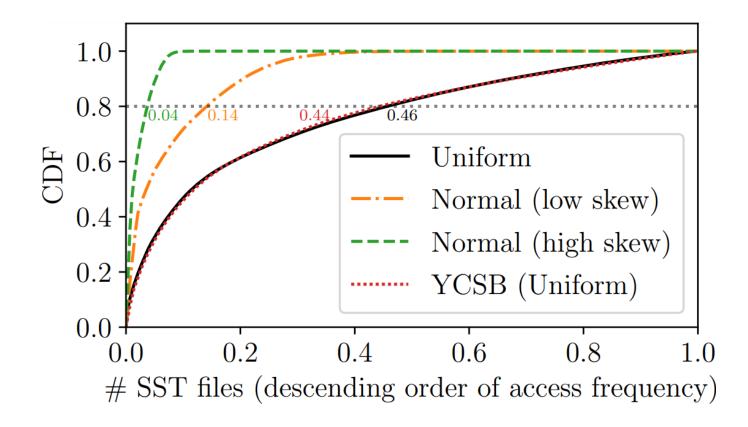


# Are all filter blocks equally important?





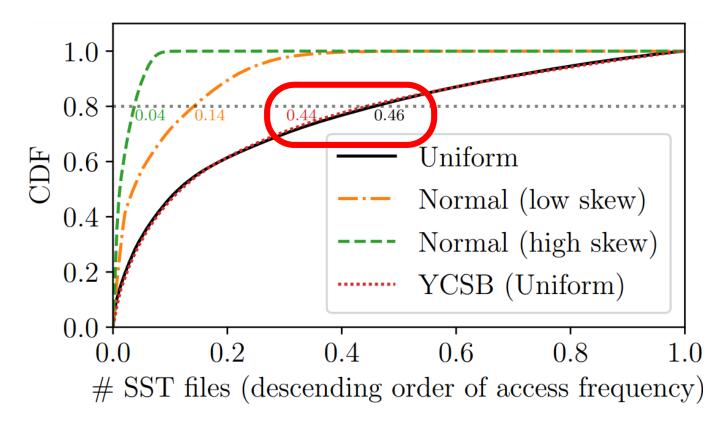
#### Access Frequency Patterns







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Even in a perfectly uniform workload, 80% of the lookups are directed to 44~46% of the SST files





memory

Bloom filters

p

p

p

[Monkey, SIGMOD 2017]

# worst-case I/O cost

$$O\left(\sum_{i} p\right)$$

false positive 
$$p = e^{-\frac{\text{bits } M}{\text{entries } N} \cdot ln(2)^2}$$





memory



Bloom filters



p

p

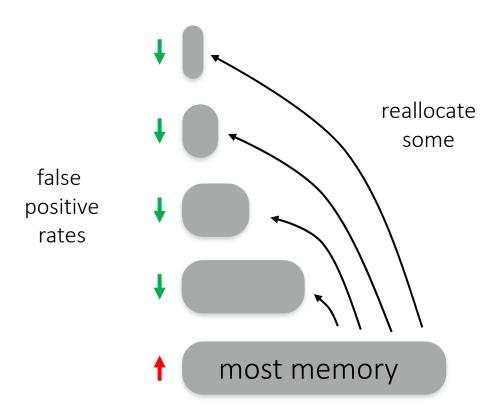
[Monkey, SIGMOD 2017]

# worst-case I/O cost

$$O(log(N) \cdot e^{-M/N})$$

#### can we do better?

# Bloom filters same memory, fewer I/O





[Monkey, SIGMOD 2017]

relax

model

optimize

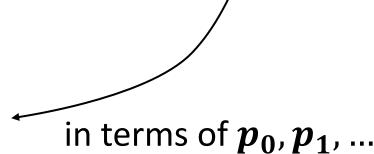
$$0 < p_2 < 1$$

$$0 < p_1 < 1$$

$$0 < p_0 < 1$$

$$lookup cost = \sum p_i$$

memory footprint = 
$$f(p_0, p_1, ...)$$
 in terms of  $p_0, p_1, ...$ 





### Bloom filters

# memory footprint

[Monkey, SIGMOD 2017]

false positive rates 
$$p_1$$

false positive 
$$p = e^{-\frac{\text{bits } M}{\text{entries } N} \cdot ln(2)^2}$$

bits
$$(\boldsymbol{p}, \boldsymbol{N}) = -\frac{ln(\boldsymbol{p})}{ln(2)^2} \cdot \boldsymbol{N}$$

$$lookup cost = \sum p_i$$



### Bloom filters

 $p_2$ 

false positive rates

 $p_0$ 

memory footprint

bits
$$(\boldsymbol{p}, \boldsymbol{N}) = -\frac{ln(\boldsymbol{p})}{ln(2)^2} \cdot \boldsymbol{N}$$

bits $(p_2, N/T^2)$  bits $(p_1, N/T)$ 

bits $(p_0, N)$ 

lookup cost = 
$$\sum p_i$$

memory = 
$$-\frac{N}{ln(2)^2} \cdot \sum \frac{ln(p_i)}{T^i}$$



[Monkey, SIGMOD 2017]

### Bloom filters

minimize:

$$lookup cost = \sum p_i$$

• • •

 $p_2$ 

false positive rates

 $p_1$ 

 $p_0$ 

w.r.t.

$$\boldsymbol{M} = -\frac{\boldsymbol{N}}{\ln(2)^2} \cdot \sum \frac{\ln(p_i)}{\boldsymbol{T}^i}$$

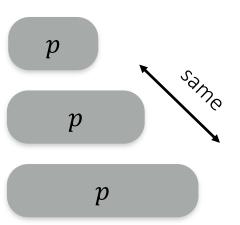
# Monkey Bloom filters $p_0/T^2$ false positive rates $p_0/T$ $p_0/T$

[Monkey, SIGMOD 2017]

### State-of-the-art

Bloom filters

• • •





[Monkey, SIGMOD 2017]



### Monkey

Bloom filters

false positive rates

$$p_0/1$$

$$p_0/T$$
  $<$   $p$ 

$$p_0$$
 >  $p$ 

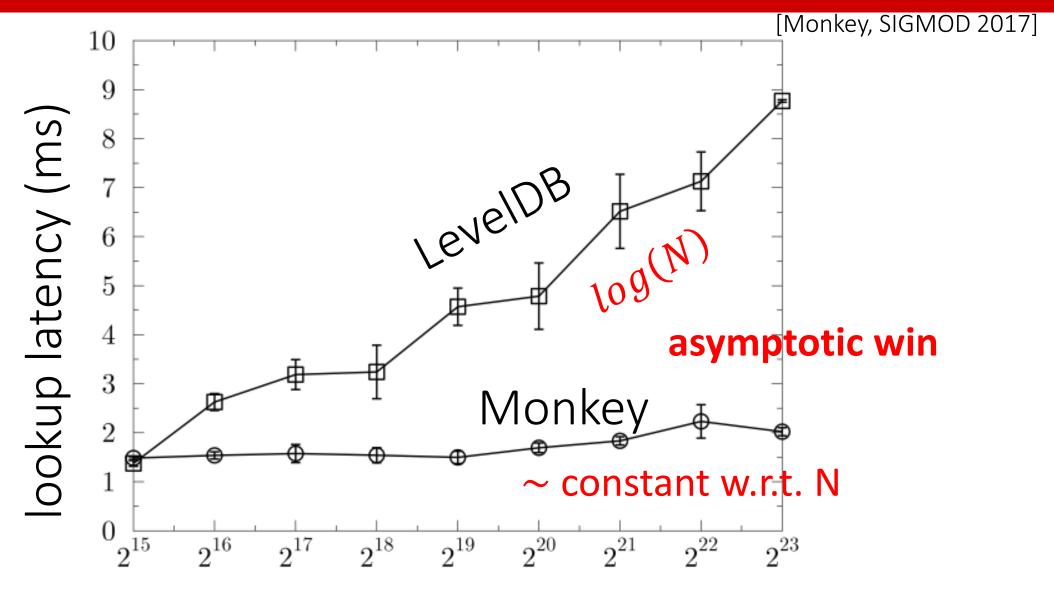
lookup cost = 
$$\sum p_i$$
 =  $\sum p$   
=  $O(e^{-M/N})$  =  $O(log(N) \cdot e^{-M/N})$ 

### asymptotic win

lookup cost increases at slower rate as data grows

### State-of-the-art

Bloom filters

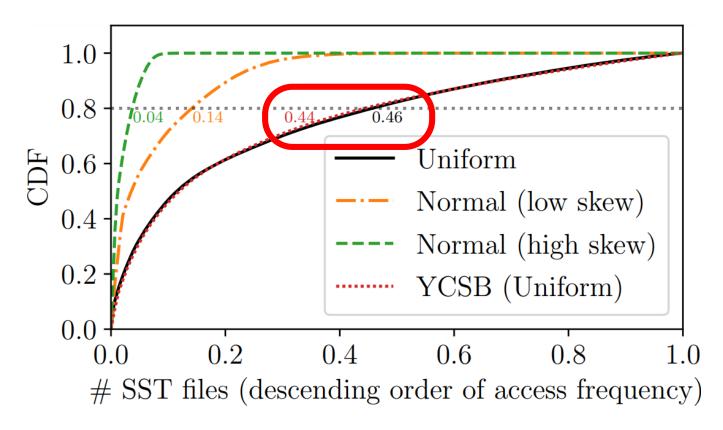


N: number of entries (log scale)





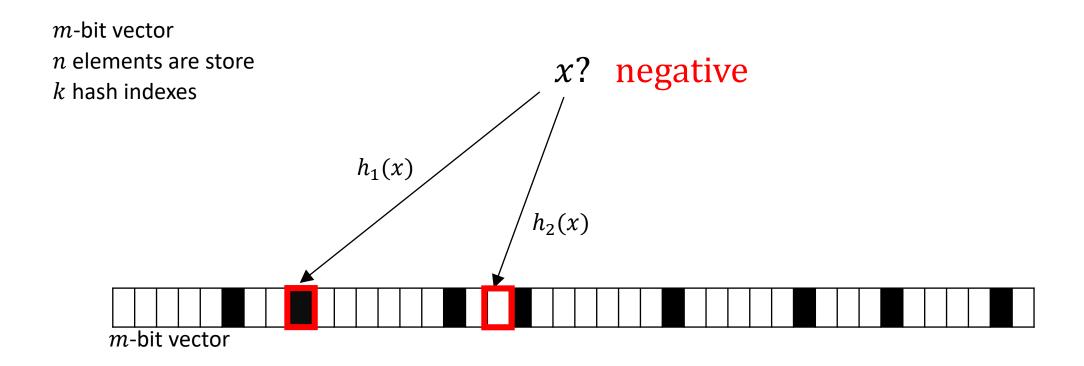
### Access Frequency Patterns



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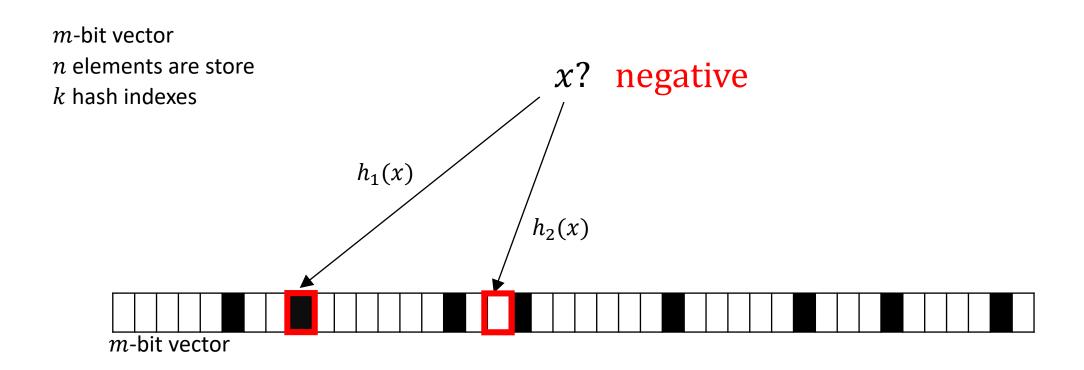






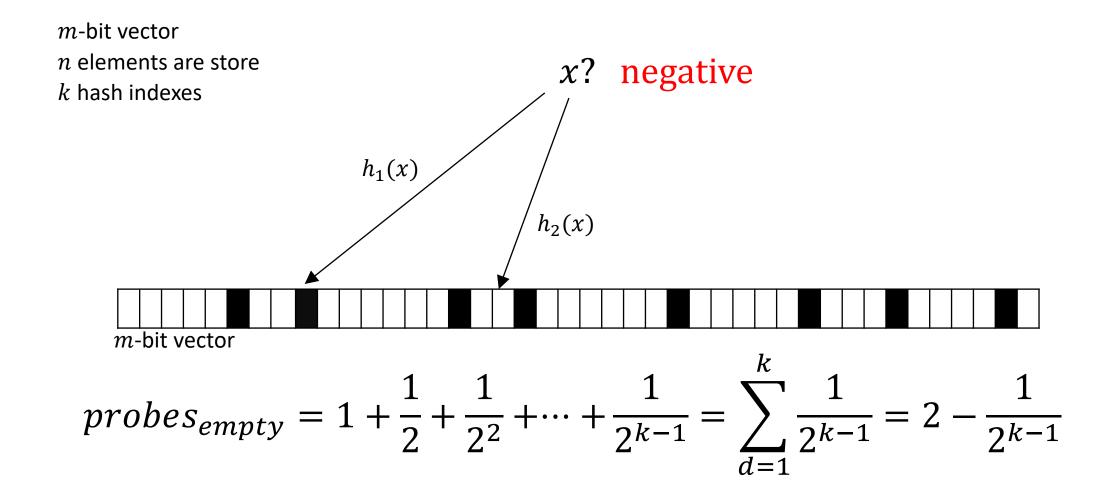




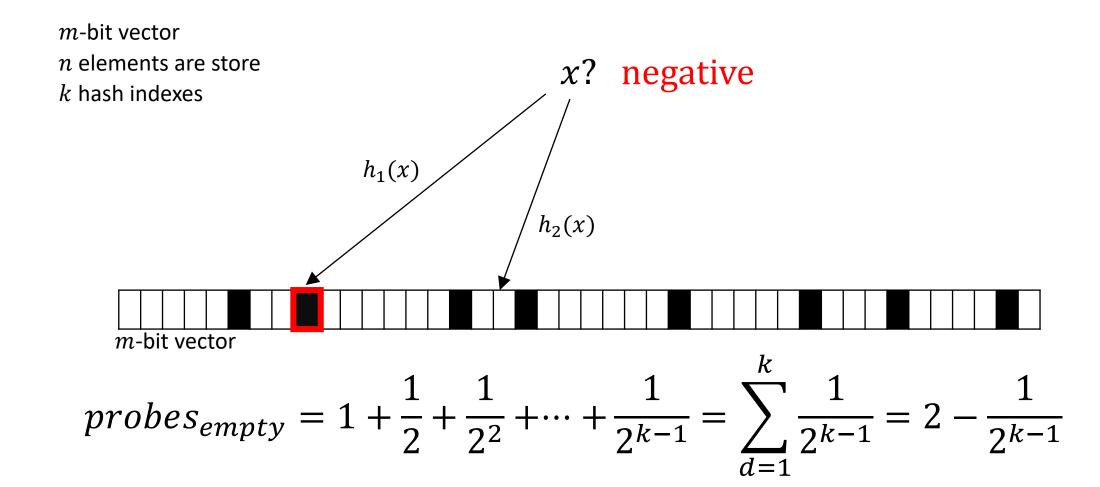


Is the entire filter useful?

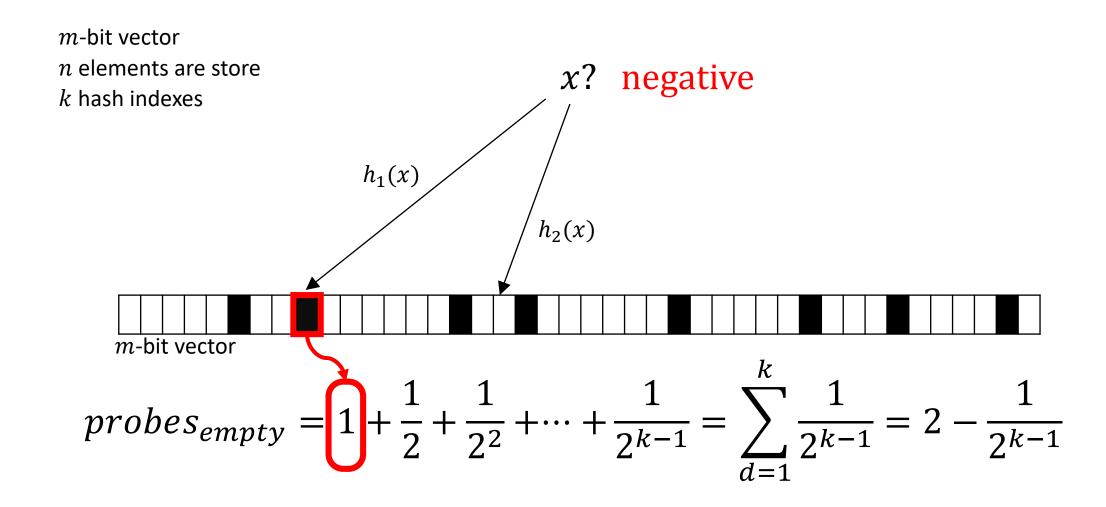


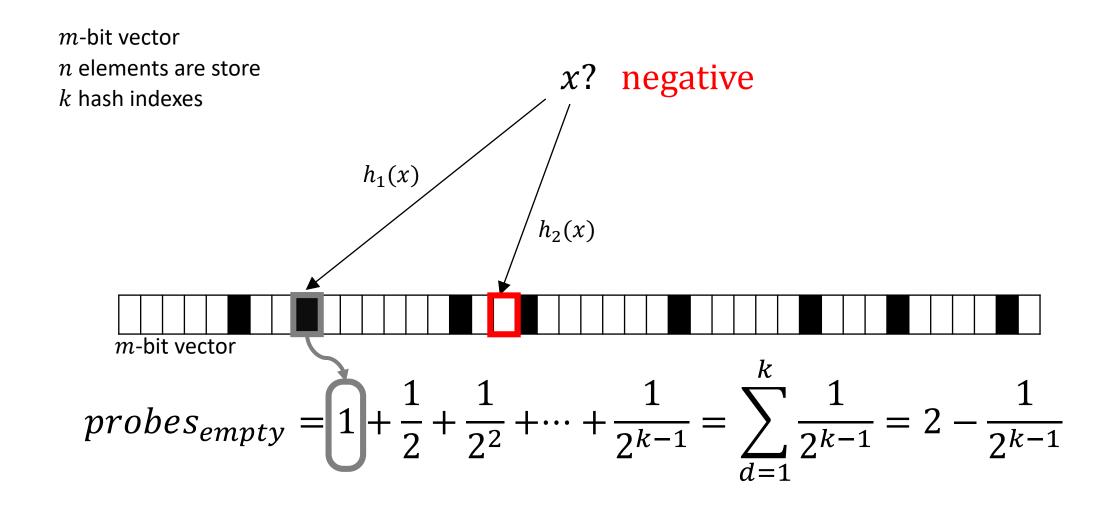


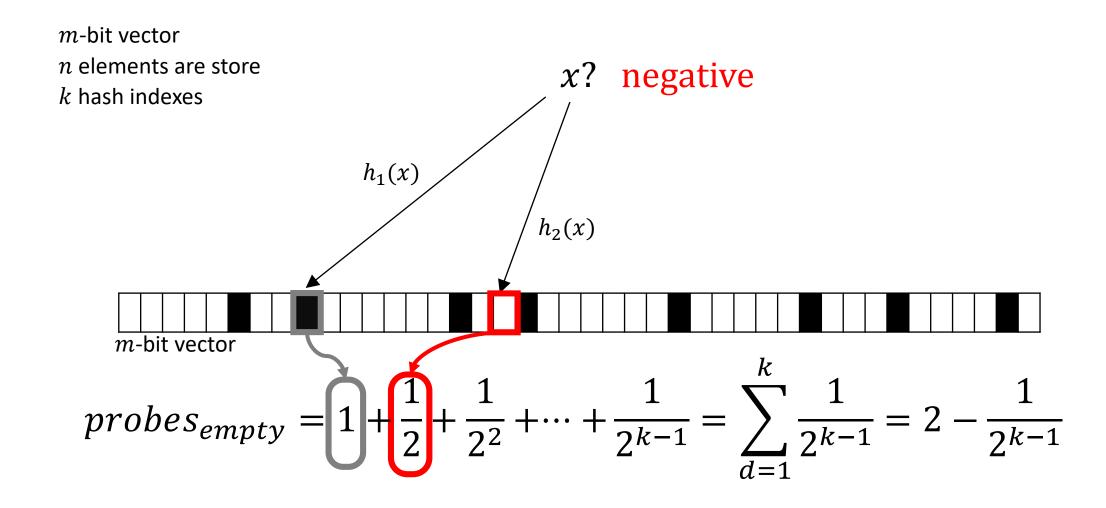


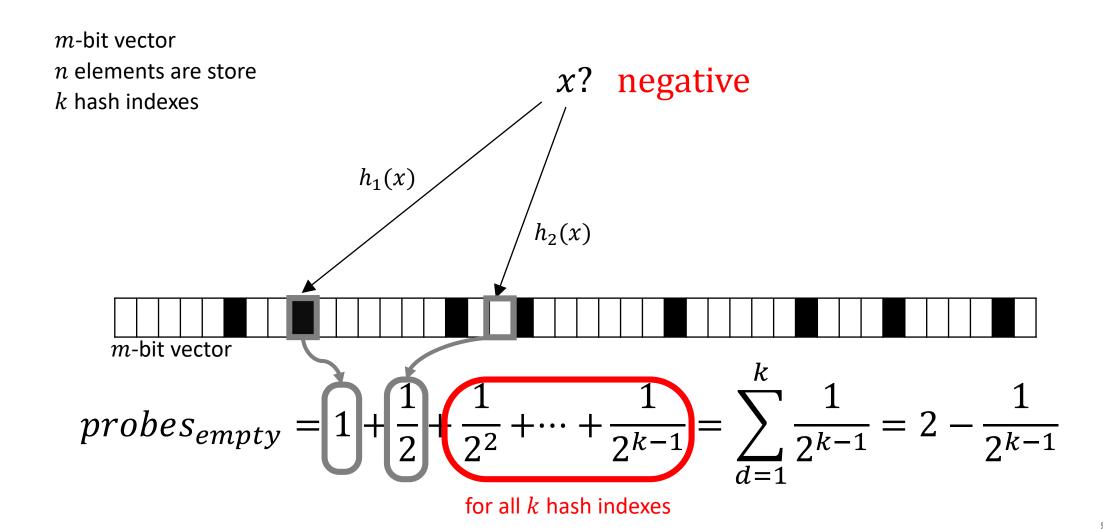




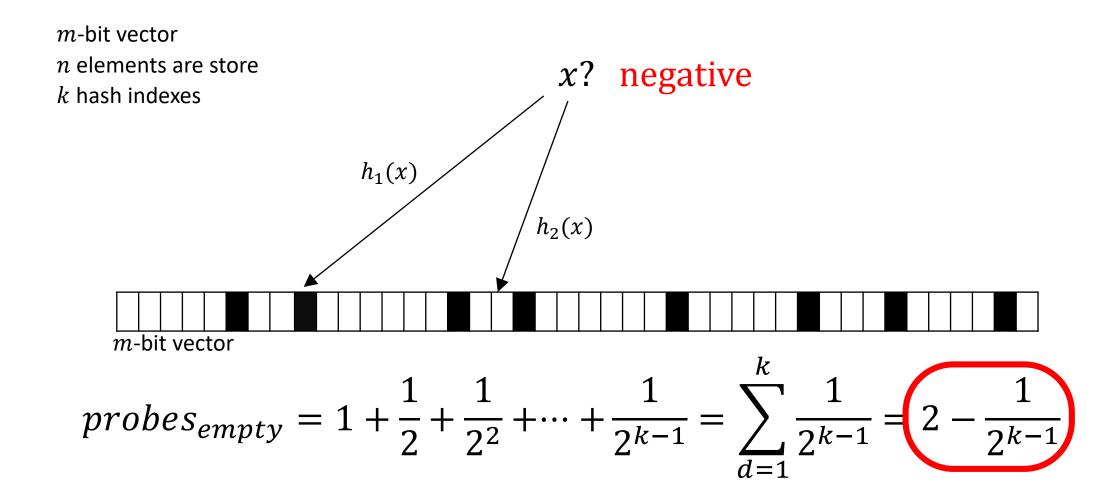








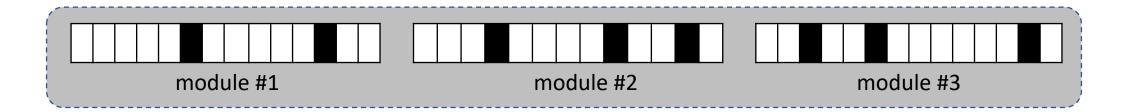






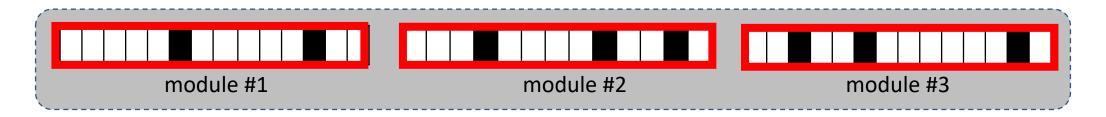


m-bit vector n elements are store k hash indexes d modules





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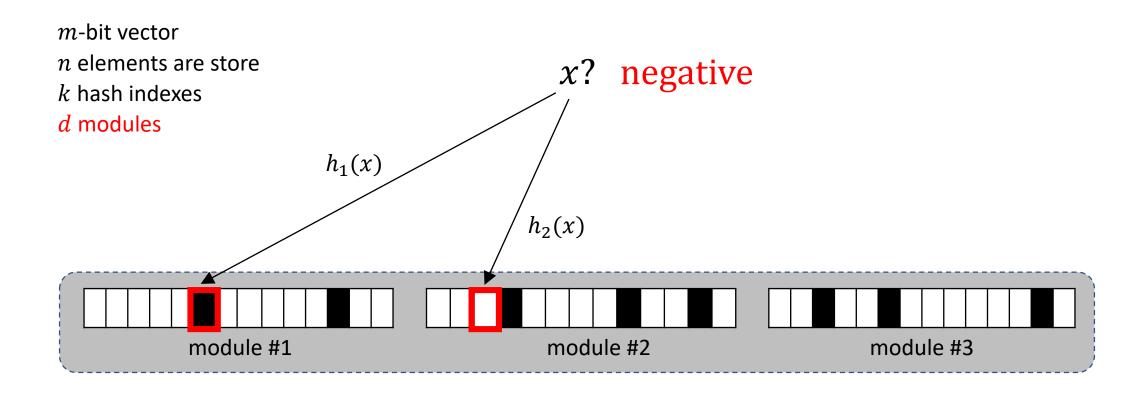


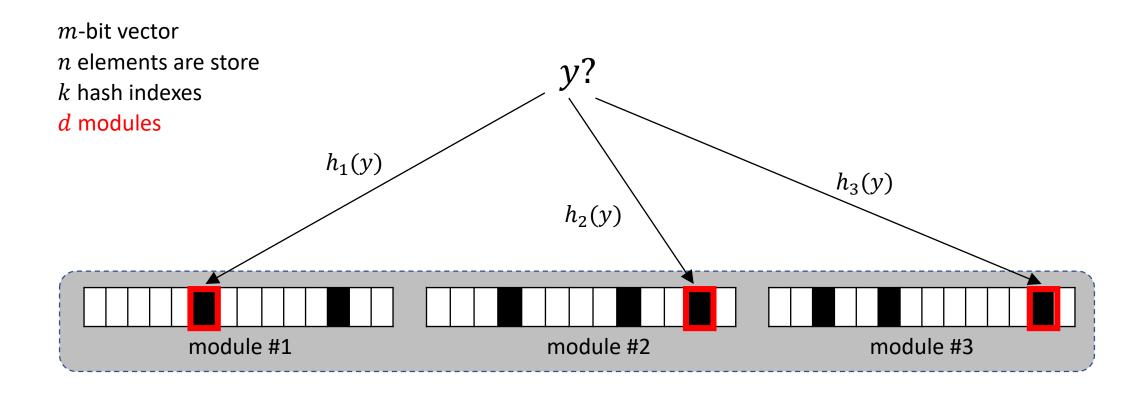
An MBF is a collection of *D* Bloom filters

- $m_d$ -bit vector
- *n* elements
- $-k_d$  hash indexes



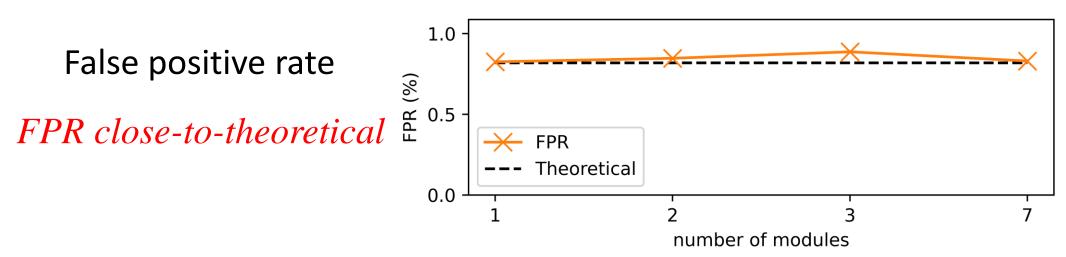






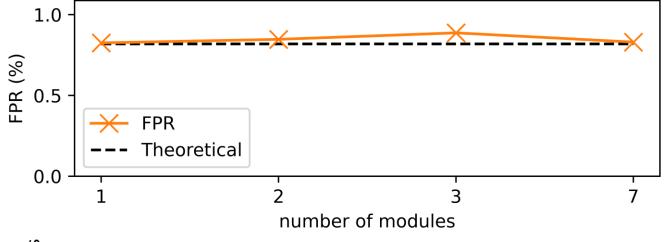


False positive rate



False positive rate

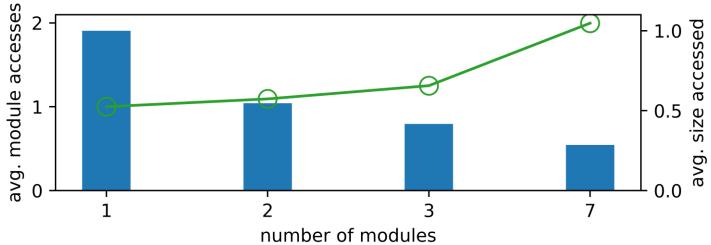
FPR close-to-theoretical



Avg. # of module accesses vs.

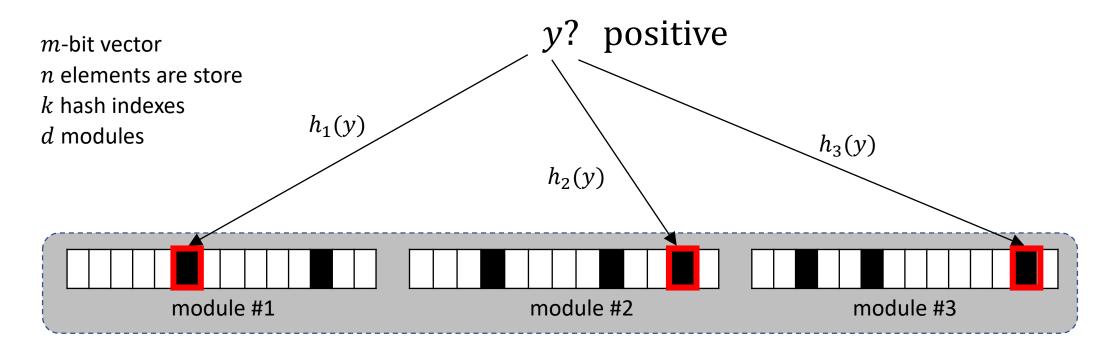
Avg. size accessed

Less memory requirement



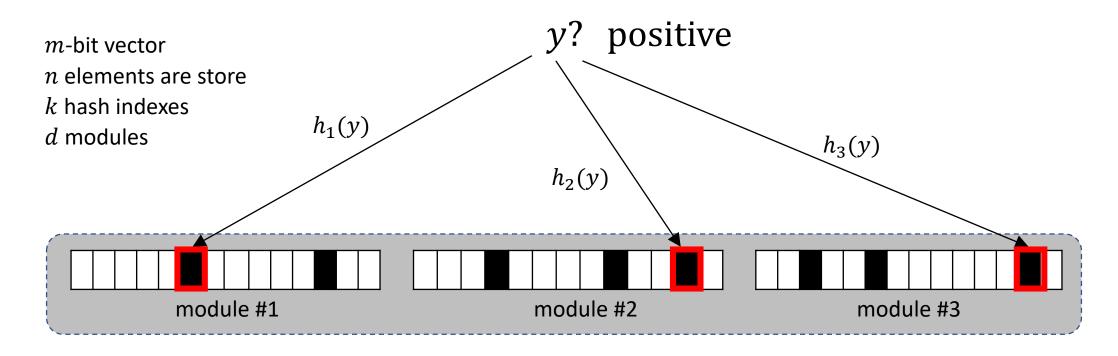






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What if we know something more about the queries?



*Utility*: a measure of the benefit of a filter or a module

$$u_{l,i,d} = expIO_{l,i,d} - expIO_{l,i,d-1}$$

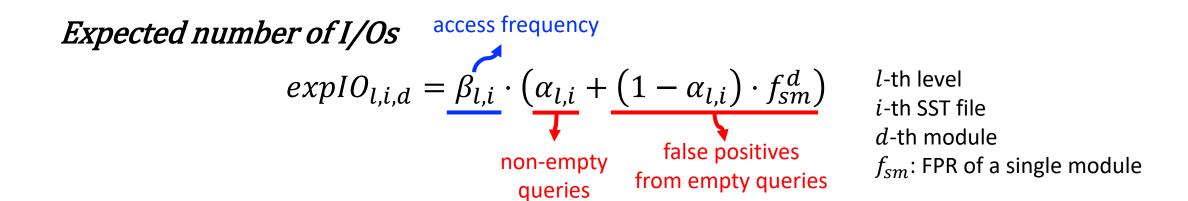
The expected number of I/Os that can be reduced by using d-th module



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The expected number of I/Os that can be reduced by using d-th module







Skipping Modules based on their utilities



Skipping Modules based on their utilities

```
u<sub>l,i,d</sub> = expIO(1,i,d) - expIO(1,i,d-1)

if u<sub>l,i,d</sub> < threshold<sub>d</sub> then
    return true

else
    result = QueryModule( key, module<sub>l,i,d</sub> )
```

Reducing Bloom Filter CPU Overhead in LSM-Trees on Modern Storage Devices, DaMoN 2021

Modular Bloom filter
&
Skipping Algorithm 
LSM-tree
&
Sharing Hashing

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Sharing Hashing with Modular Bloom filters (SHaMBa)



# **Experimental Evaluation**





### **Experiment Settings**

### LSM-tree tuning

Term	Value	Explanation
E	64	entry size (B)
K	32	key size (B)
В	64	block size (#entries)
Р	1024	buffer size/file size (#blocks)
Т	4	size ratio
b	10	bits per key for filters

### Size of blocks

Term	Value	Explanation
$S_D$	4	data block size (KB)
$\mathcal{S}_{I}$	32	index block size (KB)
$\mathcal{S}_F$	80	filter block size (KB)



## **Approaches Tested**

### Tuning knobs of SHaMBa

Term	Value
number of modules	1, <b>2</b> , 3, or 7
Size of each module	equal
skipping algorithm	none, partial ( $\mathcal P$ ), or <i>full (<math>\mathcal F</math>)</i>

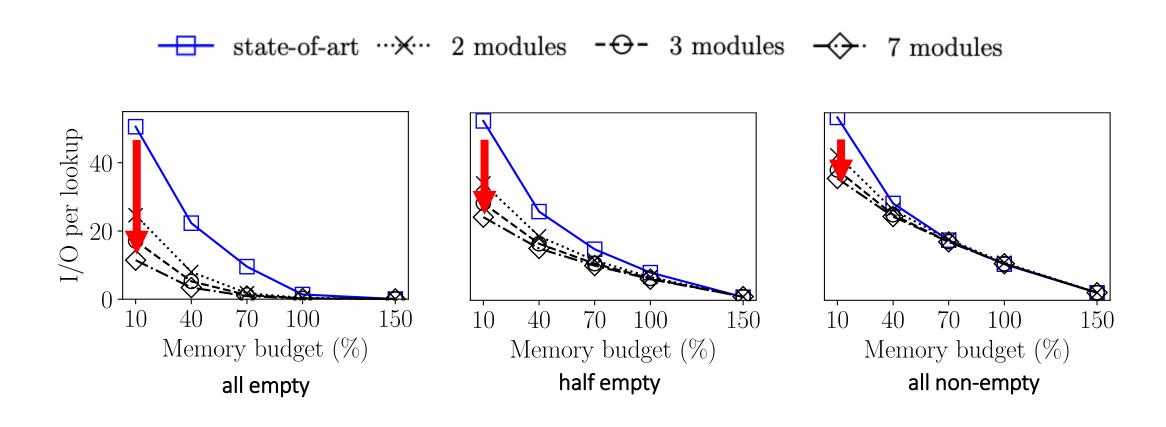
### **Approaches Tested**

- state-of-the-art
- SHaMBa-eq
- SHaMBa-eq-P
- SHaMBa-eq-F



### Impact of number of modules

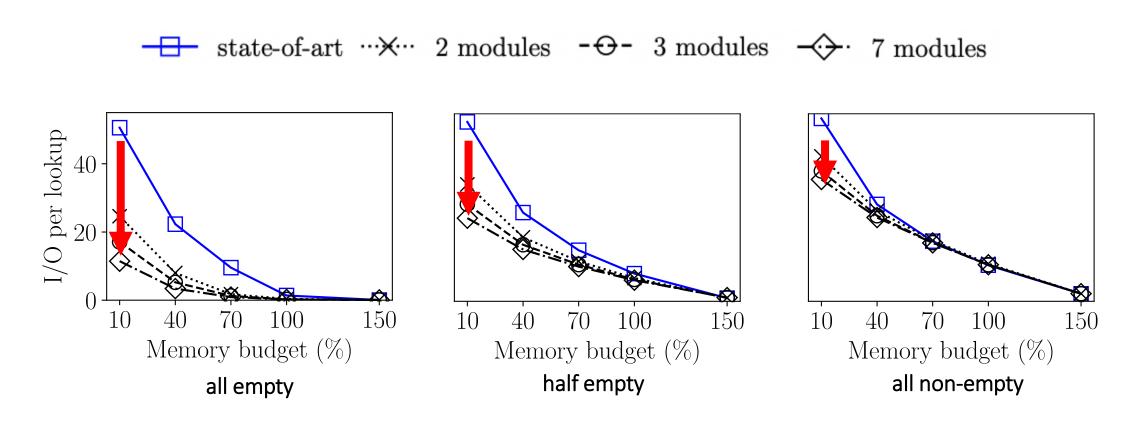
Workload: Uniform, Entry size: 64B, #Entries: 30K Tuning: no skipping algorithm, equal sized modules





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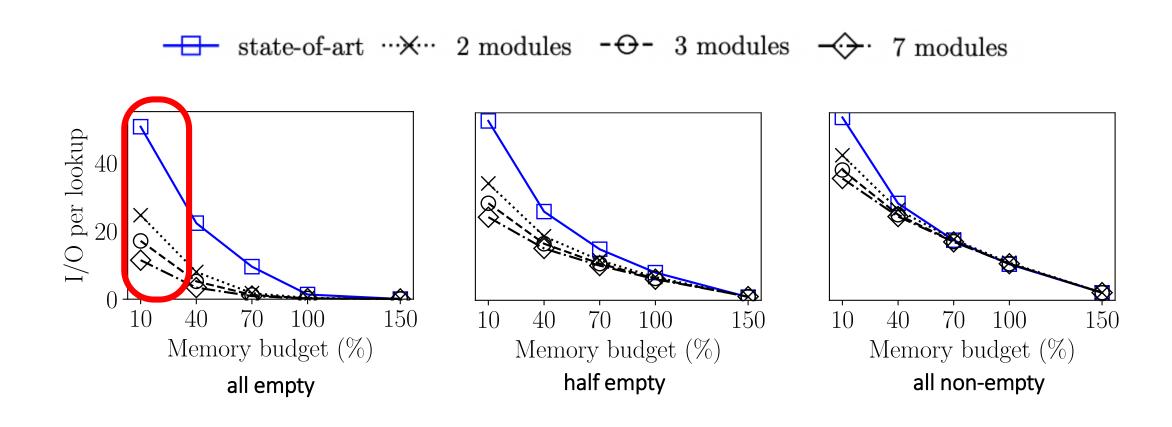


SHaMBa enhances the lookup performance for empty queries



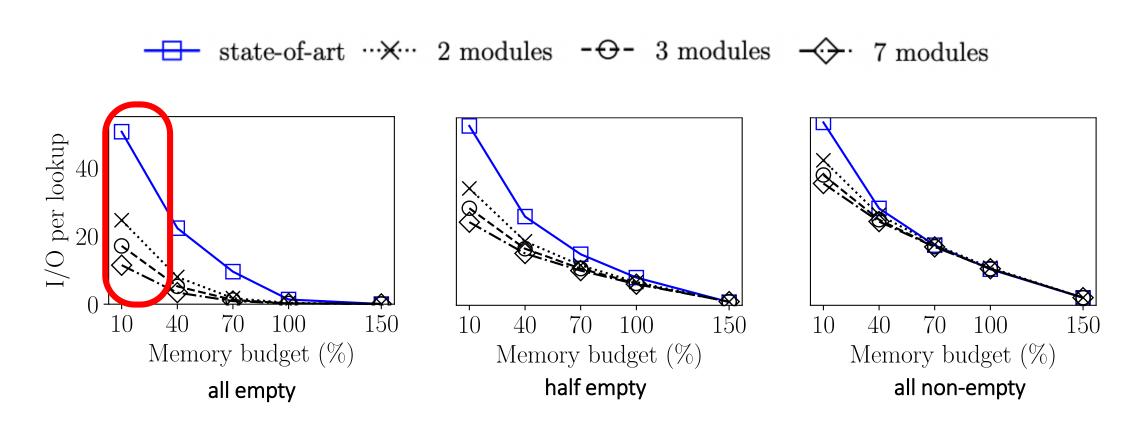
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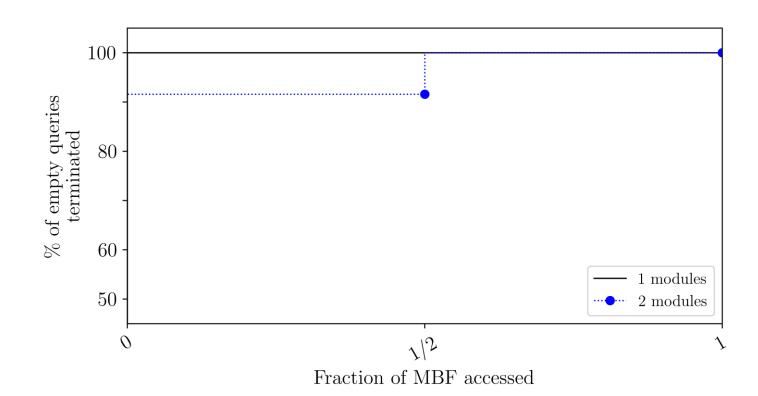


SHaMBa performs best with smaller modules



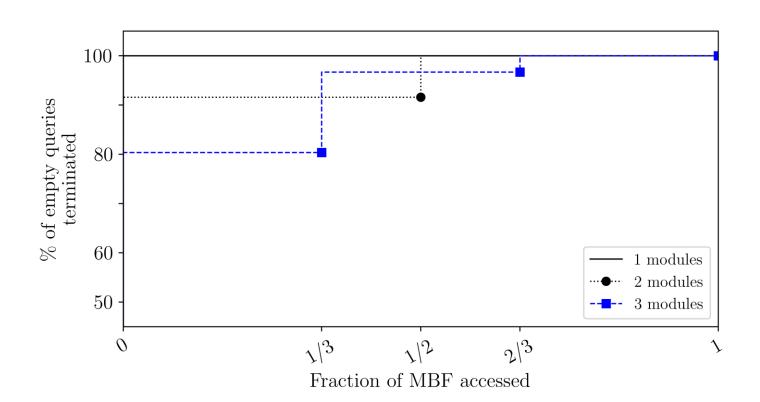




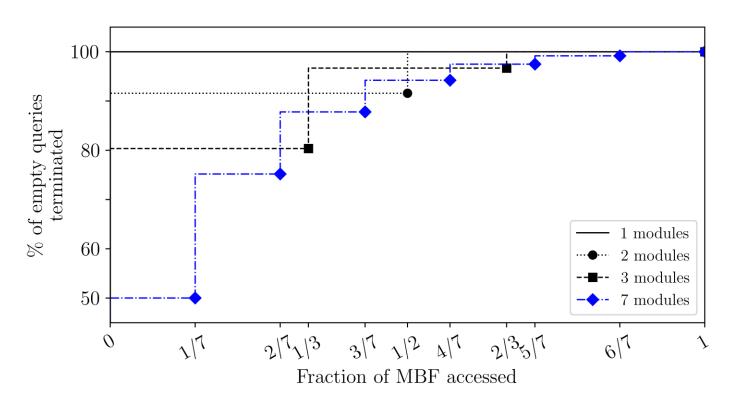










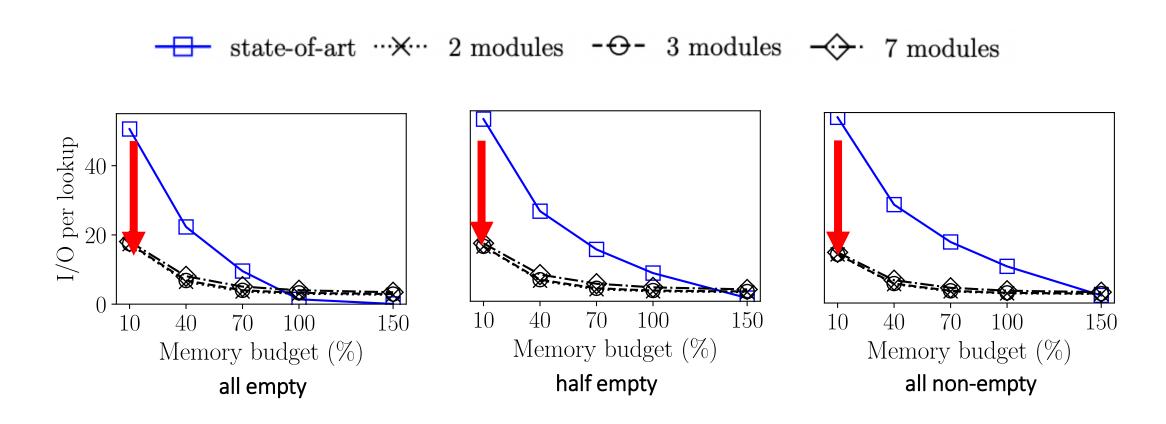


More queries can be terminated earlier with less memory.

**BOSTON** 

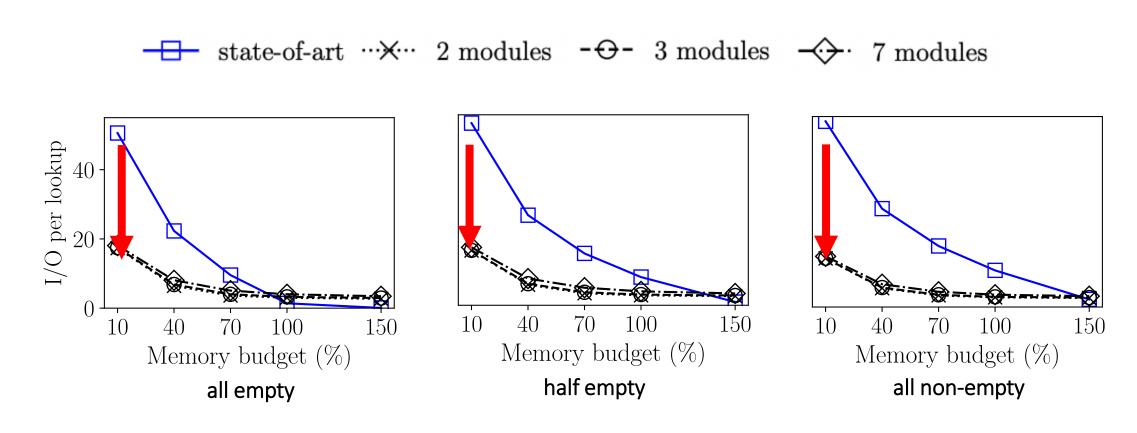


Workload: Uniform, Entry size: 64B, #Entries: 30K Tuning: full skipping algorithm, equal sized modules





Workload: Uniform, Entry size: 64B, #Entries: 30K Tuning: full skipping algorithm, equal sized modules



Skipping modules effectively skips unnecessary filters/modules.



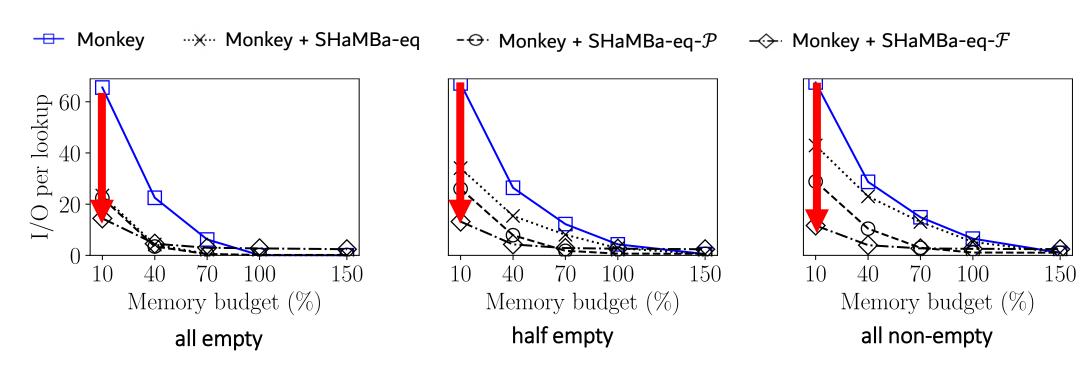
## SHaMBa with Monkey

Workload: Uniform, Entry size: 64B, #Entries: 30K

Tuning: 2 equal sized modules

Monkey allocates more bits per element in the shallower levels to aggressively reduce their false positives

Monkey: Optimal Navigable Key-Value Store, ACM SIGMOD 2017





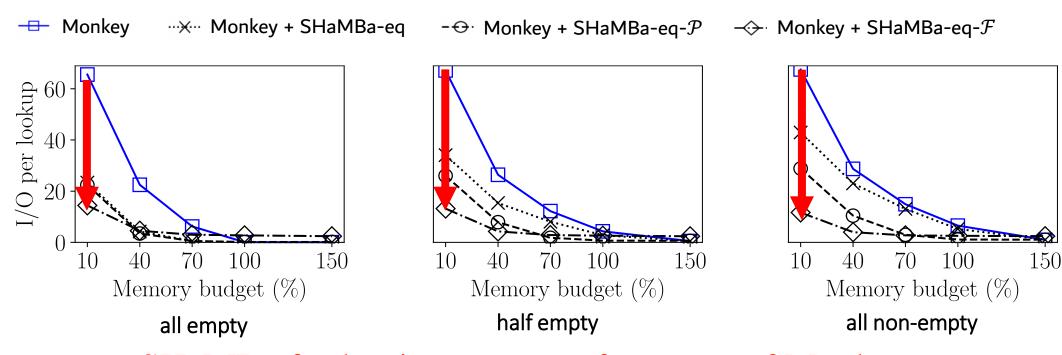
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SHaMBa further improves performance of Monkey



#### Conclusion

- ☐ Modular Bloom filters (MBFs)
  - o a BF variant that consists of multiple modules
  - o enable smooth navigation of the memory vs. performance trade-off

- ☐ SHaMBa
  - o a novel LSM-based key-value engine
  - o specifically addresses performance loss due to memory pressure
  - o the same average number of I/Os, with 1/3 of the memory by the state of the art

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Thank you!





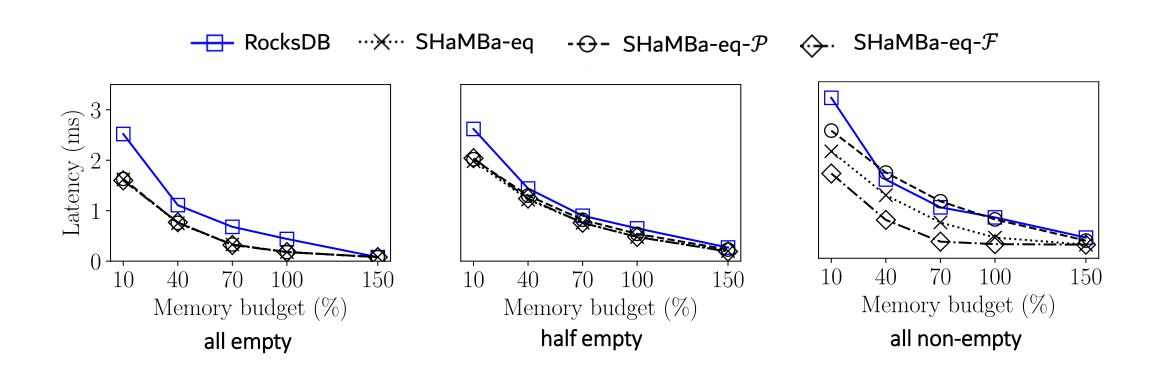


# Q&A



#### SHaMBa with RocksDB

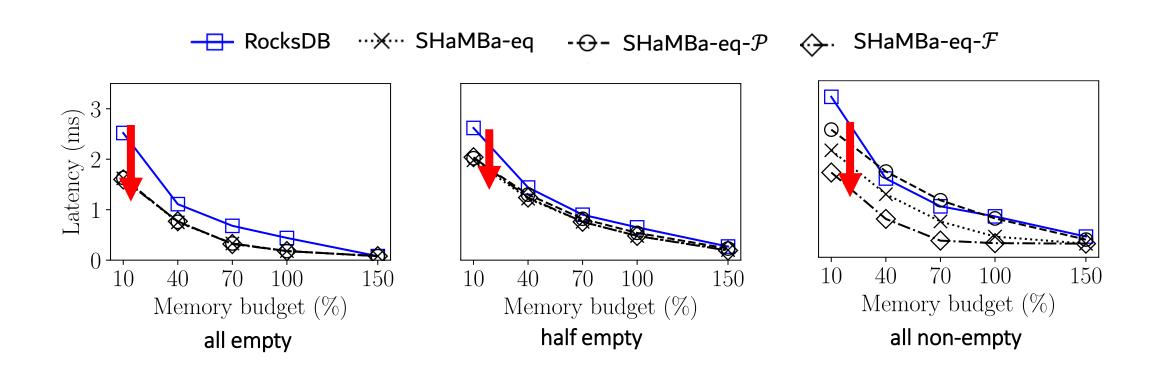
Workload: Uniform, Entry size: 64B, #Entries: 30K





#### SHaMBa with RocksDB

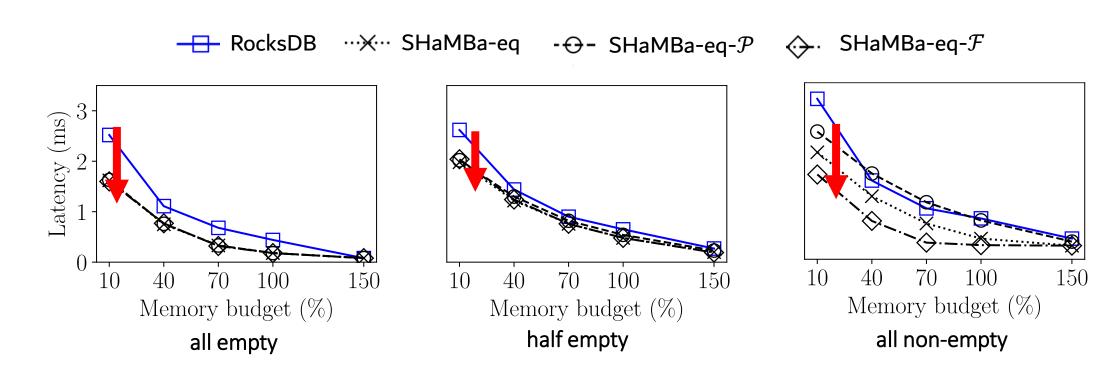
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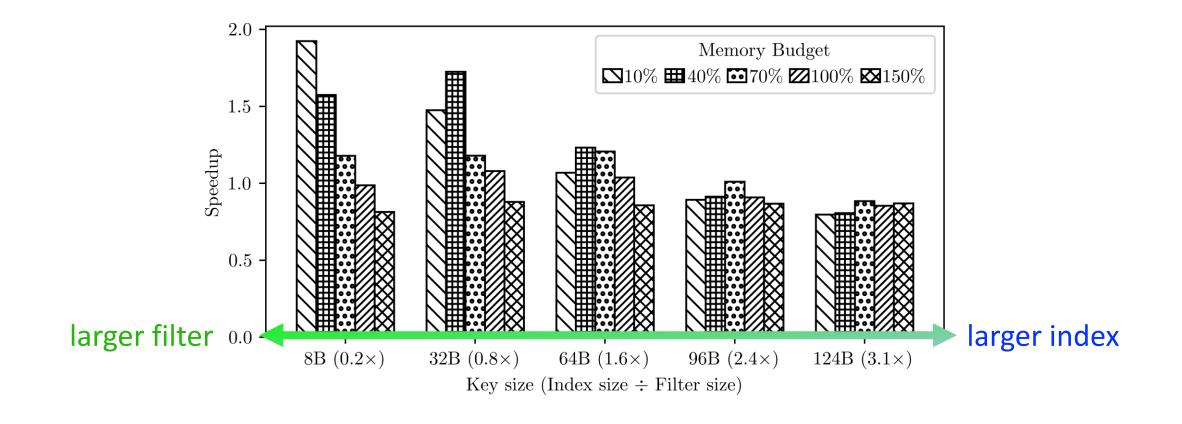


SHaMBa-eq accelerates point lookups



#### SHaMBa with larger index

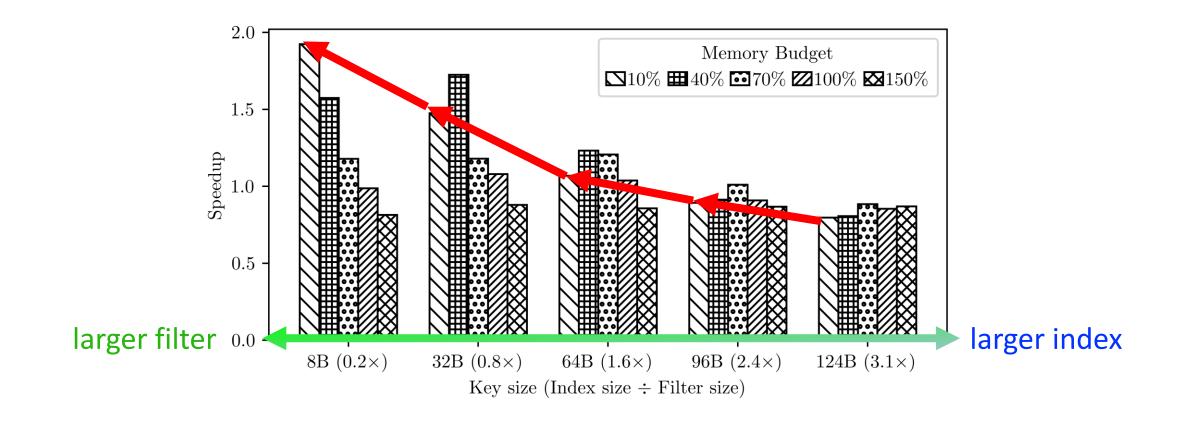
Workload: Uniform (all empty), Entry size: 128B, #Entries: 30K





#### SHaMBa with larger index

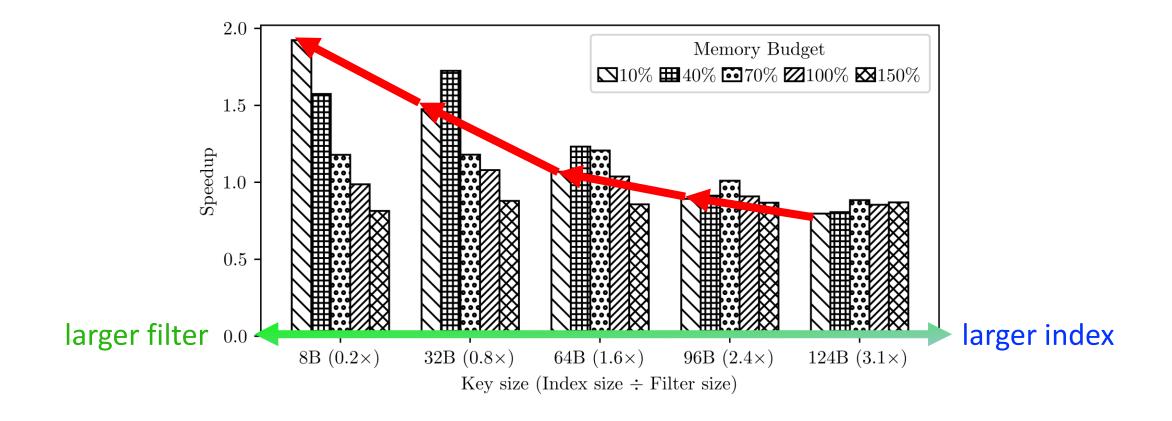
Workload: Uniform (all empty), Entry size: 128B, #Entries: 30K





#### SHaMBa with larger index

Workload: Uniform (all empty), Entry size: 128B, #Entries: 30K



SHaMBa performs best when filters are larger than indexes