

CS 591: Data Systems Architectures

Introduction to Indexing:

Trees, Tries, Hashing, Bitmap Indexes, Database Cracking

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https://midas.bu.edu/classes/CS591A1

Recap: Key-Value Stores

<key, value>

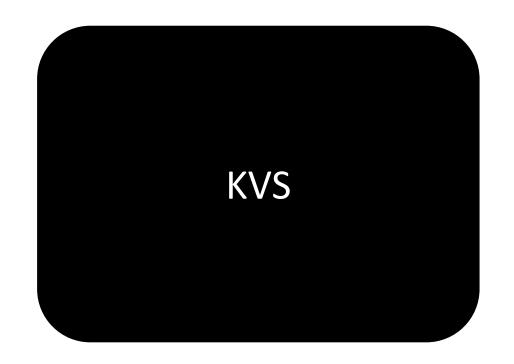
```
put(key, value)
stores value and associates with key

get(key)
returns the associated value

delete(key)
deletes the value associated with the key

get_range (key_start,key_end)
get_set(key1, key2, ...)
```

how to organize keys/values? depends on the workload!





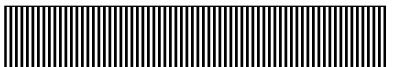
Recap: Key-Value Stores

inserts and point queries?

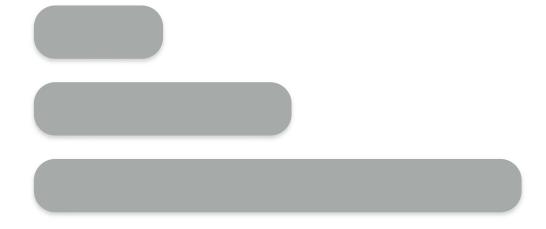
inserts, point queries, and range queries?



hash table



log

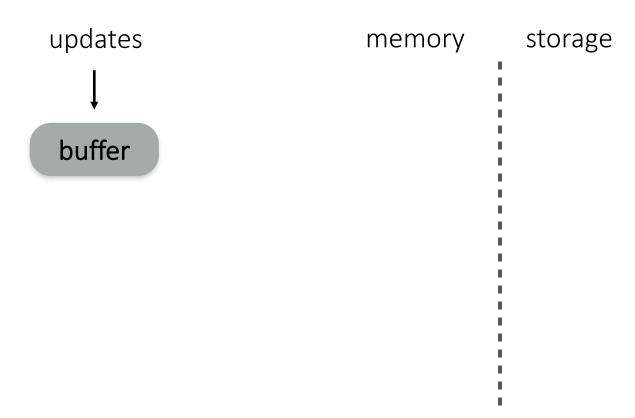


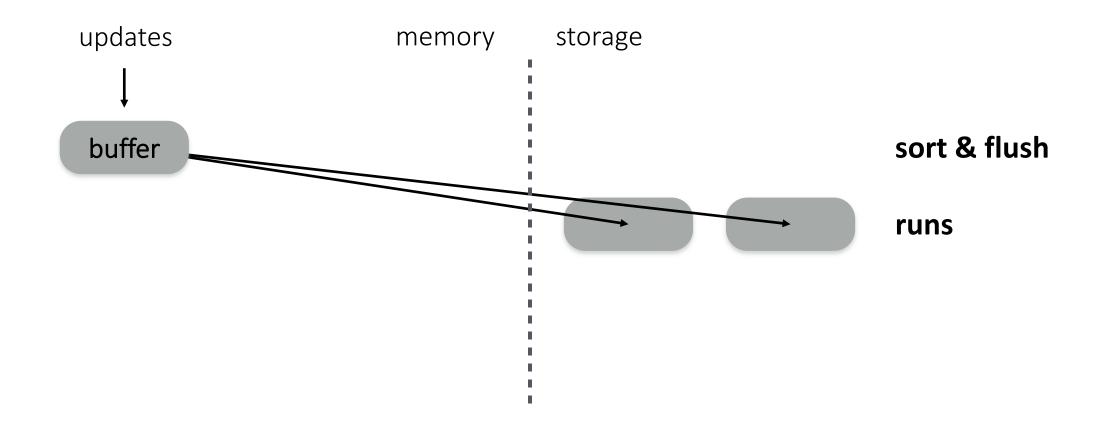
log-structured merge tree

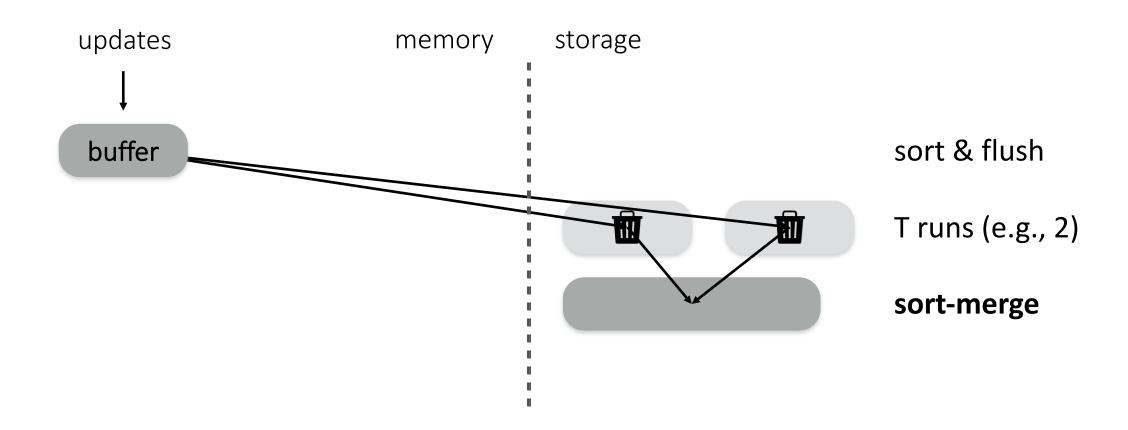


LSM-Trees

A quick review of LSM-Trees and what is expected for the systems project

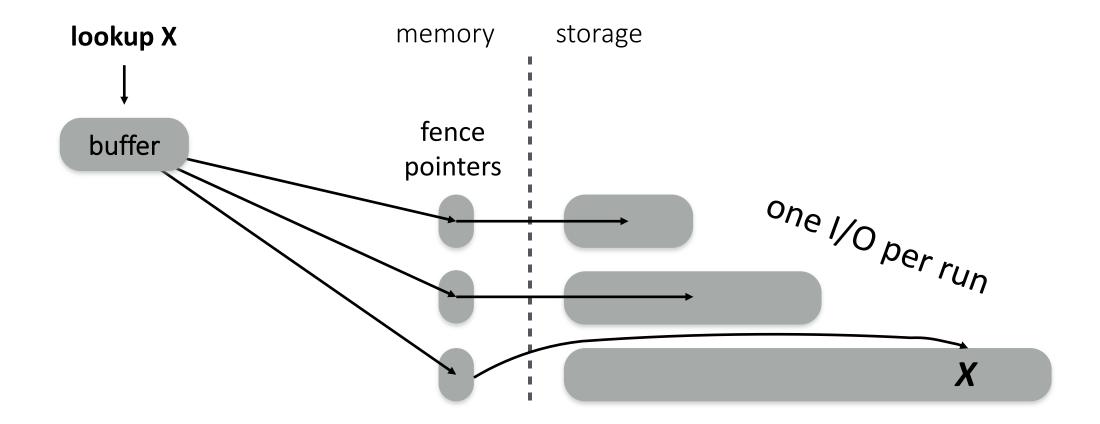


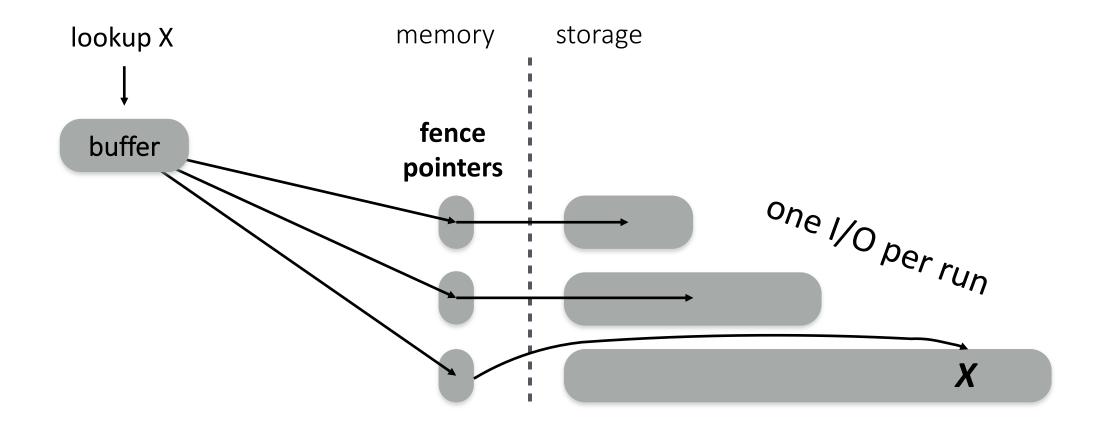


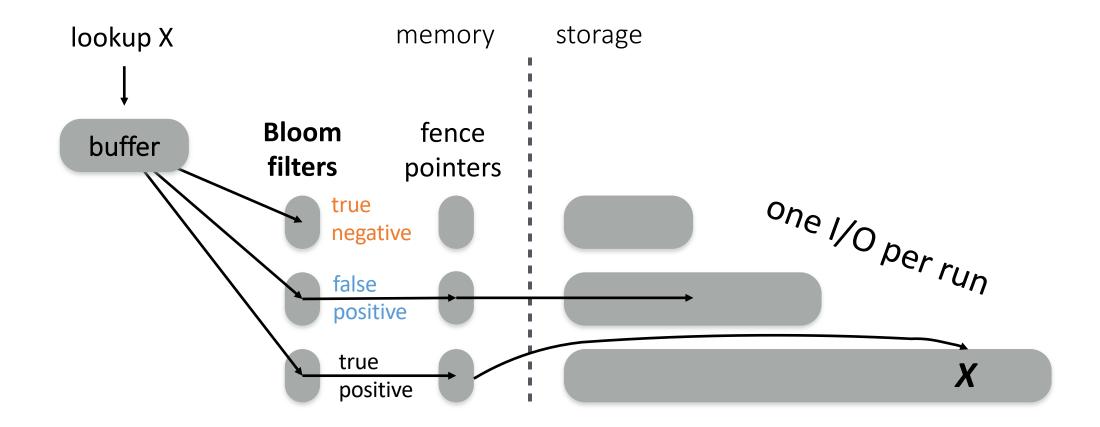


memory storage exponentially increasing sizes $O(log_T(N))$ levels

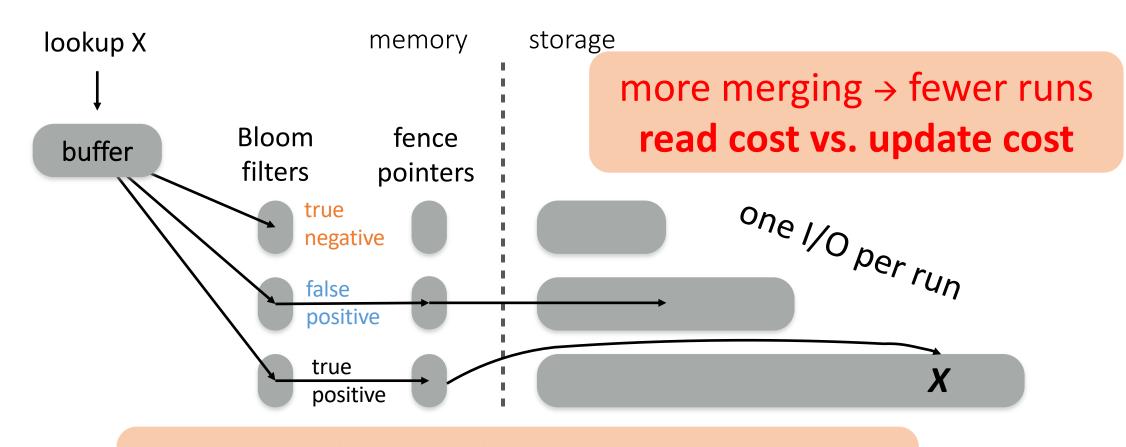
buffer





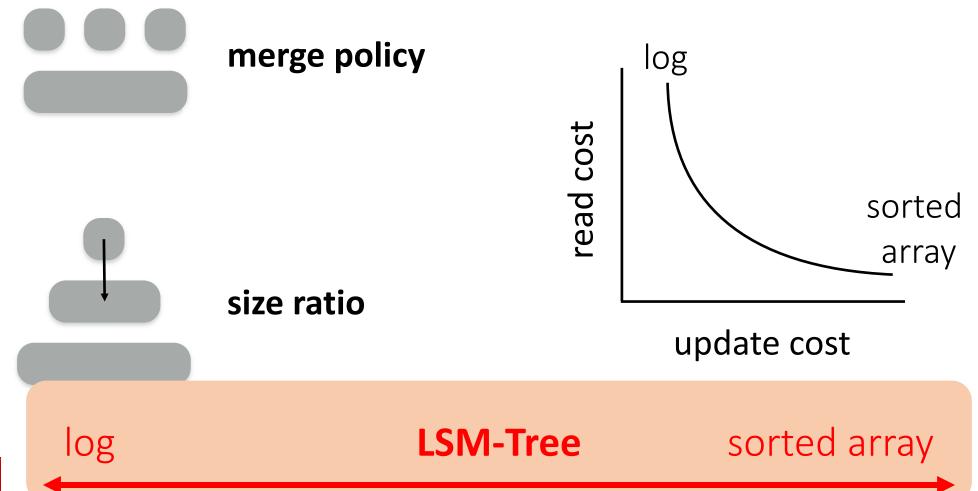


performance & cost trade-offs



bigger filters → fewer false positives memory space vs. read cost

tuning reads vs. updates



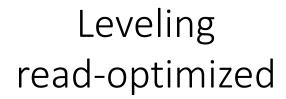


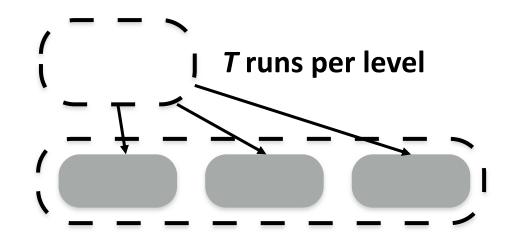
Merge Policies

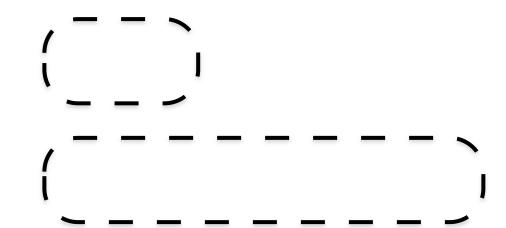
Tiering write-optimized

Leveling read-optimized

Tiering write-optimized

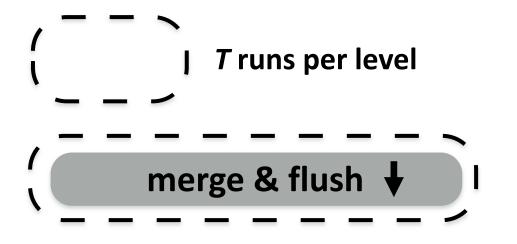


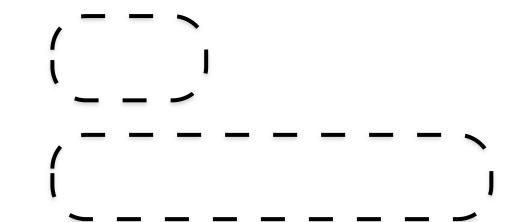




Tiering write-optimized

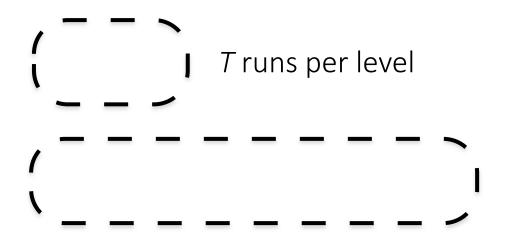
Leveling read-optimized

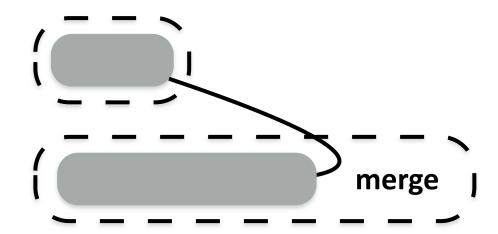




Tiering write-optimized

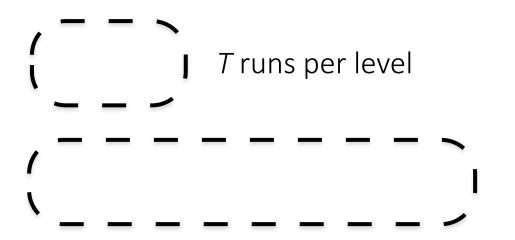


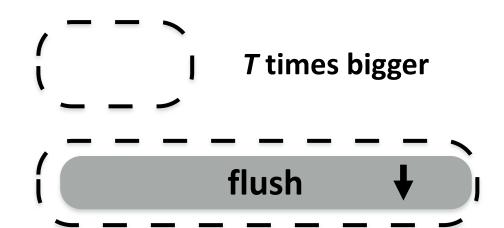




Tiering write-optimized

Leveling read-optimized





Tiering write-optimized

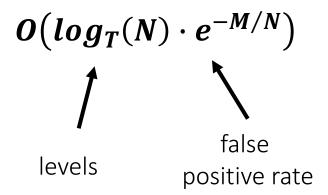


Leveling read-optimized

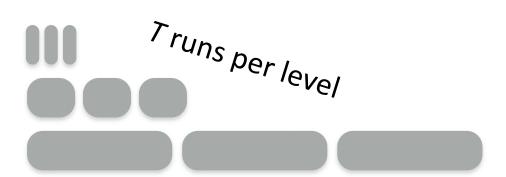


lookup cost:

$$O(T \cdot log_T(N) \cdot e^{-M/N})$$
runs
per level false
positive rate



Tiering write-optimized



Leveling read-optimized

lookup cost:
$$O(T \cdot log_T(N) \cdot e^{-M/N})$$

update cost:

$$O(log_T(N))$$

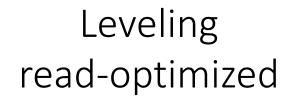
| levels

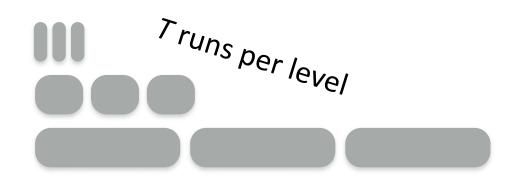
$$O(log_T(N) \cdot e^{-M/N})$$

$$O(T \cdot log_T(N))$$

merges per level levels

Tiering write-optimized







lookup cost:
$$O(T \cdot log_T(N) \cdot e^{-M/N})$$

$$O(log_T(N) \cdot e^{-M/N})$$

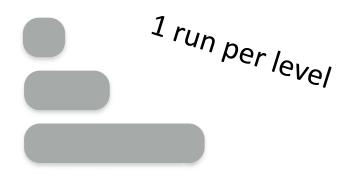
$$O(log_T(N))$$

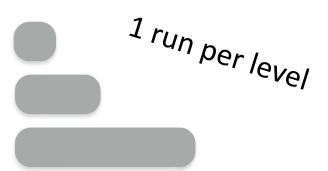
$$O(T \cdot log_T(N))$$



Tiering write-optimized

Leveling read-optimized





lookup cost:

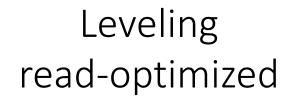
$$O(\log_T(N) \cdot e^{-M/N}) = O(\log_T(N) \cdot e^{-M/N})$$

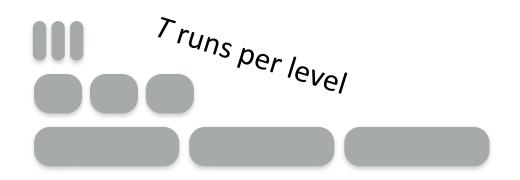
update cost:

$$O(log_T(N)) = O(log_T(N))$$

for size ratio T

Tiering write-optimized







lookup cost:
$$O(T \cdot log_T(N) \cdot e^{-M/N})$$

$$O(log_T(N) \cdot e^{-M/N})$$

update cost:
$$O(log_T(N))$$

$$O(T \cdot log_T(N))$$



Tiering write-optimized

Leveling read-optimized

O(N) runs per level

1 run per level



sorted array

lookup cost:

$$O(N \cdot e^{-M/N})$$

 $O(e^{-M/N})$

update cost:

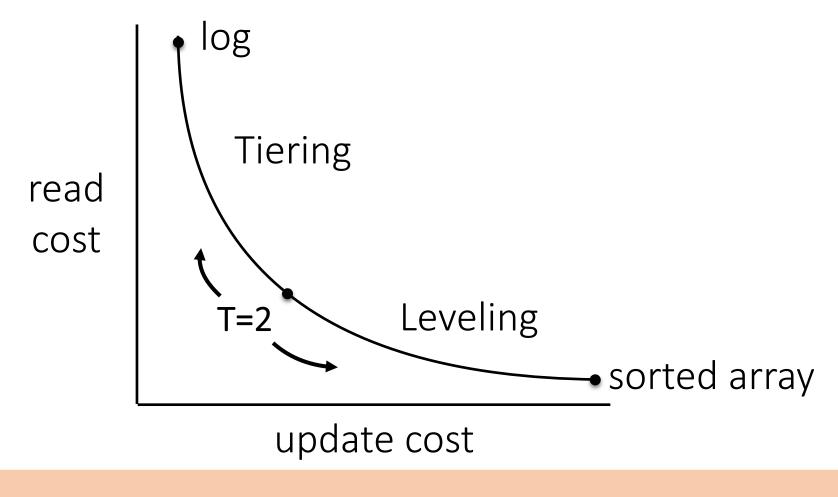
$$O(log_N(N)) = \mathbf{O}(\mathbf{1})$$

 $O(N \cdot log_N(N)) = O(N)$

for size ratio T



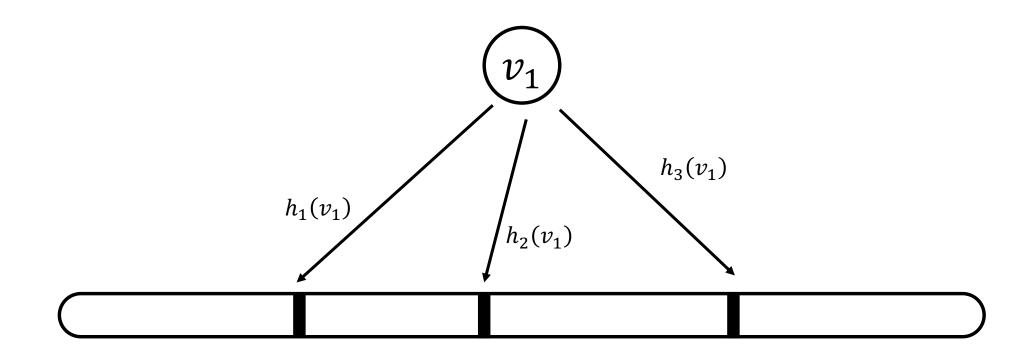
N



log **LSM-Tree** sorted array

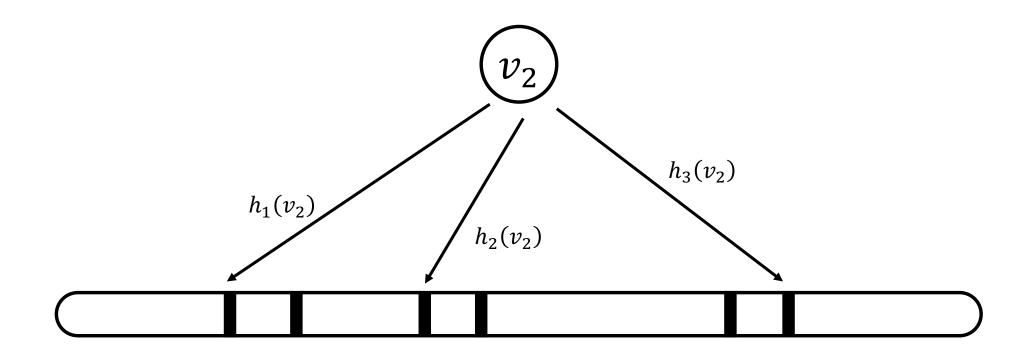
Details on Bloom filters

Inserting into a Bloom filter



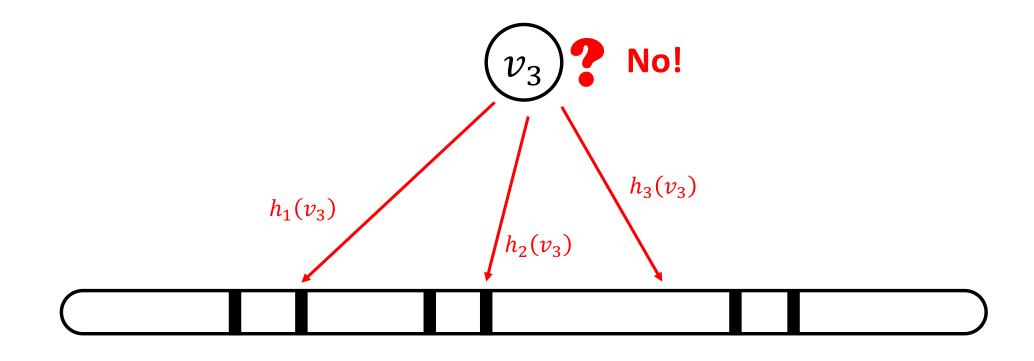


Inserting into a Bloom filter



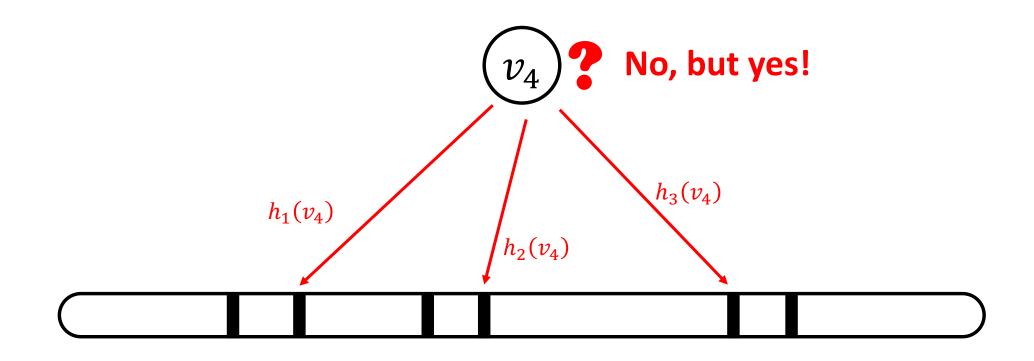


Probing a Bloom filter (true negative)



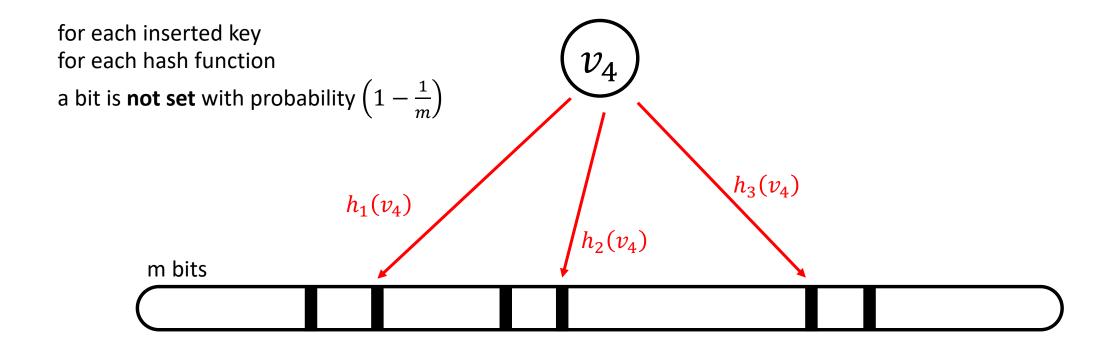


Probing a Bloom filter (false positive)

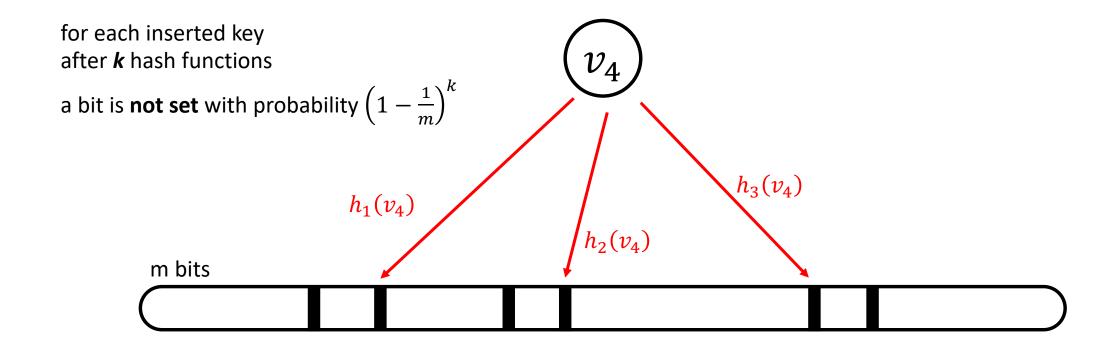


what is the probability of a false positive?

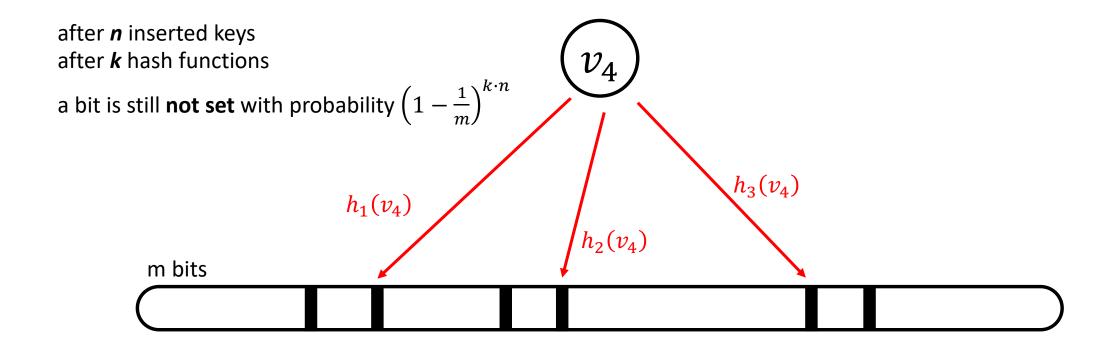




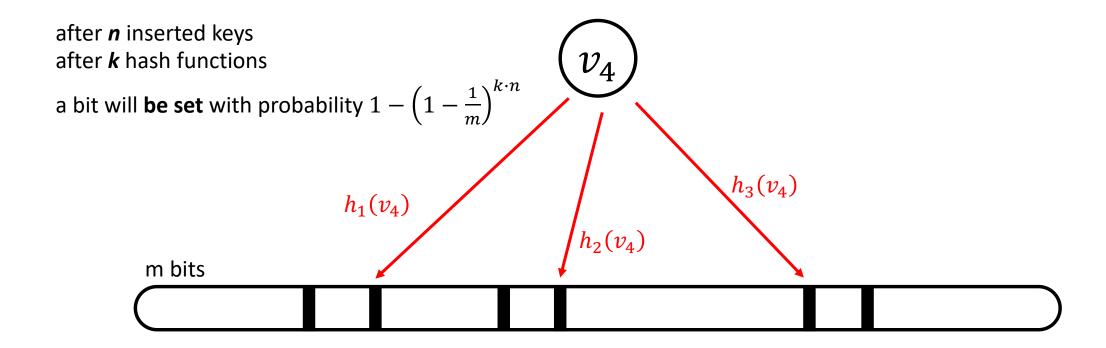




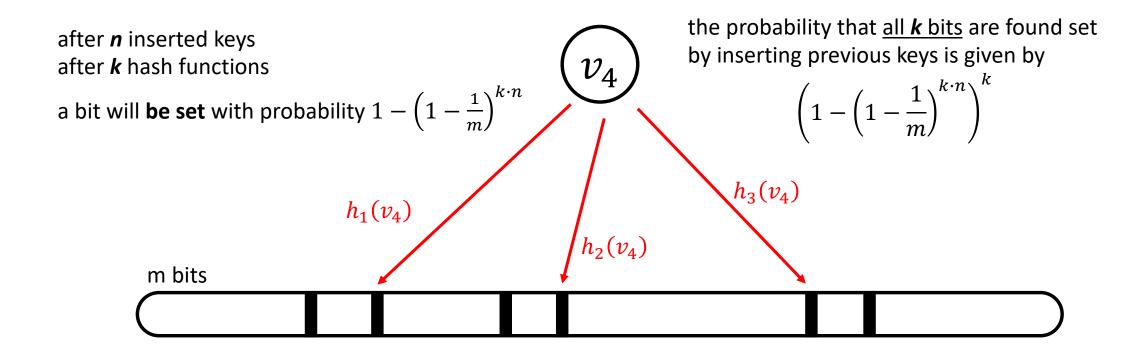




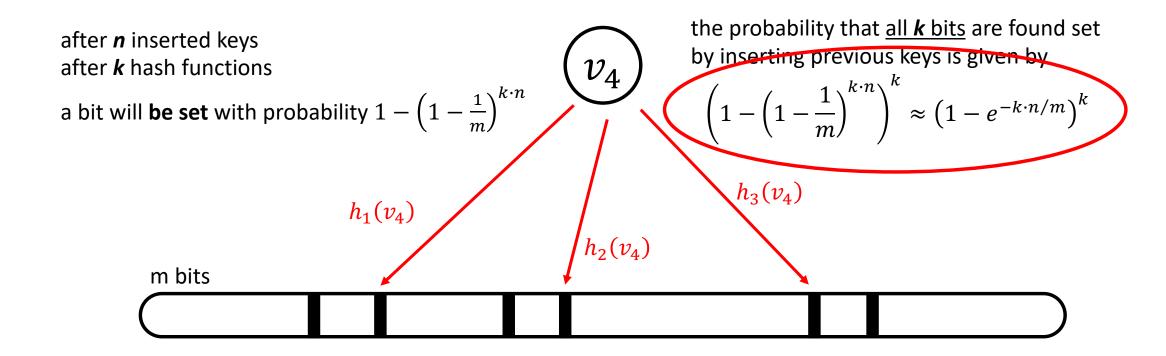














Bloom filter false positive (derivation details)

let's focus on the term: $\left(1 - \frac{1}{m}\right)^n$ assuming $\alpha = \frac{m}{n}$, and for large m, n: $\left(1 - \frac{1}{m}\right)^n = \left(1 - \frac{1}{\alpha \cdot n}\right)^n = \left(1 + \frac{-1/\alpha}{n}\right)^n \approx e^{-1/\alpha} = e^{-n/m}$, because $\lim_{n \to \infty} \left(1 + \frac{x}{n}\right)^n = e^x$

hence, the probability that all k bits are found set by inserting previous keys is given by

$$\left(1 - \left(1 - \frac{1}{m}\right)^{n \cdot k}\right)^k = \left(1 - \left(\left(1 - \frac{1}{m}\right)^n\right)^k\right)^k = \left(1 - \left(e^{-n/m}\right)^k\right)^k = \left(1 - \left(e^{-k \cdot n/m}\right)\right)^k$$

Bloom filter false positive

false positive
$$p = (1 - e^{-k \cdot n/m})^k$$

how to minimize?

it can be shown (not easy): the optimal number of hash functions k, that minimize the false positive is:

$$k = \frac{m}{n} \cdot ln(2)$$

Rule of thumb: k is a number, often between 2 and 10.



Bloom filter false positive

Combining
$$p = (1 - e^{-k \cdot n/m})^k$$
 and $k = \frac{m}{n} \cdot ln(2)$

we get:

$$e^{-\frac{m}{n}\cdot\left(ln(2)\right)^2}$$

details:

$$p = \left(1 - e^{-\frac{m}{n} \cdot ln(2) \cdot \frac{n}{m}}\right)^{\frac{m}{n} \cdot ln(2)} = \left(1 - e^{-ln(2)}\right)^{\frac{m}{n} \cdot ln(2)} = \left(1 - \frac{1}{2}\right)^{\frac{m}{n} \cdot ln(2)} = \left(\frac{1}{2}\right)^{\frac{m}{n} \cdot ln(2)}$$

using twice that
$$^1/_2 = e^{-ln(2)}$$
, $p = \left(e^{-ln(2)}\right)^{\frac{m}{n}\cdot ln(2)} = e^{-\frac{m}{n}\cdot ln(2)\cdot ln(2)} = e^{-\frac{m}{n}\cdot (ln(2))^2}$



key-value stores vs. indexes

What is an index?

Auxiliary structure to quickly find rows based on arbitrary attribute

Special form of <key, value>

indexed attribute

position/location/rowID/primary key/...



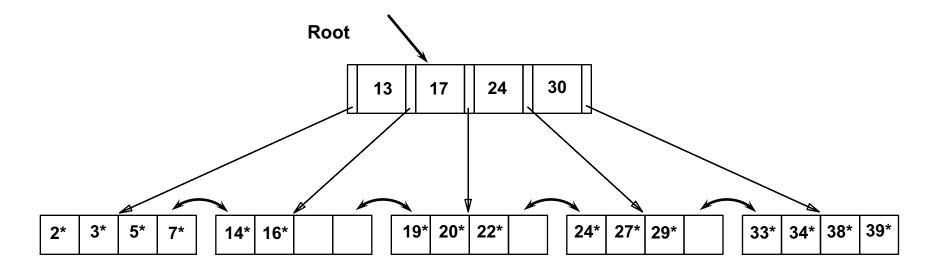
What are the possible *index designs*?

	Data Organization	Point Queries	Short Range Queries	Long Range Queries	Comments
B+ Trees	Range				Partition <i>k-ways</i> recursively
LSM Trees	Insertion & Sorted				Optimizes <i>insertion</i>
Radix Trees	Radix				Partition using the <i>key radix</i> representation
Hash Indexes	Hash				Partition by <i>hashing the key</i>
Bitmap Indexes	None				Succinctly represent <i>all rows with a key</i>
Scan Accelerators	None				Metadata to skip accesses



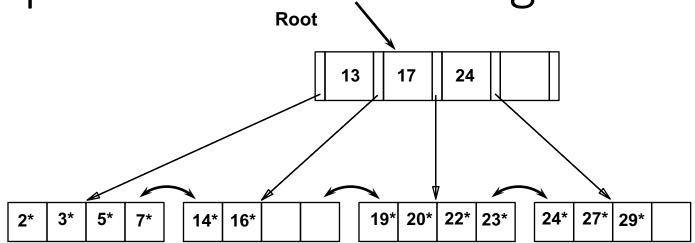
B+ Trees

Search begins at root, and key comparisons direct it to a leaf. Search for 5^* , 15^* , all data entries >= 24^* ...

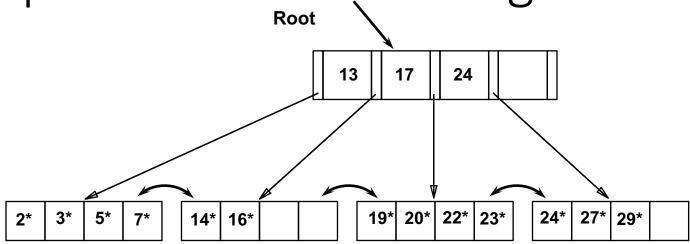


Based on the search for 15*, we know it is not in the tree!

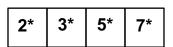


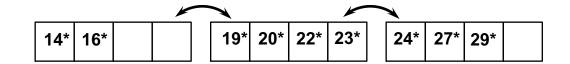




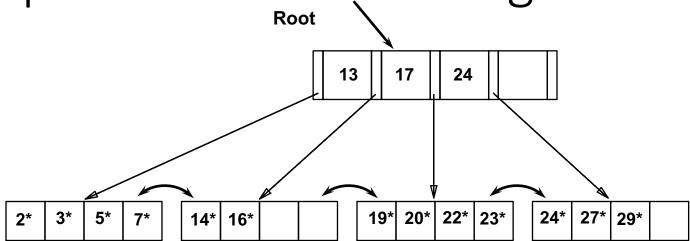




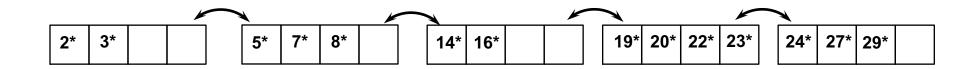




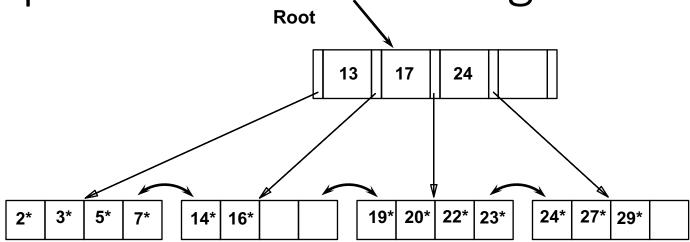


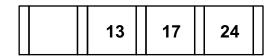


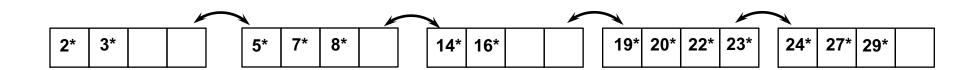




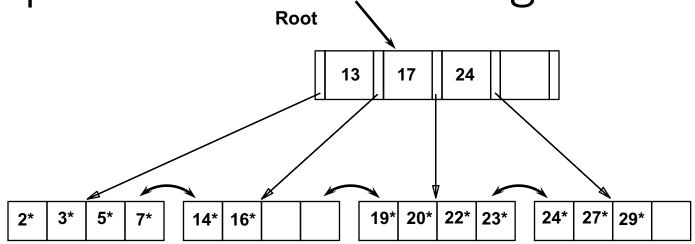


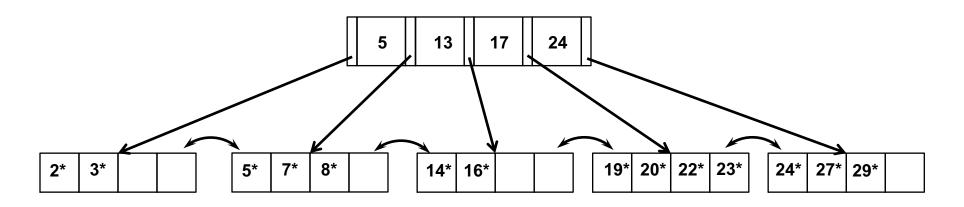




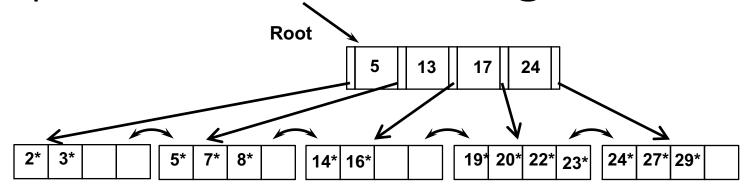


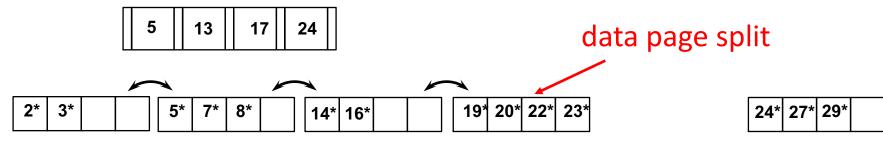




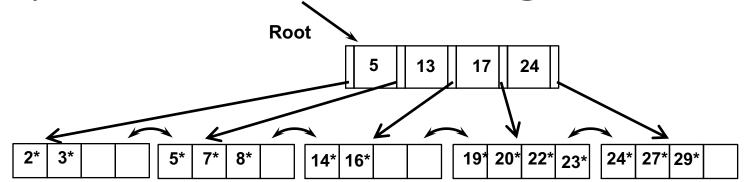


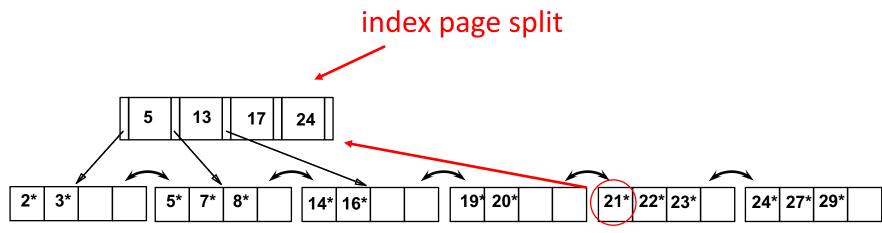




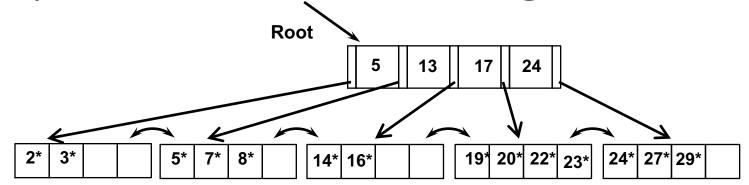


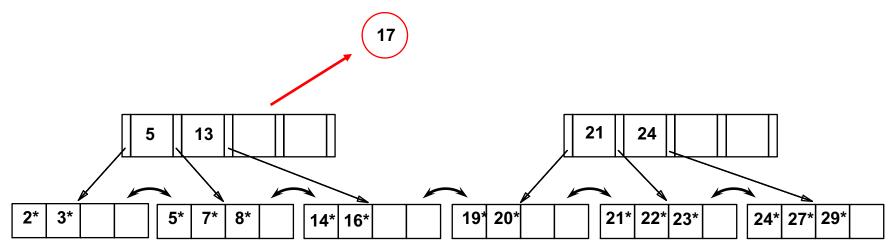




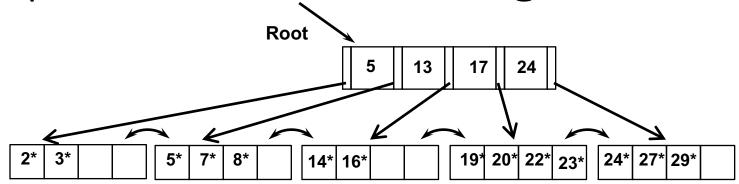


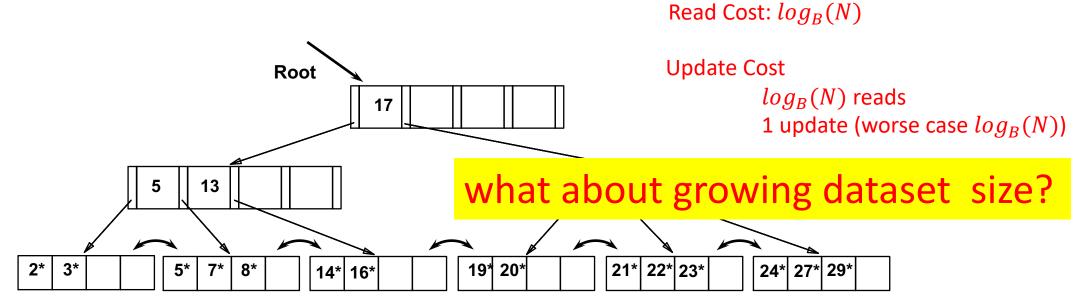










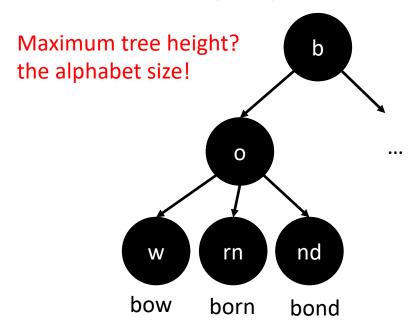


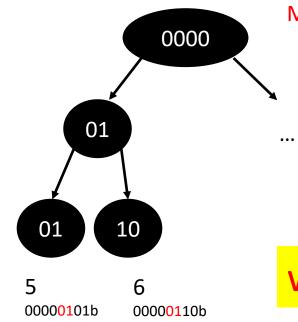


Radix Trees (special case of tries and prefix B-Trees)

Idea: use common prefixes for internal nodes to reduce size/height!

Binary representation of any domain can be used





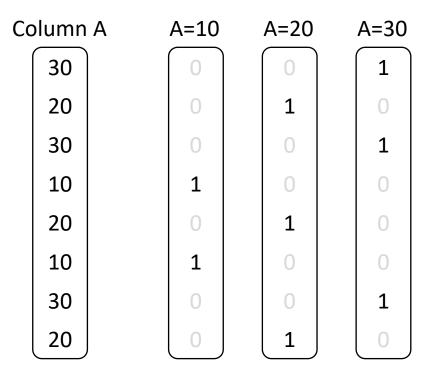
Maximum tree height?

8, that is, $log_2(max_domain_value)$ fixed worst case!

what about data skew?



Bitmap Indexes



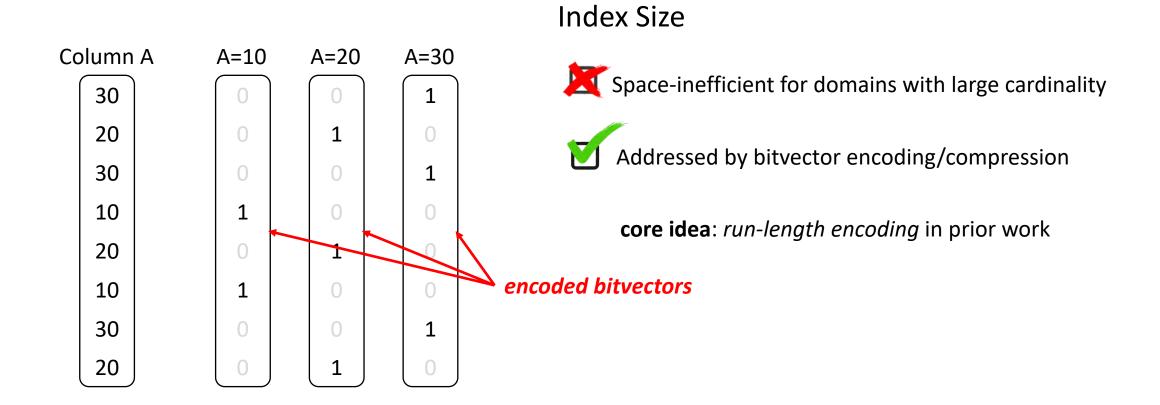
Speed & Size

- Compact representation of query result
- Query result is readily available

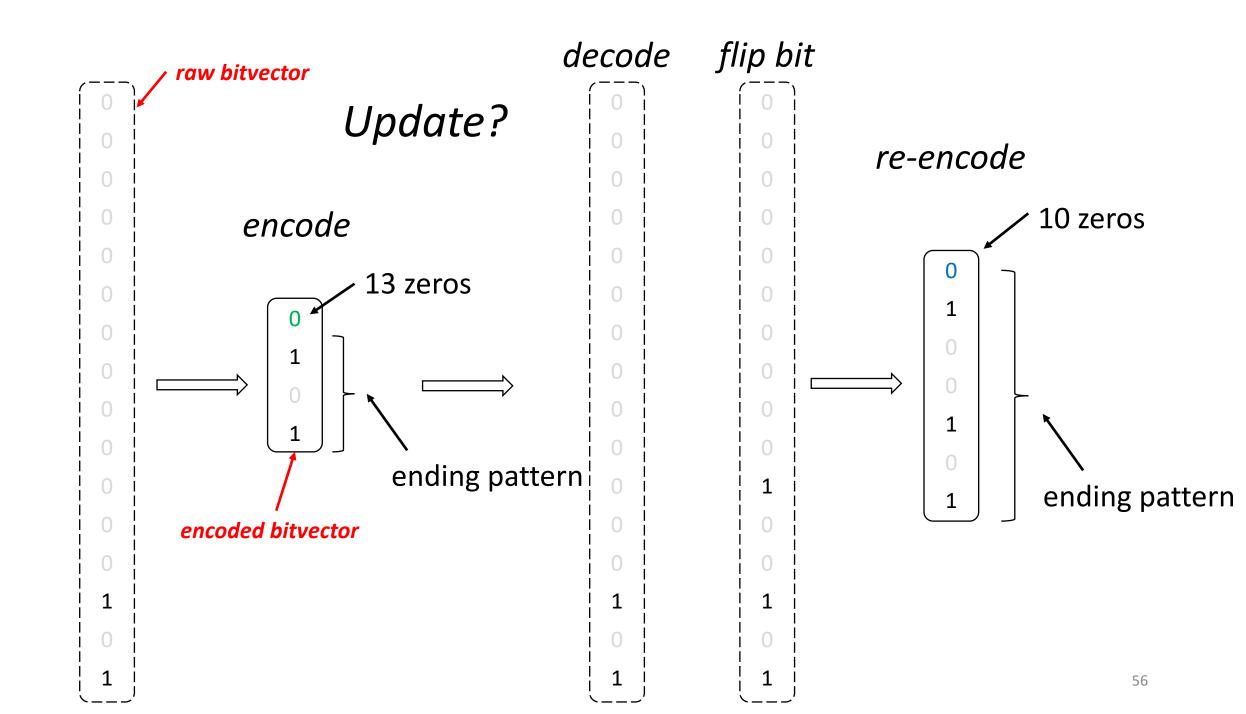
Bitvectors

- Can leverage fast Boolean operators
- Bitwise AND/OR/NOT faster than looping over meta data

Bitmap Indexes



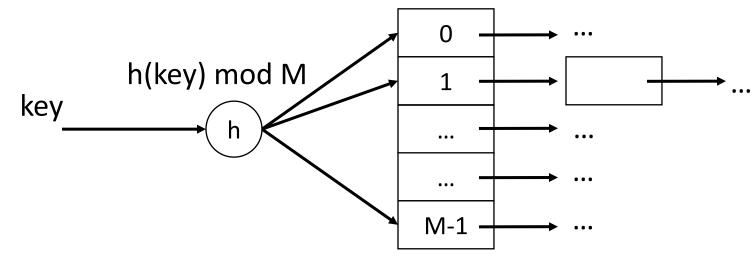
what about updates?



Hash Indexes (static hashing)

#primary bucket pages fixed, allocated sequentially, never de-allocated; overflow pages if needed

 $h(k) \mod M$ = bucket to insert data entry with key k (M: #buckets)



Primary bucket pages

Overflow pages



Zonemaps

Search for 25

 Z1: [32,72]
 Z2: [13,45]
 Z3: [1,10]
 Z4: [21,100]
 Z5: [28,35]
 Z6: [5,12]



Zonemaps

Z1: [32,72]

Z2: [13,45]

Z3: [1,10]

Z4: [21,100]

Z5: [28,35]

Z6: [5,12]

Search for 25 Search for [5,11]



Zonemaps

Z1: [32,72]

Z2: [13,45]

Z3: [1,10]

Z4: [21,100]

Z5: [28,35]

Z6: [5,12]

Search for 25 Search for [5,11] Search for [31,46]



Zonemaps

Z1: [32,72]

Z2: [13,45]

Z3: [1,10]

Z4: [21,100]

Z5: [28,35]

Z6: [5,12]

Search for 25 Search for [5,11] Search for [31,46]



Zonemaps

Z1: [32,72]

Z2: [13,45]

Z3: [1,10]

Z4: [21,100]

Z5: [28,35]

Z6: [5,12]

Search for 25

Search for [5,11]

Search for [31,46]

if data were sorted:

Z1: [1,15]

Z2: [16,30]

Z3: [31,50]

Z4: [50,67]

Z5: [68,85]

Z6: [85,100]

Search for 25

Search for [5,11]

Search for [31,46]



Zonemaps

 Z1: [32,72]
 Z2: [13,45]
 Z3: [1,10]
 Z4: [21,100]
 Z5: [28,35]
 Z6: [5,12]

Search for 25
Search for [5,11]
Search for [31,46]

if data were sorted:

 Z1: [1,15]
 Z2: [16,30]
 Z3: [31,50]
 Z4: [50,67]
 Z5: [68,85]
 Z6: [85,100]

Search for 25
Search for [5,11]
Search for [31,46]

what if data is perfectly uniformly distributed?





What are the possible *index designs*?

	Data Organization	Point Queries	Short Range Queries	Long Range Queries	Data Skew	Updates	Affected by Physical Order
B+ Trees	Range						
LSM Trees	Insertion & Sorted						
Radix Trees	Radix						
Hash Indexes	Hash						
Bitmap Indexes	None						no
Scan Accelerators	None						yes



idea: there is an *ideal* data organization

what is it (for a column of integers)? sorted!

we can reach it *eventually* if we use the *workload as a hint*



```
search < 15
32
                       32
19
                       19
11
              < 15
 6
123
                      123
55
                       55
12
                       12
78
                       78
```

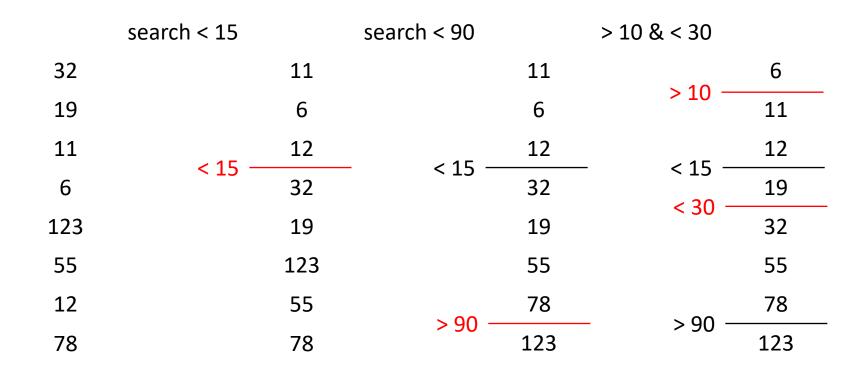


	search < 15		search < 90	
32		11		11
19		6		6
11	< 15 -	12	- < 15 <i>-</i>	12
6	< 13 -	32	< 13	32
123		19		19
55		123		123
12		55	> 00 -	55
78		78	> 90 -	78



	search < 15	search < 90	> 10 & < 30	
32	11	11	11	
19	6	6	> 10 ————	_
11	< 15 ———	< 15 ———	- < 15 12	
6	32	32	< 30 — 32	
123	19	19	19	
55	123	55	55	
12	55	78	78	
78	78	> 90 — 123		





what about updates/inserts?



Project Implementation

What to plan for the implementation (1/2)

Durable Database (open/close without losing state)

Components:

Memory buffer (array, hashtable, B+ tree)

Files (sorted levels/tiers)

Fence pointers (**Zonemaps**)

Bloom filters



What to plan for the implementation (2/2)

API + basic testing and benchmarking

available at:

https://github.com/midaslab-bu/cs591 templatedb

with a Reference Bloom filter implementation

