

Lecture 2: Conditioning, Bayes' Rule, and Independence

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EE210: Probability and Introductory Random Processes
KAIST EE

MONTH DAY, 2021

- Conditional Probability
- Bayes' Rule
- Bayesian Inference: Sneak Peek
- Independence, Conditional Independence

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 - Remember that $\mathbb{P}(\cdot|B)$ should be a new probability law (so three axioms should be satisfied)
 - $\mathbb{P}(\Omega|B) = 1$?
 - $\mathbb{P}(B|B) = 1$ from our common sense. True?

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- All other properties of the law $\mathbb{P}(\cdot)$ is applied to the conditional law $\mathbb{P}(\cdot|B)$.
- For example, finite additivity. For two disjoint events A and C ,

$$\mathbb{P}(A \cup C \mid B) = \mathbb{P}(A \mid B) + \mathbb{P}(C \mid B)$$

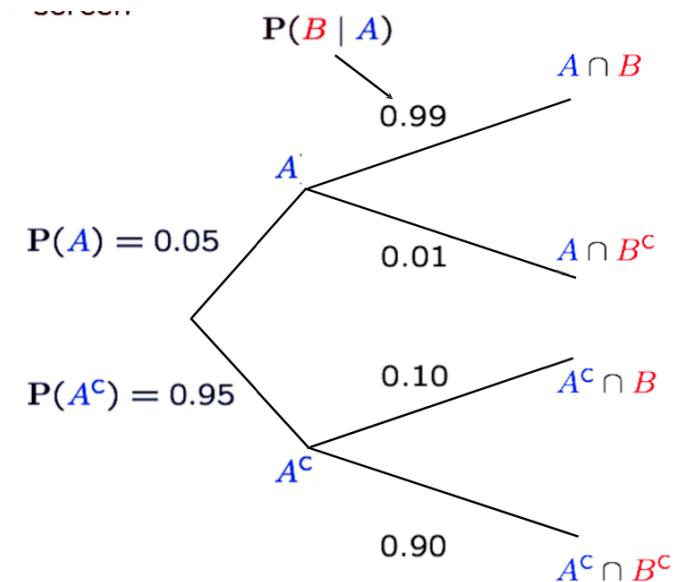
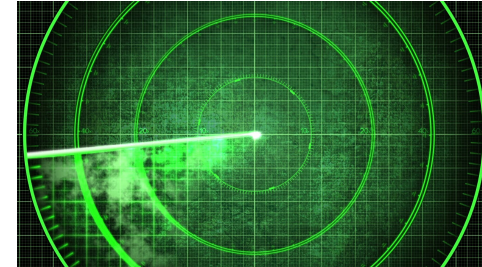
Example: Conditional Probability

- A : Airplane is flying above
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$$=$$

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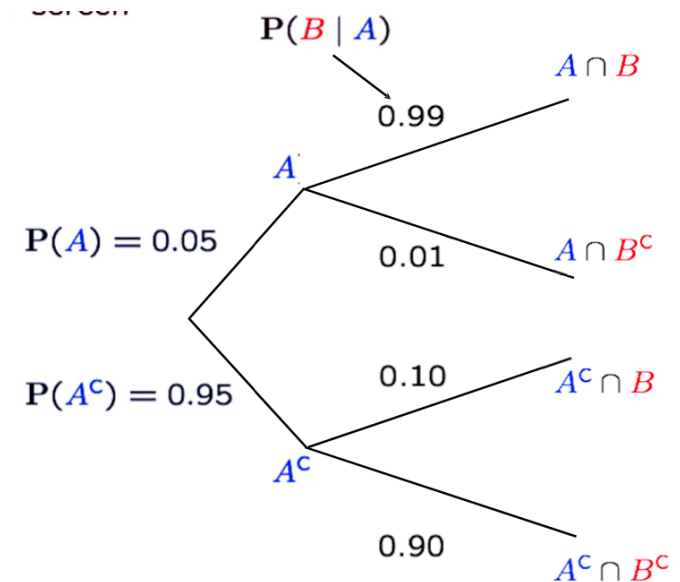
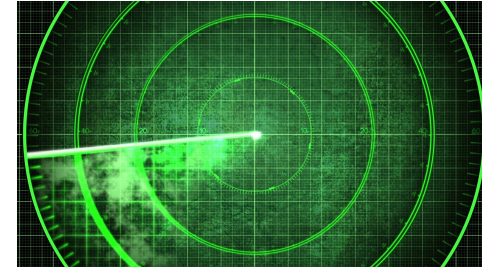
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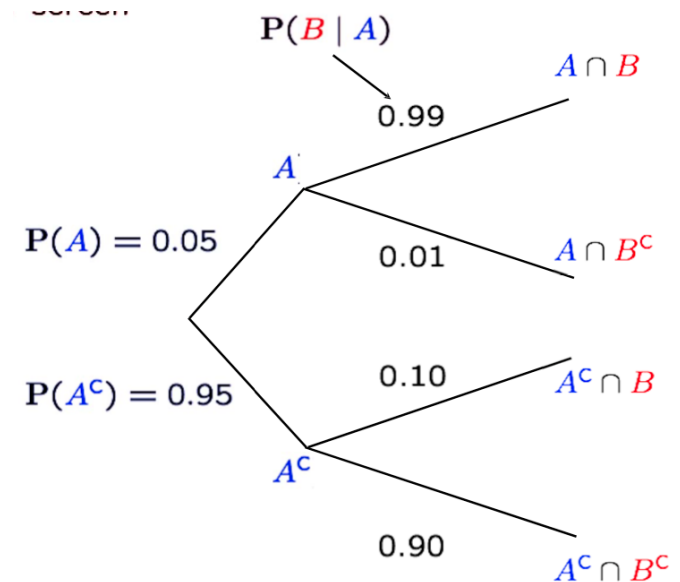
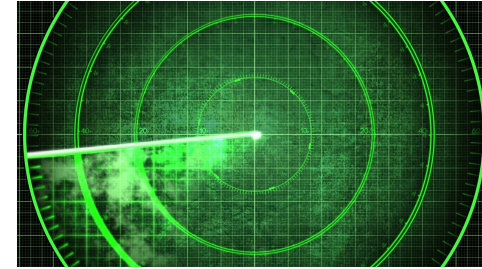
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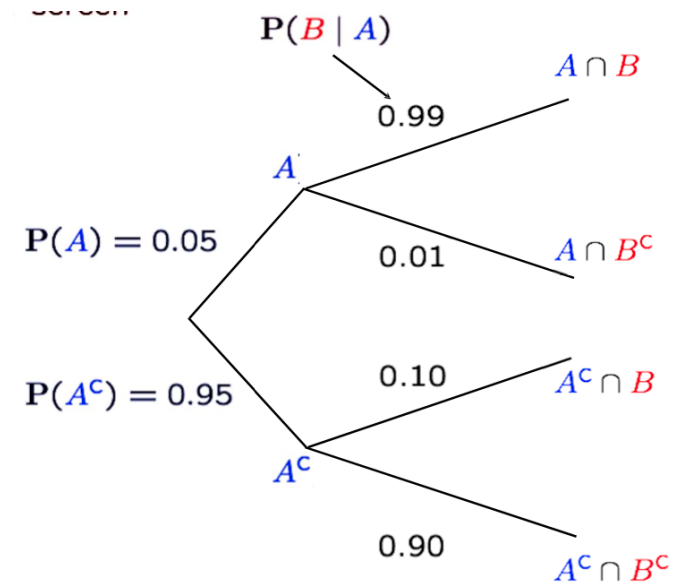
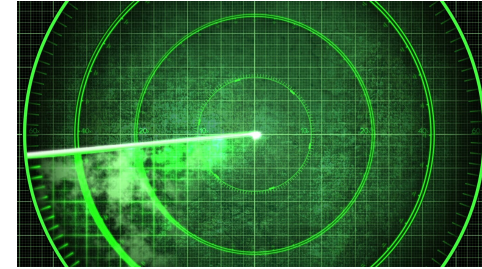
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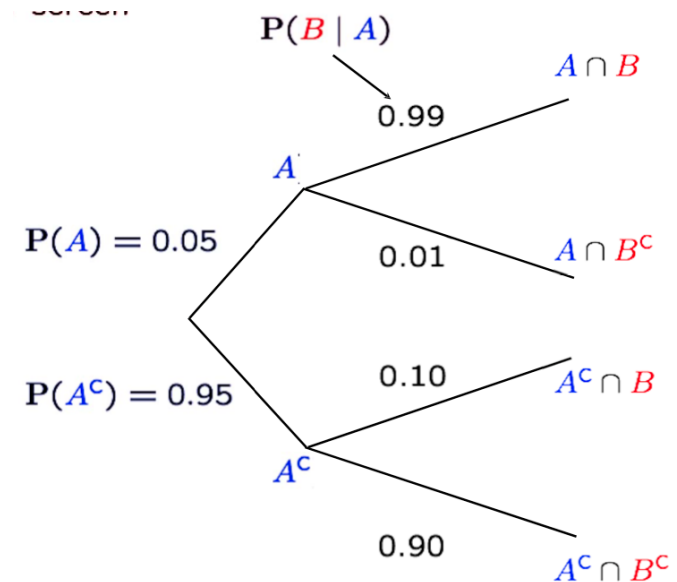
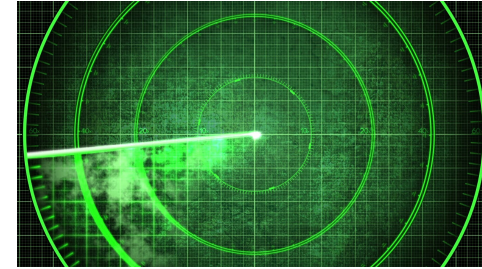
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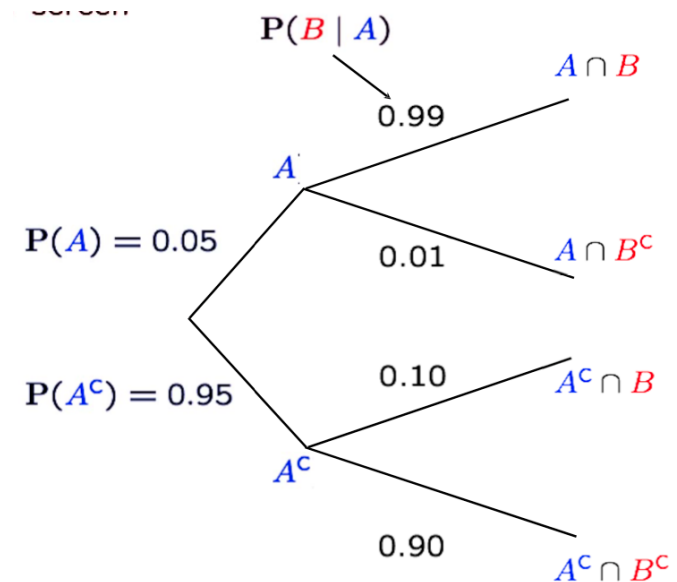
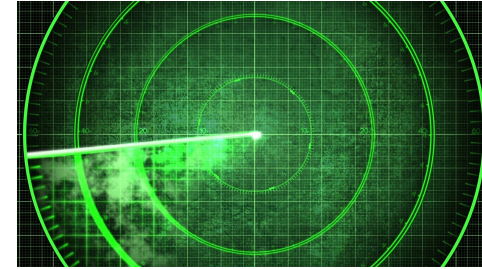
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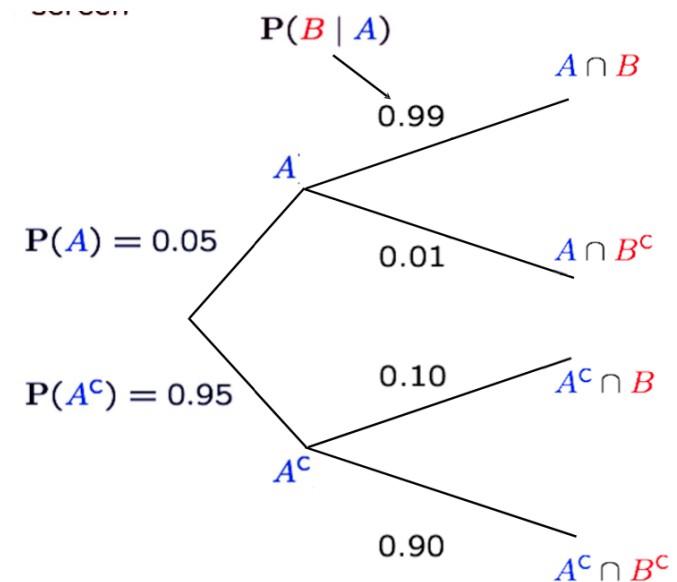
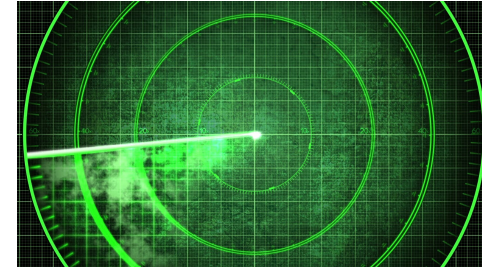
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$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} = \frac{0.0495}{0.1445} \approx 0.34$$



From now on, using the theory of probability and conditional probability constructed so far, we will develop interesting properties and theorems which are very useful to answer some exciting questions.

That is *Bayes' Rule* to make some *inference* (추론).

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We will study this topic rigorously later in this class (chapter 8).

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- A probability tree diagram illustrating the joint probability of three events A , B , and C . The tree starts with a root node branching into A and A^c . From A , it branches into B and B^c . From A^c , it branches into B and B^c . The final branches represent the joint events $A \cap B \cap C$, $A \cap B \cap C^c$, $A^c \cap B \cap C$, and $A^c \cap B \cap C^c$. Probabilities are labeled at each stage: $P(A)$ and $P(A^c)$ at the first stage, and $P(B|A)$ and $P(B|A^c)$ at the second stage.

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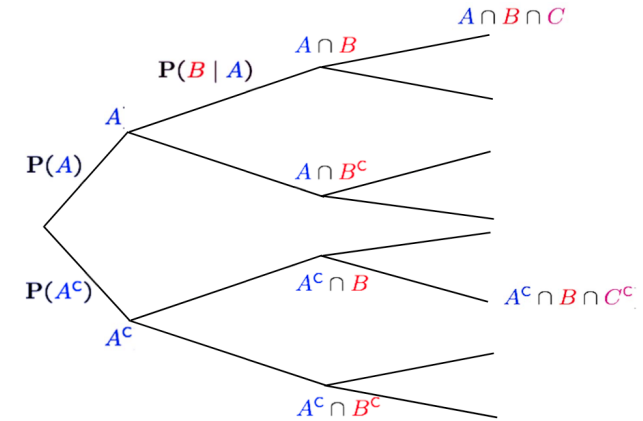
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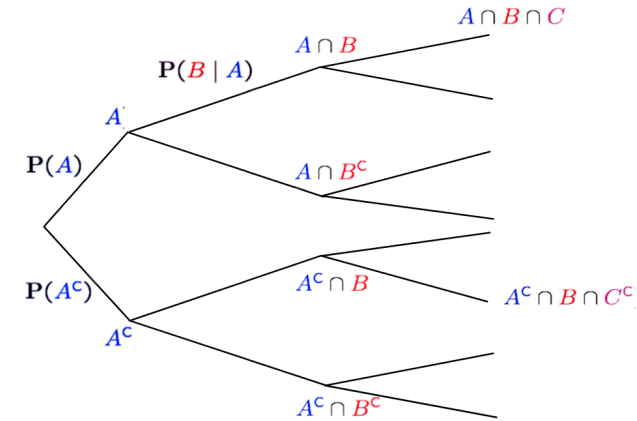


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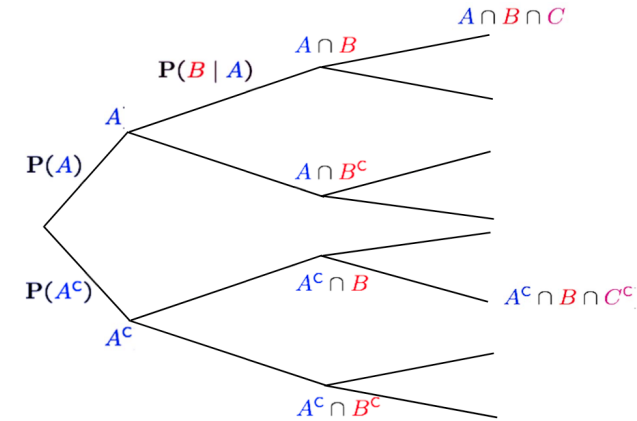


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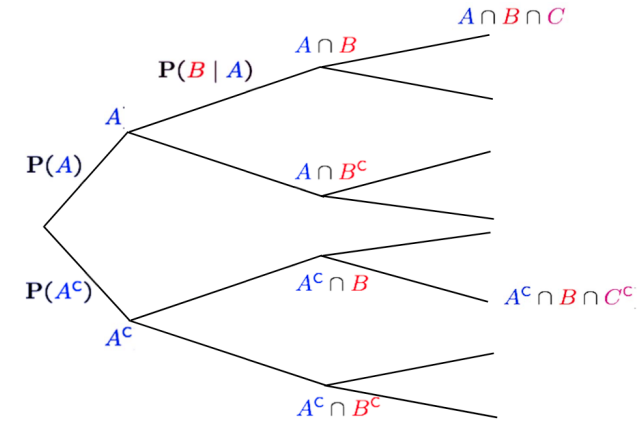


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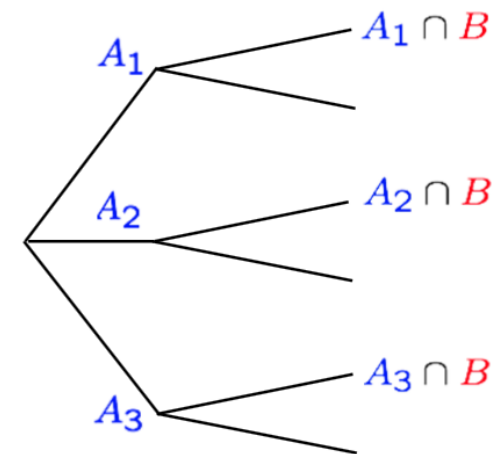
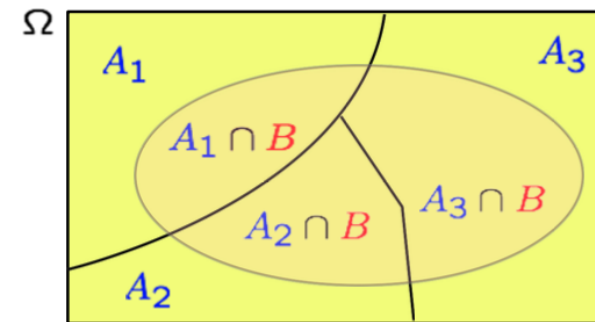
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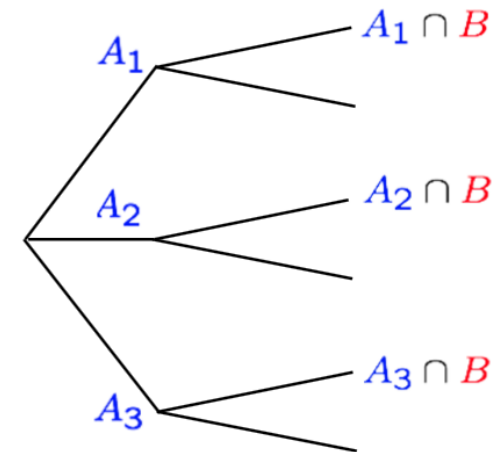
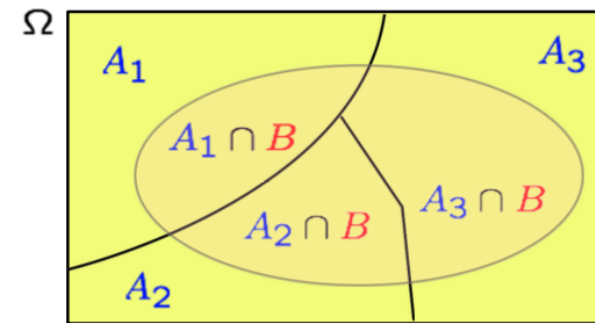
$$\mathbb{P}(A_1 \cap A_2 \cap \cdots \cap A_n) = \mathbb{P}(A_1) \cdot \mathbb{P}(A_2|A_1) \cdot \mathbb{P}(A_3|A_1, A_2) \cdots \mathbb{P}(A_n|A_1, A_2, \dots, A_{n-1})$$

Total Probability Theorem



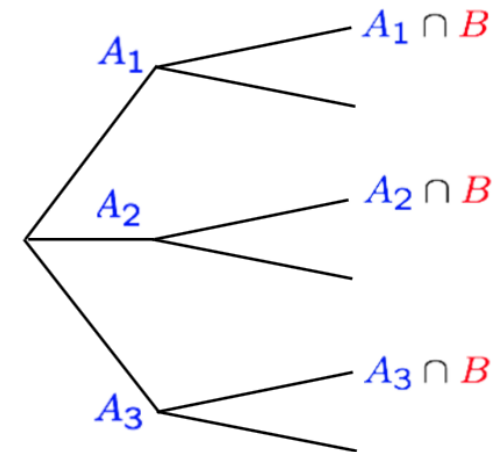
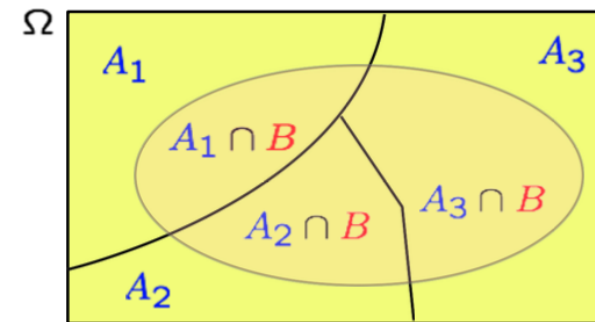
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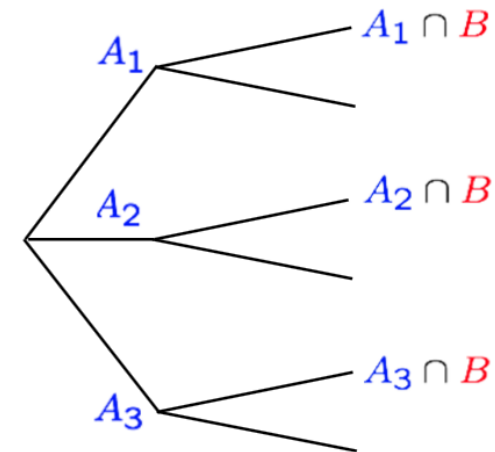
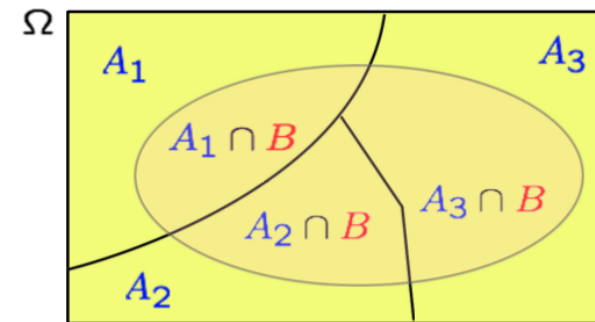
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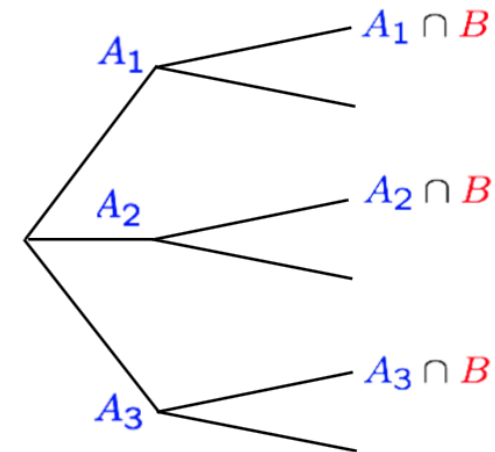
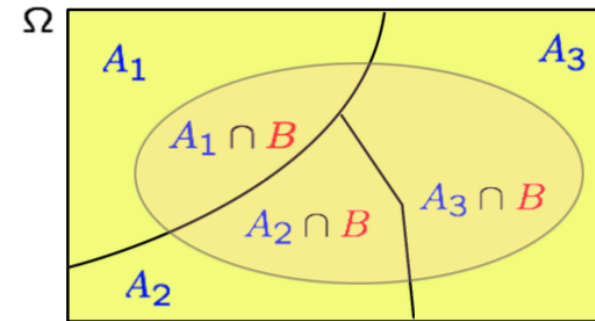
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$$\mathbb{P}(B) = \sum_i \mathbb{P}(A_i) \mathbb{P}(B|A_i)$$

- $\mathbb{P}(A_i \cap B) = \mathbb{P}(A_i) \mathbb{P}(B|A_i)$



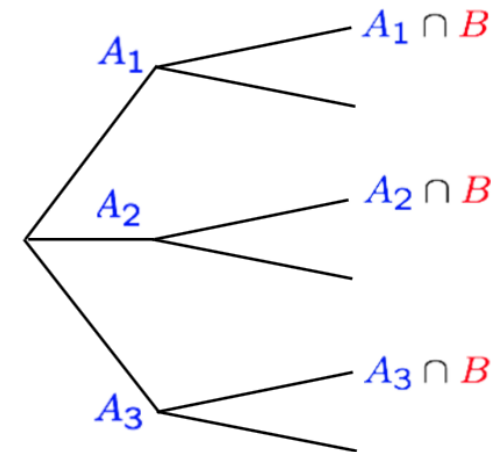
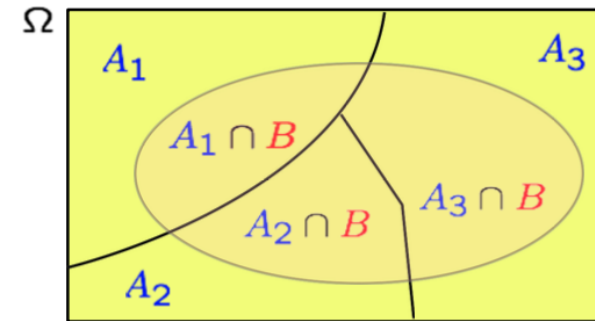
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- We know from my model: $\mathbb{P}(A_i)$ and $\mathbb{P}(B|A_i)$
- What is $\mathbb{P}(B)$? (probability of result)

Total Probability Theorem

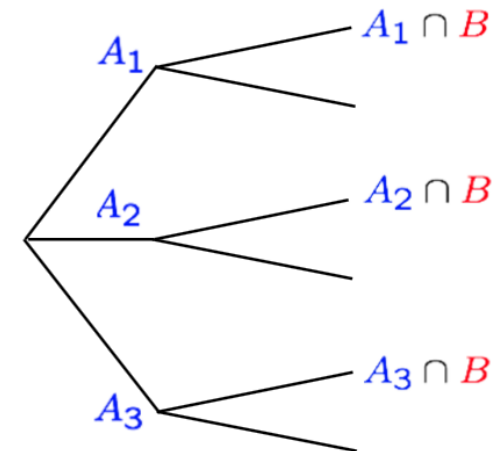
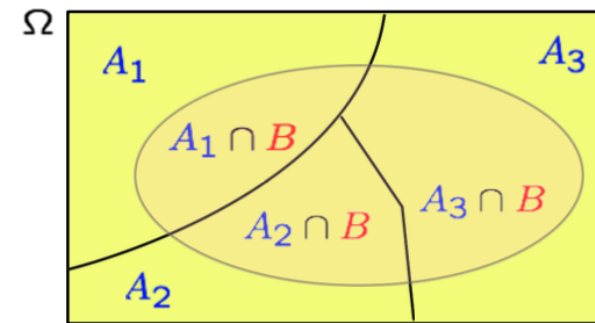
$$\mathbb{P}(B) = \sum_i \mathbb{P}(A_i) \mathbb{P}(B|A_i)$$

- $\mathbb{P}(A_i \cap B) = \mathbb{P}(A_i) \mathbb{P}(B|A_i)$
- Weighted average from the point of A_i knowledge.



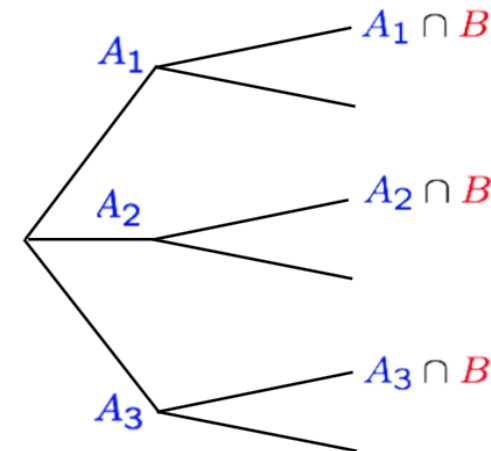
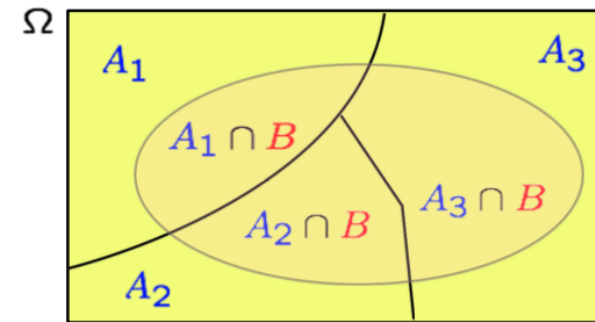
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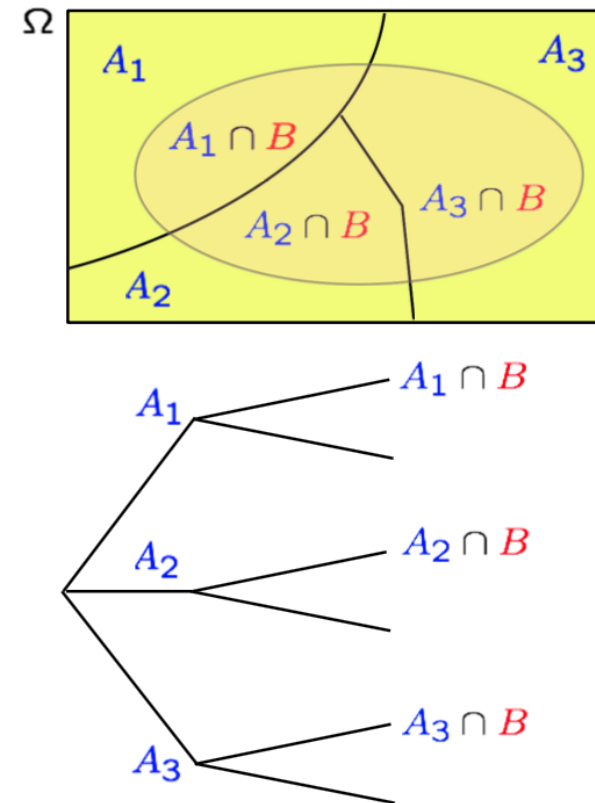


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Bayes' Rule

$$\mathbb{P}(A_i|B) = \frac{\mathbb{P}(A_i)\mathbb{P}(B|A_i)}{\sum_j \mathbb{P}(A_j)\mathbb{P}(B|A_j)}$$



- A_1 : you are happy, A_2 : you are sad
- B : you shout.
- Assume:

$$\mathbb{P}(A_1) = 0.7, \mathbb{P}(A_2) = 0.3,$$

$$\mathbb{P}(B|A_1) = 0.3, \mathbb{P}(B|A_2) = 0.5.$$

- Calculate $\mathbb{P}(A_1|B)$ and $\mathbb{P}(A_2|B)$.

$$\mathbb{P}(A_1)\mathbb{P}(B|A_1) = 0.7 \times 0.3 = 0.21$$

$$\mathbb{P}(A_2)\mathbb{P}(B|A_2) = 0.3 \times 0.5 = 0.15$$

$$\mathbb{P}(B) = 0.21 + 0.15 = 0.36$$

$$\mathbb{P}(A_1|B) = \frac{0.21}{0.36} \approx 0.583$$

$$\mathbb{P}(A_2|B) = \frac{0.15}{0.36} \approx 0.417$$

Bayesian inference was really fun.

Now, let's develop a new concept from conditioning.

That is *Independence*.

Why We Care Independence?



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- Independence makes our analysis and modeling much simpler, because I can remove independent events in my analysis.

- Occurrence of A provides no new information about B . Thus, knowledge about A does not change my belief about B .
- Using $\mathbb{P}(B|A) = \mathbb{P}(B \cap A)/\mathbb{P}(A)$,

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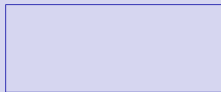
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$$A \perp\!\!\!\perp B \rightarrow A \perp\!\!\!\perp B|C?$$

- Two independent coin tosses
 - H_1 : 1st toss is a head
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 - D : two tosses have different results.

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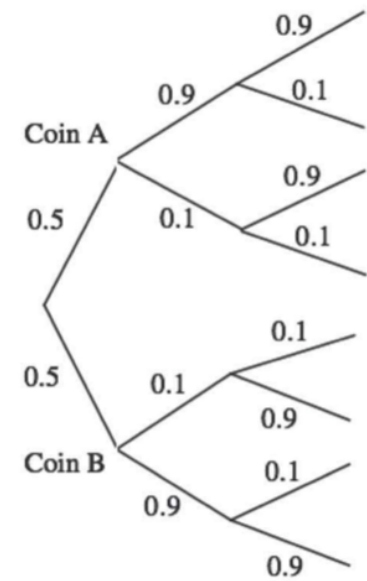
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- No.

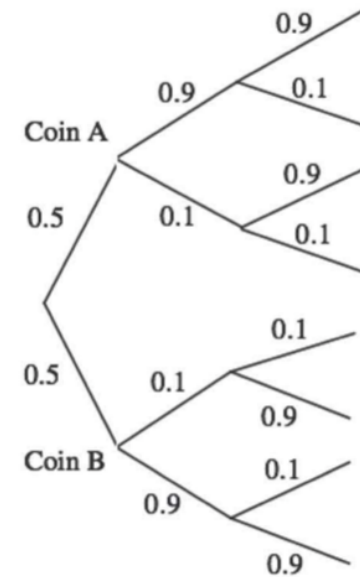
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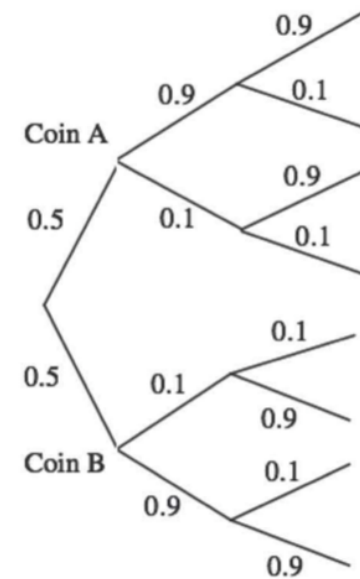
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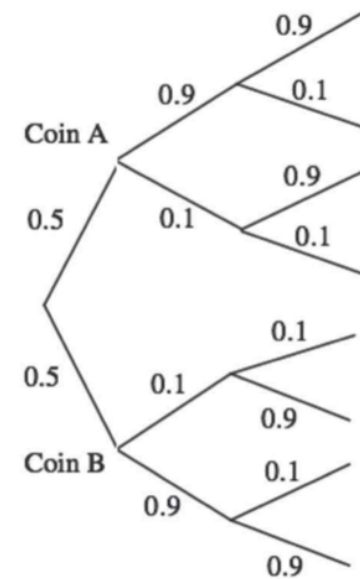


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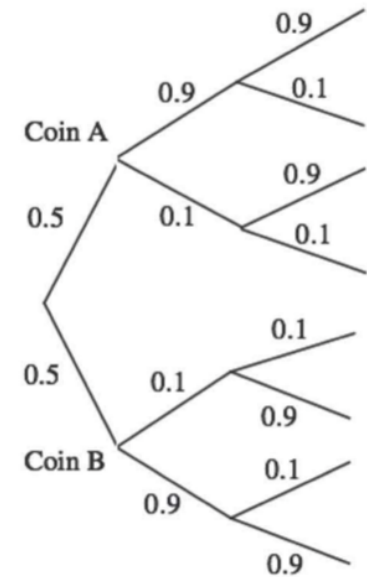
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$$= \frac{1}{2}0.9 + \frac{1}{2}0.1 = \frac{1}{2}$$

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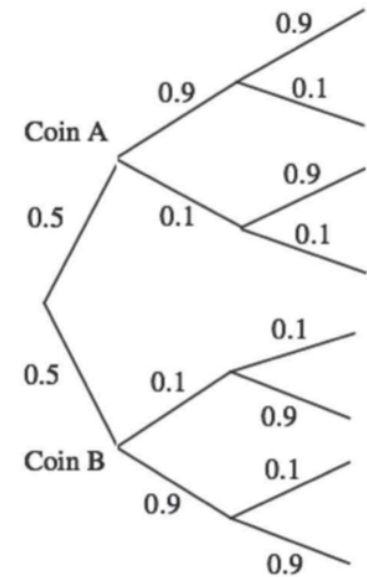
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$$= \frac{1}{2}(0.9 \times 0.9) + \frac{1}{2}(0.1 \times 0.1) \neq \frac{1}{2}$$



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Independence of Multiple Events

The events A_1, A_2, \dots, A_n are said to be independent if

$$\mathbb{P}\left(\bigcap_{i \in S} A_i\right) = \prod_{i \in S} \mathbb{P}(A_i), \quad \text{for every subset } S \text{ of } \{1, 2, \dots, n\}$$

Questions?

- 1) What is conditional probability? Why do we need it?
- 2) Explain the overall framework of Bayesian inference.
- 3) What is the total probability theorem?
- 4) What is Bayes' rule? What does it can give us?
- 5) What's the difference between independence and conditional independence?