

#### Lecture 4: Random Variable, Part II

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EE210: Probability and Introductory Random Processes KAIST EE

June 2, 2021

June 2, 2021

#### Roadmap



- (1) Continuous Random Variable and PDF (Probability Density Function)
- (2) CDF (Cumulative Distribution Function)
- (3) Exponential RVs
- (4) Gaussian (Normal) RVs
- (5) Continuous RVs: Joint, Conditioning, and Independence
- (6) Bayes' rule for RVs

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- $\mathbb{P}(a \le X \le b) = \sum_{x:a \le x \le b} p_X(x)$   $p_X(x) \ge 0$ ,  $\sum_x p_X(x) = 1$



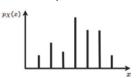
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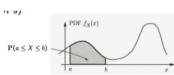
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probability density function (PDF)

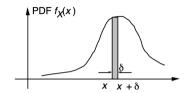
- All of the concepts and methods (expectation, PMFs, and conditioning) for discrete rvs have continuous counterparts



- $\mathbb{P}(a \le X \le b) = \sum_{x:a \le x \le b} p_X(x)$
- $p_X(x) > 0, \sum_{x} p_X(x) = \bar{1}$



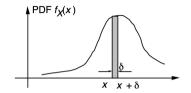
- $\mathbb{P}(a \leq X \leq b) = \int_a^b f_X(x) dx$
- $f_X(x) \ge 0$ ,  $\int_{-\infty}^{\infty} f_X(x) dx = 1$



• 
$$\mathbb{P}(a \leq X \leq a + \delta) \approx$$

#### Examples





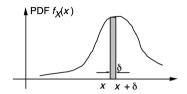
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#### Examples

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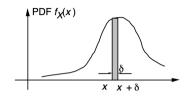
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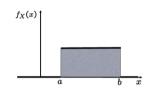


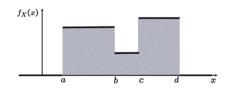


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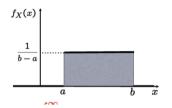
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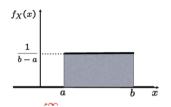






- $\mathbb{E}[X] = \int_{-\infty}^{\infty} x f_X(x) dx =$
- $\mathbb{E}[X^2] = \int_{-\infty}^{\infty} x^2 f_X(x) dx =$
- var[X] =

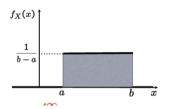




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$$\mathbb{E}[X] = \int_{-\infty}^{\infty} x f_X(x) dx = \int_a^b \frac{x}{b-a} dx = \frac{1}{b-a} \frac{b^2 - a^2}{2} = \frac{b+a}{2}$$

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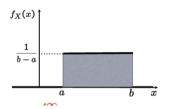




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$$var[X] = \frac{a^2 + ab + b^2}{3} - \frac{a^2 + 2ab + b^2}{4}$$

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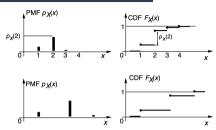


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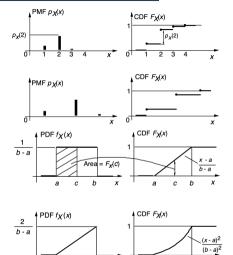




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- If X is continuous
  - $\circ$   $F_X(x)$  is a continuous function of x.

• 
$$F_X(x) = \int_{-\infty}^x f_X(t)dt$$
 and  $f_X(x) = \frac{dF_X}{dx}(x)$ 

#### Example: Maximum of Random Variables



- Take a test three times, and your final score will be the maximum of test scores
- $X = \max\{X_1, X_2, X_3\}$ , and  $X_i \in \{1, 2, \dots, 10\}$  uniformly at random
- Question.  $p_X(x)$ ?
- Approach 1:  $\mathbb{P}(\max\{X_1, X_2, X_3\} = x)$ ?
- Approach 2

$$F_X(x) = \mathbb{P}(\max\{X_1, X_2, X_3\} \le x) = \mathbb{P}(X_1 \le x, X_2 \le x, X_3 \le x)$$
$$= \mathbb{P}(X_1 \le x) \cdot \mathbb{P}(X_2 \le x) \cdot \mathbb{P}(X_3 \le x) = \left(\frac{x}{10}\right)^3$$

Thus,

$$p_X(x) = \left(\frac{x}{10}\right)^3 - \left(\frac{x-1}{10}\right)^3, \quad x = 1, 2, \dots, 10$$

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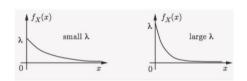
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• A rv X is called exponential with  $\lambda$ , if

$$f_X(x) = \begin{cases} \lambda e^{-\lambda x}, & x \ge 0 \\ 0, & x < 0 \end{cases}$$

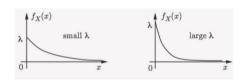




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L4(3)

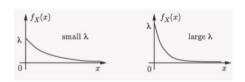
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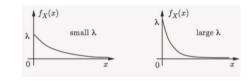
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#### Exponential RV with parameter $\lambda > 0$



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- CDF  $F_X(x) = \int_0^x \lambda e^{-\lambda s} ds = 1 e^{-\lambda x}$
- CCDF  $\mathbb{P}(X > x) = e^{-\lambda x}$
- (Check)  $\mathbb{E}[X] = 1/\lambda$ ,  $\mathbb{E}[X^2] = 2/\lambda^2$ ,  $\text{var}[X] = 1/\lambda^2$

#### Exponential RV: Mean and Variance



•  $\mathbb{E}(X) = 1/\lambda$ . Use integration by parts:  $\int u dv = uv - \int v du$ 

$$\int_0^\infty x\lambda e^{-\lambda x}dx = \left(-xe^{-\lambda x}\right)\Big|_0^\infty + \int_0^\infty e^{-\lambda x}dx = 0 - \frac{e^{-\lambda x}}{\lambda}\Big|_0^\infty = \frac{1}{\lambda}$$

•  $\mathbb{E}(X^2)$ 

$$\int_0^\infty x^2 \lambda e^{-\lambda x} dx = \left(-x^2 e^{-\lambda x}\right)\Big|_0^\infty + \int_0^\infty 2x e^{-\lambda x} dx = 0 + \frac{2}{\lambda} \mathbb{E}(X) = \frac{2}{\lambda^2}$$

•  $\operatorname{\mathsf{var}}(X) = \mathbb{E}(X^2) - (\mathbb{E}(X))^2 = \frac{1}{\lambda^2}$ 



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- What is the relationship between exponential rv and geometric rv? We will see this relationship soon, but let's look at an example first.

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# Example



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  VIDEO PAUSE

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  - $\circ \ \mathbb{E}(X) = 1/\lambda = 10.$  Thus,  $\lambda = \frac{1}{10}.$
  - $\circ$  6 a.m. from midnight = 1/4 day, 6 p.m. from midnight = 3/4 day

$$\mathbb{P}(1/4 \le X \le 3/4) = \mathbb{P}(X \ge 1/4) - \mathbb{P}(X \ge 3/4) = e^{-1/40} - e^{-3/40} = 0.0476$$

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- In many cases, continuous case is some type of limit of its corresponding discrete case.
- Can we mathematically describe how geometric and exponential rvs meet each other in the limit?



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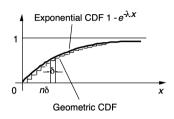
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$$\circ \ \mathbb{P}(X^{geo}_{\delta} \leq n) = 1 - (1 - p_{\delta})^n = 1 - e^{-\lambda \delta n}$$

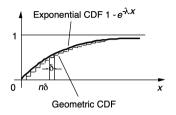
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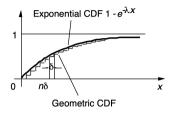


• Note that  $\mathbb{P}(X^{exp} \leq x) = 1 - e^{-\lambda x}$ . Then, when  $x = n\delta, \ n = 1, 2, \dots$ 

$$\mathbb{P}(X^{e \times p} \leq x) = 1 - e^{-\lambda \delta n} =$$

L4(3)





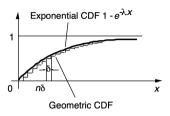
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$$\mathbb{P}(X^{exp} \leq x) = 1 - e^{-\lambda \delta n} = \mathbb{P}(X^{geo}_{\delta} \leq n)$$

• If we choose sufficiently small  $\delta$ , the slot length  $\downarrow$  and  $p_{\delta} \downarrow$ 

$$\mathbb{P}(X_{\delta}^{geo} \leq n) \xrightarrow{\delta \to 0} \mathbb{P}(X^{exp} \leq x), x = n\delta$$

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#### Normal: PDF, Expectation, Variance



• Standard Normal  $\mathcal{N}(0,1)$ 

$$f_X(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$

- $\mathbb{E}[X] = 0$
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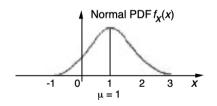
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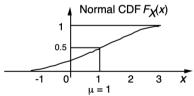
- $\mathbb{E}[X] = 0$
- var[X] = 1

• General Normal  $\mathcal{N}(\mu, \sigma^2)$ 

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}}e^{-(x-\mu)^2/2\sigma^2}$$

- $\mathbb{E}[X] = \mu$
- $\operatorname{var}[X] = \sigma^2$







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• PDF's normalization property:  $\frac{1}{\sigma\sqrt{2\pi}}\int_{-\infty}^{\infty}e^{-(x-\mu)^2/2\sigma^2}dx=1$ 



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  - $f_X(x)$  is symmetric in terms of  $x = \mu$ . Thus, we should have  $\mathbb{E}(X) = \mu$ .

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- Variance

$$var(X) = \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} (x - \mu)^2 e^{-(x - \mu)^2/2\sigma^2} dx \stackrel{y = \frac{x - \mu}{\sigma}}{=} \frac{\sigma^2}{\sqrt{2\pi}} \int_{-\infty}^{\infty} y^2 e^{-y^2/2} dy$$
$$= \frac{\sigma^2}{\sqrt{2\pi}} (-ye^{-y^2/2}) \Big|_{-\infty}^{\infty} + \frac{\sigma^2}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-y^2/2} dy = \frac{\sigma^2}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-y^2/2} dy = \sigma^2$$

$$\int u dv = uv - \int v du$$
:  $u = y$  and  $dv = ye^{-y^2/2} \rightarrow du = dy$  and  $v = -e^{-y^2/2}$ 

#### Normality: Preserved under Linear Transformation



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• Linear transformation preserves normality (we will verify this in Lecture 5)

If 
$$X \sim \mathcal{N}(\mu, \sigma^2)$$
, then for  $a \neq 0$  and  $b, \ Y = aX + b \sim \mathcal{N}(a\mu + b, a^2\sigma^2)$ .

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• Thus, every normal rv can be standardized :

If 
$$X \sim \mathcal{N}(\mu, \sigma^2)$$
, then  $Y = \frac{\mathsf{X} - \mu}{\sigma} \sim \mathcal{N}(0, 1)$ 

L4(4)

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Thus, we can make the table which records the following CDF values:

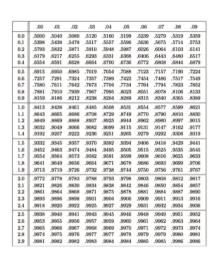
$$\Phi(y) = \mathbb{P}(Y \leq y) = \mathbb{P}(Y < y) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{y} e^{-t^2/2} dt$$

L4(4)

### Example



• Annual snowfall X is modeled as  $\mathcal{N}(60, 20^2)$ . What is the probability that this year's snowfall is at least 80 inches?



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	.00	.01	.02	.03	.04	.05	.06	.07	.08	.09
0.0	.5000	.5040	.5080	.5120	.5160	.5199	.5239	.5279	.5319	.5359
0.1	.5398	.5438	.5478	.5517	.5557	.5596	.5636	.5675	.5714	.5753
0.2	.5793	.5832	.5871	.5910	.5948	.5987	.6026	.6064	.6103	.6141
0.3	.6179	.6217	.6255	.6293	.6331	.6368	.6406	.6443	.6480	.6517
0.4	.6554	.6591	.6628	.6664	.6700	.6736	.6772	.6808	.6844	.6879
0.5	.6915	.6950	.6985	.7019	.7054	.7088	.7123	.7157	.7190	.7224
0.6	.7257	.7291	.7324	.7357	.7389	.7422	.7454	.7486	.7517	.7549
0.7	.7580	.7611	.7642	.7673	.7704	.7734	.7764	.7794	.7823	-7852
0.8	.7881	.7910	.7939	.7967	.7995	.8023	.8051	.8078	.8106	.8133
0.9	.8159	.8186	.8212	.8238	.8264	.8289	.8315	.8340	.8365	.8389
1.0	.8413	.8438	.8461	.8485	.8508	.8531	.8554	.8577	.8599	.8621
1.1	.8643	.8665	.8686	.8708	.8729	.8749	.8770	.8790	.8810	.8830
1.2	.8849	.8869	.8888	.8907	.8925	.8944	.8962	.8980	.8997	.9015
1.3	.9032	.9049	.9066	.9082	.9099	.9115	.9131	.9147	.9162	.9177
1.4	.9192	.9207	.9222	.9236	.9251	.9265	.9279	.9292	.9306	.9319
1.5	.9332	.9345	.9357	.9370	.9382	.9394	.9406	.9418	.9429	.9441
1.6	.9452	.9463	.9474	.9484	.9495	.9505	.9515	.9525	.9535	.9545
1.7	.9554	.9564	.9573	.9582	.9591	.9599	.9608	.9616	.9625	.9633
1.8	.9641	.9649	.9656	.9664	.9671	.9678	.9686	.9693	.9699	.9706
1.9	.9713	.9719	.9726	.9732	.9738	.9744	.9750	.9756	.9761	.9767
2.0	.9772	.9778	.9783	.9788	.9793	.9798	.9803	.9808	.9812	.9817
2.1	.9821	.9826	.9830	.9834	.9838	.9842	.9846	.9850	.9854	.9857
2.2	.9861	.9864	.9868	.9871	.9875	.9878	.9881	.9884	.9887	.9890
2.3	.9893	.9896	.9898	.9901	.9904	.9906	.9909	.9911	.9913	.9916
2.4	.9918	.9920	.9922	.9925	.9927	.9929	.9931	.9932	.9934	.9936
2.5	.9938	.9940	.9941	.9943	.9945	.9946	.9948	.9949	.9951	.9952
2.6	.9953	.9955	.9956	.9957	.9959	.9960	.9961	.9962	.9963	.9964
2.7	.9965	.9966	.9967	.9968	.9969	.9970	.9971	.9972	.9973	.9974
2.8	.9974	.9975	.9976	.9977	.9977	.9978	.9979	.9979	.9980	.9981
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- Annual snowfall X is modeled as  $\mathcal{N}(60, 20^2)$ . What is the probability that this year's snowfall is at least 80 inches?
- $Y = \frac{X-60}{20}$ .

$$\mathbb{P}(X \ge 80) = \mathbb{P}(Y \ge \frac{80 - 60}{20})$$
$$= \mathbb{P}(Y \ge 1) = 1 - \Phi(1)$$
$$= 1 - 0.8413 = 0.1587$$

	.00	.01	.02	.03	.04	.05	.06	.07	.08	.09
0.0	.5000	.5040	.5080	.5120	.5160	.5199	.5239	.5279	.5319	.5359
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#### Normal RVs: Why Important?



- Central limit theorem
  - One of the most remarkable findings in the probability theory
  - $\circ$  Sum of any random variables  $\approx$  Normal random variable
- · Modeling aggregate noise with many small, independent noise terms
- Convenient analytical properties, allowing closed forms in many cases
- Highly popular in communication and machine learning areas

#### Roadmap



- (1) Continuous Random Variable and PDF (Probability Density Function)
- (2) CDF (Cumulative Distribution Function)
- (3) Exponential RVs
- (4) Gaussian (Normal) RVs
- (5) Continuous RVs: Joint, Conditioning, and Independence
- (6) Bayes' rule for RVs

L4(5)

# Continuous: Joint PDF and CDF (1)



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Two continuous rvs are if a non-negative function  $f_{X,Y}(x,y)$  (called joint PDF) satisfies: for every subset B of the two dimensional plane,

$$\mathbb{P}((X,Y)\in B)=\iint_{(x,y)\in B}f_{X,Y}(x,y)dxdy,$$

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The joint PDF is used to calculate probabilities

$$\mathbb{P}\Big[(X,Y)\in B\Big]=\iint_{(X,Y)\in B}f_{X,Y}(x,y)dxdy$$

Our particular interest:  $B = \{(x, y) \mid a \le x \le b, c \le y \le d\}$ 

L4(5)

# Continuous: Joint PDF and CDF (2)



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2. The marginal PDFs of X and Y are from the joint PDF as:

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy, \quad f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx$$

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27 / 45

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27 / 45

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4. A function g(X, Y) of X and Y defines a new random variable, and

$$\mathbb{E}[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{X,Y}(x,y) dxdy$$



\* Conditional PDF, given an event A

\* Conditional PDF, given  $\{X \in C\}$ 

Notation: A is an event, but B and C is a subset that includes the possible values which can be taken by the rv X. Sorry for the confusion, if any.



- \* Conditional PDF, given an event A
- $f_X(x) \cdot \delta \approx \mathbb{P}(x \le X \le x + \delta)$ •  $f_{X|A}(x) \cdot \delta \approx \mathbb{P}(x \le X \le x + \delta|A)$

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L4(5)



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$$f_{X|\{X\in C\}}(x)\cdot\delta\approx\mathbb{P}(x\leq X\leq x+\delta|X\in C)$$

$$f_{X|\{X\in C\}}(x) = \begin{cases} 0, & \text{if } x \notin C \\ \frac{f_X(x)}{\mathbb{P}(X\in C)}, & \text{if } x \in C \end{cases}$$

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(Q) In the discrete, we consider the event  $\{X = x\}$ , not  $\{X \in B\}$ . Why?

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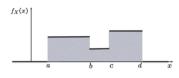
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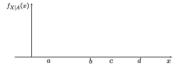


- $\mathbb{E}[X] = \int x f_X(x) dx$  $\mathbb{E}[X|A] = \int x f_{X|A}(x) dx$
- $\mathbb{E}[g(X)] = \int g(x)f_X(x)dx$  $\mathbb{E}[g(X)|A] = \int g(x)f_{X|A}(x)dx$



$$A = \left\{ \frac{a+b}{2} \le X \le b \right\}$$





• 
$$\mathbb{E}[X] = \int x f_X(x) dx$$
  
 $\mathbb{E}[X|A] = \int x f_{X|A}(x) dx$ 

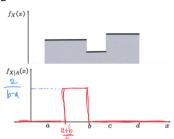
• 
$$\mathbb{E}[g(X)] = \int g(x) f_X(x) dx$$
  
 $\mathbb{E}[g(X)|A] = \int g(x) f_{X|A}(x) dx$ 

$$\mathbb{E}[X|A] =$$

$$\mathbb{E}[X^2|A] =$$



$$A = \left\{ \frac{a+b}{2} \le X \le b \right\}$$



• 
$$\mathbb{E}[X] = \int x f_X(x) dx$$
  
 $\mathbb{E}[X|A] = \int x f_{X|A}(x) dx$ 

• 
$$\mathbb{E}[g(X)] = \int g(x)f_X(x)dx$$
  
 $\mathbb{E}[g(X)|A] = \int g(x)f_{X|A}(x)dx$ 

$$\mathbb{E}[X|A] = \int_{(a+b)/2}^{b} x \frac{2}{b-a} dx = \frac{a}{4} + \frac{3b}{4}$$

$$\mathbb{E}[X^{2}|A] = \int_{(a+b)/2}^{b} x^{2} \frac{2}{b-a} dx =$$



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Definition. A random variable X is called memoryless if, for any  $n, m \ge 0$ ,

$$\mathbb{P}(X > n + m | X > m) = \mathbb{P}(X > n)$$

• Proof. Note that the exponential rv's CCDF  $\mathbb{P}(X>x)=e^{-\lambda x}$ .



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Definition. A random variable X is called memoryless if, for any n, m > 0,

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• Proof. Note that the exponential rv's CCDF  $\mathbb{P}(X > x) = e^{-\lambda x}$ . Then,

$$\mathbb{P}(X>n+m|X>m)=\frac{\mathbb{P}(X>n+m)}{\mathbb{P}(X>m)}=\frac{e^{-\lambda(n+m)}}{e^{-\lambda m}}=e^{-\lambda n}=\mathbb{P}(X>n)$$

L4(5)



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Partition of  $\Omega$  into  $A_1, A_2, A_3, \ldots$ 

\* Discrete case

\* Continuous case



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#### Total Probability Theorem

$$p_X(x) = \sum_i \mathbb{P}(A_i)\mathbb{P}(X = x|A_i)$$
  
=  $\sum_i \mathbb{P}(A_i)p_{X|A_i}(x)$ 

#### Total Expectation Theorem

$$\mathbb{E}[X] = \sum_i \mathbb{P}(A_i) \mathbb{E}[X|A_i]$$

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$$f_X(x) = \sum_i \mathbb{P}(A_i) f_{X|A_i}(x)$$



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#### Total Probability Theorem

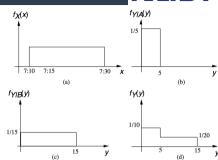
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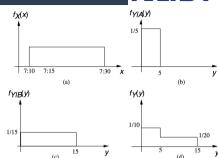
**KAIST EE** 

- The train's arrival every quarter hour (0, 15min, 30min, 45min).
- Your arrival  $\sim \mathcal{U}(7:10, 7:30)$  am.



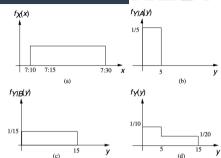


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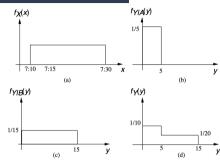




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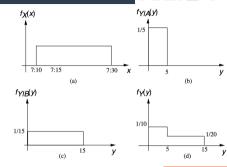


## Example: Train Arrival



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#### VIDEO PAUSE

$$f_{Y}(y) = \mathbb{P}(A)f_{Y|A}(y) + \mathbb{P}(B)f_{Y|B}(y)$$
 for  $0 \le y \le 5$ 

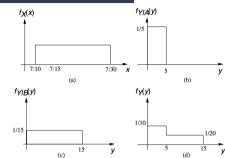
for 
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$$\begin{split} f_Y(y) &= \mathbb{P}(A) f_{Y|A}(y) + \mathbb{P}(B) f_{Y|B}(y) \\ f_Y(y) &= \frac{1}{4} \frac{1}{5} + \frac{3}{4} \frac{1}{15} = \frac{1}{10}, \quad \text{for } 0 \le y \le 5 \end{split}$$

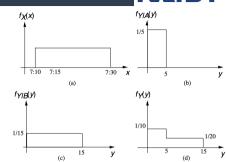
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$$f_{Y}(y) = \mathbb{P}(A)f_{Y|A}(y) + \mathbb{P}(B)f_{Y|B}(y)$$

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• 
$$p_{X|Y}(x|y) = \frac{p_{X,Y}(x,y)}{p_Y(y)}$$



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- $p_{X|Y}(x|y) = \frac{p_{X,Y}(x,y)}{p_Y(y)}$
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$$\int_{-\infty}^{\infty} f_{X|Y}(x|y) \frac{dx}{dx} = \frac{\int_{-\infty}^{\infty} f_{X,Y}(x,y) dx}{f_{Y}(y)} = 1$$



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Independence

$$f_{X,Y}(x,y) = f_X(x)f_Y(y)$$
, for all x and y



(Prob 21 at pp. 191)

- Break a stick of length / twice
  - first break at  $Y \sim \mathcal{U}[0, I]$
  - second break at  $X \sim \mathcal{U}[0, Y]$



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- (a) joint PDF  $f_{X,Y}(x,y)$ ?

$$f_Y(y) = \frac{1}{l}, \quad 0 \le y \le 1$$

$$f_{X|Y}(x|y) = \frac{1}{l}, \quad 0 \le x \le y$$

L4(5)

Using 
$$f_{X,Y}(x,y) = f_Y(y)f_{X|Y}(x|y)$$
,

$$f_{X,Y}(x,y) = \begin{cases} \frac{1}{l} \cdot \frac{1}{y}, & 0 \le x \le y \le l, \\ 0, & \text{otherwise} \end{cases}$$

 $<sup>{}^0\</sup>mathcal{U}[a,b]$ : continuous uniform random variable over the interval [a,b]



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L4(5)

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marginal PDF  $f_X(x)$ ?

$$f_X(x) = \int f_{X,Y}(x,y)dy = \int_x^I \frac{1}{Iy}dy$$
$$= \frac{1}{I}\ln(I/x), \quad 0 \le x \le I$$

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(c) Evaluate  $\mathbb{E}(X)$ , using  $f_X(x)$ 

(d) Evaluate  $\mathbb{E}(X)$ , using  $X = Y \cdot (X/Y)$ If  $Y \perp \!\!\! \perp X/Y$ , it becomes easy, but true? (e) Evaluate  $\mathbb{E}(X)$ , using TET



(c) Evaluate  $\mathbb{E}(X)$ , using  $f_X(x)$ 

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$$0\mathbb{E}[X] = \int_{-\infty}^{\infty} f_Y(y)\mathbb{E}[X|Y=y]dy$$
$$= \int_{0}^{1} \frac{1}{l} \mathbb{E}[X|Y=y]dy = \int_{0}^{1} \frac{1}{l} \frac{y}{2} dy = \frac{l}{4}$$



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 Message. There are many ways to rearch our goal. Of crucial importance is how to find the best way!

L4(5)

### Roadmap



- (1) Continuous Random Variable and PDF (Probability Density Function)
- (2) CDF (Cumulative Distribution Function)
- (3) Exponential RVs
- (4) Gaussian (Normal) RVs
- (5) Continuous RVs: Joint, Conditioning, and Independence
- (6) Bayes' rule for RVs

L4(6)

# Bayes Rule for Continuous



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- X: state/cause/original value  $\rightarrow Y$ : result/resulting action/noisy measurement
- Given:  $\mathbb{P}(X)$  and  $\mathbb{P}(Y|X)$  (cause o result)
- Inference:  $\mathbb{P}(X|Y)$ ?

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- Question. What can we say about the underlying paramter  $\lambda$ ? In other words, what is  $f_{\Lambda|Y}(\lambda|y)$ ?

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$$f_{\Lambda|Y}(\lambda|y) = \frac{f_{\Lambda}(\lambda)f_{Y|\Lambda}(y|\lambda)}{\int_{-\infty}^{\infty} f_{\Lambda}(t)f_{Y|\Lambda}(y|t)dt}$$

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# Using Bayes Rule for Parameter Learning



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- X: parameter → Y: result of my model
- Given:  $\mathbb{P}(X)$  and  $\mathbb{P}(Y|X)$  (parameter  $\to$  model)
- Inference:  $\mathbb{P}(X|Y)$ ? Probabilistic feature of the parameter given the result of the model?

#### Example.

# Using Bayes Rule for Parameter Learning



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#### Example.

- 1. Light bulb's lifetime  $Y \sim \exp(\lambda)$ . Given the lifetime V, the modified belief about  $\lambda$ ?
- 2. Romeo and Juliet start dating, but Romeo will be late by a random variable  $Y \sim \mathcal{U}[0, \theta]$ . Given the time of being late  $\mathbf{v}$ , the modified belief about  $\theta$ ?

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K: discrete, Y: continuous

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K: discrete, Y: continuous

• Inference of K given Y

• Inference of Y given K

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K: discrete, Y: continuous

• Inference of K given Y

$$p_{K|Y}(k|y) = \frac{p_K(k)f_{Y|K}(y|k)}{f_Y(y)}$$
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Inference of Y given K



K: discrete, Y: continuous

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• Wait!  $p_{K|Y}(k|y)$ ? Well-defined?

$$p_{K|Y}(k|y) = \frac{\mathbb{P}(K=k, Y=y)}{\mathbb{P}(Y=y)} = \frac{0}{0}$$

# $p_{K|Y}(k|y)$ ?



• For small  $\delta$  (in other words, taking the limit as  $\delta \to 0$ ).

Let 
$$A = \{K = k\}.$$

$$\frac{p_{K|Y}(k|y)}{\mathbb{P}(A|y \leq Y \leq y + \delta)} \\
= \frac{\mathbb{P}(A)\mathbb{P}(y \leq Y \leq y + \delta|A)}{\mathbb{P}(y \leq Y \leq y + \delta)} \\
\approx \frac{\mathbb{P}(A)f_{Y|A}(y)\delta}{f_{Y}(y)\delta} \\
= \frac{\mathbb{P}(A)f_{Y|A}(y)}{f_{Y}(y)}$$

L4(6)

# Example: Signal Detection (1)



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Inference of discrete K given continuous Y:

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L4(6)



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- Y: measured signal with Gaussian noise, Y = K + W,  $W \sim \mathcal{N}(0,1)$
- Your received signal = 0.7. What's your guess about the original signal? +1
- Your received signal = -0.2. What's your guess about the original signal? -1
- Your intuition: If positive received signal, +1. If negative received signal, -1. How can we mathematically verify this?

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• Probability that K = 1, given Y = y? After some algebra,

$$p_{K|Y}(1|y) = \frac{1}{1 + e^{-2y}}$$

L4(6)



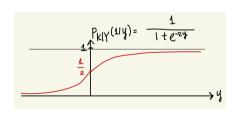
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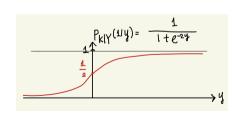
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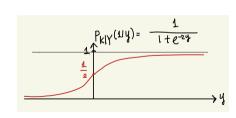
•  $Y|\{K=1\} \sim \mathcal{N}(1,1)$  and  $Y|\{K=-1\} \sim \mathcal{N}(-1,1)$ . (Remind: linear transformation preserves normality.)

$$\begin{split} f_{Y|K}(y|k) &= \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(y-k)^2}, \quad k = 1, -1 \\ f_{Y}(y) &= \frac{1}{2} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(y+1)^2} + \frac{1}{2} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(y-1)^2} \end{split} \tag{from TPT}$$

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- If y > 0, the inference probability for K = 1 exceeds  $\frac{1}{2}$ . So, original signal = 1.
- Similarly, compute  $p_{K|Y}(-1|y)$  and then do the inference





# Questions?

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#### Review Questions



- 1) What is PDF and CDF?
- 2) Why do we need CDF?
- 3) What are joint/marginal/conditional PDFs?
- 4) Explain memorylessness of exponential random variables.
- Explain the version of Bayes' rule for continuous and mixed random variables.

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