

Lecture 4: Random Variable, Part II

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EE210: Probability and Introductory Random Processes KAIST EE

May 5, 2021

Roadmap



- (1) Continuous Random Variable and PDF (Probability Density Function)
- (2) CDF (Cumulative Distribution Function)
- (3) Exponential RVs
- (4) Gaussian (Normal) RVs
- (5) Continuous RVs: Joint, Conditioning, and Independence
- (6) Bayes' rule for RVs

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A rv X is continuous if \exists a function f_X , called probability density function (PDF), s.t. $\mathbb{P}(X \in B) = \int_B f_X(x) dx, \quad \text{every subset } B \in \mathbb{R}$

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- All of the concepts and methods (expectation, PMFs, and conditioning) for discrete rvs have continuous counterparts

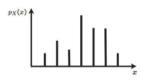
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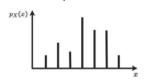
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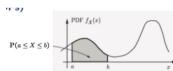
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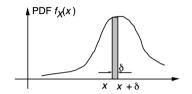
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- $\mathbb{P}(a \le X \le b) = \int_a^b f_X(x) dx$ $f_X(x) \ge 0$, $\int_{-\infty}^{\infty} f_X(x) dx = 1$



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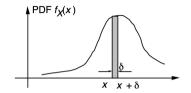


•
$$\mathbb{P}(a \leq X \leq a + \delta) \approx$$

Examples

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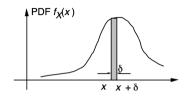
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Examples

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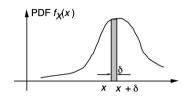
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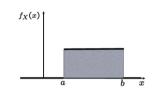


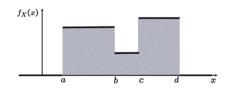


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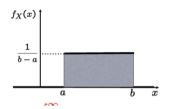
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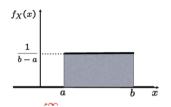






- $\mathbb{E}[X] = \int_{-\infty}^{\infty} x f_X(x) dx =$
- $\mathbb{E}[X^2] = \int_{-\infty}^{\infty} x^2 f_X(x) dx =$
- var[X] =

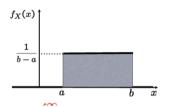




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$$\mathbb{E}[X] = \int_{-\infty}^{\infty} x f_X(x) dx = \int_a^b \frac{x}{b-a} dx = \frac{1}{b-a} \frac{b^2 - a^2}{2} = \frac{b+a}{2}$$

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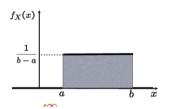




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$$var[X] = \frac{a^2 + ab + b^2}{3} - \frac{a^2 + 2ab + b^2}{4}$$

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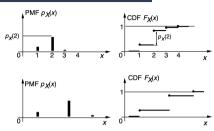


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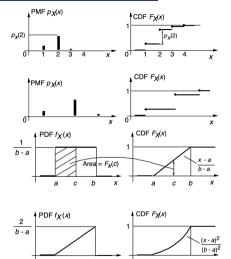
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L4(2)



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- If X is continuous
 - $F_X(x)$ is a continuous function of x.

•
$$F_X(x) = \int_{-\infty}^x f_X(t)dt$$
 and $f_X(x) = \frac{dF_X}{dx}(x)$

Example: Maximum of Random Variables



- Take a test three times, and your final score will be the maximum of test scores
- $X = \max\{X_1, X_2, X_3\}$, and $X_i \in \{1, 2, \dots, 10\}$ uniformly at random
- Question. $p_X(x)$?
- Approach 1: $\mathbb{P}(\max\{X_1, X_2, X_3\} = x)$?
- Approach 2

$$F_X(x) = \mathbb{P}(\max\{X_1, X_2, X_3\} \le x) = \mathbb{P}(X_1 \le x, X_2 \le x, X_3 \le x)$$
$$= \mathbb{P}(X_1 \le x) \cdot \mathbb{P}(X_2 \le x) \cdot \mathbb{P}(X_3 \le x) = \left(\frac{x}{10}\right)^3$$

Thus,

$$p_X(x) = \left(\frac{x}{10}\right)^3 - \left(\frac{x-1}{10}\right)^3, \quad x = 1, 2, \dots, 10$$

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L4(3)

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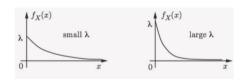




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• A rv X is called exponential with λ , if

$$f_X(x) = \begin{cases} \lambda e^{-\lambda x}, & x \ge 0 \\ 0, & x < 0 \end{cases}$$



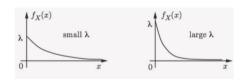


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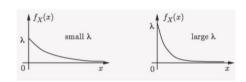


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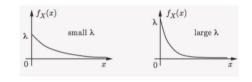
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Exponential RV with parameter $\lambda > 0$



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- CDF $F_X(x) = \int_0^x \lambda e^{-\lambda s} ds = 1 e^{-\lambda x}$
- CCDF $\mathbb{P}(X > x) = e^{-\lambda x}$
- (Check) $\mathbb{E}[X] = 1/\lambda$, $\mathbb{E}[X^2] = 2/\lambda^2$, $var[X] = 1/\lambda^2$

Exponential RV: Mean and Variance



• $\mathbb{E}(X) = 1/\lambda$. Use integration by parts: $\int u dv = uv - \int v du$

$$\int_0^\infty x\lambda e^{-\lambda x}dx = \left(-xe^{-\lambda x}\right)\Big|_0^\infty + \int_0^\infty e^{-\lambda x}dx = 0 - \frac{e^{-\lambda x}}{\lambda}\Big|_0^\infty = \frac{1}{\lambda}$$

• $\mathbb{E}(X^2)$

$$\int_0^\infty x^2 \lambda e^{-\lambda x} dx = \left(-x^2 e^{-\lambda x}\right)\Big|_0^\infty + \int_0^\infty 2x e^{-\lambda x} dx = 0 + \frac{2}{\lambda} \mathbb{E}(X) = \frac{2}{\lambda^2}$$

• $\operatorname{\mathsf{var}}(X) = \mathbb{E}(X^2) - (\mathbb{E}(X))^2 = \frac{1}{\lambda^2}$



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- What is the relationship between exponential rv and geometric rv? We will see this relationship soon, but let's look at an example first.

Example



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Example¹



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 VIDEO PAUSE

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 VIDEO PAUSE
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- (Solution)
 - $\circ \ \mathbb{E}(X) = 1/\lambda = 10.$ Thus, $\lambda = \frac{1}{10}.$
 - \circ 6 a.m. from midnight = 1/4 day, 6 p.m. from midnight = 3/4 day

$$\mathbb{P}(1/4 \le X \le 3/4) = \mathbb{P}(X \ge 1/4) - \mathbb{P}(X \ge 3/4) = e^{-1/40} - e^{-3/40} = 0.0476$$

L4(3)

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- In many cases, continuous case is some type of limit of its corresponding discrete case.
- Can we mathematically describe how geometric and exponential rvs meet each other in the limit?



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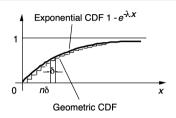


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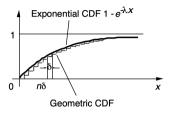
$$\circ \ \mathbb{P}(X^{geo}_{\delta} \leq n) = 1 - (1 - p_{\delta})^n = 1 - e^{-\lambda \delta n}$$



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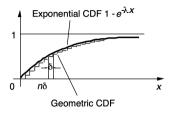


• Note that $\mathbb{P}(X^{exp} \leq x) = 1 - e^{-\lambda x}$. Then, when $x = n\delta, n = 1, 2, ...$

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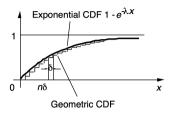
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$$\mathbb{P}(X^{exp} \le x) = 1 - e^{-\lambda \delta n} = \mathbb{P}(X^{geo}_{\delta} \le n)$$





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$$\mathbb{P}(X^{exp} \leq x) = 1 - e^{-\lambda \delta n} = \mathbb{P}(X^{geo}_{\delta} \leq n)$$

• If we choose sufficiently small δ , the slot length \downarrow and $p_{\delta} \downarrow$

$$\mathbb{P}(X_{\delta}^{geo} \leq n) \xrightarrow{\delta \to 0} \mathbb{P}(X^{exp} \leq x), x = n\delta$$

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Normal: PDF, Expectation, Variance



• Standard Normal $\mathcal{N}(0,1)$

$$f_X(x) = \frac{1}{\sqrt{2\pi}}e^{-x^2/2}$$

- $\mathbb{E}[X] = 0$
- var[X] = 1

Normal: PDF, Expectation, Variance



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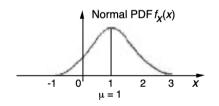
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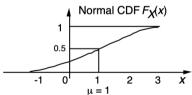
- $\mathbb{E}[X] = 0$
- var[X] = 1

• General Normal $\mathcal{N}(\mu, \sigma^2)$

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}}e^{-(x-\mu)^2/2\sigma^2}$$

- $\mathbb{E}[X] = \mu$
- $\operatorname{var}[X] = \sigma^2$







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• PDF's normalization property: $\frac{1}{\sigma\sqrt{2\pi}}\int_{-\infty}^{\infty}e^{-(x-\mu)^2/2\sigma^2}dx=1$



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 - A little bit boring :-). See Problem 14 at pp 189.



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- PDF's normalization property: $\frac{1}{\sigma\sqrt{2\pi}}\int_{-\infty}^{\infty} \mathrm{e}^{-(x-\mu)^2/2\sigma^2}dx=1$
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- Expectation
 - $f_X(x)$ is symmetric in terms of $x = \mu$. Thus, we should have $\mathbb{E}(X) = \mu$.



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- Expectation
 - $f_X(x)$ is symmetric in terms of $x = \mu$. Thus, we should have $\mathbb{E}(X) = \mu$.
- Variance

$$var(X) = \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} (x - \mu)^2 e^{-(x - \mu)^2/2\sigma^2} dx \stackrel{y = \frac{x - \mu}{\sigma}}{=} \frac{\sigma^2}{\sqrt{2\pi}} \int_{-\infty}^{\infty} y^2 e^{-y^2/2} dy$$
$$= \frac{\sigma^2}{\sqrt{2\pi}} (-ye^{-y^2/2}) \Big|_{-\infty}^{\infty} + \frac{\sigma^2}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-y^2/2} dy = \frac{\sigma^2}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-y^2/2} dy = \sigma^2$$

$$\int u dv = uv - \int v du$$
: $u = y$ and $dv = ye^{-y^2/2} \rightarrow du = dy$ and $v = -e^{-y^2/2}$

Normality: Preserved under Linear Transformation



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Normality: Preserved under Linear Transformation



22 / 45

• Linear transformation preserves normality (we will verify this in Lecture 5)

If
$$X \sim \mathcal{N}(\mu, \sigma^2)$$
, then for $a \neq 0$ and $b, \ Y = aX + b \sim \mathcal{N}(a\mu + b, a^2\sigma^2)$.

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• Thus, we can make the table which records the following CDF values:

$$\Phi(y) = \mathbb{P}(Y \leq y) = \mathbb{P}(Y < y) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{y} e^{-t^2/2} dt$$

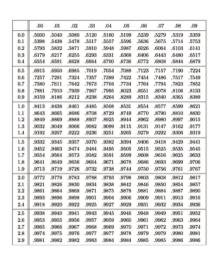
L4(4)

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Example



• Annual snowfall X is modeled as $\mathcal{N}(60, 20^2)$. What is the probability that this year's snowfall is at least 80 inches?



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	.00	.01	.02	.03	.04	.05	.06	.07	.08	.09
0.0	.5000	.5040	.5080	.5120	.5160	.5199	.5239	.5279	.5319	.5359
0.1	.5398	.5438	.5478	.5517	.5557	.5596	.5636	.5675	.5714	.5753
0.2	.5793	.5832	.5871	.5910	.5948	.5987	.6026	.6064	.6103	.6141
0.3	.6179	.6217	.6255	.6293	.6331	.6368	.6406	.6443	.6480	.6517
0.4	.6554	.6591	.6628	.6664	.6700	.6736	.6772	.6808	.6844	.6879
0.5	.6915	.6950	.6985	.7019	.7054	.7088	.7123	.7157	.7190	.7224
0.6	.7257	.7291	.7324	.7357	.7389	.7422	.7454	.7486	.7517	.7549
0.7	.7580	.7611	.7642	.7673	.7704	.7734	.7764	.7794	.7823	.7852
0.8	.7881	.7910	.7939	.7967	.7995	.8023	.8051	.8078	.8106	.8133
0.9	.8159	.8186	.8212	.8238	.8264	.8289	.8315	.8340	.8365	.8389
1.0	.8413	.8438	.8461	.8485	.8508	.8531	.8554	.8577	.8599	.8621
1.1	.8643	.8665	.8686	.8708	.8729	.8749	.8770	.8790	.8810	.8830
1.2	.8849	.8869	.8888	.8907	.8925	.8944	.8962	.8980	.8997	.9015
1.3	.9032	.9049	.9066	.9082	.9099	.9115	.9131	.9147	.9162	.9177
1.4	.9192	.9207	.9222	.9236	.9251	.9265	.9279	.9292	.9306	.9319
1.5	.9332	.9345	.9357	.9370	.9382	.9394	.9406	.9418	.9429	.9441
1.6	.9452	.9463	.9474	.9484	.9495	.9505	.9515	.9525	.9535	.9545
1.7	.9554	.9564	.9573	.9582	.9591	.9599	.9608	.9616	.9625	.9633
1.8	.9641	.9649	.9656	.9664	.9671	.9678	.9686	.9693	.9699	.9706
1.9	.9713	.9719	.9726	.9732	.9738	.9744	.9750	.9756	.9761	.9767
2.0	.9772	.9778	.9783	.9788	.9793	.9798	.9803	.9808	.9812	.9817
2.1	.9821	.9826	.9830	.9834	.9838	.9842	.9846	.9850	.9854	.9857
2.2	.9861	.9864	.9868	.9871	.9875	.9878	.9881	.9884	.9887	.9890
2.3	.9893	.9896	.9898	.9901	.9904	.9906	.9909	.9911	.9913	.9916
2.4	.9918	.9920	.9922	.9925	.9927	.9929	.9931	.9932	.9934	.9936
2.5	.9938	.9940	.9941	.9943	.9945	.9946	.9948	.9949	.9951	.9952
2.6	.9953	.9955	.9956	.9957	.9959	.9960	.9961	.9962	.9963	.9964
2.7	.9965	.9966	.9967	.9968	.9969	.9970	.9971	.9972	.9973	.9974
2.8	.9974	.9975	.9976	.9977	.9977	.9978	.9979	.9979	.9980	.9981
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- $Y = \frac{X-60}{20}$.

$$\mathbb{P}(X \ge 80) = \mathbb{P}(Y \ge \frac{80 - 60}{20})$$
$$= \mathbb{P}(Y \ge 1) = 1 - \Phi(1)$$
$$= 1 - 0.8413 = 0.1587$$

	.00	.01	.02	.03	.04	.05	.06	.07	.08	.09
0.0	.5000	.5040	.5080	.5120	.5160	.5199	.5239	.5279	.5319	.5359
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Normal RVs: Why Important?



- Central limit theorem
 - One of the most remarkable findings in the probability theory
 - \circ Sum of any random variables \approx Normal random variable
- · Modeling aggregate noise with many small, independent noise terms
- Convenient analytical properties, allowing closed forms in many cases
- Highly popular in communication and machine learning areas

Roadmap



- (1) Continuous Random Variable and PDF (Probability Density Function)
- (2) CDF (Cumulative Distribution Function)
- (3) Exponential RVs
- (4) Gaussian (Normal) RVs
- (5) Continuous RVs: Joint, Conditioning, and Independence
- (6) Bayes' rule for RVs

L4(5)

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Continuous: Joint PDF and CDF (1)



Two continuous rvs are if a non-negative function $f_{X,Y}(x,y)$

(called joint PDF) satisfies: for every subset B of the two dimensional plane,

$$\mathbb{P}((X,Y)\in B)=\iint_{(x,y)\in B}f_{X,Y}(x,y)dxdy,$$

Continuous: Joint PDF and CDF (1)



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1. The joint PDF is used to calculate probabilities

$$\mathbb{P}\big[(X,Y)\in B\big]=\iint_{(x,y)\in B}f_{X,Y}(x,y)dxdy$$

Our particular interest: $B = \{(x, y) \mid a \le x \le b, c \le y \le d\}$

L4(5)

Continuous: Joint PDF and CDF (2)



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2. The marginal PDFs of X and Y are from the joint PDF as:

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy, \quad f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx$$

Continuous: Joint PDF and CDF (2)



27 / 45

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3. The joint CDF is defined by $F_{X,Y}(x,y) = \mathbb{P}(X \le x, Y \le y)$, and determines the joint PDF as:

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Continuous: Joint PDF and CDF (2)



27 / 45

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4. A function g(X, Y) of X and Y defines a new random variable, and

$$\mathbb{E}[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{X,Y}(x,y) dxdy$$



* Conditional PDF, given an event A

* Conditional PDF, given $\{X \in C\}$

Notation: A is an event, but B and C is a subset that includes the possible values which can be taken by the rv X. Sorry for the confusion, if any.



- * Conditional PDF, given an event A
- $f_X(x) \cdot \delta \approx \mathbb{P}(x \le X \le x + \delta)$ $f_{X|A}(x) \cdot \delta \approx \mathbb{P}(x \le X \le x + \delta|A)$

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L4(5)



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- $\mathbb{P}(X \in B) = \int_B f_X(x) dx$ $\mathbb{P}(X \in B|A) = \int_{B} f_{X|A}(x) dx$

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L4(5)



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$$f_{X|\{X\in C\}}(x)\cdot\delta\approx\mathbb{P}(x\leq X\leq x+\delta|X\in C)$$

$$f_{X|\{X\in C\}}(x) = \begin{cases} 0, & \text{if } x \notin C \\ \frac{f_X(x)}{\mathbb{P}(X\in C)}, & \text{if } x \in C \end{cases}$$

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(Q) In the discrete, we consider the event $\{X = x\}$, not $\{X \in B\}$. Why?

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L4(5)

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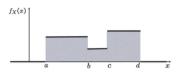
• $\mathbb{E}[X] = \int x f_X(x) dx$ $\mathbb{E}[X|A] = \int x f_{X|A}(x) dx$

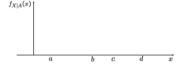


- $\mathbb{E}[X] = \int x f_X(x) dx$ $\mathbb{E}[X|A] = \int x f_{X|A}(x) dx$
- $\mathbb{E}[g(X)] = \int g(x)f_X(x)dx$ $\mathbb{E}[g(X)|A] = \int g(x)f_{X|A}(x)dx$



$$A = \left\{ \frac{a+b}{2} \le X \le b \right\}$$





•
$$\mathbb{E}[X] = \int x f_X(x) dx$$

 $\mathbb{E}[X|A] = \int x f_{X|A}(x) dx$

•
$$\mathbb{E}[g(X)] = \int g(x) f_X(x) dx$$

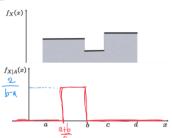
 $\mathbb{E}[g(X)|A] = \int g(x) f_{X|A}(x) dx$

$$\mathbb{E}[X|A] =$$

$$\mathbb{E}[X^2|A] =$$



$$A = \left\{ \frac{a+b}{2} \le X \le b \right\}$$



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- $\mathbb{E}[g(X)] = \int g(x)f_X(x)dx$ $\mathbb{E}[g(X)|A] = \int g(x)f_{X|A}(x)dx$

$$\mathbb{E}[X|A] = \int_{(a+b)/2}^{b} x \frac{2}{b-a} dx = \frac{a}{4} + \frac{3b}{4}$$

$$\mathbb{E}[X^{2}|A] = \int_{(a+b)/2}^{b} x^{2} \frac{2}{b-a} dx =$$



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$$\mathbb{P}(X > n + m | X > m) = \mathbb{P}(X > n)$$

• Proof. Note that the exponential rv's CCDF $\mathbb{P}(X>x)=e^{-\lambda x}$.



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• Proof. Note that the exponential rv's CCDF $\mathbb{P}(X>x)=e^{-\lambda x}$. Then,

$$\mathbb{P}(X>n+m|X>m)=\frac{\mathbb{P}(X>n+m)}{\mathbb{P}(X>m)}=\frac{e^{-\lambda(n+m)}}{e^{-\lambda m}}=e^{-\lambda n}=\mathbb{P}(X>n)$$

L4(5)



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Partition of Ω into A_1, A_2, A_3, \dots

* Discrete case

* Continuous case



Partition of Ω into A_1, A_2, A_3, \dots

* Discrete case

Total Probability Theorem

$$p_X(x) = \sum_i \mathbb{P}(A_i)\mathbb{P}(X = x|A_i)$$

= $\sum_i \mathbb{P}(A_i)p_{X|A_i}(x)$

Total Expectation Theorem

$$\mathbb{E}[X] = \sum_i \mathbb{P}(A_i) \mathbb{E}[X|A_i]$$

* Continuous case



Partition of Ω into A_1, A_2, A_3, \dots

* Discrete case

Total Probability Theorem

$$\rho_X(x) = \sum_i \mathbb{P}(A_i) \mathbb{P}(X = x | A_i)$$

$$= \sum_i \mathbb{P}(A_i) \rho_{X|A_i}(x)$$

Total Expectation Theorem

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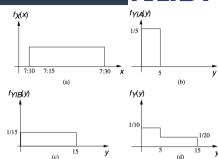
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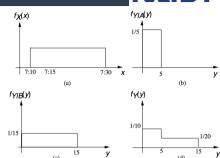
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- The train's arrival every quarter hour (0, 15min, 30min, 45min).
- Your arrival $\sim \mathcal{U}(7:10, 7:30)$ am.



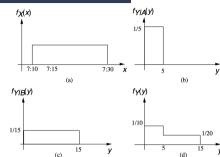


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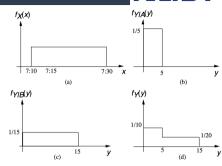
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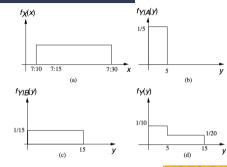
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VIDEO PAUSE

$$f_Y(y) = \mathbb{P}(A)f_{Y|A}(y) + \mathbb{P}(B)f_{Y|B}(y)$$
 for $0 \le y \le 5$

for
$$5 < y \le 15$$

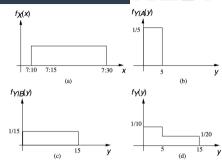
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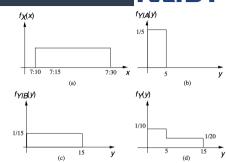
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•
$$p_{X|Y}(x|y) = \frac{p_{X,Y}(x,y)}{p_Y(y)}$$



33 / 45

- $p_{X|Y}(x|y) = \frac{p_{X,Y}(x,y)}{p_Y(y)}$
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L4(5)



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Independence

$$f_{X,Y}(x,y) = f_X(x)f_Y(y)$$
, for all x and y



(Prob 21 at pp. 191)

- Break a stick of length / twice
 - first break at $Y \sim \mathcal{U}[0, I]$
 - second break at $X \sim \mathcal{U}[0,\,Y]$



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- (a) joint PDF $f_{X,Y}(x,y)$?

L4(5)

$$f_Y(y) = \frac{1}{l}, \quad 0 \le y \le 1$$

$$f_{X|Y}(x|y) = \frac{1}{l}, \quad 0 \le x \le y$$

Using
$$f_{X,Y}(x,y) = f_Y(y)f_{X|Y}(x|y)$$
,

$$f_{X,Y}(x,y) = \begin{cases} \frac{1}{l} \cdot \frac{1}{y}, & 0 \le x \le y \le l, \\ 0, & \text{otherwise} \end{cases}$$

 $^{{}^{0}\}mathcal{U}[a,b]$: continuous uniform random variable over the interval [a,b]



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L4(5)

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marginal PDF $f_X(x)$?

$$f_X(x) = \int f_{X,Y}(x,y)dy = \int_x^I \frac{1}{Iy}dy$$
$$= \frac{1}{I}\ln(I/x), \quad 0 \le x \le I$$

 $^{{}^{0}\}mathcal{U}[a,b]$: continuous uniform random variable over the interval [a,b]



(c) Evaluate $\mathbb{E}(X)$, using $f_X(x)$

(d) Evaluate $\mathbb{E}(X)$, using $X = Y \cdot (X/Y)$ If $Y \perp \!\!\! \perp X/Y$, it becomes easy, but true? (e) Evaluate $\mathbb{E}(X)$, using TET



(c) Evaluate $\mathbb{E}(X)$, using $f_X(x)$

$$\mathbb{E}(X) = \int_0^l x f_X(x) dx = \int_0^l \frac{x}{l} \ln(l/x) dx$$
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If $Y \perp \!\!\! \perp X/Y$, it becomes easy, but true? Yes, because whatever Y is, the fraction X/Y does not depend on it.

$$\mathbb{E}(X) = \mathbb{E}(Y)\mathbb{E}(X/Y) = \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{4}$$

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$$0\mathbb{E}[X] = \int_{-\infty}^{\infty} f_Y(y)\mathbb{E}[X|Y=y]dy$$
$$= \int_{0}^{1} \frac{1}{l} \mathbb{E}[X|Y=y]dy = \int_{0}^{1} \frac{1}{l} \frac{y}{2} dy = \frac{l}{4}$$



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 Message. There are many ways to rearch our goal. Of crucial importance is how to find the best way!

Roadmap



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- (1) Continuous Random Variable and PDF (Probability Density Function)
- (2) CDF (Cumulative Distribution Function)
- (3) Exponential RVs
- (4) Gaussian (Normal) RVs
- (5) Continuous RVs: Joint, Conditioning, and Independence
- (6) Bayes' rule for RVs

Bayes Rule for Continuous



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- X: state/cause/original value $\rightarrow Y$: result/resulting action/noisy measurement
- Given: $\mathbb{P}(X)$ and $\mathbb{P}(Y|X)$ (cause \to result)
- Inference: $\mathbb{P}(X|Y)$?

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Using Bayes Rule for Parameter Learning



- X: parameter → Y: result of my model
- Given: $\mathbb{P}(X)$ and $\mathbb{P}(Y|X)$ (parameter \to model)
- Inference: $\mathbb{P}(X|Y)$? Probabilistic feature of the parameter given the result of the model?

Example.

Using Bayes Rule for Parameter Learning



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Example.

- 1. Light bulb's lifetime $Y \sim \exp(\lambda)$. Given the lifetime y, the modified belief about λ ?
- 2. Romeo and Juliet start dating, but Romeo will be late by a random variable $Y \sim \mathcal{U}[0, \theta]$. Given the time of being late y, the modified belief about θ ?



K: discrete, Y: continuous



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• Inference of K given Y

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• Wait! $p_{K|Y}(k|y)$? Well-defined?

$$p_{K|Y}(k|y) = \frac{\mathbb{P}(K=k, Y=y)}{\mathbb{P}(Y=y)} = \frac{0}{0}$$

$p_{K|Y}(k|y)$?



• For small δ (in other words, taking the limit as $\delta \to 0$).

Let
$$A = \{K = k\}.$$

$$\frac{p_{K|Y}(k|y)}{\mathbb{P}(A|y \leq Y \leq y + \delta)} = \frac{\mathbb{P}(A)\mathbb{P}(y \leq Y \leq y + \delta|A)}{\mathbb{P}(y \leq Y \leq y + \delta)} \\
\approx \frac{\mathbb{P}(A)f_{Y|A}(y)\delta}{f_{Y}(y)\delta} \\
= \frac{\mathbb{P}(A)f_{Y|A}(y)}{f_{Y}(y)}$$

L4(6)

Example: Signal Detection (1)



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Inference of discrete K given continuous Y:

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• K: -1, +1, original signal, equally likely. $p_K(1) = 1/2, p_K(-1) = 1/2$.



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- K: -1, +1, original signal, equally likely. $p_K(1) = 1/2$, $p_K(-1) = 1/2$.
- Y: measured signal with Gaussian noise, $Y = K + W, \ W \sim \mathcal{N}(0,1)$
- Your received signal = 0.7. What's your guess about the original signal?



Inference of discrete *K* given continuous *Y*:

$$p_{K|Y}(k|y) = \frac{p_K(k)f_{Y|K}(y|k)}{f_Y(y)}, \quad f_Y(y) = \sum_{k'} p_K(k')f_{Y|K}(y|k')$$

- K: -1, +1, original signal, equally likely. $p_K(1) = 1/2$, $p_K(-1) = 1/2$.
- Y: measured signal with Gaussian noise, Y = K + W, $W \sim \mathcal{N}(0,1)$
- Your received signal = 0.7. What's your guess about the original signal?
- Your received signal = -0.2. What's your guess about the original signal?



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- Your received signal = 0.7. What's your guess about the original signal? +1
- Your received signal = -0.2. What's your guess about the original signal? -1
- Your intuition: If positive received signal, +1. If negative received signal, -1. How can we mathematically verify this?



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• Probability that K = 1, given Y = y? After some algebra,

$$p_{K|Y}(1|y) = \frac{1}{1 + e^{-2y}}$$

L4(6)



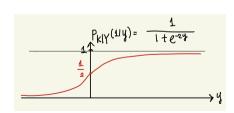
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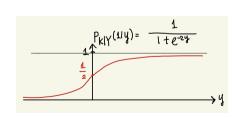
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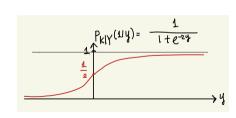
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$$\begin{split} f_{Y|K}(y|k) &= \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(y-k)^2}, \quad k = 1, -1 \\ f_{Y}(y) &= \frac{1}{2} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(y+1)^2} + \frac{1}{2} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(y-1)^2} \end{split} \tag{from TPT}$$

• Probability that K = 1, given Y = y? After some algebra,

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- If y > 0, the inference probability for K = 1 exceeds $\frac{1}{2}$. So, original signal = 1.
- Similarly, compute $p_{K|Y}(-1|y)$ and then do the inference



L4(6)



Questions?

Review Questions



- 1) What is PDF and CDF?
- 2) Why do we need CDF?
- 3) What are joint/marginal/conditional PDFs?
- 4) Explain memorylessness of exponential random variables.
- 5) Explain the version of Bayes' rule for continuous and mixed random variables.