

## Lecture 5: Random Variable, Part III

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EE210: Probability and Introductory Random Processes  
KAIST EE

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- (1) Derived distribution of  $Y = g(X)$  or  $Z = g(X, Y)$
- (2) Derived distribution of  $Z = X + Y$
- (3) Covariance: Degree of dependence between two rvs.
- (4) Correlation coefficient
- (5) Conditional expectation and law of iterative expectations
- (6) Conditional variance and law of total variance
- (7) Random number of sum of random variables

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- What are easy or difficult cases?
- Easy cases
  - Discrete
  - Linear:  $Y = aX + b$

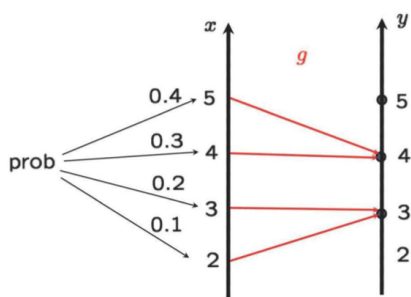


- Take all values of  $x$  such that  $g(x) = y$ , i.e.,

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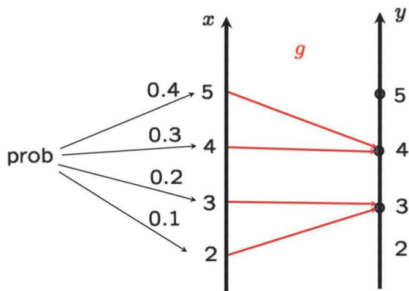
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$$p_Y(3) = p_X(2) + p_X(3) = 0.1 + 0.2 = 0.3$$

$$p_Y(4) = p_X(4) + p_X(5) = 0.3 + 0.4 = 0.7$$



If  $a > 0$ ,

If  $a < 0$ ,

$$\text{If } a > 0, \quad F_Y(y) = \mathbb{P}(aX + b \leq y) = \mathbb{P}(X \leq \frac{y-b}{a}) = F_X(\frac{y-b}{a})$$

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Therefore,

$$f_Y(y) = \frac{1}{|a|} f_X\left(\frac{y-b}{a}\right)$$

$$f_X(x) = \begin{cases} \lambda e^{-\lambda x}, & \text{if } x \geq 0 \\ 0, & \text{otherwise} \end{cases}$$

$$f_Y(y) = \begin{cases} \frac{\lambda}{|a|} e^{-\lambda(y-b)/a}, & \text{if } (y-b)/a \geq 0 \\ 0, & \text{otherwise} \end{cases}$$

- If  $b = 0$  and  $a > 0$ ,  $Y$  is exponential with parameter  $\frac{\lambda}{a}$ , but generally not.

- Remember? Linear transformation preserves normality. Time to prove.

If  $X \sim \mathcal{N}(\mu, \sigma^2)$ , then for  $a \neq 0$  and  $b$ ,  $Y = aX + b \sim \mathcal{N}(a\mu + b, a^2\sigma^2)$ .

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$$\begin{aligned} f_Y(y) &= \frac{1}{|a|} f_X\left(\frac{y-b}{a}\right) = \frac{1}{|a|} \frac{1}{\sqrt{2\pi}} \exp\left\{-\left(\frac{y-b}{a} - \mu\right)^2 / 2\sigma^2\right\} \\ &= \frac{1}{\sqrt{2\pi}|a|\sigma} \exp\left\{-\frac{(y-b-a\mu)^2}{2a^2\sigma^2}\right\} \end{aligned}$$

Generally,  $Y = g(X)$ ,  $X$ : Continuous

Step 1. Find the CDF of  $Y$ :

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Ex1.  $Y = X^2$ .

$$\begin{aligned} F_Y(y) &= \mathbb{P}(X^2 \leq y) = \mathbb{P}(-\sqrt{y} \leq X \leq \sqrt{y}) \\ &= F_X(\sqrt{y}) - F_X(-\sqrt{y}) \end{aligned}$$

$$\begin{aligned} f_Y(y) &= \frac{1}{2\sqrt{y}} f_X(\sqrt{y}) + \\ &\quad \frac{1}{2\sqrt{y}} f_X(-\sqrt{y}), \quad y \geq 0 \end{aligned}$$



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When  $Y = g(X)$  is monotonic, a **general formula** can be drawn (see the textbook at pp 207)

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VIDEO PAUSE

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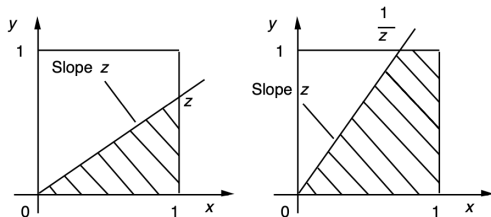
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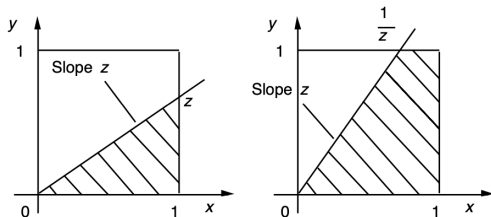
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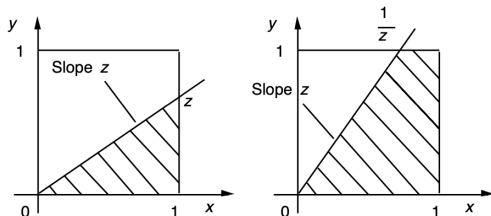
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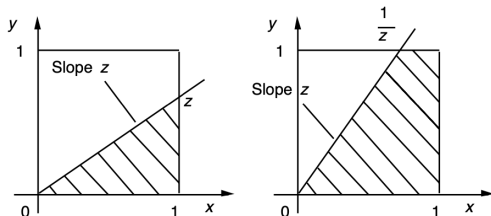
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**(Note)** Sometimes, the problem is tricky, which requires careful case-by-case handling. :-)

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- $p_Z(z)$  is called  of the PMFs of  $X$  and  $Y$ .

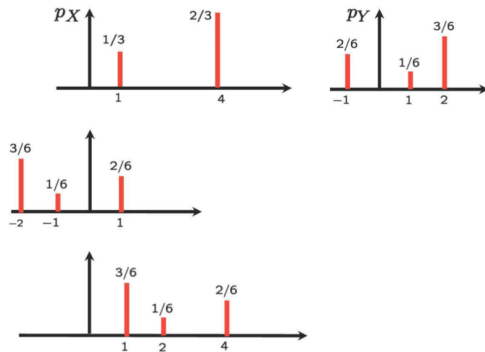
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- $p_Z(z)$  is called convolution of the PMFs of  $X$  and  $Y$ .

- Convolution:  $p_Z(z) = \sum_x p_X(x)p_Y(z-x)$
- Interpretation for a given  $z$ :
  - (i) Flip (horizontally) the PMF of  $Y$  ( $p_Y(-x)$ )
  - (ii) Put it underneath the PMF of  $X$
  - (iii) Right-shift the flipped PMF by  $z$  ( $p_Y(-x+z)$ )

Example.  $z = 3$



- Same logic as the discrete case

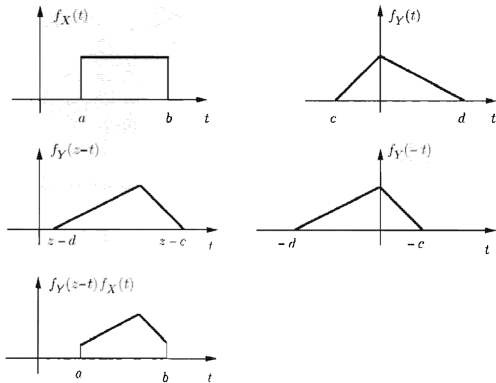
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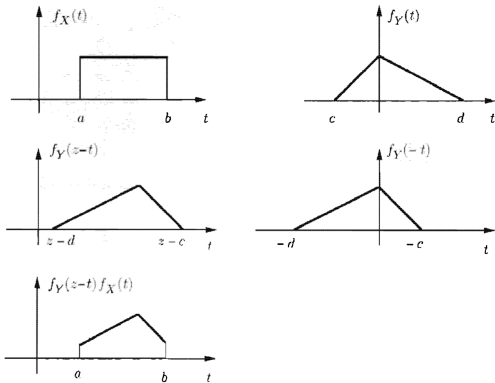


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- Youtube animation for convolution:  
<https://www.youtube.com/watch?v=C1N55M1VD2o>

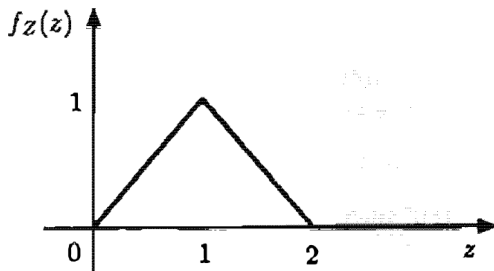
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- **Example.**  $X, Y \sim \mathcal{U}[0, 1]$  and  $X \perp\!\!\!\perp Y$ . What is the PDF of  $Z = X + Y$ ? Draw the PDF of  $Z$ .

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<https://www.youtube.com/watch?v=MQm6ZP1F6ms>

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### Sum of two independent normal rvs

$X \sim \mathcal{N}(\mu_x, \sigma_x^2)$  and  $Y \sim \mathcal{N}(\mu_y, \sigma_y^2)$  Then,  $X + Y \sim \mathcal{N}(\mu_x + \mu_y, \sigma_x^2 + \sigma_y^2)$

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- Why normal rvs are used to model the **sum of random noises**.
- **Extension**. The sum of **finitely many** independent normals is also normal.

$$\begin{aligned} f_Z(z) &= \int_{-\infty}^{\infty} f_X(x) f_Y(z-x) dx \\ &= \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}\sigma_x} \exp\left\{-\frac{(x-\mu_x)^2}{2\sigma_x^2}\right\} \frac{1}{\sqrt{2\pi}\sigma_y} \exp\left\{-\frac{(z-x-\mu_y)^2}{2\sigma_y^2}\right\} dx \end{aligned}$$

- The details of integration is a little bit tedious. :-)

$$f_Z(z) = \frac{1}{\sqrt{2\pi(\sigma_x^2 + \sigma_y^2)}} \exp\left\{-\frac{(z - \mu_x - \mu_y)^2}{2(\sigma_x^2 + \sigma_y^2)}\right\}$$



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- Good engineers: Good at making good metrics
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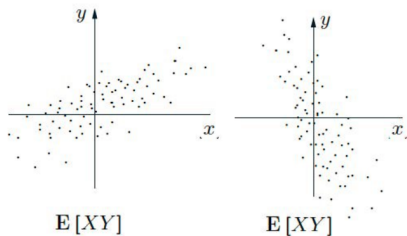
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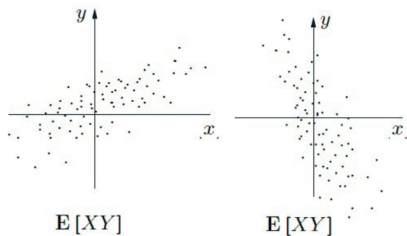


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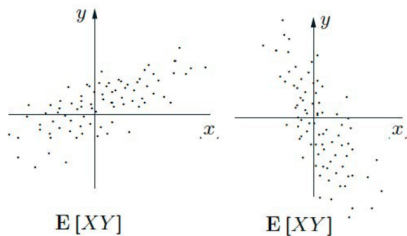


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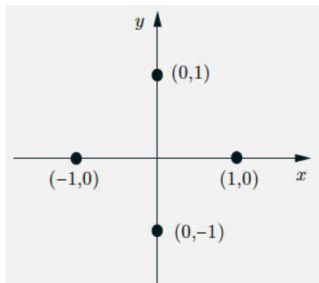
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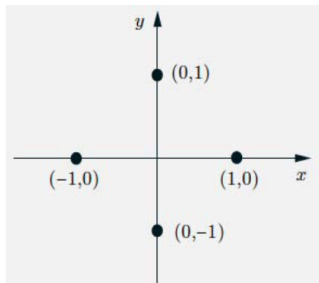
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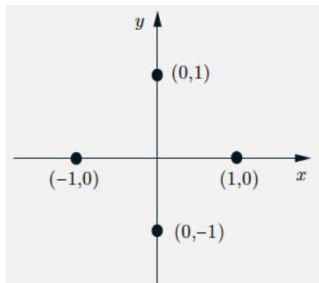




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- Theorem.**
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  - $|\rho| = 1 \Leftrightarrow X - \mu_X = c(Y - \mu_Y)$  for some constant  $c$  ( $c > 0$  when  $\rho = 1$  and  $c < 0$  when  $\rho = -1$ ). In other words, linear relation, meaning VERY related.

$$1. -1 \leq \rho \leq 1$$

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Now, choose  $a = \frac{\mathbb{E}(XY)}{\mathbb{E}(Y^2)}$ . Then,

$$\mathbb{E}(X^2) - 2\frac{\mathbb{E}(XY)}{\mathbb{E}(Y^2)}\mathbb{E}(XY) + \frac{(\mathbb{E}[XY])^2}{(\mathbb{E}[Y^2])^2}\mathbb{E}(Y^2) = \mathbb{E}(X^2) - \frac{(\mathbb{E}[XY])^2}{\mathbb{E}(Y^2)} \geq 0$$

$$2. |\rho| = 1 \Leftrightarrow X - \mu_X = c(Y - \mu_Y)$$

( $\Rightarrow$ ) Suppose that  $|\rho| = 1$ . In the proof of CSI,

$$\mathbb{E} \left[ \left( \tilde{X} - \frac{\mathbb{E}(\tilde{X}\tilde{Y})}{\mathbb{E}(\tilde{Y}^2)} \tilde{Y} \right)^2 \right] = \mathbb{E}(\tilde{X}^2) - \frac{(\mathbb{E}[\tilde{X}\tilde{Y}])^2}{\mathbb{E}(\tilde{Y}^2)} = \mathbb{E}(\tilde{X}^2)(1 - \rho^2) = 0$$

$$\tilde{X} - \frac{\mathbb{E}(\tilde{X}\tilde{Y})}{\mathbb{E}(\tilde{Y}^2)} \tilde{Y} = 0 \Leftrightarrow \tilde{X} = \frac{\mathbb{E}(\tilde{X}\tilde{Y})}{\mathbb{E}(\tilde{Y}^2)} \tilde{Y} = \rho \sqrt{\frac{\mathbb{E}(\tilde{X}^2)}{\mathbb{E}(\tilde{Y}^2)}} \tilde{Y}$$

( $\Leftarrow$ ) If  $\tilde{Y} = c\tilde{X}$ , then

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- If  $h(y) = y^2$ , then a new rv  $h(Y)$  is:

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$$\mathbb{E}[X|Y = y] = \begin{cases} 3, & \text{if } y = 0 \\ 8, & \text{if } y = 1 \\ 9, & \text{if } y = 2 \end{cases}$$

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- The rv  $g(Y)$  looks special, so let's give a fancy notation to it.
- What about?  $X_{\text{exp}}(Y)$ ,  $\mathbb{E}[X_Y]$ ,  $\mathbb{E}_X[Y]$ ?

A random variable  $g(Y) = \boxed{\phantom{000}}$ , called  $\boxed{\phantom{000}}$ , takes the value  $g(y) = \mathbb{E}[X|Y = y]$ , if  $Y$  happens to take the value  $y$ .

## Conditional Expectation

A random variable  $g(Y) = \mathbb{E}[X|Y]$ , called **conditional expectation of  $X$  given  $Y$** , takes the value  $g(y) = \mathbb{E}[X|Y = y]$ , if  $Y$  happens to take the value  $y$ .

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- A function of  $Y$
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- Thus, having a distribution, expectation, variance, all the things that a random variable has.
- Often confusing because of the notation.



## Expectation of Conditional Expectation

$$\mathbb{E}[\mathbb{E}[X|Y]] = \mathbb{E}[X], \quad \text{Law of iterated expectations}$$

Proof.

$$\begin{aligned}\mathbb{E}[\mathbb{E}[X|Y]] &= \sum_y \mathbb{E}[X|Y=y]p_Y(y) \\ &= \mathbb{E}[X]\end{aligned}$$



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- $X$  : February sales
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Revised forecast:  $\mathbb{E}[X|Y = y]$   
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- Law of iterated expectations  
 $\mathbb{E}[\text{revised forecast}] = \text{original one}$

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$$\sum_{s=1}^k \frac{n_s}{n} m_s = \sum_{s=1}^k \frac{n_s}{n} \frac{1}{n_s} \sum_{i \in A_s} x_i = \frac{1}{n} \sum_{i=1}^n x_i = m$$

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- (1) Derived distribution of  $Y = g(X)$  or  $Z = g(X, Y)$
- (2) Derived distribution of  $Z = X + Y$
- (3) Covariance: Degree of dependence between two rvs
- (4) Correlation coefficient
- (5) Conditional expectation and law of iterative expectations
- (6) **Conditional variance and law of total variance**
- (7) Random number of sum of random variables

$$\text{var}[X] = \mathbb{E}[(X - \mathbb{E}[X])^2]$$

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A random variable  $g(Y) = \boxed{\text{var}[X|Y]}$  and called  $\text{conditional variance of } X \text{ given } Y$ , takes the value  $g(y) = \text{var}[X|Y = y]$ , if  $Y$  happens to take the value  $y$ .

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	$\mathbb{E}[X Y]$	$\text{var}[X Y]$
Expectation	$\mathbb{E}[\mathbb{E}(X Y)]$	$\mathbb{E}[\text{var}(X Y)]$
Variance	$\text{var}[\mathbb{E}(X Y)]$	$\text{var}[\text{var}(X Y)]$

## Law of total variance (LTV)

$$\text{var}[X] =$$

Proof.

(1)

(2)

## Law of total variance (LTV)

$$\text{var}[X] = \mathbb{E}[\text{var}(X|Y)] + \text{var}[\mathbb{E}(X|Y)]$$

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Proof.

$$\text{var}(X|Y) = \mathbb{E}[X^2|Y] - (\mathbb{E}[X|Y])^2 \tag{1}$$

(2)

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$$(1) + (2) = \mathbb{E}[X^2] - (\mathbb{E}[X])^2 = \text{var}[X]$$

- Same setting as that in page 36
- $X$ : score of a randomly chosen student,  $Y$ : section of a student ( $\in \{1, \dots, k\}$ )



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- $\text{var}[\mathbb{E}(X|Y)]$ : variability of the average of the different sections
  - $\mathbb{E}(X|Y = s)$ : average score in section  $s$

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  - Weighted average of the section variances
  - **average score variability within individual sections**
- $\text{var}[\mathbb{E}(X|Y)]$ : variability of the average of the different sections
  - $\mathbb{E}(X|Y = s)$ : average score in section  $s$
  - **variability between sections**

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- **Fact.** If a rv  $X \sim \mathcal{U}[0, \theta]$ , then  $\text{var}(X) = \frac{\theta^2}{12}$

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- **Fact.** If a rv  $X \sim \mathcal{U}[0, \theta]$ , then  $\text{var}(X) = \frac{\theta^2}{12}$
- Since  $X \sim \mathcal{U}[0, Y]$ ,  $\text{var}(X|Y) = \frac{Y^2}{12} \rightarrow \mathbb{E}[\text{var}[X|Y]] = \frac{1}{12} \int_0^l \frac{1}{l} y^2 dy = \frac{l^2}{36}$



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- (1) Derived distribution of  $Y = g(X)$  or  $Z = g(X, Y)$
- (2) Derived distribution of  $Z = X + Y$
- (3) Covariance: Degree of dependence between two rvs
- (4) Correlation coefficient
- (5) Conditional expectation and law of iterative expectations
- (6) Conditional variance and law of total variance
- (7) Random number of sum of random variables

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Questions?

- 1) What are the key steps to get the derived distributions of  $Y = g(X)$  or  $Z = g(X, Y)$ ?
- 2) How can we compute the distribution of  $Z = X + Y$  when  $X$  and  $Y$  are independent?
- 3) What are covariance and correlation coefficient? Why do we need them?
- 4) Please explain the concepts of conditional expectation and conditional variance.