

Lecture 3: Random Variable, Part I

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EE210: Probability and Introductory Random Processes KAIST EE

April 27, 2021

Roadmap



- (1) Random variable: Idea and formal definition
- (2) Popular discrete random variables
- (3) Summarizing random variables: Expectation and Variance
- (4) (Functions of) multiple random variables
- (5) Conditioning for random variables
- (6) Independence for random variables

Roadmap



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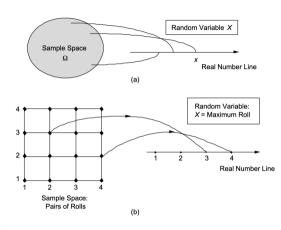
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Random Variable: Idea



- In reality, many outcomes are , e.g., stock price.
- Even if not, very convenient if we map numerical values to random outcomes, e.g., '0' for male and '1' for female.



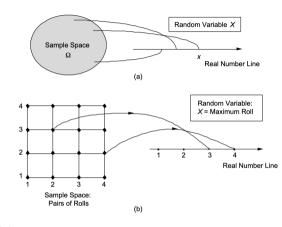
(b) Two rolls of tetrahedral dice

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¹Finite or countably infinite.



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L3(1)

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- Assume that values x are discrete such as 1, 2, 3, For notational convenience.

$$\rho_X(x) \triangleq \mathbb{P}(X=x) \triangleq \mathbb{P}\Big(\{\omega \in \Omega \mid X(\omega)=x\}\Big)$$

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$$p_X(x) \triangleq \mathbb{P}(X = x) \triangleq \mathbb{P}(\{\omega \in \Omega \mid X(\omega) = x\})$$

• For a discrete random variable X, we call $p_X(x)$ (PMF).

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Example



- Rolls a dice, $\Omega = \{1, 2, 3, 4, 5, 6\}$
- Define a random variable X = 1 for even numbers and X = 0 for odd numbers
- Event $A_1=\{\omega\in\Omega\mid X(\omega)=1\}=\{2,4,6\}\subset\Omega,$ but simply $A_1=\{X=1\}$
- Event $A_0 = \{\omega \in \Omega \mid X(\omega) = 0\} = \{1, 3, 5\} \subset \Omega$, but simply $A_0 = \{X = 0\}$
- Remember that the random variable X is a function from Ω to $\mathbb R$

L3(1)

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L3(2)



Only binary values

¹w.p.: with probability



Only binary values

$$X = \begin{cases} 0, & \text{w.p.} \quad 1 - p, \\ 1, & \text{w.p.} \quad p \end{cases}$$

In other words, $p_X(0) = 1 - p$ and $p_X(1) = p$ from our PMF notation.

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- Models a trial that results in binary results, e.g., success/failure, head/tail
- Very useful for an indicator rv of an event A. Define a rv $\mathbf{1}_A$ as:

$$\mathbf{1}_{\mathcal{A}} = egin{cases} 1, & ext{if A occurs,} \ 0, & ext{otherwise} \end{cases}$$

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• integers a, b, where $a \le b$



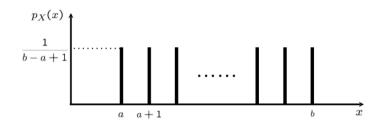
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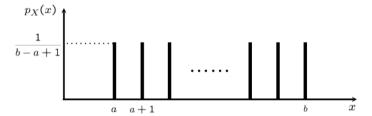
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Models complete ignorance (I don't know anything about X)



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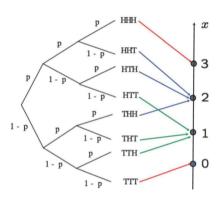
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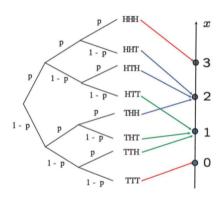
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- Models the number of successes in a given number of independent trials
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$$p_X(k) = \binom{n}{k} p^k (1-p)^{n-k}$$



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 Infinitely many independent Bernoulli trials, where each trial has success probability p



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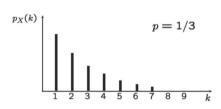
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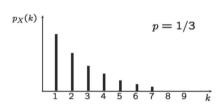




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 Models waiting times until something happens.



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Expectation/Mean



Average

Definition

$$\mathbb{E}[X] = \sum_{x} x p_X(x)$$

• $p_X(x)$: relative frequency of value x (trials with x/total trials)

Expectation/Mean



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- Example. Bernoulli rv with p

$$\mathbb{E}[X] = 1 \times p + 0 \times (1 - p) = p = p_X(1)$$

Properties of Expectation



Not very surprising. Easy to prove using the definition.

• If
$$X \ge 0$$
, $\mathbb{E}[X] \ge 0$.

• If
$$a \leq X \leq b$$
, $a \leq \mathbb{E}[X] \leq b$.

• For a constant
$$c$$
, $\mathbb{E}[c] = c$.



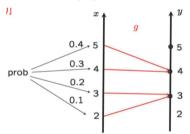
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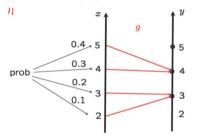
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- Compute $\mathbb{E}[Y]$ for the following:



L3(3)



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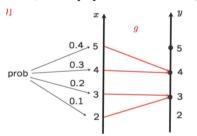
$$4 \times (0.4 + 0.3) + 3 \times (0.1 + 0.2)$$

= 2.8 + 0.9 = 3.7

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Linearity of Expectation

$$\mathbb{E}[aX + b] = a\mathbb{E}[X] + b$$



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Variance, Standard Deviation

$$var[X] = \mathbb{E}[(X - \mu)^2]$$

$$\sigma_X = \sqrt{\operatorname{var}[X]}$$

L3(3)



•
$$\operatorname{var}[X] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$

•
$$Y = X + b$$
, $var[Y] = var[X]$

•
$$Y = aX$$
, $var[Y] = a^2 var[X]$

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Example: Variance of a Bernoulli rv(p)



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Example: Variance of a Bernoulli rv (p)

$$\mu = \mathbb{E}[X] = 1 \times p + 0 \times (1 - p) = p$$
 $\mathbb{E}[X^2] = 1 \times p + 0 \times (1 - p) = p$
 $\text{var}[X] = \mathbb{E}[X^2] - \mu^2 = p - p^2$
 $= p(1 - p)$

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For two random variables X, Y, consider two events $\{X = x\}$ and $\{Y = y\}$, and

$$\mathbb{P}\Big(\{X=x\}\cap\{Y=y\}\Big)$$



• Joint PMF. For two random variables X, Y, consider two events $\{X = x\}$ and $\{Y = y\}$, and

$$p_{X,Y}(x,y) \triangleq \mathbb{P}(\{X=x\} \cap \{Y=y\})$$

L3(4)



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$$\sum_{x}\sum_{y}p_{X,Y}(x,y)=1$$

L3(4)



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 $\{Y=y\}$, and

$$p_X(x) = \sum_y p_{X,Y}(x,y),$$

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Joint PMF. For two random variables

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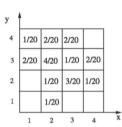
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- Marginal PMF.

$$p_X(x) = \sum_{y} p_{X,Y}(x,y),$$

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Example.

VIDEO PAUSE



$$p_{X,Y}(1,3) =$$

$$p_X(4) =$$

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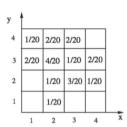
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Example.

VIDEO PAUSE



$$p_{X,Y}(1,3) = 2/20$$

$$p_X(4) = 2/20 + 1/20 = 3/20$$

$$\mathbb{P}(X = Y) = 1/20 + 4/20 + 3/20 = 8/20$$

Functions of Multiple RVs



• Consider a rv Z = g(X, Y). (Ex) X + Y, $X^2 + Y^2$. Then, PMF of Z is:

Similarly,

$$\mathbb{E}[Z] = \mathbb{E}[g(X,Y)] =$$

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$$p_Z(z) = \mathbb{P}(g(X, Y) = z) = \sum_{(x,y):g(x,y)=z} p_{X,Y}(x,y)$$

Similarly,

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- $\mathbb{E}[2X+3Y-Z]=2\mathbb{E}[X]+3\mathbb{E}[Y]-\mathbb{E}[Z]$



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- $Y = X_1 + ... X_n$, where X_i is a Bernoulli rv.
- $\mathbb{E}[Y] = n\mathbb{E}[X_i] = n\mathbb{P}(X_i = 1) = np$



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Message. When some rv X is written as a linear combination of other rvs, X becomes easy to handle.

Roadmap



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- (1) Random variable: Idea and formal definition
- (2) Popular discrete random variables
- (3) Summarizing random variables: Expectation and Variance
- (4) (Functions of) multiple random variables
- (5) Conditioning for random variables
- (6) Independence for random variables

L3(5) April 27, 2021



Remember two probability laws: $\mathbb{P}(\cdot)$ and $\mathbb{P}(\cdot|A)$ for an event A.

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•
$$p_X(x) \triangleq \mathbb{P}(X=x)$$

•
$$p_{X|A}(x) \triangleq \mathbb{P}(X = x|A)$$



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- $p_X(x) \triangleq \mathbb{P}(X=x)$
- $\mathbb{E}[X] = \sum_{x} x p_X(x)$

- $p_{X|A}(x) \triangleq \mathbb{P}(X = x|A)$ $\mathbb{E}[X|A] \triangleq \sum_{x} x p_{X|A}(x)$



•
$$p_X(x) \triangleq \mathbb{P}(X = x)$$

•
$$\mathbb{E}[X] = \sum_{x} x p_X(x)$$

•
$$\mathbb{E}[g(X)] = \sum_{x} g(x) p_X(x)$$

$$p_{X|A}(x) \triangleq \mathbb{P}(X=x|A)$$

$$\mathbb{E}[X|A] \triangleq \sum_{x} x p_{X|A}(x)$$

•
$$p_{X|A}(x) \triangleq \mathbb{P}(X = x|A)$$

• $\mathbb{E}[X|A] \triangleq \sum_{x} x p_{X|A}(x)$
• $\mathbb{E}[g(X)|A] \triangleq \sum_{x} g(x) p_{X|A}(x)$



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•
$$\operatorname{var}[X] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$

$$p_{X|A}(x) \triangleq \mathbb{P}(X=x|A)$$

•
$$p_{X|A}(x) \triangleq \mathbb{P}(X = x|A)$$

• $\mathbb{E}[X|A] \triangleq \sum_{x} x p_{X|A}(x)$

•
$$\mathbb{E}[g(X)|A] \triangleq \sum_{x} g(x) p_{X|A}(x)$$

•
$$\operatorname{var}[X|A] \triangleq \mathbb{E}[X^2|A] - (\mathbb{E}[X|A])^2$$



Remember two probability laws: $\mathbb{P}(\cdot)$ and $\mathbb{P}(\cdot|A)$ for an event A.

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$$p_X(x) \triangleq \mathbb{P}(X = x)$$

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$$\mathbb{E}[X] = \sum_{x} x p_X(x)$$

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•
$$var[X] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$

$$p_{X|A}(x) \triangleq \mathbb{P}(X=x|A)$$

•
$$p_{X|A}(x) \triangleq \mathbb{P}(X = x|A)$$

• $\mathbb{E}[X|A] \triangleq \sum_{x} x p_{X|A}(x)$

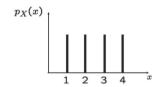
•
$$\mathbb{E}[g(X)|A] \triangleq \sum_{x} g(x) p_{X|A}(x)$$

•
$$\operatorname{var}[X|A] \triangleq \mathbb{E}[X^2|A] - (\mathbb{E}[X|A])^2$$

• (Note) $p_{X|A}(x)$, $\mathbb{E}[X|A]$, $\mathbb{E}[g(X)|A]$, and var[X|A] are all just notations!

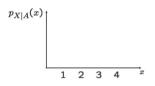


$$A = \{X \ge 2\}$$



$$\mathbb{E}[X] =$$

$$var[X] =$$

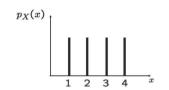


$$\mathbb{E}[X|A] =$$

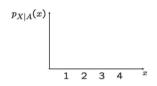
$$var[X|A] =$$



$$A = \{X \ge 2\}$$



$$\mathbb{E}[X] = \frac{1}{4}(1+2+3+4) = 2.5$$
 $\mathsf{var}[X] =$



$$\mathbb{E}[X|A] =$$

$$var[X|A] =$$



$$A = \{X \ge 2\}$$

$$p_X(x)$$

$$\mathbb{E}[X] = \frac{1}{4}(1+2+3+4) = 2.5$$

$$var[X] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$
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$$\mathbb{E}[X|A] = \frac{1}{3}(2+3+4) = 3$$

$$\text{var}[X|A] =$$

$$var[X|A] =$$



$$A = \{X \ge 2\}$$

$$p_X(x)$$

$$\mathbb{E}[X] = \frac{1}{4}(1+2+3+4) = 2.5$$

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$$\mathbb{E}[X|A] = \frac{1}{3}(2+3+4) = 3$$

$$\text{var}[X|A] = \mathbb{E}[X^2|A] - (\mathbb{E}[X|A])^2$$

$$\mathsf{var}[X|A] = \mathbb{E}[X^2|A] - (\mathbb{E}[X|A])^2$$



$$A = \{X \ge 2\}$$

$$\begin{array}{c} p_X(x) \\ \hline \\ 1 & 2 & 3 & 4 & x \end{array}$$

$$\mathbb{E}[X] = \frac{1}{4}(1+2+3+4) = 2.5$$

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$$\text{var}[X|A] = \mathbb{E}[X^2|A] - (\mathbb{E}[X|A])^2$$

$$= \frac{1}{3}(2^2+3^2+4^2) - 3^2 = 2/3$$



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•
$$p_{X|A}(x) \triangleq \mathbb{P}(X=x|A)$$

•
$$p_{X|Y}(x|y) \triangleq \mathbb{P}(X=x|Y=y)$$



- $p_{X|A}(x) \triangleq \mathbb{P}(X = x|A)$ $\mathbb{E}[X|A] \triangleq \sum_{x} x p_{X|A}(x)$

- $p_{X|Y}(x|y) \triangleq \mathbb{P}(X = x|Y = y)$ $\mathbb{E}[X|Y = y] \triangleq \sum_{x} x p_{X|Y}(x|y)$



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$$p_{X|A}(x) \triangleq \mathbb{P}(X = x|A)$$

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$$\mathbb{E}[X|A] \triangleq \sum_{x} x p_{X|A}(x)$$

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•
$$\operatorname{var}[X|Y = y] \triangleq \mathbb{E}[X^2|Y = y] - (\mathbb{E}[X|Y = y])^2$$



Conditional PMF

Multiplication rule

$$p_{X,Y}(x,y) =$$

•
$$p_{X,Y,Z}(x,y,z) =$$



Conditional PMF

$$p_{X|Y}(x|y) \triangleq \mathbb{P}(X=x|Y=y) = \frac{p_{X,Y}(x,y)}{p_{Y}(y)}$$

for y such that $p_Y(y) > 0$.

Multiplication rule

$$p_{X,Y}(x,y) =$$

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- $\sum_{x} p_{X|Y}(x|y) = 1$
- Multiplication rule

$$p_{X,Y}(x,y) =$$

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$$p_{X,Y}(x,y) = p_Y(y)p_{X|Y}(x|y)$$

= $p_X(x)p_{Y|X}(y|x)$

• $p_{X,Y,Z}(x,y,z) =$



Conditional PMF

$$p_{X|Y}(x|y) \triangleq \mathbb{P}(X=x|Y=y) = \frac{p_{X,Y}(x,y)}{p_{Y}(y)}$$

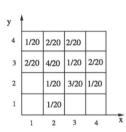
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VIDEO PAUSE



$$p_{X|Y}(2|2) =$$

$$p_{X|Y}(3|2) =$$

$$\mathbb{E}[X|Y=3]=$$



Conditional PMF

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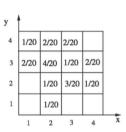
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$$p_{X,Y}(x,y) = p_Y(y)p_{X|Y}(x|y)$$
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• $p_{X,Y,Z}(x,y,z) = p_X(x)p_{Y|X}(y|x)p_{Z|X,Y}(z|x,y)$

VIDEO PAUSE



$$p_{X|Y}(2|2) = \frac{1}{1+3+1}$$

$$p_{X|Y}(3|2) = \frac{3}{1+3+1}$$

$$\mathbb{E}[X|Y=3] = 1(2/9) + 2(4/9) + 3(1/9) + 4(2/9)$$

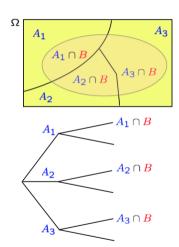
Remind: Total Probability Theorem (from Lecture 2)



- Partition of Ω into A_1, A_2, A_3
- Known: $\mathbb{P}(A_i)$ and $\mathbb{P}(B|A_i)$
- What is $\mathbb{P}(B)$?

Total Probability Theorem

$$\mathbb{P}(B) = \sum_{i} \mathbb{P}(A_i) \mathbb{P}(B|A_i)$$



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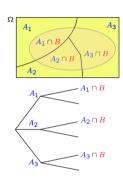
Total Probability Theorem: $B = \{X = x\}$



• Partition of Ω into A_1, A_2, A_3

Total Probability Theorem

$$p_X(x) = \sum_i \mathbb{P}(A_i)\mathbb{P}(X = x|A_i) = \sum_i \mathbb{P}(A_i)p_{X|A_i}(x)$$



Total Expectation Theorem for $\{A_i\}$



• Partition of Ω into A_1, A_2, A_3

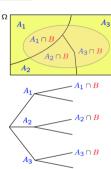
Total Probability Theorem

$$p_X(x) = \sum_i \mathbb{P}(A_i)\mathbb{P}(X = x|A_i) = \sum_i \mathbb{P}(A_i)p_{X|A_i}(x)$$

Total Expectation Theorem

$$\mathbb{E}[X] = \sum_{i} \mathbb{P}(A_i) \mathbb{E}[X|A_i]$$

• Weighted average of expectations from A_i 's perspective



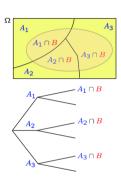
Total Expectation Theorem for $\{Y = y\}$



• Partition of Ω into A_1, A_2, A_3

Total Expectation Theorem

$$\mathbb{E}[X] = \sum_{i} \mathbb{P}(A_{i}) \mathbb{E}[X|A_{i}]$$



Total Expectation Theorem for $\{Y = y\}$



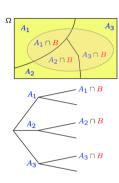
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Total Expectation Theorem

$$\mathbb{E}[X] = \sum_{i} \mathbb{P}(A_{i}) \mathbb{E}[X|A_{i}]$$

Total Expectation Theorem

$$\mathbb{E}[X] = \sum_{y} \mathbb{P}(Y = y) \mathbb{E}[X | Y = y] = \sum_{y} p_{Y}(y) \mathbb{E}[X | Y = y]$$

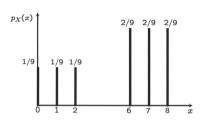




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- Question. What is $\mathbb{E}(X)$?
- $\left(1
 ight)$ Just using the definition of expectation,

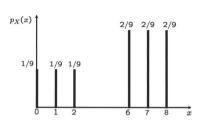
$$\mathbb{E}[X] =$$





- Question. What is $\mathbb{E}(X)$?
- (1) Just using the definition of expectation,

$$\mathbb{E}[X] = \frac{1}{9}(0+1+2) + \frac{2}{9}(6+7+8)$$
$$= \frac{3+12+14+16}{9} = 5$$



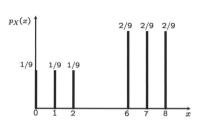


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(2) Let's use TET, for which consider

$$A_1=\{X\in\{0,1,2\}\},\ A_2=\{X\in\{6,7,8\}\}$$





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- (1) Just using the definition of expectation,

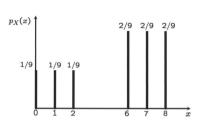
$$\mathbb{E}[X] = \frac{1}{9}(0+1+2) + \frac{2}{9}(6+7+8)$$
$$= \frac{3+12+14+16}{9} = 5$$

(2) Let's use TET, for which consider

$$A_1 = \{X \in \{0, 1, 2\}\}, \ A_2 = \{X \in \{6, 7, 8\}\}$$

$$\mathbb{E}[X] = \sum_{i=1, 2} \mathbb{P}(A_i) \mathbb{E}[X|A_i]$$

$$= 1/3 \cdot 1 + 2/3 \cdot 7 = 5$$





• Write softwares over and over, and each time w.p. p of working correctly (independent from previous programs).

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- Write softwares over and over, and each time w.p. *p* of working correctly (independent from previous programs).
- X: number of trials until the program works correctly.

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- X is a geometric rv

Example 2: Mean of Geometric rv



- Write softwares over and over, and each time w.p. *p* of working correctly (independent from previous programs).
- X: number of trials until the program works correctly.
- (Q) $\mathbb{E}(X)$?
- X is a geometric rv
- Direct computation is boring.

$$\mathbb{E}[X] = \sum_{k=1}^{\infty} k(1-p)^{k-1}p = p + 2(1-p)p + 3(1-p)^2p + \cdots$$

Example 2: Mean of Geometric rv



- Write softwares over and over, and each time w.p. *p* of working correctly (independent from previous programs).
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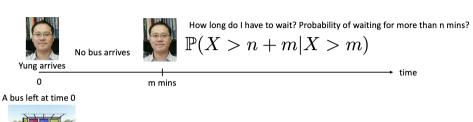
Total expectation theorem and a notion of memorylessness helps a lot.

L3(5)

Memoryless Property: Motivating Example



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time 0



How long do I have to wait? Probability of waiting for more than n mins?

$$\mathbb{P}(X > n)$$

Lin arrives

Background: Memoryless Property



• Some random variable often does not have memory.

Background: Memoryless Property



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- Some random variable often does not have memory.
- Definition. A random variable X is called memoryless if, for any $n, m \ge 0$,

$$\mathbb{P}(X > n + m | X > m) = \mathbb{P}(X > n)$$

Background: Memoryless Property



- Some random variable often does not have memory.
- Definition. A random variable X is called memoryless if, for any $n, m \ge 0$,

$$\mathbb{P}(X > n + m | X > m) = \mathbb{P}(X > n)$$

• Meaning. Conditioned on X > m, X - m's distribution is the same as the original X.

$$\mathbb{P}(X-m>n|X>m)=\mathbb{P}(X>n)$$

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• Theorem. Any **geometric** random variable is memoryless.



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- Theorem. Any geometric random variable is memoryless.
- Remind. Geometric rv X with parameter p

$$\mathbb{P}(X=k)=(1-p)^{k-1}p, \quad \mathbb{P}(X>k)=\sum_{i=k+1}^{\infty}(1-p)^{i-1}p=(1-p)^k$$



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- Theorem. Any geometric random variable is memoryless.
- Remind. Geometric rv X with parameter p

$$\mathbb{P}(X=k)=(1-p)^{k-1}p, \quad \mathbb{P}(X>k)=\sum_{i=k+1}^{\infty}(1-p)^{i-1}p=(1-p)^k$$

• Proof.

$$\mathbb{P}(X > n + m | X > m) = \frac{\mathbb{P}(X > n + m \text{ and } X > m)}{\mathbb{P}(X > m)} = \frac{\mathbb{P}(X > n + m)}{\mathbb{P}(X > m)}$$
$$= \frac{(1 - p)^{n + m}}{(1 - p)^m} = (1 - p)^n = \mathbb{P}(X > n)$$



- Theorem. Any geometric random variable is memoryless.
- Remind. Geometric rv X with parameter p

$$\mathbb{P}(X = k) = (1 - p)^{k-1}p, \quad \mathbb{P}(X > k) = \sum_{i=k+1}^{\infty} (1 - p)^{i-1}p = (1 - p)^k$$

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$$\mathbb{P}(X > n + m | X > m) = \frac{\mathbb{P}(X > n + m \text{ and } X > m)}{\mathbb{P}(X > m)} = \frac{\mathbb{P}(X > n + m)}{\mathbb{P}(X > m)}$$
$$= \frac{(1 - p)^{n+m}}{(1 - p)^m} = (1 - p)^n = \mathbb{P}(X > n)$$

• Meaning. Conditioned on X > m, X - m is geometric with the same parameter.

L3(5)



(from memorylessness)

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• $A_1=\{X=1\}$ (first try is success), $A_2=\{X>1\}$ (first try is failure). $\mathbb{E}[X]=1+\mathbb{E}[X-1]$ = (from TET)



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• $A_1 = \{X = 1\}$ (first try is success), $A_2 = \{X > 1\}$ (first try is failure).

$$\begin{split} \mathbb{E}[X] &= 1 + \mathbb{E}[X-1] \\ &= 1 + \mathbb{P}(A_1)\mathbb{E}[X-1|X=1] + \mathbb{P}(A_2)\mathbb{E}[X-1|X>1] \\ &= \end{split} \qquad \qquad \text{(from TET)} \\ \end{split}$$



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• $A_1 = \{X = 1\}$ (first try is success), $A_2 = \{X > 1\}$ (first try is failure).

$$\begin{split} \mathbb{E}[X] &= 1 + \mathbb{E}[X-1] \\ &= 1 + \mathbb{P}(A_1)\mathbb{E}[X-1|X=1] + \mathbb{P}(A_2)\mathbb{E}[X-1|X>1] \\ &= 1 + (1-\rho)\mathbb{E}[X] \end{split} \tag{from TET)}$$



(from memorylessness)

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• $A_1=\{X=1\}$ (first try is success), $A_2=\{X>1\}$ (first try is failure). $\mathbb{E}[X]=1+\mathbb{E}[X-1]$ $=1+\mathbb{P}(A_1)\mathbb{E}[X-1|X=1]+\mathbb{P}(A_2)\mathbb{E}[X-1|X>1]$ (from TET)

• Thus,
$$\mathbb{E}[X] = \frac{1}{p}$$

 $= 1 + (1 - p)\mathbb{E}[X]$

Roadmap



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- (1) Random variable: Idea and formal definition
- (2) Popular discrete random variables
- (3) Summarizing random variables: Expectation and Variance
- (4) (Functions of) multiple random variables
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- (6) Independence for random variables



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Two events

$$\mathbb{P}(A \cap B) = \mathbb{P}(A) \cdot \mathbb{P}(B)$$

$$\mathbb{P}(A \cap B | C) = \mathbb{P}(A | C) \cdot \mathbb{P}(B | C)$$



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Two events

$$\mathbb{P}(A \cap B) = \mathbb{P}(A) \cdot \mathbb{P}(B)$$

$$\mathbb{P}(A \cap B | C) = \mathbb{P}(A | C) \cdot \mathbb{P}(B | C)$$

A rv and an event

$$\mathbb{P}(\{X = x\} \cap B) = \mathbb{P}(X = x) \cdot \mathbb{P}(B), \text{ for all } x$$

$$\mathbb{P}(\{X = x\} \cap B | \mathbf{C}) = \mathbb{P}(X = x | \mathbf{C}) \cdot \mathbb{P}(B | \mathbf{C}), \text{ for all } x$$



Two events

$$\mathbb{P}(A \cap B) = \mathbb{P}(A) \cdot \mathbb{P}(B)$$

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A rv and an event

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Two rvs

$$\mathbb{P}(\{X=x\} \cap \{Y=y\}) = \mathbb{P}(X=x) \cdot \mathbb{P}(Y=y), \text{ for all } x, y$$

$$\mathbb{P}(\{X=x\} \cap \{Y=y\} | Z=z) = \mathbb{P}(X=x | Z=z) \cdot \mathbb{P}(Y=y | Z=z), \text{ for all } x, y$$



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Two rvs

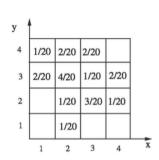
$$\mathbb{P}(\{X = x\} \cap \{Y = y\}) = \mathbb{P}(X = x) \cdot \mathbb{P}(Y = y), \text{ for all } x, y$$
$$p_{X,Y}(x, y) = p_X(x) \cdot p_Y(y)$$

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• *X* ⊥⊥ *Y*?

• $X \perp \!\!\! \perp Y | \{X \le 2 \text{ and } Y \ge 3\}$?

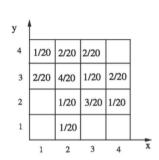




•
$$X \perp \!\!\! \perp Y?$$

 $p_{X,Y}(1,1) = 0$
 $p_X(1) = 3/20$
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• $X \perp \!\!\! \perp Y | \{X \le 2 \text{ and } Y \ge 3\}$?



L3(6)



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• $X \perp \!\!\!\perp Y | \{X \leq 2 \text{ and } Y \geq 3\}$?

VIDEO PAUSE

Y=4		
Y=3		
	X = 1	X=2

у	†				
4	1/20	2/20	2/20		
3	2/20	4/20	1/20	2/20	
2		1/20	3/20	1/20	
1		1/20			
	1	2	3	4	X



•
$$X \perp \!\!\! \perp Y$$
?
 $p_{X,Y}(1,1) = 0$
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• $X \perp \!\!\! \perp Y | \{X \le 2 \text{ and } Y \ge 3\}$?

Y = 4 (1/3)	1/9	2/9	
Y = 3 (2/3)	2/9	4/9	
	X = 1 (1/3)	X = 2 (2/3)	

у	Ť				
4	1/20	2/20	2/20		
3	2/20	4/20	1/20	2/20	
2		1/20	3/20	1/20	
1		1/20			
	1	2	3	4	X

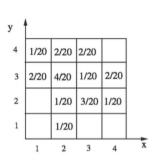


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Y = 4 (1/3)	1/9	2/9	
Y = 3 (2/3)	2/9	4/9	
	X = 1 (1/3)	X = 2 (2/3)	

- Yes.





Always true.

$$\mathbb{E}[X+Y] = \mathbb{E}[X] + \mathbb{E}[Y]$$

L3(6)



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eq g(\mathbb{E}[X],\mathbb{E}[Y])$



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L3(6)



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• Proof.

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$var[X + Y] \neq var[X] + var[Y]$



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• Why not generally true?

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• Why not generally true?

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$$= \mathbb{E}[X^{2} + Y^{2} + 2XY] - ((\mathbb{E}[X])^{2} + (\mathbb{E}[Y])^{2} + 2\mathbb{E}[X]\mathbb{E}[Y])$$

$$= var[X] + var[Y] + 2(\mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y])$$

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is a sufficient condition for $\mathbb{E}[XY] = \mathbb{E}[X]\mathbb{E}[Y]$

$[\mathsf{var}[X+Y] eq \mathsf{var}[X] + \mathsf{var}[Y]^t$



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- $\circ \mid {m{\mathsf{X}}} \perp \!\!\! \perp {m{\mathsf{Y}}} \mid$ is a sufficient condition for $\mathbb{E}[XY] = \mathbb{E}[X]\mathbb{E}[Y]$
- Also, a necessary condition? we will see later, when we study covariance.



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- X: number of people with their own hat



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• $\{X_i\}, i = 1, 2, ..., n$: identically distributed (from symmetry)



•
$$\mathbb{E}[X] = n\mathbb{E}[X_1] = n\mathbb{P}(X_1 = 1) = n \times \frac{1}{n} = 1.$$



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•
$$var(X) = 2 - 1 = 1$$



Questions?

Review Questions



- 1) What is Random Variable? Why is it useful?
- 2) What is PMF (Probability Mass Function)?
- 3) Explain Bernoulli, Binomial, Poisson, Geometric rvs, when they are used and what their PMFs are.
- 4) What are joint and marginal PMFs?
- 5) Describe and explain the total probability/expectation theorem for random variables?
- 6) When is it useful to use total probability/expectation theorem?
- 7) What is conditional independence?