

Lecture 8: Random Processes, Part II

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EE210: Probability and Introductory Random Processes KAIST EE

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Roadmap



- Basics on Random Process
- Bernoulli Process
- Poisson Process
- Use of Bernoulli and Poisson Processes
- Markov Chain
 - Definition, Transition Probability Matrix, State Transition Diagram
 - Classification of States
 - Steady-state Behaviors and Stationary Distribution
 - Transient Behaviors

Recap and Markov Chain



- Assume discrete times $n = 1, 2, \dots$
 - Random process: A sequence of X_1, X_2, X_3, \cdots
 - "Simplest" random process
 - Process without memory

$$\mathbb{P}(X_n = i_n \mid X_{n-1} = i_{n-1}, X_{n-2} = i_{n-2}, X_{n-3} = i_{n-3}, \dots, X_1 = i_1) = \mathbb{P}(X_n = i_n)$$

- Bernoulli process
- A random process that is a little more complex than the above?
 - Process that depends only on "yesterday", not the entire history

$$\mathbb{P}(X_n = i_n \mid X_{n-1} = i_{n-1}, X_{n-2} = i_{n-2}, X_{n-3} = i_{n-3}, \dots, X_1 = i_1) = \mathbb{P}(X_n = i_n \mid X_{n-1} = i_{n-1})$$

- Markov chain
- One of the most popular random processes in engineering

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Example: Machine Failure, Repair, and Replacement



- A machine: working or broken down on a given day.
 - If working, break down in the next day w.p. b, and continue working w.p. 1-b.
 - If broken down, it will be repaired and be working in the next day w.p. r, and continue to be broken down w.p. 1-r.
- $X_n \in \{1,2\}$: status of the machine, 1: working and 2: broken down
- $(X_n)_{n=1}^{\infty}$: A random process satisfying: for any $n \ge 1$,

$$\mathbb{P}(X_{n+1} = 1 | X_n = 1) = 1 - b, \quad \mathbb{P}(X_{n+1} = 2 | X_n = 1) = b$$

$$\mathbb{P}(X_{n+1} = 1 | X_n = 2) = r, \quad \mathbb{P}(X_{n+1} = 2 | X_n = 2) = 1 - r$$

• What will happen at (n+1)-th day depends only on what happens at n-th day?

Markov Chain: Definition



• Definition. Let X_1, \ldots, X_n, \ldots be a sequence of random variables taking values in some finite space $\mathcal{S}=\{1,2,\ldots,m\}$, such that for all $i,j\in\mathcal{S},\;n\geq0,$ the following Markov property is satisfied:

$$\mathbb{P}(X_{n+1}=j|X_n=i)=\mathbb{P}(X_{n+1}=j|X_n=i,X_{n-1}=i_{n-1},\ldots,X_0=i_0),$$

- For any fixed n, the future of the process after n is independent of $\{X_1, \ldots, X_n\}$, given X_n (i.e., depends only on X_n)
- The value that X_n can take is called 'state'. Thus, the space S is called state space.
- Time homogeneity. The probability $\mathbb{P}(X_{n+1} = j | X_n = i)$ does NOT depends on n. Thus, for any $n \ge 0$, we introduce a simple notation p_{ij} $p_{ii} \triangleq \mathbb{P}(X_{n+1} = j | X_n = i)$

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Transition Prob. Matrix and State Transition Diagram



- Transition Probability Matrix. Consider a $m \times m$ matrix $\mathbf{P} = [p_{ii}]$, where $\rho_{ij} \triangleq \mathbb{P}(X_{n+1} = j | X_n = i)$
- Machine example.

$$p_{11} = \mathbb{P}(X_{n+1} = 1 | X_n = 1) = 1 - b,$$
 $p_{12} = \mathbb{P}(X_{n+1} = 2 | X_n = 1) = b$
 $p_{21} = \mathbb{P}(X_{n+1} = 1 | X_n = 2) = r,$ $p_{22} = \mathbb{P}(X_{n+1} = 2 | X_n = 2) = 1 - r$

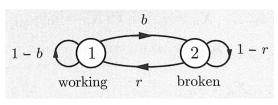
$$p_{12} = \mathbb{P}(X_{n+1} = 2|X_n = 1) = b$$

 $p_{22} = \mathbb{P}(X_{n+1} = 2|X_n = 2) = 1 - r$

- Transition probability matrix

$$\begin{bmatrix} 1-b & b \\ r & 1-r \end{bmatrix}$$

State transition diagram

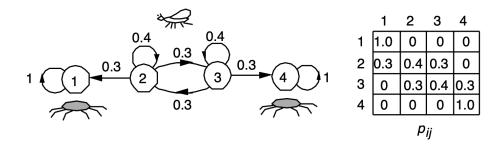


- Both are the complete description of Markov chain.
- $\sum_{i=1}^{m} p_{ij} = 1$ (for each row i, the column sum = 1)

Spider-Fly example



- A fly moves along a line in unit increments.
- At each time, it moves one unit (i) left w.p. 0.3, (ii) right w.p. 0.3 and (iii) stays in place w.p. 0.4, independent of the past history of movements.
- Two spiders lurk at positions 1 and 4: if the fly lands there, it is captured by the spider, and the process terminates. Assume that the fly starts in a position between 1 and 4.
- X_n : position of the fly. Please draw the state transition diagram and find the transition probability matrix.



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Probability of a Sample Path



(Q) What is the probability of a sample path in a Markov chain?

$$\mathbb{P}\left(X_{0} = i_{0}, X_{1} = i_{1}, X_{2} = i_{2}, \dots, X_{n} = i_{n}\right) \\
= \mathbb{P}\left(X_{n} = i_{n} | X_{0} = i_{0}, X_{1} = i_{1}, \dots, X_{n-1} = i_{n-1}\right) \cdot \mathbb{P}\left(X_{0} = i_{0}, X_{1} = i_{1}, \dots, X_{n-1} = i_{n-1}\right) \\
= \rho_{i_{n-1}i_{n}} \cdot \mathbb{P}\left(X_{0} = i_{0}, X_{1} = i_{1}, \dots, X_{n-1} = i_{n-1}\right) = \mathbb{P}(X_{0} = i_{0}) \cdot \rho_{i_{0}i_{1}} \cdot \rho_{i_{1}i_{2}} \cdots \rho_{i_{n-1}i_{n}}$$

Spider-Fly example

$$\mathbb{P}(X_0=2,X_1=2,X_2=2,X_3=3,X_4=4) = \mathbb{P}(X_0=2)p_{22}p_{22}p_{23}p_{34} = \mathbb{P}(X_0=2)(0.4)^2(0.3)^2$$

Probability after n Steps

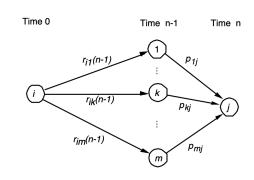


- (Q) What is the probability that my state is i, starting from i after n steps?
- *n*-step transition probability

$$r_{ij}(n) \triangleq \mathbb{P}(X_n = j \mid X_0 = i)$$

• Recursive formula, starting with $r_{ij}(1) = p_{ij}$

$$r_{ij}(n) = \mathbb{P}(X_n = j \mid X_0 = i) = \sum_{k=1}^{m} \mathbb{P}(X_{n-1} = k | X_0 = i) \mathbb{P}(X_n = j | X_{n-1} = k, X_0 = i)$$
$$= \sum_{k=1}^{m} r_{ik}(n-1) p_{kj}$$



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Examples: Different States and Classes

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0.3

0.2

0.5

0.1 / 0.5

0.3

- Classes
 - 3 can only be reached from 3
 - 1 and 2 can reach each other but no other state
 - 4, 5, and 6 all reach each other.
 - Divide into three classes: {3}, {1,2}, {4,5,6}
 - Insight 1. Multiple classes may exist.



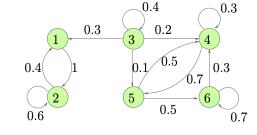
- 1: If I start from 1, visit 1 infinite times.
- 3: If I start from 3, visit 3 only finite times (move to other classes and don't return).
- Insight 2. Some states are visited infinite times, but some states are not.
- State 2 will share the above properties with 1 (similarly, 4,5, and 6)
- Insigt 3. States in the same class share some properties.

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Classification of States (1)

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- Definition. State j is accessible from state i, if for some n $r_{ij}(n) > 0$.
 - 6 is accessible from 3, but not the other way around.
- Definition. If i is accessible from j and j is accessible from i, we say that i communicates with j.
 - $1 \leftrightarrow 2$, but 3 does not communicate with 5.

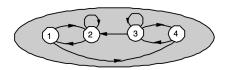


- Definition. Let $A(i) = \{$ states accessible from $i \}$. State i is recurrent, if $\forall j \in A(i)$, i is also accessible from j. In other words, "I communicate with all of my neighbors!"
 - A state that is not recurrent is transient.
 - 2 is recurrent? Yes. 3 is recurrent? No.
 - If we start from a recurrent state *i*, then there is always some probability of returning to *i*. It means that, given enough time, it is certain that it returns to *i*.

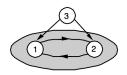
Classification of States (2)

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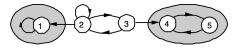
- A set of recurrent states which communicate with each other form a class.
- Markov chain decomposition
 - A MC can be decomposed into one or more recurrent classes, plus possibly some transient states.
 - A recurrent state is accessible from all states in its class, but it not accessible from recurrent states in other classes.
 - A transient state is not accessible from any recurrent state.
 - At least one, possibly more, recurrent states are accessible from a given transient state.
- The MC with only a single recurrent class is said to be irreducible (더이상 분해할 수 없는).



Single class of recurrent states



Single class of recurrent states (1 and 2) and one transient state (3)



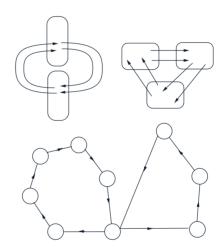
Two classes of recurrent states (class of state1 and class of states 4 and 5) and two transient states (2 and 3)

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Periodicity

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- The states in a recurrent class are periodic if they can be grouped into d>1 groups so that all transitions from one group lead to the next group.
- A recurrent class that is not periodic is said to be aperiodic.





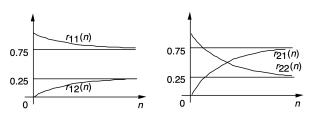
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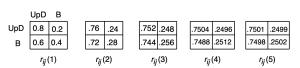
n-step transition prob.: $r_{ij}(n)$ for large n

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Convergence irrespective of the starting state

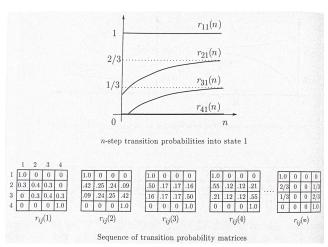


n-step transition probabilities as a function of the number *n* of transitions



Sequence of *n*-step transition probability matrices

Convergence depending on the starting state

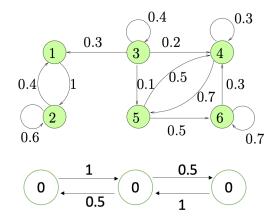


(Q) Under what conditions, convergence occurs? If so, how does it depend on the starting state?

Steady-state behavior



- $r_{ij}(n) \xrightarrow{n \to \infty} \pi_j$, for some $\pi_j \le 1$?
- Convergence occurs, independent of the starting state, if:
 - C1. Only a single recurrent class
 - C2. such recurrent class is aperiodic
- **C1.** For the case of multiple recurrent classes, one stays at the class including the starting state.
- **C2.** Divergent behavior for periodic recurrent classes.



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Balance Equation



• If $r_{ij}(n) \xrightarrow{n \to \infty} \pi_j$, for some $\pi_j \le 1$,

$$r_{ij}(n) = \sum_{k=1}^{m} r_{ik}(n-1)p_{kj} \Longrightarrow \pi_j = \sum_{k=1}^{m} \pi_k p_{kj}$$
 (Balance equation)

• Normalization equation

$$\sum_{i=1}^{m} \pi_i = 1$$

• Balance equation + Normalization equation \Longrightarrow Finding the steady-state probabilities $\{\pi_i\}$.

Example



A two-state MC with:

$$p_{11} = 0.8, \quad p_{12} = 0.2,$$

 $p_{21} = 0.6, \quad p_{22} = 0.4.$

Balance equation:

$$\pi_1 = \pi_1 p_{11} + \pi_2 p_{21}$$
$$\pi_2 = \pi_2 p_{22} + \pi_1 p_{12}$$

- Normalization equation: $\pi_1 + \pi_2 = 1$
- The stationary distribution is: $\pi_1 = 0.25$, $\pi_2 = 0.75$.

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Stationary Distribution



- $\{\pi_i\}$ is also called a stationary distribution. Why?
- Distribution, because $\sum_{j=1}^{m} \pi_j = 1$.
- Stationary, because, if you choose the starting state according to $\{\pi_i\}$, then

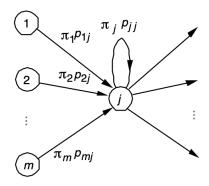
$$\mathbb{P}(X_0 = j) = \pi_j, \quad j = 1, \dots, m \Longrightarrow \mathbb{P}(X_1 = j) = \sum_{k=1}^m \mathbb{P}(X_0 = k) p_{kj} = \sum_{k=1}^m \pi_k p_{kj} = \pi_j$$

- Then, $\mathbb{P}(X_n = j) = \pi_j$, for all n and j.
- If the initial state is chosen according to $\{\pi_j\}$, the state at any future time will have the same distribution (i.e., the distribution does not change over time).
- We say that "the limiting distribution is equal to to the stationary distribution"

Long-term Frequency Interpretation



- π_i : the long-term expected fraction of time that the state is equal to j.
- Balance equation: $\sum_{k=1}^{m} \pi_k p_{kj} = \pi_j$ means:
 - The expected frequency π_j of visits to j is equal to the sum of the expected frequencies $\pi_k p_{kj}$ of transitions that lead to j.



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Roadmap

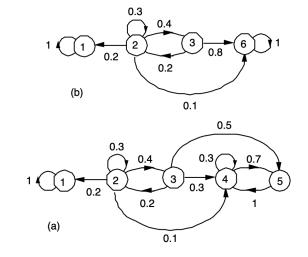


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Absorption Probability

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- Definition. A state k is absorbing, if p_{kk} = 1, and p_{kj} = 0 for all j ≠ k.
 states 1 and 6 are absorbing
- (Q) For a fixed absorbing state s, the probability a_i of reaching s, starting from a transient state i?
 - Fix s = 6. $a_1 = 0$, $a_6 = 1$ $a_2 = 0.2a_1 + 0.3a_2 + 0.4a_3 + 0.1a_6$ $a_3 = 0.2a_2 + 0.8a_6$



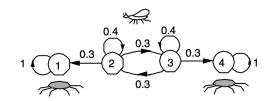
- (Q) What if there are some non-absorbing recurrent state?
- Convert it into the one only with absorbing recurrent states (from (a) to (b)).

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Expected Time to Any Absorbing State



(Q) Starting from a transient state i, expected number of transitions μ_i until absorption to any absorbing state?



Spider-fly example

$$\mu_1 = \mu_4 = 0$$
 (for recurrent states) $\mu_2 = \frac{1}{0.4} + 0.3 \mu_2 + 0.3 \mu_3$, $\mu_3 = \frac{1}{0.4} + 0.3 \mu_3$ (for transient states)

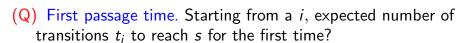
• For generalized description, please see the textbook (pp. 367).

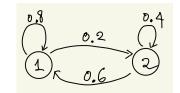
⁰The notation a_i should have dependence on s, but we omit it for simplicity.

Expected time to a particular recurrent state s



- Assume a single recurrent class





- (Q) First recurrence time. Starting from a s, expected number of transitions t_s^* to reach s for the first time?
 - Mean first passage time from 2 to 1

$$t_1 = 0$$

 $t_2 = 1 + p_{21}t_1 + p_{22}t_2 = 1 + 0.4t_2 \Longrightarrow t_2 = 5/3$

Mean first recurrence time from 1 to 1

$$t_1^{\star} = 1 + p_{11}t_1 + p_{12}t_2 = 1 + 0 + 0.2\frac{5}{3} = \frac{4}{3}$$

• For generalized description, please see the textbook (pp. 368)

⁰The notation t_i should have the dependence on s, but we omit it for simplicity.

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Questions?

Review Questions



- 1) Why do you think Markov chain (MC) is important?
- 2) What is the Markov property and its meaning? What's the key difference of MC from Bernoulli processes?
- 3) What are the limiting distribution and the stationary distribution of MCs?
- 4) How are you going to compute the stationary distribution, if you are given a transition probability matrix?
- 5) What are recurrent and transient states in MC?