

Lecture 3: Random Variable, Part I

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EE210: Probability and Introductory Random Processes KAIST EE

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Roadmap



- (1) Random variable: Idea and formal definition
- (2) Popular discrete random variables
- (3) Summarizing random variables: Expectation and Variance
- (4) (Functions of) multiple random variables
- (5) Conditioning for random variables
- (6) Independence for random variables

Roadmap



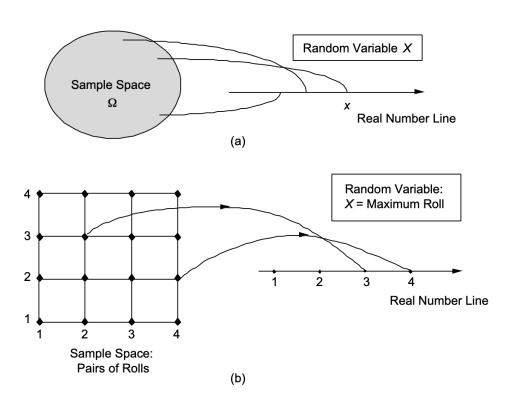
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Random Variable: Idea



- In reality, many outcomes are numerical , e.g., stock price.
- Even if not, very convenient if we map numerical values to random outcomes, e.g., '0' for male and '1' for female.



(b) Two rolls of tetrahedral dice

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Random Variable: More Formally



- \circ Mathematically, a random variable X is a function which maps from Ω to \mathbb{R} .
- Notation. Random variable X, numerical value x.
- Different random variables can be defined on the same sample space.
- \circ For a fixed value x, we can associate an | event | that a random variable X has the value x, i.e., $|\{\omega \in \Omega \mid X(\omega) = x\}|$
- Assume that values x are discrete such as $1, 2, 3, \ldots$ For notational convenience,

$$p_X(x) \triangleq \mathbb{P}(X = x) \triangleq \mathbb{P}(\{\omega \in \Omega \mid X(\omega) = x\})$$

• For a discrete random variable X, we call $p_X(x)$ probability mass function (PMF).

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¹Finite or countably infinite.

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Bernoulli X with parameter $p \in [0, 1]$



Only binary values

$$X = egin{cases} 0, & ext{w.p.} & 1-p, \ 1, & ext{w.p.} & p \end{cases}$$

In other words, $p_X(0) = 1 - p$ and $p_X(1) = p$ from our PMF notation.

- Models a trial that results in binary results, e.g., success/failure, head/tail
- Very useful for an indicator rv of an event A. Define a rv $\mathbf{1}_A$ as:

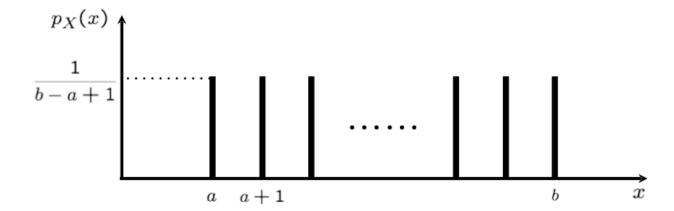
$$\mathbf{1}_A = egin{cases} 1, & ext{if } A ext{ occurs}, \ 0, & ext{otherwise} \end{cases}$$

¹w.p.: with probability

Uniform X with parameter a, b



- integers a, b, where $a \le b$
- Choose a number out of $\Omega = \{a, a+1, \ldots, b\}$ uniformly at random.
- $p_X(i) = \frac{1}{b-a+1}, i \in \Omega$



• Models complete ignorance (I don't know anything about X)

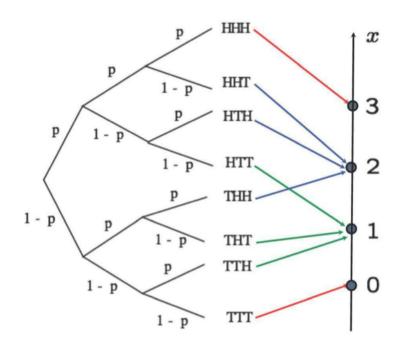
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Binomial X with parameter n, p



- Models the number of successes in a given number of independent trials
- *n* independent trials, where one trial has the success probability *p*.

$$p_X(k) = \binom{n}{k} p^k (1-p)^{n-k}$$



 $[\]binom{1}{k} = \frac{n!}{k!(n-k)!}$, which we read 'n choose k'.

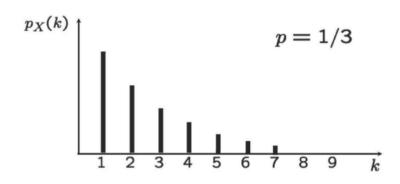
Geometric X with parameter p



- Infinitely many independent Bernoulli trials, where each trial has success probability p
- Random variable: number of trials until the first success.

$$p_X(k) = (1-p)^{k-1}p$$

 Models waiting times until something happens.



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Expectation/Mean



Average

Definition

$$\mathbb{E}[X] = \sum_{x} x p_X(x)$$

- $p_X(x)$: relative frequency of value x (trials with x/total trials)
- Example. Bernoulli rv with p

$$\mathbb{E}[X] = 1 \times p + 0 \times (1-p) = p = p_X(1)$$

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Properties of Expectation



Not very surprising. Easy to prove using the definition.

$$\circ$$
 If $X \geq 0$, $\mathbb{E}[X] \geq 0$.

• If
$$a \le X \le b$$
, $a \le \mathbb{E}[X] \le b$.

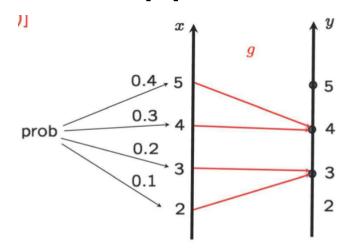
• For a constant
$$c$$
, $\mathbb{E}[c] = c$.

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Expectation of a function of a RV



- For a rv X, Y = g(X) is also a r.v.
- $\mathbb{E}[Y] = \mathbb{E}[g(X)] = \sum_{x} g(x) \rho_X(x)$
- Compute $\mathbb{E}[Y]$ for the following:



$$4 \times (0.4 + 0.3) + 3 \times (0.1 + 0.2)$$

= $2.8 + 0.9 = 3.7$

Linearity of Expectation

$$\mathbb{E}[aX+b]=a\mathbb{E}[X]+b$$

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Variance



- Measures how much the spread of a PMF is.
- What about $\mathbb{E}[X \mu]$, where $\mu = \mathbb{E}[X]$? Zero
- Then, what about $\mathbb{E}[(X \mu)^2]$?

Variance, Standard Deviation

$$var[X] = \mathbb{E}[(X - \mu)^2]$$

$$\sigma_X = \sqrt{\operatorname{var}[X]}$$

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Variance: Useful Property



- $\operatorname{var}[X] = \mathbb{E}[X^2] (\mathbb{E}[X])^2$ $\operatorname{var}[X] = \mathbb{E}[X^2 - 2\mu X + \mu^2]$ $= \mathbb{E}[X^2] - 2\mu \mathbb{E}[X] + \mu^2 = \mathbb{E}[X^2] - \mu^2$
- Y = X + b, var[Y] = var[X] $var[Y] = \mathbb{E}[(X + b)^2] - (\mathbb{E}[X + b])^2$
- Y = aX, $var[Y] = a^2 var[X]$ $var[Y] = \mathbb{E}[a^2X^2] - (a\mathbb{E}[X])^2$

Example: Variance of a Bernoulli rv(p)

$$\mu = \mathbb{E}[X] = 1 \times p + 0 \times (1 - p) = p$$
 $\mathbb{E}[X^2] = 1 \times p + 0 \times (1 - p) = p$
 $\text{var}[X] = \mathbb{E}[X^2] - \mu^2 = p - p^2$
 $= p(1 - p)$

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Joint PMF



• Joint PMF. For two random variables X, Y, consider two events $\{X = x\}$ and $\{Y = y\}$, and

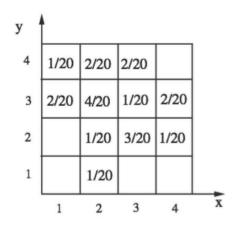
$$p_{X,Y}(x,y) \triangleq \mathbb{P}(\{X=x\} \cap \{Y=y\})$$

- $\sum_{x} \sum_{y} p_{X,Y}(x,y) = 1$
- Marginal PMF.

$$p_X(x) = \sum_{y} p_{X,Y}(x,y),$$
$$p_Y(y) = \sum_{x} p_{X,Y}(x,y)$$

Example.

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$$p_{X,Y}(1,3) = 2/20$$

$$p_X(4) = 2/20 + 1/20 = 3/20$$

$$\mathbb{P}(X = Y) = 1/20 + 4/20 + 3/20 = 8/20$$

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Functions of Multiple RVs



• Consider a rv Z = g(X, Y). (Ex) X + Y, $X^2 + Y^2$. Then, PMF of Z is:

$$p_Z(z) = \mathbb{P}(g(X, Y) = z) = \sum_{(x,y):g(x,y)=z} p_{X,Y}(x,y)$$

Similarly,

$$\mathbb{E}[Z] = \mathbb{E}[g(X,Y)] = \sum_{x} \sum_{y} g(x,y) p_{X,Y}(x,y)$$

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Linearity of Expectation for Multiple RVs



- Remember: $\mathbb{E}[aX + b] = a\mathbb{E}[X] + b$
- Similarly,

$$\mathbb{E}[X+Y] = \mathbb{E}[X] + \mathbb{E}[Y]$$

(easy to prove, using the definition.)

- $\mathbb{E}[X_1 \ldots + X_n] = \mathbb{E}[X_1] + \ldots + \mathbb{E}[X_n]$
- $\mathbb{E}[2X+3Y-Z]=2\mathbb{E}[X]+3\mathbb{E}[Y]-\mathbb{E}[Z]$

- Example. Mean of a binomial rv Y with (n, p)
- Y: number of successes in n Bernoulli trials with p
- $Y = X_1 + ... X_n$, where X_i is a Bernoulli rv.
- $\mathbb{E}[Y] = n\mathbb{E}[X_i] = n\mathbb{P}(X_i = 1) = np$

Message. When some rv X is write as a linear combination of other rvs, it is often easy to handle X.

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Conditional PMF: Conditioning on an event



Remember two probability laws: $\mathbb{P}(\cdot)$ and $\mathbb{P}(\cdot|A)$ for an event A.

•
$$p_X(x) \triangleq \mathbb{P}(X=x)$$

•
$$\mathbb{E}[X] = \sum_{x} x p_X(x)$$

•
$$\mathbb{E}[g(X)] = \sum_{x} g(x) p_X(x)$$

•
$$var[X] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$

•
$$p_{X|A}(x) \triangleq \mathbb{P}(X = x|A)$$

• $\mathbb{E}[X|A] \triangleq \sum_{x} x p_{X|A}(x)$

•
$$\mathbb{E}[X|A] \triangleq \sum_{x} x p_{X|A}(x)$$

•
$$\mathbb{E}[g(X)|A] \triangleq \sum_{x} g(x) p_{X|A}(x)$$

•
$$\operatorname{var}[X|A] \triangleq \mathbb{E}[X^2|A] - (\mathbb{E}[X|A])^2$$

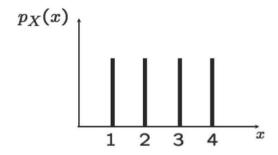
• (Note) $p_{X|A}(x)$, $\mathbb{E}[X|A]$, $\mathbb{E}[g(X)|A]$, and var[X|A] are all just notations!

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Example: Conditional PMF

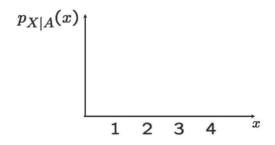


$$A = \{X \ge 2\}$$



$$\mathbb{E}[X] = \frac{1}{4}(1+2+3+4) = 2.5$$

$$var[X] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$
$$= \frac{1}{4}(1+2^2+3^2+4^2) - 2.5^2$$



$$\mathbb{E}[X|A] = \frac{1}{3}(2+3+4) = 3$$

$$var[X|A] = \mathbb{E}[X^2|A] - (\mathbb{E}[X|A])^2$$
$$= \frac{1}{3}(2^2 + 3^2 + 4^2) - 3^2 = 2/3$$

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Conditional PMF: Conditioning on a RV



What do we mean by "conditioning on a rv"? Consider $A = \{Y = y\}$ for a rv Y.

•
$$p_{X|A}(x) \triangleq \mathbb{P}(X = x|A)$$

•
$$\mathbb{E}[X|A] \triangleq \sum_{x} x p_{X|A}(x)$$

•
$$\mathbb{E}[g(X)|A] \triangleq \sum_{x} g(x) p_{X|A}(x)$$

•
$$\operatorname{var}[X|A] \triangleq \mathbb{E}[X^2|A] - (\mathbb{E}[X|A])^2$$

•
$$p_{X|Y}(x|y) \triangleq \mathbb{P}(X = x|Y = y)$$

• $\mathbb{E}[X|Y = y] \triangleq \sum_{x} x p_{X|Y}(x|y)$

•
$$\mathbb{E}[X|Y=y] \triangleq \sum_{x} x p_{X|Y}(x|y)$$

•
$$\mathbb{E}[g(X)|Y=y] \triangleq \sum_{x} g(x) p_{X|Y}(x|y)$$

•
$$\operatorname{var}[X|Y = y] \triangleq \mathbb{E}[X^2|Y = y] - (\mathbb{E}[X|Y = y])^2$$

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Conditional PMF



Conditional PMF

$$p_{X|Y}(x|y) \triangleq \mathbb{P}(X=x|Y=y) = \frac{p_{X,Y}(x,y)}{p_{Y}(y)}$$

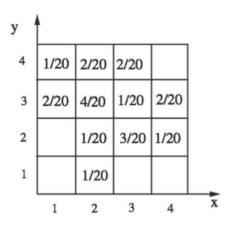
for y such that $p_Y(y) > 0$.

- $\bullet \ \sum_{x} p_{X|Y}(x|y) = 1$
- Multiplication rule.

$$p_{X,Y}(x,y) = p_Y(y)p_{X|Y}(x|y)$$
$$= p_X(x)p_{Y|X}(y|x)$$

• $p_{X,Y,Z}(x, y, z) = p_X(x)p_{Y|X}(y|x)p_{Z|X,Y}(z|x, y)$

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$$p_{X|Y}(2|2) = \frac{1}{1+3+1}$$

$$p_{X|Y}(3|2) = \frac{3}{1+3+1}$$

$$\mathbb{E}[X|Y=3] = 1(2/9) + 2(4/9) + 3(1/9) + 4(2/9)$$

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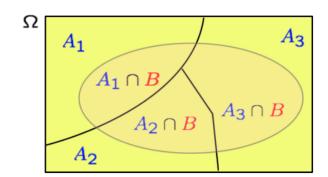
Remind: Total Probability Theorem (from Lecture 2)

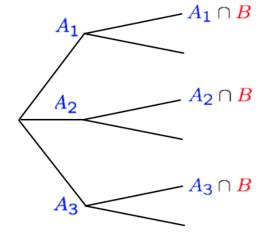


- Partition of Ω into A_1, A_2, A_3
- \circ Known: $\mathbb{P}(A_i)$ and $\mathbb{P}(B|A_i)$
- What is $\mathbb{P}(B)$? (probability of result)

Total Probability Theorem

$$\mathbb{P}(B) = \sum_{i} \mathbb{P}(A_i) \mathbb{P}(B|A_i)$$





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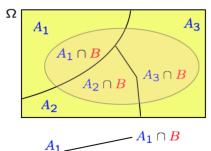
Total Probability Theorem: $B = \{X = x\}$

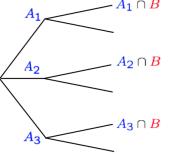


Partition of Ω into A_1, A_2, A_3

Total Probability Theorem

$$p_X(x) = \sum_i \mathbb{P}(A_i)\mathbb{P}(X = x|A_i) = \sum_i \mathbb{P}(A_i)p_{X|A_i}(x)$$





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Total Expectation Theorem for $\{A_i\}$



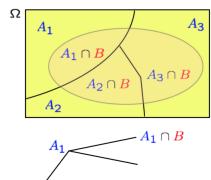
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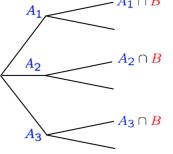
Total Probability Theorem

$$p_X(x) = \sum_i \mathbb{P}(A_i)\mathbb{P}(X = x|A_i) = \sum_i \mathbb{P}(A_i)p_{X|A_i}(x)$$

Total Expectation Theorem

$$\mathbb{E}[X] = \sum_{i} \mathbb{P}(A_i) \mathbb{E}[X|A_i]$$





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Total Expectation Theorem for $\{Y = y\}$



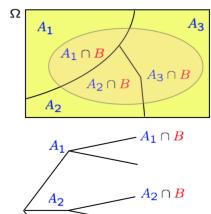
• Partition of Ω into A_1, A_2, A_3

Total Expectation Theorem

$$\mathbb{E}[X] = \sum_{i} \mathbb{P}(A_i) \mathbb{E}[X|A_i]$$

Total Expectation Theorem

$$\mathbb{E}[X] = \sum_{y} \mathbb{P}(Y = y) \mathbb{E}[X|Y = y] = \sum_{y} p_{Y}(y) \mathbb{E}[X|Y = y]$$



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Example 1: Total Expectation Theorem



Using the definition of expectation,

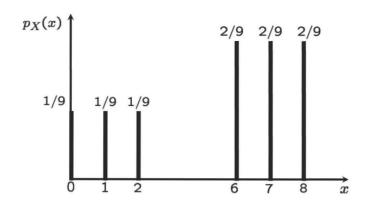
$$\mathbb{E}[X] = \frac{1}{9}(0+1+2) + \frac{2}{9}(6+7+8)$$
$$= \frac{3+12+14+16}{9} = 5$$

• Let's use TET, for which consider

$$A_1 = \{X \in \{0, 1, 2\}\}, \ A_2 = \{X \in \{6, 7, 8\}\}$$

$$\mathbb{E}[X] = \sum_{i=1,2} \mathbb{P}(A_i)\mathbb{E}[X|A_i]$$

$$= 1/3 \cdot 1 + 2/3 \cdot 7 = 5$$



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Background: Memoryless Property



- Some random variable often does not have memory.
- Definition. A random variable X is called $\boxed{\text{memoryless}}$ if, for any $n, m \geq 0$, $\mathbb{P}(X > n + m | X > m) = \mathbb{P}(X > n)$
- Meaning. Conditioned on X > m, X m's distribution is the same as the original X.

$$\mathbb{P}(X - m > n | X > m) = \mathbb{P}(X > n)$$

• Suppose that X is the time of waiting for a bus and X is memoryless. At the bus stop, I have waited for the bus for 10 mins. Then, the time until the bus arrival does not depend on how much I have waited for a bus. No memory.

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Background: Memoryless Property of Geometric RVs



- Theorem. Any geometric random variable is memoryless.
- Remind. Geometric rv X with parameter p

$$\mathbb{P}(X=k)=(1-p)^{k-1}p, \quad \mathbb{P}(X>k)=1-\sum_{k'=1}^k (1-p)^{k'-1}p=(1-p)^k$$

Proof.

$$\mathbb{P}(X > n + m | X > m) = \frac{\mathbb{P}(X > n + m \text{ and } X > m)}{\mathbb{P}(X > m)} = \frac{\mathbb{P}(X > n + m)}{\mathbb{P}(X > m)}$$
$$= \frac{(1 - p)^{n+m}}{(1 - p)^m} = (1 - p)^n = \mathbb{P}(X > n)$$

• Meaning. Conditioned on X > m, X - m is geometric with the same parameter.

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Example 2: Mean of Geometric rv



- Write softwares over and over, and each time w.p. p of working correctly (independent from prev. programs).
- X: number of trials until the program works correctly.
- (Q) mean of *X*
- *X* is geometric
- Direct computation is boring.

$$\mathbb{E}[X] = \sum_{k=1}^{\infty} k(1-p)^{k-1}p$$

 Total expectation theorem and memorylessness helps a lot.

•
$$A_1=\{X=1\}$$
 (first try is success), $A_2=\{X>1\}$ (first try is failure).
$$\mathbb{E}[X]=1+\mathbb{E}[X-1]$$

$$=1+\mathbb{P}(A_1)\mathbb{E}[X-1|X=1]$$
 $+\mathbb{P}(A_2)\mathbb{E}[X-1|X>1]$

$$\mathbb{E}[X] = 1 + (1 - p)\frac{1}{p} = 1/p.$$

 $=1+(1-p)\mathbb{E}[X]$

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Independence, Conditional Independence



Two events

$$\mathbb{P}(A \cap B) = \mathbb{P}(A) \cdot \mathbb{P}(B)$$

 $\mathbb{P}(A \cap B | C) = \mathbb{P}(A | C) \cdot \mathbb{P}(B | C)$

A rv and an event

$$\mathbb{P}(\{X = x\} \cap B) = \mathbb{P}(X = x) \cdot \mathbb{P}(B), \text{ for all } x$$

$$\mathbb{P}(\{X = x\} \cap B | C) = \mathbb{P}(X = x | C) \cdot \mathbb{P}(B | C), \text{ for all } x$$

Two rvs

$$\mathbb{P}(\{X=x\} \cap \{Y=y\}) = \mathbb{P}(X=x) \cdot \mathbb{P}(Y=y), \text{ for all } x, y$$
$$p_{X,Y}(x,y) = p_X(x) \cdot p_Y(y)$$

$$\mathbb{P}(\{X=x\} \cap \{Y=y\} | Z=z) = \mathbb{P}(X=x | Z=z) \cdot \mathbb{P}(Y=y | Z=z), \text{ for all } x, y$$
$$p_{X,Y|Z}(x,y) = p_{X|Z}(x) \cdot p_{Y|Z}(y)$$

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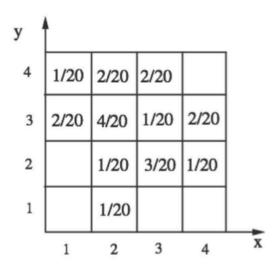
Example



$$p_{X,Y}(1,1) = 0, \quad p_X(1) = 3/20$$

 $p_Y(1) = 1/20.$

• $X \perp \!\!\! \perp Y | \{X \le 2 \text{ and } Y \ge 3\}$? - Yes.



| Y = 4 (1/3) | 1/9 | 2/9 |
|-------------|-------------|------------|
| Y = 3 (2/3) | 2/9 | 4/9 |
| | X = 1 (1/3) | X = 2(2/3) |

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Expectation and Variance



Always true.

$$\mathbb{E}[X+Y] = \mathbb{E}[X] + \mathbb{E}[Y]$$

- ullet Generally, $\mathbb{E}[g(X,Y)]
 eq g(\mathbb{E}[X],\mathbb{E}[Y])$
- However, if $X \perp \!\!\!\perp Y$,

$$\mathbb{E}[XY] = \mathbb{E}[X]\mathbb{E}[Y]$$
 $\mathbb{E}[g(X)h(Y)] = \mathbb{E}[g(X)]\mathbb{E}[g(Y)]$

• Proof.

$$\mathbb{E}[g(X)h(Y)] = \sum_{x} \sum_{y} g(x)h(y)p_{X,Y}(x,y)$$
$$= \sum_{x} xp_{X}(x) \sum_{y} yp_{Y}(y)$$

- Always true. $var[aX] = a^2 var[X]$, var[X + a] = var[X]
- Generally, $var[X + Y] \neq var[X] + var[Y]$
- However, if $X \perp \!\!\! \perp Y$, var[X + Y] = var[X] + var[Y]
- Practice.
 - $\circ X = Y \Longrightarrow var[X + Y] = 4var[X]$
 - $X = -Y \Longrightarrow var[X + Y] = 0$

$var[X + Y] \neq var[X] + var[Y]$



• Why not generally true?

$$var[X + Y] = \mathbb{E}[(X + Y)^{2}] - (\mathbb{E}[X + Y])^{2}$$

$$= \mathbb{E}[X^{2} + Y^{2} + 2XY] - ((\mathbb{E}[X])^{2} + (\mathbb{E}[Y])^{2} + 2\mathbb{E}[X]\mathbb{E}[Y])$$

$$= var[X] + var[Y] + 2(\mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y])$$

- \circ $X \perp\!\!\!\perp Y$ is a sufficient condition for $\mathbb{E}[XY] = \mathbb{E}[X]\mathbb{E}[Y]$
- Also, a necessary condition? we will see later, when we study covariance.

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Example: The hat problem (1)



- n people throw their hats in a box and then pick one at random
- X: number of people with their own hat
- $\mathbb{E}[X]$? var[X]?
- All permutations are equally likely as 1/n!. Thus, this equals to picking one hat at a time.
- Key step 1. Define a rv $X_i = 1$ if i selects own hat and 0 otherwise.

$$X = \sum_{i=1}^{n} X_i.$$

• $\{X_i\}, i = 1, 2, ..., n$: identically distributed (symmetry)

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Example: The hat problem (2)



- $\mathbb{E}[X] = n\mathbb{E}[X_1] = n\mathbb{P}(X_1 = 1) = n \times \frac{1}{n} = 1.$
- Key step 2. Are X_i s are independent? If yes, easy to get var(X).
- Assume n=2. Then, $X_1=1 \rightarrow X_2=1$, and $X_1=0 \rightarrow X_2=0$. Thus, dependent.

$$\operatorname{var}(X) = \mathbb{E}[X^{2}] - (\mathbb{E}[X])^{2}$$

$$= \mathbb{E}\left[\sum_{i} X_{i}^{2} + \sum_{i,j:i \neq j} X_{i} X_{j}\right] - (\mathbb{E}[X])^{2}$$

$$\mathbb{E}[X_i^2] = 1 \times \frac{1}{n} + 0 \times \frac{n-1}{n} = \frac{1}{n}$$

$$\mathbb{E}[X_i X_j] = \mathbb{E}[X_1 X_2] = 1 \times \mathbb{P}(X_1 X_2 = 1) = \mathbb{P}(X_1 = 1) \mathbb{P}(X_2 = 1 | X_1 = 1), \quad (i \neq j)$$

•
$$\mathbb{E}[X^2] = n\mathbb{E}[X_1^2] + n(n-1)\mathbb{E}[X_1X_2] = n\frac{1}{n} + n(n-1)\frac{1}{n(n-1)} = 2$$

•
$$var(X) = 2 - 1 = 1$$

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Questions?

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Review Questions



- 1) What is Random Variable? Why is it useful?
- 2) What is PMF (Probability Mass Function)?
- 3) Explain Bernoulli, Binomial, Poisson, Geometric rvs, when they are used and what their PMFs are.
- 4) What are joint and marginal PMFS?
- 5) Describe and explain the total probability/expectation theorem for random variables?
- 6) When is it useful to use total probability/expectation theorem?
- 7) What is conditional independence?

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