

Lecture 4: Random Variable, Part II

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EE210: Probability and Introductory Random Processes KAIST EE

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Roadmap



- (1) Continuous Random Variable and PDF (Probability Density Function)
- (2) CDF (Cumulative Distribution Function)
- (3) Exponential RVs
- (4) Gaussian (Normal) RVs
- (5) Continuous RVs: Joint, Conditioning, and Independence
- (6) Bayes' rule for RVs

Roadmap



3 / 32

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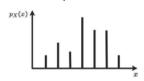
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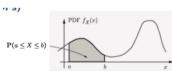
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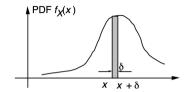
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- $\mathbb{P}(a \le X \le b) = \int_a^b f_X(x) dx$ $f_X(x) \ge 0$, $\int_{-\infty}^{\infty} f_X(x) dx = 1$



5 / 32

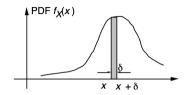


•
$$\mathbb{P}(a \leq X \leq a + \delta) \approx$$

Examples



5 / 32

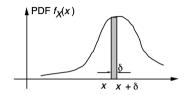


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$$\mathbb{P}(a \leq X \leq a + \delta) \approx |f_X(a) \cdot \delta|$$

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5 / 32

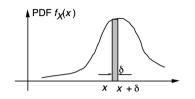


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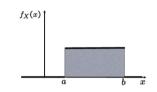


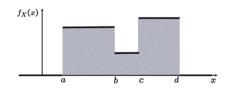


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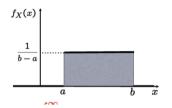
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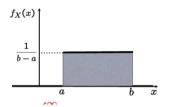






- $\mathbb{E}[X] = \int_{-\infty}^{\infty} x f_X(x) dx =$
- $\mathbb{E}[X^2] = \int_{-\infty}^{\infty} x^2 f_X(x) dx =$
- var[X] =

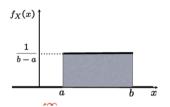




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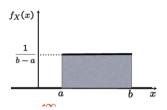




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•
$$var[X] = \frac{a^2 + ab + b^2}{3} - \frac{a^2 + 2ab + b^2}{4}$$

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7 / 32

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L4(2)

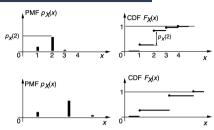


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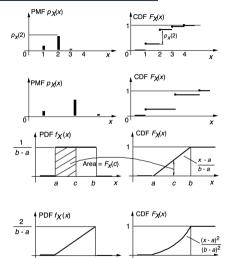


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L4(2) April 27, 2021 9 / 32



9 / 32

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- If X is continuous
 - \circ $F_X(x)$ is a continuous function of x.

•
$$F_X(x) = \int_{-\infty}^x f_X(t)dt$$
 and $f_X(x) = \frac{dF_X}{dx}(x)$

Example: Maximum of Random Variables



- Take a test three times, and your final score will be the maximum of test scores
- $X = \max\{X_1, X_2, X_3\}$, and $X_i \in \{1, 2, \dots, 10\}$ uniformly at random
- Question. $p_X(x)$?
- Approach 1: $\mathbb{P}(\max\{X_1, X_2, X_3\} = x)$?
- Approach 2

$$F_X(x) = \mathbb{P}(\max\{X_1, X_2, X_3\} \le x) = \mathbb{P}(X_1 \le x, X_2 \le x, X_3 \le x)$$
$$= \mathbb{P}(X_1 \le x) \cdot \mathbb{P}(X_2 \le x) \cdot \mathbb{P}(X_3 \le x) = \left(\frac{x}{10}\right)^3$$

Thus,

$$p_X(x) = \left(\frac{x}{10}\right)^3 - \left(\frac{x-1}{10}\right)^3, \quad x = 1, 2, \dots, 10$$

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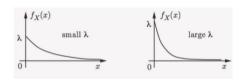
12 / 32



12 / 32

• A rv X is called exponential with λ , if

$$f_X(x) = \begin{cases} \lambda e^{-\lambda x}, & x \ge 0 \\ 0, & x < 0 \end{cases}$$



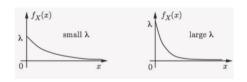


12 / 32

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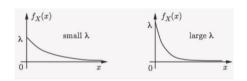




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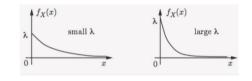


Exponential RV with parameter $\lambda > 0$



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- CDF $F_X(x) = \int_0^x \lambda e^{-\lambda s} ds = 1 e^{-\lambda x}$
- CCDF $\mathbb{P}(X > x) = e^{-\lambda x}$
- (Check) $\mathbb{E}[X] = 1/\lambda$, $\mathbb{E}[X^2] = 2/\lambda^2$, $var[X] = 1/\lambda^2$

Exponential RV: Mean and Variance



• $\mathbb{E}(X) = 1/\lambda$. Use integration by parts: $\int u dv = uv - \int v du$

$$\int_0^\infty x\lambda e^{-\lambda x}dx = \left(-xe^{-\lambda x}\right)\Big|_0^\infty + \int_0^\infty e^{-\lambda x}dx = 0 - \frac{e^{-\lambda x}}{\lambda}\Big|_0^\infty = \frac{1}{\lambda}$$

• $\mathbb{E}(X^2)$

$$\int_0^\infty x^2 \lambda e^{-\lambda x} dx = \left(-x^2 e^{-\lambda x}\right)\Big|_0^\infty + \int_0^\infty 2x e^{-\lambda x} dx = 0 + \frac{2}{\lambda} \mathbb{E}(X) = \frac{2}{\lambda^2}$$

• $\operatorname{\mathsf{var}}(X) = \mathbb{E}(X^2) - (\mathbb{E}(X))^2 = \frac{1}{\lambda^2}$



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$$\mathbb{P}(X > x) = e^{-\lambda x}$$



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- (Q) What is the discrete rv which models a waiting time? Geometric
- What is the relationship between exponential rv and geometric rv? We will see this relationship soon, but let's look at an example first.

L4(3)

Example



15 / 32

• A very small meteorite first lands anywhere in Korea



L4(3) April 27, 2021

Example



15 / 32

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Example¹



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 VIDEO PAUSE

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 VIDEO PAUSE
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- (Solution)
 - $\circ \ \mathbb{E}(X) = 1/\lambda = 10.$ Thus, $\lambda = \frac{1}{10}$.
 - \circ 6 a.m. from midnight = 1/4 day, 6 p.m. from midnight = 3/4 day

$$\mathbb{P}(1/4 \le X \le 3/4) = \mathbb{P}(X \ge 1/4) - \mathbb{P}(X \ge 3/4) = e^{-1/40} - e^{-3/40} = 0.0476$$

L4(3)



16 / 32

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- In many cases, continuous case is some type of limit of its corresponding discrete case.
- Can we mathematically describe how geometric and exponential rvs meet each other in the limit?



17 / 32

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17 / 32

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17 / 32

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L4(3)

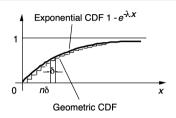


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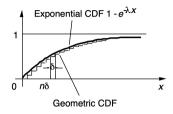
$$\circ \ \mathbb{P}(X^{geo}_{\delta} \leq n) = 1 - (1 - p_{\delta})^n = 1 - e^{-\lambda \delta n}$$



18 / 32





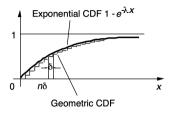


• Note that $\mathbb{P}(X^{exp} \leq x) = 1 - e^{-\lambda x}$. Then, when $x = n\delta, n = 1, 2, ...$

$$\mathbb{P}(X^{exp} \le x) = 1 - e^{-\lambda \delta n} =$$

L4(3)





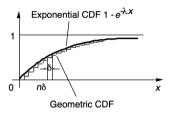
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$$\mathbb{P}(X^{exp} \le x) = 1 - e^{-\lambda \delta n} = \mathbb{P}(X^{geo}_{\delta} \le n)$$

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18 / 32





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$$\mathbb{P}(X^{\mathsf{exp}} \leq x) = 1 - e^{-\lambda \delta n} = \mathbb{P}(X^{\mathsf{geo}}_{\delta} \leq n)$$

• If we choose sufficiently small δ , the slot length \downarrow and $p_{\delta} \downarrow$

$$\mathbb{P}(X_{\delta}^{geo} \leq n) \xrightarrow{\delta \to 0} \mathbb{P}(X^{exp} \leq x), x = n\delta$$

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19 / 32

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Normal: PDF, Expectation, Variance



• Standard Normal $\mathcal{N}(0,1)$

$$f_X(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$

- $\mathbb{E}[X] = 0$
- $\bullet \ \operatorname{var}[X] = 1$

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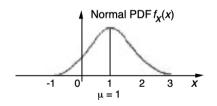
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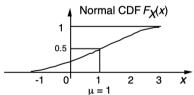
- $\mathbb{E}[X] = 0$
- var[X] = 1

• General Normal $\mathcal{N}(\mu, \sigma^2)$

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}}e^{-(x-\mu)^2/2\sigma^2}$$

- $\mathbb{E}[X] = \mu$
- $\operatorname{var}[X] = \sigma^2$







21 / 32

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21 / 32

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L4(4) April 27, 2021



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- Variance

$$var(X) = \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} (x - \mu)^2 e^{-(x - \mu)^2/2\sigma^2} dx \stackrel{y = \frac{x - \mu}{\sigma}}{=} \frac{\sigma^2}{\sqrt{2\pi}} \int_{-\infty}^{\infty} y^2 e^{-y^2/2} dy$$
$$= \frac{\sigma^2}{\sqrt{2\pi}} (-ye^{-y^2/2}) \Big|_{-\infty}^{\infty} + \frac{\sigma^2}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-y^2/2} dy = \frac{\sigma^2}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-y^2/2} dy = \sigma^2$$

$$\int u dv = uv - \int v du$$
: $u = y$ and $dv = ye^{-y^2/2} \rightarrow du = dy$ and $v = -e^{-y^2/2}$

L4(4)

Normality: Preserved under Linear Transformation



22 / 32

Normality: Preserved under Linear Transformation



22 / 32

• Linear transformation preserves normality (we will verify this in Lecture 5)

If
$$X \sim \mathcal{N}(\mu, \sigma^2)$$
, then for $a \neq 0$ and $b, \ Y = aX + b \sim \mathcal{N}(a\mu + b, a^2\sigma^2)$.

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L4(4)

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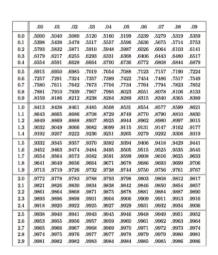
• Thus, we can make the table which records the following CDF values:

$$\Phi(y) = \mathbb{P}(Y \leq y) = \mathbb{P}(Y < y) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{y} e^{-t^2/2} dt$$

Example



• Annual snowfall X is modeled as $\mathcal{N}(60, 20^2)$. What is the probability that this year's snowfall is at least 80 inches?



L4(4) April 27, 2021 23 / 32

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	.00	.01	.02	.03	.04	.05	.06	.07	.08	.09
0.0	.5000	.5040	.5080	.5120	.5160	.5199	.5239	.5279	.5319	.5359
0.1	.5398	.5438	.5478	.5517	.5557	.5596	.5636	.5675	.5714	.5753
0.2	.5793	.5832	.5871	.5910	.5948	.5987	.6026	.6064	.6103	.6141
0.3	.6179	.6217	.6255	.6293	.6331	.6368	.6406	.6443	.6480	.6517
0.4	.6554	.6591	.6628	.6664	.6700	.6736	.6772	.6808	.6844	.6879
0.5	.6915	.6950	.6985	.7019	.7054	.7088	.7123	.7157	.7190	.7224
0.6	.7257	.7291	.7324	.7357	.7389	.7422	.7454	.7486	.7517	.7549
0.7	.7580	.7611	.7642	.7673	.7704	.7734	.7764	.7794	.7823	.7852
0.8	.7881	.7910	.7939	.7967	.7995	.8023	.8051	.8078	.8106	.8133
0.9	.8159	.8186	.8212	.8238	.8264	.8289	.8315	.8340	.8365	.8389
1.0	.8413	.8438	.8461	.8485	.8508	.8531	.8554	.8577	.8599	.8621
1.1	.8643	.8665	.8686	.8708	.8729	.8749	.8770	.8790	.8810	.8830
1.2	.8849	.8869	.8888	.8907	.8925	.8944	.8962	.8980	.8997	.9015
1.3	.9032	.9049	.9066	.9082	.9099	.9115	.9131	.9147	.9162	.9177
1.4	.9192	.9207	.9222	.9236	.9251	.9265	.9279	.9292	.9306	.9319
1.5	.9332	.9345	.9357	.9370	.9382	.9394	.9406	.9418	.9429	.9441
1.6	.9452	.9463	.9474	.9484	.9495	.9505	.9515	.9525	.9535	.9545
1.7	.9554	.9564	.9573	.9582	.9591	.9599	.9608	.9616	.9625	.9633
1.8	.9641	.9649	.9656	.9664	.9671	.9678	.9686	.9693	.9699	.9706
1.9	.9713	.9719	.9726	.9732	.9738	.9744	.9750	.9756	.9761	.9767
2.0	.9772	.9778	.9783	.9788	.9793	.9798	.9803	.9808	.9812	.9817
2.1	.9821	.9826	.9830	.9834	.9838	.9842	.9846	.9850	.9854	.9857
2.2	.9861	.9864	.9868	.9871	.9875	.9878	.9881	.9884	.9887	.9890
2.3	.9893	.9896	.9898	.9901	.9904	.9906	.9909	.9911	.9913	.9916
2.4	.9918	.9920	.9922	.9925	.9927	.9929	.9931	.9932	.9934	.9936
2.5	.9938	.9940	.9941	.9943	.9945	.9946	.9948	.9949	.9951	.9952
2.6	.9953	.9955	.9956	.9957	.9959	.9960	.9961	.9962	.9963	.9964
2.7	.9965	.9966	.9967	.9968	.9969	.9970	.9971	.9972	.9973	.9974
2.8	.9974	.9975	.9976	.9977	.9977	.9978	.9979	.9979	.9980	.9981
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L4(4) April 27, 2021 23 / 32

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$$\mathbb{P}(X \ge 80) = \mathbb{P}(Y \ge \frac{80 - 60}{20})$$
$$= \mathbb{P}(Y \ge 1) = 1 - \Phi(1)$$
$$= 1 - 0.8413 = 0.1587$$

	.00	.01	.02	.03	.04	.05	.06	.07	.08	.09
0.0	.5000	.5040	.5080	.5120	.5160	.5199	.5239	.5279	.5319	.5359
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L4(4) April 27, 2021 23 / 32

Normal RVs: Why Important?



- Central limit theorem
 - One of the most remarkable findings in the probability theory
 - \circ Sum of any random variables \approx Normal random variable
- · Modeling aggregate noise with many small, independent noise terms
- Convenient analytical properties, allowing closed forms in many cases
- Highly popular in communication and machine learning areas

Roadmap



25 / 32

- (1) Continuous Random Variable and PDF (Probability Density Function)
- (2) CDF (Cumulative Distribution Function)
- (3) Exponential RVs
- (4) Gaussian (Normal) RVs
- (5) Continuous RVs: Joint, Conditioning, and Independence
- (6) Bayes' rule for RVs

Continuous: Joint PDF and CDF (1)



Two continuous rvs are if a non-negative function $f_{X,Y}(x,y)$

(called joint PDF) satisfies: for every subset B of the two dimensional plane,

$$\mathbb{P}((X,Y)\in B)=\iint_{(x,y)\in B}f_{X,Y}(x,y)dxdy,$$

Continuous: Joint PDF and CDF (1)



26 / 32

Two continuous rvs are jointly continuous if a non-negative function $f_{X,Y}(x,y)$ (called joint PDF) satisfies: for every subset B of the two dimensional plane,

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1. The joint PDF is used to calculate probabilities

$$\mathbb{P}\big[(X,Y)\in B\big]=\iint_{(x,y)\in B}f_{X,Y}(x,y)dxdy$$

Our particular interest: $B = \{(x, y) \mid a \le x \le b, c \le y \le d\}$

L4(5)

Continuous: Joint PDF and CDF (2)



27 / 32

2. The marginal PDFs of X and Y are from the joint PDF as:

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy, \quad f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx$$

Continuous: Joint PDF and CDF (2)



27 / 32

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3. The joint CDF is defined by $F_{X,Y}(x,y) = \mathbb{P}(X \le x, Y \le y)$, and determines the joint PDF as:

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Continuous: Joint PDF and CDF (2)



27 / 32

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4. A function g(X, Y) of X and Y defines a new random variable, and

$$\mathbb{E}[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{X,Y}(x,y) dxdy$$



* Conditional PDF, given an event A

* Conditional PDF, given $\{X \in C\}$

Notation: A is an event, but B and C is a subset that includes the possible values which can be taken by the rv X. Sorry for the confusion, if any.



- * Conditional PDF, given an event A
- $f_X(x) \cdot \delta \approx \mathbb{P}(x \le X \le x + \delta)$ • $f_{X|A}(x) \cdot \delta \approx \mathbb{P}(x \le X \le x + \delta|A)$

* Conditional PDF, given $\{X \in C\}$



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- $\mathbb{P}(X \in B) = \int_B f_X(x) dx$ $\mathbb{P}(X \in B|A) = \int_B f_{X|A}(x) dx$

* Conditional PDF, given $\{X \in C\}$



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- $\mathbb{P}(X \in B) = \int_B f_X(x) dx$ $\mathbb{P}(X \in B|A) = \int_B f_{X|A}(x) dx$
- $\int f_{X|A}(x)dx = 1$

* Conditional PDF, given $\{X \in C\}$



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* Conditional PDF, given $\{X \in C\}$

$$f_{X|\{X\in C\}}(x)\cdot\delta\approx\mathbb{P}(x\leq X\leq x+\delta|X\in C)$$

$$f_{X|\{X\in C\}}(x) = \begin{cases} 0, & \text{if } x \notin C \\ \frac{f_X(x)}{\mathbb{P}(X\in C)}, & \text{if } x \in C \end{cases}$$



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(Q) In the discrete, we consider the event $\{X = x\}$, not $\{X \in B\}$. Why?



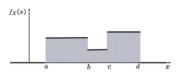
• $\mathbb{E}[X] = \int x f_X(x) dx$ $\mathbb{E}[X|A] = \int x f_{X|A}(x) dx$

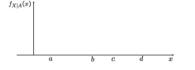


- $\mathbb{E}[X] = \int x f_X(x) dx$ $\mathbb{E}[X|A] = \int x f_{X|A}(x) dx$
- $\mathbb{E}[g(X)] = \int g(x)f_X(x)dx$ $\mathbb{E}[g(X)|A] = \int g(x)f_{X|A}(x)dx$



$$A = \left\{ \frac{a+b}{2} \le X \le b \right\}$$





•
$$\mathbb{E}[X] = \int x f_X(x) dx$$

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•
$$\mathbb{E}[g(X)] = \int g(x) f_X(x) dx$$

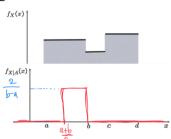
 $\mathbb{E}[g(X)|A] = \int g(x) f_{X|A}(x) dx$

$$\mathbb{E}[X|A] =$$

$$\mathbb{E}[X^2|A] =$$



$$A = \left\{ \frac{a+b}{2} \le X \le b \right\}$$



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$$\mathbb{E}[X] = \int x f_X(x) dx$$

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 $\mathbb{E}[g(X)|A] = \int g(x) f_{X|A}(x) dx$

$$\mathbb{E}[X|A] = \int_{(a+b)/2}^{b} x \frac{2}{b-a} dx = \frac{a}{4} + \frac{3b}{4}$$

$$\mathbb{E}[X^{2}|A] = \int_{(a+b)/2}^{b} x^{2} \frac{2}{b-a} dx =$$



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• Proof. Note that the exponential rv's CCDF $\mathbb{P}(X>x)=e^{-\lambda x}$.



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$$\mathbb{P}(X>n+m|X>m)=\frac{\mathbb{P}(X>n+m)}{\mathbb{P}(X>m)}=\frac{e^{-\lambda(n+m)}}{e^{-\lambda m}}=e^{-\lambda n}=\mathbb{P}(X>n)$$

L4(5)



31 / 32

Partition of Ω into A_1, A_2, A_3, \dots

* Discrete case

* Continuous case



Partition of Ω into A_1, A_2, A_3, \dots

* Discrete case

Total Probability Theorem

$$p_X(x) = \sum_i \mathbb{P}(A_i)\mathbb{P}(X = x|A_i)$$

= $\sum_i \mathbb{P}(A_i)p_{X|A_i}(x)$

Total Expectation Theorem

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Total Probability Theorem

$$f_X(x) = \sum_i \mathbb{P}(A_i) f_{X|A_i}(x)$$

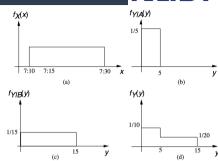
Total Expectation Theorem

$$\mathbb{E}[X] = \sum_{i} \mathbb{P}(A_i) \mathbb{E}[X|A_i]$$

KAIST EE

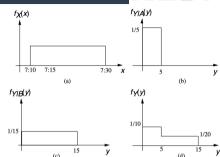
32 / 32

- The train's arrival every quarter hour (0, 15min, 30min, 45min).
- Your arrival $\sim \mathcal{U}(7:10, 7:30)$ am.



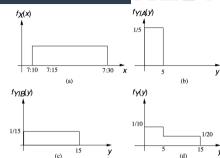


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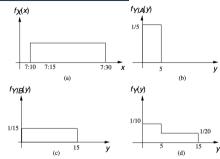
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- X : your arrival time, Y : waiting time.
- The value of X makes a different waiting time. So, consider two events:

$$A = \{7:10 \le X \le 7:15\}$$
$$B = \{7:15 \le X \le 7:30\}$$

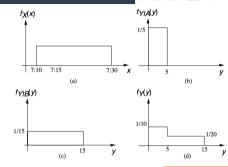


Example: Train Arrival



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VIDEO PAUSE

$$f_Y(y) = \mathbb{P}(A)f_{Y|A}(y) + \mathbb{P}(B)f_{Y|B}(y)$$
 for $0 \le y \le 5$

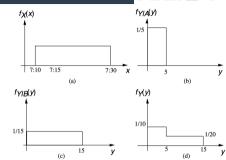
for
$$5 < y \le 15$$

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$$f_{Y}(y) = \mathbb{P}(A)f_{Y|A}(y) + \mathbb{P}(B)f_{Y|B}(y)$$

$$f_{Y}(y) = \frac{1}{4}\frac{1}{5} + \frac{3}{4}\frac{1}{15} = \frac{1}{10}, \text{ for } 0 \le y \le 5$$

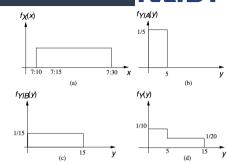
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33 / 32

•
$$p_{X|Y}(x|y) = \frac{p_{X,Y}(x,y)}{p_Y(y)}$$



33 / 32

- $p_{X|Y}(x|y) = \frac{p_{X,Y}(x,y)}{p_Y(y)}$
- Similarly, for $f_Y(y) > 0$,

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$$\int_{-\infty}^{\infty} f_{X|Y}(x|y) \frac{dx}{dx} = \frac{\int_{-\infty}^{\infty} f_{X,Y}(x,y) dx}{f_{Y}(y)} = 1$$



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Multiplication rule.
$$f_{X,Y}(x,y) = f_Y(y) \cdot f_{X|Y}(x|y) = f_X(x)f_{Y|X}(y|x)$$



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• Total prob./exp. theorem.

$$f_X(x) = \int_{-\infty}^{\infty} f_Y(y) f_{X|Y}(x|y) dy$$

$$\mathbb{E}[X|Y = y] = \int_{-\infty}^{\infty} x f_{X|Y}(x|y) dx$$

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Independence

$$f_{X,Y}(x,y) = f_X(x)f_Y(y)$$
, for all x and y



(Prob 21 at pp. 191)

- Break a stick of length / twice
 - first break at $Y \sim \mathcal{U}[0, I]$
 - second break at $X \sim \mathcal{U}[0,\,Y]$



(Prob 21 at pp. 191)

- Break a stick of length / twice
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 - second break at $X \sim \mathcal{U}[0, Y]$
- (a) joint PDF $f_{X,Y}(x,y)$?

L4(5)

$$f_Y(y) = \frac{1}{l}, \quad 0 \le y \le 1$$

$$f_{X|Y}(x|y) = \frac{1}{l}, \quad 0 \le x \le y$$

Using
$$f_{X,Y}(x,y) = f_Y(y)f_{X|Y}(x|y)$$
,

$$f_{X,Y}(x,y) = \begin{cases} \frac{1}{l} \cdot \frac{1}{y}, & 0 \le x \le y \le l, \\ 0, & \text{otherwise} \end{cases}$$

 $^{{}^0\}mathcal{U}[a,b]$: continuous uniform random variable over the interval [a,b]



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L4(5)

$$f_{X|Y}(x|y) = \frac{1}{y}, \quad 0 \le x \le y$$

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Using $f_{X,Y}(x,y) = f_{Y}(y)f_{X|Y}(x|y)$,

b) marginal PDF $f_X(x)$?

$$f_X(x) = \int f_{X,Y}(x,y)dy = \int_x^I \frac{1}{Iy}dy$$
$$= \frac{1}{I}\ln(I/x), \quad 0 \le x \le I$$

 $^{{}^{0}\}mathcal{U}[a,b]$: continuous uniform random variable over the interval [a,b]



35 / 32

(c) Evaluate $\mathbb{E}(X)$, using $f_X(x)$

(d) Evaluate $\mathbb{E}(X)$, using $X = Y \cdot (X/Y)$

If $Y \perp \!\!\! \perp X/Y$, it becomes easy, but true?

(e) Evaluate $\mathbb{E}(X)$, using TET



(c) Evaluate $\mathbb{E}(X)$, using $f_X(x)$

$$\mathbb{E}(X) = \int_0^l x f_X(x) dx = \int_0^l \frac{x}{l} \ln(l/x) dx$$
$$= \frac{l}{4}$$

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(c) Evaluate $\mathbb{E}(X)$, using $f_X(x)$

$$\mathbb{E}(X) = \int_0^I x f_X(x) dx = \int_0^I \frac{x}{I} \ln(I/x) dx$$
$$= \frac{I}{4}$$

(d) Evaluate $\mathbb{E}(X)$, using $X = Y \cdot (X/Y)$

If $Y \perp \!\!\! \perp X/Y$, it becomes easy, but true? Yes, because whatever Y is, the fraction X/Y does not depend on it.

$$\mathbb{E}(X) = \mathbb{E}(Y)\mathbb{E}(X/Y) = \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{4}$$

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(e) Evaluate $\mathbb{E}(X)$, using TET

$$0\mathbb{E}[X] = \int_{-\infty}^{\infty} f_Y(y)\mathbb{E}[X|Y=y]dy$$
$$= \int_{0}^{1} \frac{1}{l} \mathbb{E}[X|Y=y]dy = \int_{0}^{1} \frac{1}{l} \frac{y}{2}dy = \frac{l}{4}$$



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 Message. There are many ways to rearch our goal. Of crucial importance is how to find the best way!

Roadmap



36 / 32

- (1) Continuous Random Variable and PDF (Probability Density Function)
- (2) CDF (Cumulative Distribution Function)
- (3) Exponential RVs
- (4) Gaussian (Normal) RVs
- (5) Continuous RVs: Joint, Conditioning, and Independence
- (6) Bayes' rule for RVs

Bayes Rule for Continuous



37 / 32

- X: state/cause/original value $\rightarrow Y$: result/resulting action/noisy measurement
- Given: $\mathbb{P}(X)$ and $\mathbb{P}(Y|X)$ (cause \to result)
- Inference: $\mathbb{P}(X|Y)$?

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• A light bulb $Y \sim \exp(\lambda)$. However, there are some quality control problems. So, the parameter λ of Y is actually a random variable, denoted by Λ , which is $\Lambda \sim \mathcal{U}[1,3/2]$. We test a light bulb and record its lifetime.

L4(6) April 27, 2021 38 / 32



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- Question. What can we say about the underlying paramter λ ? In other words, what is $f_{\Lambda|Y}(\lambda|y)$?

April 27, 2021 38 / 32



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- $f_{\Lambda}(\lambda) = 2$ for $1 \le \lambda \le 3/2$ and $f_{Y|\Lambda}(y|\lambda) = pdf$ of $exp(\lambda)$. Then, the inference about the parameter given the lifetime of a light bulb is:

L4(6) April 27, 2021 38 / 32



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L4(6) April 27, 2021 38 / 32

Using Bayes Rule for Parameter Learning



39 / 32

- X: parameter → Y: result of my model
- Given: $\mathbb{P}(X)$ and $\mathbb{P}(Y|X)$ (parameter \to model)
- Inference: $\mathbb{P}(X|Y)$? Probabilistic feature of the parameter given the result of the model?

Example.

Using Bayes Rule for Parameter Learning



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Example.

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Using Bayes Rule for Parameter Learning



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Example.

- 1. Light bulb's lifetime $Y \sim \exp(\lambda)$. Given the lifetime y, the modified belief about λ ?
- 2. Romeo and Juliet start dating, but Romeo will be late by a random variable $Y \sim \mathcal{U}[0, \theta]$. Given the time of being late y, the modified belief about θ ?



K: discrete, Y: continuous



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• Inference of K given Y

• Inference of Y given K



K: discrete, Y: continuous

• Inference of K given Y

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$$f_Y(y) = \sum_{k'} p_K(k')f_{Y|K}(y|k')$$

Inference of Y given K



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$$p_K(k) = \int f_Y(y')p_{K|Y}(k|y')dy'$$

• Wait! $p_{K|Y}(k|y)$? Well-defined?

$$p_{K|Y}(k|y) = \frac{\mathbb{P}(K=k, Y=y)}{\mathbb{P}(Y=y)} = \frac{0}{0}$$

$p_{K|Y}(k|y)$?



• For small δ (in other words, taking the limit as $\delta \to 0$).

Let
$$A = \{K = k\}.$$

$$\frac{p_{K|Y}(k|y)}{\mathbb{P}(A|y \leq Y \leq y + \delta)} = \frac{\mathbb{P}(A)\mathbb{P}(y \leq Y \leq y + \delta|A)}{\mathbb{P}(y \leq Y \leq y + \delta)} \\
\approx \frac{\mathbb{P}(A)f_{Y|A}(y)\delta}{f_{Y}(y)\delta} \\
= \frac{\mathbb{P}(A)f_{Y|A}(y)}{f_{Y}(y)}$$

L4(6)

Example: Signal Detection (1)



42 / 32

Inference of discrete K given continuous Y:

$$p_{K|Y}(k|y) = \frac{p_K(k)f_{Y|K}(y|k)}{f_Y(y)}, \quad f_Y(y) = \sum_{k'} p_K(k')f_{Y|K}(y|k')$$



42 / 32

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- Y: measured signal with Gaussian noise, $Y=K+W,\ W\sim \mathcal{N}(0,1)$



April 27 2021

42 / 32

Inference of discrete K given continuous Y:

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- Your received signal = 0.7. What's your guess about the original signal?



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- Your received signal = 0.7. What's your guess about the original signal?
- Your received signal = -0.2. What's your guess about the original signal?



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- Y: measured signal with Gaussian noise, $Y = K + W, \ W \sim \mathcal{N}(0,1)$
- Your received signal = 0.7. What's your guess about the original signal? +1
- Your received signal = -0.2. What's your guess about the original signal? -1
- Your intuition: If positive received signal, +1. If negative received signal, -1. How can we mathematically verify this?



• $Y|\{K=1\} \sim \mathcal{N}(1,1)$ and $Y|\{K=-1\} \sim \mathcal{N}(-1,1)$. (Remind: linear transformation preserves normality.)



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43 / 32

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• Probability that K = 1, given Y = y? After some algebra,

$$p_{K|Y}(1|y) = \frac{1}{1 + e^{-2y}}$$



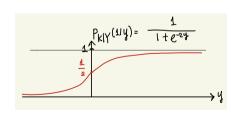
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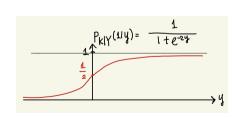
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• Probability that K = 1, given Y = y? After some algebra,

$$ho_{K|Y}(1|y) = rac{1}{1 + e^{-2y}}$$

• If y > 0, the inference probability for K = 1 exceeds $\frac{1}{2}$. So, original signal = 1.





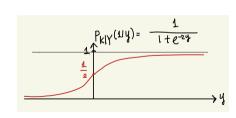
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- If y > 0, the inference probability for K = 1 exceeds $\frac{1}{2}$. So, original signal = 1.
- Similarly, compute $p_{K|Y}(-1|y)$ and then do the inference





Questions?

Review Questions



- 1) What is PDF and CDF?
- 2) Why do we need CDF?
- 3) What are joint/marginal/conditional PDFs?
- 4) Explain memorylessness of exponential random variables.
- Explain the version of Bayes' rule for continuous and mixed random variables.