Working parts:

ScienceMode state interrupt

Watchdog setup

Still To-Do:

EEPROM

Have GPS and Gyro; Need Mag, SD card, Radio

Ex) if return 1 -> check how many times GPS has failed;

If =3 -> **simulate gps**

If < 3 -> write (# of times +1) to EEPROM -> **need to wrap around and retry gps**

Simulate GPS