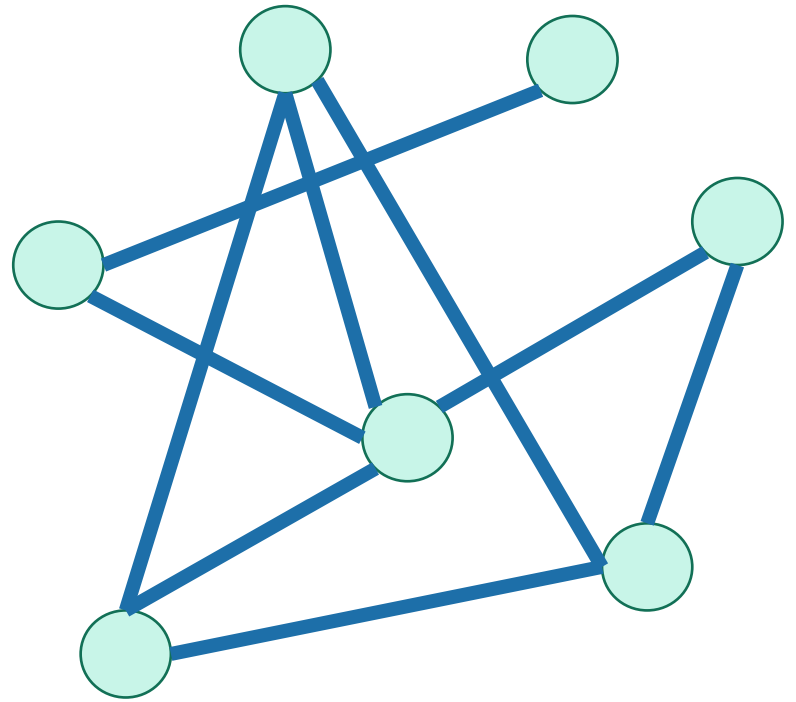


Graphs, BFS and DFS

Adapted from
Stanford CS161 course

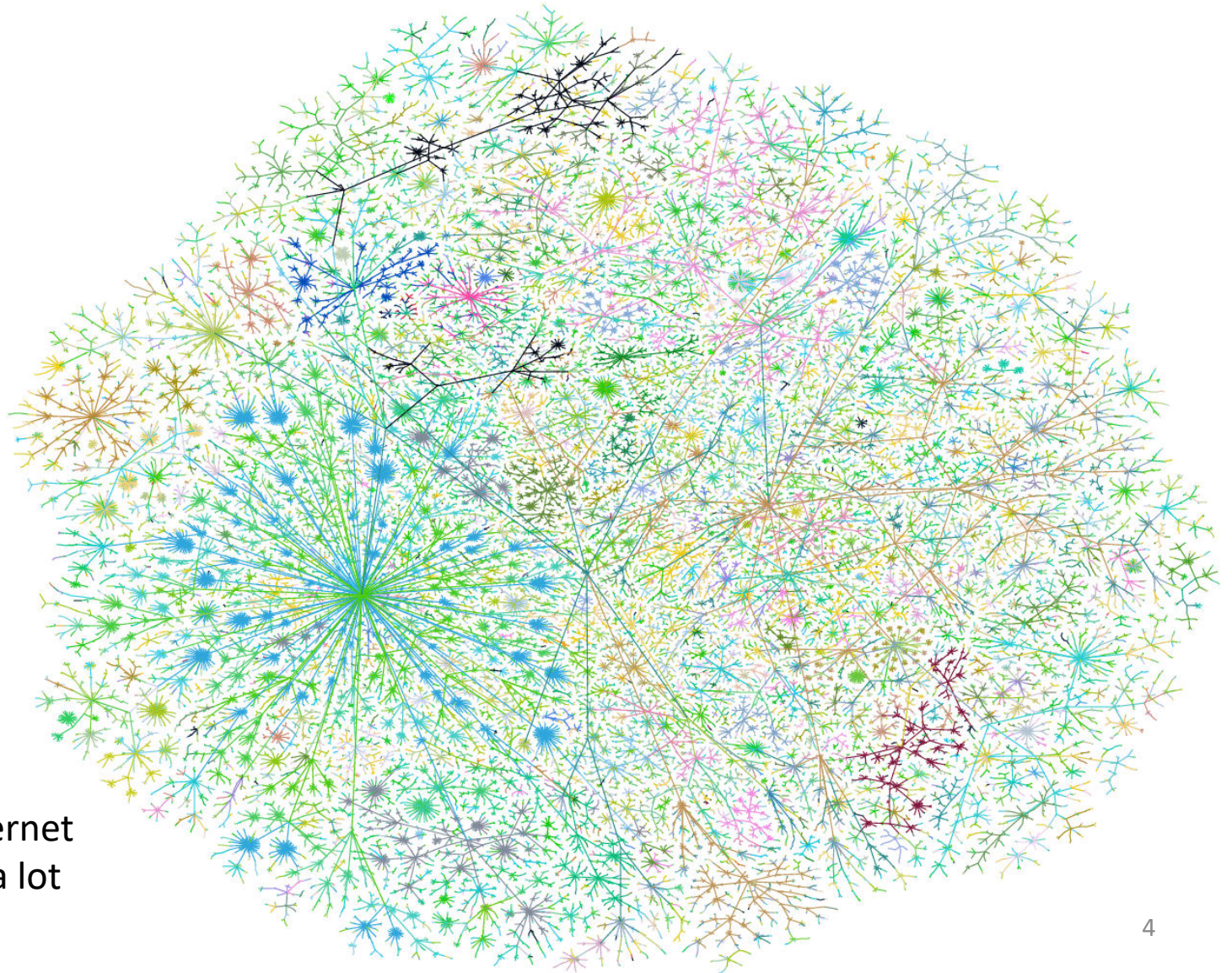
Outline

- Part 0: Graphs and terminology
- Part 1: Depth-first search
 - Application: topological sorting
 - Application: in-order traversal of BSTs
- Part 2: Breadth-first search
 - Application: shortest paths
 - Application: is a graph bipartite?



Part 0: Graphs

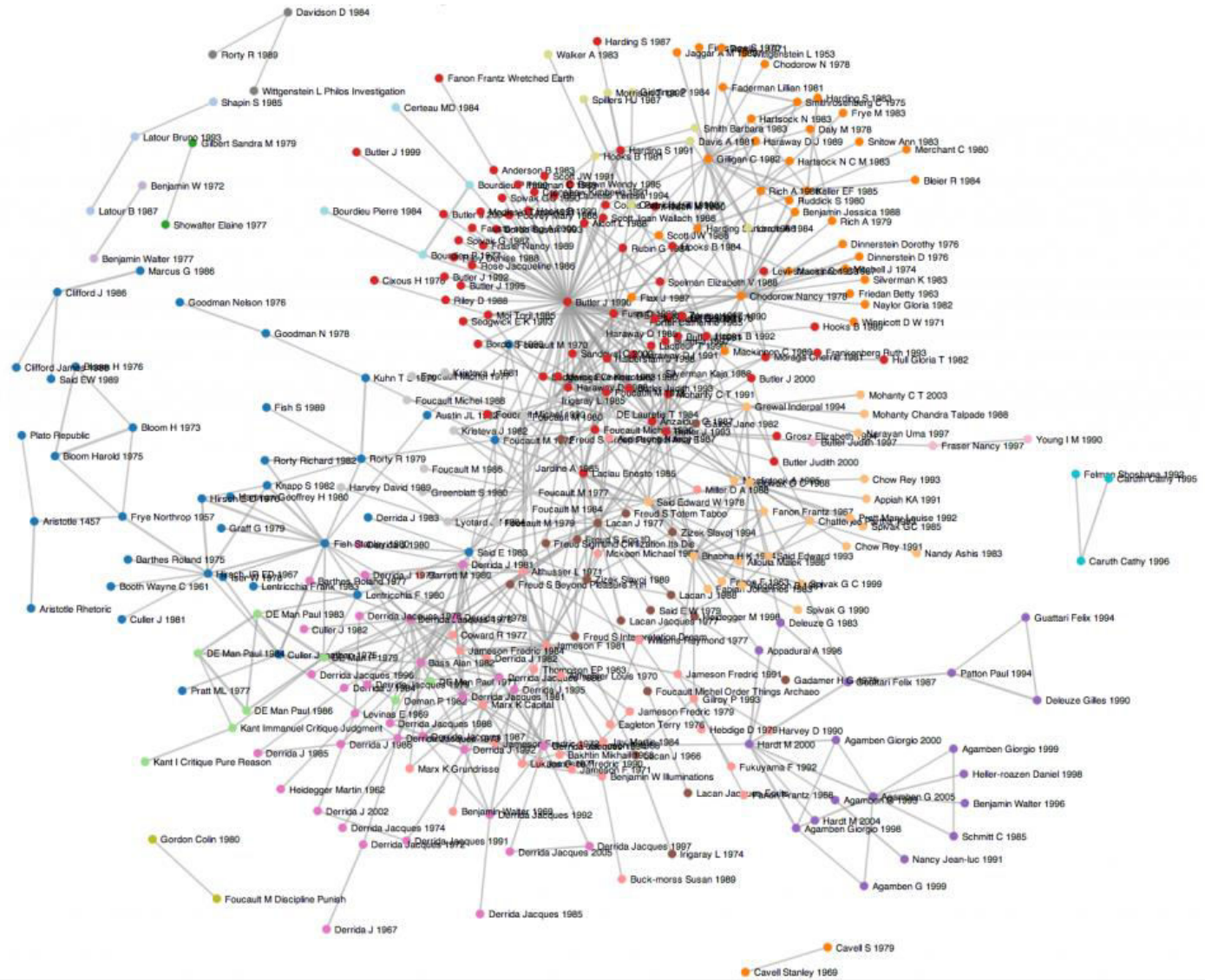
Graphs



Graph of the internet
(circa 1999...it's a lot
bigger now...)

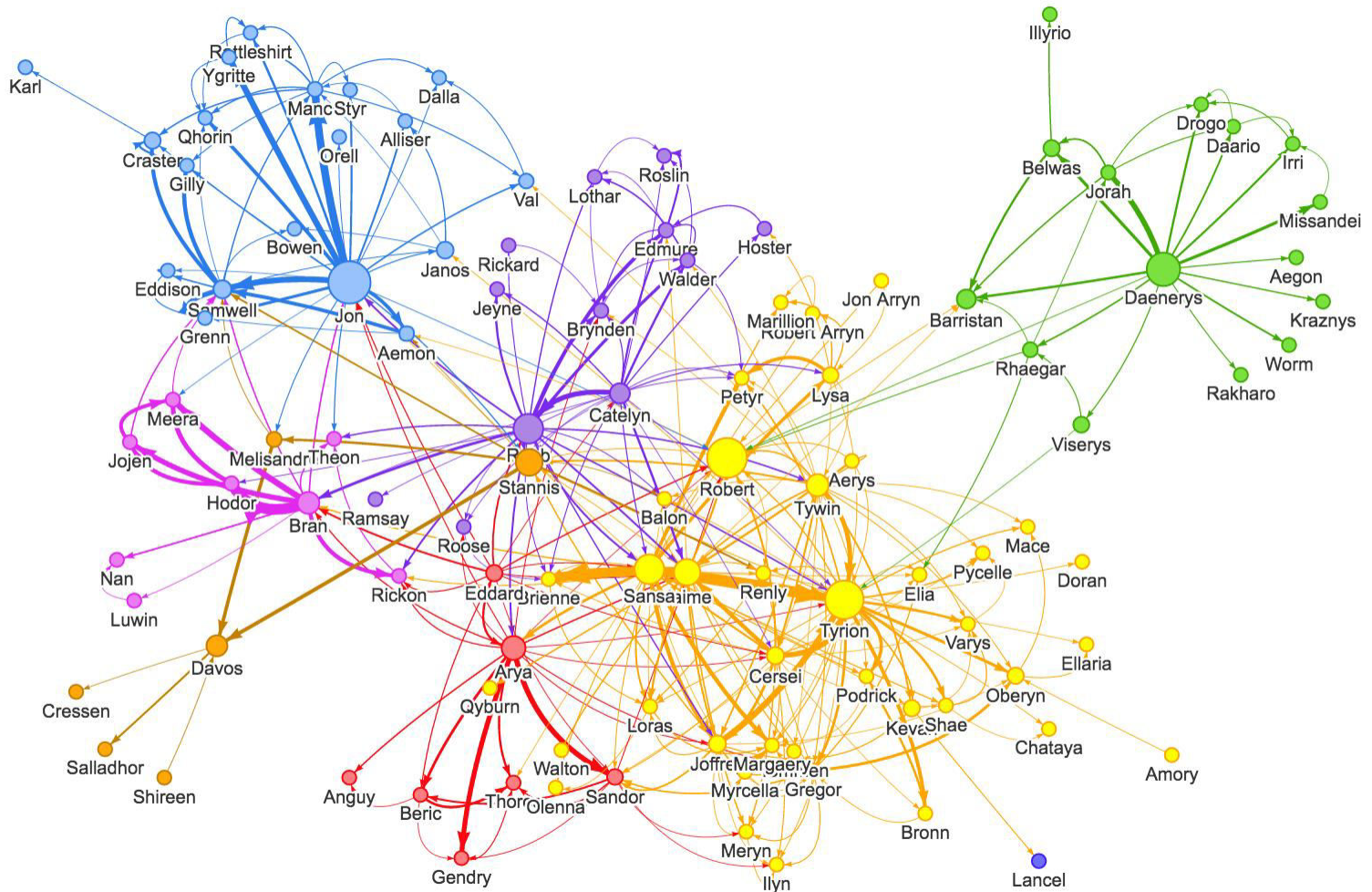
Graphs

Citation graph of
literary theory
academic papers



Graphs

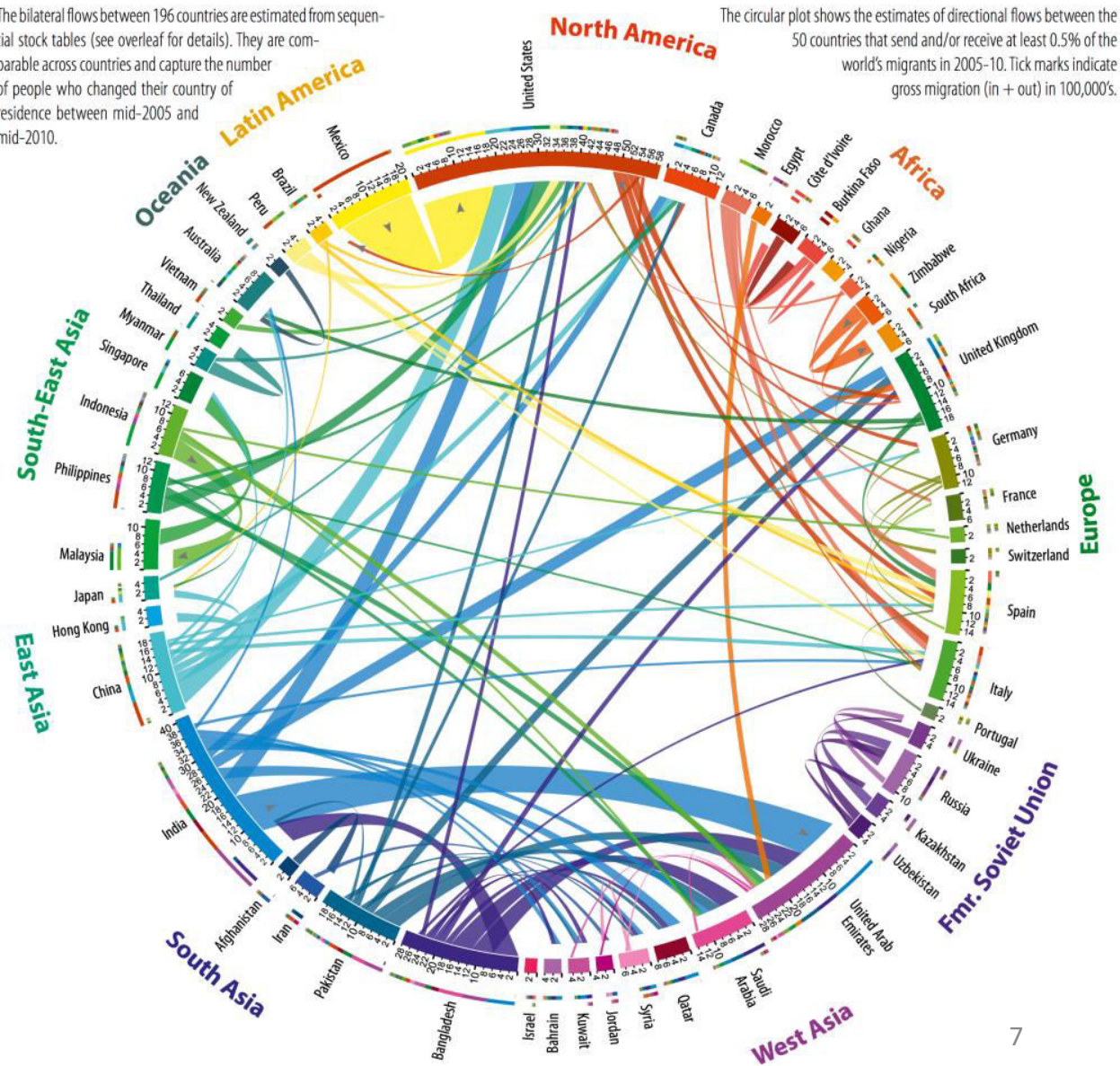
Game of Thrones Character Interaction Network



Graphs

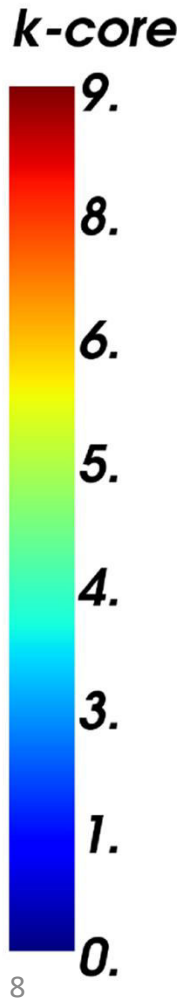
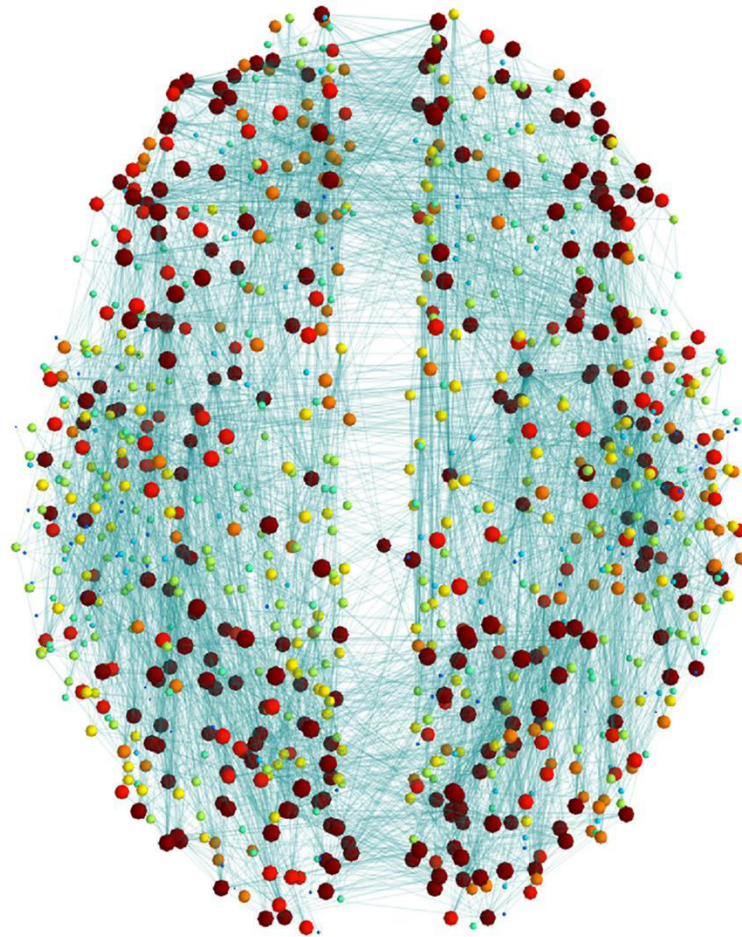
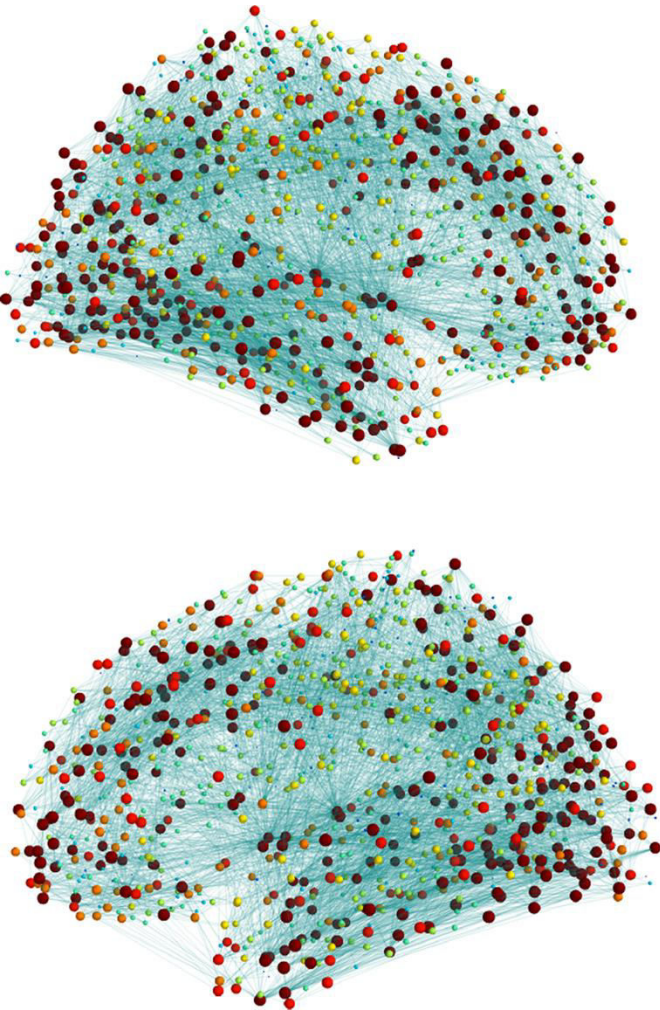
Immigration flows

The bilateral flows between 196 countries are estimated from sequential stock tables (see overleaf for details). They are comparable across countries and capture the number of people who changed their country of residence between mid-2005 and mid-2010.



Graphs

Neural connections
in the brain



Graphs

- **There are a lot of graphs.**
- We want to answer questions about them.
 - Efficient routing?
 - Community detection/clustering?
 - From pre-lecture exercise:
 - Computing Bacon numbers
 - Signing up for classes without violating pre-req constraints
 - How to distribute fish in tanks so that none of them will fight.
- This is what we'll do for the next several lectures.

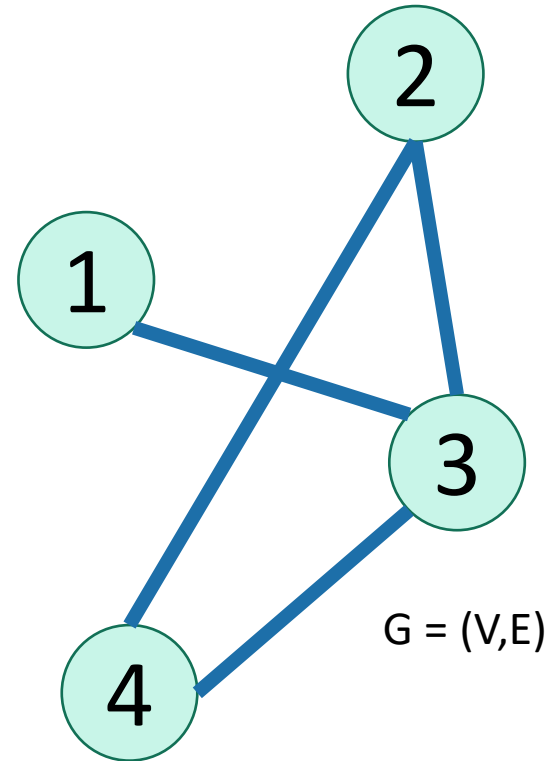
Undirected Graphs

- An undirected graph G has:

- A set V of vertices
- A set E of edges
- Formally, $G = (V, E)$

- Example

- $V = \{1, 2, 3, 4\}$
- $E = \{ \{1, 3\}, \{2, 4\}, \{3, 4\}, \{2, 3\} \}$



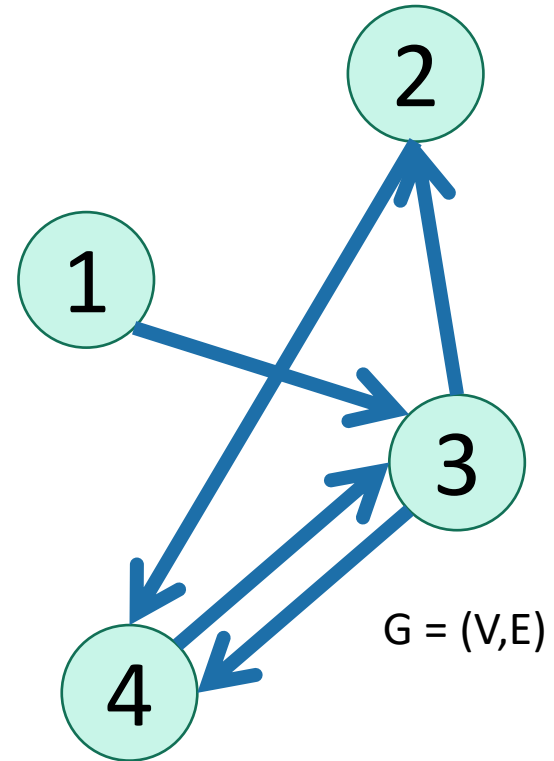
- The **degree** of vertex 4 is 2.
 - There are 2 edges coming out
- Vertex 4's **neighbors** are 2 and 3

Directed Graphs

- A directed graph G has:
 - A set V of vertices
 - A set E of **DIRECTED** edges
 - Formally, $G = (V, E)$

- Example

- $V = \{1, 2, 3, 4\}$
- $E = \{ (1, 3), (2, 4), (3, 4), (4, 3), (3, 2) \}$

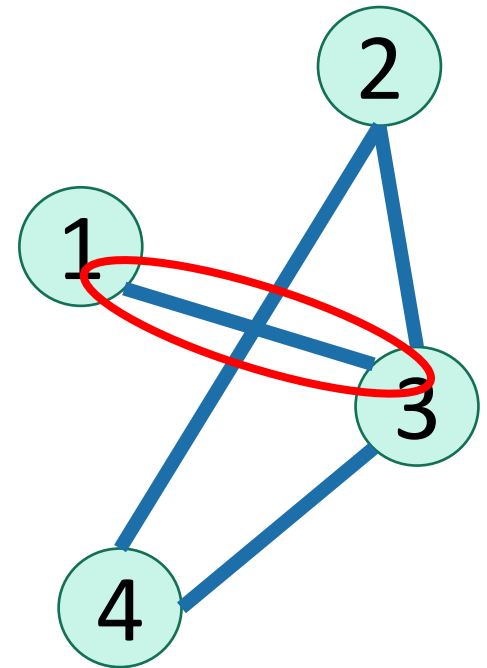


- The **in-degree** of vertex 4 is 2.
- The **out-degree** of vertex 4 is 1.
- Vertex 4's **incoming neighbors** are 2, 3
- Vertex 4's **outgoing neighbor** is 3.

How do we represent graphs?

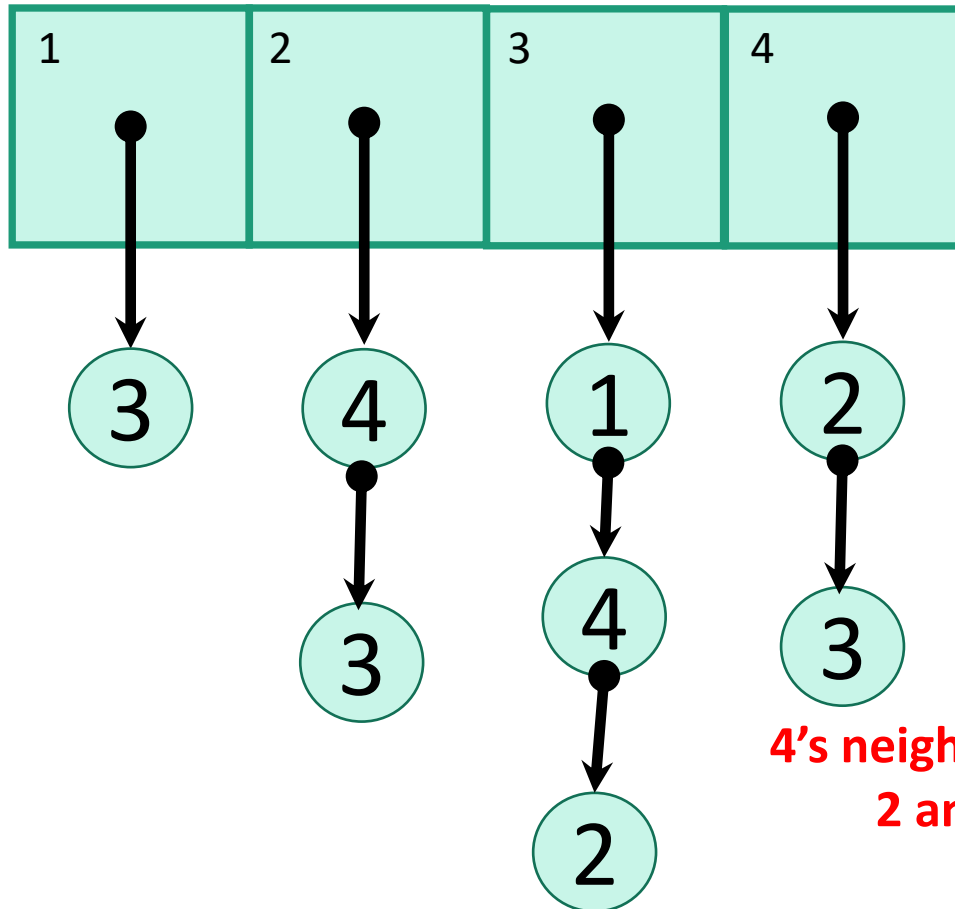
- Option 1: adjacency matrix

	1	2	3	4
1	0	0	1	0
2	0	0	1	1
3	1	1	0	1
4	0	1	1	0

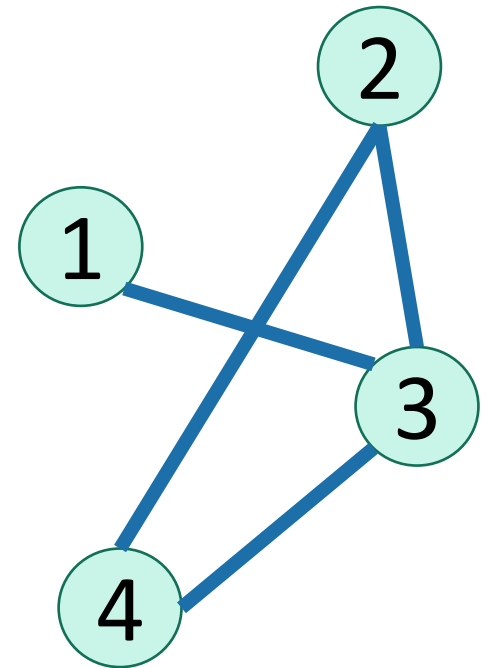


How do we represent graphs?

- Option 2: adjacency lists.



**4's neighbors are
2 and 3**



How would you
modify this for
directed graphs?



In either case

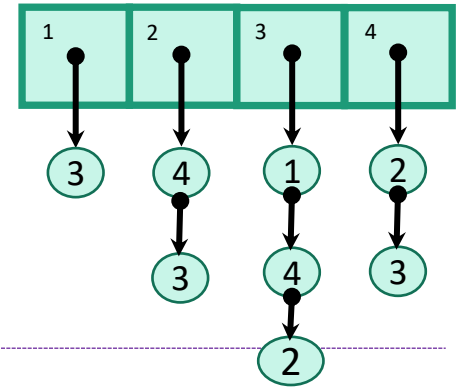
- Vertices can store other information
 - Attributes (name, IP address, ...)
 - helper info for algorithms that we will perform on the graph
- Basic operations:
 - **Edge Membership**: Is edge e in E ?
 - **Neighbor Query**: What are the neighbors of vertex v ?

Trade-offs

Say there are n vertices
and m edges.

$$\begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

Generally better for **sparse**
graphs (where $m \ll n^2$)



Edge membership
Is $e = \{v, w\}$ in E ?

$O(1)$

$O(\deg(v))$ or
 $O(\deg(w))$

Neighbor query
Give me v 's neighbors.

$O(n)$

$O(\deg(v))$

Space requirements

$O(n^2)$

$O(n + m)$

See Lecture 9 IPython notebook for an actual
implementation!

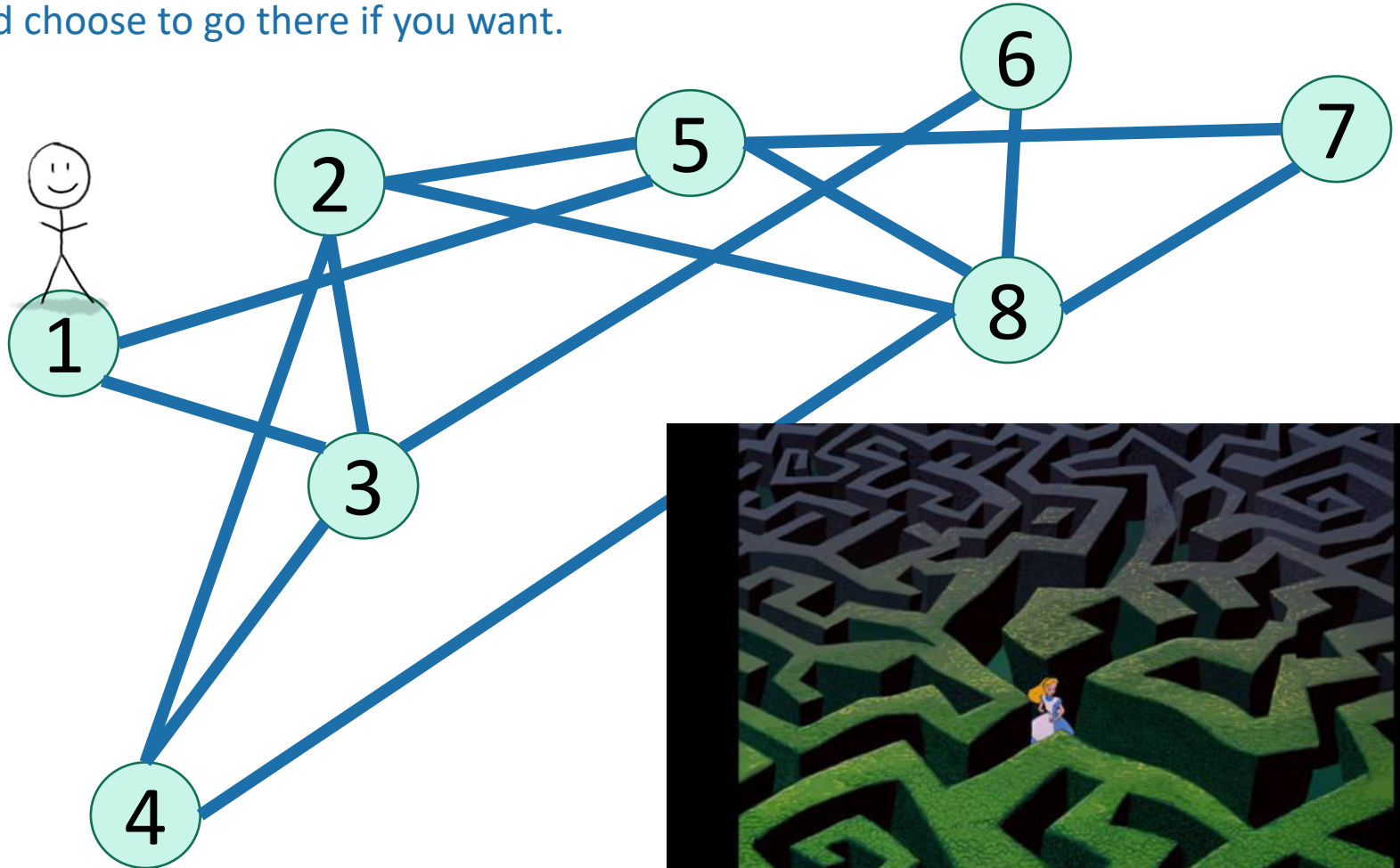
We'll assume this
representation for
the rest of the class

Part 1: Depth-first search

labyrinth

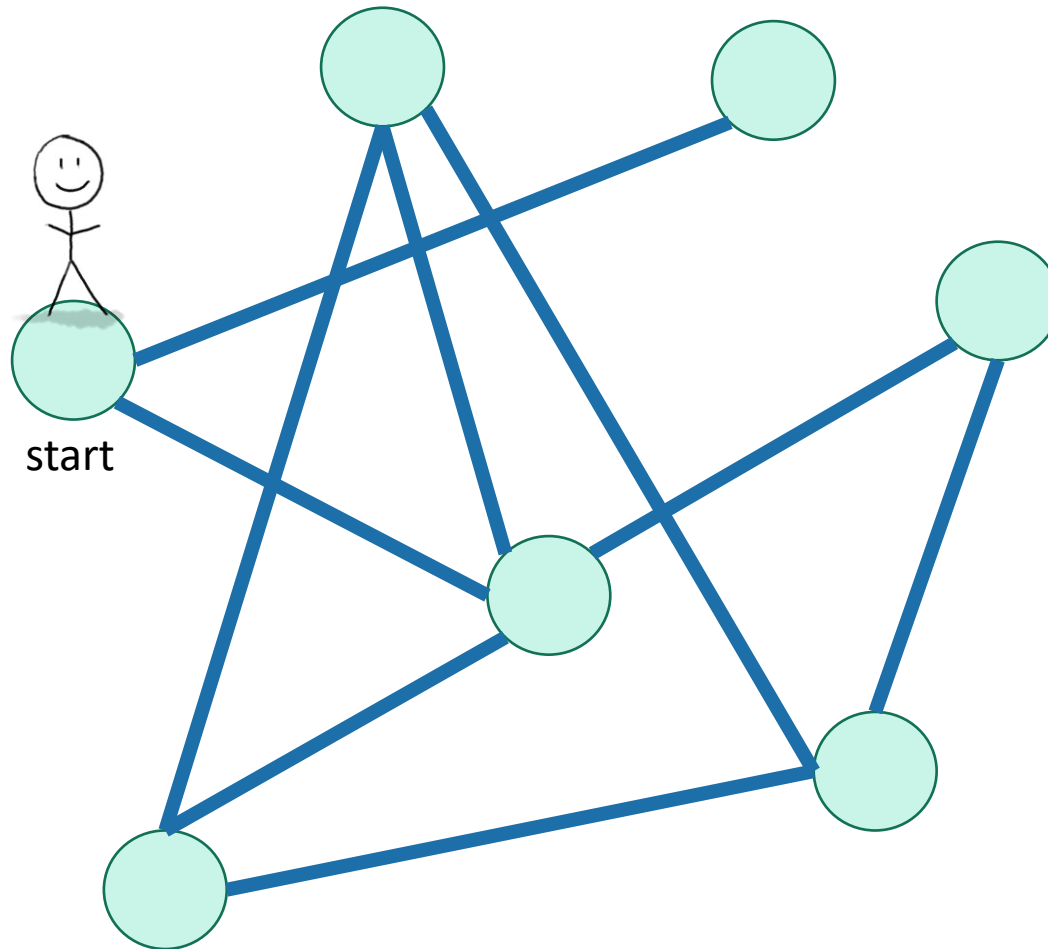
How do we explore a graph?




At each node, you can get a list of neighbors,
and choose to go there if you want.



Depth First Search

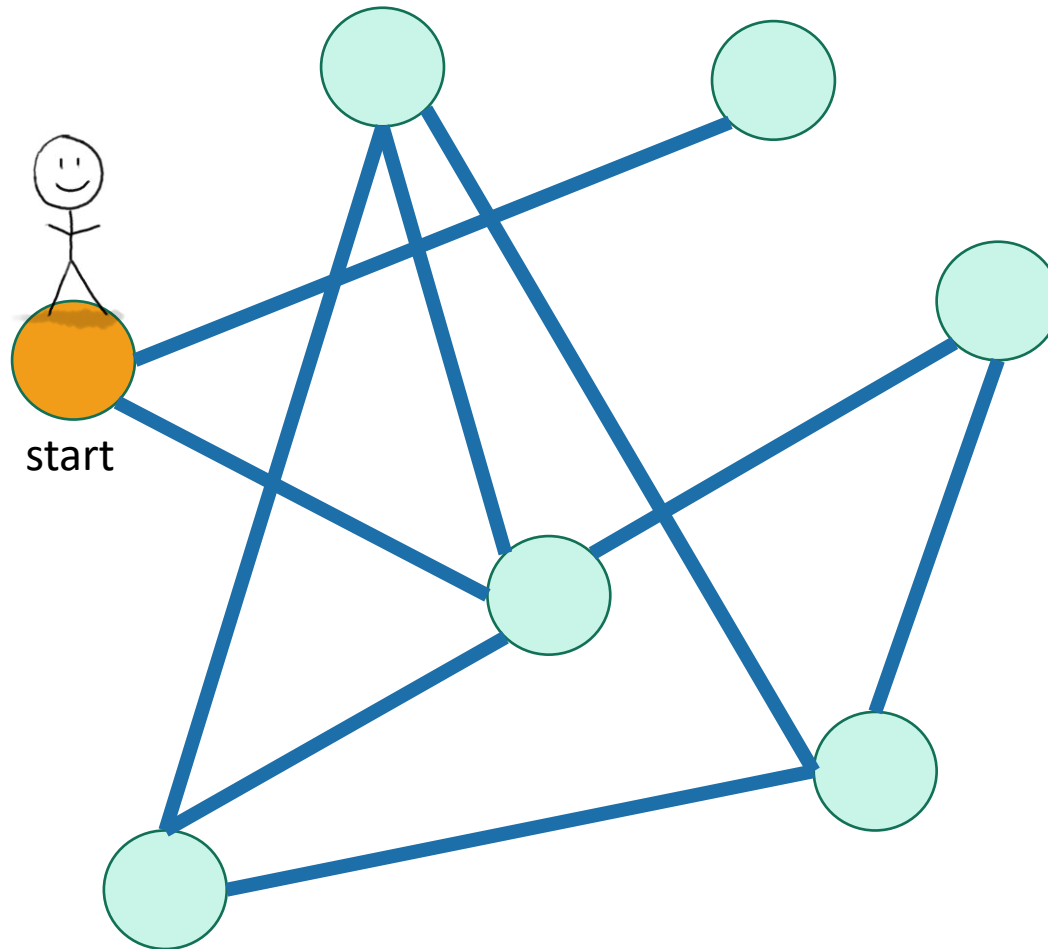
Exploring a labyrinth with chalk and a piece of string






-  Not been there yet
-  Been there, haven't explored all the paths out.
-  Been there, have explored all the paths out.

Depth First Search

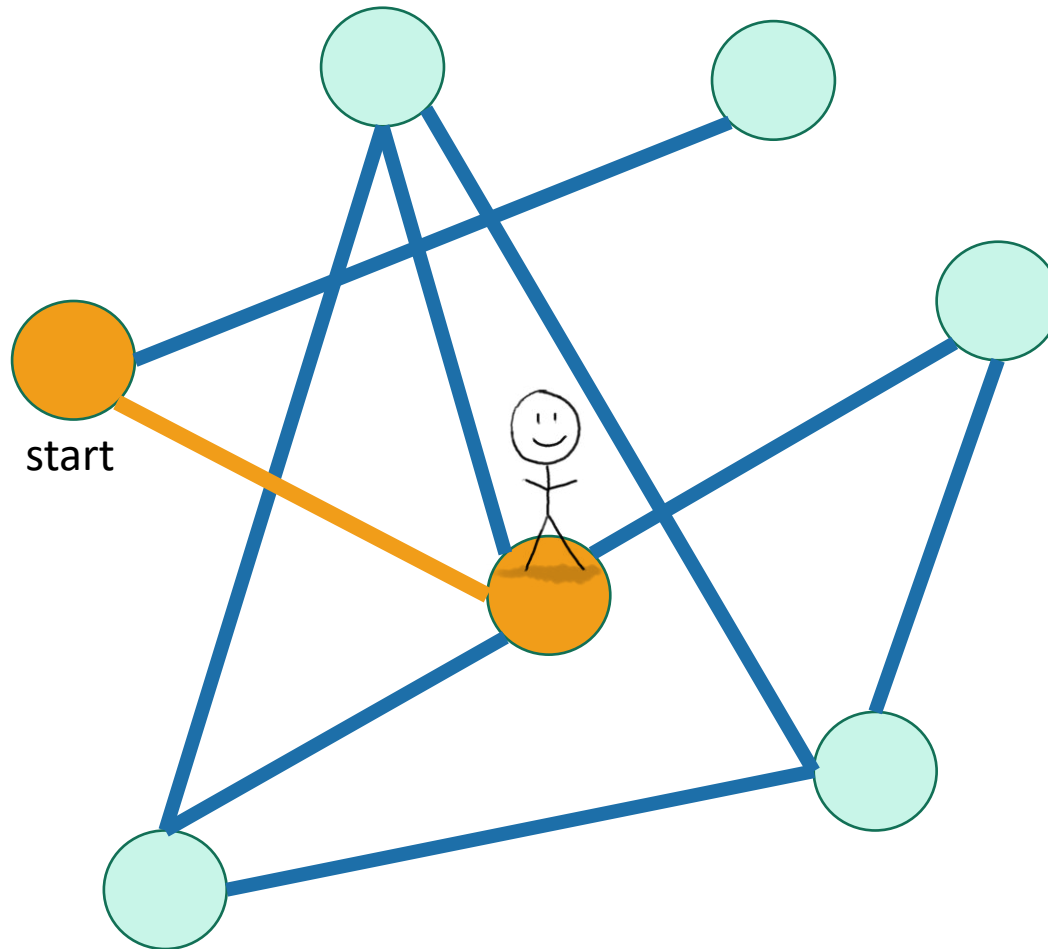
Exploring a labyrinth with chalk and a piece of string






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Depth First Search

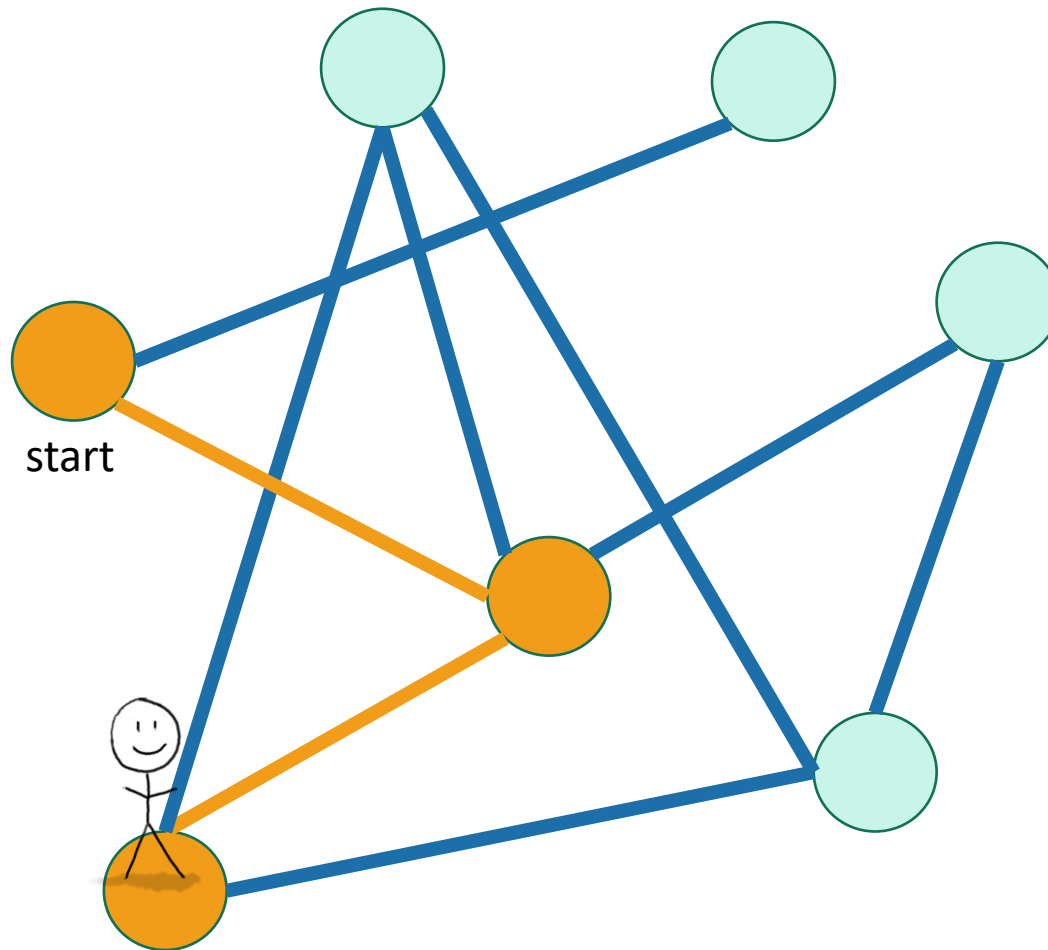
Exploring a labyrinth with chalk and a piece of string






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Depth First Search

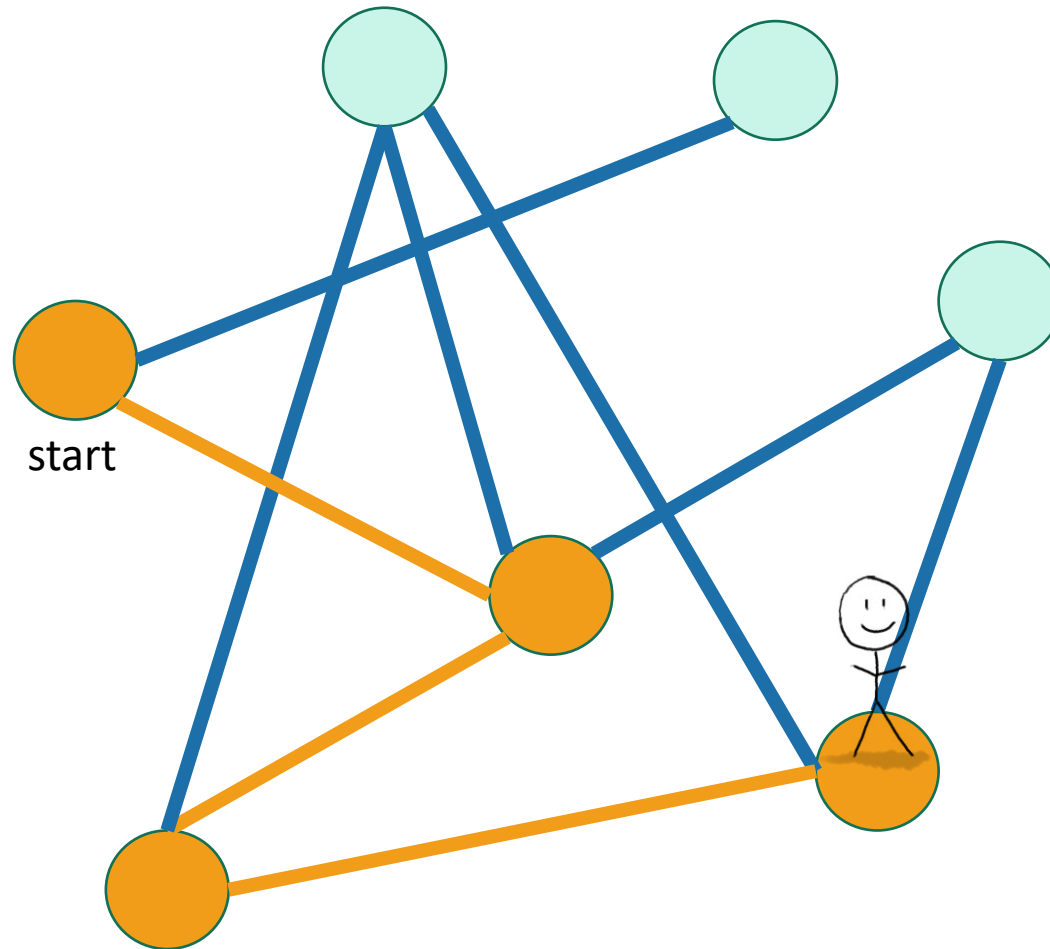
Exploring a labyrinth with chalk and a piece of string






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Depth First Search

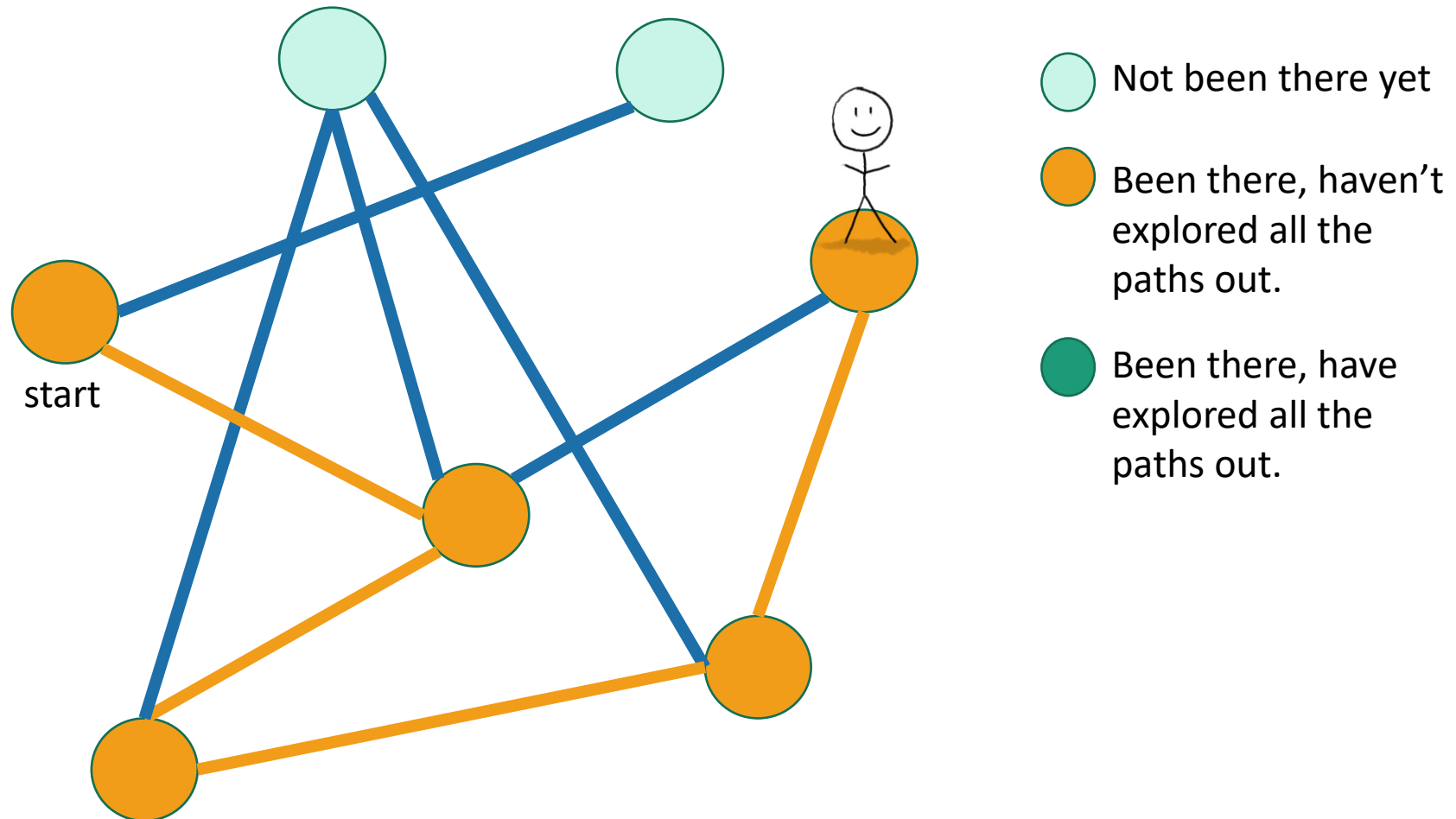
Exploring a labyrinth with chalk and a piece of string



-  Not been there yet
-  Been there, haven't explored all the paths out.
-  Been there, have explored all the paths out.

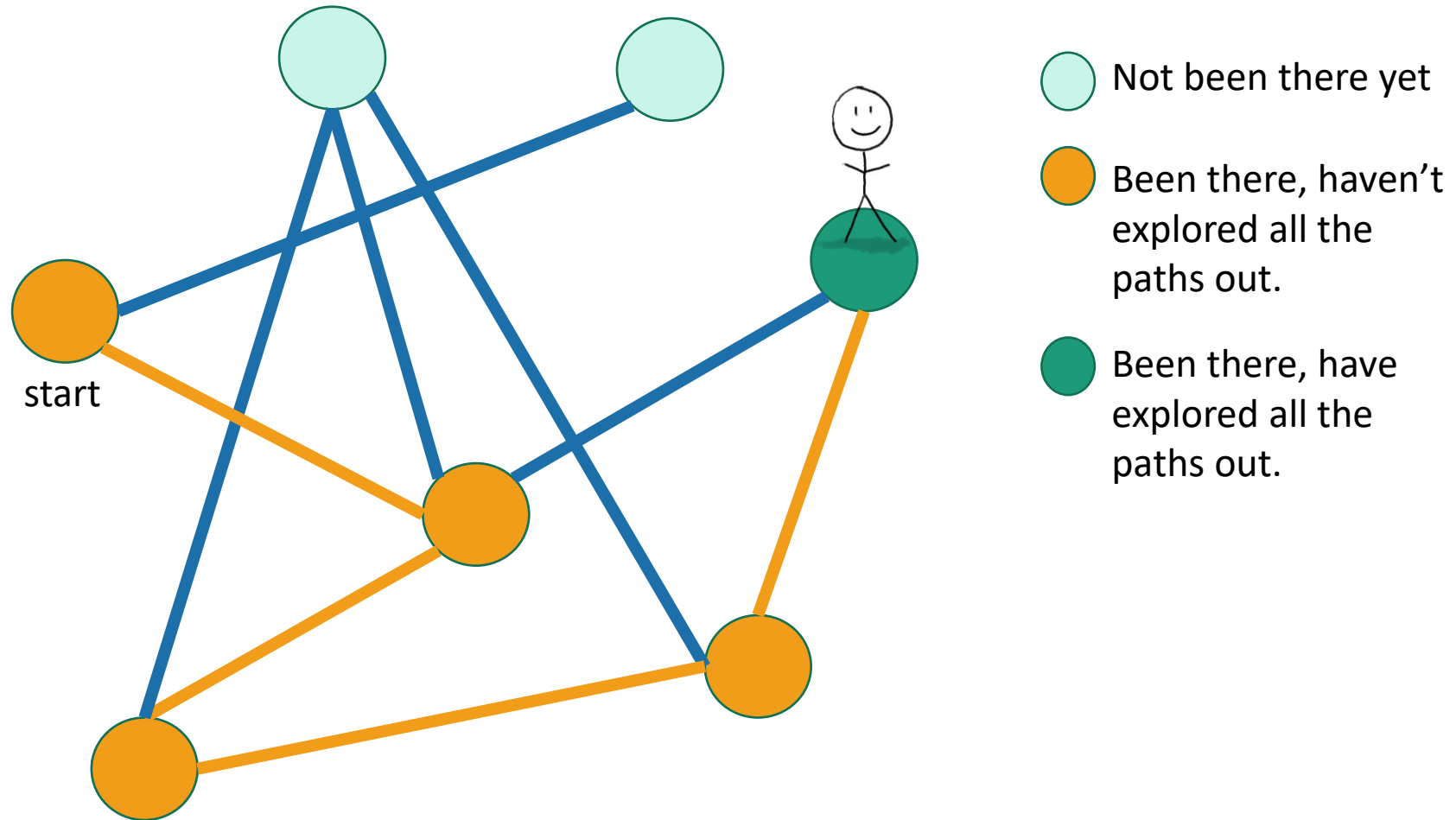
Depth First Search

Exploring a labyrinth with chalk and a piece of string



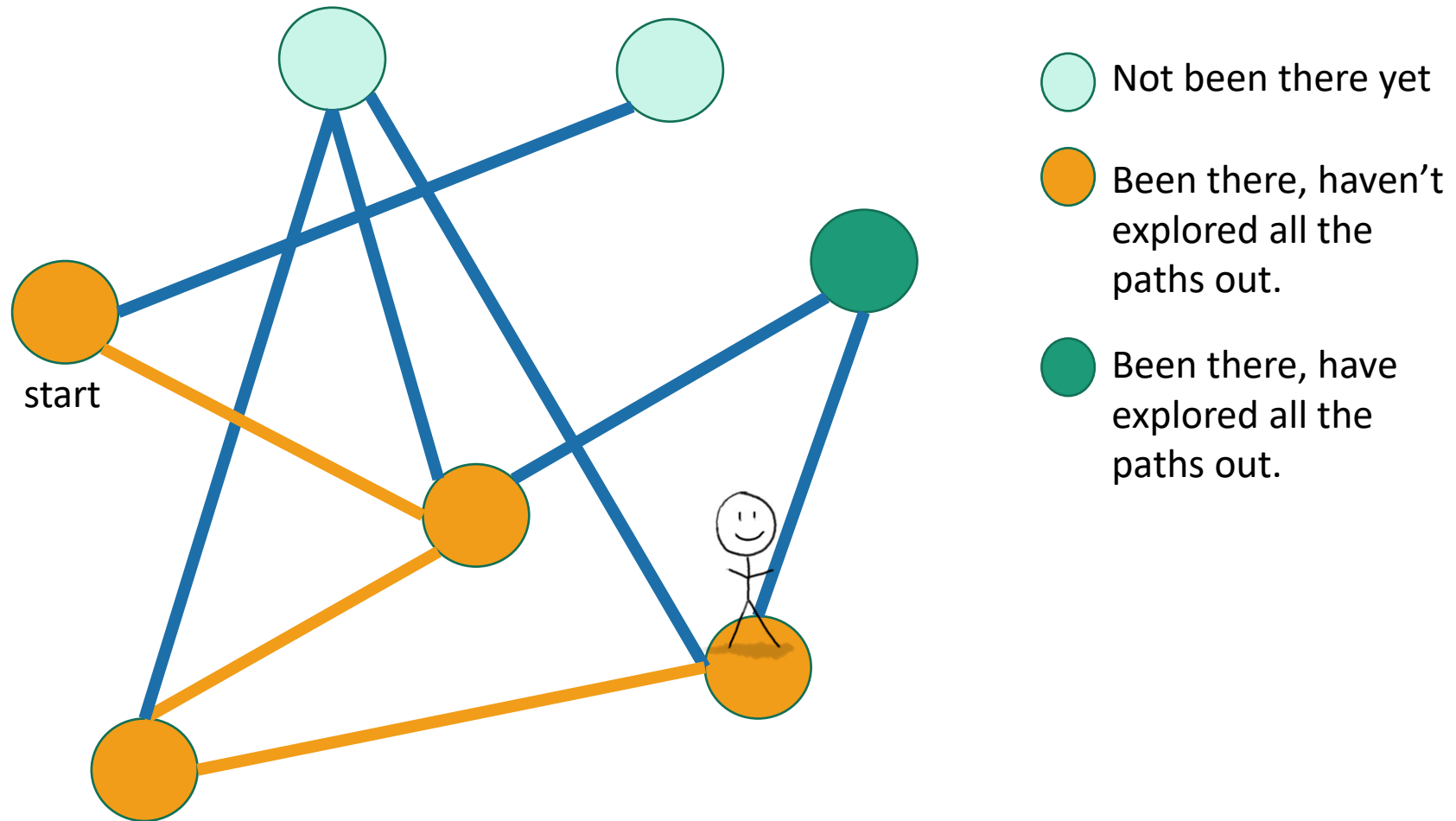
Depth First Search

Exploring a labyrinth with chalk and a piece of string



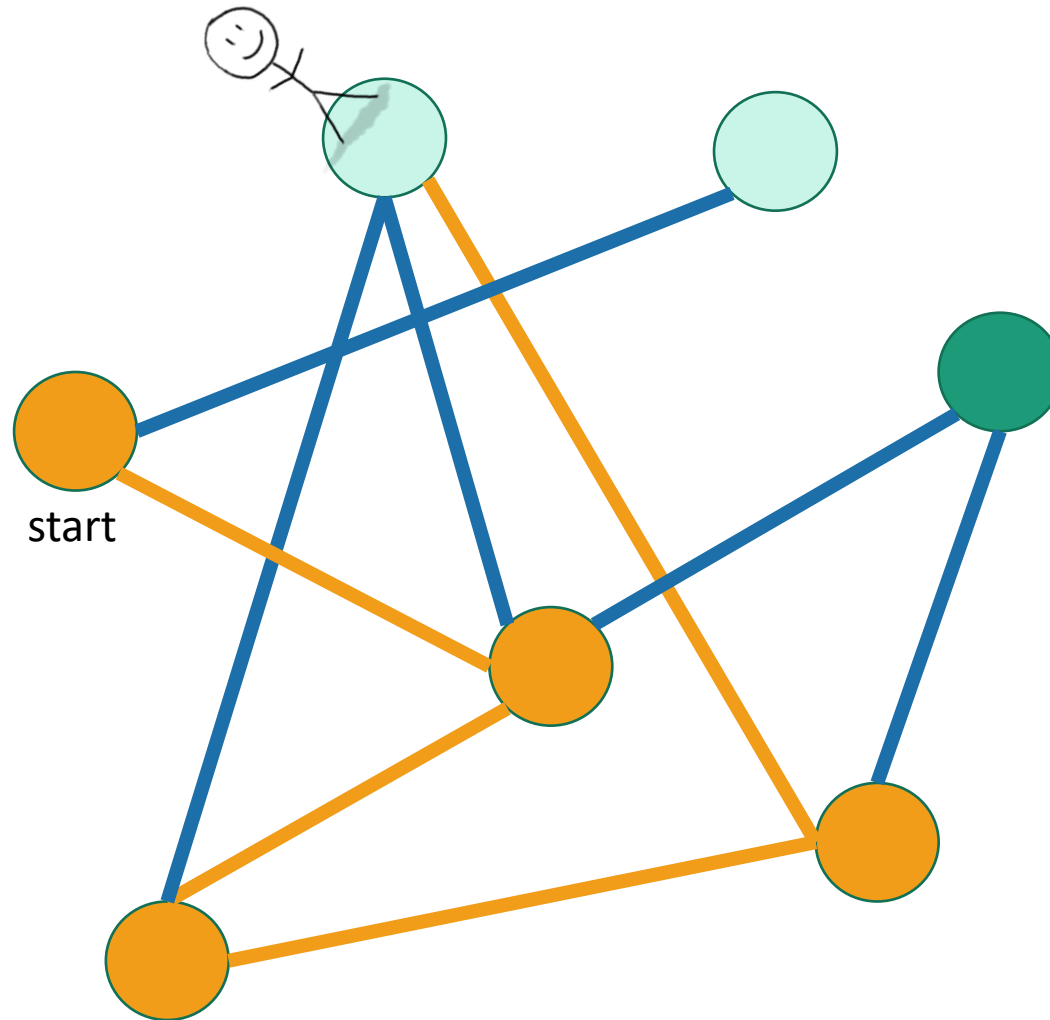
Depth First Search




Exploring a labyrinth with chalk and a piece of string



Depth First Search

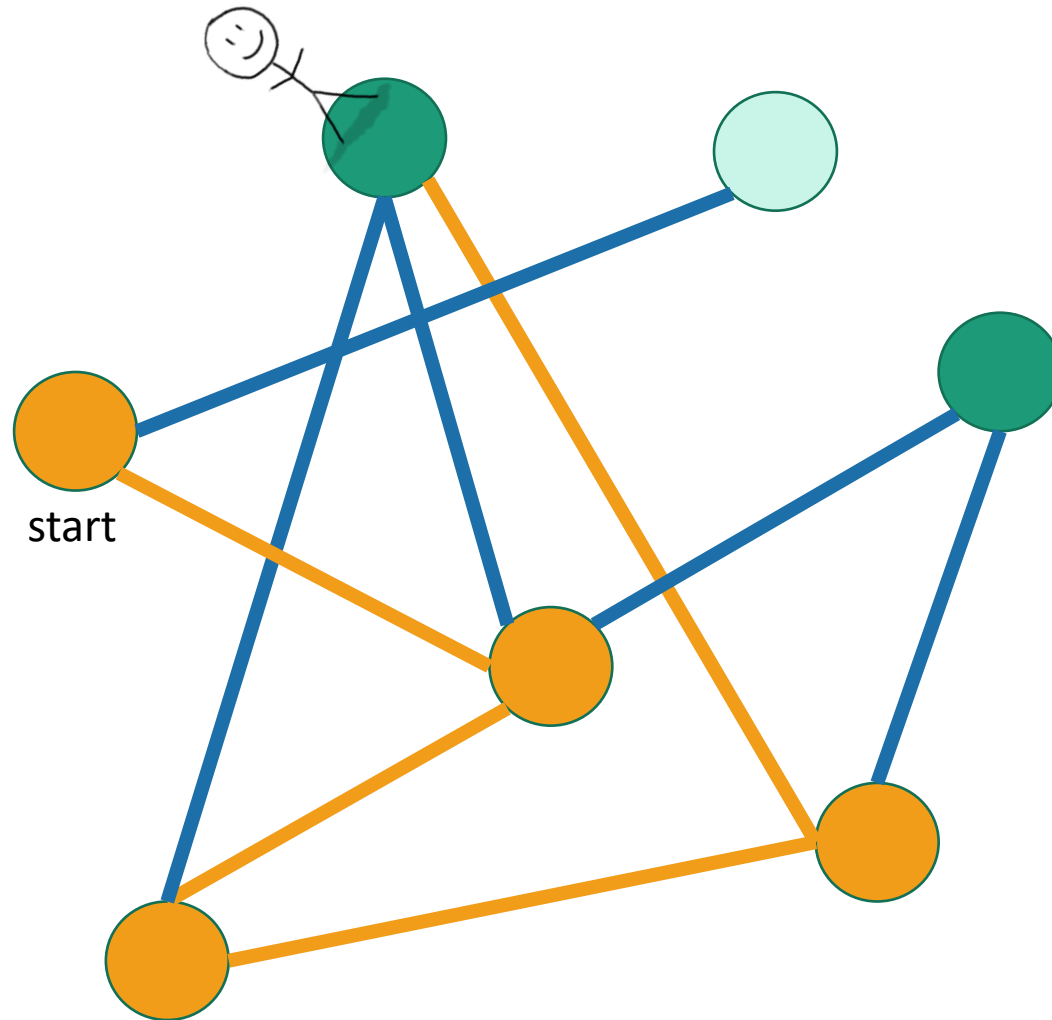
Exploring a labyrinth with chalk and a piece of string






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Depth First Search

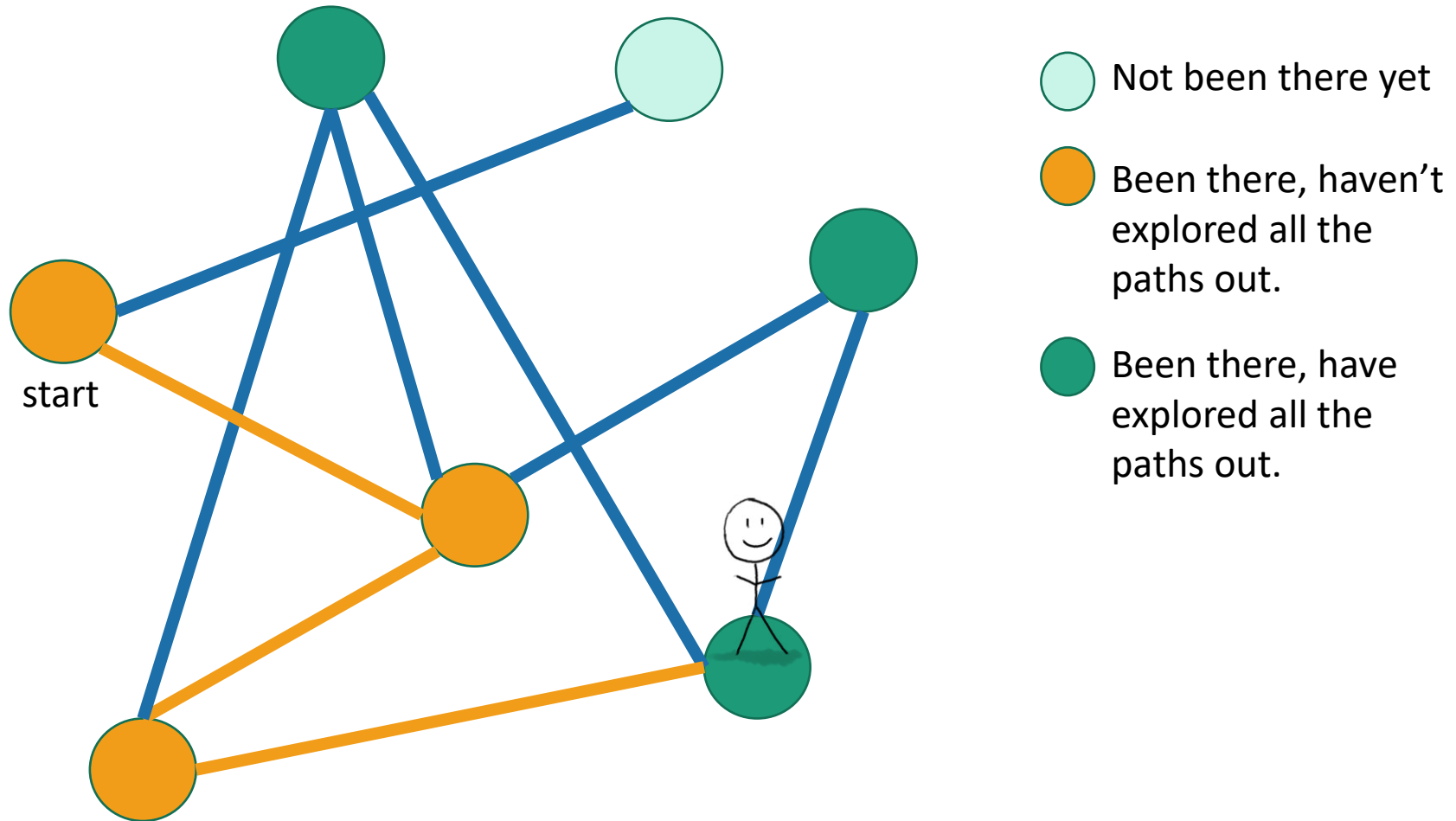
Exploring a labyrinth with chalk and a piece of string



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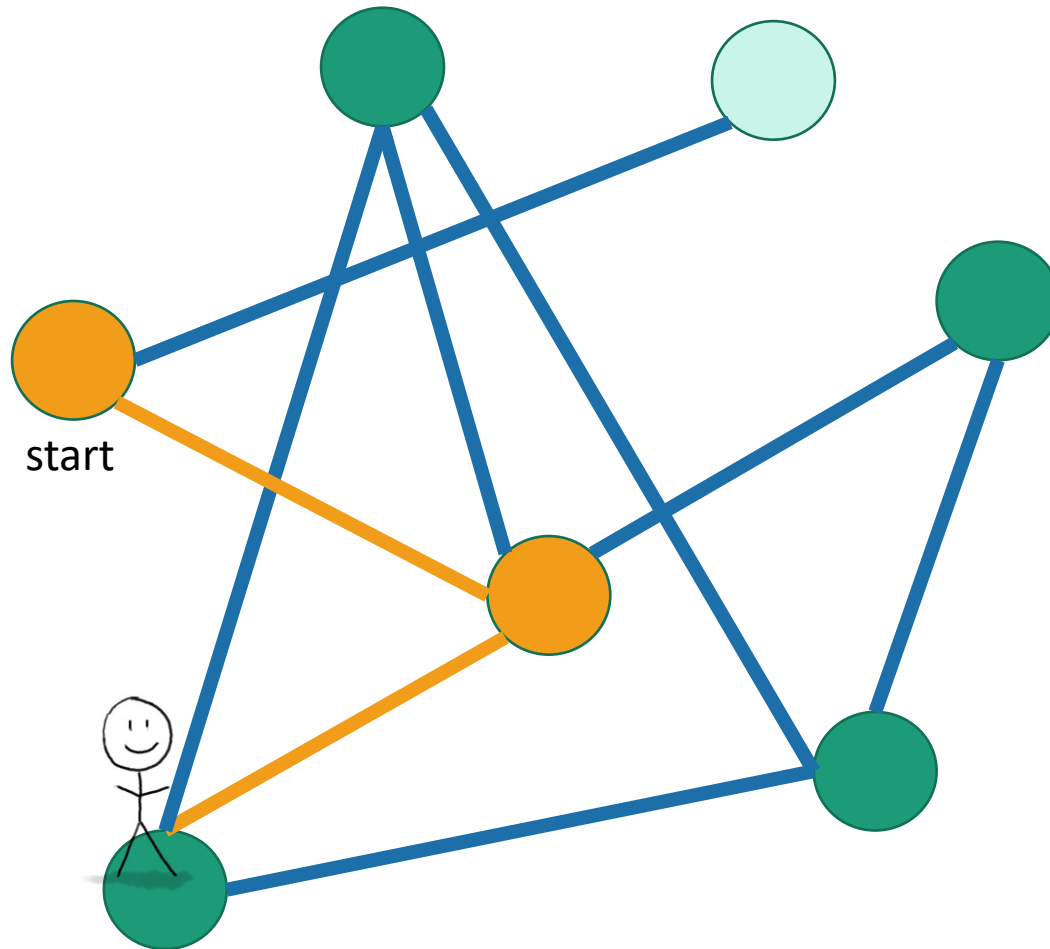
Depth First Search




Exploring a labyrinth with chalk and a piece of string



Depth First Search

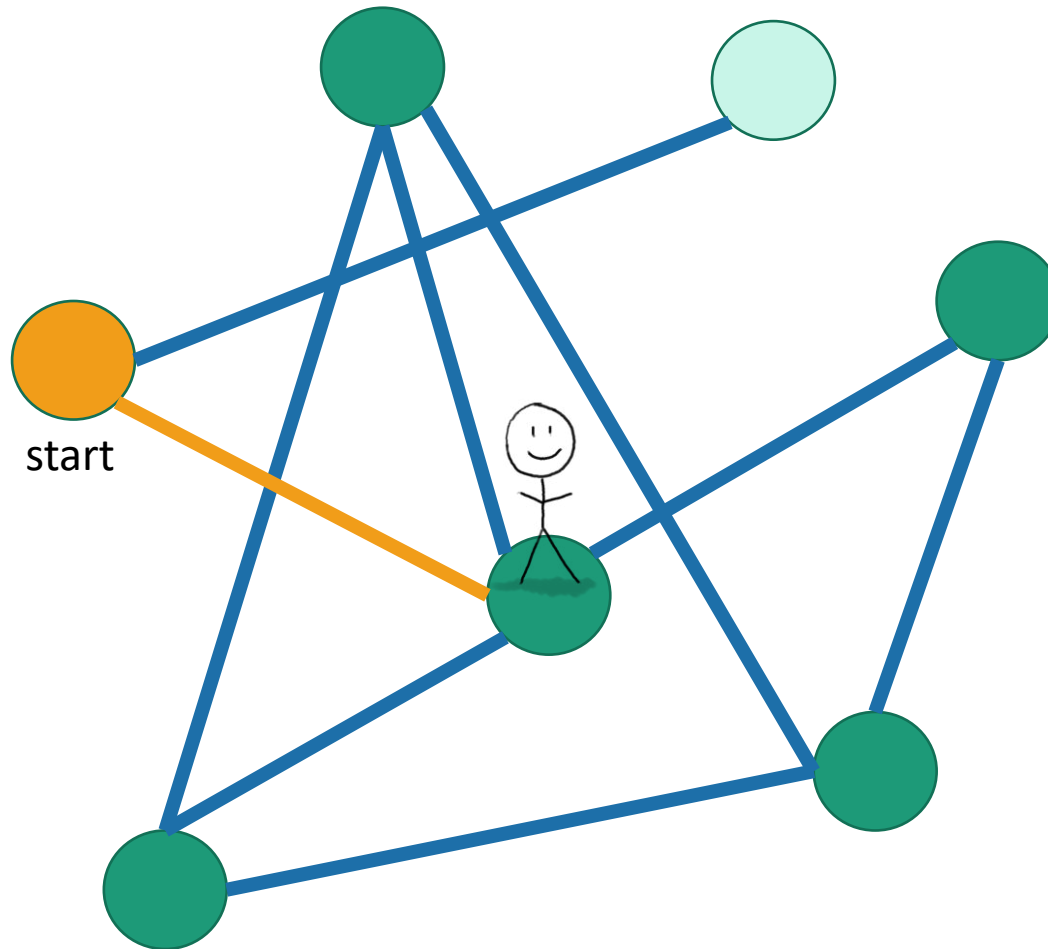
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Depth First Search

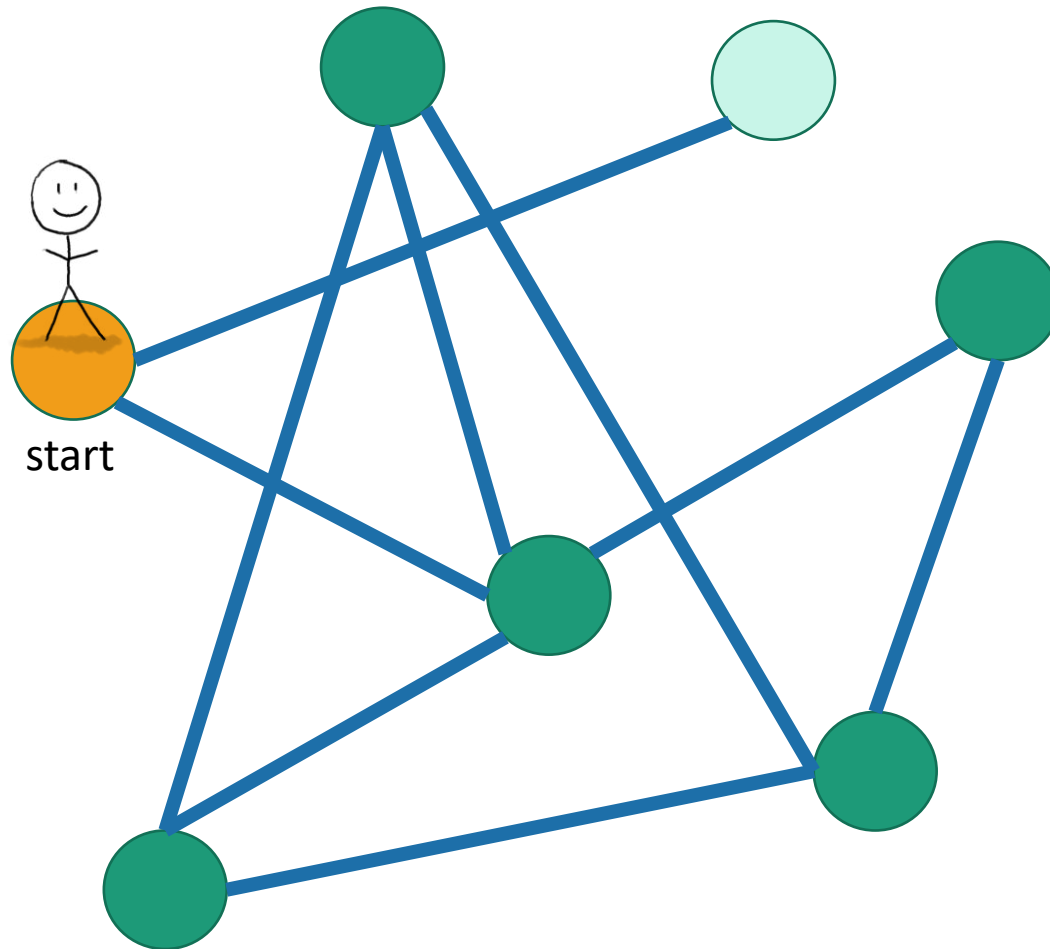
Exploring a labyrinth with chalk and a piece of string






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Depth First Search

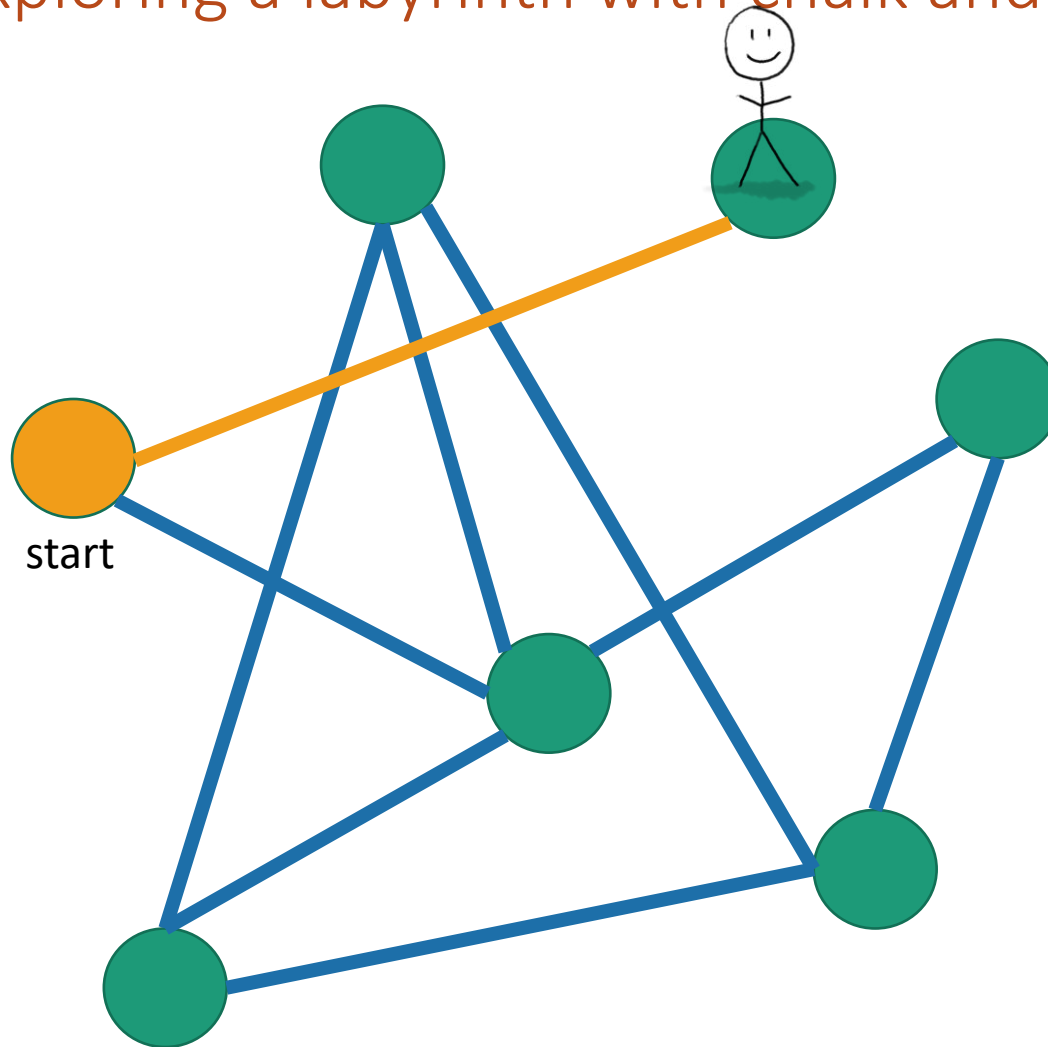
Exploring a labyrinth with chalk and a piece of string






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Depth First Search

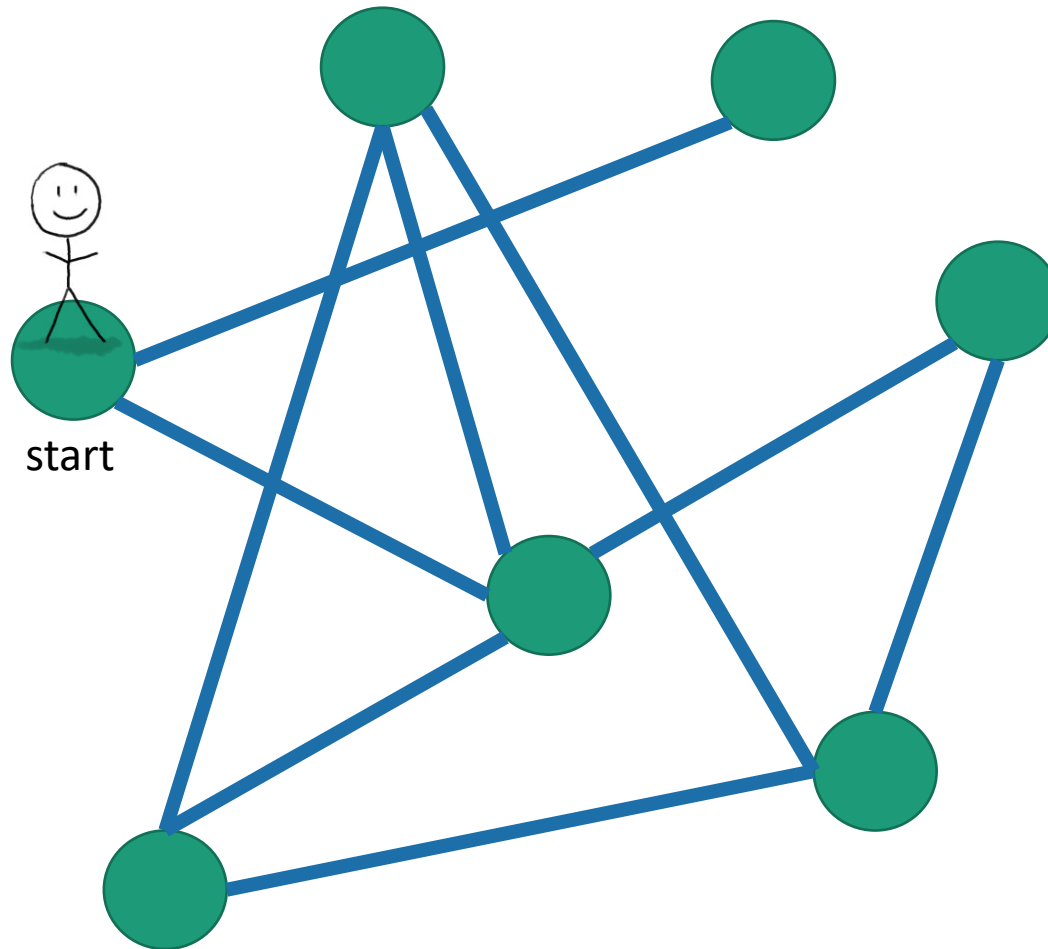
Exploring a labyrinth with chalk and a piece of string






-  Not been there yet
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-  Been there, have explored all the paths out.

Depth First Search

Exploring a labyrinth with chalk and a piece of string






-  Not been there yet
-  Been there, haven't explored all the paths out.
-  Been there, have explored all the paths out.

*Labyrinth:
explored!*

Depth First Search

Exploring a labyrinth with pseudocode

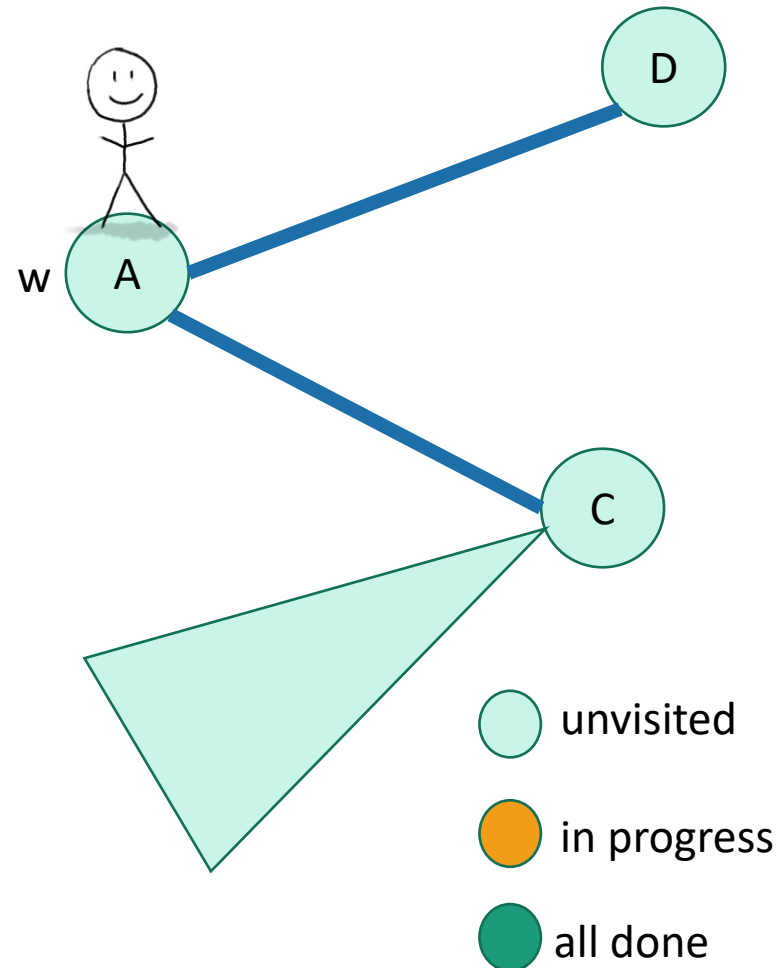
- Each vertex keeps track of whether it is:
 - Unvisited 
 - In progress 
 - All done 
- Each vertex will also keep track of:
 - The time we **first enter it**.
 - The time we finish with it and mark it **all done**.



You might have seen other ways to implement DFS than what we are about to go through. This way has more bookkeeping – the bookkeeping will be useful later!

Depth First Search

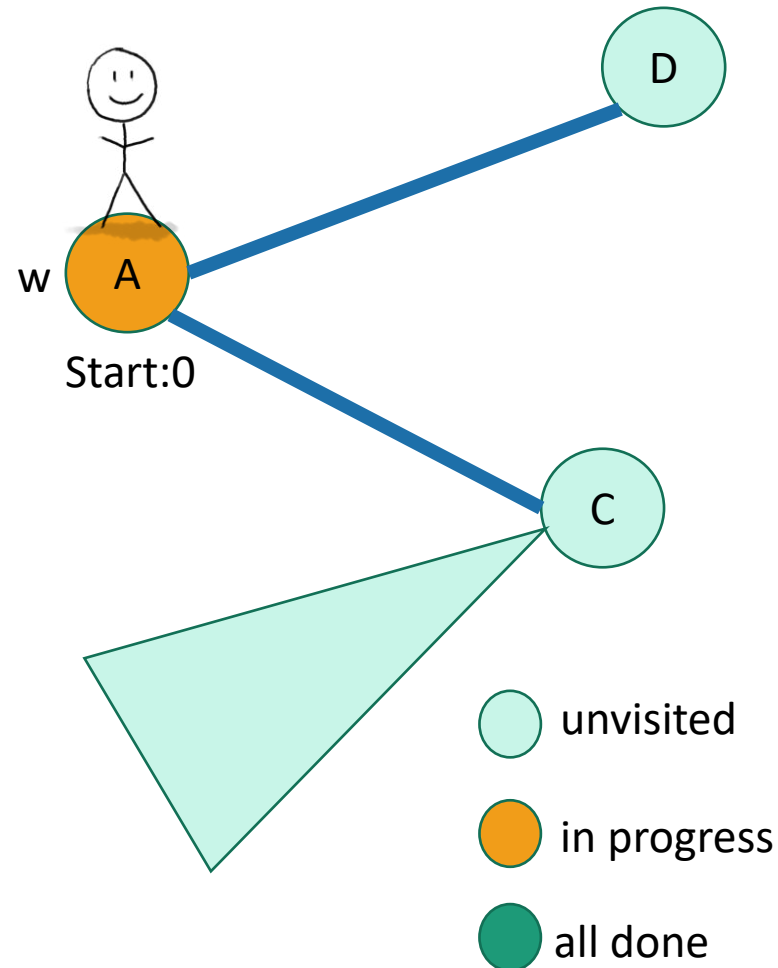
currentTime = 0



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

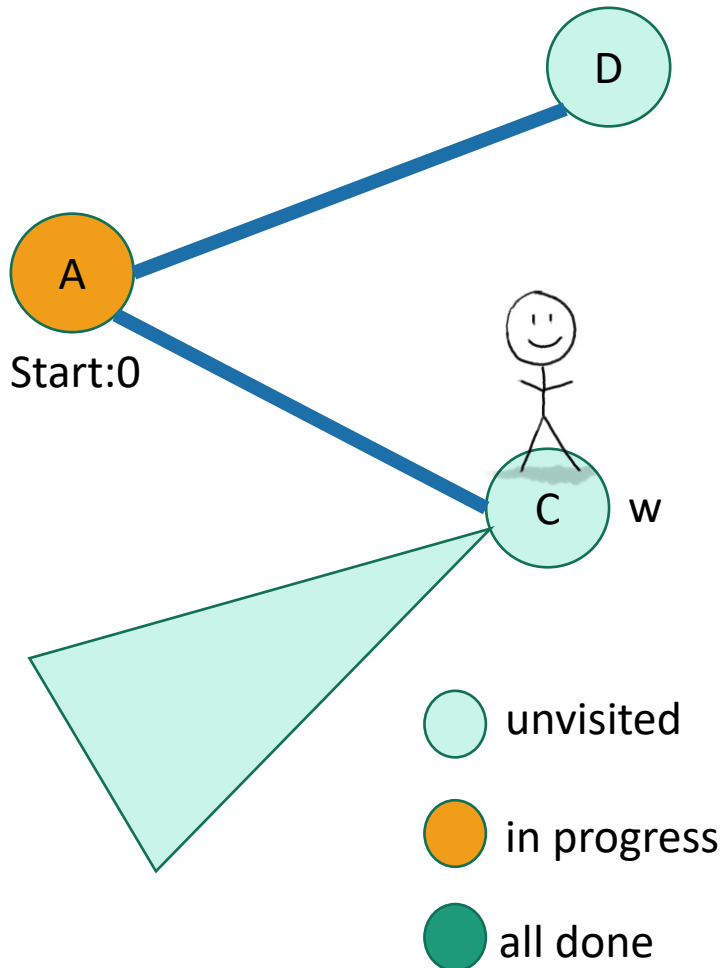
currentTime = 1



- **DFS(w, currentTime):**
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS(v, currentTime)**
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

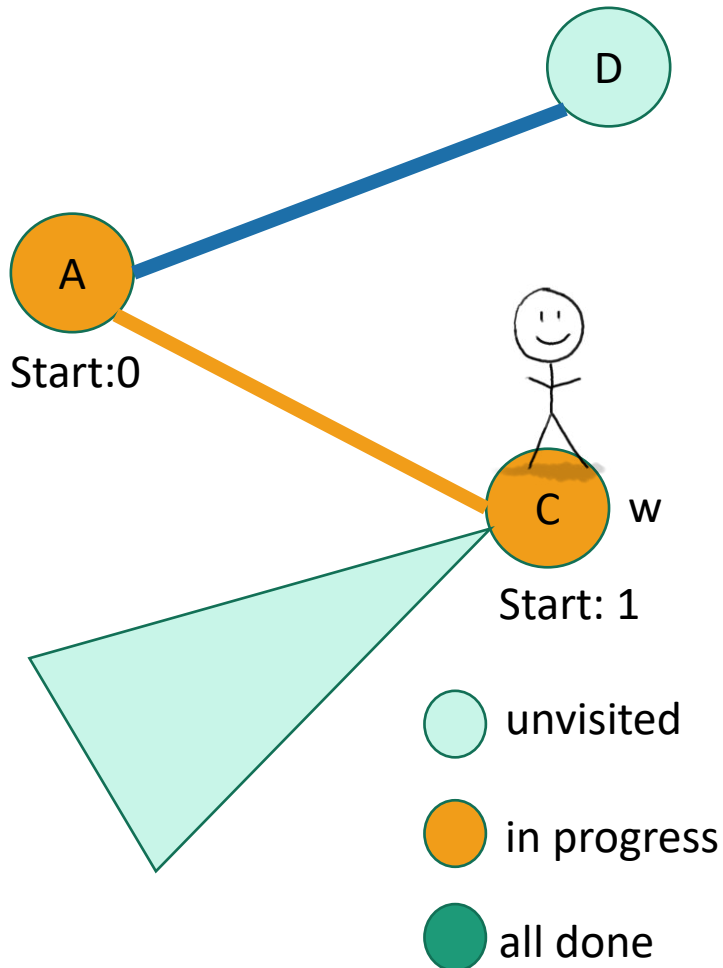
currentTime = 1



- **DFS(w, currentTime):**
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS(v, currentTime)**
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

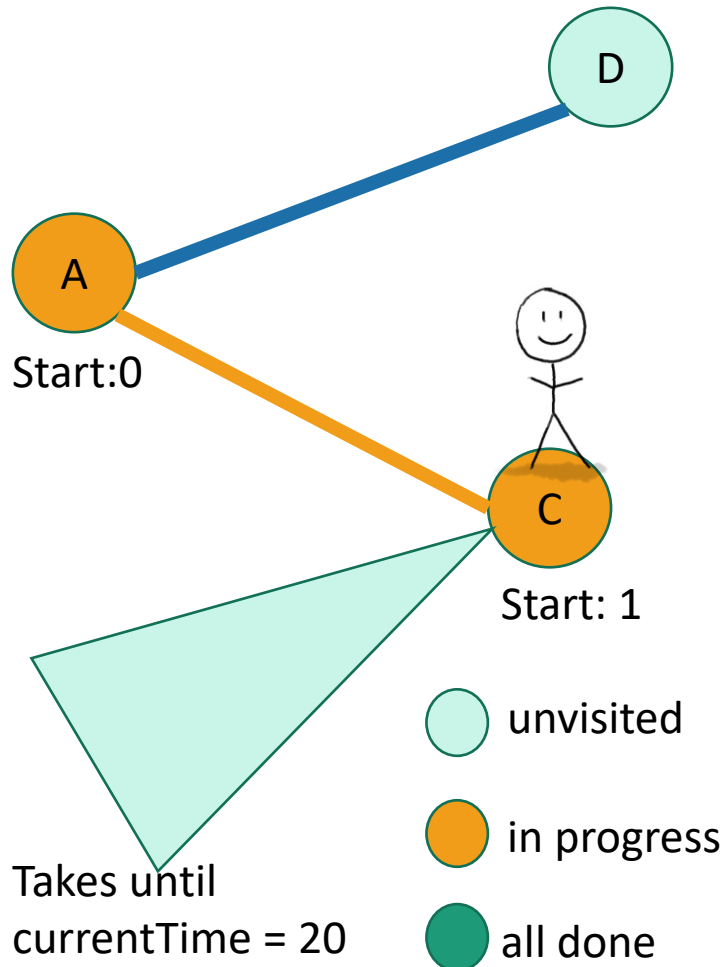
currentTime = 2



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

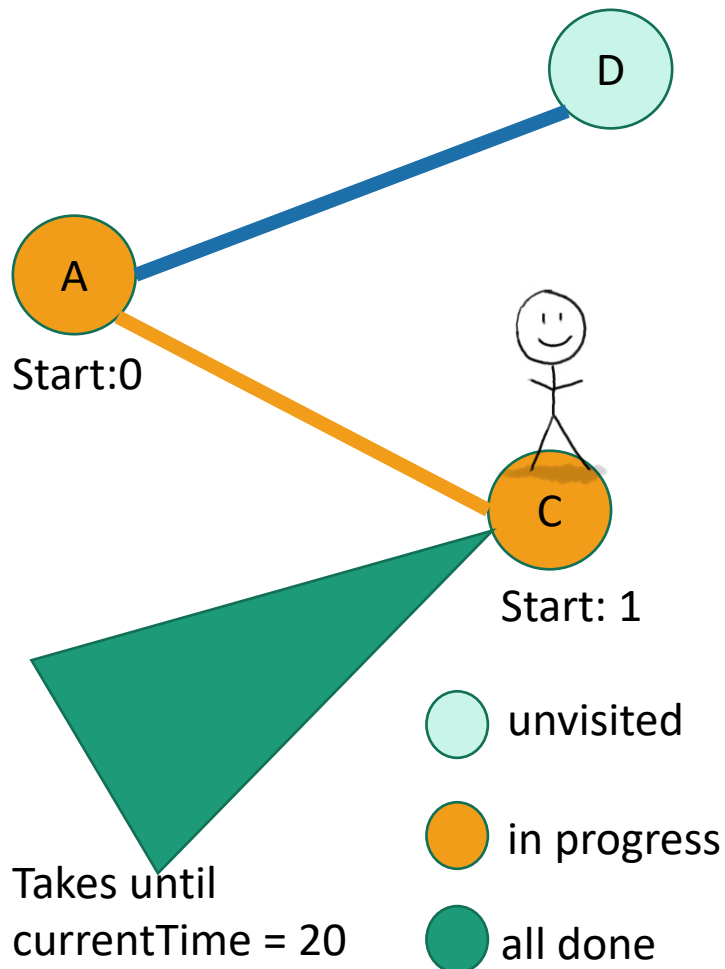
currentTime = 20



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

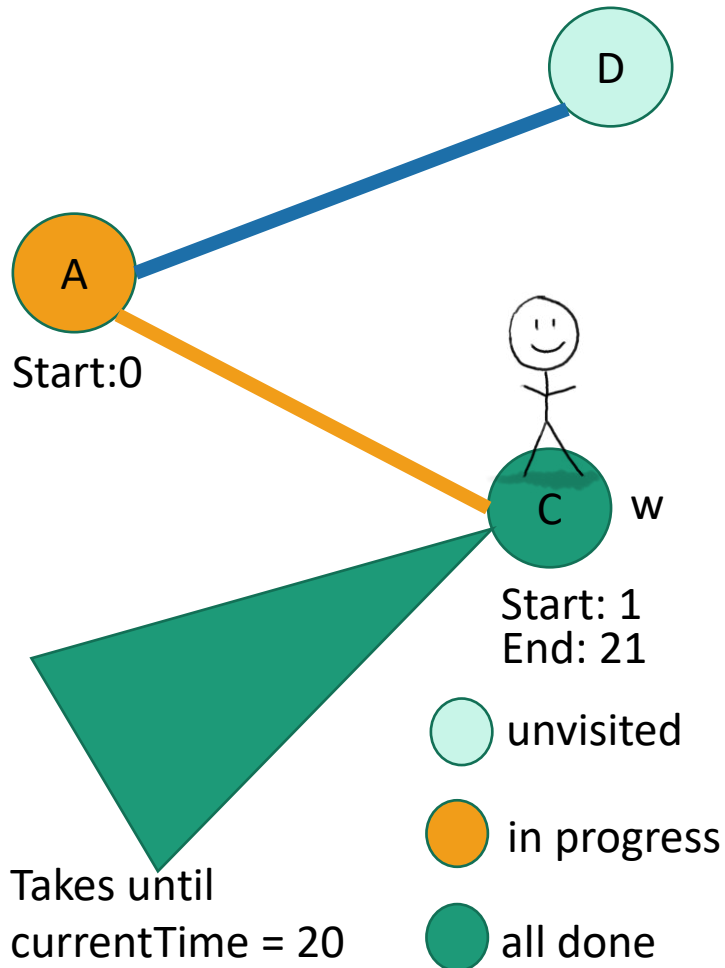
currentTime = 21



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime
= **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

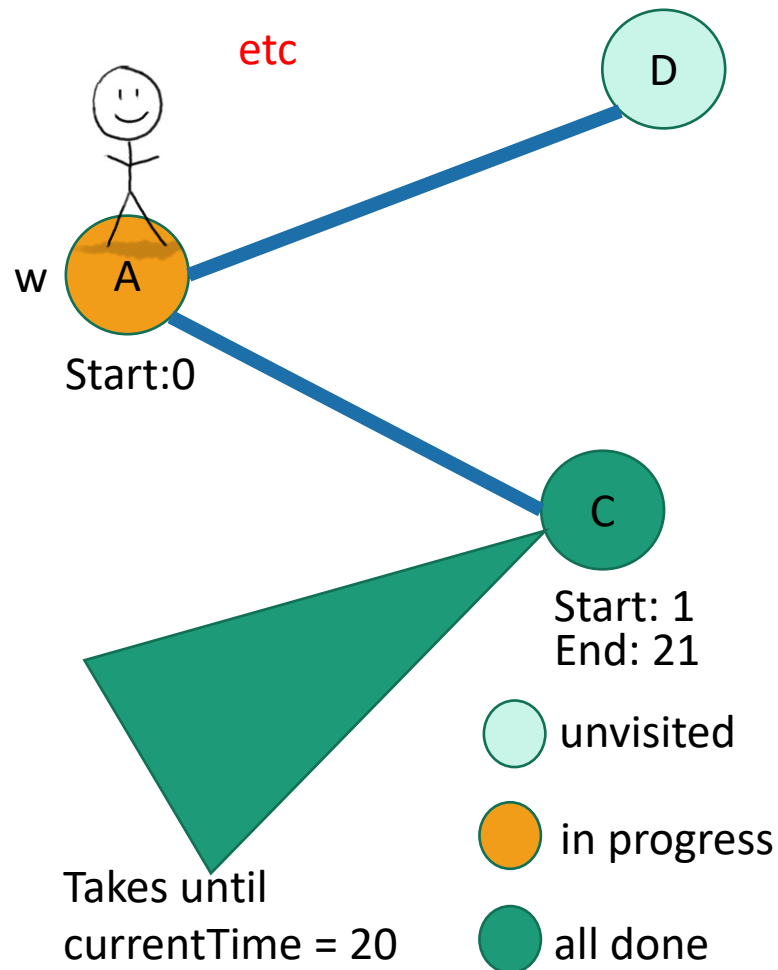
currentTime = 21



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime
= **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

currentTime = 22



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime
= **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

This is not the only way to write DFS!

- See the textbook for an iterative version.
- (And/or figure out how to do it yourself!)

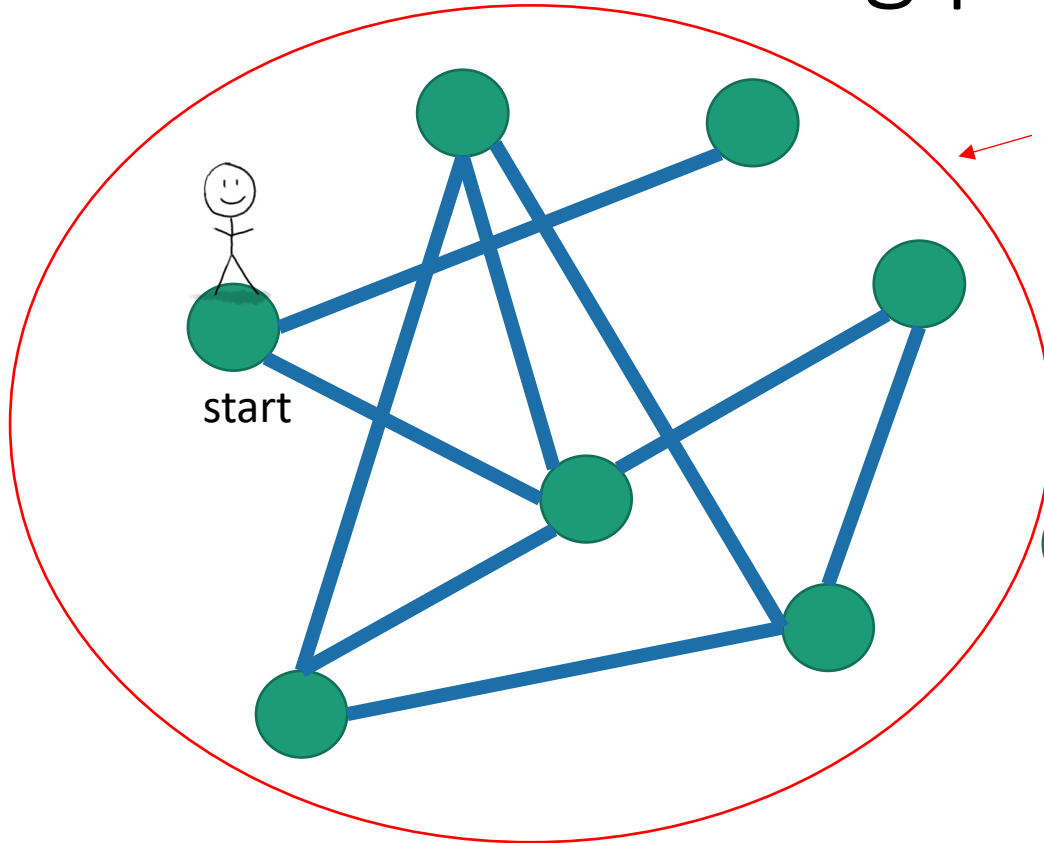


Problem 1

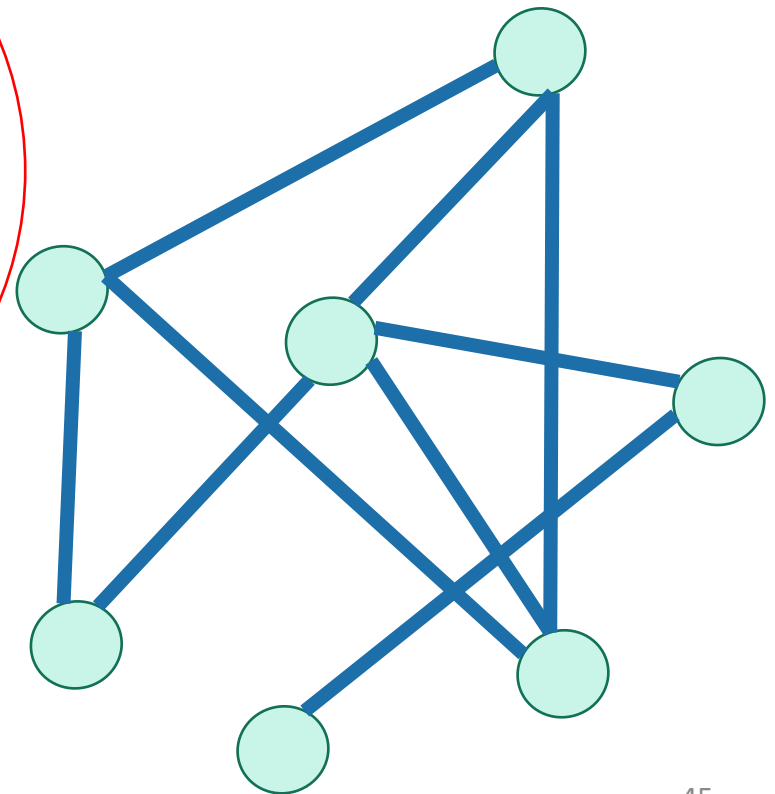
- Land of Fire has n villages with the capital named Hidden Leaf Village, and m roads between them.
- Construct minimum number of new roads so that every village is connected to the capital.
- What if we can build only a few roads (suppose 1)?



DFS finds all the nodes reachable from the starting point



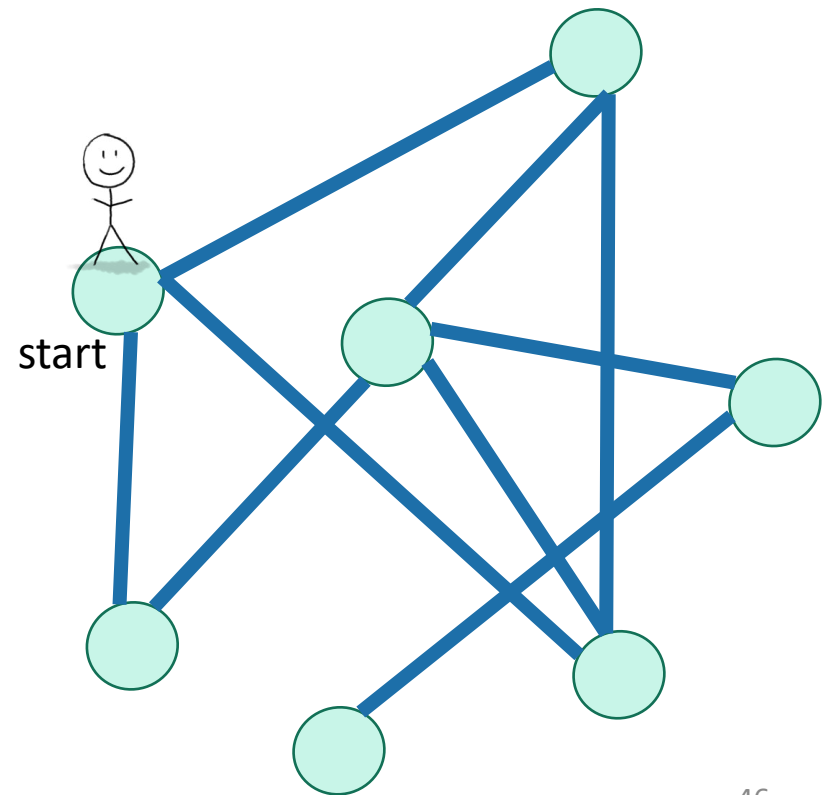
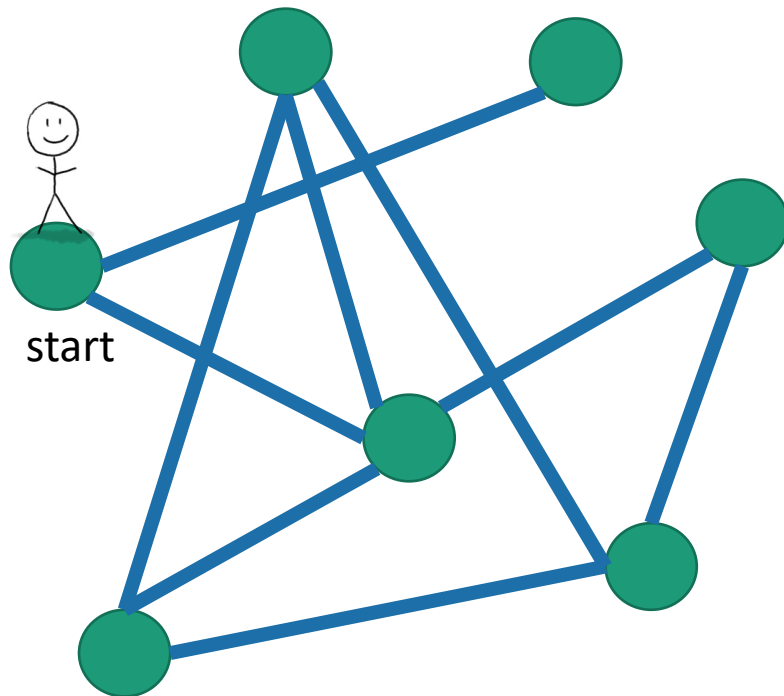
In an undirected graph, this is called a **connected component**.



One application of DFS: finding connected components.

To explore the whole graph

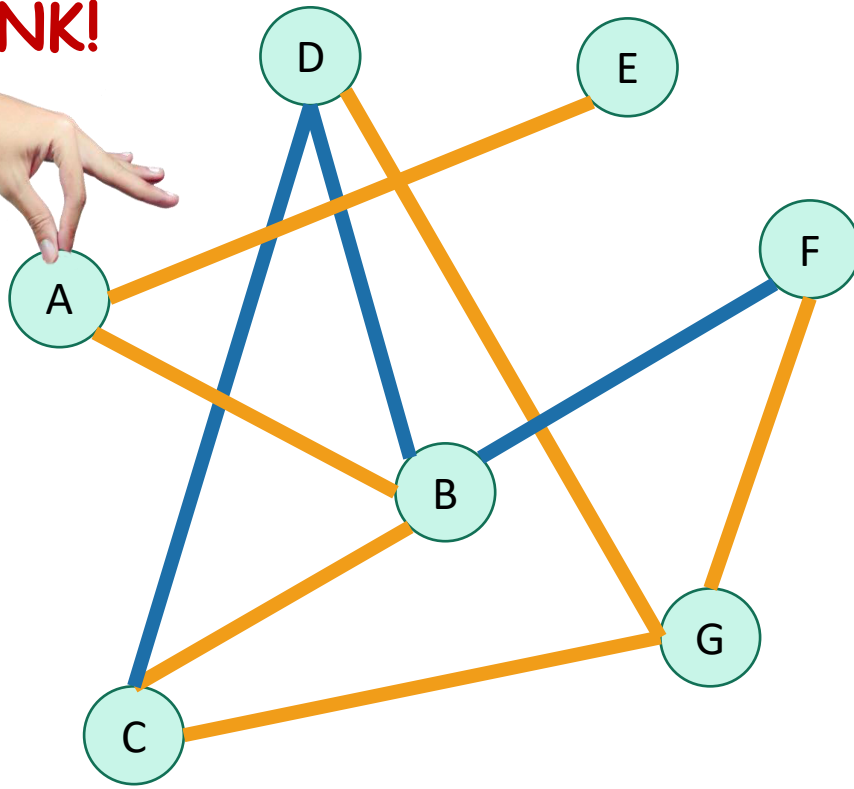
- Do it repeatedly!



Why is it called depth-first?

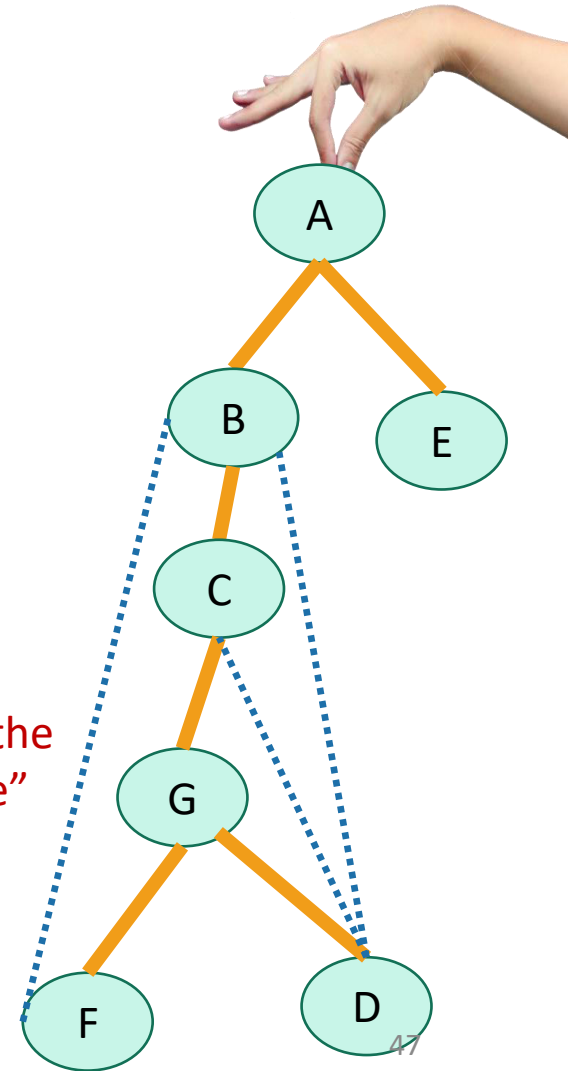
- We are implicitly building a tree:

YOINK!



- First, we go as deep as we can.

Call this the
"DFS tree"



Running time

- We look at each edge at most twice.
 - Once from each of its endpoints
- We visit each vertex at most once
- And basically we don't do anything else.
- So...



$$O(m+n)$$

Running time

- Express it in terms of only number of nodes "n"



Running time

- Express it in terms of only number of nodes " n "
- Dense graph vs sparse graph?



Running time

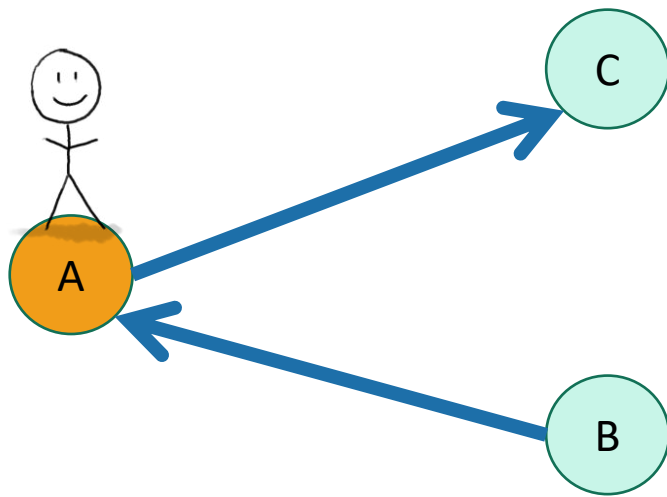
- Express it in terms of only number of nodes "n"
- Dense graph vs sparse graph?



$$O(n^2)$$

You check:

DFS works fine on directed graphs too!



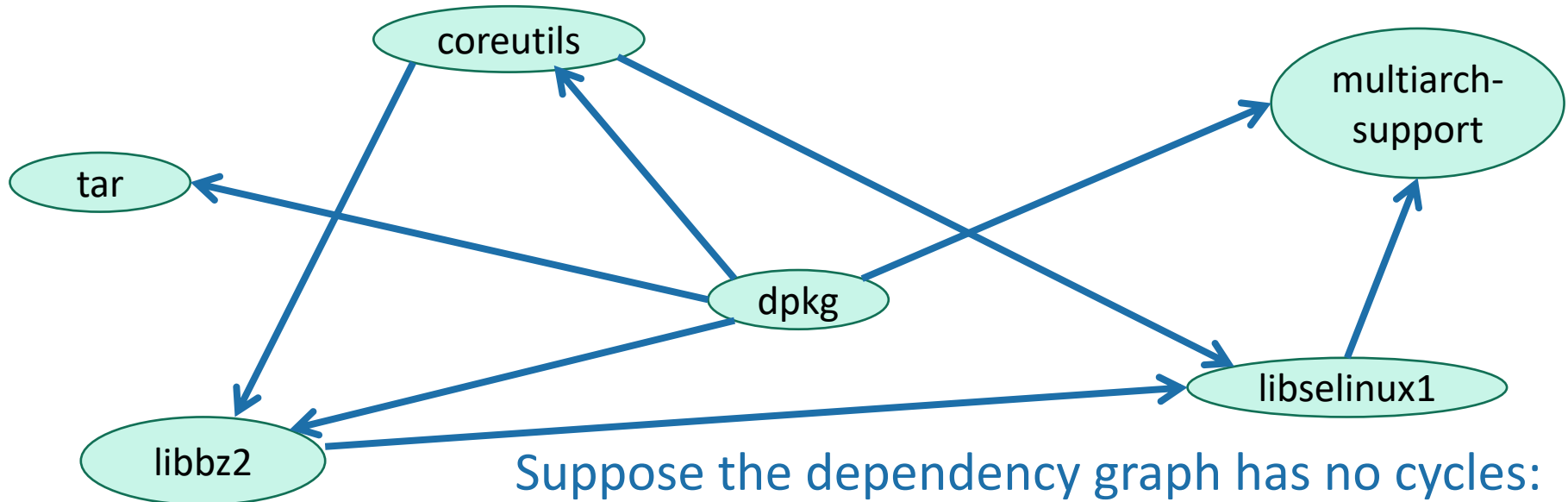
Only walk to C, not to B.



Siggi the studious stork

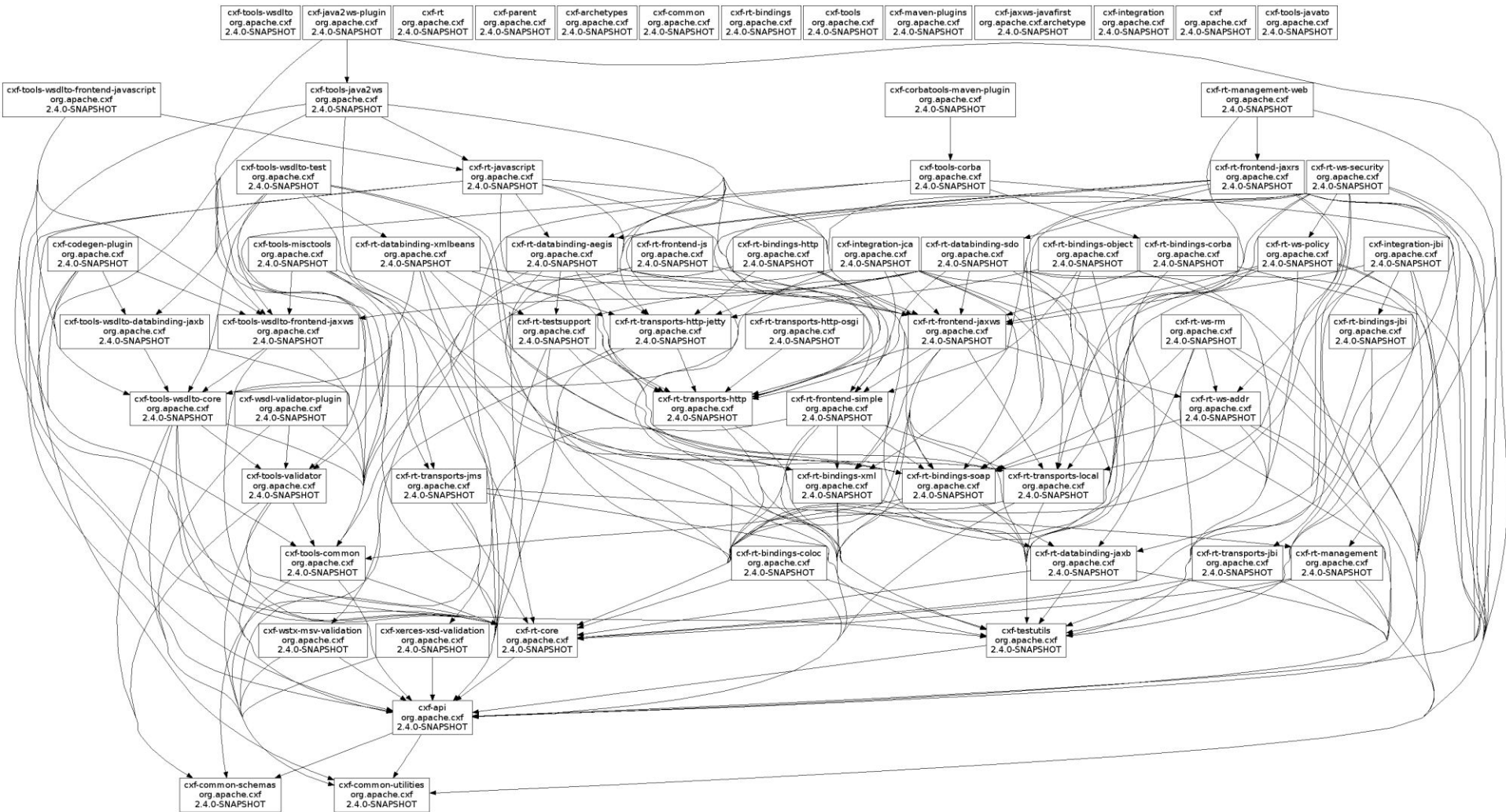
Application of DFS: topological sorting

- Find an ordering of vertices so that all of the dependency requirements are met.
 - Aka, if v comes before w in the ordering, there is not an edge from w to v .



Suppose the dependency graph has no cycles:
it is a **Directed Acyclic Graph (DAG)**

Can't always eyeball it.

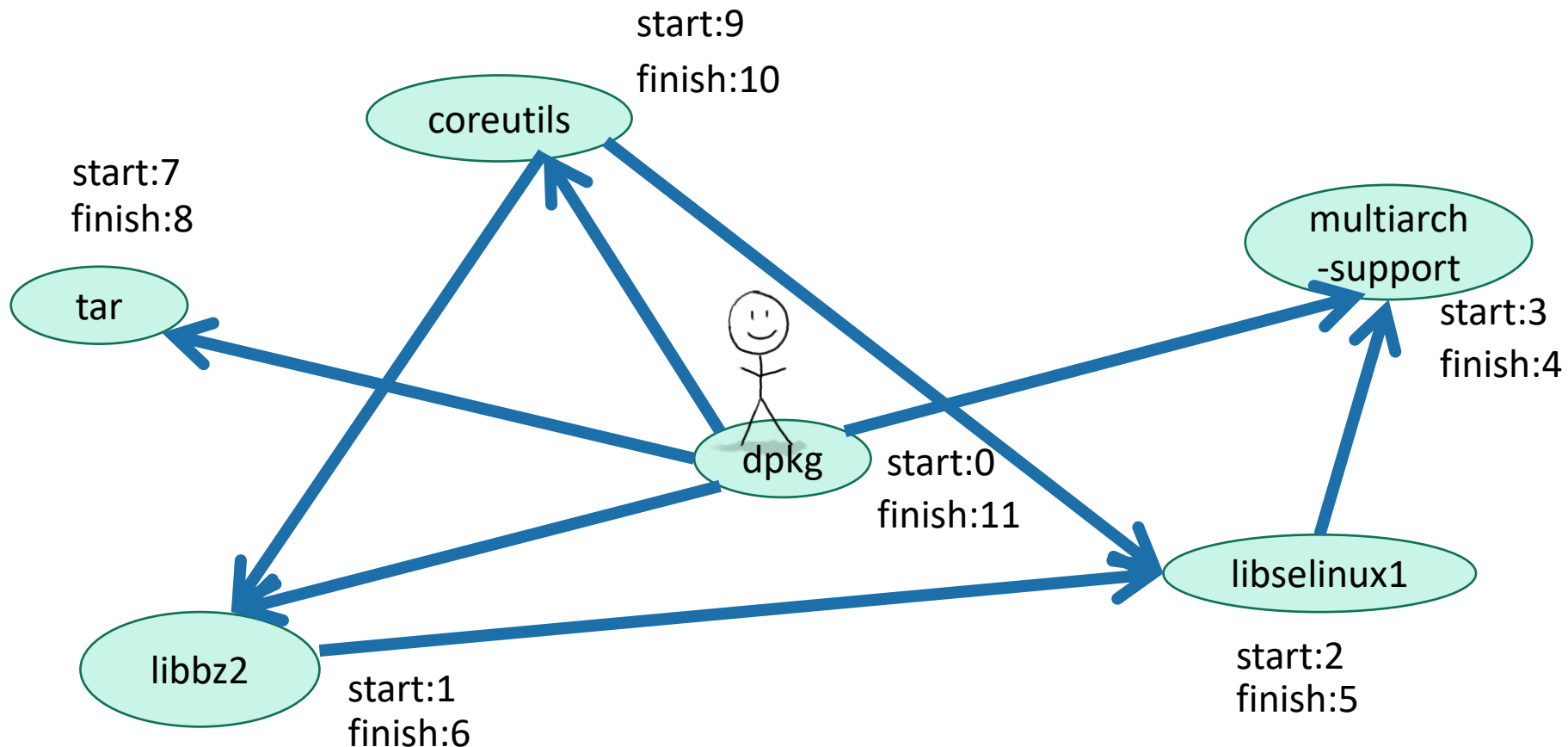
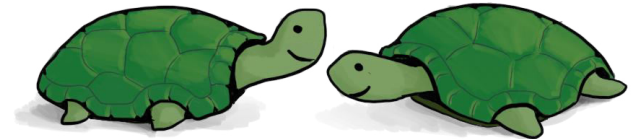


Let's do DFS

What do you notice about the finish times? Any ideas for how we should do topological sort?

1 minute think

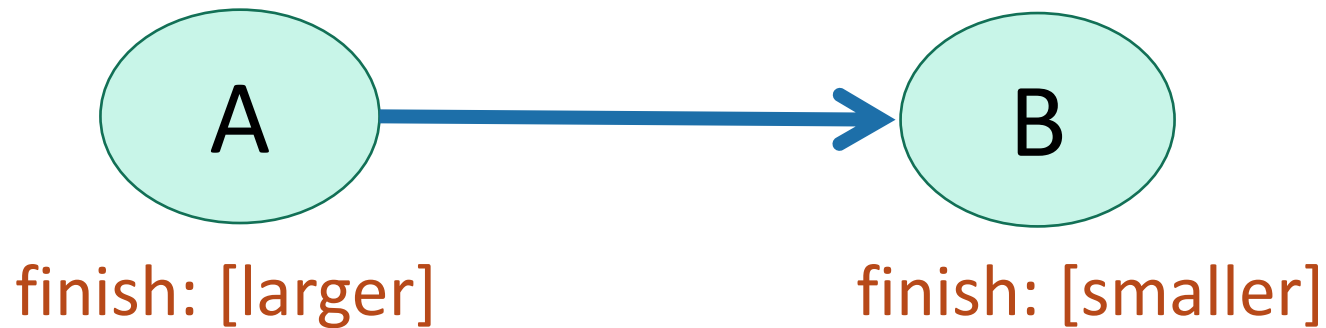
1 minute pair+share



Suppose the underlying
graph has no cycles

Finish times seem useful

Claim: In general, we'll always have:



To understand why, let's go back to that DFS tree.

A more general statement (this holds even if there are cycles)

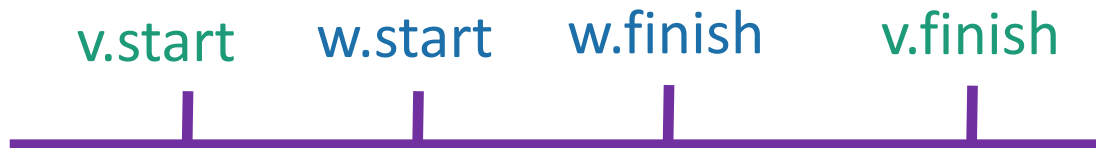
(check this
statement
carefully!)



- If v is a descendant of w in this tree:



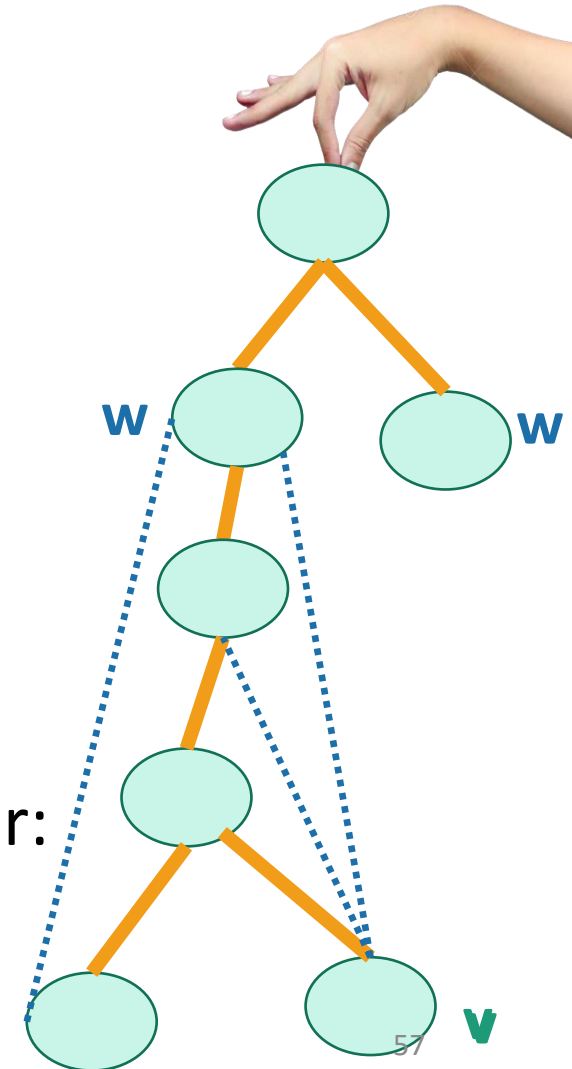
- If w is a descendant of v in this tree:



- If neither are descendants of each other:

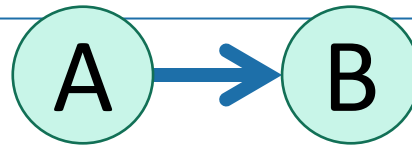


(or the other way around)



Proof of this →

If



Then $B.\text{finishTime} < A.\text{finishTime}$

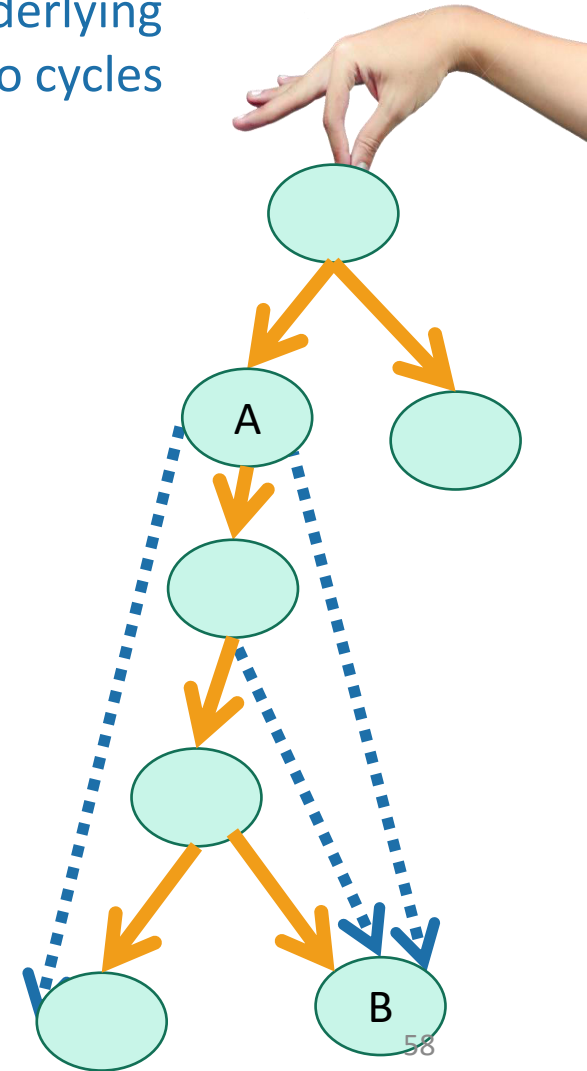
Suppose the underlying
graph has no cycles

- **Case 1:** B is a descendant of A in the DFS tree.

- Then

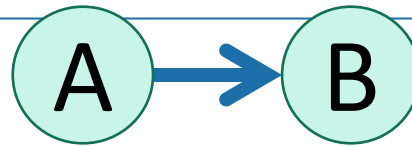


- aka, $B.\text{finishTime} < A.\text{finishTime}$.



Proof of this →

If



Then $B.\text{finishTime} < A.\text{finishTime}$

Suppose the underlying graph has no cycles

- **Case 2:** B is a **NOT** descendant of A in the DFS tree.

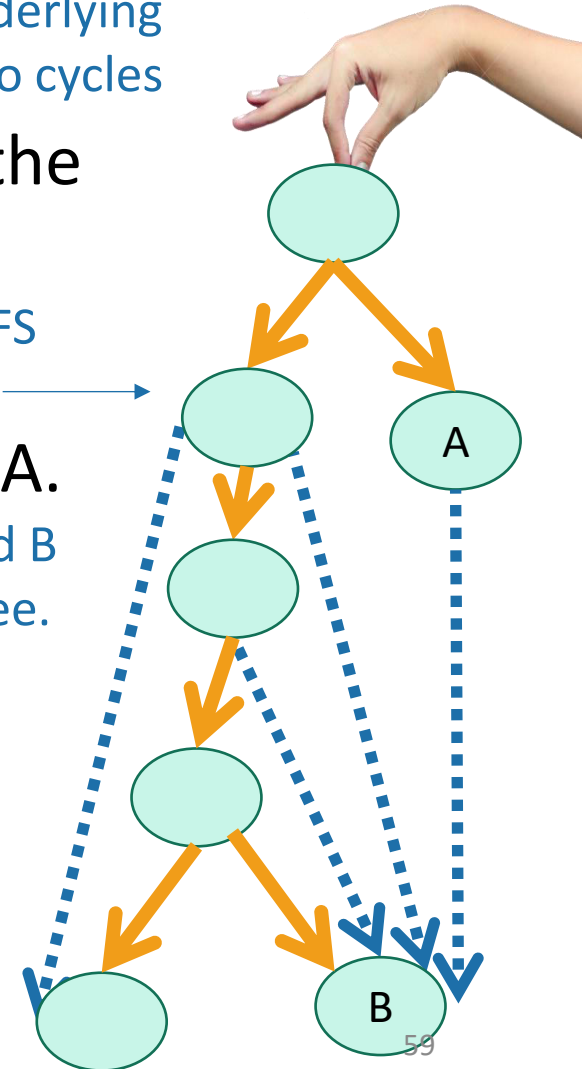
- Notice that A can't be a descendant of B in the DFS tree or else there'd be a cycle; so it looks like this →

- Then we must have explored B before A.
 - Otherwise we would have gotten to B from A, and B would have been a descendant of A in the DFS tree.

- Then

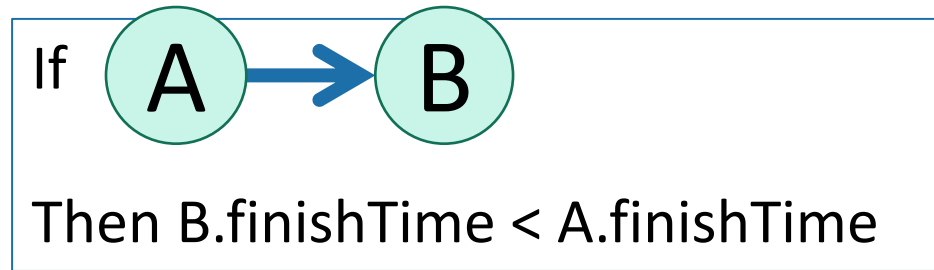


- aka, **$B.\text{finishTime} < A.\text{finishTime}$** .

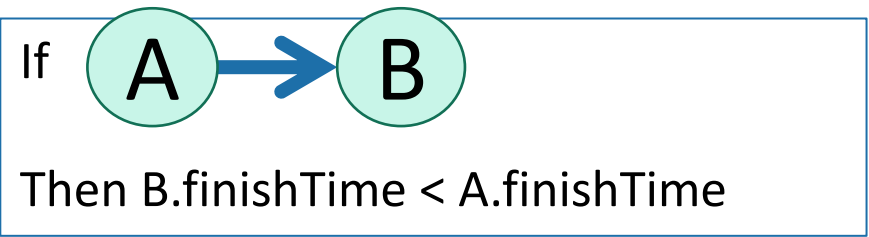


Theorem

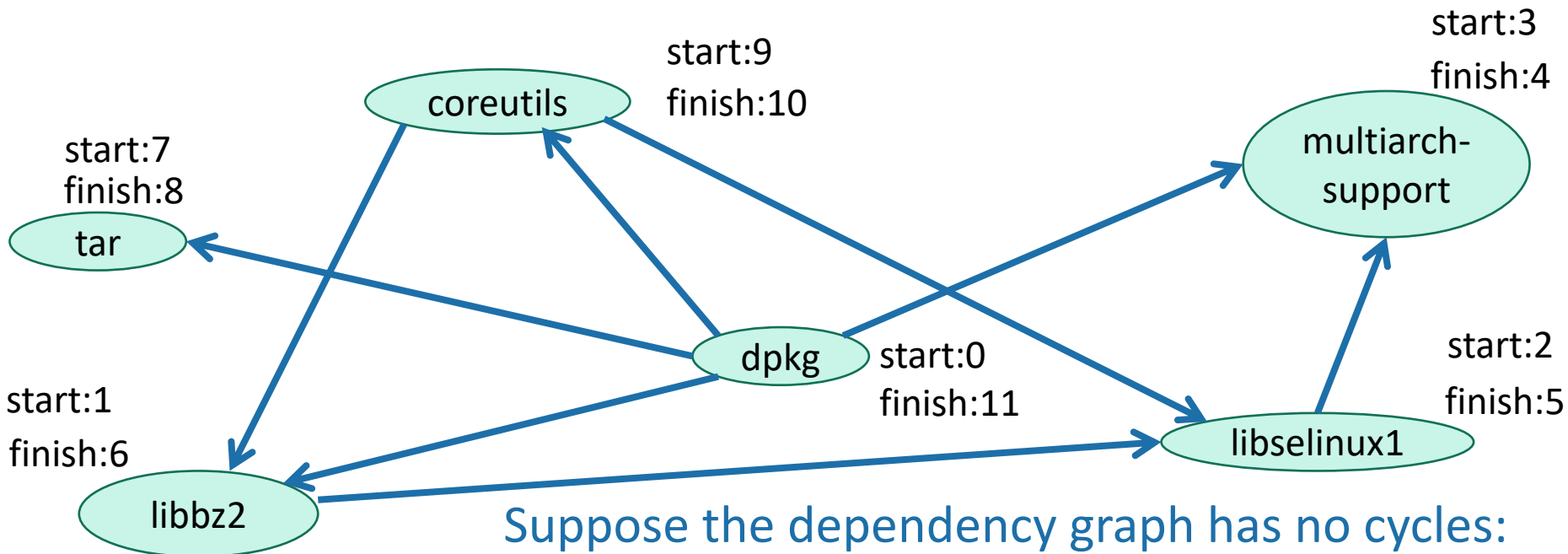
- If we run DFS on a directed acyclic graph,



Back to topological sorting



- In what order should I install packages?
- In reverse order of finishing time in DFS!



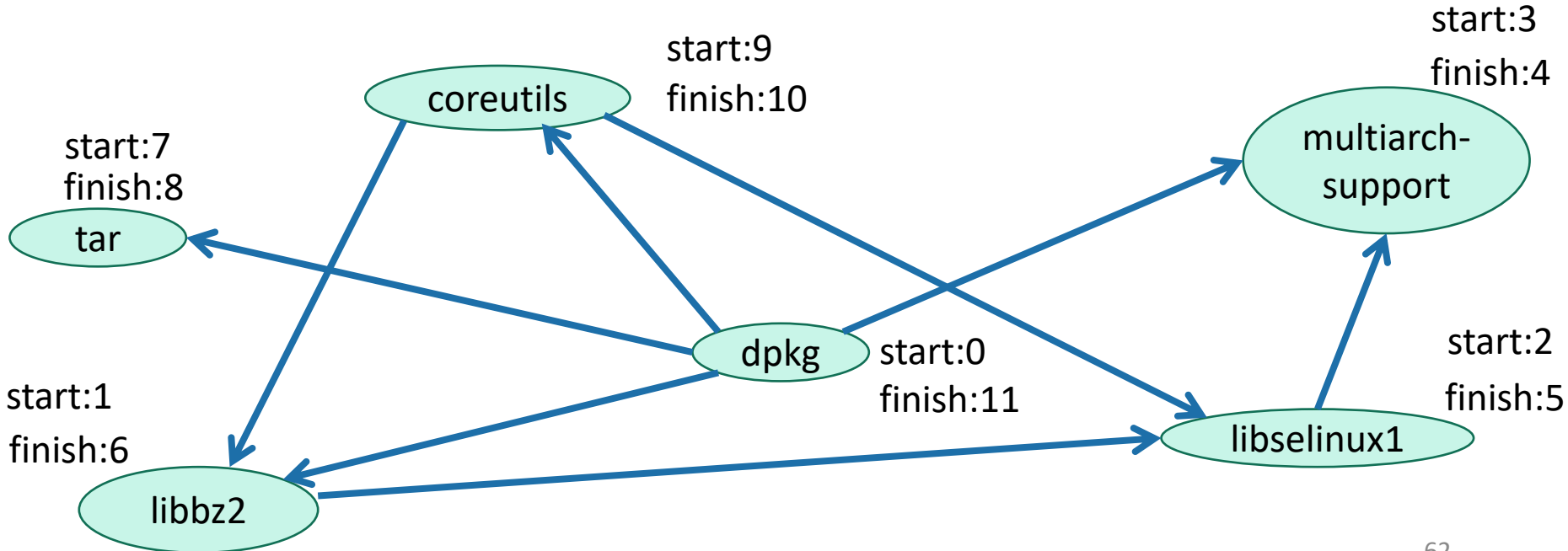
Suppose the dependency graph has no cycles:
it is a **Directed Acyclic Graph (DAG)**

Topological Sorting (on a DAG)

Check out [iPython notebook](#) for an implementation!

- Do DFS
- When you mark a vertex as **all done**, put it at the **beginning** of the list.

- dpkg
- coreutils
- tar
- libbz2
- libselinux1
- multiarch_support

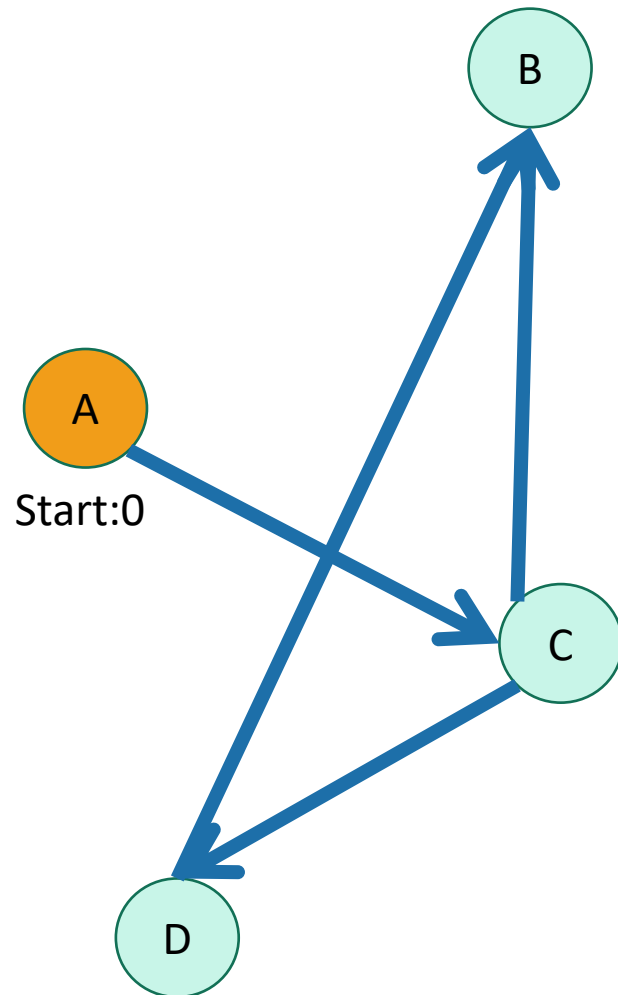


What have we learned?

- DFS can help you solve the **topological sorting problem**
 - That's the fancy name for the problem of finding an ordering that respects all the dependencies
- Thinking about the DFS tree is helpful.

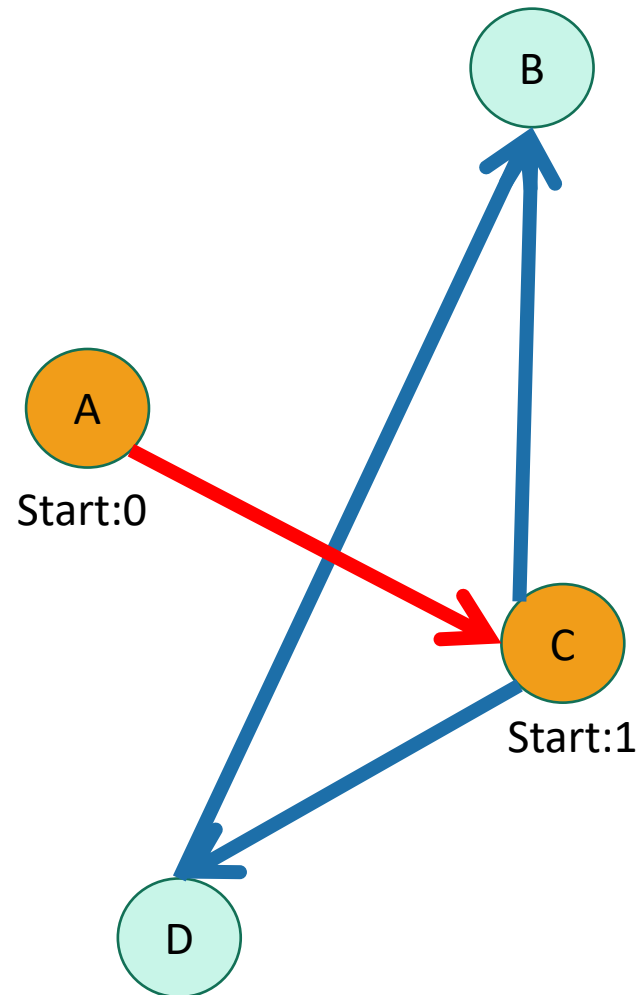
Example:

This example skipped in class – here for reference.



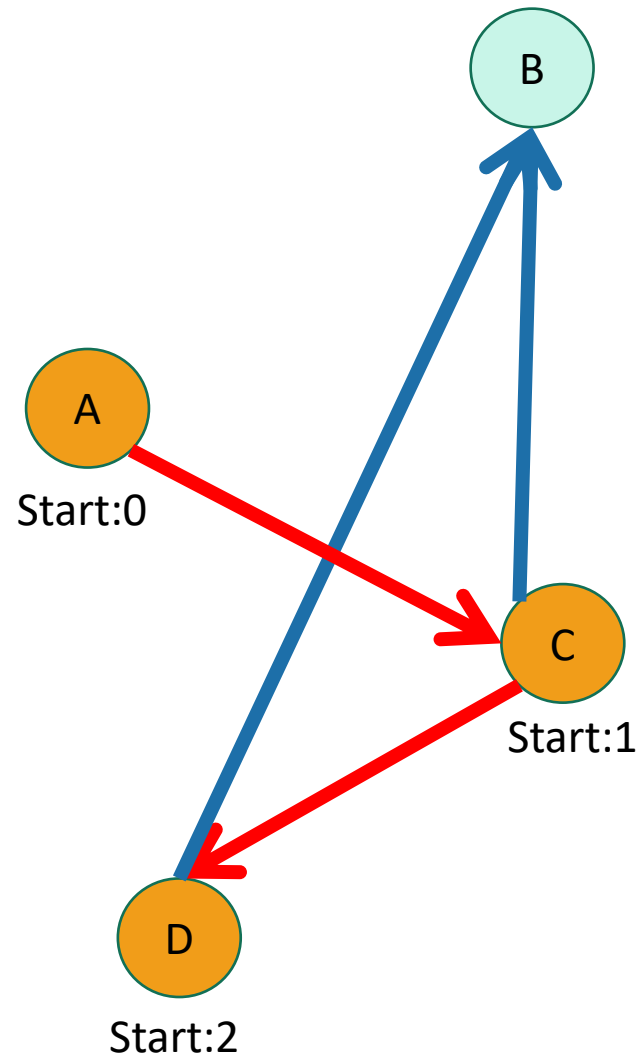
Example

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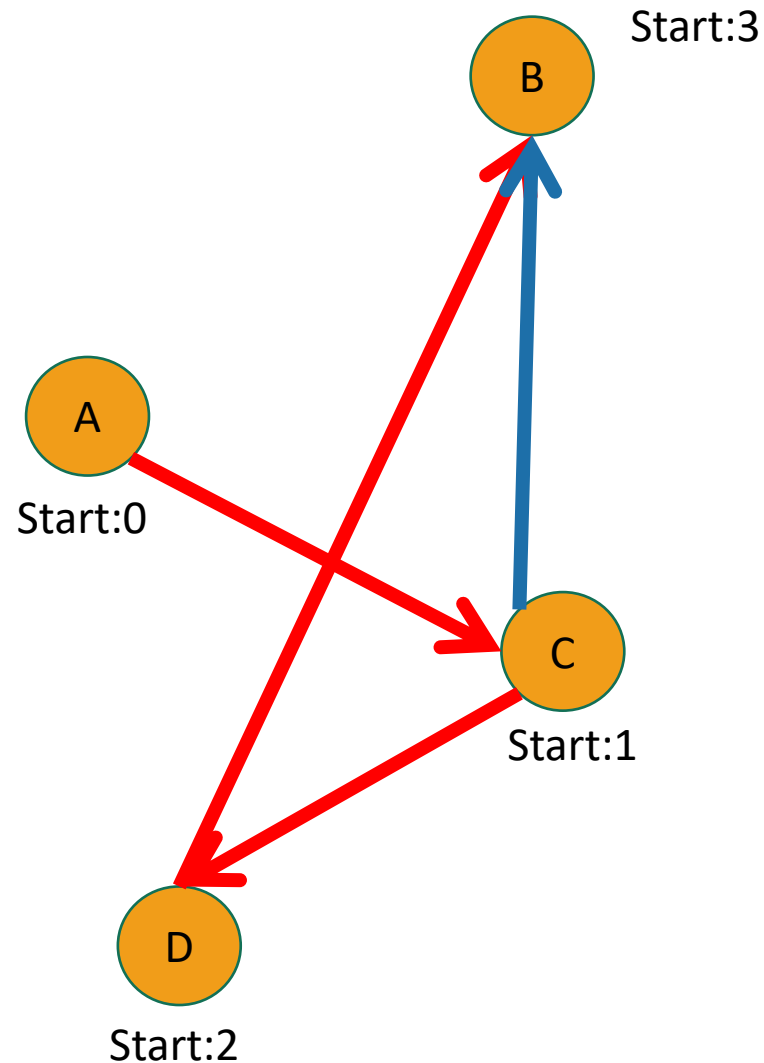
Example

This example skipped in class – here for reference.



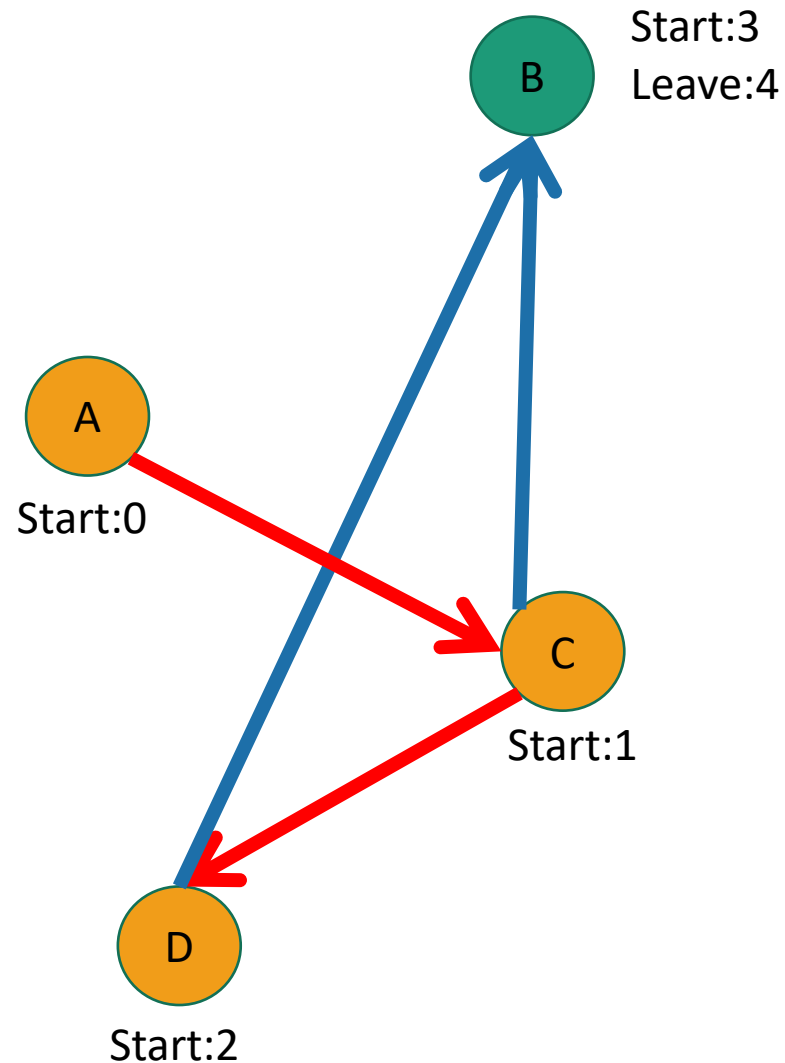
Example

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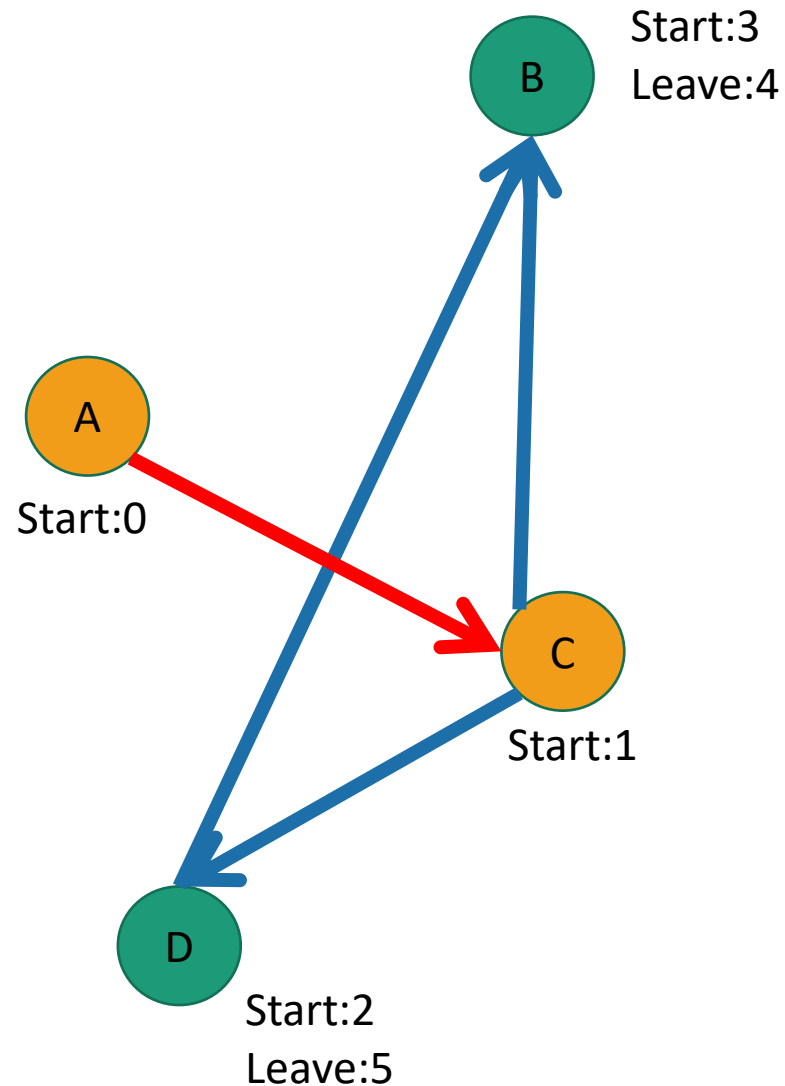
Example

This example skipped in class – here for reference.



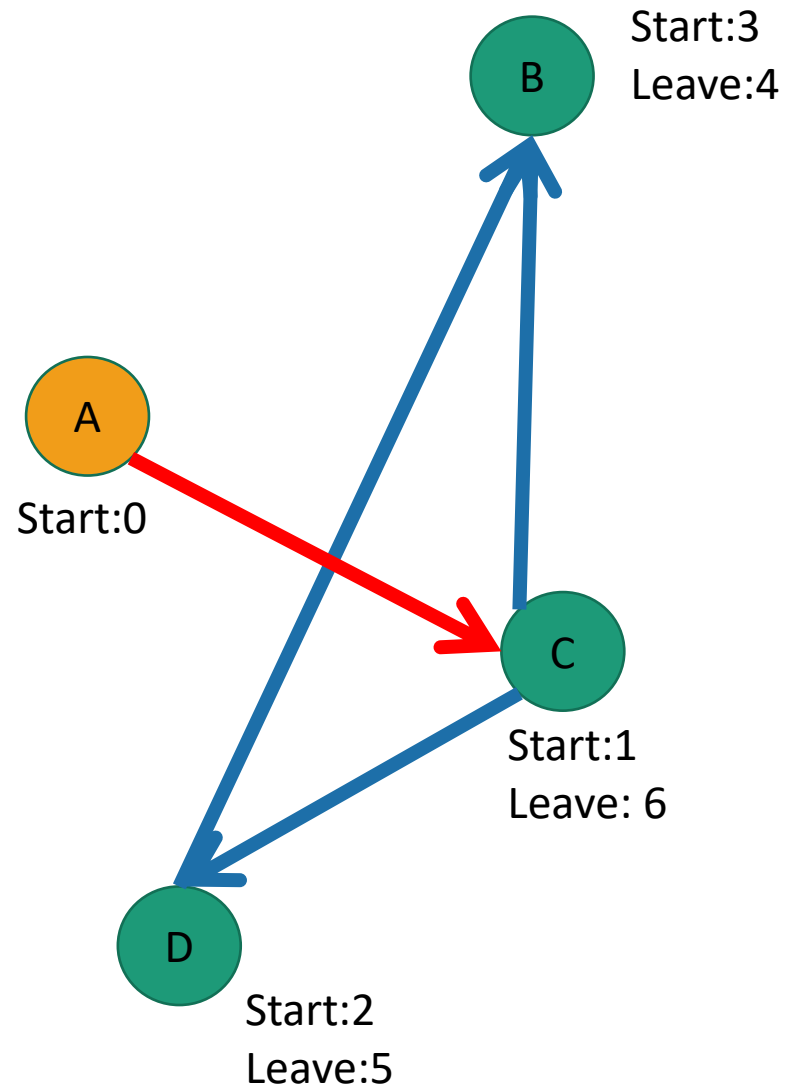
Example

This example skipped in class – here for reference.



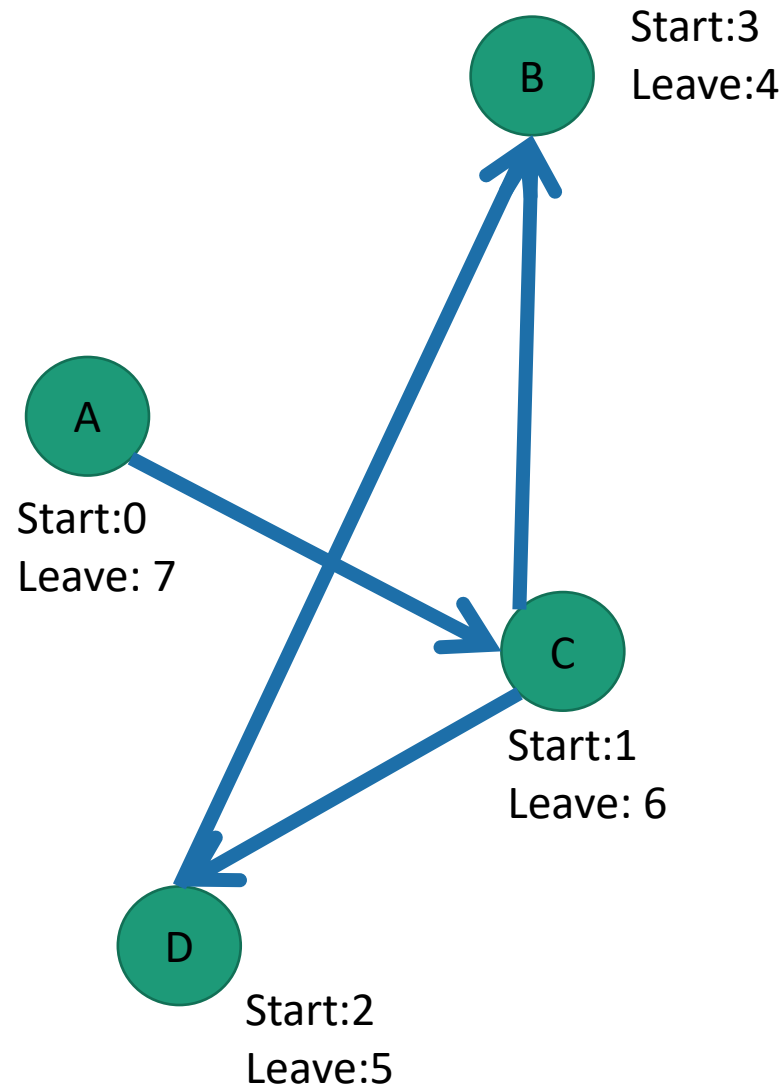
Example

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Example

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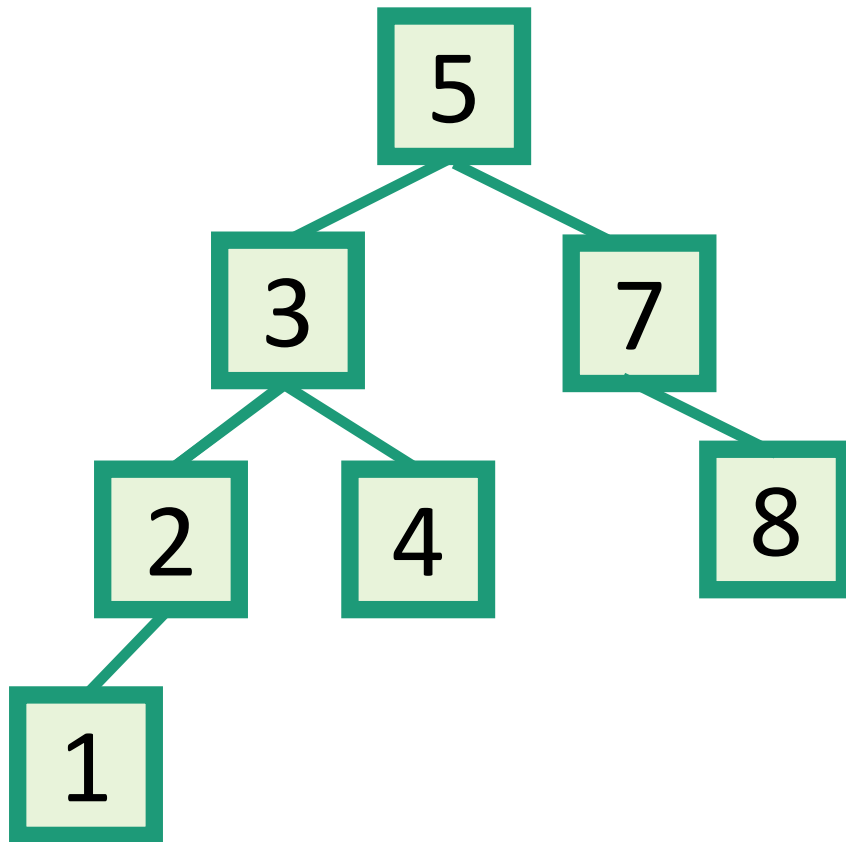


Do them in this order:



Another use of DFS that we've already seen

- In-order enumeration of binary search trees

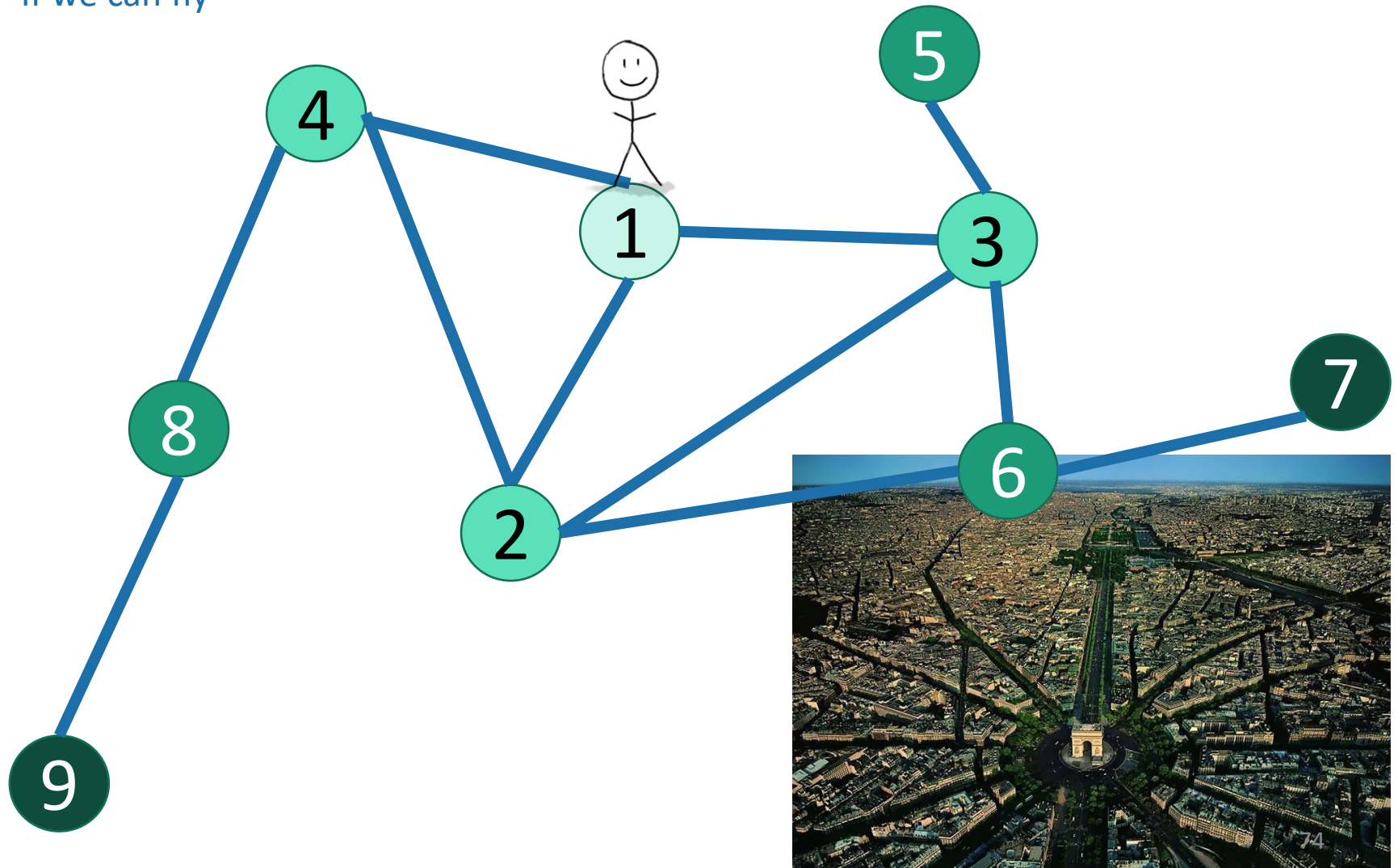


Do DFS and print a node's label when you are done with the left child and before you begin the right child.

Part 2: breadth-first search

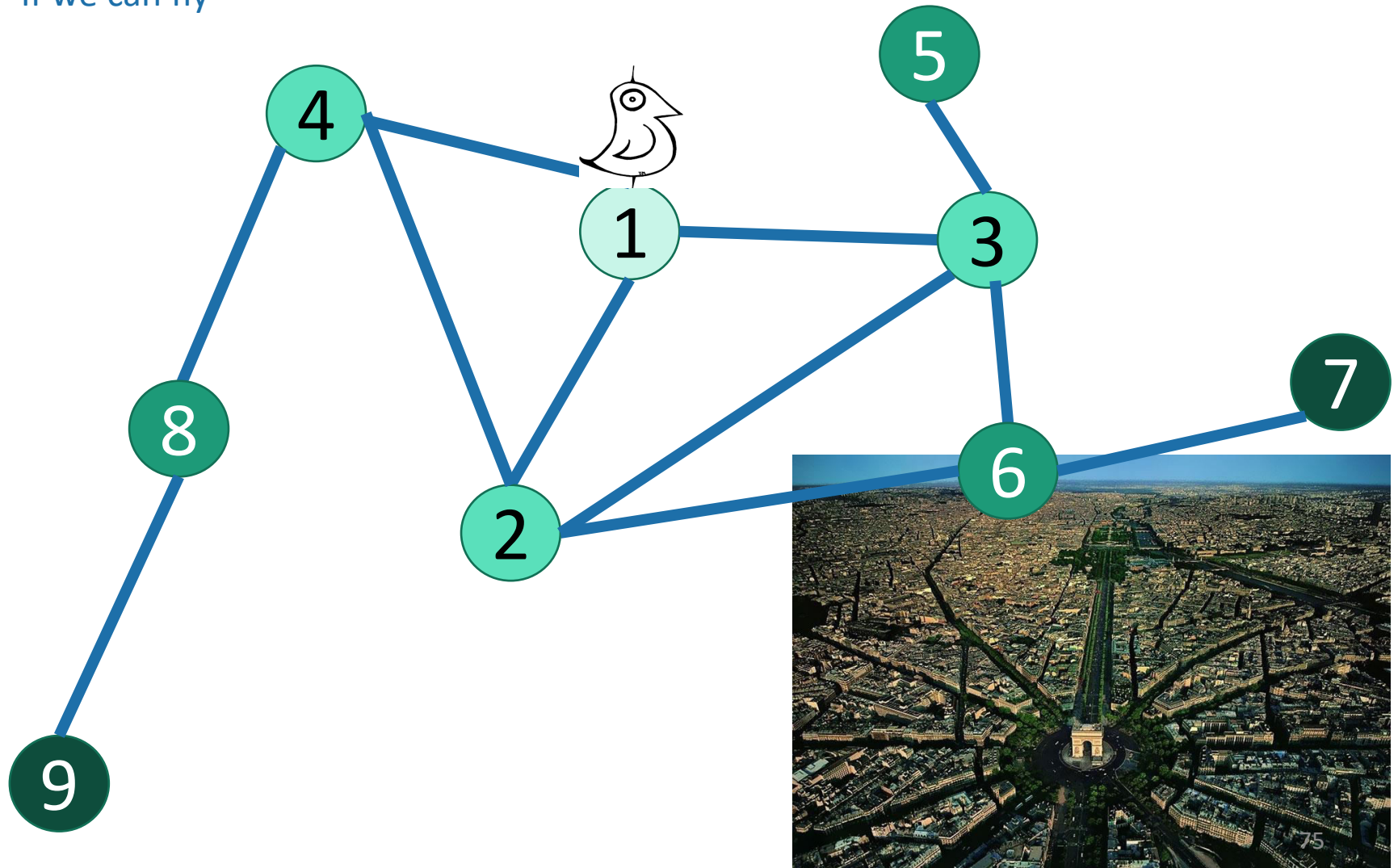
How do we explore a graph?

If we can fly



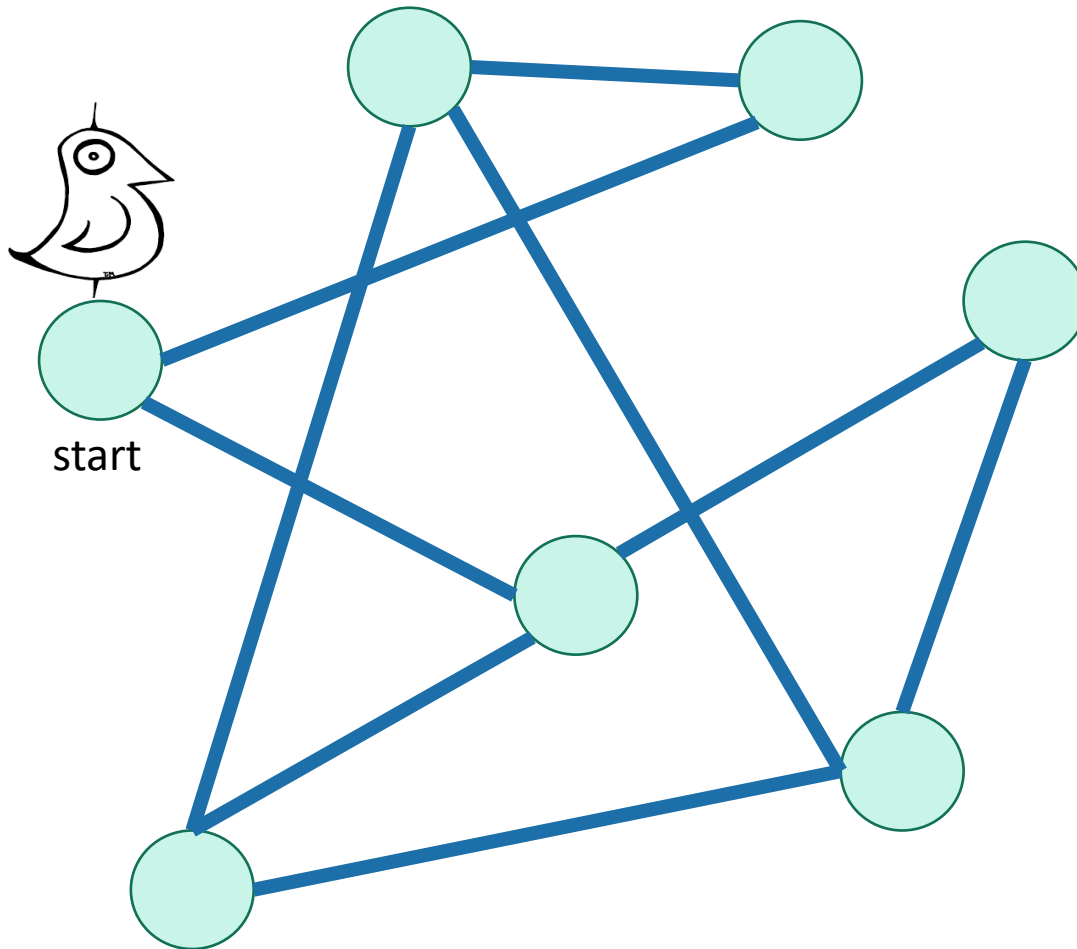
How do we explore a graph?






If we can fly



Breadth-First Search

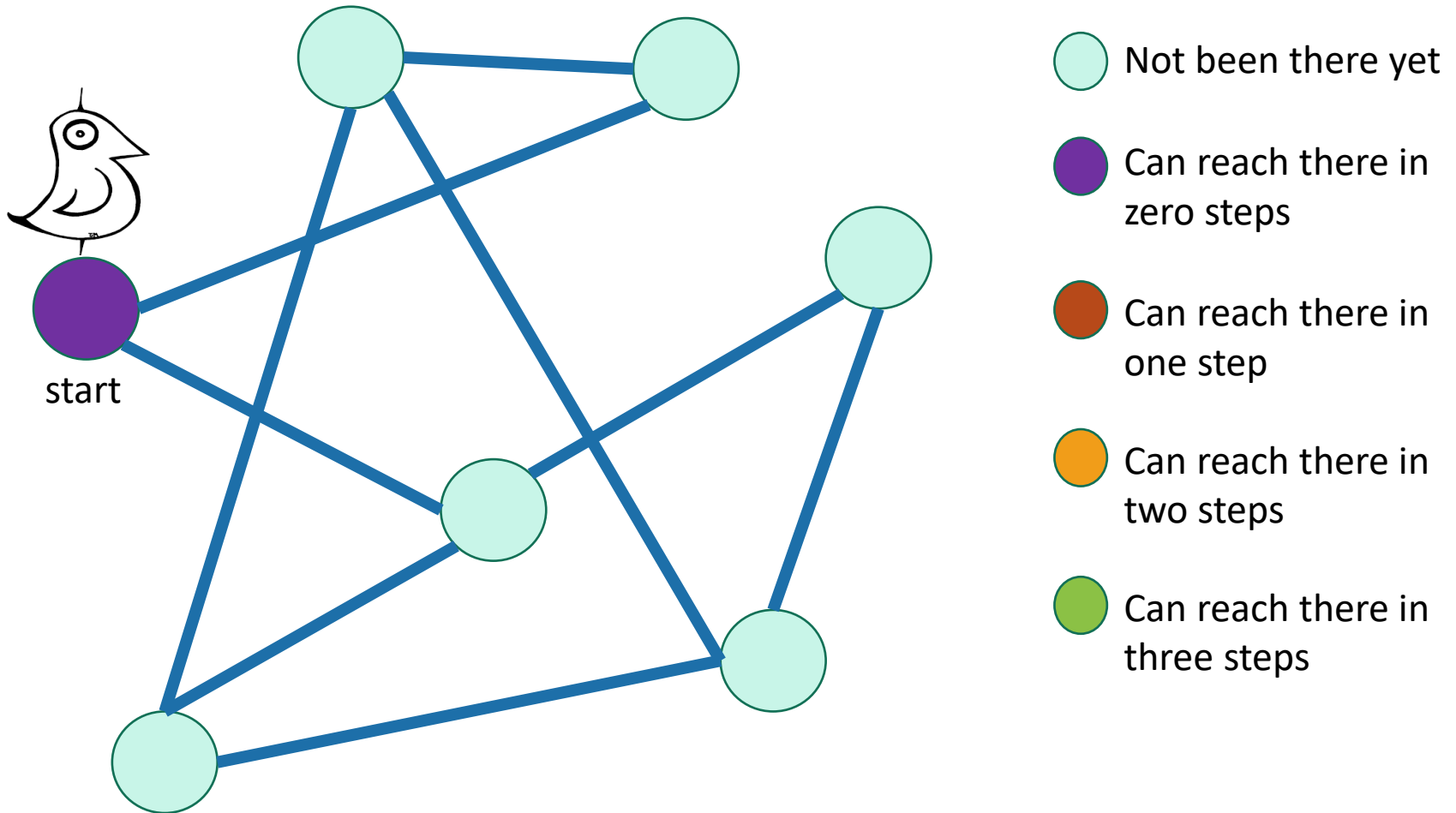
Exploring the world with a bird's-eye view



-  Not been there yet
-  Can reach there in zero steps
-  Can reach there in one step
-  Can reach there in two steps
-  Can reach there in three steps

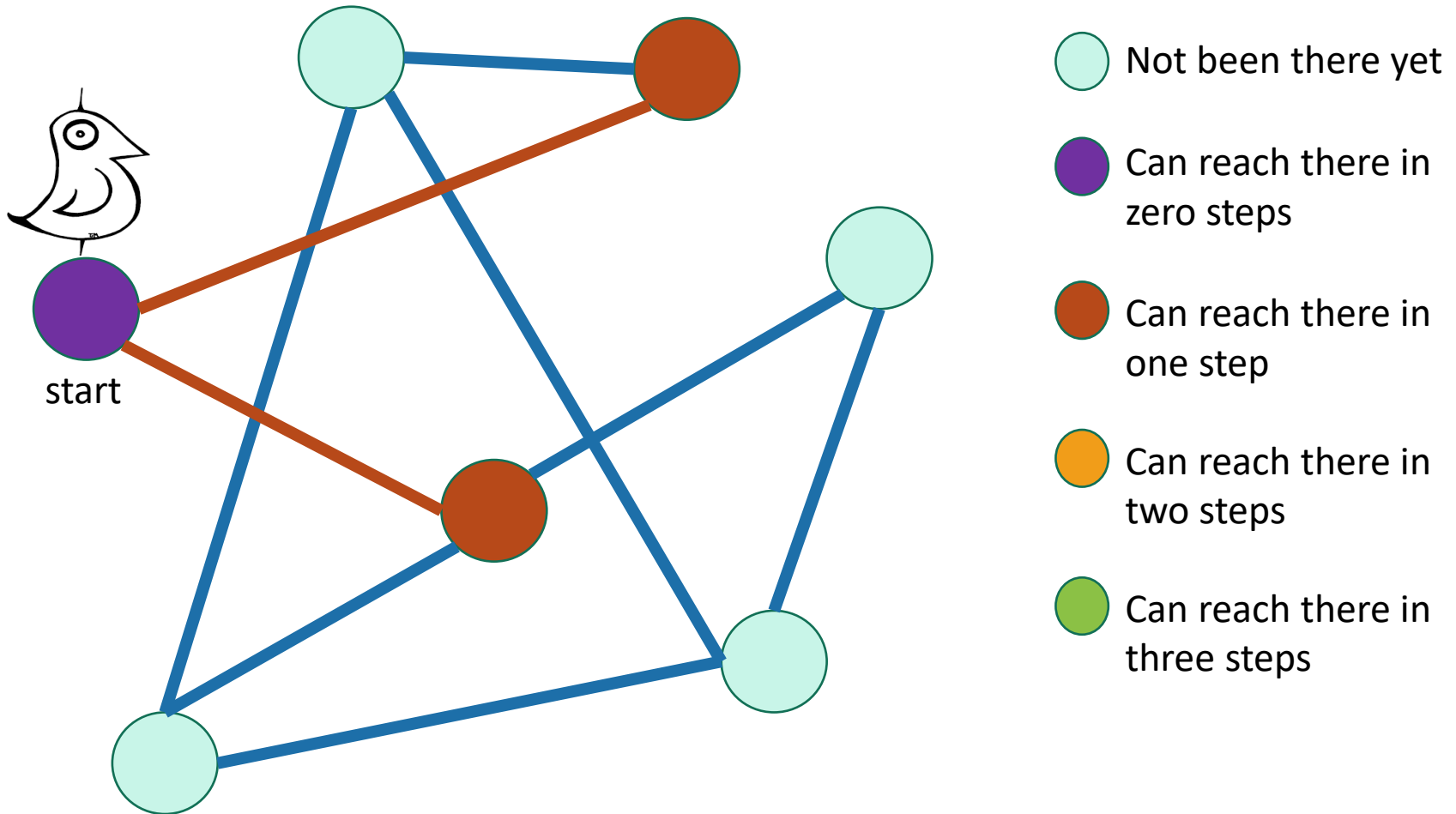
Breadth-First Search

Exploring the world with a bird's-eye view



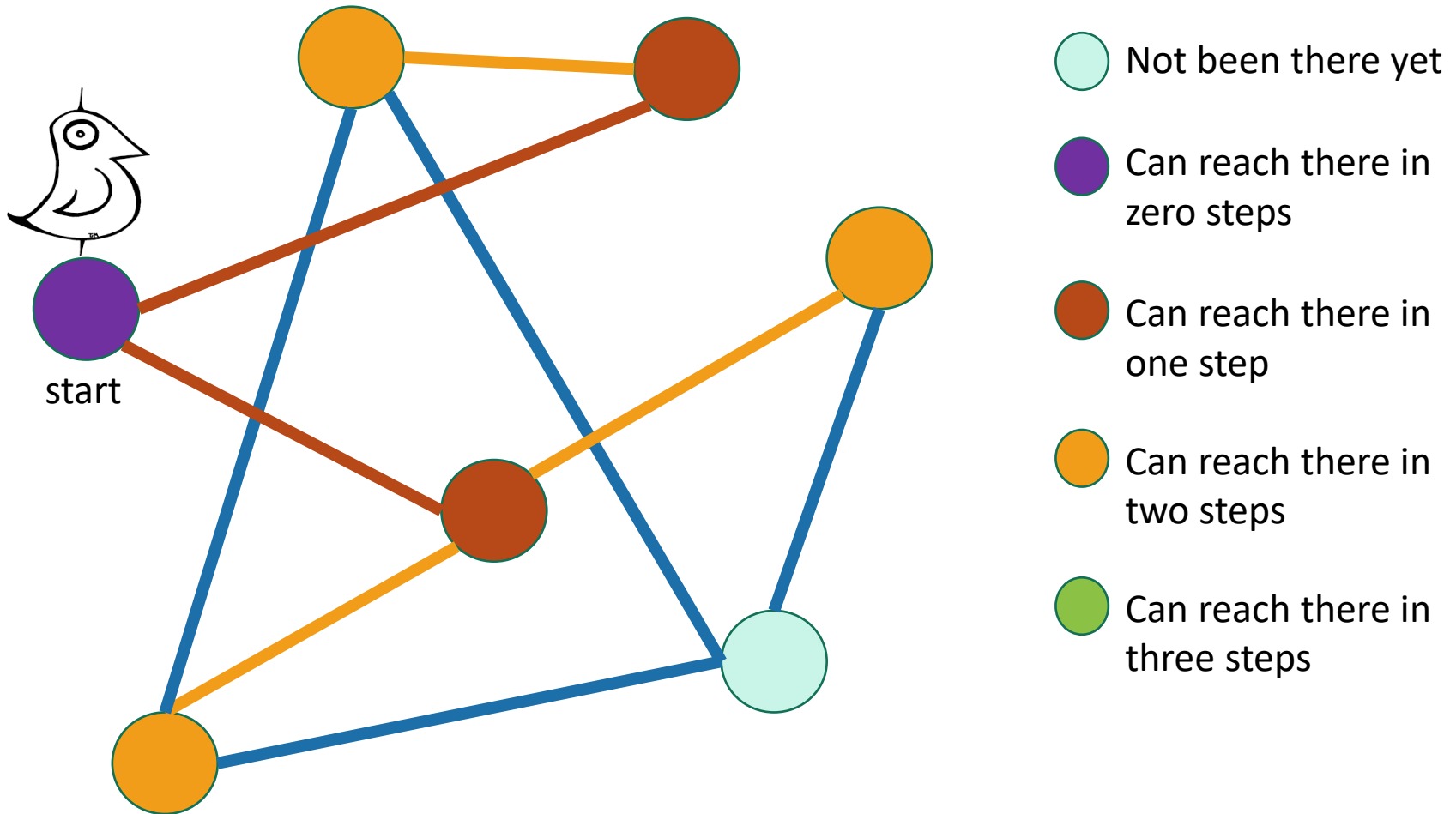
Breadth-First Search

Exploring the world with a bird's-eye view



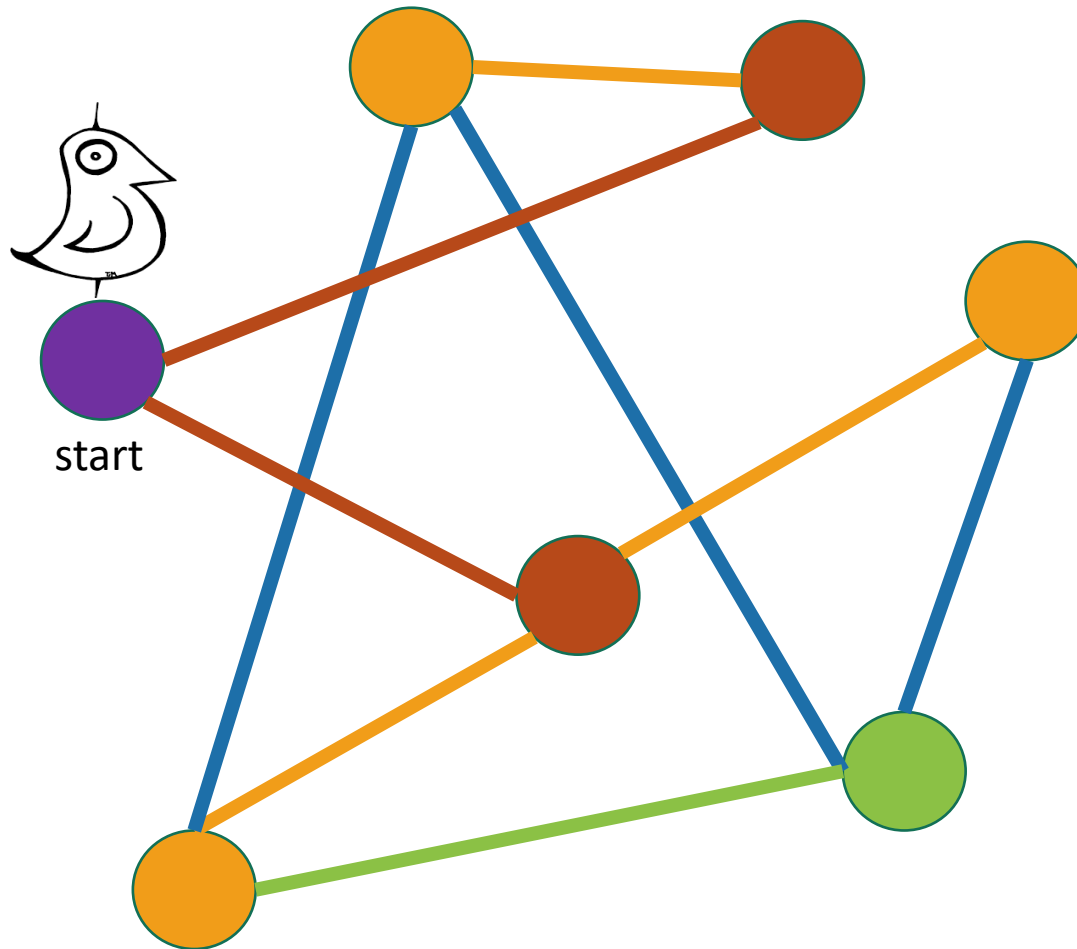
Breadth-First Search






Exploring the world with a bird's-eye view



Breadth-First Search

Exploring the world with a bird's-eye view



-  Not been there yet
-  Can reach there in zero steps
-  Can reach there in one step
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-  Can reach there in three steps

World:
explored!

Same disclaimer as for DFS: you may have seen other ways to implement this,
this will be convenient for us.

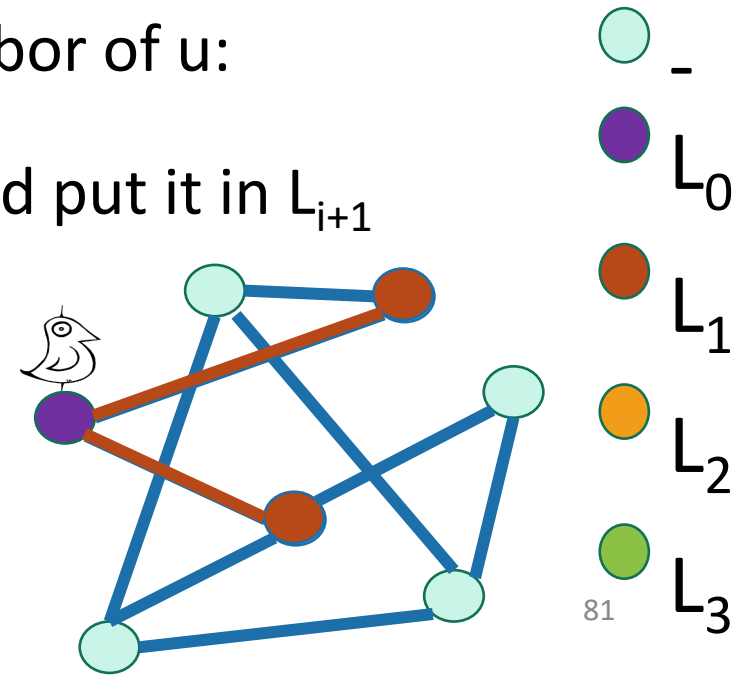
Breadth-First Search

Exploring the world with pseudocode

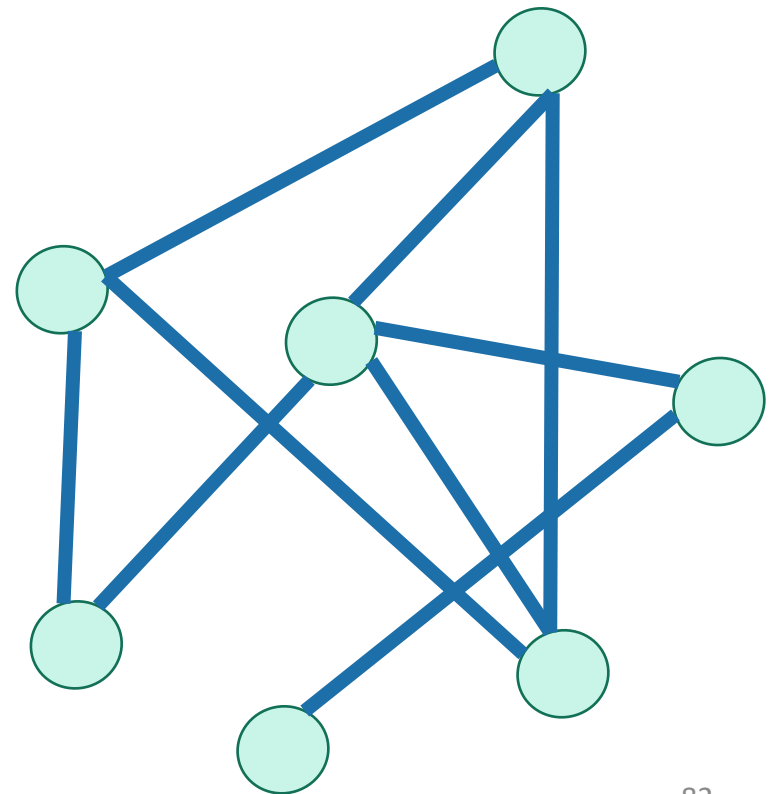
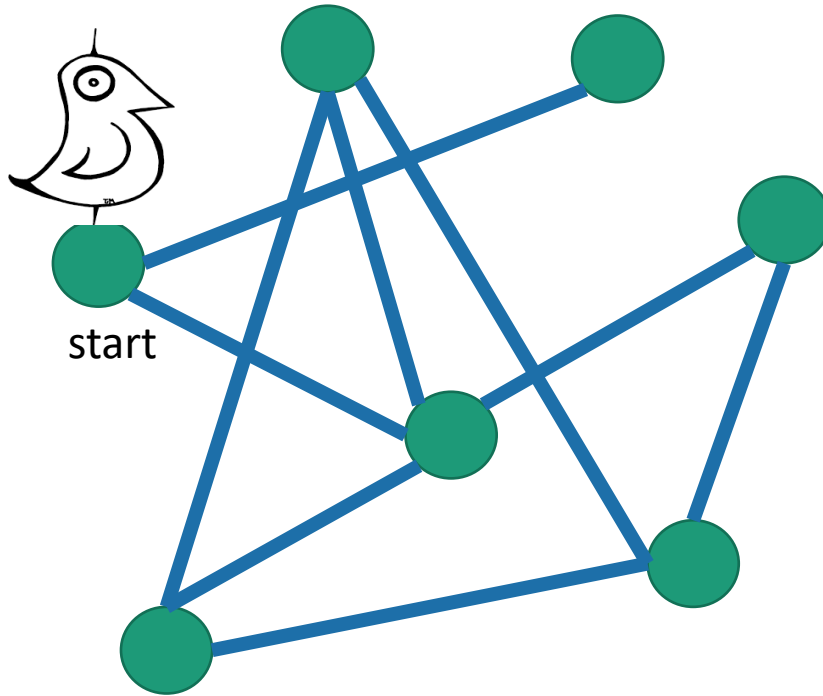
- Set $L_i = []$ for $i=1, \dots, n$
- $L_0 = [w]$, where w is the start node
- Mark w as visited
- **For** $i = 0, \dots, n-1$:
 - **For** u in L_i :
 - **For** each v which is a neighbor of u :
 - **If** v isn't yet visited:
 - mark v as visited, and put it in L_{i+1}

L_i is the set of nodes
we can reach in i
steps from w

Go through all the nodes
in L_i and add their
unvisited neighbors to L_{i+1}



BFS also finds all the nodes reachable from the starting point



It is also a good way to find all the **connected components**.

Running time and extension to directed graphs

- To explore the whole graph, explore the connected components one-by-one.
 - Same argument as DFS: BFS running time is $O(n + m)$
- Like DFS, BFS also works fine on directed graphs.

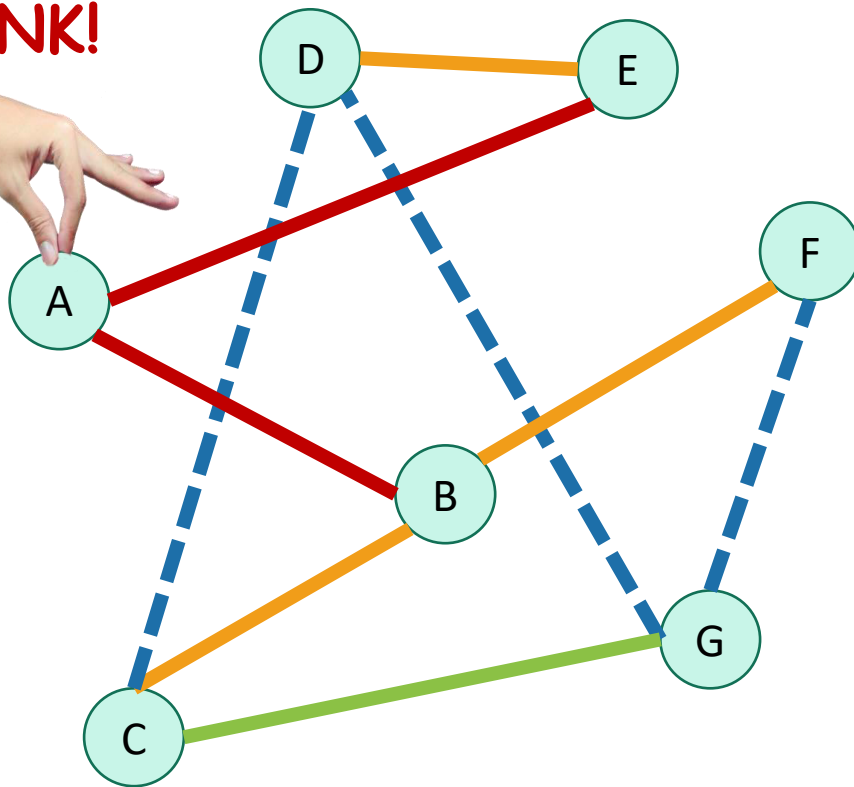
Verify these!



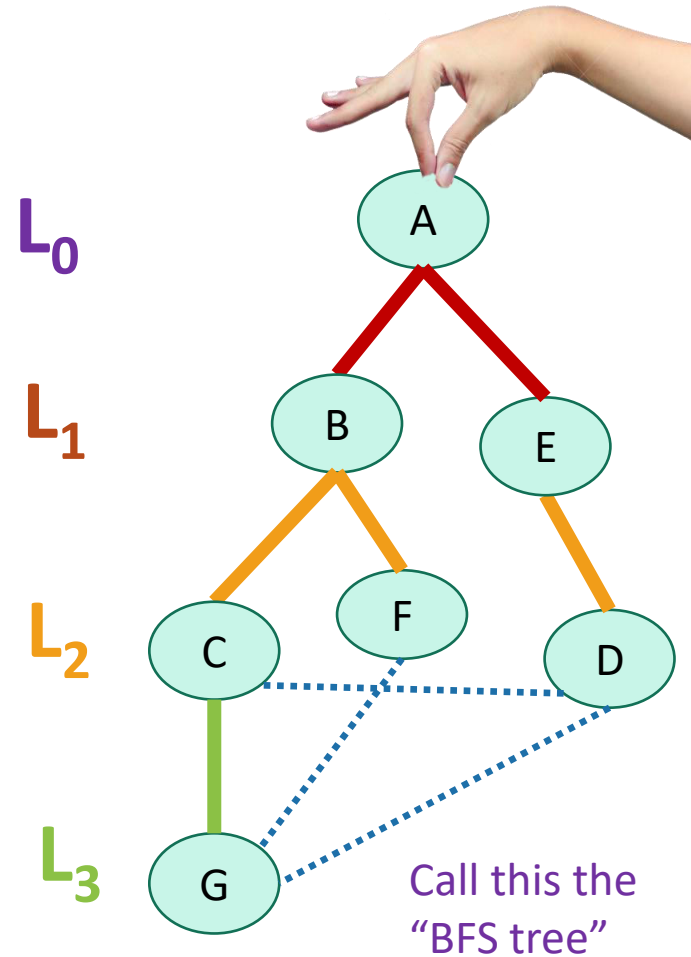
Why is it called breadth-first?

- We are implicitly building a tree:

YOINK!

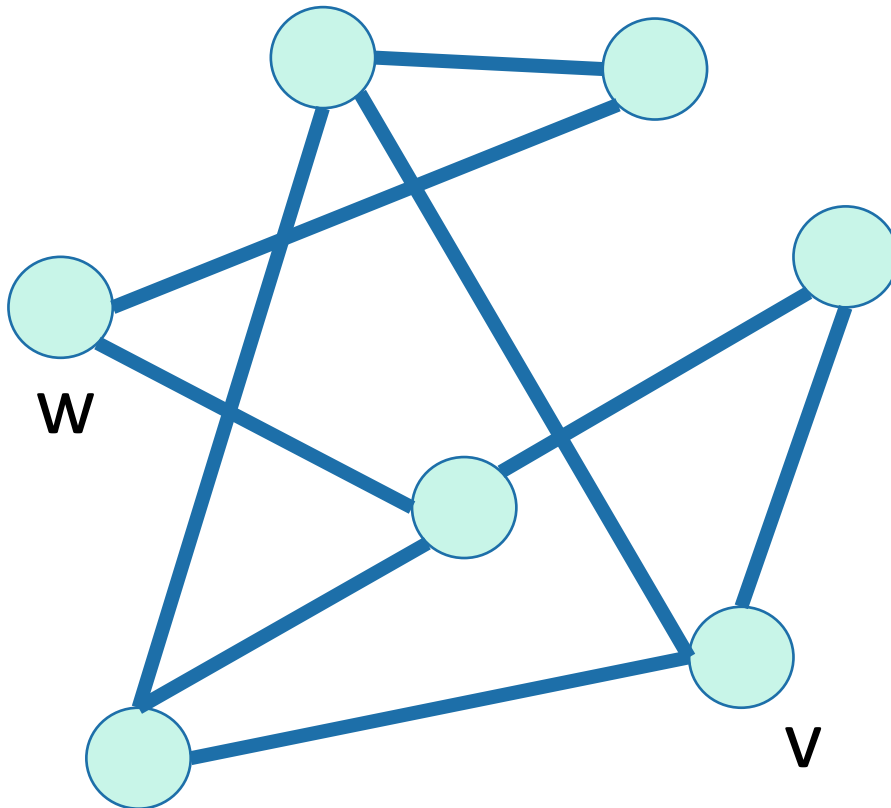


- First we go as broadly as we can.



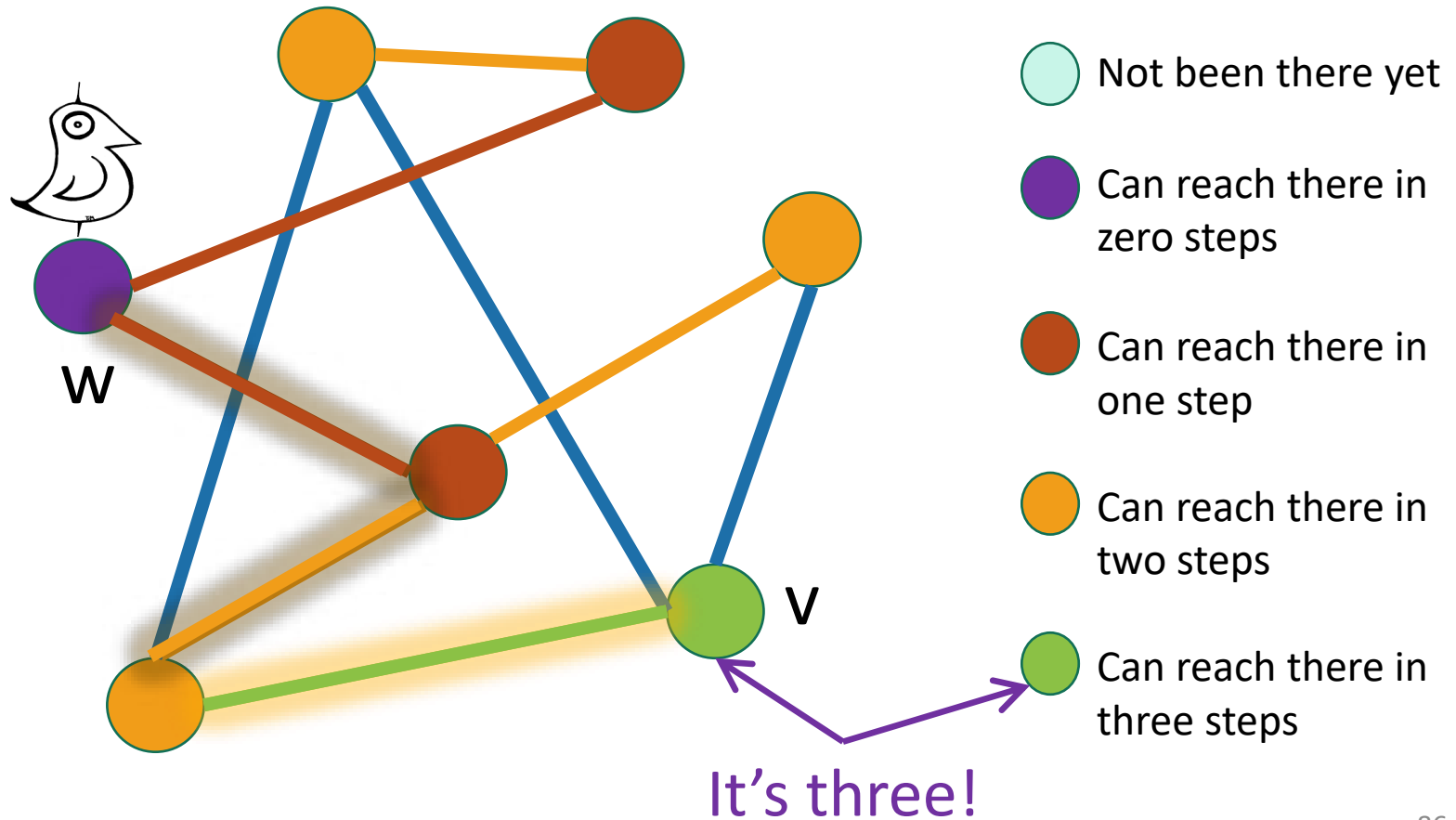
Application of BFS: shortest path

- How long is the shortest path between w and v?



Application of BFS: shortest path

- How long is the shortest path between w and v?

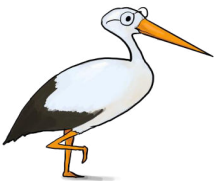


To find the **distance** between w and all other vertices v

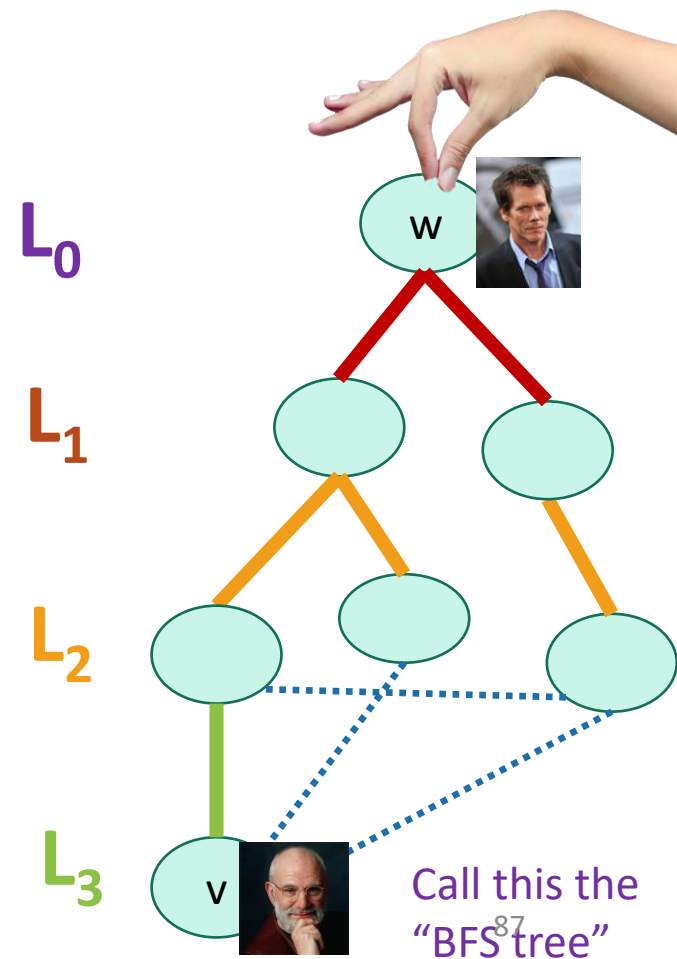
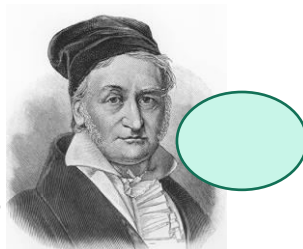
- Do a BFS starting at w
- For all v in L_i
 - The shortest path between w and v has length i
 - A shortest path between w and v is given by the path in the BFS tree.
- If we never found v , the distance is infinite.

The **distance** between two vertices is the number of edges in the shortest path between them.

Modify the BFS pseudocode to return shortest paths!
Prove that this indeed returns shortest paths!



Gauss has no Bacon number



Problem 2

Can you find two farthest nodes of a graph if it is a tree??

Problem 2

Can you find two farthest nodes of a graph if it is a tree??

"Called diameter of a tree"

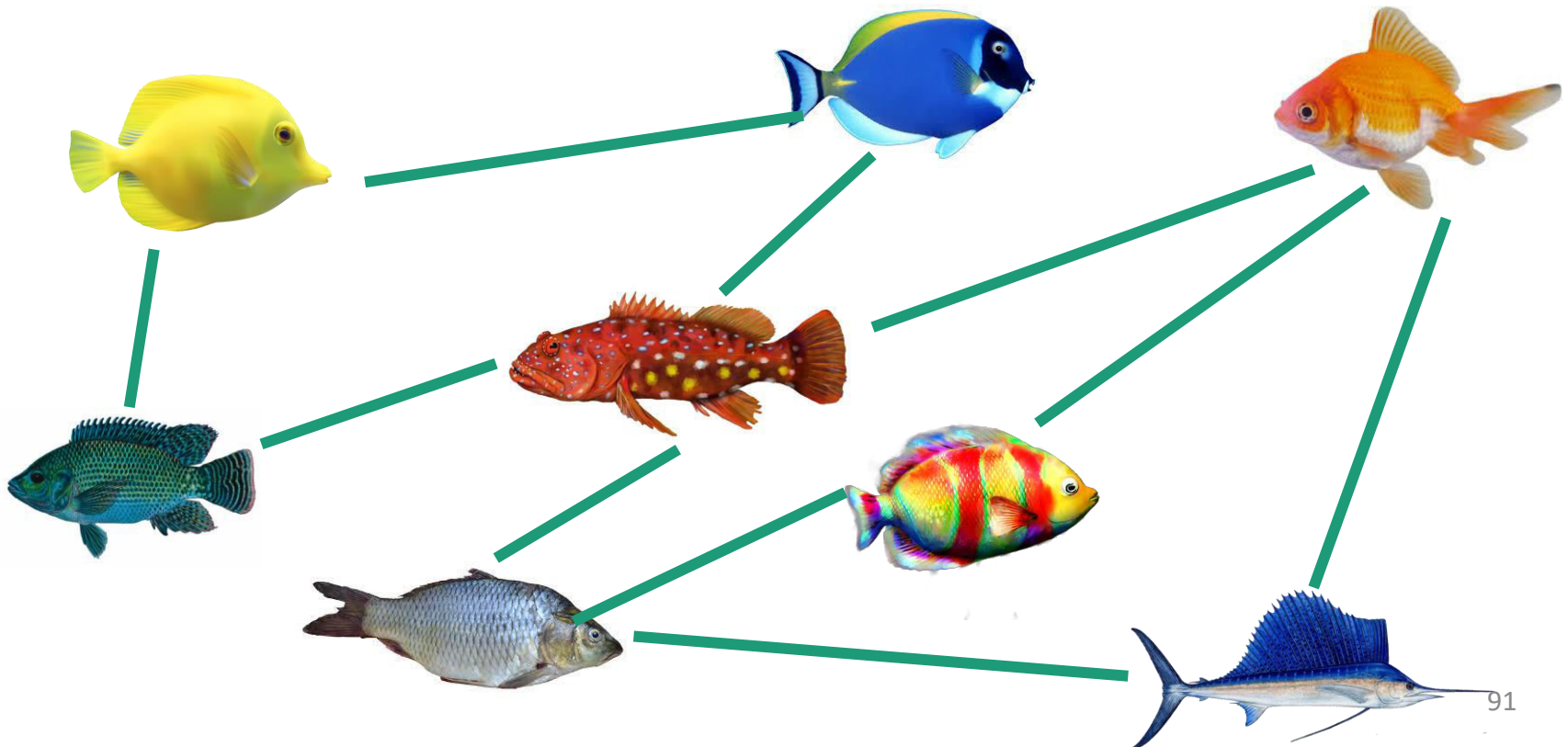
Problem 3

You are given a tree consisting of n nodes.

Your task is to determine for each node the sum of the distances from the node to all other nodes.

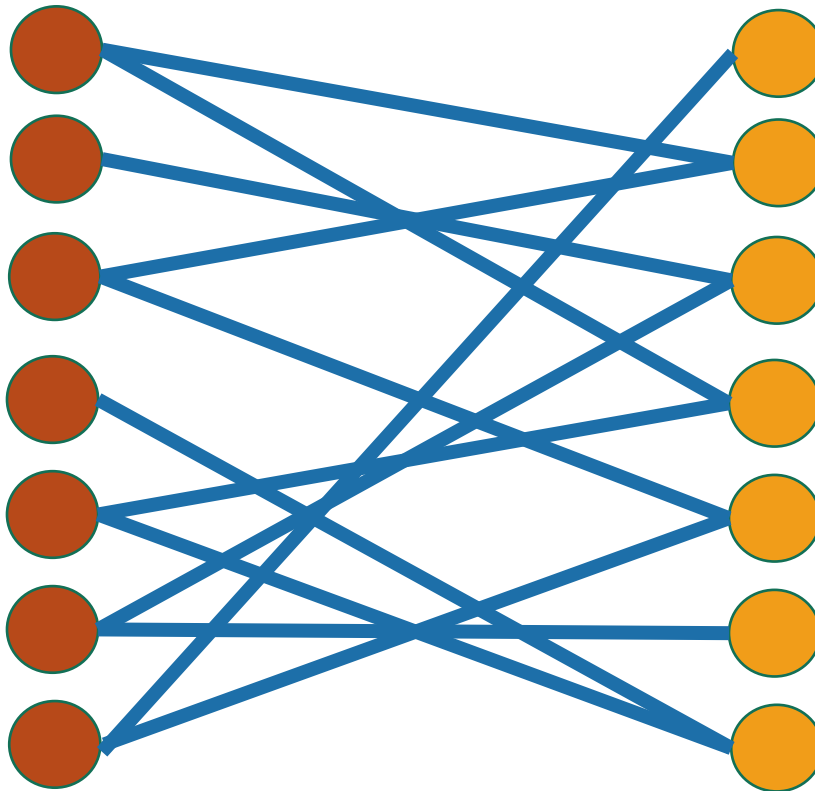
Pre-lecture exercise: fish

- You have a bunch of fish and two fish tanks.
- Some pairs of fish will fight if put in the same tank.
 - Model this as a graph: connected fish will fight.
- Can you put the fish in the two tanks so that there is no fighting?



Bipartite graphs

- A bipartite graph looks like this:



Can color the vertices red and orange so that there are no edges between any same-colored vertices

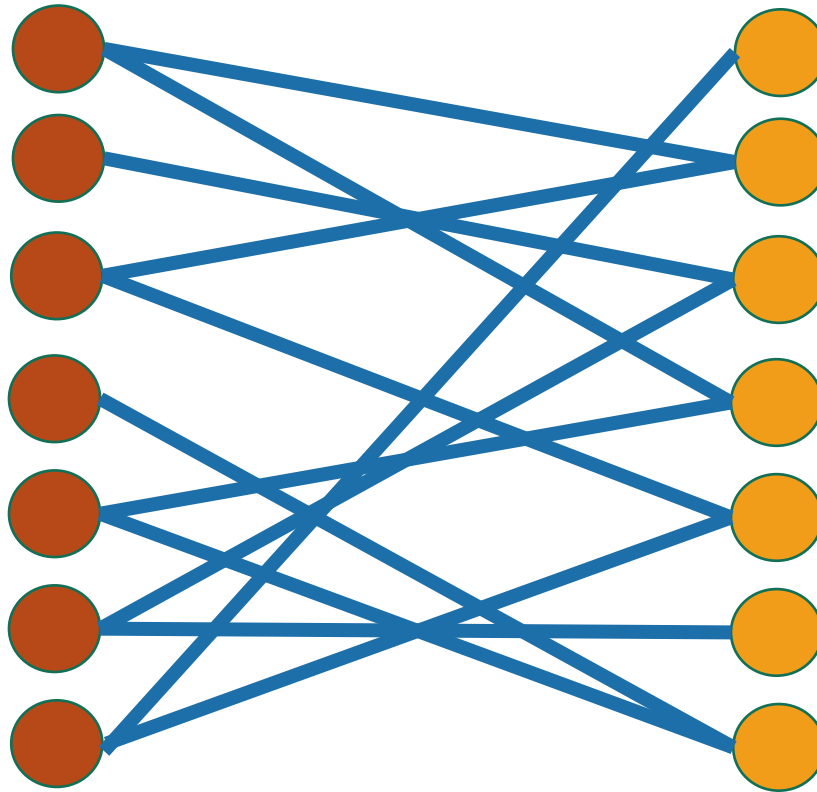
Example:

- are in tank A
- are in tank B
- — ● if the fish fight

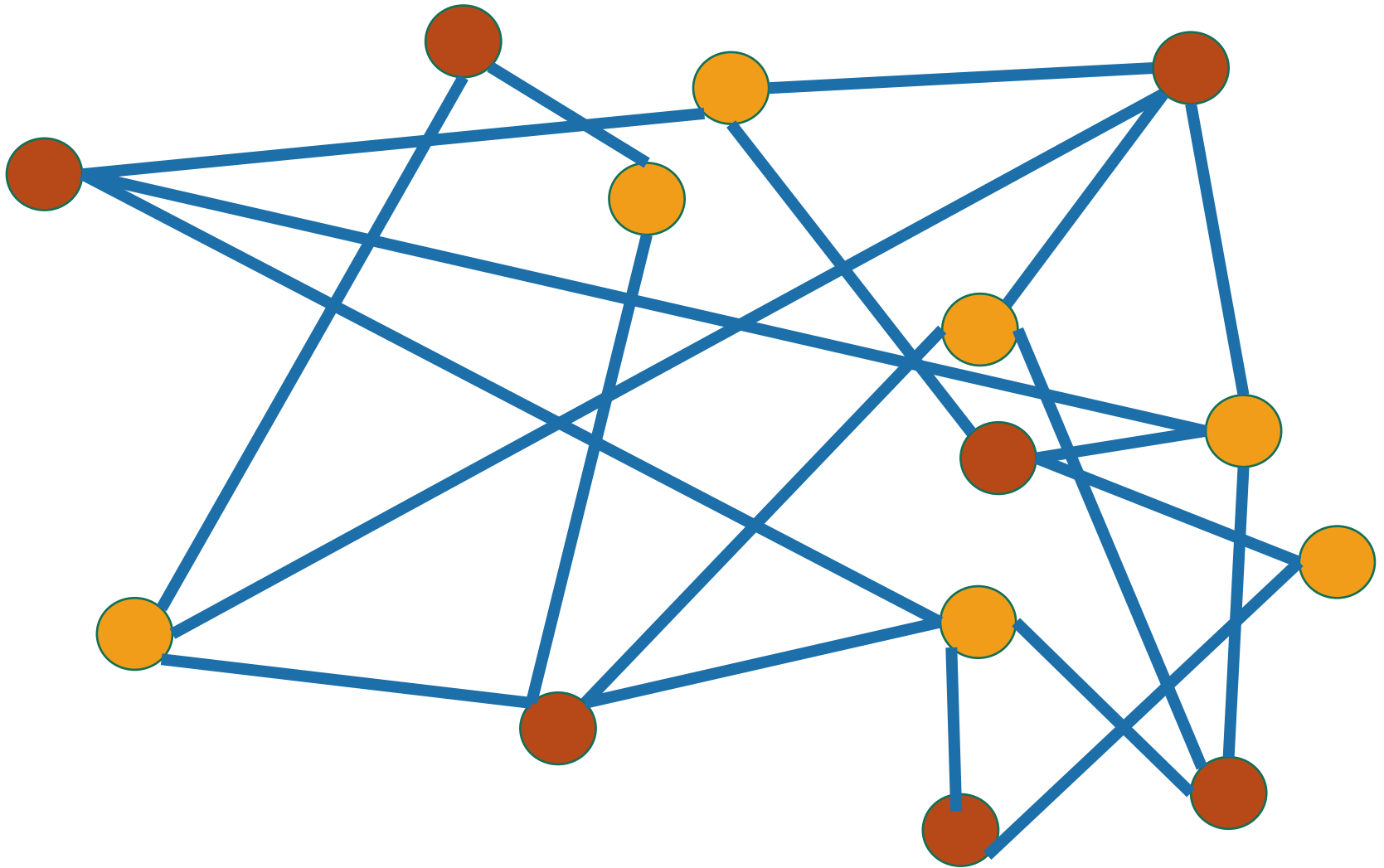
Example:

- are students
- are classes
- — ● if the student is enrolled in the class

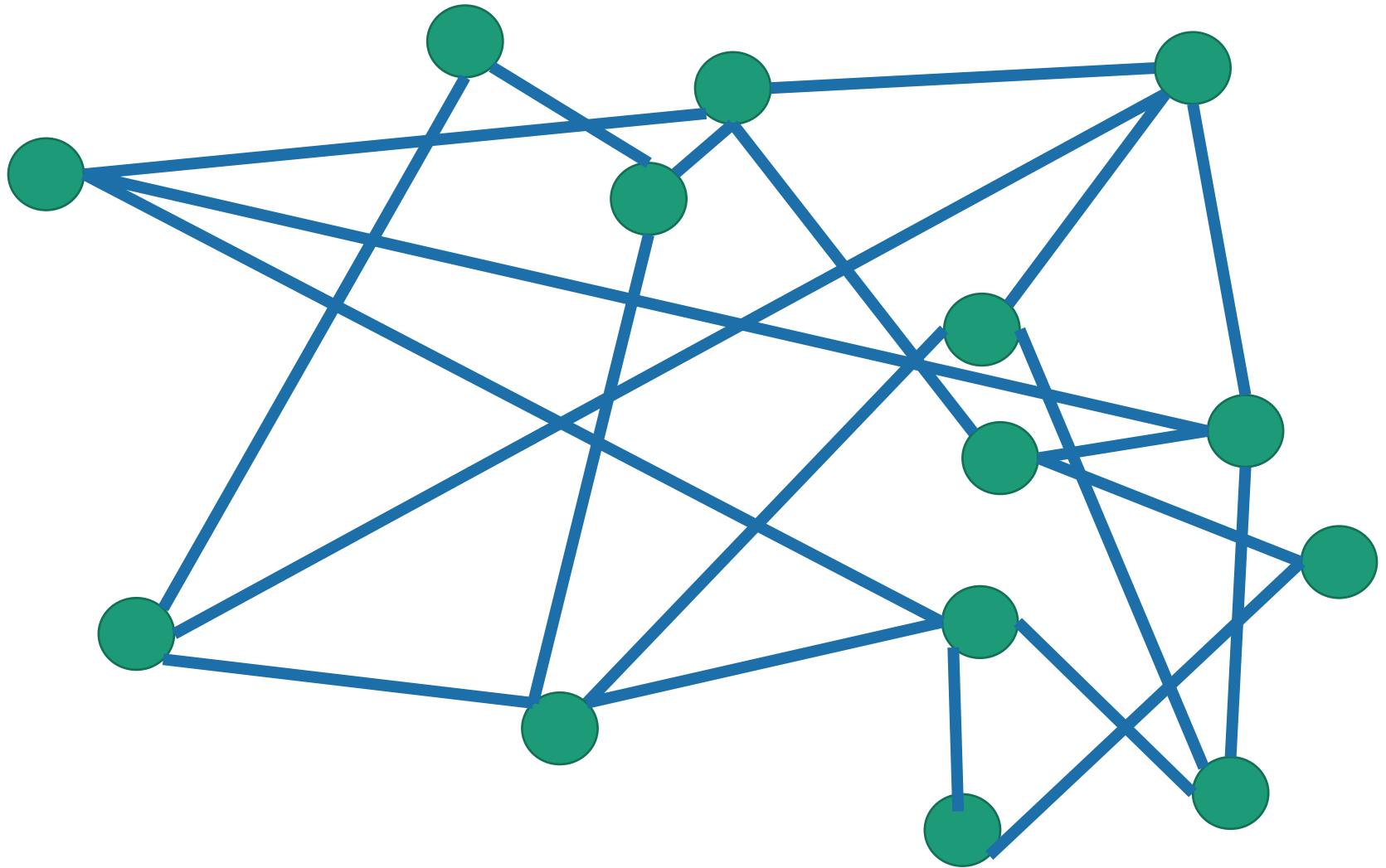
Is this graph bipartite?



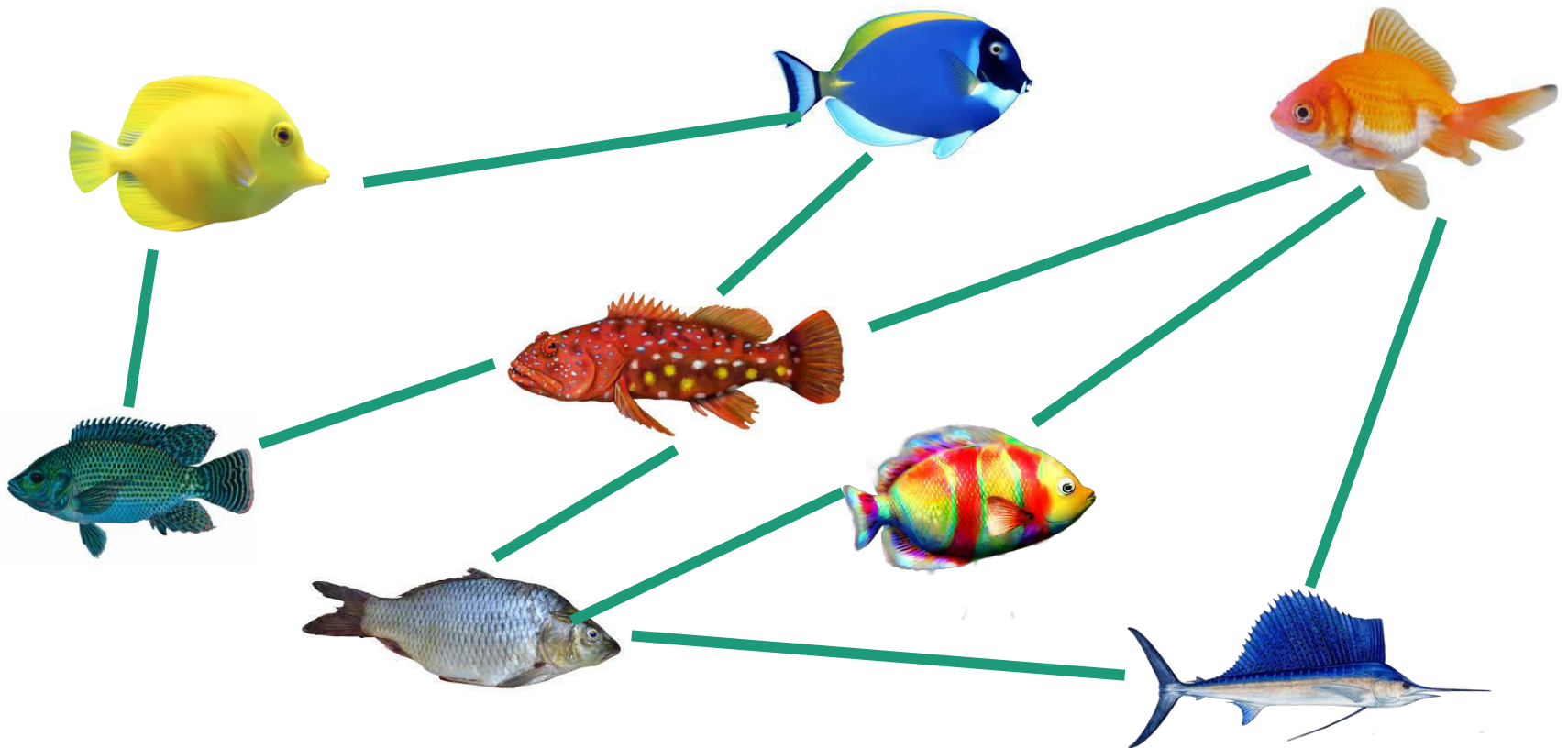
How about this one?



How about this one?

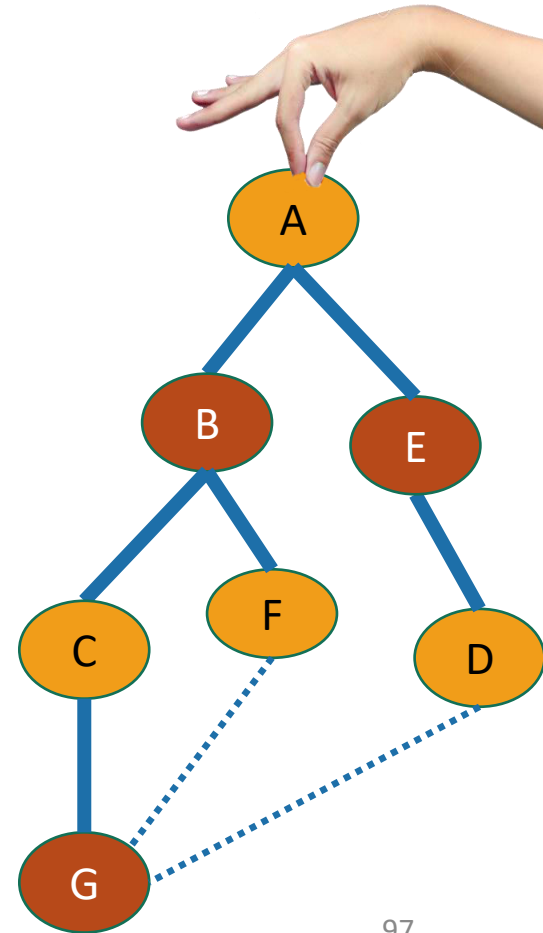


This one?



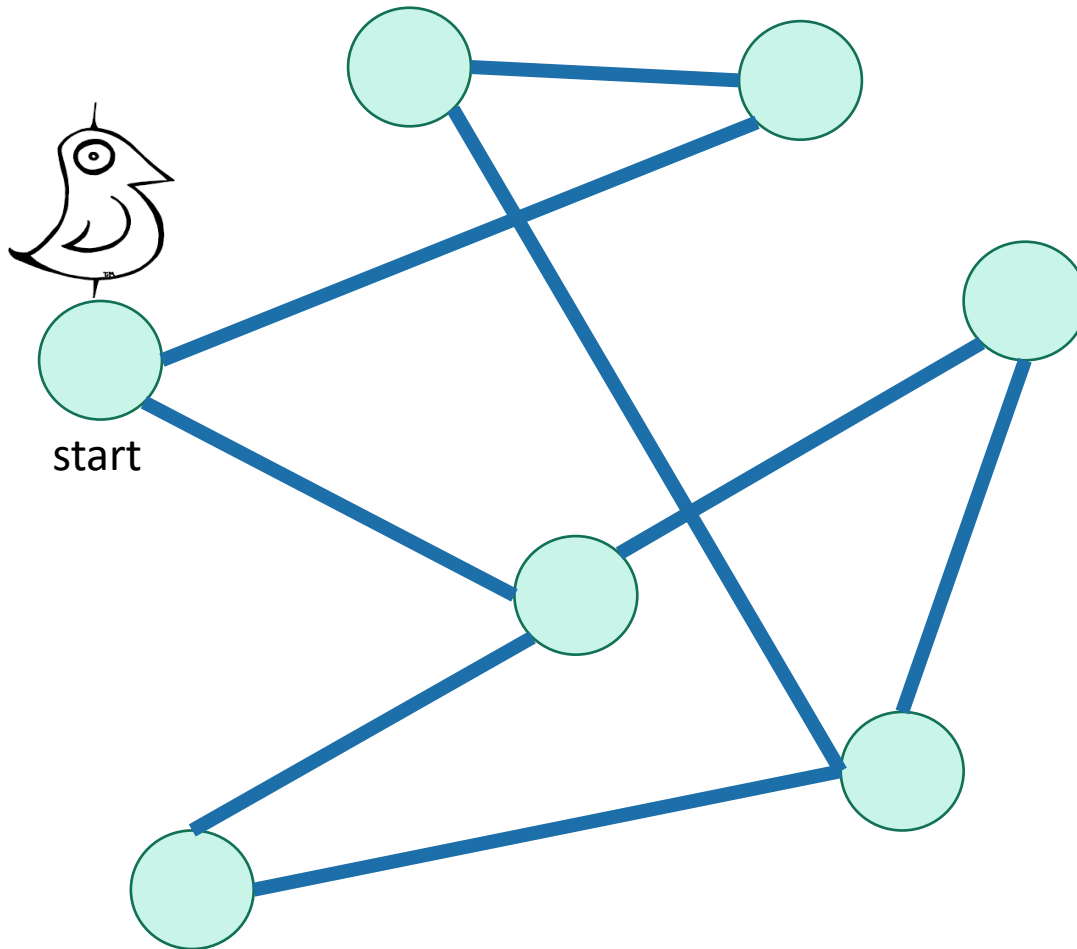
Application of BFS: Testing Bipartiteness






- Color the levels of the BFS tree in alternating colors.
- If you never color two connected nodes the same color, then it is bipartite.
- Otherwise, it's not.



Breadth-First Search

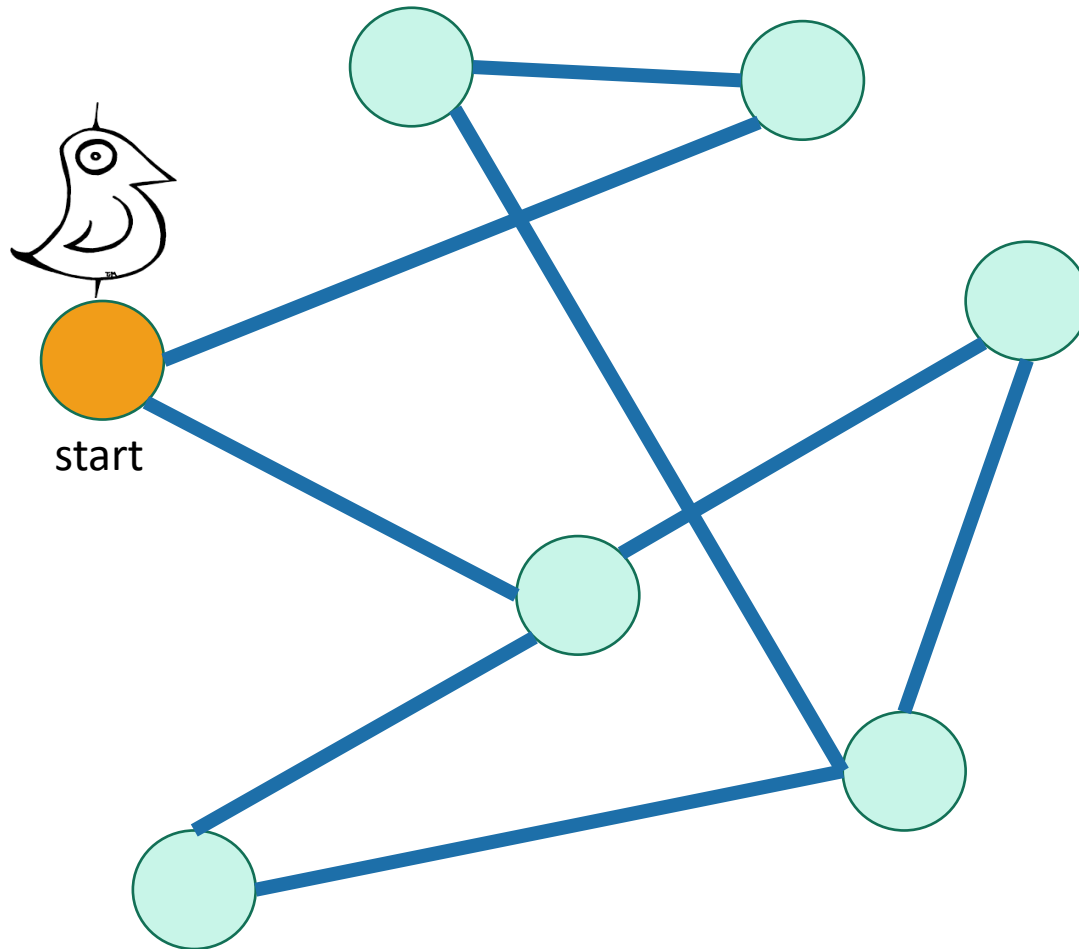
For testing bipartite-ness








-  Not been there yet
-  Can reach there in zero steps
-  Can reach there in one step
-  Can reach there in two steps
-  Can reach there in three steps

Breadth-First Search

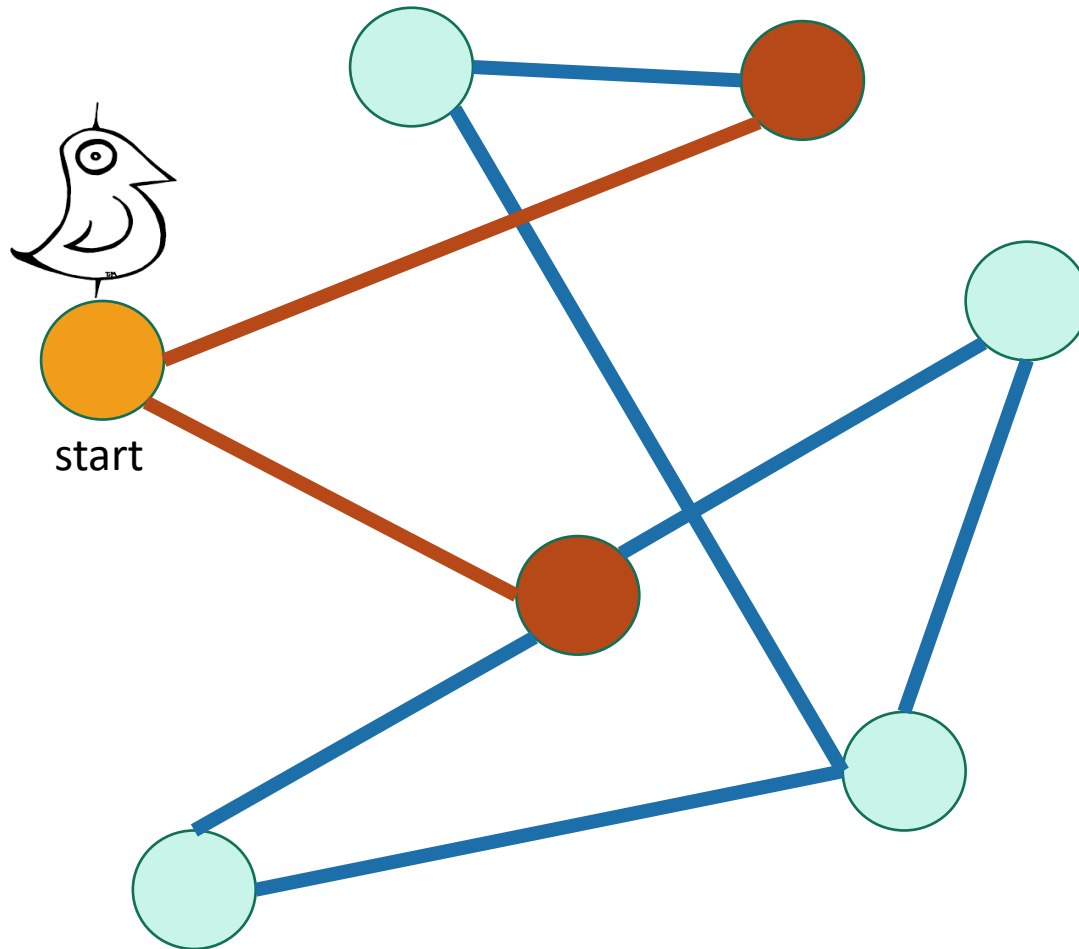
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Breadth-First Search

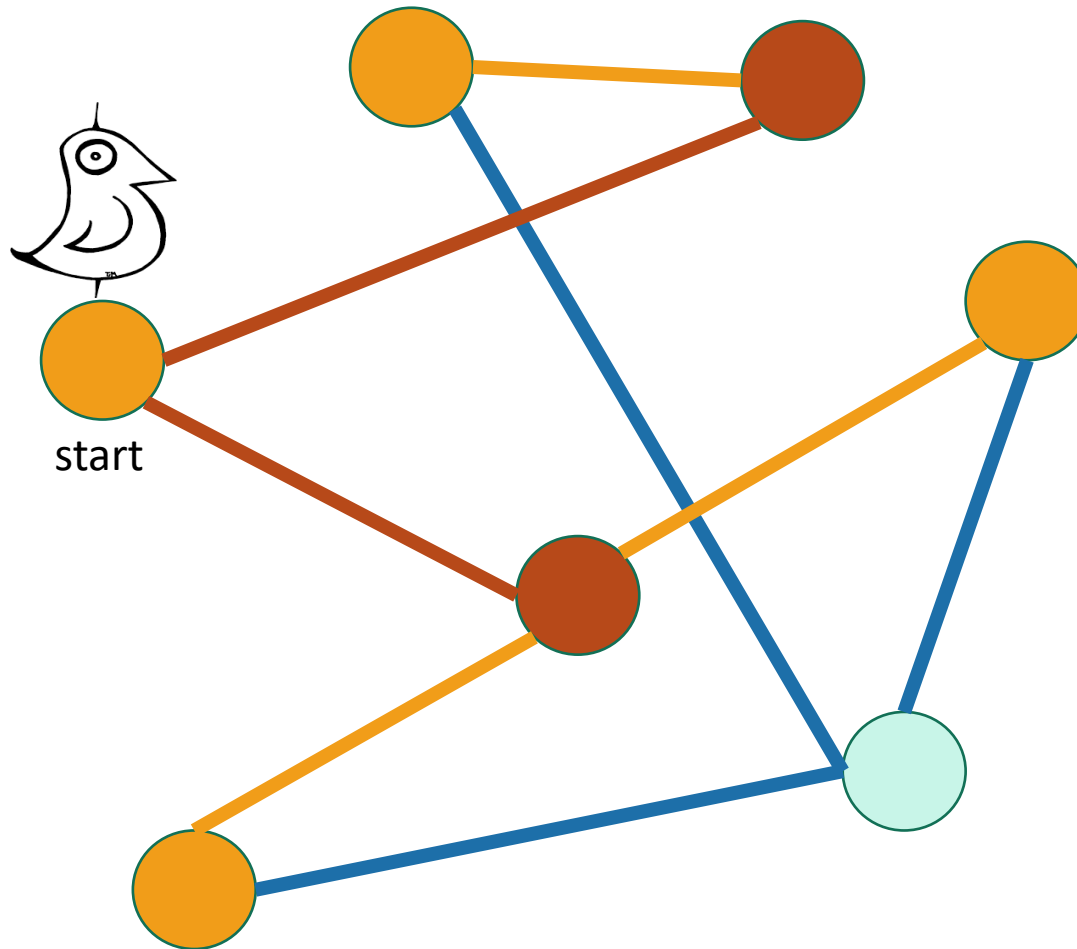
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Breadth-First Search

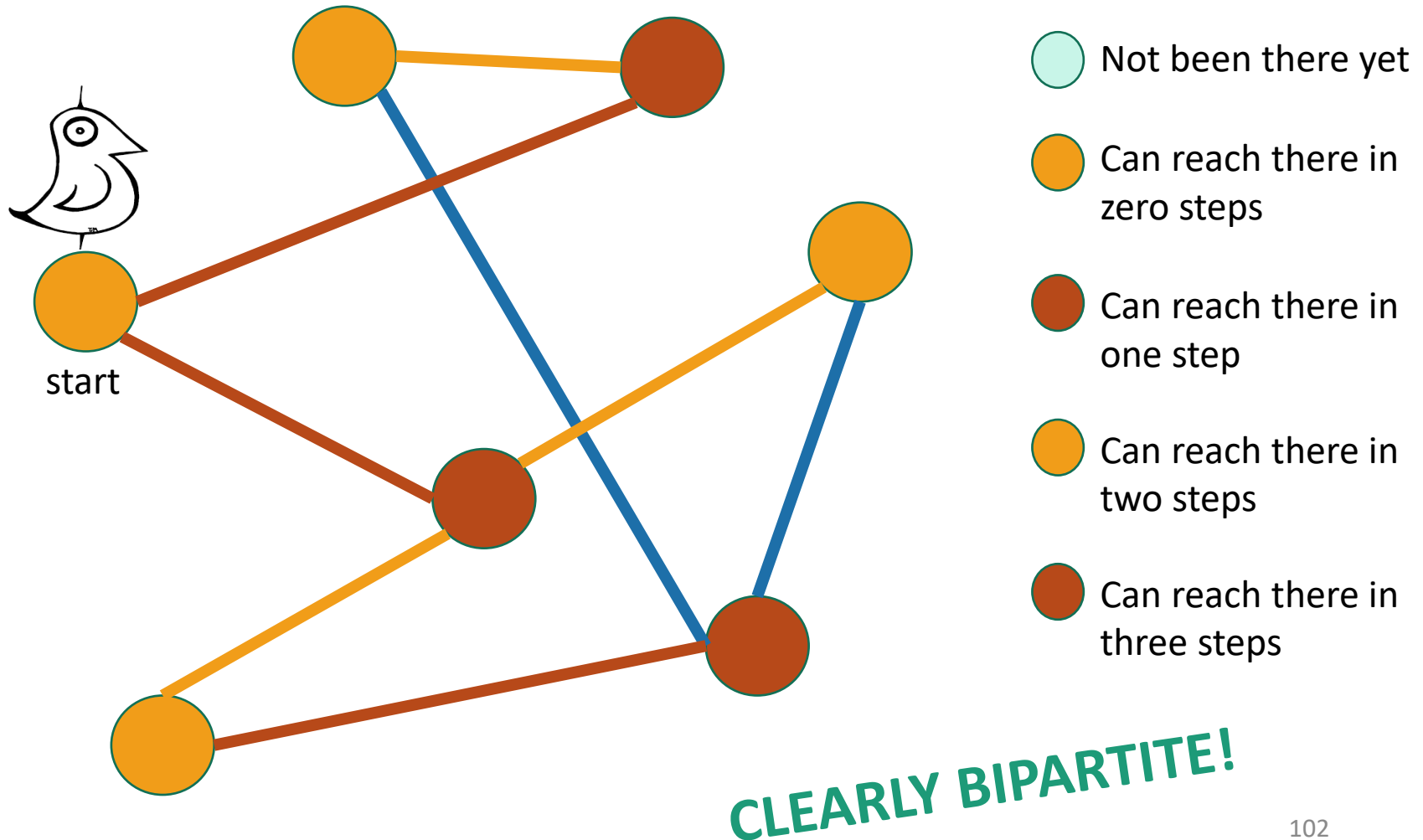
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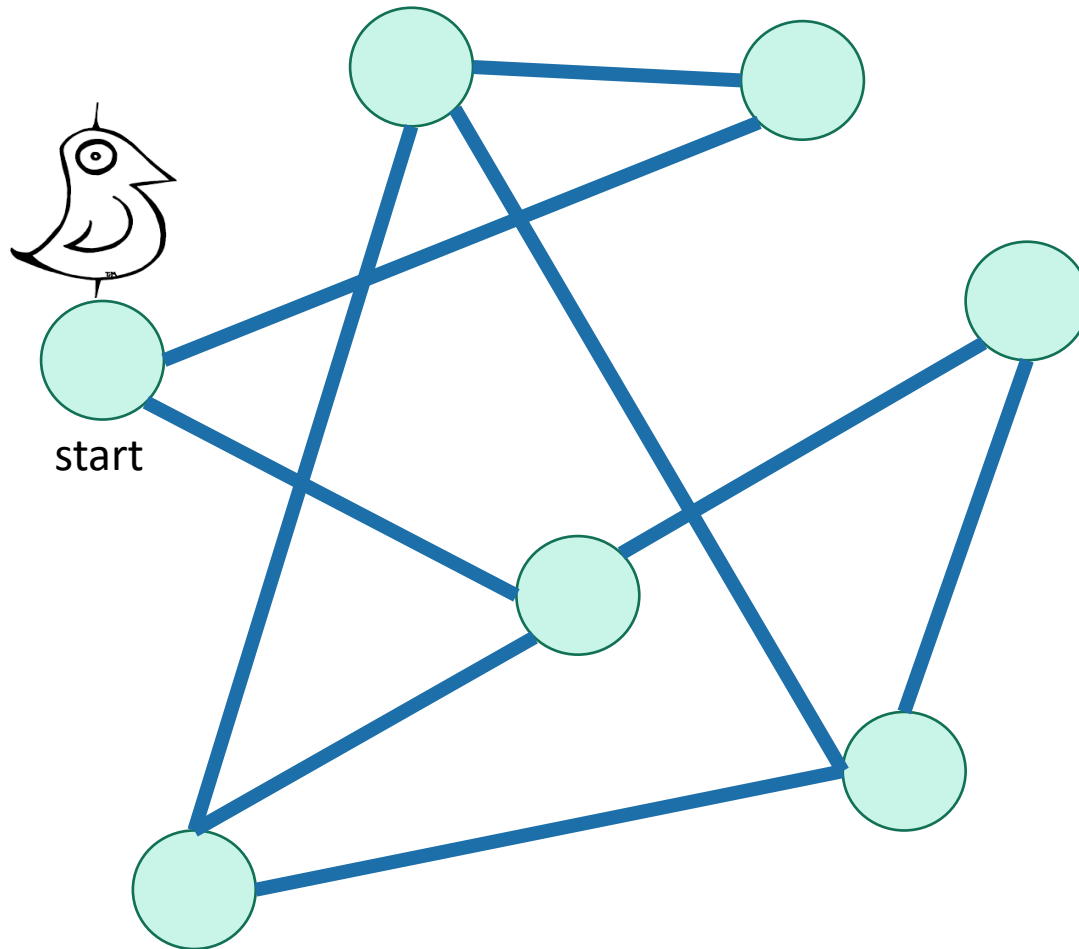
Breadth-First Search






For testing bipartite-ness



Breadth-First Search

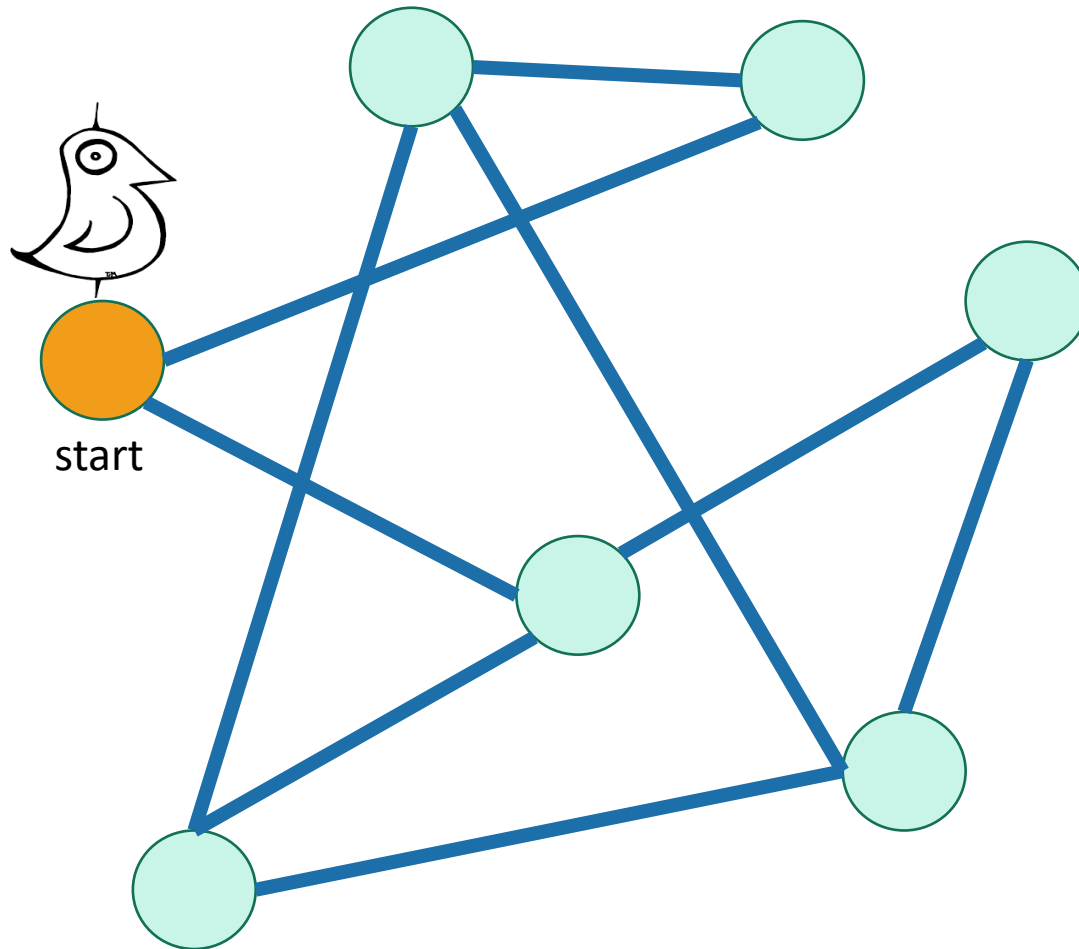
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Breadth-First Search

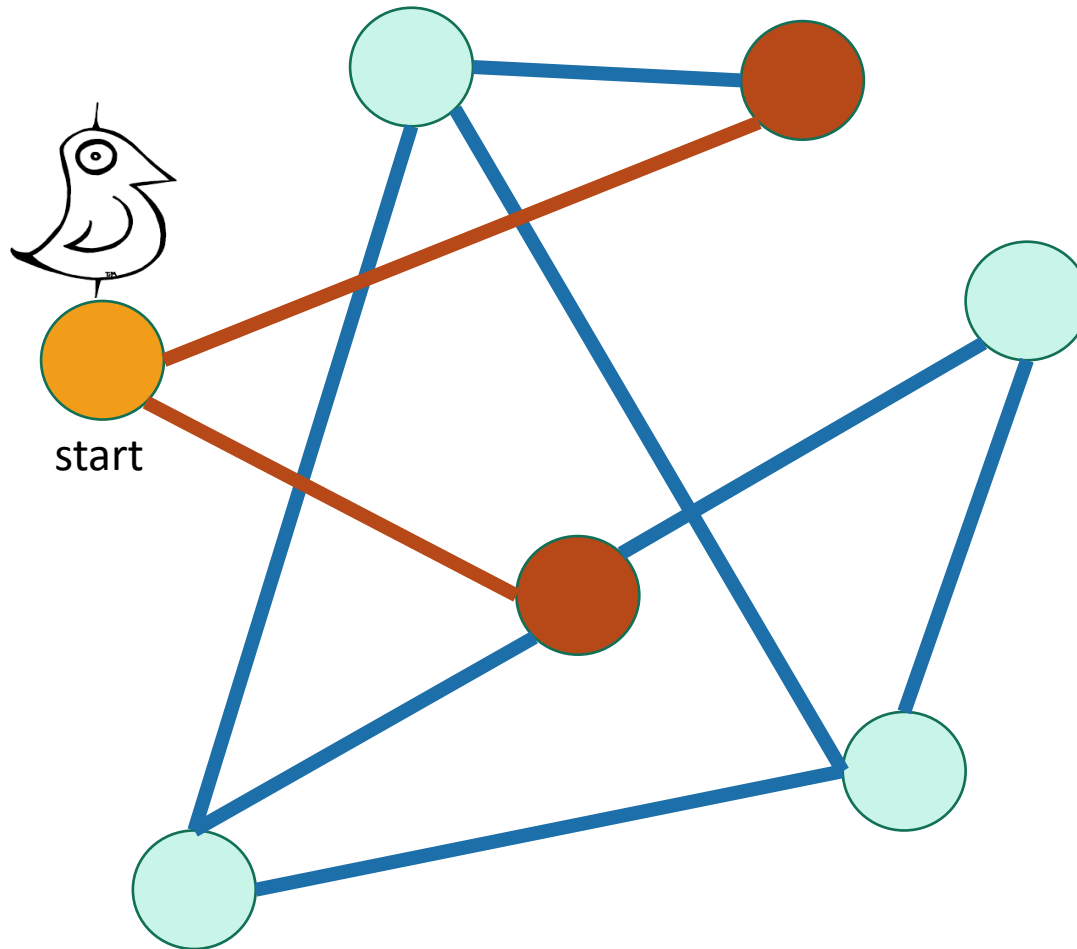
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Breadth-First Search

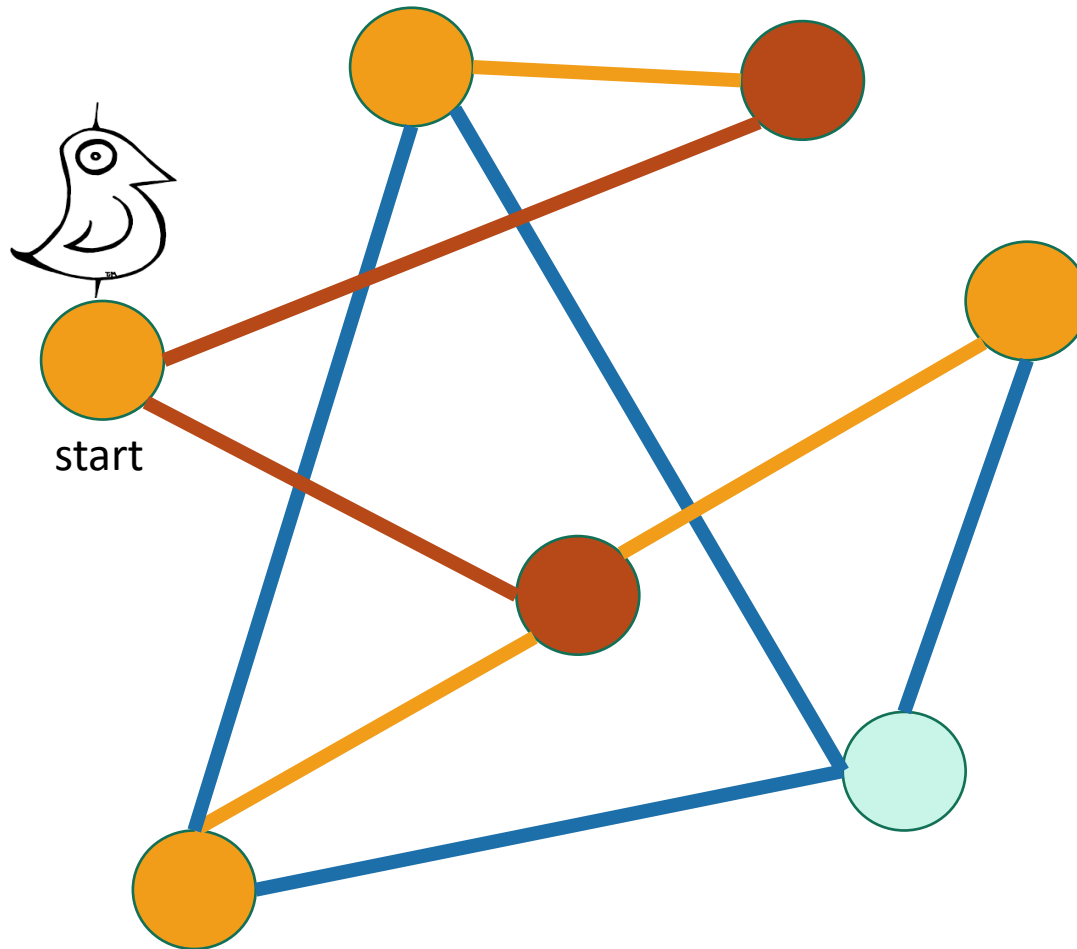
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Breadth-First Search

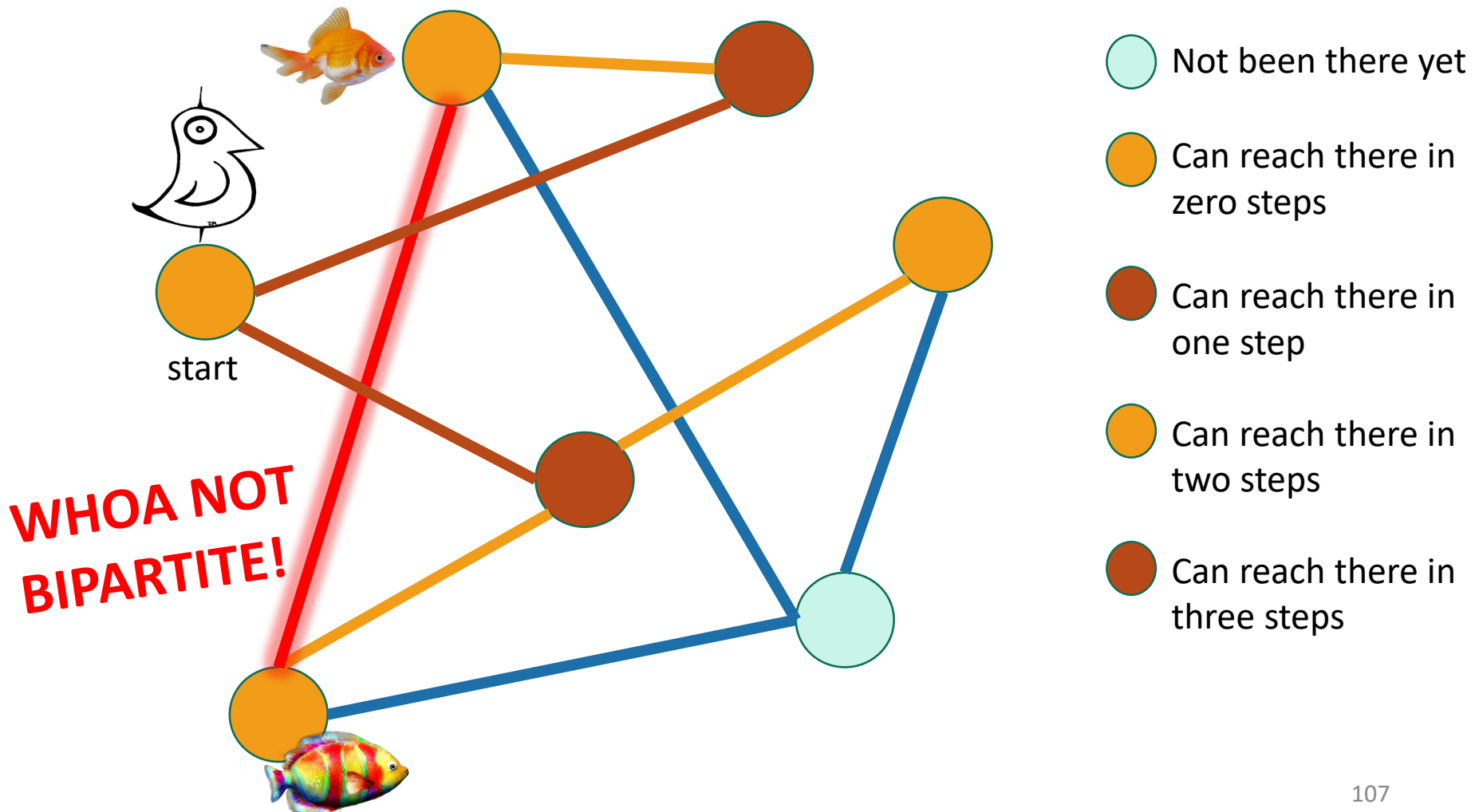
For testing bipartite-ness



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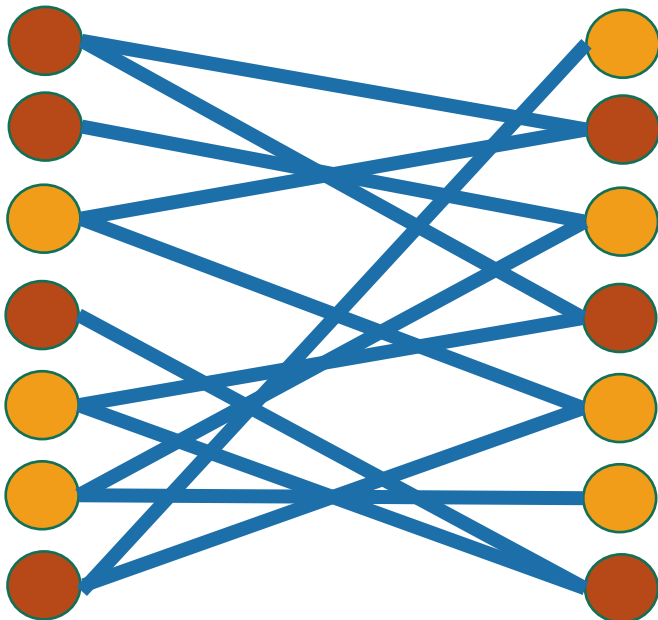
Breadth-First Search

For testing bipartite-ness



Hang on now.

- Just because **this** coloring doesn't work, why does that mean that there is **no** coloring that works?



I can come up
with plenty of bad
colorings on this
legitimately
bipartite graph...



Plucky the
pedantic penguin

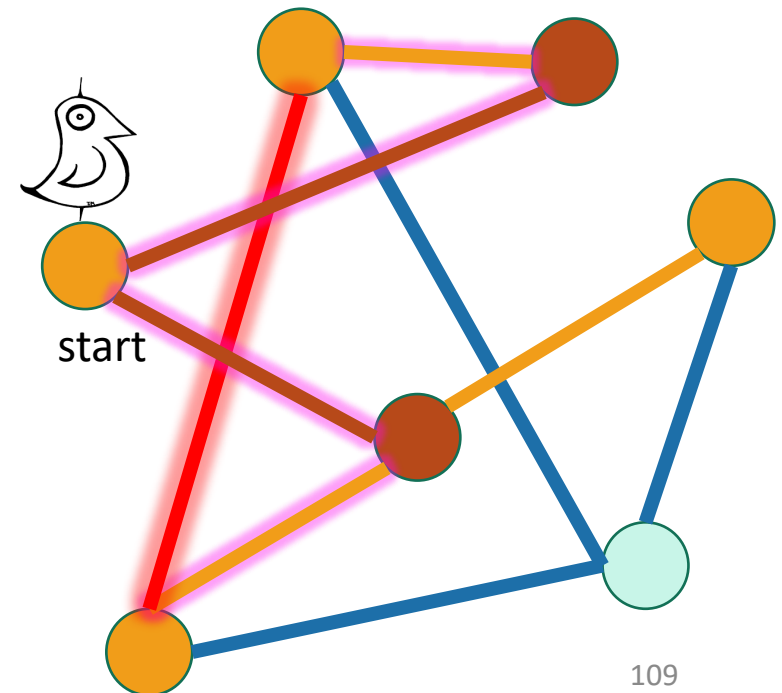
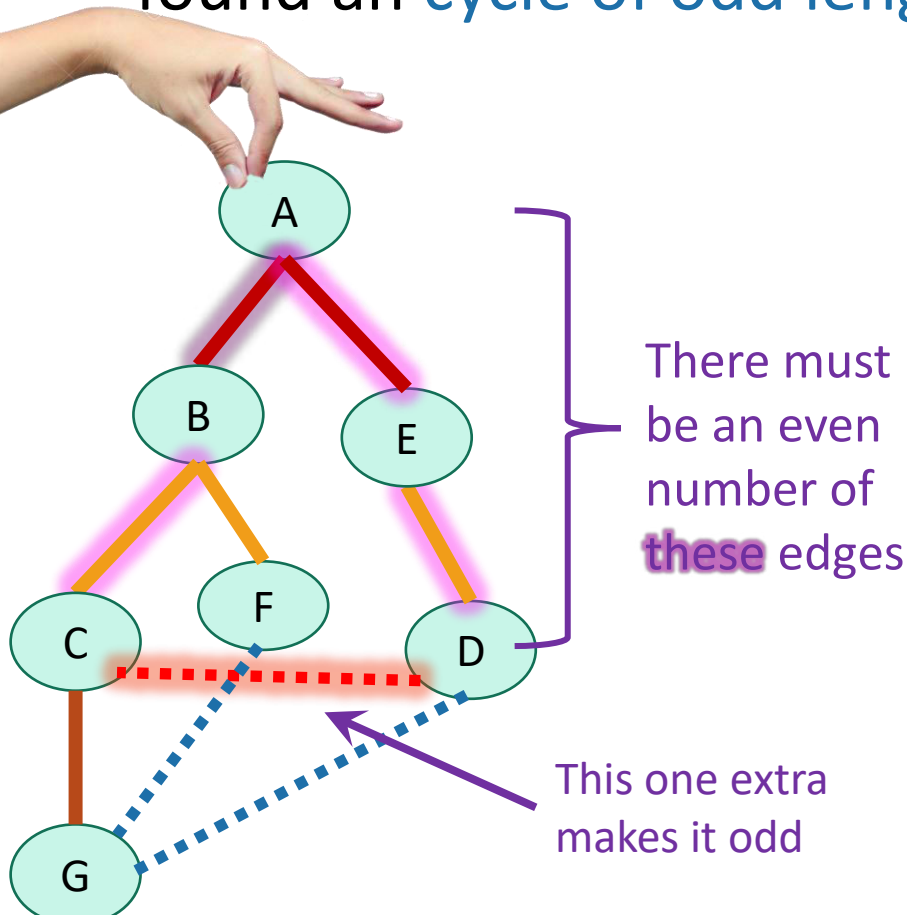
Make this proof
sketch formal!



Ollie the over-achieving ostrich

Some proof required

- If BFS colors two neighbors the same color, then it's found an **cycle of odd length** in the graph.



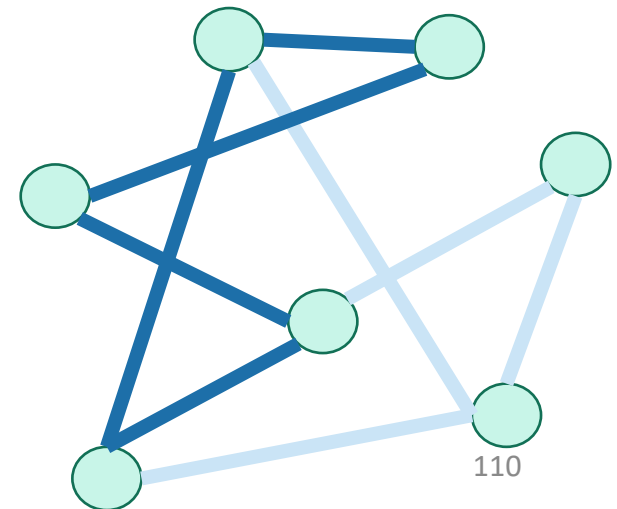
Make this proof
sketch formal!



Ollie the over-achieving ostrich

Some proof required

- If BFS colors two neighbors the same color, then it's found an **cycle of odd length** in the graph.
- But you can **never** color an odd cycle with two colors so that no two neighbors have the same color.
 - [Fun exercise!]
- So you can't legitimately color the whole graph either.
- **Thus it's not bipartite.**



What have we learned?

BFS can be used to detect bipartite-ness in time $O(n + m)$.



What about tripartite?

What about tripartite?

- Very Hard
- NP-complete

Thank You