

Vector Calculus

Vector Differentiation

If $\mathbf{F}(t) = ti + t^2 j + t^3 k$ find $\frac{d\bar{F}}{dt}$, $\frac{d^2 \bar{F}}{dt^2}$, $\frac{d\bar{F}}{dt} \times \frac{d^2 \bar{F}}{dt^2}$

$$\frac{d\bar{F}}{dt} = i + 2tj + 3t^2k \quad \frac{d^2 \bar{F}}{dt^2} = 2j + 6tk$$

$$\frac{d\bar{F}}{dt} \times \frac{d^2 \bar{F}}{dt^2} = \begin{vmatrix} i & j & k \\ 1 & 2t & 3t^2 \\ 0 & 2 & 6t \end{vmatrix} = 6t^2i + 6tj + 2k$$

Product formula

$$\frac{d(\bar{F} \cdot \bar{G})}{dt} = \bar{F} \cdot \frac{d\bar{G}}{dt} + \bar{G} \cdot \frac{d\bar{F}}{dt}$$

$$\frac{d(\bar{F}x\bar{G})}{dt} = \bar{F}x \frac{d\bar{G}}{dt} + \frac{d\bar{F}}{dt} x \bar{G}$$

Problem

Show that $\frac{d(\vec{P}x\vec{P}')}{dt} = \vec{P}x\vec{P}''$

$$\frac{d(\vec{P}x\vec{P}')}{dt} = \vec{P}x\vec{P}'' + \vec{P}'x\vec{P}' = \vec{P}x\vec{P}''$$

Problem of partial differentiation

If $\mathbf{a} = e^{st}i + (2s-t)j + t \sin sk$ find $\frac{\partial^2 \bar{a}}{\partial s^2}$, $\frac{\partial^2 \bar{a}}{\partial t^2}$, $\frac{\partial \bar{a}}{\partial s} \times \frac{\partial \bar{a}}{\partial t}$

$$\frac{\partial \bar{a}}{\partial s} = te^{st}i + 2j + t \cos sk \quad \frac{\partial^2 \bar{a}}{\partial s^2} = t^2e^{st}i - t \sin sk$$

$$\frac{\partial \bar{a}}{\partial t} = se^{st}i - j + \sin sk \quad \frac{\partial^2 \bar{a}}{\partial t^2} = s^2e^{st}i$$

$$\frac{\partial \bar{a}}{\partial s} \times \frac{\partial \bar{a}}{\partial t} = \begin{vmatrix} i & j & k \\ te^{st} & 2 & t \cos sk \\ se^{st} & -1 & \sin sk \end{vmatrix} = (2 \sin s + t \cos s)i + j(se^{st}t \cos s - e^{st} \sin s) + k(-te^{st} - 2se^{st})$$

Problem

Find a unit vector in the direction of $i \frac{\partial f}{\partial x} + j \frac{\partial f}{\partial y} + k \frac{\partial f}{\partial z}$ at (1, 0, 2)

where $f(x, y, z) = 4(x^2 + y^2) - z^2$

$$\frac{\partial f}{\partial x} = 8x \quad \frac{\partial f}{\partial y} = 8y \quad \frac{\partial f}{\partial z} = -2z$$

$$i \frac{\partial f}{\partial x} + j \frac{\partial f}{\partial y} + k \frac{\partial f}{\partial z} = 8xi + 8yj - 2zk = 8i - 4k$$

Unit vector along $i \frac{\partial f}{\partial x} + j \frac{\partial f}{\partial y} + k \frac{\partial f}{\partial z}$ is $\frac{8i - 4k}{\sqrt{80}} = \frac{2i - k}{\sqrt{5}}$

Gradient, Divergence and Curl

The vector operator ∇ (del or nabla) is defined by $\nabla = i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z}$

Definitions:

1. **Gradient-** If $\phi = \phi(x, y, z)$ is scalar point function then gradient of ϕ written as $\text{grad } \phi$ or $\nabla \phi$ is defined as

$$\begin{aligned} \nabla \phi &= \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \phi \quad (\text{vector quantity}) \\ &= i \frac{\partial \phi}{\partial x} + j \frac{\partial \phi}{\partial y} + k \frac{\partial \phi}{\partial z} \end{aligned}$$

2. **Divergence-** If $\mathbf{v} = v(x, y, z) = v_1(x, y, z)i + v_2(x, y, z)j + v_3(x, y, z)k$ is a vector point function then divergence of \mathbf{v} written as $\text{div } \mathbf{v}$ or $\nabla \cdot \mathbf{v}$ is defined as

$$\begin{aligned} \nabla \cdot \mathbf{v} &= \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \cdot (v_1i + v_2j + v_3k) \\ &= \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z} \quad (\text{scalar quantity}) \quad \nabla \cdot \mathbf{v} \neq \mathbf{v} \cdot \nabla \end{aligned}$$

3. **Curl-** If $\mathbf{v} = v(x, y, z) = v_1(x, y, z)i + v_2(x, y, z)j + v_3(x, y, z)k$ is a vector point function then curl of \mathbf{v} written as $\text{curl } \mathbf{v}$ or $\nabla \times \mathbf{v}$ is defined as

$$\nabla \times \mathbf{v} = \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \times (v_1i + v_2j + v_3k)$$

$$= \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_1 & v_2 & v_3 \end{vmatrix} = i \left(\frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \right) + j \left(\frac{\partial v_1}{\partial z} - \frac{\partial v_3}{\partial x} \right) + k \left(\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \right) \text{ (vector quantity)}$$

Problem

1. If $f(x, y, z) = 3x^2y - y^3z^2$ find ∇f at the point P(1, -2, -1)

$$\begin{aligned} \nabla f &= i \frac{\partial(3x^2y - y^3z^2)}{\partial x} + j \frac{\partial(3x^2y - y^3z^2)}{\partial y} + k \frac{\partial(3x^2y - y^3z^2)}{\partial z} \\ &= 6xyi + (3x^2 - 3y^2z^2)j + 2y^3zk \\ \nabla f(1, -2, -1) &= -12i - 9j - 16k \end{aligned}$$

2. Ex. If $\phi = \frac{1}{r}$ and $r = \sqrt{x^2 + y^2 + z^2}$ find $\nabla \phi$

$$\begin{aligned} \nabla \phi &= \nabla \frac{1}{r} = i \frac{\partial}{\partial x} \left(\frac{1}{r} \right) + j \frac{\partial}{\partial y} \left(\frac{1}{r} \right) + k \frac{\partial}{\partial z} \left(\frac{1}{r} \right) \\ &= i \frac{\partial}{\partial r} \left(\frac{1}{r} \right) \frac{\partial r}{\partial x} + j \frac{\partial}{\partial r} \left(\frac{1}{r} \right) \frac{\partial r}{\partial y} + k \frac{\partial}{\partial r} \left(\frac{1}{r} \right) \frac{\partial r}{\partial z}, \quad r^2 = x^2 + y^2 + z^2 \quad 2r \frac{\partial r}{\partial x} = 2x \\ &= -\frac{1}{r^3} xi - \frac{1}{r^3} yj - \frac{1}{r^3} zk \quad \frac{\partial r}{\partial x} = \frac{x}{r} \quad \frac{\partial r}{\partial y} = \frac{y}{r} \quad \frac{\partial r}{\partial z} = \frac{z}{r} \\ &= -\frac{1}{r^3}(xi + yj + zk) \quad = -\frac{1}{r^3} \mathbf{r} \end{aligned}$$

3. Ex. If $\mathbf{A} = x^2z^2i - 2y^2z^2j + xy^2zk$ find $\nabla \cdot \mathbf{A}$ at P(1, -1, 1)

$$\begin{aligned} \nabla \cdot \mathbf{A} &= \frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \\ &= \frac{\partial}{\partial x}(x^2z^2) + \frac{\partial}{\partial y}(-2y^2z^2) + \frac{\partial}{\partial z}(xy^2z) \\ &= 2xz^2 - 4yz^2 + xy^2 \\ \nabla \cdot \mathbf{A}(1, -1, 1) &= 2 + 4 + 1 = 7 \end{aligned}$$

4. Ex. If $\mathbf{A} = x^2z^2i - 2y^2z^2j + xy^2zk$ find $\nabla \times \mathbf{A}$ at P(1, -1, 1)

$$\nabla \times \mathbf{A} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2z^2 & -2y^2z^2 & xy^2z \end{vmatrix}$$

$$\begin{aligned}
&= i \left(\frac{\partial(xy^2z)}{\partial y} - \frac{\partial(-2y^2z^2)}{\partial z} \right) + j \left(\frac{\partial(x^2z^2)}{\partial z} - \frac{\partial(xy^2z)}{\partial x} \right) + k \left(\frac{\partial(-2y^2z^2)}{\partial x} - \frac{\partial(x^2z^2)}{\partial y} \right) \\
&= (2xyz + 4yz^2)i + (y^2z - 2x^2z)j \\
&\text{hence at } P, \nabla x \mathbf{A} = 2i + j
\end{aligned}$$

1. Prove that $\nabla \cdot (\phi \mathbf{A}) = (\nabla \phi) \cdot \mathbf{A} + \phi (\nabla \cdot \mathbf{A})$

hence find $\nabla \cdot (r^3 \mathbf{r})$

Let $\mathbf{A} = A_1 \mathbf{i} + A_2 \mathbf{j} + A_3 \mathbf{k}$

$$\nabla \cdot (\phi \mathbf{A}) = \nabla \cdot (\phi A_1 \mathbf{i} + \phi A_2 \mathbf{j} + \phi A_3 \mathbf{k})$$

$$\begin{aligned}
&= \frac{\partial}{\partial x}(\phi A_1) + \frac{\partial}{\partial y}(\phi A_2) + \frac{\partial}{\partial z}(\phi A_3) \\
&= \phi \frac{\partial A_1}{\partial x} + A_1 \frac{\partial \phi}{\partial x} + \phi \frac{\partial A_2}{\partial y} + A_2 \frac{\partial \phi}{\partial y} + \phi \frac{\partial A_3}{\partial z} + A_3 \frac{\partial \phi}{\partial z} \\
&= \frac{\partial \phi}{\partial x} A_1 + \frac{\partial \phi}{\partial y} A_2 + \frac{\partial \phi}{\partial z} A_3 + \phi \frac{\partial A_1}{\partial x} + \phi \frac{\partial A_2}{\partial y} + \phi \frac{\partial A_3}{\partial z} \\
&= \left(\frac{\partial \phi}{\partial x} i + \frac{\partial \phi}{\partial y} j + \frac{\partial \phi}{\partial z} k \right) \cdot (A_1 \mathbf{i} + A_2 \mathbf{j} + A_3 \mathbf{k}) + \phi \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) \\
&= (\nabla \phi) \cdot \mathbf{A} + \phi (\nabla \cdot \mathbf{A})
\end{aligned}$$

$$\nabla \cdot (r^3 \mathbf{r}) = (\nabla r^3) \cdot \mathbf{r} + r^3 (\nabla \cdot \mathbf{r})$$

$$\begin{aligned}
\nabla \cdot \mathbf{r} &= \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \cdot (x \mathbf{i} + y \mathbf{j} + z \mathbf{k}) \\
&= \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} = 3
\end{aligned}$$

$$\begin{aligned}
\nabla r^3 &= i \frac{\partial}{\partial x}(r^3) + j \frac{\partial}{\partial y}(r^3) + k \frac{\partial}{\partial z}(r^3) \\
&= i \frac{\partial}{\partial r}(r^3) \frac{\partial r}{\partial x} + j \frac{\partial}{\partial r}(r^3) \frac{\partial r}{\partial y} + k \frac{\partial}{\partial r}(r^3) \frac{\partial r}{\partial z}, \quad r^2 = x^2 + y^2 + z^2 \quad 2r \frac{\partial r}{\partial x} = 2x \\
&= 3r^2 \frac{x}{r} i + 3r^2 \frac{y}{r} j + 3r^2 \frac{z}{r} k \quad \frac{\partial r}{\partial x} = \frac{x}{r} \quad \frac{\partial r}{\partial y} = \frac{y}{r} \quad \frac{\partial r}{\partial z} = \frac{z}{r} \\
&= 3r(x \mathbf{i} + y \mathbf{j} + z \mathbf{k}) \\
&= 3r \mathbf{r}
\end{aligned}$$

$$\nabla \cdot (r^3 \mathbf{r}) = (3r \mathbf{r}) \cdot \mathbf{r} + r^3 (3) = 6r^3$$

$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2}$$

$$\nabla^2 \phi = \nabla \cdot \nabla \phi = \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \cdot \left(i \frac{\partial \phi}{\partial x} + j \frac{\partial \phi}{\partial y} + k \frac{\partial \phi}{\partial z} \right) = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2}$$

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \quad \text{Laplacian}$$

2. Prove that $\nabla x(\phi \mathbf{A}) = \phi(\nabla x \mathbf{A}) + \nabla \phi x \mathbf{A}$

Let $\mathbf{A} = A_1 \mathbf{i} + A_2 \mathbf{j} + A_3 \mathbf{k}$

$$\nabla x(\phi \mathbf{A}) = \nabla x(\phi A_1 \mathbf{i} + \phi A_2 \mathbf{j} + \phi A_3 \mathbf{k})$$

$$= \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \phi A_1 & \phi A_2 & \phi A_3 \end{vmatrix}$$

$$= i \left(\frac{\partial(\phi A_3)}{\partial y} - \frac{\partial(\phi A_2)}{\partial z} \right) + j \left(\frac{\partial(\phi A_1)}{\partial z} - \frac{\partial(\phi A_3)}{\partial x} \right) + k \left(\frac{\partial(\phi A_2)}{\partial x} - \frac{\partial(\phi A_1)}{\partial y} \right)$$

=

$$i \left(\phi \frac{\partial A_3}{\partial y} + \frac{\partial \phi}{\partial y} A_3 - \phi \frac{\partial A_2}{\partial z} - \frac{\partial \phi}{\partial z} A_2 \right)$$

$$+ j \left(\phi \frac{\partial A_1}{\partial z} + \frac{\partial \phi}{\partial z} A_1 - \phi \frac{\partial A_3}{\partial x} - \frac{\partial \phi}{\partial x} A_3 \right) + k \left(\phi \frac{\partial A_2}{\partial x} + \frac{\partial \phi}{\partial x} A_2 - \phi \frac{\partial A_1}{\partial y} - \frac{\partial \phi}{\partial y} A_1 \right)$$

$$= \phi \left[\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) i + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) j + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) k \right]$$

$$+ \left[\left(\frac{\partial \phi}{\partial y} A_3 - \frac{\partial \phi}{\partial z} A_2 \right) i + \left(\frac{\partial \phi}{\partial z} A_1 - \frac{\partial \phi}{\partial x} A_3 \right) j + \left(\frac{\partial \phi}{\partial x} A_2 - \frac{\partial \phi}{\partial y} A_1 \right) k \right]$$

$$= \phi(\nabla x \mathbf{A}) + \begin{vmatrix} i & j & k \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix}$$

$$= \phi(\nabla x \mathbf{A}) + \nabla \phi x \mathbf{A}$$

Alternative method

$$\nabla \phi = i \frac{\partial \phi}{\partial x} + j \frac{\partial \phi}{\partial y} + k \frac{\partial \phi}{\partial z} = \sum i \frac{\partial \phi}{\partial x}$$

$$\nabla = \sum i \frac{\partial}{\partial x}$$

$$\bar{A} = A_1 i + A_2 j + A_3 k$$

$$\nabla \cdot \bar{A} = \frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z}$$

$$i \cdot \frac{\partial \bar{A}}{\partial x} = i \left[i \frac{\partial A_1}{\partial x} + j \frac{\partial A_2}{\partial x} + k \frac{\partial A_3}{\partial x} \right] = \frac{\partial A_1}{\partial x}$$

$$j \cdot \frac{\partial \bar{A}}{\partial y} = j \left[i \frac{\partial A_1}{\partial y} + j \frac{\partial A_2}{\partial y} + k \frac{\partial A_3}{\partial y} \right] = \frac{\partial A_2}{\partial y}$$

$$k \cdot \frac{\partial \bar{A}}{\partial z} = \frac{\partial A_3}{\partial z}$$

$$\nabla \cdot \bar{A} = i \cdot \frac{\partial \bar{A}}{\partial x} + j \cdot \frac{\partial \bar{A}}{\partial y} + k \cdot \frac{\partial \bar{A}}{\partial z} = \sum i \cdot \frac{\partial \bar{A}}{\partial x}$$

$$\nabla \cdot = \sum i \cdot \frac{\partial}{\partial x}$$

$$\mathbf{v} = v_1 \mathbf{i} + v_2 \mathbf{j} + v_3 \mathbf{k}$$

$$\nabla \cdot \mathbf{x} \mathbf{v} = \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \mathbf{x} (\mathbf{v}_1 \mathbf{i} + \mathbf{v}_2 \mathbf{j} + \mathbf{v}_3 \mathbf{k})$$

$$= \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_1 & v_2 & v_3 \end{vmatrix} = i \left(\frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \right) + j \left(\frac{\partial v_1}{\partial z} - \frac{\partial v_3}{\partial x} \right) + k \left(\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \right)$$

$$i X \frac{\partial \bar{v}}{\partial x} = i X \frac{\partial}{\partial x} (v_1 \mathbf{i} + v_2 \mathbf{j} + v_3 \mathbf{k}) = k \frac{\partial v_2}{\partial x} - j \frac{\partial v_3}{\partial x}$$

$$j X \frac{\partial \bar{v}}{\partial y} = j X \frac{\partial}{\partial y} (v_1 \mathbf{i} + v_2 \mathbf{j} + v_3 \mathbf{k}) = -k \frac{\partial v_1}{\partial y} + i \frac{\partial v_3}{\partial y}$$

$$k X \frac{\partial \bar{v}}{\partial z} = k X \frac{\partial}{\partial z} (v_1 \mathbf{i} + v_2 \mathbf{j} + v_3 \mathbf{k}) = j \frac{\partial v_1}{\partial z} - i \frac{\partial v_2}{\partial z}$$

$$\nabla X \bar{v} = i X \frac{\partial \bar{v}}{\partial x} + j X \frac{\partial \bar{v}}{\partial y} + k X \frac{\partial \bar{v}}{\partial z} = \sum i X \frac{\partial \bar{v}}{\partial x}$$

$$\nabla X = \sum i X \frac{\partial}{\partial x}$$

Prove that

$$3. \nabla \cdot (\mathbf{F} \times \mathbf{G}) = \mathbf{G} \cdot \operatorname{curl} \mathbf{F} - \mathbf{F} \cdot \operatorname{curl} \mathbf{G}$$

$$\begin{aligned}\nabla \cdot (\mathbf{F} \times \mathbf{G}) &= \sum i \cdot \frac{\partial}{\partial x} (\bar{F} X \bar{G}) = \sum i \left[\frac{\partial \bar{F}}{\partial x} X \bar{G} + \bar{F} X \frac{\partial \bar{G}}{\partial x} \right] \\ &= \sum i \left(\frac{\partial \bar{F}}{\partial x} X \bar{G} \right) + \sum i \left(\bar{F} X \frac{\partial \bar{G}}{\partial x} \right) \\ &= \sum G \left(i X \frac{\partial \bar{F}}{\partial x} \right) + \sum F \left(\frac{\partial \bar{G}}{\partial x} X i \right) \\ &= \bar{G} \cdot \sum i X \frac{\partial \bar{F}}{\partial x} - \bar{F} \cdot \sum i X \frac{\partial \bar{G}}{\partial x} \\ &= \mathbf{G} \cdot \operatorname{curl} \mathbf{F} - \mathbf{F} \cdot \operatorname{curl} \mathbf{G}\end{aligned}$$

$$4. \nabla \times (\mathbf{F} \times \mathbf{G}) = \mathbf{F} \operatorname{div} \mathbf{G} - \mathbf{G} \operatorname{div} \mathbf{F} + (\mathbf{G} \cdot \nabla) \mathbf{F} - (\mathbf{F} \cdot \nabla) \mathbf{G}$$

$$5. \nabla \cdot (\mathbf{F} \cdot \mathbf{G}) = \mathbf{F} \operatorname{curl} \mathbf{G} + \mathbf{G} \operatorname{curl} \mathbf{F} + (\mathbf{F} \cdot \nabla) \mathbf{G} + (\mathbf{G} \cdot \nabla) \mathbf{F}$$

Vector analysis by Raisinghania

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Ex. 1. Prove that $\nabla \times \nabla \phi = 0$ $\operatorname{curl} \operatorname{grad} \phi = 0$

$$\nabla \times \nabla \phi = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{vmatrix} = \left(\frac{\partial^2 \phi}{\partial y \partial z} - \frac{\partial^2 \phi}{\partial z \partial y} \right) i + \left(\frac{\partial^2 \phi}{\partial z \partial x} - \frac{\partial^2 \phi}{\partial x \partial z} \right) j + \left(\frac{\partial^2 \phi}{\partial x \partial y} - \frac{\partial^2 \phi}{\partial y \partial x} \right) k = 0$$

Remarks: If $\nabla \times \mathbf{v} = \mathbf{0}$ then \mathbf{v} must be $\nabla \phi$

Ex. 2. Prove that $\nabla \cdot (\nabla \times \mathbf{A}) = 0$ $\operatorname{div} \operatorname{curl} \mathbf{A} = 0$

$$\nabla \times \mathbf{A} = \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \times (A_1 \mathbf{i} + A_2 \mathbf{j} + A_3 \mathbf{k})$$

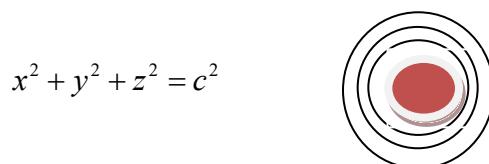
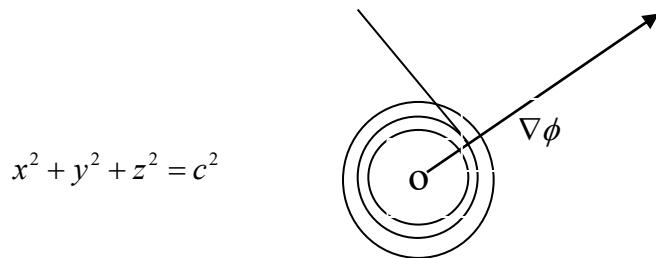
$$= \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} = i \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + j \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + k \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \text{ (vector quantity)}$$

$$\begin{aligned} \nabla \cdot (\nabla \times \mathbf{A}) &= \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \cdot \left\{ i \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + j \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + k \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \right\} \\ &= \left(\frac{\partial^2 A_3}{\partial x \partial y} - \frac{\partial^2 A_2}{\partial x \partial z} \right) + \left(\frac{\partial^2 A_1}{\partial y \partial z} - \frac{\partial^2 A_3}{\partial y \partial x} \right) + \left(\frac{\partial^2 A_2}{\partial z \partial x} - \frac{\partial^2 A_1}{\partial z \partial y} \right) \\ &= 0 \end{aligned}$$

Remarks: If $\nabla \cdot \mathbf{v} = 0$ then \mathbf{v} must be $\nabla \times \mathbf{A}$

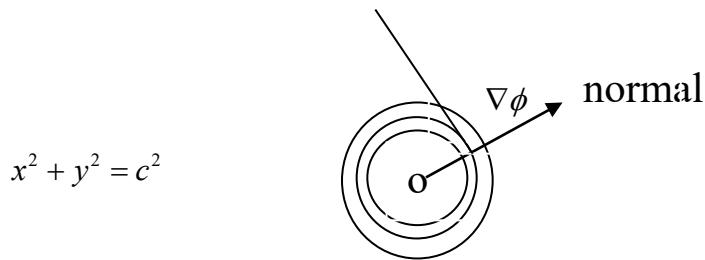
Definition:

Level surface: The family of surfaces $f(x,y,z)=k$ is called iso-surface or level surface. For different values of c the surface such as $x^2 + y^2 + z^2 = c^2$ represents a family of concentric spheres with center at the origin and varying radius c and they constitute a level surface. The surfaces (i) of constant temperature known as isothermal surface (ii) of constant gravitational or electric potential known as equipotential surface are examples of level surfaces.



Level curve: In two dimensions the family of curves $f(x,y)=k$ is called level curve. For different values of c the curve such as

$x^2 + y^2 = c^2$ represents a family of concentric circles with centre at the origin and varying radius c and they constitute a level curve. The curve of constant temperature known as isothermal curve is an example of level curve.



Geometrical meaning of gradient of scalar ϕ

Theorem

Prove that ∇f is a vector perpendicular to the level surface $f(x, y, z) = c$ where c is a constant.

Let $\mathbf{r} = xi + yj + zk$ be the position vector to any point $P(x, y, z)$ on the surface. Then $d\mathbf{r} = dx\mathbf{i} + dy\mathbf{j} + dz\mathbf{k}$ lies in the tangent plane to the surface at P .

$$f(x, y, z) = c$$

$$df = 0$$

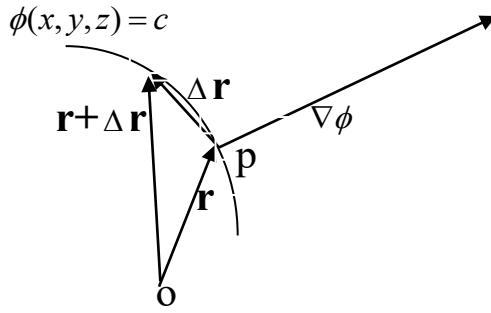
$$\frac{\partial f}{\partial x}dx + \frac{\partial f}{\partial y}dy + \frac{\partial f}{\partial z}dz = 0$$

$$\left(i\frac{\partial f}{\partial x} + j\frac{\partial f}{\partial y} + k\frac{\partial f}{\partial z} \right) \cdot (dx\mathbf{i} + dy\mathbf{j} + dz\mathbf{k}) = 0$$

$$\nabla f \cdot d\mathbf{r} = 0$$

So that ∇f is perpendicular to $d\mathbf{r}$ i.e. perpendicular to the tangent plane to the surface at (x, y, z) .

Hence ∇f is a vector perpendicular to the surface $f(x, y, z) = c$ at any point (x, y, z) .



Formula

The unit normal to the surface $f(x, y, z) = c$ at the point

$$(x, y, z)$$
 is $\mathbf{n} = \frac{\nabla f}{|\nabla f|}$

Problem

Find the unit normal to the surface $x^2y + 2xz = 4$ at the point $(2, -2, 3)$.

$$\begin{aligned}\nabla(x^2y + 2xz) &= i \frac{\partial(x^2y + 2xz)}{\partial x} + j \frac{\partial(x^2y + 2xz)}{\partial y} + k \frac{\partial(x^2y + 2xz)}{\partial z} \\ &= (2xy + 2z)i + x^2j + 2xk \\ &= -2i + 4j + 4k\end{aligned}$$

The unit normal to the surface is

$$\mathbf{n} = \frac{\nabla f}{|\nabla f|} = \frac{-2i + 4j + 4k}{\sqrt{36}} = -\frac{1}{3}i + \frac{2}{3}j + \frac{2}{3}k$$

Problem

Find the angle between the surfaces $xy^2z = 3x + z^2$ and $3x^2 - y^2 + 2z = 1$ at $(1, -2, 1)$

Let $f(x, y, z) = xy^2z - 3x - z^2$

$$g(x, y, z) = 3x^2 - y^2 + 2z - 1$$

$$\begin{aligned}\nabla f &= \nabla(xy^2z - 3x - z^2) = i \frac{\partial(xy^2z - 3x - z^2)}{\partial x} + j \frac{\partial(xy^2z - 3x - z^2)}{\partial y} + k \frac{\partial(xy^2z - 3x - z^2)}{\partial z} \\ &= i(y^2z - 3) + j2xyz + k(xy^2 - 2z) \\ &= i - 4j + 2k\end{aligned}$$

$$\nabla g = 6i + 4j + 2k$$

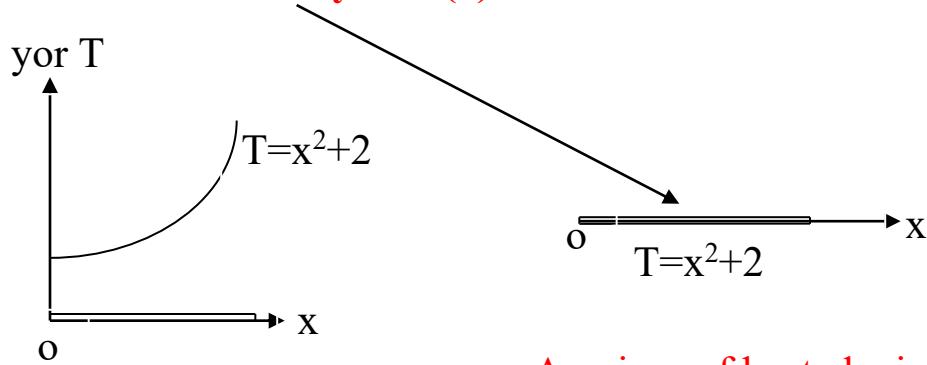
$$\nabla f \cdot \nabla g = |\nabla f| \cdot |\nabla g| \cos \theta$$

$$\cos \theta = \frac{\nabla f \cdot \nabla g}{\|\nabla f\| \|\nabla g\|} = \frac{(i - 4j + 2k) \cdot (6i + 4j + 2k)}{\sqrt{21} \cdot 2\sqrt{14}} = \frac{\sqrt{6}}{14}$$

$$\theta = \cos^{-1} \frac{\sqrt{6}}{14}$$

Slope/gradient/rate of change in different dimensions in differential calculus

One dimensional body $T=f(x)$



A piece of heated wire

Geometrically y or $T = f(x)$ is the equation of a curve

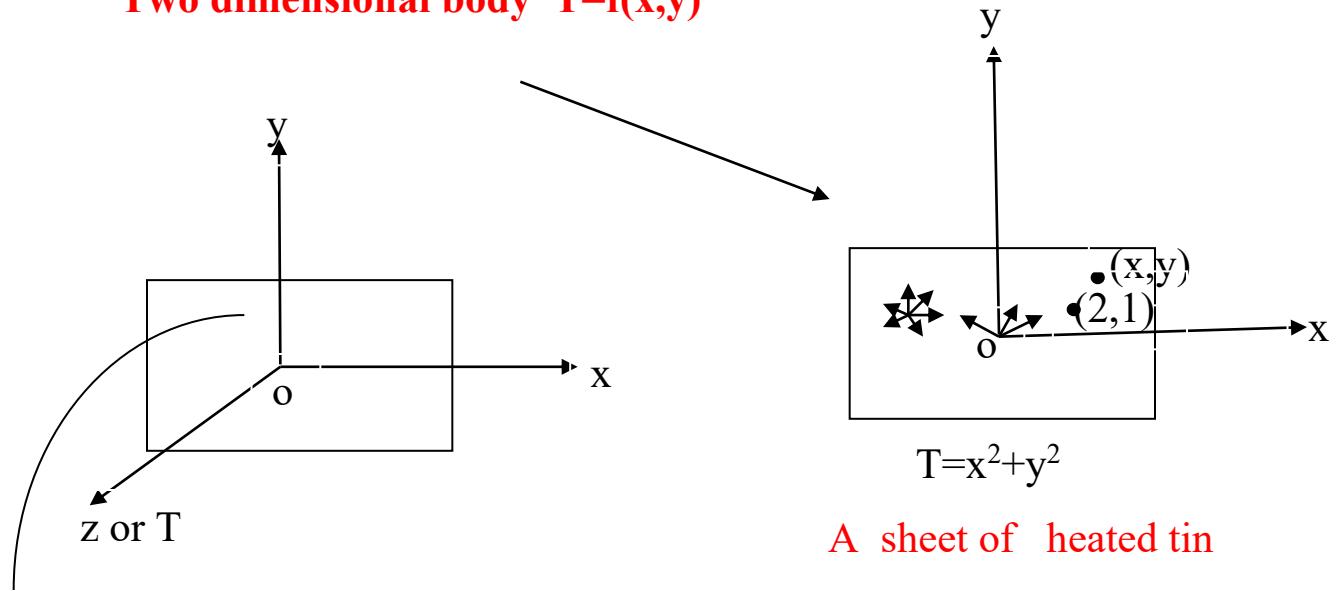
$\frac{dy}{dx}$ = rate of change of y along x -axis/directional derivative of y

along x -axis/ gradient of y with respect to x ,

$\frac{dy}{dx}$ = Slope of the tangent at P to the curve $y = f(x)$

Ex. $T=f(x)$, $\frac{dT}{dx}$

Two dimensional body $T=f(x,y)$



Geometrically $z = f(x,y)$ is the equation of a surface

$\frac{\partial z}{\partial x}$, $\frac{\partial z}{\partial y}$ are the rate of changes of z along x and y -axes/directional derivative of z along x and y -axes/ gradient of z with respect to x and y ,

$$\text{Ex. } T=f(x,y) \quad \frac{\partial T}{\partial x}, \quad \frac{\partial T}{\partial y}$$

Three dimensional body $T=f(x,y,z)$

$u=f(x,y,z)$, (solid) $\frac{\partial u}{\partial x}$, $\frac{\partial u}{\partial y}$ and $\frac{\partial u}{\partial z}$ are the rate of changes along x , y and z -axes/directional derivative along x , y and z -axes

$$\text{Ex. } T=f(x,y,z) \quad \frac{\partial T}{\partial x}, \quad \frac{\partial T}{\partial y} \text{ and } \frac{\partial T}{\partial z}$$

What is the relation between Gradient of a scalar in vector calculus and Slope/gradient/rate of change in differential calculus

One dimension

$$\nabla \phi = i \frac{\partial \phi}{\partial x} \quad \phi = \phi(x) \quad y = f(x) \quad T = T(x)$$

$\nabla \phi.i = \frac{\partial \phi}{\partial x}$ = Slope/gradient/rate of change of ϕ with respect to x

in differential calculus = $\frac{dy}{dx}$ or $\frac{dT}{dx}$

Two dimension

$$\nabla \phi = i \frac{\partial \phi}{\partial x} + j \frac{\partial \phi}{\partial y} \quad \phi = \phi(x, y), \quad z = f(x, y), \quad T = T(x, y)$$

$\nabla \phi.i = \frac{\partial \phi}{\partial x}$ = Slope/gradient/rate of change of ϕ with respect to x

in differential calculus = $\frac{\partial z}{\partial x}$ or $\frac{\partial T}{\partial x}$

$\nabla \phi.j = \frac{\partial \phi}{\partial y}$ = Slope/gradient/rate of change of ϕ with respect to y

in differential calculus = $\frac{\partial z}{\partial y}$ or $\frac{\partial T}{\partial y}$

Three dimension

$$\nabla \phi = i \frac{\partial \phi}{\partial x} + j \frac{\partial \phi}{\partial y} + k \frac{\partial \phi}{\partial z} \quad \phi = \phi(x, y, z) \quad u = f(x, y, z) \quad T = T(x, y, z)$$

$\nabla \phi.i = \frac{\partial \phi}{\partial x}$ = Slope/gradient/rate of change of ϕ with respect to x

in differential calculus = $\frac{\partial u}{\partial x}$ or $\frac{\partial T}{\partial x}$

$\nabla \phi.j = \frac{\partial \phi}{\partial y}$ = Slope/gradient/rate of change of ϕ with respect to y

in differential calculus = $\frac{\partial u}{\partial y}$ or $\frac{\partial T}{\partial y}$

$\nabla \phi.k = \frac{\partial \phi}{\partial z}$ = Slope/gradient/rate of change of ϕ with respect to z

in differential calculus = $\frac{\partial u}{\partial z}$ or $\frac{\partial T}{\partial z}$

Directional derivative

$\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z}$ are called directional derivative in vector calculus

$$\nabla \phi_i = \frac{\partial \phi}{\partial x}$$

The directional derivative of ϕ along x-direction is obtained by taking dot product of $\nabla \phi$ and unit vector along x-direction

The directional derivative of ϕ along any direction is obtained by taking dot product of $\nabla \phi$ and unit vector along that direction.

The directional derivative/rate of change of ϕ along any vector \mathbf{a} is $\nabla \phi \cdot \hat{a}$ where \hat{a} is unit vector along \mathbf{a} .

Maximum rate of change

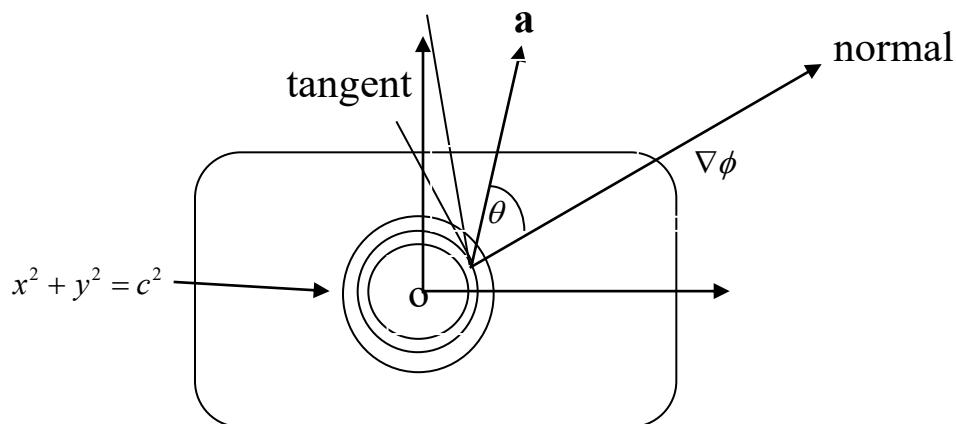
Geometrical meaning of $|\nabla \phi|$

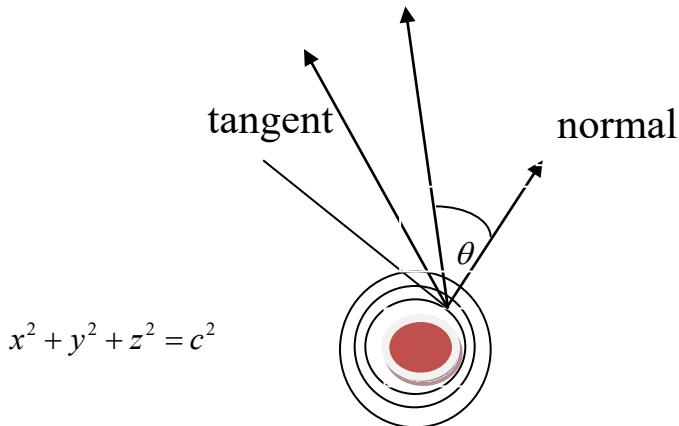
$$\nabla \phi \cdot \hat{a} = |\nabla \phi| |\cos \theta| = |\nabla \phi| \cos \theta \text{ where } \hat{a} \text{ is unit vector along } \mathbf{a}$$

This rate of change is maximum when $\theta = 0$.

The rate of change is maximum along the normal to the surface $\phi(x, y, z) = c$ and it is equal to $|\nabla \phi|$

$$|\nabla \phi| = \sqrt{\left(\frac{\partial \phi}{\partial x}\right)^2 + \left(\frac{\partial \phi}{\partial y}\right)^2 + \left(\frac{\partial \phi}{\partial z}\right)^2}$$





Problem

Find the directional derivative of $\phi = x^2yz + 4xz^2$ at P(1, -2, 1) in the direction of the vector $\mathbf{a} = 2\mathbf{i} - \mathbf{j} - \mathbf{k}$. Also find the maximum rate of change of ϕ .

$$\phi = x^2yz + 4xz^2$$

$$\begin{aligned}\nabla\phi &= i \frac{\partial\phi}{\partial x} + j \frac{\partial\phi}{\partial y} + k \frac{\partial\phi}{\partial z} \\ &= i \frac{\partial(x^2yz + 4xz^2)}{\partial x} + j \frac{\partial(x^2yz + 4xz^2)}{\partial y} + k \frac{\partial(x^2yz + 4xz^2)}{\partial z} \\ &= i(2xyz + 4z^2) + j(x^2z) + k(x^2y + 8xz) \\ &= j + 6k\end{aligned}$$

The unit vector along \mathbf{a} is $\hat{a} = \frac{\vec{a}}{|\vec{a}|} = \frac{2i - j - k}{\sqrt{6}}$

the directional derivative is $\nabla\phi \cdot \hat{a} = (j + 6k) \cdot \frac{2i - j - k}{\sqrt{6}} = \frac{-7}{\sqrt{6}}$

The maximum rate of change of ϕ is

$$|\nabla\phi| = \sqrt{\left(\frac{\partial\phi}{\partial x}\right)^2 + \left(\frac{\partial\phi}{\partial y}\right)^2 + \left(\frac{\partial\phi}{\partial z}\right)^2} = \sqrt{0^2 + 1^2 + 6^2} = \sqrt{37}$$

Physical Interpretation of Curl of vector function

Ex If $\mathbf{v} = \vec{\omega} \times \mathbf{r}$, Prove that $\vec{\omega} = \frac{1}{2} \operatorname{curl} \mathbf{v}$ where $\vec{\omega}$ is a constant vector.

Let $\vec{\omega} = \omega_1 \mathbf{i} + \omega_2 \mathbf{j} + \omega_3 \mathbf{k}$ be the angular velocity and $\mathbf{r} = xi + y\mathbf{j} + zk$

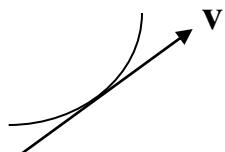
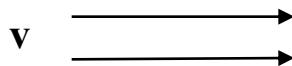
$$\boldsymbol{\omega} \times \mathbf{r} = \begin{vmatrix} i & j & k \\ \omega_1 & \omega_2 & \omega_3 \\ x & y & z \end{vmatrix} = (\omega_2 z - \omega_1 y) \mathbf{i} + (\omega_3 x - \omega_1 z) \mathbf{j} + (\omega_1 y - \omega_2 x) \mathbf{k}$$

$$\begin{aligned} \operatorname{curl} \mathbf{v} = \nabla \times (\boldsymbol{\omega} \times \mathbf{r}) &= \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \omega_2 z - \omega_1 y & \omega_3 x - \omega_1 z & \omega_1 y - \omega_2 x \end{vmatrix} \\ &= 2(\omega_1 \mathbf{i} + \omega_2 \mathbf{j} + \omega_3 \mathbf{k}) \\ &= 2\vec{\omega} \end{aligned}$$

$$\vec{\omega} = \frac{1}{2} \operatorname{curl} \mathbf{v}$$

Thus physically interpreted, curl of linear velocity of any particle is twice the angular velocity of the particle.

Curl has the effect of rotation $\operatorname{curl} \mathbf{A} = \operatorname{rot} \mathbf{A}$



Condition of irrotational motion

$\operatorname{curl} \mathbf{v} = 2\vec{\omega}$, If $\operatorname{curl} \mathbf{v} = \mathbf{0}$ the motion is irrotational

Also we know that $\nabla \times \nabla \phi = \mathbf{0}$,

If the motion is irrotational i. e. $\operatorname{curl} \mathbf{v} = \mathbf{0}$ then \mathbf{v} must be $\nabla \phi$, ϕ is called scalar potential function.

Ex. Determine the constant a, b, c so that vector

$\mathbf{v} = (-4x - 3y + az)\mathbf{i} + (bx + 3y + 5z)\mathbf{j} + (4x + cy + 3z)\mathbf{k}$ is irrotational.

Find a scalar function ϕ so that $\mathbf{v} = \nabla \phi$.

\mathbf{v} is irrotational if $\nabla \times \mathbf{v} = \mathbf{0}$

$$\nabla \mathbf{X} \mathbf{v} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -4x - 3y + az & bx + 3y + 5z & 4x + cy + 3z \end{vmatrix}$$

$$=(c-5)i-(4-a)j+(b+3)k = \mathbf{0} = 0i+0j+0k$$

$$a=4, \quad b=-3, \quad c=5$$

As $\nabla \mathbf{X} \mathbf{v} = \mathbf{0}$, \mathbf{v} must be $\nabla \phi$

$$\mathbf{v} = \nabla \phi$$

$$(-4x - 3y + 4z)i + (-3x + 3y + 5z)j + (4x + 5y + 3z)k = i \frac{\partial \phi}{\partial x} + j \frac{\partial \phi}{\partial y} + k \frac{\partial \phi}{\partial z}$$

$$\frac{\partial \phi}{\partial x} = -4x - 3y + 4z \quad \dots \dots \dots (1)$$

$$\frac{\partial \phi}{\partial y} = -3x + 3y + 5z \quad \dots \dots \dots (2)$$

$$\frac{\partial \phi}{\partial z} = 4x + 5y + 3z \quad \dots \dots \dots (3)$$

Integrating (1) with respect to x partially

$$\phi = -2x^2 - 3xy + 4xz + f(y, z) \quad \dots \dots (4)$$

$$\frac{\partial \phi}{\partial y} = -3x + \frac{\partial f(y, z)}{\partial y} \quad \dots \dots \dots (5)$$

$$\frac{\partial \phi}{\partial z} = 4x + \frac{\partial f(y, z)}{\partial z} \quad \dots \dots \dots (6)$$

$$\text{Comparing (2) and (5)} \quad \frac{\partial f(y, z)}{\partial y} = 3y + 5z \quad \dots \dots (7)$$

$$\text{Comparing (3) and (6)} \quad \frac{\partial f(y, z)}{\partial z} = 5y + 3z \quad \dots \dots (8)$$

$$\text{Integrating (7) with respect to y, } f(y, z) = \frac{3}{2}y^2 + 5zy + g(z)$$

$$\frac{\partial f(y, z)}{\partial z} = 5y + g'(z) \quad \dots \dots (9)$$

$$\text{Comparing (8) and (9)} \quad g'(z) = 3z \quad g(z) = \frac{3}{2}z^2 + c$$

$$\text{therefore } f(y, z) = \frac{3}{2}y^2 + 5yz + \frac{3}{2}z^2 + c$$

$$\text{hence } \phi = -2x^2 - 3xy + 4xz + \frac{3}{2}y^2 + 5yz + \frac{3}{2}z^2 + c$$

Alternative method

$$\mathbf{v} = \nabla \phi$$

$$(-4x - 3y + 4z)\mathbf{i} + (-3x + 3y + 5z)\mathbf{j} + (4x + 5y + 3z)\mathbf{k} = i \frac{\partial \phi}{\partial x} + j \frac{\partial \phi}{\partial y} + k \frac{\partial \phi}{\partial z}$$

$$\frac{\partial \phi}{\partial x} = -4x - 3y + 4z \quad \dots \dots \dots (1)$$

$$\frac{\partial \phi}{\partial y} = -3x + 3y + 5z \quad \dots \dots \dots (2)$$

$$\frac{\partial \phi}{\partial z} = 4x + 5y + 3z \quad \dots \dots \dots (3)$$

$$\phi = -2x^2 - 3xy + 4xz + f(y, z)$$

$$\phi = -3xy + \frac{3}{2}y^2 + 5yz + g(z, x)$$

$$\phi = 4xz + 5yz + \frac{3}{2}z^2 + h(x, y)$$

$$\phi = -2x^2 - 3xy + 4xz + \quad + \quad + \quad + f(y, z)$$

$$\phi = -3xy + \quad + \frac{3}{2}y^2 + 5yz + \quad + g(z, x)$$

$$\phi = \quad + \quad + 4xz + \quad + 5yz + \frac{3}{2}z^2 + h(x, y)$$

$$f(y, z) = \frac{3}{2}y^2 + 5yz + \frac{3}{2}z^2$$

$$g(z, x) = -2x^2 + 4xz + \frac{3}{2}z^2$$

$$h(x, y) = -2x^2 - 3xy + \frac{3}{2}y^2$$

$$\text{hence } \phi = -2x^2 - 3xy + 4xz + \frac{3}{2}y^2 + 5yz + \frac{3}{2}z^2 + c$$

Physical interpretation of divergence of the vector function

Consider fluid motion in space. Let $P(x, y, z)$ be any point of fluid at time t . Let $\mathbf{v} = u\mathbf{i} + v\mathbf{j} + w\mathbf{k}$ be the fluid velocity at P . Construct a small rectangular box with edges of length

δx , δy , δz parallel to the respective coordinate axes, having P at one of the angular points as shown in the figure.

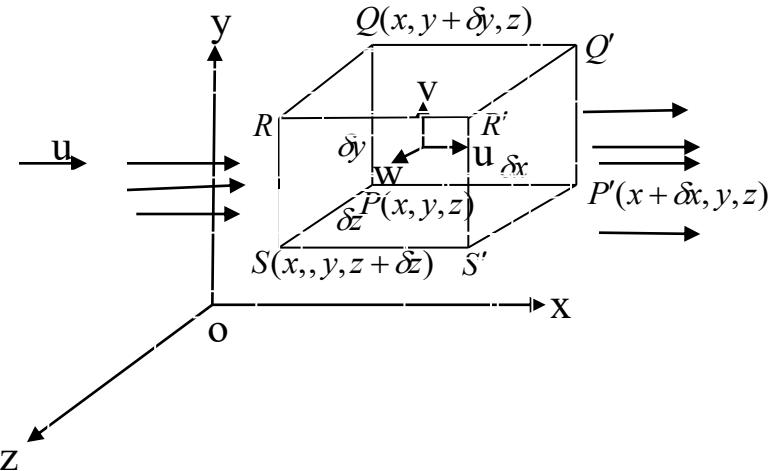


Fig18.

Then we have volume of the fluid that passes through the face $PQRS = (\delta y \delta z)u$ per unit time

$$= f(x, y, z) \text{ per unit time (say)}$$

Hence the fluid that passes out through the opposite face $P'Q'R'S' = f(x + \delta x, y, z)$ per unit time

$$= f(x, y, z) + \delta x \frac{\partial f(x, y, z)}{\partial x} + \text{terms containing higher powers}$$

of δx [Taylore's theorem]

[Face to face only x changes]

$$f(x+h) = f(x) + h f'(x) + \frac{h^2}{2} f''(x) + \dots$$

$$\begin{aligned} \text{The net outward flow from the rectangular box along x-axis per unit time} &= f(x, y, z) + \delta x \frac{\partial f(x, y, z)}{\partial x} - f(x, y, z) \\ &= \delta x \frac{\partial f(x, y, z)}{\partial x} = \delta x \frac{\partial}{\partial x} u \delta y \delta z = \frac{\partial u}{\partial x} \delta x \delta y \delta z \end{aligned}$$

Similarly the net outward flow from the rectangular box along y-axis and z-axis per unit time will be $\frac{\partial v}{\partial y} \delta x \delta y \delta z$ and $\frac{\partial w}{\partial z} \delta x \delta y \delta z$ respectively.

Hence total net outward flow per unit time (rate of flow) through the rectangular box of volume $\delta x \delta y \delta z$ is

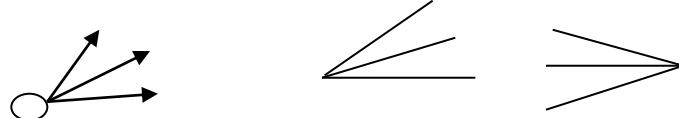
$$\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \delta x \delta y \delta z$$

The total rate of outward flow of the fluid through a unit volume

$$= \frac{\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \delta x \delta y \delta z}{\delta x \delta y \delta z} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = \nabla \cdot \mathbf{v}$$

Thus physically interpreted $\text{div } \mathbf{v}$ represents the net outward flow of the fluid per unit volume per unit time.

Divergence=Net outward flow



Remark: The name divergence originated in the above mentioned interpretation of $\text{div } \mathbf{v}$

Equation of continuity of an incompressible fluid:

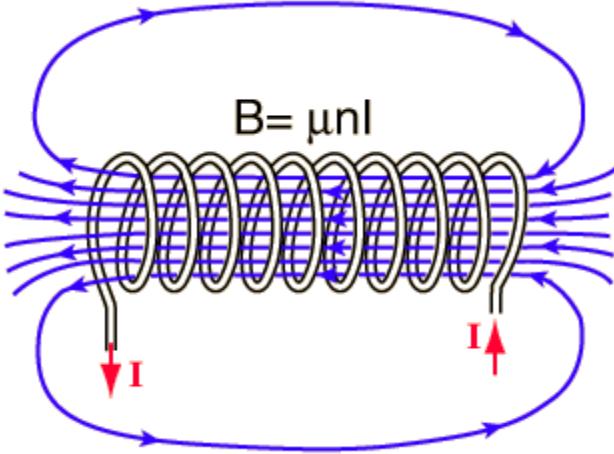
If the fluid is incompressible then fluid inflow = fluid outflow and there will be no net outward flow of fluid. Hence $\text{div } \mathbf{v} = 0$

This is known as condition of incompressibility of fluid or equation of continuity of incompressible fluid.

Solenoidal force field

Solen (Greek word) -pipe

Solenoid-shape of a pipe, strong magnet



The magnetic field is concentrated into a nearly uniform field in the center of a long solenoid. The field outside is weak and divergent.

Figure of solenoid

In a solenoid the magnetic force \mathbf{F} is **uniform**, So $\operatorname{div} \mathbf{F} = 0$

If $\operatorname{div} \mathbf{F} = 0$ then \mathbf{F} is a solenoidal

Or, if \mathbf{F} is solenoidal then $\nabla \cdot \mathbf{F} = 0$

Problem

Ex. Determine the constant a so that vector

$\mathbf{F} = (-4x - 6y + 3z)\mathbf{i} + (-2x + y - 5z)\mathbf{j} + (5x + 6y + az)\mathbf{k}$ is solenoidal.

\mathbf{F} is solenoidal if $\nabla \cdot \mathbf{F} = 0$

$$\nabla \cdot \mathbf{F} = \frac{\partial}{\partial x}(-4x - 6y + 3z) + \frac{\partial}{\partial y}(-2x + y - 5z) + \frac{\partial}{\partial z}(5x + 6y + az) = 0$$

$$\text{Or, } -4 + 1 - a = 0 \quad a = -3$$