

Qn: 1

Plot the Bode diagram for the following transfer function and obtain the gain and phase cross over frequencies

$$G(s) = \frac{10}{s(1+4s)(1+s)}$$

Steps

- Take transfer function of the given $G(s)$ \rightarrow std. form
- Put $s=j\omega$ in the given transfer function

1) Magnitude plot

1. Find corner frequencies
2. Magnitude table
3. choose lowest & highest freq starting at $\omega=1$
4. Find the mag. at each freq.
5. Draw plot in semilog graph.

2) Phase plot

1. Find the phase (angle) of the given function $G(j\omega)$
2. Substitute the value of ω & find the corresponding angles
3. Draw Bodeplot on semilog graph

$$G(s) = \frac{10}{s(1+4s)(1+s)} \rightarrow \text{std form.} \Rightarrow (1+js)$$

$$\textcircled{1} \text{ put } s=j\omega \Rightarrow G(j\omega) = \frac{10}{j\omega(1+4j\omega)(1+j\omega)}$$

Magnitude plot

$$\textcircled{2} \text{ corner frequencies } \omega_{c_1} = \frac{1}{4} = 2.5 \text{ rad/s}$$

$$\omega_{c_2} = \frac{1}{1} = 10 \text{ rad/s}$$

[The reciprocal of the co-efficient of $j\omega$ term is the corner freq.]

\textcircled{3}

Term	Corner freq rad/sec	Slope (db/dec)	Change in slope (total slope)
<u>40dB</u>	-	-20	-20
$\frac{10}{j\omega}$	-	-20	$-20 + -20 = -40$
$2\log\left(\frac{10}{2.5}\right)$ $= 2\log 4$ $= 12\text{dB}$	2.5ω	-20	$-40 + -20 = -60^\circ$
$\frac{1}{1+j0.1\omega}$	10	-20	

$$\begin{aligned}
 j\omega &\rightarrow 20 \text{ (slope)} \\
 j\omega^2 &\rightarrow 40 \text{ dB/dec} \\
 j\omega^3 &\rightarrow 60 \text{ dB/dec.} \\
 \frac{1}{j\omega} &\rightarrow -20 \text{ dB/dec} \\
 \frac{1}{j\omega^2} &\rightarrow -40 \text{ dB/dec} \\
 \frac{1}{j\omega^3} &\rightarrow -60 \text{ dB/dec.}
 \end{aligned}$$

$$\begin{aligned}
 -40 \times \log\left(\frac{10}{2.5}\right) + 12 \text{dB} \\
 -12.08 \text{ dB}
 \end{aligned}$$

$$\begin{aligned}
 -60 \times \log\left(\frac{100}{10}\right) + -12 \\
 -72
 \end{aligned}$$

④ choose lowest & highest freq.

Let $\omega_1 = 0.1$, $\omega_{c1} = 2.5$, $\omega_{c2} = 10 \text{ rad/sec}$. Let $\omega_h = 50 \text{ rad/sec}$
 $(\omega_1 < \omega_{c1})$ ($\omega_h > \omega_{c2}$).

starting point,

$20 \log (\text{First term}) \text{ at } \omega = 0.1$

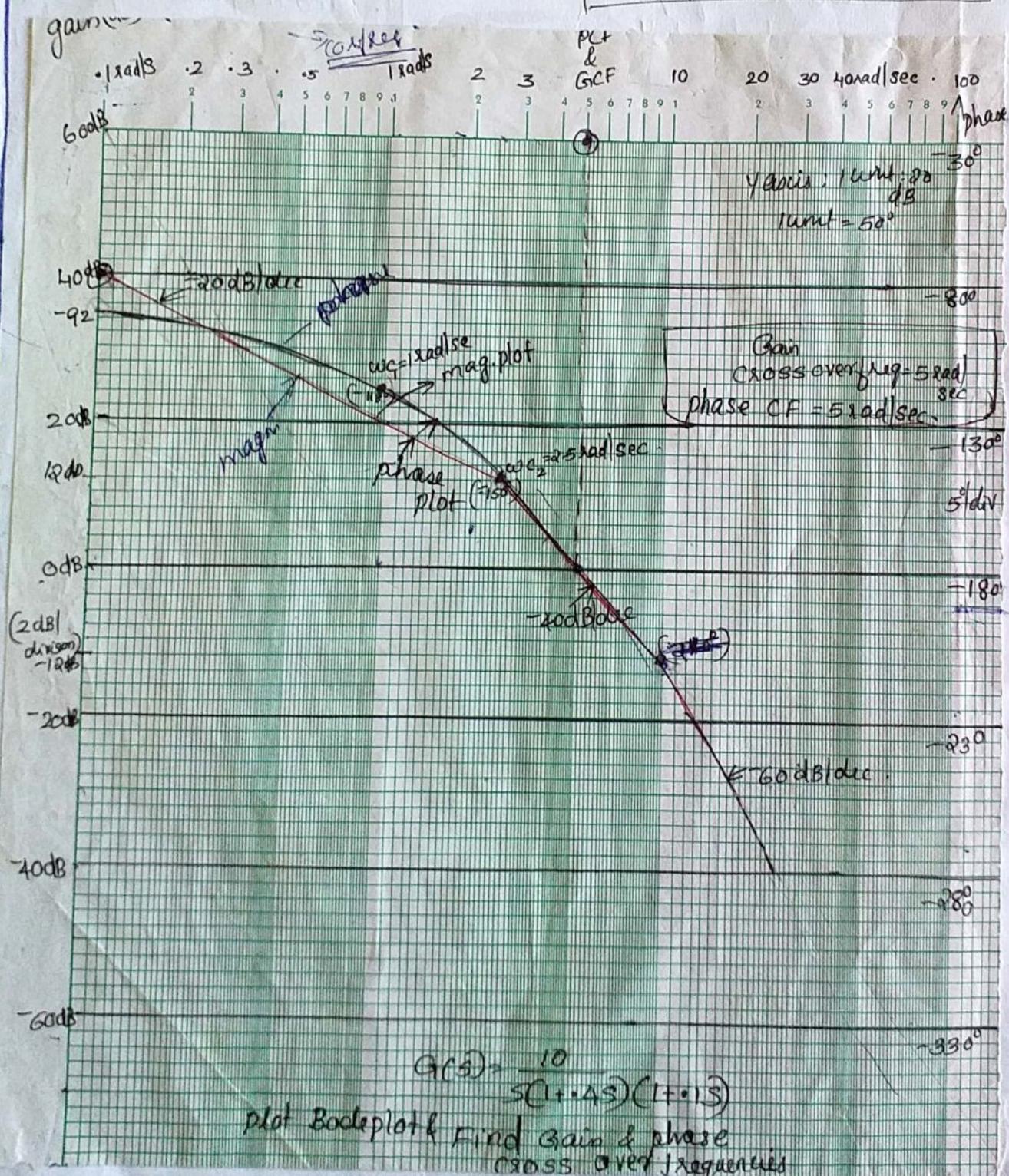
[First term $\frac{1}{j\omega}$)
 j is not considered)

$$\therefore 20 \log \left(\frac{1}{j\omega}\right) = 40 \text{ dB}$$

Phase plot $\phi = -90^\circ - \tan^{-1} 4w - \tan^{-1} 1/w$

Result Gain & Phase cross over freq = 5 rad/sec

ω	$\phi = -\angle G(j\omega) + \angle(j\omega) = -90 - \tan^{-1} 4w - \tan^{-1} 1/w$
0.1	-92
1	-118
2.5	-150
4	-170
10	-210
20	-236



③ Draw the Bodeplot & hence find gain cross over frequency, phase cross over freq, gain margin, phase margin & stability of the system

$$G(s)H(s) = \frac{20}{s(1+s)(10+s)}$$

Step 1 : Standard form $\Rightarrow G(s)H(s) = \frac{20}{s(1+s)} 10 \left(1 + \frac{s}{10}\right)$

$$= \frac{2}{s(1+s)} \left(1 + \frac{s}{10}\right). \quad \begin{bmatrix} \text{std form} \\ (1+Ts) \end{bmatrix}$$

Step 2: substitute $s = j\omega$

$$G(j\omega)H(j\omega) = \frac{2}{j\omega(1+j\omega)} \left(1 + \frac{j\omega}{10}\right).$$

Step 3: Table for Gain Plot.

→ Find corner frequencies

→ The reciprocal of the co-efficient of $j\omega$ term in $(1+j\omega)$ is the corner frequency.

$$\omega_c_1 = \frac{1}{1} = 1 \quad \omega_c_2 = \frac{1}{10} = 10 \quad \text{slope}$$

term	CF	Slope	Total slope	$j\omega \rightarrow 20$	$j\omega \rightarrow -20$
$\frac{2}{j\omega}$	—	-20	-20 dB/dec	$j\omega^2 \rightarrow 40$	$\frac{1}{j\omega^2} \rightarrow -40$
$\frac{1}{1+j\omega}$	$\frac{1}{1+j\omega}$	-20	-40 dB/dec	$j\omega^3 \rightarrow 60$	$\frac{1}{j\omega^3} \rightarrow -60$
$\frac{1}{1+0.1j\omega}$	$\frac{1}{1+0.1j\omega}$	-20	-60	$-40 \times \log(\frac{10}{1}) + 6 \text{dB} = -36 \text{dB}$	

Step 4: Finding starting point.

$$20 \log (\text{first term}) \text{ at } \omega = 0 \text{ rad/sec} \quad \begin{bmatrix} \text{First term } \frac{2}{j\omega} \\ j\omega \text{ is not considered} \end{bmatrix}$$

$$20 \log \frac{2}{0} = 20 \log \frac{2}{1} = \underline{26 \text{dB}} \text{ starting pt.}$$

Step 5: Phase plot

ω	$\angle G(j\omega)H(j\omega)$
$\omega_c_1 = 1$	$-90^\circ - \tan^{-1}(1) - \tan^{-1}(\frac{1}{10})$
$\omega_c_2 = 3$	-108.4°
$\omega_c_3 = 5$	-120°
$\omega_c_4 = 10$	-140°
$\omega_c_5 = 20$	-152.4°
$\omega_c_6 = 30$	-178.2°
$\omega_c_7 = 50$	-195.2°
$\omega_c_8 = 100$	-249.6°

calculate in degree mode of calculator.

phase

$$j\omega \rightarrow 90^\circ \quad \frac{1}{j\omega} \rightarrow -90^\circ$$

$$j\omega^2 \rightarrow 180^\circ \quad \frac{1}{j\omega^2} \rightarrow -180^\circ$$

$$j\omega^3 \rightarrow 270^\circ \quad \frac{1}{j\omega^3} \rightarrow -270^\circ$$

* If it is in $(a+jb)$ form, then
find $\tan^{-1}(b/a)$

Q

- * The Point where 0dB line intersects the gain plot, the corresponding frequency value will be gain cross over frequency (gcf) $\Rightarrow \omega_{gc}$
- * The point where -180° line intersect the phase plot, the corresponding freq. value will be phase cross over freq. (pcf) $\Rightarrow \omega_{pc}$

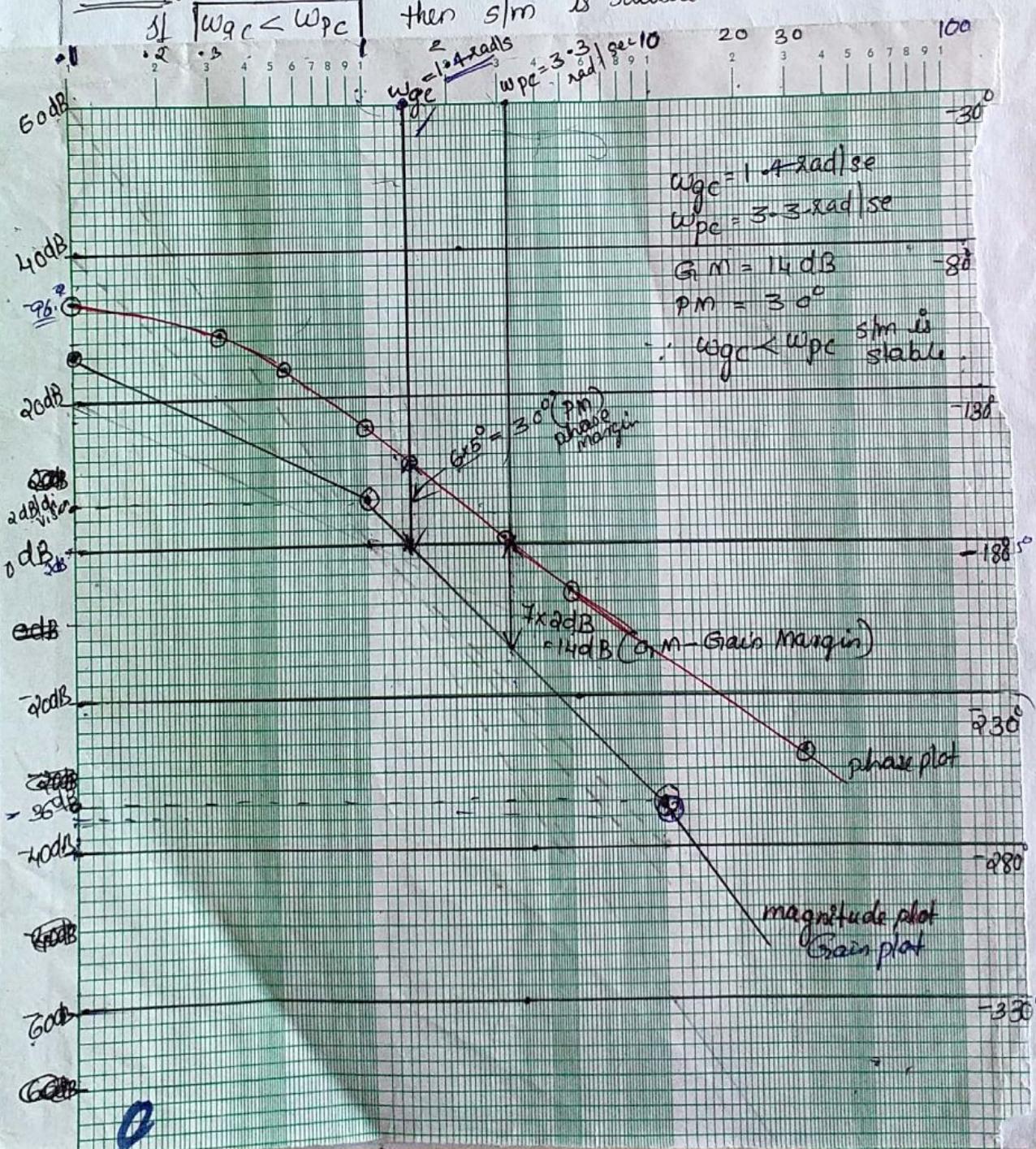
phase margin:-

The line plots from gcf to the phasplot is called phase Gain Margin [During ω_{gc} , magnitude difference with 0dB] \Rightarrow margin

The line plots from pcf to the gainplot is called Gain margin

[During ω_{pc} , phase having difference with -180°] \Rightarrow margin

Stability



④ Sketch Bode Plot for the following transfer function and determine the system gain K for the gain cross over frequency to be 5 rad/sec .

$$G(s) = \frac{Ks^2}{(1+2s)(1+0.02s)}$$

\Rightarrow Assume $K=1$

\Rightarrow substitute $s=j\omega$

$$G(j\omega) = \frac{(j\omega)^2}{(1+2j\omega)(1+0.02j\omega)}$$

\Rightarrow Magnitude plot (Gain Plot)

term	$\omega(\text{rad/sec})$ corner freq	slope	Total slope	
$(j\omega)^2$	-	40 dB/dec	40	$\Rightarrow 20\log(1^{\text{st term}})$ $\xrightarrow{\text{not term}}$
$\frac{1}{1+2j\omega}$	$\frac{1}{2} = 5$	-20	-20	$\Rightarrow 20\log(1^{\text{st term}}) \text{ at } \omega = 5 \text{ rad/s.}$ $20\log(5^2) = 28 \text{ dB}$
$\frac{1}{1+0.02j\omega}$	$\frac{1}{0.02} = 50$	-20	0	\Rightarrow (slope from ω_C to $\omega_{C_2} \times \log \frac{\omega_{C_2}}{\omega_C}$) + Anag. at ω_{C_1}

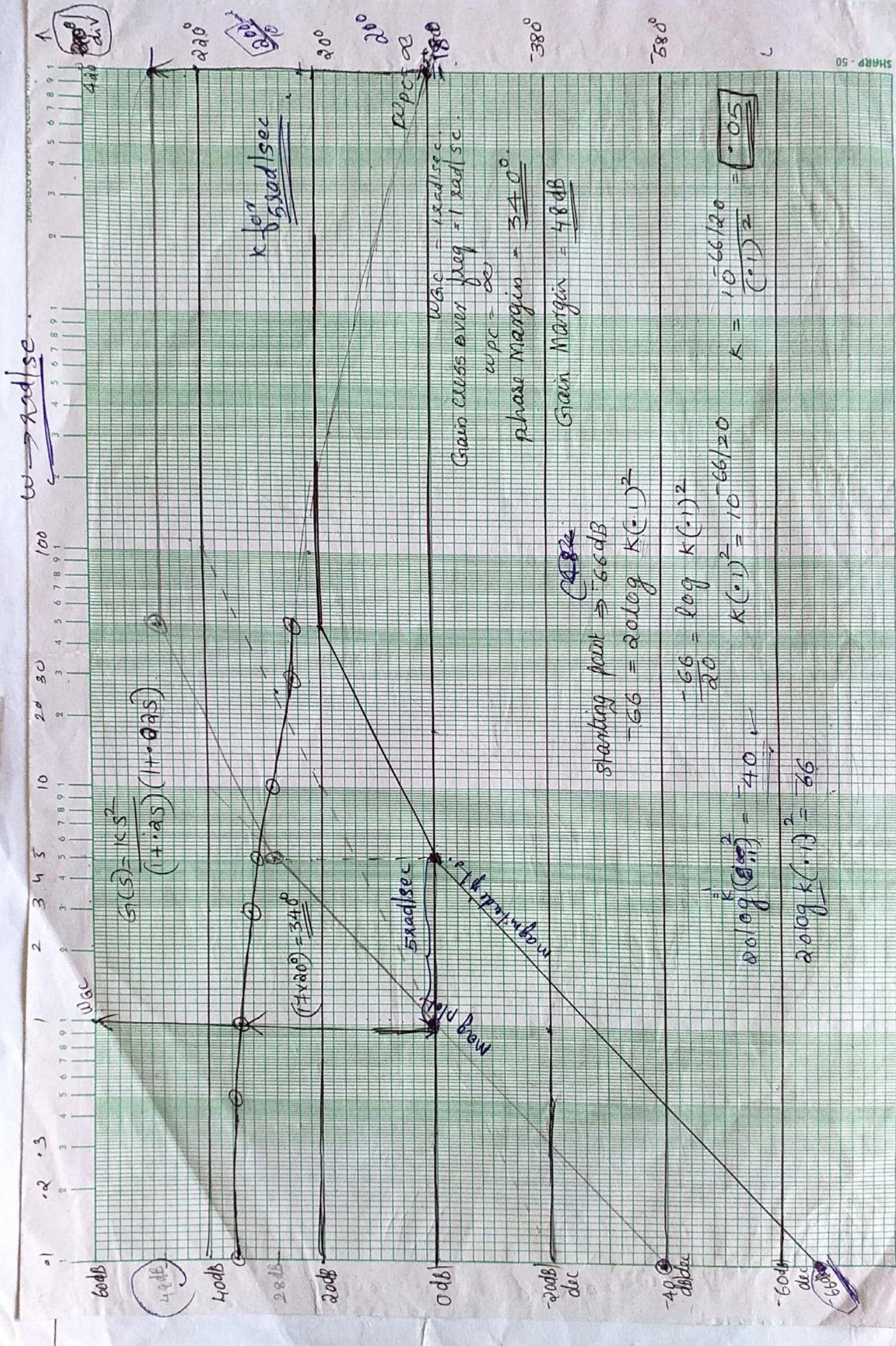
$$\Rightarrow \text{Starting pt} = 20\log(1^{\text{st term}}) \text{ at } \omega = 1 \text{ rad/s} \quad 20 \times \log \frac{50}{5} + 28 = 48 \text{ dB}$$

$$= 20\log(\omega^2) = 20\log(1^2) = -40 \text{ dB}$$

$$\text{End pt at } \omega = 100 \text{ rad/s.} \quad 0 \times \log \frac{100}{50} + 48 \text{ dB} = 48 \text{ dB}$$

\Rightarrow phase plot

ω (rad/sec)	$\Phi = \angle G(j\omega) + \tan^{-1}(2\omega) - \tan^{-1}(0.02\omega)$
1	178.7
5	173.7
10	167.5
30	145.6
50	129.3
100	105.3
300	68.4
500	50



$$Q_2 \quad G(s) = \frac{50}{s(1+0.25s)(1+0.1s)}$$

put $s = j\omega$

$$G(j\omega) = \frac{50}{j\omega(1+0.25j\omega)(1+0.1j\omega)}$$

terms	corner frequency (rad/sec)	slope (dB)	change in slope (dB)
$\frac{50}{j\omega}$		-20	
$\frac{1}{1+0.25j\omega}$	$\omega_{C1} = \frac{1}{0.25} = 4$	-20	-40
$\frac{1}{1+0.1j\omega}$	$\omega_{C2} = \frac{1}{0.1} = 10$	-20	-60

Let $\omega_L = 0.1$ rad/sec

$\omega_H = 50$ rad/sec

At $\omega = \omega_L$

$$\omega_L = 0.1 \text{ rad/sec}$$

$$|A| = 20 \log \left| \frac{50}{5\omega} \right| \text{ at } \omega = \omega_L$$

$$= 20 \log \frac{50}{0.1} = \underline{\underline{53.97 \text{ dB}}} \cancel{+ 5.4 \text{ dB}}$$

At $\omega = \omega_{C1}$

$$\omega_{C1} = 4 \text{ rad/sec}$$

$$|A| = 20 \log \left| \frac{50}{4} \right| = \underline{\underline{21.94 \text{ dB}}} \cancel{- 22 \text{ dB}}$$

At $\omega = \omega_{C2}$

$$\omega_{C2} = 10 \text{ rad/sec}$$

$$|A| = -40 \times \log \left| \frac{50}{4} \right| + 21.94$$

$$= \underline{\underline{6.022 \text{ dB}}}$$

At $\omega = \omega_H$

$$\omega_H = 50 \text{ rad/sec}$$

$$|A| = -60 \times \log \left| \frac{50}{10} \right| + 6.022$$

$$= \underline{\underline{-35.916 \text{ dB}}}$$

ω (rad/sec)	$ A $ dB
0.1	58.98
4	21.94
10	6.022
50	-36.916

$$\angle G(j\omega) = -\tan^{-1}(\omega) - \tan^{-1}(0.25j\omega) - \tan^{-1}(0.1j\omega)$$

ω (rad/sec)	$\angle G(j\omega) - \tan^{-1}(\omega) - \tan^{-1}(0.25j\omega) - \tan^{-1}(0.1j\omega)$	ϕ
0.1	-90	-1.432
1	-90	-14.03
4	-90	-45
10	-90	-68.0198
20	-90	-78.69
50	-90	-85.426

$$\omega_{DC} = \underline{12 \text{ rad/sec}}$$

$$\omega_{DC} = \underline{\underline{7 \text{ rad/sec}}}$$

$$GM = \underline{\underline{-12 \text{ dB}}}$$

$$PM = 180 + -212 = \underline{\underline{-32 \text{ dB}}}$$

So, the system is unstable.

Note 1:- If $G(s) = \frac{10}{s(1+0.1s)}$.

put $k=1$ and draw the bode plot. Find the condition of ω_{nc} . If $\omega_{nc} = 5$ rad/sec and $|H|$ in dB is 28 dB. Shift magnitude plot by -28 dB to obtain the original plot.

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Second order

$$eg:- G(s) = \frac{\pi s (1+0.2s)}{s(s^2 + 16s + 100)}$$

Second order general form $\rightarrow s^2 + 2\zeta\omega_n s + \omega_n^2$

$$\omega_n^2 = 100$$

$$\omega_n = 10$$

$$2\zeta\omega_n = 16$$

$$\zeta = \frac{16}{2 \times 10} = 0.8$$

$$G(s) = \frac{\pi s (1+0.2s)}{s \times 100 \left(1 + \frac{16s}{100} + \frac{s^2}{100} \right)}$$

$$= \frac{0.4\pi (1+0.2s)}{s (1 + 0.16s + 0.1s^2)}$$

put, $s = j\omega$

$$G(j\omega) = \frac{0.4\pi (1+0.2j\omega)}{j\omega (1 + 0.16j\omega + 0.1(j\omega)^2)}$$

$$G(j\omega) = \frac{0.75 (1+j0.2\omega)}{j\omega (1-0.01\omega^2 + 0.16j\omega)}$$

Term	Crossover Frequency	Slope	Change in Slope (dB)
$0.75/j\omega$		-20	
$1+j0.2\omega$	$\omega_{C_1} = \frac{1}{0.2} = 5$	-20	0
$1-0.01\omega^2 + j0.16\omega$	$\omega_{C_2} = \omega_H = 10$	-40	-40

At $\omega = \omega_L$

$$\omega_L = 0.5 \text{ rad/sec}$$

$$\omega_H = 10 \text{ rad/sec}$$

$$\omega_L = 0.5 \text{ rad/sec}$$

$$|A| = 20 \log \left| \frac{0.75}{0.5} \right| = \underline{\underline{3.5 \text{ dB}}}$$

At $\omega = \omega_{C_1}$

$$\omega_{C_1} = 10 \text{ rad/sec}$$

$$|A| = 20 \log \left| \frac{0.75}{5} \right| = -16.47 = \underline{\underline{-16.5 \text{ dB}}}$$

At $\omega = \omega_{C_2}$

$$= -\underline{\underline{0}} + -16.5 = \underline{\underline{-16.5 \text{ dB}}}$$

At $\omega = \omega_H$

$$= -40 \times 20 \log \left| \frac{20}{10} \right| + -16.5 = \underline{\underline{-28.5 \text{ dB}}}$$

ω	$ H $
0.5	3.5
5	-16.5
10	-16.5
20	-28.5

$$\angle G(j\omega) = \tan^{-1}(0.2\omega) - \tan^{-1}(\infty) - \tan^{-1}\left(\frac{0.16\omega}{1-0.01\omega^2}\right)$$

ω (rad/sec)	$\tan^{-1}(0.2\omega)$	$-\tan^{-1}(\infty)$	$-\tan^{-1}\left(\frac{0.16\omega}{1-0.01\omega^2}\right)$	ϕ
0.1	1.14	-90	-0.91	-88.77
0.5	6.31	-90	-4.68	-88.87
1	11.30	-90	-9.18	-83.88
5	45	-90	-46.84	-91.84
10	63.43	-90	0 - 90	-116
20	76.96	-90	$-46.84 + 180^\circ$ $= 133.16$	-148
50				

Frequency domain specification

Resonant peak :-

The maximum value of magnitude is known as resonant peak. Gives the information about the relative stability of the system

$$M_A = \frac{1}{2\sqrt{1-\zeta^2}}$$

Resonant frequency, ω_R

The frequency at which magnitude has maximum value of ω_R is large the time response is fast

$$\omega_R = \omega_N \sqrt{1-2\zeta^2}$$

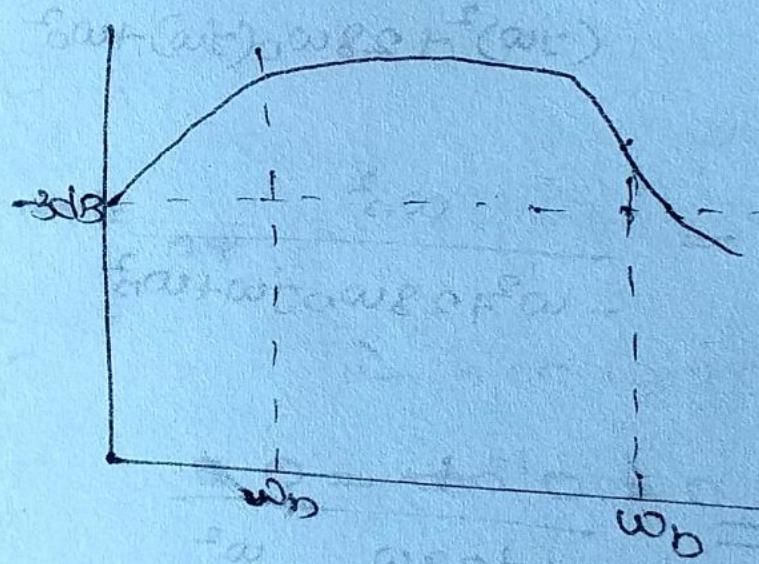
Bandwidth

Bandwidth is defined as the range of frequencies in which the magnitude of close loop does not drop ~ 3 dB.

~~PS~~
cutoff frequency, ω_b
The frequency at which the magnitude
is 3dB below its zero frequency value.

cutoff rate, ϕ

slope of the along magnitude curve



4.5 FREQUENCY RESPONSE PLOTS

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Frequency response analysis of control systems can be carried either analytically or graphically. The various graphical techniques available for frequency response analysis are

- | | |
|---------------------------------|--------------------|
| 1. Bode plot | 4. M and N circles |
| 2. Polar plot (or Nyquist plot) | 5. Nichols chart |
| 3. Nichols plot | |

The Bode plot, Polar plot and Nichols plot are usually drawn for open loop systems. From the open loop response plot the performance and stability of closed loop system are estimated. The M and N circles and Nichols chart are used to graphically determine the frequency response of unity feedback closed loop system from the knowledge of open loop response.

The frequency response plots are used to determine the frequency domain specifications, to study the stability of the systems and to adjust the gain of the system to satisfy the desired specifications.

4.6 BODE PLOT

The Bode plot is a frequency response plot of the transfer function of a system. A Bode plot consists of two graphs. One is a plot of the magnitude of a sinusoidal transfer function versus $\log \omega$. The other is a plot of the phase angle of a sinusoidal transfer function versus $\log \omega$.

The Bode plot can be drawn for both open loop and closed loop transfer function. Usually the bode plot is drawn for open loop system. The standard representation of the logarithmic magnitude of open loop transfer function of $G(j\omega)$ is $20 \log |G(j\omega)|$ where the base of the logarithm is 10. The unit used in this representation of the magnitude is the decibel, usually abbreviated db. The curves are drawn on semilog paper, using the log scale (abscissa) for frequency and the linear scale (ordinate) for either magnitude (in decibels) or phase angle (in degrees).

The main advantage of the bode plot is that multiplication of magnitudes can be converted into addition. Also a simple method for sketching an approximate log-magnitude curve is available.