

Spatial Spectrum Nulling for Wideband OFDM-DFRC System With Hybrid Beamforming Architecture

Presentation at WCNC2022, Austin, TX, USA

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July 31, 2022

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Why DFRC?

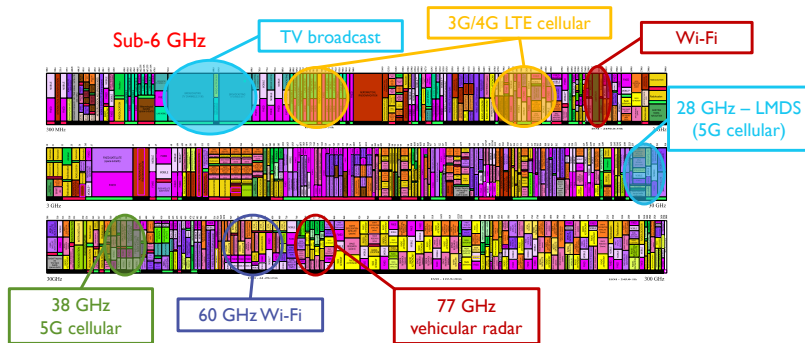
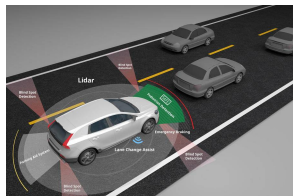


Figure: U.S. Frequency Allocation Chart as of October 2011

How to make efficient use of spectrum resources?

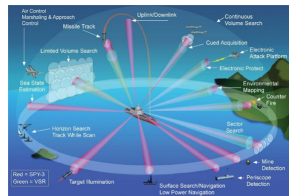
Why DFRC?



(a)



(b)



(c)

Figure: Practical application of DFRC technology

DFRC has wide application scenarios!

- Existing works on DFRC
 - 1 Communication-Centric
 - 2 Radar-Centric
 - 3 **Joint Waveform Design**
- Drawback
 - 1 Fully digital beamforming: Requires one high-resolution RF chain per antenna element.
 - 2 Signal-dependent interference scenarios has not been considered.
- Motivation
 - 1 **Hybrid beamforming** provides a trade-off between performance and hardware cost.
 - 2 **Spatial spectrum nulling** suppresses the unwanted reflect caused by strong interference.

System Model

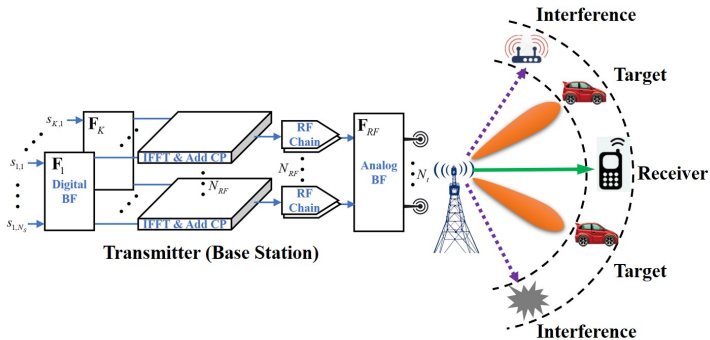


Figure: Overview of a wideband OFDM-DFRC system with hybrid analog and digital beamforming architecture at the transmitter.

System Model

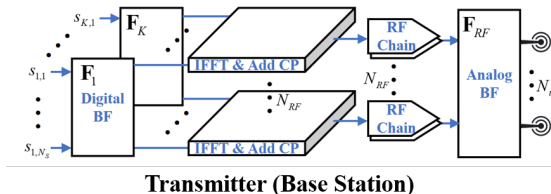


Figure: Overview of a wideband OFDM-DFRC system with hybrid analog and digital beamforming architecture at the transmitter.

In the OFDM hybrid beamforming structure, the transmit signal $\mathbf{x}(t) \in \mathbb{C}^{N_t}$ at time instant t can be expressed as

$$\mathbf{x}(t) = \mathbf{F}_{RF} \sum_{k=1}^K \mathbf{F}_k s_k e^{j2\pi f_k t} \text{rect}(t), \quad (1)$$

- Communication Precoding Design **Main Idea:**

- ① High Quality of Service (QoS) communication.

- **Downlink Communication Model:**

- ① Received signal at downlink user is given by

$$\hat{\mathbf{s}}_k = \mathbf{W}_k^H \mathbf{H}_k \mathbf{F}_{RF} \mathbf{F}_k \mathbf{s}_k + \mathbf{W}_k^H \mathbf{n}_k, \forall k, \quad (2)$$

- ② Minimum Mean Square Error (MMSE)

$$\begin{aligned} \mathbf{E}_k(\mathbf{W}_k, \mathbf{F}_{RF}, \mathbf{F}_k) &= \mathbb{E} \left[(\hat{\mathbf{s}}_k - \mathbf{s}_k) (\hat{\mathbf{s}}_k - \mathbf{s}_k)^H \right] \\ &= \left(\mathbf{W}_k^H \mathbf{H}_k \mathbf{F}_{RF} \mathbf{F}_k - \mathbf{I}_{N_s} \right) \left(\mathbf{W}_k^H \mathbf{H}_k \mathbf{F}_{RF} \mathbf{F}_k - \mathbf{I}_{N_s} \right)^H + \sigma_n^2 \mathbf{W}_k^H \mathbf{W}_k. \end{aligned}$$

- **Communication Performance:** Spectral efficiency achieved at downlink user is given by

$$R_k = \log \left(\left| \mathbf{I}_{N_s} + \mathbf{C}_k^{-1} \mathbf{W}_k^H \mathbf{H}_k \mathbf{F}_{RF} \mathbf{F}_k \mathbf{F}_k^H \mathbf{F}_{RF}^H \mathbf{H}_k^H \mathbf{W}_k \right| \right), \quad (3)$$

where $\mathbf{C}_k = \sigma_n^2 \mathbf{W}_k^H \mathbf{W}_k$ is the noise covariance matrix at k -th subcarrier.

- Radar Waveform Design **Main Idea**:

- ① Effectively control the energy at main-lobe and side-lobe.
- ② Avoid the unwanted return causing by strong interference.

- **Integrated Side-lobe to Main-lobe Ratio (ISMR)** [1] is defined as

$$\begin{aligned} \text{ISMR}(k) &= \frac{\int_{\Delta t} \int_{\Theta_s} |\mathbf{a}^H(f_k, \theta) \mathbf{x}(t)|^2 d\theta dt}{\int_{\Delta t} \int_{\Theta_m} |\mathbf{a}^H(f_k, \theta) \mathbf{x}(t)|^2 d\theta dt} \\ &= \frac{\text{tr}\{\mathbf{F}_{RF} \mathbf{F}_k \mathbf{F}_k^H \mathbf{F}_{RF}^H \mathbf{\Omega}_{s,k}\}}{\text{tr}\{\mathbf{F}_{RF} \mathbf{F}_k \mathbf{F}_k^H \mathbf{F}_{RF}^H \mathbf{\Omega}_{m,k}\}}, \end{aligned} \quad (4)$$

- **Spatial Spectrum Nulling (SNN)** is defined as

$$\|\mathbf{a}^H(f_k, \vartheta) \mathbf{F}_{RF} \mathbf{F}_k\|_F^2 \leq \Gamma_k, \vartheta \in \Theta_k, \quad (5)$$

[1] H. Xu, R. S. Blum, J. Wang and J. Yuan, "Colocated MIMO radar waveform design for transmit beampattern formation," in *IEEE Transactions on Aerospace and Electronic Systems*, vol. 51, no. 2, pp. 1558-1568, April 2015.

Problem Formulation

Problem of interest:

$$\max_{\mathbf{F}_{RF}, \{\mathbf{F}_k\}, \{\mathbf{W}_k\}} \frac{1}{K} \sum_{k=1}^K R_k \quad (6a)$$

$$\text{s.t.} \quad \text{ISMR}(k) \leq \gamma_k, \forall k \quad (6b)$$

$$\|\mathbf{a}^H(f_k, \vartheta) \mathbf{F}_{RF} \mathbf{F}_k\|_F^2 \leq \Gamma_k, \vartheta \in \Theta_k, \forall k \quad (6c)$$

$$\|\mathbf{F}_{RF} \mathbf{F}_k\|_F^2 = P_k, \forall k \quad (6d)$$

$$|\mathbf{F}_{RF}[i, j]| = 1, \forall i, j, \quad (6e)$$

- Joint waveform design criteria.
- High dimension and non-convex problem.

Problem Formulation

- Problem Reformulation based on WMMSE [1]

$$\begin{aligned} \min_{\substack{\mathbf{F}_{RF}, \{\mathbf{F}_k\} \\ \{\mathbf{\Xi}_k\}, \{\mathbf{W}_k\}}} & \frac{1}{K} \sum_{k=1}^K (\text{tr} \{ \mathbf{\Xi}_k \mathbf{E}_k (\mathbf{W}_k, \mathbf{F}_{RF}, \mathbf{F}_k) \} - \log |\mathbf{\Xi}_k|) \\ \text{s.t.} & \quad (5b) - (5e). \end{aligned} \quad (7)$$

The problem w.r.t $\{\mathbf{\Xi}_k\}$ is convex, and the first-order optimality condition yields

$$\mathbf{\Xi}_k = \mathbf{E}_k^{-1} (\mathbf{W}_k, \mathbf{F}_{RF}, \mathbf{F}_k), \forall k, \quad (8)$$

- Origin problem can be simplified as

$$\begin{aligned} \min_{\substack{\mathbf{F}_{RF}, \{\mathbf{F}_k\}, \{\mathbf{W}_k\}}} & \frac{1}{K} \sum_{k=1}^K \text{tr} \{ \mathbf{\Xi}_k^t \mathbf{E}_k (\mathbf{W}_k, \mathbf{F}_{RF}, \mathbf{F}_k) \} \\ \text{s.t.} & \quad (5b) - (5e), \end{aligned} \quad (9)$$

Problem (9) is still hard to tackle!

[1] Q. Shi, M. Razaviyayn, Z. Luo and C. He, "An Iteratively Weighted MMSE Approach to Distributed Sum-Utility Maximization for a MIMO Interfering Broadcast Channel," in *IEEE Transactions on Signal Processing*, vol. 59, no. 9, pp. 4331-4340, Sept. 2011.

Proposed CADMM-Based Approach

- By introducing auxiliary $\{\mathbf{T}_k\}$, $\{\mathbf{V}_k\}$ and $\{\mathbf{Y}_k\}$, the problem (6) can be reformulated as the following consensus problem

$$\min_{\mathbf{F}_{RF}, \{\mathbf{F}_k\}, \{\mathbf{W}_k\}, \{\mathbf{T}_k\}, \{\mathbf{V}_k\}, \{\mathbf{Y}_k\}} \frac{1}{K} \sum_{k=1}^K \text{tr} \{ \mathbf{\Xi}^t \mathbf{E}_k (\mathbf{W}_k, \mathbf{T}_k) \} \quad (10a)$$

$$\text{s.t.} \quad \mathbf{T}_k = \mathbf{V}_k = \mathbf{Y}_k = \mathbf{F}_{RF} \mathbf{F}_k, \forall k \quad (10b)$$

$$\text{tr} \{ \mathbf{V}_k \mathbf{V}_k^H \mathbf{\Omega}_k \} \leq 0, \forall k \quad (10c)$$

$$\| \mathbf{A}_k^H \mathbf{Y}_k \|_F^2 \leq \bar{\Gamma}_k, \forall k \quad (10d)$$

$$\| \mathbf{T}_k \|_F^2 = P, \forall k \quad (10e)$$

$$| \mathbf{F}_{RF} [i, j] | = 1, \forall i, j, \quad (10f)$$

where $\mathbf{A}_k = [\mathbf{a}(f_k, \vartheta_1), \dots, \mathbf{a}(f_k, \vartheta_{k, I_k})]$, $\mathbf{\Omega}_k = \mathbf{\Omega}_{s,k} - \gamma_k \mathbf{\Omega}_{m,k}$ and $\bar{\Gamma}_k = I_k \Gamma_k$.

Proposed CADMM-Based Approach

- Placing the bi-linear equality constraint into the augmented Lagrangian function of yields

$$\mathcal{L} = \sum_{k=1}^K \mathcal{L}_k(\mathbf{F}_{RF}, \mathbf{F}_k, \mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k), \quad (11)$$

- $\mathcal{L}_k(\mathbf{F}_{RF}, \mathbf{F}_k, \mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k)$ is defined as

$$\begin{aligned} & \mathcal{L}_k(\mathbf{F}_{RF}, \mathbf{F}_k, \mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k) \\ &= \frac{1}{K} \text{tr} \{ \mathbf{\Xi}^t \mathbf{E}_k(\mathbf{W}_k, \mathbf{T}_k) \} + \frac{\rho_{1,k}}{2} \left\| \mathbf{T}_k - \mathbf{F}_{RF} \mathbf{F}_k + \frac{\mathbf{\Lambda}_{1,k}}{\rho_{1,k}} \right\|_F^2 \\ &+ \frac{\rho_{2,k}}{2} \left\| \mathbf{T}_k - \mathbf{V}_k + \frac{\mathbf{\Lambda}_{2,k}}{\rho_{2,k}} \right\|_F^2 + \frac{\rho_{3,k}}{2} \left\| \mathbf{T}_k - \mathbf{Y}_k + \frac{\mathbf{\Lambda}_{3,k}}{\rho_{3,k}} \right\|_F^2, \end{aligned}$$

- $\mathbf{\Lambda}_{1,k}, \mathbf{\Lambda}_{2,k}, \mathbf{\Lambda}_{3,k} \in \mathbb{C}^{N_t \times N_s}, \forall k$ denote the dual variables,
- $\rho_{1,k}, \rho_{2,k}, \rho_{3,k} > 0$ stand for corresponding penalty parameters.

Proposed CADMM-Based Approach

- As a result, at the I -th iteration, the corresponding CADMM framework takes the following iterations:

$$\left(\mathbf{W}_k^{(I+1)}, \mathbf{T}_k^{(I+1)}, \mathbf{V}_k^{(I+1)}, \mathbf{Y}_k^{(I+1)} \right) \quad (12a)$$

$$\leftarrow \arg \min_{\mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k} \mathcal{L}_k \left(\mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k, \mathbf{F}_{RF}^{(I)}, \mathbf{F}_k^{(I)} \right)$$

$$\left(\mathbf{F}_{RF}^{(I+1)}, \mathbf{F}_k^{(I+1)} \right) \quad (12b)$$

$$\leftarrow \arg \min_{\mathbf{F}_{RF}, \mathbf{F}_k} \mathcal{L}_k \left(\mathbf{W}_k^{(I+1)}, \mathbf{T}_k^{(I+1)}, \mathbf{V}_k^{(I+1)}, \mathbf{Y}_k^{(I+1)}, \mathbf{F}_{RF}, \mathbf{F}_k \right)$$

Optimization of $(\mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k)$

- With fixed $(\mathbf{F}_{RF}, \mathbf{F}_k)$ and $(\mathbf{\Lambda}_{1,k}, \mathbf{\Lambda}_{2,k}, \mathbf{\Lambda}_{3,k})$, the $(\mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k)$ are updated by solving the following problem

$$\min_{\mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k} \mathcal{L}_k(\mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k) \quad (13a)$$

$$\text{s.t.} \quad \text{tr}\{\mathbf{V}_k \mathbf{V}_k^H \mathbf{\Omega}_k\} \leq 0 \quad (13b)$$

$$\|\mathbf{A}_k^H \mathbf{Y}_k\|_F^2 \leq \bar{\Gamma}_k \quad (13c)$$

$$\|\mathbf{T}_k\|_F^2 = P, \forall k. \quad (13d)$$

Optimization of $(\mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k)$

STEP1: Update of \mathbf{T}_k

- ① By leveraging the Karush-Kuhn-Tucker (KKT) conditions, the close-form solution to \mathbf{T}_k can be calculated by

$$\mathbf{T}_k^*(\mu_k) = \{\Phi_k + 2\mu_k \mathbf{I}_{N_t}\}^{-1} \Upsilon_k, \quad (14)$$

- $\Phi_k = \frac{2}{K} \mathbf{H}_k^H \mathbf{W}_k \Xi_k^t \mathbf{W}_k^H \mathbf{H}_k + (\rho_{1,k} + \rho_{2,k} + \rho_{3,k}) \mathbf{I}_{N_t}$
- $\Upsilon_k = \frac{2}{K} \mathbf{H}_k^H \mathbf{W}_k \Xi_k^t + \rho_{1,k} \mathbf{F}_{RF} \mathbf{F}_k + \rho_{2,k} \mathbf{T}_k + \rho_{3,k} \mathbf{Y}_k - \Lambda_{1,k} - \Lambda_{2,k} - \Lambda_{3,k}$.

- ② Defining eigenvalue decomposition (EIG) $\Phi_k = \mathbf{Q}_k \mathbf{D}_k \mathbf{Q}_k^H$ and substituting (14) into the power constraint, one gets

$$\|\mathbf{T}_k^*(\mu_k)\|_F^2 = \sum_{n=1}^{N_t} \frac{(\mathbf{Q}_k^H \Upsilon_k \Upsilon_k^H \mathbf{Q}_k)[n, n]}{(\mathbf{D}_k[n, n] + 2\mu_k)^2} = P. \quad (15)$$

- ③ The optimal multiplier μ_k can be easily obtained via using golden-section search or Newton's method.
- ④ Plugging the μ_k into (14), we can obtain the solution of \mathbf{T}_k .

Optimization of $(\mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k)$

STEP2: Update of \mathbf{V}_k

- ① By leveraging the KKT conditions, we can obtain

$$\mathbf{V}_k^* = \{\rho_{2,k} \mathbf{I}_{N_t} + 2\chi_1 \mathbf{\Omega}^H\}^{-1} \mathbf{\Psi}_k \quad (16a)$$

$$\chi_1 \text{tr}\{\mathbf{V}_k \mathbf{V}_k^H \mathbf{\Omega}_k\} = 0, \chi_1 \geq 0 \quad (16b)$$

$$\text{tr}\{\mathbf{V}_k \mathbf{V}_k^H \mathbf{\Omega}_k\} \leq 0 \quad (16c)$$

where $\mathbf{\Psi}_k = \mathbf{\Lambda}_{2,k} + \rho_{2,k} \mathbf{T}_k$.

- ② Case 1: For $\chi_1 = 0$, from the (16a) we have $\mathbf{V}_k^* = \{\rho_{2,k} \mathbf{I}_{N_t}\}^{-1} \mathbf{\Psi}_k$, which must satisfy the condition (16c), otherwise
- ③ Case 2: For $\chi_1 \neq 0$, from the (16a) we have

$$\mathbf{V}_k^*(\chi_1) = \{\rho_{2,k} \mathbf{I}_{N_t} + 2\chi_1 \mathbf{\Omega}^H\}^{-1} \mathbf{\Psi}_k \quad (17)$$

- Plugging (17) into equality constraint $\text{tr}\{\mathbf{V}_k \mathbf{V}_k^H \mathbf{\Omega}_k\} = 0$, we obtain

$$\text{tr}\{\mathbf{V}_k^*(\chi_1) (\mathbf{V}_k^*(\chi_1))^H \mathbf{\Omega}_k\} = \sum_{n=1}^{N_t} \frac{\mathbf{M}_{1,k}[n, n] (\mathbf{Z}_{1,k}^H \mathbf{\Psi}_k \mathbf{\Psi}_k^H \mathbf{Z}_{1,k})[n, n]}{(\rho_{2,k} + 2\chi_1 \mathbf{M}_{1,k}[n, n])^2} = 0. \quad (18)$$

Optimization of $(\mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k)$

STEP3: Update of \mathbf{Y}_k

- Following the same procedure for updating \mathbf{V}_k , we can obtain

$$\mathbf{Y}_k^* = \{\rho_{3,k} \mathbf{I}_{N_t} + 2\chi_2 \mathbf{A}_k \mathbf{A}_k^H\}^{-1} \mathbf{\Pi} \quad (19a)$$

$$\|\mathbf{A}_k^H \mathbf{Y}_k^*\|_F^2 \leq \bar{\Gamma}_k \quad (19b)$$

$$\chi_2 \left(\|\mathbf{A}_k^H \mathbf{Y}_k^*\|_F^2 - \bar{\Gamma}_k \right) = 0, \quad \chi_2 \geq 0, \quad (19c)$$

STEP4: Update of \mathbf{W}_k

- According to MMSE receiver, its optimal solution of \mathbf{W}_k can be calculated as

$$\mathbf{W}_k = (\mathbf{H}_k \mathbf{T}_k \mathbf{T}_k^H \mathbf{H}_k^H - \mathbf{I})^{-1} \mathbf{H}_k \mathbf{T}_k. \quad (20)$$

Optimization of $(\mathbf{F}_{RF}, \mathbf{F}_k)$

- With fixed $(\mathbf{W}_k, \mathbf{T}_k, \mathbf{V}_k, \mathbf{Y}_k)$ and $(\Lambda_{1,k}, \Lambda_{2,k}, \Lambda_{3,k})$, the $(\mathbf{F}_{RF}, \mathbf{F}_k)$ are updated by solving the following problem

$$\begin{aligned} \min_{\mathbf{F}_{RF}, \{\mathbf{F}_k\}} \quad & \sum_{k=1}^K \frac{\rho_{1,k}}{2} \left\| \mathbf{T}_k - \mathbf{F}_{RF} \mathbf{F}_k + \frac{\Lambda_{1,k}}{\rho_{1,k}} \right\|_F^2 \\ \text{s.t.} \quad & |\mathbf{F}_{RF}[i, j]| = 1, \forall i, j. \end{aligned} \quad (21)$$

STEP1: Update of \mathbf{F}_k

- The close-form solution of \mathbf{F}_k is given by

$$\mathbf{F}_k = (\mathbf{F}_{RF}^H \mathbf{F}_{RF})^{-1} \mathbf{F}_{RF}^H \left(\mathbf{T}_k + \frac{\Lambda_{1,k}}{\rho_{1,k}} \right). \quad (22)$$

Optimization of $(\mathbf{F}_{RF}, \mathbf{F}_k)$

STEP2: Update of \mathbf{F}_{RF}

- 1 Block Coordinate Descent (BCD) method is implemented to update \mathbf{F}_{RF}
- 2 The optimization problem w.r.t. $\mathbf{F}_{RF} [i, j]$ can be written as

$$\begin{aligned} \min_{\mathbf{F}_{RF}[i,j]} \quad & -\Re \{ \mathbf{F}_{RF} [i, j] \zeta_{i,j} \} \\ \text{s.t.} \quad & \mathbf{F}_{RF} [i, j] = e^{-j\varpi_{i,j}}, \end{aligned} \quad (23)$$

- $\zeta_{i,j} = \sum_{k=1}^K \rho_{1,k} \left(\mathbf{F}_k \bar{\mathbf{T}}_k^H - \mathbf{F}_k (\bar{\mathbf{F}}_{RF}^{i,j} \mathbf{F}_k)^H \right) [j, i],$
 - $\bar{\mathbf{T}}_k = \mathbf{T}_k + \frac{\Lambda_{1,k}}{\rho_{1,k}},$
 - $\bar{\mathbf{F}}_{RF}^{i,j}$ denotes the matrix \mathbf{F}_{RF} with (i, j) element is zero.
- 3 It is obvious that the optimal solution of $\mathbf{F}_{RF} [i, j]$ is

$$\varpi_{i,j} = \text{angle}(\zeta_{i,j}) \quad (24)$$

Computational Complexity

- 1 The main computational complexity is caused by updating $(\mathbf{F}_{RF}, \{\mathbf{F}_k\})$ and $(\{\mathbf{W}_k\}, \{\mathbf{T}_k\}, \{\mathbf{V}_k\}, \{\mathbf{Y}_k\})$ in each iteration.
- 2 Updating $(\mathbf{F}_{RF}, \{\mathbf{F}_k\})$ requires $\mathcal{O}(K(N_t N_{RF} N_s + N_t N_{RF}^2))$ operations.
- 3 Updating $(\{\mathbf{W}_k\}, \{\mathbf{T}_k\}, \{\mathbf{V}_k\}, \{\mathbf{Y}_k\})$ needs $\mathcal{O}(K N_t^2 (\log(2) + N_s))$ operations,.
- 4 As a result, the overall complexity of the proposed algorithm is given by $\mathcal{O}(T_{max} K(N_t N_{RF} N_s + N_t N_{RF}^2 + N_t^2 N_s + N_t^2 \log(2)))$.

Parameters Setting

Parameter	Value	Parameter	Value
M_t	32	N_s	4
M_{RF}	4	N_r	2
f_c	10GHz	Δf	20MHz
K	128	P_k	1

Table: Collection of parameters values

- The main-lobe region $\Theta_m = [-10^\circ, 10^\circ]$,
- The side-lobe region $\Theta_s = [-90^\circ, -10^\circ) \cup (10^\circ, 90^\circ]$,
- The SSN azimuths Θ_k are assumed as $\Theta_k = [-24^\circ, -21^\circ] \cup [21^\circ, 24^\circ], \forall k$,
- The threshold Γ_k of the SSN on k -th subcarrier is set as 50dB,
- The initial penalty parameter and the convergence tolerance are set to $\rho_{1,k} = \rho_{2,k} = \rho_{3,k} = 1, \forall k$ and $\hbar_1 = \hbar_2 = \hbar_3 = 10^{-6}$, respectively.

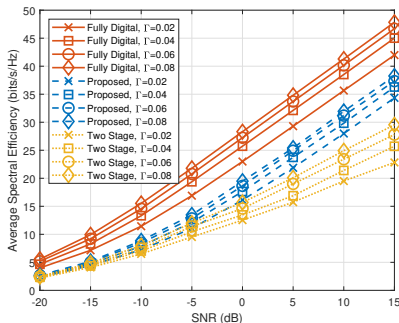


Figure: The achievable spectral efficiency versus number of iteration in an OFDM-DFRC based SU-MIMO system with different ISMR value γ .

- The attained spectral efficiencies increase along with the γ for all algorithms,
- The proposed algorithm always achieve better performance that two stage method with the same ISMR constraint.

Radar Performance

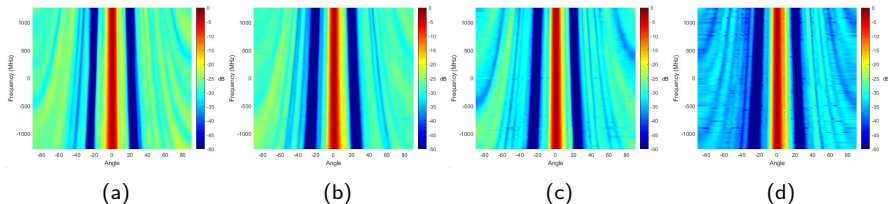


Figure: The space-frequency spectral behaviors of the OFDM-DFRC with different ISMR value (1) $\gamma = 0.08$, (2) $\gamma = 0.06$, (3) $\gamma = 0.04$, (4) $\gamma = 0.02$.

- As the ISMR level γ decreases, the side-lobe energy becomes lower and lower,
- The beampattern has desired SSN at interference azimuth for all γ ,
- There exist the coupling effect between the space and frequency.

- In this paper, we address the problem of the hybrid beamforming design for the OFDM-DFRC system. The corresponding problem is to maximize the spectral efficiency via optimizing the hybrid beamformer, while fulfilling the requirements for the radar side.
- The simulation results shows that:
 - We propose an alternating optimization based method to tackle the non-convex problem.
 - The simulation results show that the proposed method can achieve satisfactory performance and outperform the conventional two-stage method.

Thank you !!

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