



BRIGHAM YOUNG UNIVERSITY
AUVSI CAPSTONE TEAM (TEAM 45)

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1 Descriptions

Each of the primary concepts is described in further detail below.

1.1 Parachute

A parachute is attached to the UGV, and is opened upon release of the UGV from the aircraft. To improve the accuracy of this concept, the effect of wind on the parachute and payload is characterized and used to calculate the optimal drop location given the estimated wind speed at the time of drop. No control mechanisms are used during the drop.

1.2 Parachute w Controls

Similar to the Parachute concept, but control surfaces (fins) are attached to the payload and actuated as the payload drops. This provides some controllability to stabilize the drop and to improve accuracy.

1.3 Skycrane

The UGV is lowered on a string or rope while the airframe circles overhead. The circling motion causes the UGV to orbit in a smaller circle as it is lowered. When the UGV hits the ground, it releases itself from the string to prevent interrupting the flight of the airframe. Preferably the UGV controls the rate of descent so it can easily feed back its distance from the ground.

1.4 Glider

A glider is carried onboard the airframe and is released when the UGV drop is attempted. The glider either incorporates or carries a ground vehicle. The glider is unpowered, but is controlled like a normal aircraft.

2 Evaluation Methods and Results

As can be seen from the decision matrix in Table ??,

Table 1: A decision matrix the UGV Drop Method. A scale of 1-5 was used for weights with 5 having high importance and 1 having low importance. A 1-5 scale was also used to rate each option's performance under each requirement. In this case, a 1 was used to indicate poor performance while a 5 indicates favorable performance.

UGV Drop Method	Weight	Glider	Sky Crane	Parachute	Un-aided Drop (Reference)
UGV Weight	1	0	0	0	0
Stowed Drag	1	0	0	0	0
Max Drop Height	1	0	0	0	0
Max Landing Velocity	1	0	0	0	0
Accuracy in Hitting Target	1	0	0	0	0
Totals	.	0	0	0	0