							4 5	3	2	1		Pro
						Import	The autopilot follows the planned path The path planner plans effective paths	The path planner plans paths quickly	The path planner hits waypoints	Market Requirements The path planner avoids obstacles	Moultot Donning works	oduct: UAV Autopilot
Measured	Predicted	Target	Upper Acceptable	dea	Acceptable		10	5	6	9	Performance Measures Units	its
1	0	0	3	0	0	ω				_	Number of Obstacles Hit Count	nnt
3.146	3	3	2	2	0	3				2	Average Waypoint Miss Distance Meter	ter
7	20	20	45	20	0	9				3	Path Planning Time	Seconds
17	10	10	20	0	0	9				4	Root mean squared distance from desired path Meter	ter
3.5	5	2	5	1.5	_	9				2	Ratio of Planned Path to Total Waypoint Distance Unitless	itless