

Brigham Young University AUVSI Capstone Team (Team 45)

UGV Requirements Matrix

	ID	Rev.	Date	Description	Author	Checked By
	RM-001	0.1	10-23-	Initial require-	Jacob Willis	Brady Moon
			2018	ments		
Ī	RM-001	1.1	10-26-	Better perfor-	Jacob Willis	Kameron Eves
			2018	mance mea-		
				sures		



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	Product: UAV Subsystem: PAYLOAD/Unmanned Ground Vehicle (UGV) Notes: *normalized by the fusalage diameter cubed **normalized by chord	Subsystem Performance Measures	Drop mechanism mass	Weight mechanism can support	Aircraft internal volume consumed*	Mounting distance from aircraft CG**	Stowed drop mechanism drag	Maximum landing velocity	UGV landing distance from target	Rule violations
	Target Design Requirements	Importance	1	2	3	4	5	6	7	8
1	Complies with competition rules	5								
2	Capable of lowering the payload to the ground	5								
3	Lands UGV within landing zone	3								
5	Delivers UGV without damage	3								
6	Deployable from airframe	4								
7	Does not interfere with takeoff/landing	3								
8	Causes minimal aerodynamic interference	3								
9	Drop mechanism does not interfere with UGV movement	2								
		ble Ideal Lower Acceptable	0	9.0	-	-100	0	0	-	1
		Ideal	0.1	1.3	0	0	0.3	1	0	0
		Upper Acceptable	9.0	I	100	100	1.5	5	22	7

 $Figure\ 1:\ Requirements\ matrix\ for\ the\ subsystem\ which\ will\ deliver\ the\ UGV\ to\ the\ ground.$