

Brigham Young University AUVSI Capstone Team (Team 45)

Airframe Subsystem Requirements Matrix

ID	Rev.	Date	Description	Author	Checked By
AF-001	0.1	10-23-18	Initial Draft	Tyler Critchfield	Derek Knowles
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AF-001	0.2	11-06-18	Revisions for	Tyler Critchfield	Ryan Anderson &
			Final Submis-		Kameron Eves
			sion		



			ω			(7)	_	(1)	<u></u>	Ι_,	1			
				7 Fast and cheap rebuild	6 Capable of carrying UGV and water bottle	5 Complies with AMA safety code	4 Components are protected	3 Minimize flight path deviation	2 Capable of traveling an extended distance	1 Capable of flight for extended period of time	Market Requirements	Product UAS Subsystem: Airframe		
					d water bottle)de			nded distance	d period of time				
Upper Acceptable	Ideal	Lower Acceptable	_	S	3	9	9	9	9	9	Importance	Performance Measures	Units	
N/A	75	40							•		_	Battery life	Minutes	
N/A	20	5			•				•		2	Lift-to-drag ratio	Unitless	
1	1	0.2			•				•		ω	Motor/prop efficiency	Unitless	
50	4	0			•				•	•	4	Airframe weight	Kilograms	
30	15	10			•				•		5	Average flight speed	Meters/second	
20	10	N/A			•			•			6	Stall speed	Meters/second	
-0.01	-0.05	-0.1						•			7	Spiral stability eigenvalue	Unitless	
0.2	0.1	0						•			8	Static margin	Unitless	
0.15	0.1	0.05						•			9	Cn,beta (yaw)	Unitless	
0	-0.1	-0.15						•			10	CI,beta (roll)	Unitless	
0	0	0)			1	Number of components that fall off the plane	Unitless	
0	0	0		•)			12	Number of damaged components on landing	Unitless	
0	0	0				•					13	Number of AMA safety code violations	Unitless	
1	0.5	0.4			•						14	Lift coefficient	Unitless	
12000	10000	8000			•						15	Storage volume	Cubic centimeters	
4	0	0		•							16	Time to rebuild	Hours	
10	10	5		•							17	Focus group ease of repair	1-10 scale	
		5	-	_	_	 	-	+	+	+	18		1	

Figure 1: Airframe subsystem requirements matrix. Note that sometimes ideal values are unrealistic; rather, they are ideal. E.g., the ideal required build time is not time at all. Realism will be incorporated into target values in a future version of the Requirements Matrix.