

# Capstone Team 45 Status Update 03-13-2019

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The following is a list of status updates and goals for each of the four subteams:

## Airframe

(Ryan Anderson, Tyler Critchfield, Kameron Eves)

### Last Week:

- Worked on second airframe (very close to being finished, receiving some final parts)
- Assisted in the new mission planner software design
- We lost a battery... we think it might have been because we left it plugged in for too long, starting from too low a voltage during hardware testing

### Next Week:

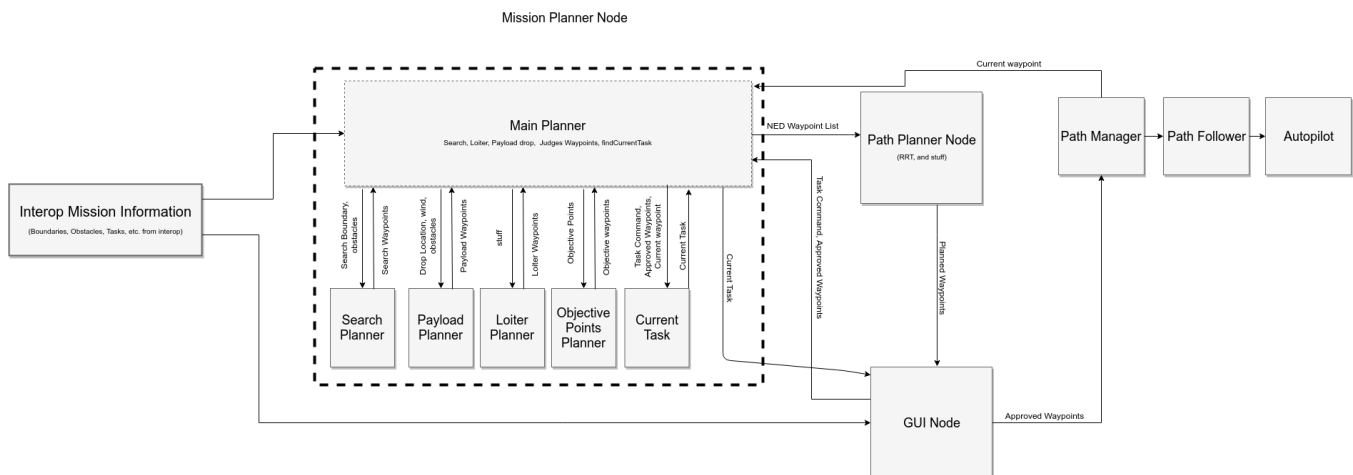
- Finish the second airframe
- Assist in software development

## Controls

(Andrew Torgesen, Brady Moon, John Akagi)

### Last Week:

- Completed the overhauled estimator and tested/validated it on flight test data
- Created a software scheme for all mission objectives that makes things modular and changes how tasks are commanded, with the following advantages:
  - we can use the old system for completing our key success measures while streamlining the cleaned-up system for the competition in June
  - development is made easier for us now, as well as next year's team
  - it allows for dynamic reconfiguration of waypoints in the air, which is necessary for things like accounting for wind in the payload drop



### Next Week:

- have preliminary “vanilla” static obstacle path planner working (we can leverage last year’s code here)
- fly waypoints in hardware and get ready for mock competition

## UGV

*(Jacob Willis, Derek Knowles, Brandon McBride)*

### Last Week:

- Started developing payload planner for mission software suite.
- Fixed problem with arduino on airframe
- Added LED to arduino to time signal to release
- Not much else. We've been helping with other things this week.

### Next Week:

- Assemble the UGV with all the new electronics
- Work on wiring for the second airframe
- Work on the path planner for the payload drop

## Vision

*(Tyler Miller, Jake Johnson, Connor Olsen)*

### Last Week:

- figured out why we couldn't stream images - ros network issue
- geolocation, unit test progress
- shape classifier does well against detected targets - 3/5 correctly classified (improvement from v1's 0/5). have an idea on how to augment dataset for better accuracy

### Next Week:

- geolocation unit tests
- verify we have fixed the network issue, document solution, test fly live manual classification

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Please send us any feedback with regards to the progress we've made, as well as our plans for the coming week.