Product: UAV Autopilot	Ø	t	Jé	Seconds	Jé.	ess
	Units	Count	Meter	Sec	Meter	Unif
	Performance Measures	Number of Obstacles Hit	Average Waypoint Miss Distance	Path Planning Time	Root mean squared distance from desired path	Ratio of Planned Path to Total Waypoint Distance Unitless
Market Requirements	п.	<u> </u>	2	3 F	4	5
1 The path planner avoids obstacles	9					
2 The path planner hits waypoints	6					
3 The path planner plans paths quickly	5					
4 The autopilot follows the planned path	10					
5 The path planner plans effective paths	9					
Importa	nce	8	3	9	9	9
	Acceptable	0	0	0	0	-
	Ideal	0	2	20	0	1.5
	Upper Acceptable	3	2	45	20	5
	Target	0	3	20	10	2
	Predicted	0	3	20	10	5
	Measured	_	3.146	2	17	3.5