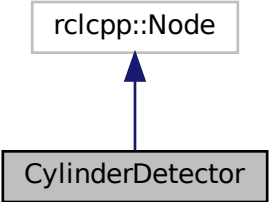


rclcpp::Node



```
graph BT; CougKinematics --> rclcpp::Node
```

CougKinematics