Control Stack	Control Mode	Enum	North	East	Down	Yaw	Use Case Examples
High Level	0	MODE_NPOS_EPOS_DPOS_YAW	Pos	Pos	Pos	Angle	Waypoint Following
Mid Level	4	MODE_NPOS_EPOS_DVEL_YAW	Pos	Pos	Vel	Angle	Landing
	1	MODE_NVEL_EVEL_DPOS_YAWRATE	Vel	Vel	Pos	Rate	Constant Altitude
	3	MODE_NVEL_EVEL_DVEL_YAWRATE	Vel	Vel	Vel	Rate	Target Following
Low Level	2	MODE_NACC_EACC_DACC_YAWRATE	Accel	Accel	Accel	Rate	Trajectory Following