Lab 8

- 1. Define two structural elements, perform binary dilation, erosion, opening, and closing operations on noisy_fingerprint.pgm and noise_rectangle.pgm
- 2. Extract the boundaries of licoln.pgm and U.pgm
- 3. Count the number of pixels in each white connected component from connected.pgm and put them into a .txt file
- 4. Problem 9.36, write a program to separate the three required sets from bubbles_on_black_background.pgm

Algorithm:

1. Dilation

$$A \oplus B = \{z | [((\hat{B})_z \cap A] \subseteq A\}$$

```
Input: array of image f
for(i=0; i<size of image;i++){
    if there is one pixel value =255 within the structural element
        image[i]=255
return image
```

2. Erosion

$$A \ominus B = \{z | (B)_z \subseteq A\}$$

```
Input: array of image f
for(i=0; i<size of image;i++){
    if there is one pixel value =0 within the structural element
        image[i]=0
return image</pre>
```

3. Opening

First conduct erosion operation and then dilation operation

Input: array of image f outimage=Erosion(image) outimage=Dilation(outimage) return outimage

4. Closing

First conduct dilation operation and then erosion operation

Input: array of image f outimage= Dilation(image) outimage= Erosion(outimage) return outimage

5. Boundary Extraction

Input: array of image f erosionimage = Erosion(outimage) outimage=image-erosionimage return outimage

Count the number of pixels in each white connected component
 Denote the input image is A0, the iteration matrix is Xk, and the connected component storage

matrix is B

A=A0

```
while(there is still white dot in A){
  find the point in A , the grey value of which is 1
  select the first point whose grey value is 1 as the initial point
  find the intersection after dilation
  if(Xk==Xk-1) ends iteration
  B=B+Xk
  A=A-B
}
7. Extract Boundary-Overlapping-Only Particles
  Input: the array of image
```

```
temp=0 array with length of image size
temp[0]=255
while (true) {
    Xk = temp
    memcpy(Xk, temp, size);
    temp = Dilation(temp);
    for (i = 0; i < size of image; i++) {
        if (temp[i] > image[i]) {
            temp[i] = image [i];
        }
    }
    if (Xk is the same as temp) ends the iteration
}
outimage = temp
return outimage;
```

8. Extract Particle-Overlapping-Only Particles

Input: the array of image

A=the area of one particle.

- 1. First depends on the result of Boundary-Overlapping-Only method to remove those particles on the boundary
- 2. Then depends on the result of the connected component algorithm, count the number of pixels in each component. If the number of pixels in current component is less than $A+\epsilon$, where ϵ is a small error that can be tolerated, than remove it.
- 9. Extract None-Overlapping Particles

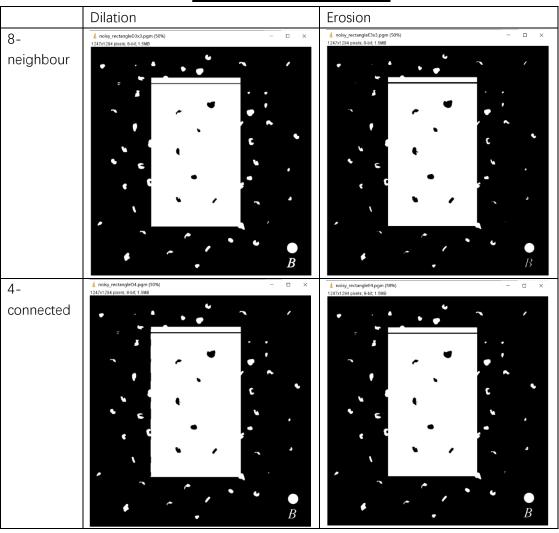
Input: the array of image

```
bondraryoverlapping=boundary-Overlapping-Only(image)
particleoverlapping= Particle-Overlapping-Only(image)
outimage=image- bondraryoverlapping- particleoverlapping
```

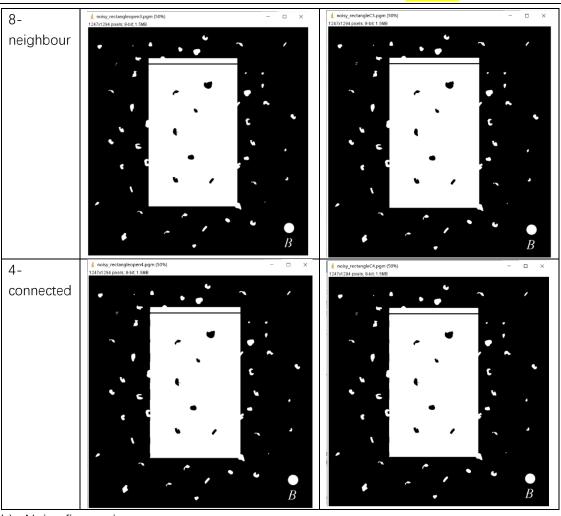
Results (compare the results with the original image):

- 1. Here use 8-neighbour and 4-connected structural elements in task 1.
 - a) Noisy_rectangle.pgm





Opening	Closing
9 5 5 5 5 5 5	0.009



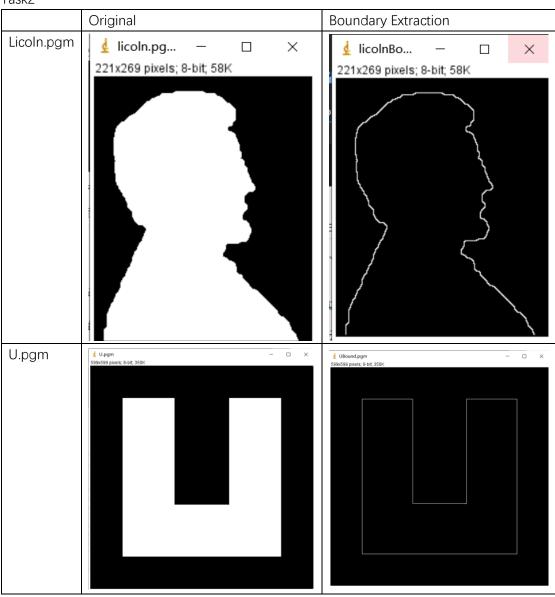
b) Noise_fingerprint.pgm



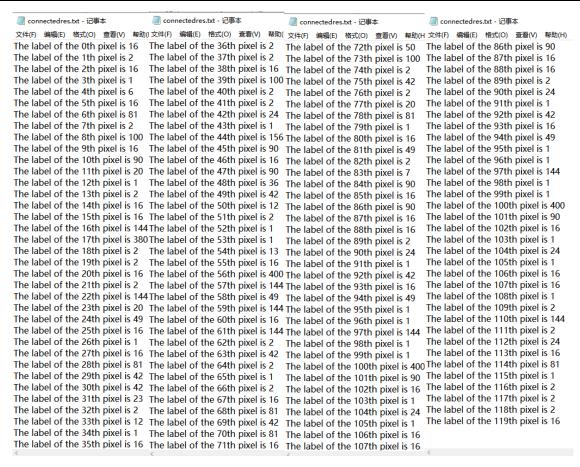




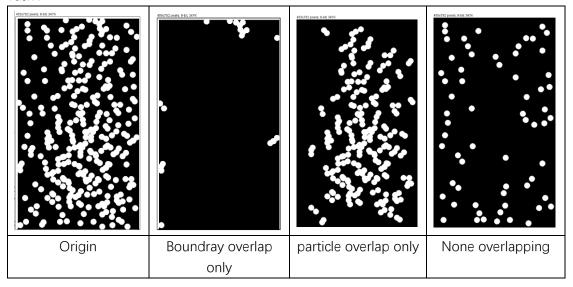
2. Task2



3. Task 3



4. Task4



Discussion:

- 1. In task 1, the performance of 4-connected structural element is worse than the 8-neighbour structural element.
- 2. From the result of task 1, we can see that the erosion operation helps to remove noise. erosion operations on low-size structural elements easily remove scattered salt and pepper noise points. And the dilation operation helps to connect adjacent elements in the image.
- 3. Opening operation: erosion first, then dilation, can remove some bright pixels, magnify local low brightness areas, separate objects at thin points, and smooth the boundary of larger objects while not significantly changing its area.
- 4. Closed operation: dilation, then erosion, can remove some dark pixels, i.e. exclude small black

holes (black areas)

- 5. During the process of boundary extraction, when a 3x3 1-value structural element is used, the extracted boundary value is 1 pixel. Just as the result of previously shown.
- 6. The connected component analysis is useful to the following image separation and segmentation. The algorithm that I implemented in this lab has a low efficiency because there are too many iterations.
- 7. In Task 5, the operation of separating the image is the combination of dilation, connected component analysis operation.

Codes:

1. Dilation

2. Erosion

```
for (i = 1; i < image->Height - 1; i++) {
    for (j = 1; j < image->Width - 1; j++) {
             for (p = -1; p < 2; p++) {
for (q = -1; q < 2; q++) {
                       if (tempin[(i + p) * image->Width + (j + q)] == 0) {
                            temp[i * image->Width + j] = 0;
         else {
             if (tempin[(i - 1) * image->Width + j] == 0) {
                  temp[i * image->Width + j] = 0;
             else if (tempin[(i + 1) * image->Width + j] == 0) {
                  temp[i * image->Width + j] = 0;
                  break:
             else if (tempin[i * image->Width + (j - 1)] == 0) {
    temp[i * image->Width + j] = 0;
                  break;
             else if (tempin[i * image->Width + (j + 1)] == 0) {
    temp[i * image->Width + j] = 0;
```

3. Opening

```
□Image* Opening(Image* image, int flag) {
     Image* outimage:
     outimage = Erosion(image, flag);
     outimage = Dilation(outimage, flag);
     return outimage;
                                                   Closing
```

4. Closina

```
□Image* Closing(Image* image, int flag) {
     Image* outimage:
     outimage = Dilation(image, flag);
     outimage = Erosion(outimage, flag);
     return outimage;
```

5. Boundary Extraction

```
JImage* BoundaryExtraction(Image* image) {
    unsigned char* tempin, * tempout;
    Image* outimage:
    int* temp = (int*)malloc(sizeof(int) * image->Height * image->Width);
    tempin = image->data;
    outimage = Erosion(image, 1);
    tempout = outimage->data;
    for (i = 0; i < image->Height * image->Width; i++) {
         tempout[i] = tempin[i] - tempout[i];
    return outimage;
```

6. Count the number of pixels in each white connected component

```
while (FindPoint(A, pixel, 255 , image->Height, image->Width)) {
    X1[pixel[0].y * image->Width + pixel[0].x] = 255:
          unsigned char *Xk = (unsigned char*)malloc(sizeof(unsigned char) * size);
          memcpy(Xk, X1, size);
          X1 = DilationArr(X1, image->Height, image->Width);
              if (memcmp(Xk, X1, size) == 0) {
     num[count] = FindPoint(X1, pixel , 255, image->Height, image->Width):
     for (i = 0; i < size; i++) {
    if (B[i] < X1[i]) {
        B[i] = X1[i]:
    }
}</pre>
     memset(X1, 0, sizeof(unsigned char) * size);
     for (i = 0; i < size: i++) {
    A[i] -= B[i];
    if (A[i] < 100) {
        A[i] = 0:
```

7. Extract Boundary-Overlapping-Only Particles

```
temp[0] = 255;
                                                 unsigned char* Xk = (unsigned char*) malloc(sizeof(unsigned char) * image->Height * image->Width);
                                                      memcpy(Xk, temp, size);
                                                         temp = DilationArr(temp, image->Height, image->Width);
                                                   for (i = 0; i < size; i++) {
    if (temp[i] > tempin[i]) {
        temp[i] = tempin[i];
}
                                                          \hspace{0.1cm} 
                                                         free(Xk):
```

```
if (memcmp(Xk, X1, size) = 0) {
    break;
  .num[count] = FindPoint(X1, pixel, 255, image=>Height, image=>Width):
 for (int i = 0; i < size; i++) {
   tempout[i] = X2[i];</pre>
```

8. Extract None-Overlapping Particles

```
∃Image* NoneOverlapping(Image* image) {
    int size = image->Height * image->Width;
     Image* WithP,* WithB;
    Image* outimage = CreateNewImage(image, "NoneOverlapping", image->Width, image->Height);
    WithB = BoundaryOverlappingOnly(image);
    WithP = ParticalOverlappingOnly(image);
    unsigned char* tempin = image->data;
    unsigned char* temp1 = WithB->data;
    unsigned char* temp2 = WithP->data;
    unsigned char* tempout = outimage->data;
         tempout[i] = tempin[i] - temp1[i] - temp2[i];
    return outimage;
```