

# BAUYRZHAN ZHAKANOV

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*Targeting a 3-month, full-time internship position from 05.2020-08.2020*

## EDUCATION

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### Nazarbayev University, Kazakhstan

Bachelor of Engineering & Digital Sciences  
Robotics and Mechatronics

Sep 2017 - expected Jun 2021

## WORK EXPERIENCE

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### Research Assistant (RA) in alaris.kz

May 2019 - present

- The laboratory focuses on research in specific areas of intelligent industrial, assistive and mobile robotics.
- Successfully implemented RTabMap for Localization and Mapping via Kinect V1
- Successfully used and tested different version of Visual Odometry for Localization and Mapping

### Stand Exhibitor at EXPO-2017

June 2017 - August 2017

- EXPO 2017 Future Energy is the international event situated in 2017 in Nur-Sultan, Kazakhstan. Visitors were able to know more about new green technologies from presentations, staff and engineers

## PROJECTS (ALL AVAILABLE IN GITHUB)

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### Machine Learning Project: Driver Distraction Identification

- This is a machine learning course project at Nazarbayev University.
- Implemented VGG16 architecture neural network for identification of driver position.
- The dataset is the property of professor H. Eraqi from the Machine Intelligence group at the American University in Cairo, Egypt.

### Gesture Control with Arduino

- This is a gesture control by hands via Arduino Uno and two Ultrasonic sensors. Project was made during the Microcontrollers Course (ROBT 204) at Nazarbayev University, Nur-Sultan, Kazakhstan.

### Browser

- The project is created with a help of Delphi7
- Created during the high school

## MENTORSHIP

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### Student Mentor at Microsoft Digigirlz

June 2019

- Successfully organized the Microsoft Digigirlz event
- Mentored and helped girls to build a RoboHand with Arduino via C Language which was held at Microsoft Digigirlz, Nur-Sultan, Kazakhstan.

## TECHNICAL SKILLS

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**Programming:** Python3, C++, MATLAB, Java, Delphi7

**Software & Tools:** Deep Learning Frameworks: PyTorch, Caffe2, OpenCV, PointCloud

**Mechanical Design and Simulation:** Solidworks, MATLAB, V-REP, Gazebo, ROS