Hands on Machine Learning Linear Regression

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Given m data points, e.g., $f(a_1, a_1) = 2 + 3a_1 + 2a_2 + 2a_1 + 2a_2 + 2a_1 + 2a_2 + 2a_1 + 2a_2 + 2a_2 + 2a_1 + 2a_2 + 2a_$ Let $\mathbf{a}_i = (a_{i,1}, \dots, a_{i,n})^T$. We search for a <u>linear</u> function f with $f: \mathbb{R}^n \to \mathbb{R}$, such that, $\underline{\forall i} \in \{1, \dots, m\} \underbrace{: f(\mathbf{a}_i) = x_0 + x_1 \cdot \underline{a}_{i,1} + \dots \times x_n \cdot \underline{a}_{i,n-1} = \langle \mathbf{a}_i^T, \mathbf{x} \rangle = \underline{b}_i}$ In other words, we search for x, such that $\mathbf{A} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} \begin{bmatrix} a_{1,1} \\ \ddots \\ x_1 \\ \vdots \\ 1 \end{bmatrix} \begin{bmatrix} a_{1,n-1} \\ \vdots \\ a_{n-1} \end{bmatrix}, \mathbf{x} = \begin{bmatrix} \mathbf{x}_0 \\ \vdots \\ x_{n-1} \end{bmatrix}, \mathbf{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix}$ with

$$\begin{array}{ccc}
\mathcal{C}(A) & & & & \\
\hline
P & & & \\
\hline$$

We want to solve the linear equation

$$\mathbf{A} \cdot \mathbf{x} = \mathbf{b} \tag{1}$$

where $\mathbf{A} \in \mathbb{R}^{m \times n}$, m > n (more rows than columns).

It is very likely that \mathbf{A}^{-1} does not exists and therefore, there is no solution, i.e., no \mathbf{x} satisfies the equation.

In general we search for

$$\underbrace{ \underset{\hat{\mathbf{x}} \in \mathbb{R}^n}{\operatorname{arg \, min}} \|\mathbf{A}\hat{\mathbf{x}} - \mathbf{b}\| = \|\mathbf{e}\|}_{\hat{\mathbf{x}} \in \mathbb{R}^n} \tag{2}$$

 $\|\mathbf{e}\|$ is the minimal Euclidean distance from \mathbf{b} to $C(\mathbf{A})$ (column space of \mathbf{A}). Therefore, $\mathbf{A}\hat{\mathbf{x}} = \mathbf{p}$ is the projection of \mathbf{b} onto $C(\mathbf{A})$.

Since $\mathbf{b} - \mathbf{A}\hat{\mathbf{x}} = \mathbf{e} \perp C(\mathbf{A})$, it follows that

$$\mathbf{A}^{T}\mathbf{p} = \mathbf{A}^{T}(\mathbf{b} - \mathbf{A}\hat{\mathbf{x}}) = \mathbf{0}$$
(3)

Therefore, we solve

$$\mathbf{A}^T \mathbf{A} \dot{\mathbf{x}} = \mathbf{A}^T \mathbf{b} \tag{4}$$

for which a solution exists!

$$\hat{\mathbf{x}} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{b} \tag{5}$$

We can also compute the projection matrix

$$\mathbf{P} = \mathbf{A}(\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \tag{6}$$