# CUDA Fortran for Material Science

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# **OUTLINE**

- Motivation
- Porting strategy

#### Motivation

- GPUs are very attractive in High Performance Computing:
  - Massive multithreaded many-core chips
  - High flops count (both SP and DP): ~5TF in DP for P100
  - High memory bandwidth, ECC: ~500 GB/s on P100
  - Programming languages: CUDA C, CUDA Fortran, OpenACC, Python, OpenCL, MATLAB
  - Tools: libraries (BLAS, FFT, LAPACK, RNG),

debuggers (Totalview, DDT), profilers (Nvidia Visual Profiler)

#### Motivation

- Several efforts (in the past and ongoing) to port material science codes to GPU (QE, VASP, Gaussian,...) using different approaches (CUDA C, OpenACC)
- In this workshop we will use Quantum Espresso to show how to port Fortran code to the GPU
- We will describe a new implementation of PW, all done in CUDA Fortran:

Modify source as little as possible

Single source code for CPU and GPU versions

This is going to be very hand on/interactive: few slides, a lot of example code!!!

# **PORTING STRATEGY**

## **Porting Strategy**

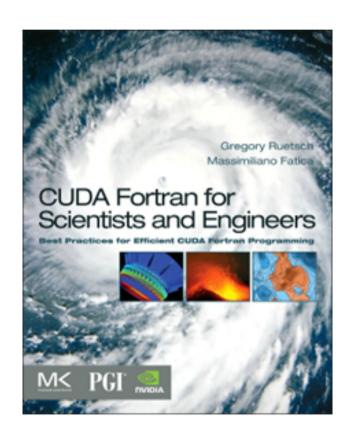
Since the code is in Fortran 90, natural choices are CUDA Fortran or OpenACC

#### Choice of CUDA Fortran motivated by:

- Personal preference
- Use of CUF kernels made effort comparable to OpenACC
- Explicit data movement is important to optimize CPU/GPU data transfers and network traffic
- Easier to work around compiler/library bugs
- ExplicitCUDA Fortran kernels when/if needed
- Nice interface for most of the CUDA libraries

#### **CUDA Fortran**

- CUDA is a scalable model for parallel computing
- CUDA Fortran is the Fortran analog to CUDA C
  - Program has host and device code similar to CUDA C
  - Host code is based on the runtime API
  - Fortran language extensions to simplify data management
- CUDA Fortran implemented in the PGI compiler
- Free Community edition (starting with 16.10)



# Kernel Loop Directives (CUF Kernels)

Automatic kernel generation and invocation of host code region (arrays used in loops must reside on GPU)

```
program incTest
   use cudafor
   implicit none
   integer, parameter :: n = 256
   integer :: a(n), b
   integer, device :: a_d(n)

a = 1; b = 3; a_d = a

!$cuf kernel do <<<*,*>>>
   do i = 1, n
        a_d(i) = a_d(i) + b
   enddo

a = a_d
   if (all(a == 4)) write(*,*) 'Test Passed'
end program incTest
```

# Kernel Loop Directives (CUF Kernels)

Multidimensional arrays

```
!$cuf kernel do(2) <<< *,* >>>
do j = 1, ny
   do i = 1, nx
       a_d(i,j) = b_d(i,j) + c_d(i,j)
   enddo
enddo
```

• Can specify parts of execution parameter

```
!$cuf kernel do(2) <<<(*,*),(32,4)>>>
```

• Compiler recognizes use of scalar reduction and generates one result

```
rsum = 0.0
!$cuf kernel do <<<*,*>>>
do i = 1, nx
  rsum = rsum + a_d(i)
enddo
```

#### **Details**

F2003 sourced allocation:

allocate(array\_b, source=array\_a)

- Allocates array\_b with the same bounds of array\_a
- Initializes array\_b with values of array\_a
- If array\_b is defined with the device attribute, allocation will be on the GPU and host-to-device data transfer occurs
- Variables renaming from modules:

```
#ifdef USE_CUDA
    use cudafor
    use local_arrays, only: vx => vx_d, vy => vy_d, vz => vz_d
#else
    use local_arrays, only: vx,vy,vz
#endif
```

Use attribute(device):

```
subroutine ExplicitTermsVX(qcap)
implicit none
real(fp_kind), dimension(1:nx,xstart(2):xend(2),xstart(3):xend(3)),intent(OUT) :: qcap
#ifdef USE_CUDA
attributes(device) :: vx,vy,vz,temp,qcap,udx3c
#endif
```

Use of generic interfaces:

```
Interface updateQuantity

module procedure updateQuantity_cpu

module procedure updateQuantity_gpu

end interface updateQuantity
```

## Code Example

```
subroutine CalcMaxCFL(cflm)
 use param, only: fp kind, nxm, dy, dz, udx3m
 use local arrays, only: vx,vy,vz
 use decomp 2d
 use mpih
 implicit none
 realintent(out) :: cflm
 integer :: j,k,jp,kp,i,ip
real :: qcf
 cflm=0.0000001d0
 !$OMP PARALLEL DO &
 !$OMP DEFAULT(none) &
 !$OMP SHARED(xstart,xend,nxm,vz,vy,vx) &
 | SHARED(dz,dy,udx3m) & | SHARED(dz,dy,udx3m) & | SHARED(dz,dy,udx3m) & | SOMP | PRIVATE(i,j,k,ip,jp,kp,qcf) & | SOMP | REDUCTION(max:cflm)
 do i=xstart(3),xend(3)
   ip=i+1
   do j=xstart(2),xend(2)
      jp=j+1
      do k=1,nxm
        kp=k+1
        qcf=( abs((vz(k,j,i)+vz(k,j,ip))*0.5d0*dz) & 
+abs((vy(k,j,i)+vy(k,jp,i))*0.5d0*dy) & 
+abs((vx(k,j,i)+vx(kp,j,i))*0.5d0*udx3m(k)))
        cflm = max(cflm,qcf)
      enddo
   enddo
 enddo
 !$OMP END PARALLEL DO
 call MpiAllMaxRealScalar(cflm)
 return
end
```

```
subroutine CalcMaxCFL(cflm)
#ifdef USE CUDA
 use cudafor
 use param, only: fp kind, nxm, dy \Rightarrow dy d, dz \Rightarrow dz d, udx3m \Rightarrow udx3m d
 use local arrays, only: vx => vx d, vy => vy d, vz => vz d
 use param, only: fp kind, nxm, dy, dz, udx3m
 use local arrays, only: vx,vy,vz
 use decomp_2d
 use mpih
 implicit none
 real(fp kind),intent(out) :: cflm
 integer :: j,k,jp,kp,i,ip
real(fp_kind) :: qcf
 cflm=real(0.0000001.fp kind)
#ifdef USE CUDA
 !$cuf kernel do(3) <<<*,*>>>
 !$OMP PARALLEL DO &
 !$OMP DEFAULT(none) &
 !$OMP SHARED(xstart,xend,nxm,vz,vy,vx) &
 | SHARED(dz,dy,udx3m) & | SHARED(dz,dy,udx3m) & | SHARED(dz,dy,udx3m) & | SOMP | PRIVATE(i,j,k,ip,jp,kp,qcf) & | SOMP | REDUCTION(max:cflm)
  do i=xstart(3),xend(3)
    ip=i+1
    do j=xstart(2),xend(2)
      jp=j+1
do k=1,nxm
        kp=k+1
        qcf=( abs((vz(k,j,i)+vz(k,j,ip)))*real(0.5,fp_kind)*dz) & 
+abs((vy(k,j,i)+vy(k,jp,i))*real(0.5,fp_kind)*dy) & 
+abs((vx(k,j,i)+vx(kp,j,i))*real(0.5,fp_kind)*udx3m(k)))
        cflm = max(cflm,qcf)
      enddo
    enddo
  enddo
!$OMP END PARALLEL DO
 call MpiAllMaxRealScalar(cflm)
return
end
```

# **Profiling**

Profiling is very important to understand bottlenecks and to spot opportunities for better interaction between the CPU and the GPU

For GPU codes, profiling information can be generated with Nvprof and visualized with Nvvp

For CPU+GPU codes, it is possible to annotate the profiling timelines using the NVIDIA Tools Extension (NVTX) library

NVTX from Fortran and CUDA Fortran:

https://devblogs.nvidia.com/parallelforall/customize-cuda-fortran-profiling-nvtx/

#### **TIMING**

#### Use CPU timers:

remember to add explicit synchronization barrier cudaDeviceSynchronize() without the barrier, the timer will measure the kernel launch time not the kernel execution time

#### Use CUDA events:

light-weight alternatives to CPU timers via the CUDA event API

call to create events, destroy events, record events and compute the elapsed time in milliseconds between two recorded events.

#### **NVTX Example**

! Create custom label for each marker

call nvtxStartRange("Label "//itcount,n)

write(itcount, '(i4)') n

call sleep(1)

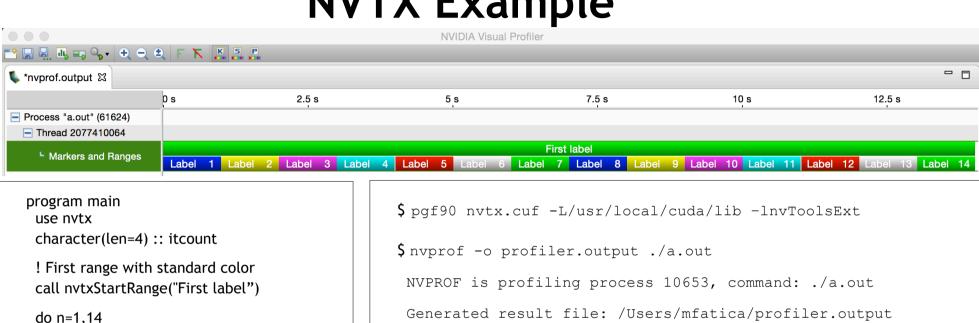
end do

call nvtxEndRange

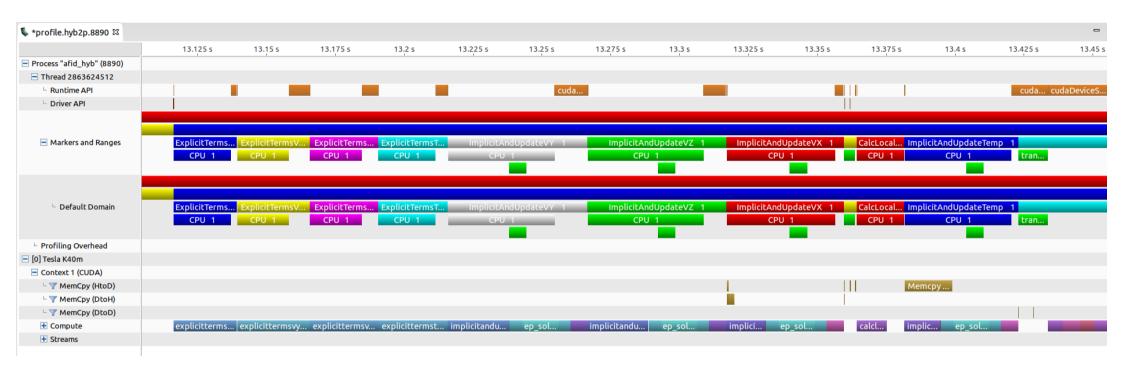
call nvtxEndRange end program main

! Range with custom color

! Add sleep to make markers big



# **NVVP** Example



Profiler output for the hybrid version