



Hybrid parallel programming

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Including adapted teaching material from books, lectures and presentations by B. Barney, B. Cumming, W. Gropp, G. Hager, M. Martinasso, R. Rabenseifner, O. Schenk, G. Wellein

Day 4, Thursday – Aug 3rd

- 1. Hybrid parallelism (8.00-9.00 hands on).
- 2. Hybridize some of the projects together (9.15-10.00).
- 3. Advanced topics (10.15-11.00).
- 4. Start to present results from the projects (11.10 11.50).
- 5. Exercise sheet related to the day's topic (11.50-12.00 hands on).

<u>Outline</u>

Hybrid parallelism in general

- Recap hardware & programming models
- Merging OpenMP & MPI
- "Hello World" in hybrid

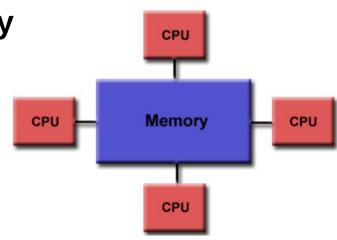
Putting things together:

- Time Iteration, Adaptive Sparse Grids, HPC

<u>Shared memory systems – OpenMP</u>

- Process can access same GLOBAL memory

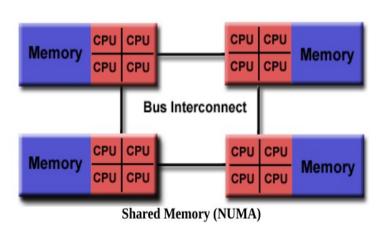
- Uniform Memory Access (UMA) model
 - Access time to memory is uniform.
 - Local cache, all other peripherals are shared.



Shared Memory (UMA)

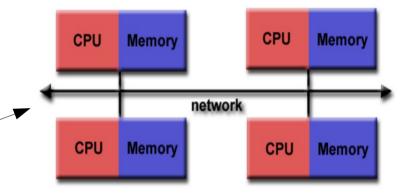
- Non-Uniform Memory Access (NUMA) model

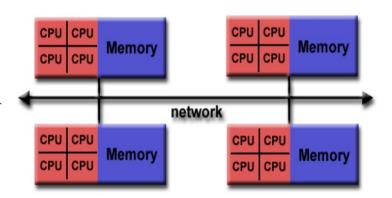
- Memory is physically distributed among processors.
- Global virtual address spaces accessible from all processors.
- Access time to local and remote data is different.
- → OpenMP, but other solutions available (e.g. Intel's TBB).



<u>Distributed-memory parallel</u> <u>programming – MPI</u>

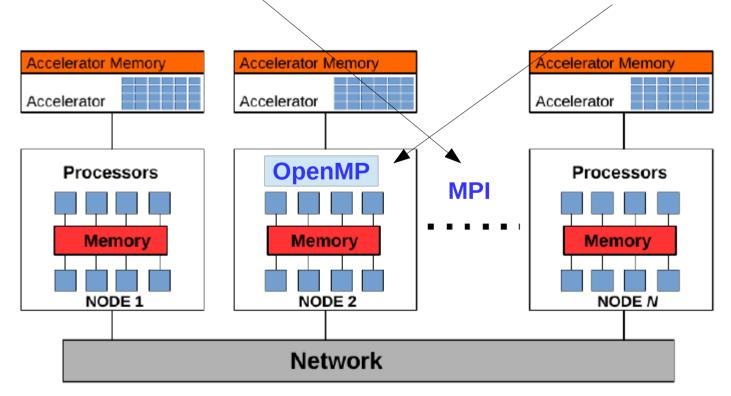
- We need to use explicit message passing, i.e., communication between processes:
 - → Most tedious and complicated but also the most flexible parallelization method.
- Message passing is required if a parallel computer is of distributed-memory type, i.e., if there is no way for one processor to directly access the address space of another.
- However, it can also be regarded
 as a programming model and used
 on shared-memory or hybrid systems as well.
- → Message Passing Interface (MPI).





Today's HPC systems

- Efficient programming of clusters of **shared memory (SMP) nodes**
- Hierarchical system layout
- Hybrid programming seems natural:
 - → MPI among the nodes. \
 - → Shared memory programming inside of each SMP node OpenMP.



Hybrid parallelism with MPI and OpenMP

When Does Hybridization Make Sense?

- When one wants to scale a shared memory OpenMP application for use on **multiple SMP nodes** in a cluster.
- When one wants to reduce an MPI application's sensitivity to becoming communication bound.
- When one is designing a parallel program (nowadays) from the very beginning.
- for 8/16/32/64/...ranks per multi-core node, this can have scaling problems with many nodes/MPI ranks.

Hybridization Using MPI and OpenMP

- facilitates cooperative shared memory (OpenMP) programming across clustered SMP nodes.
- MPI facilitates **communication** among SMP nodes.
- OpenMP manages the **workload** on each SMP node.
- MPI and OpenMP are used in tandem to manage the overall concurrency of the application.

The hybrid MPI & OpenMP model

The MPI only model assigns one process per core:

- → for 8/16/32/64/...ranks per multi-core node, this can have scaling problems with many nodes/MPI ranks.
- → the amount of data passed around in messages increases as number of ranks increases.
- → to take advantage of shared cache and DRAM on a socket, why not use threads on the socket/node, and pass messages between sockets/nodes? (it's a lot faster then sending messages around)

The hybrid MPI & OpenMP model has light-weight threads that share on-node memory.

Domain decomposition

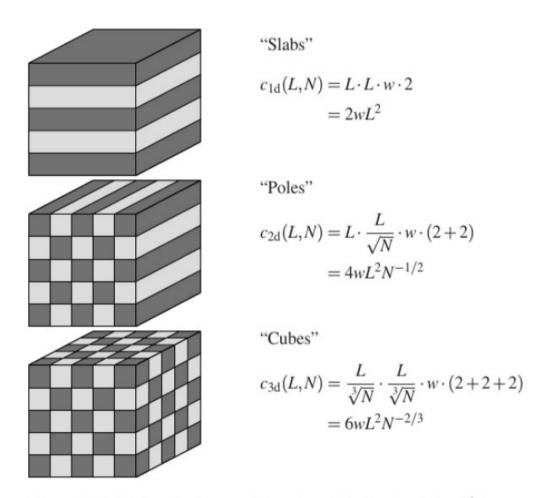


Figure 10.9: 3D domain decomposition of a cubic domain of size L^3 (strong scaling) and periodic boundary conditions: Per-process communication volume c(L,N) for a single-site data volume w (in bytes) on N processes when cutting in one (top), two (middle), or all three (bottom) dimensions.

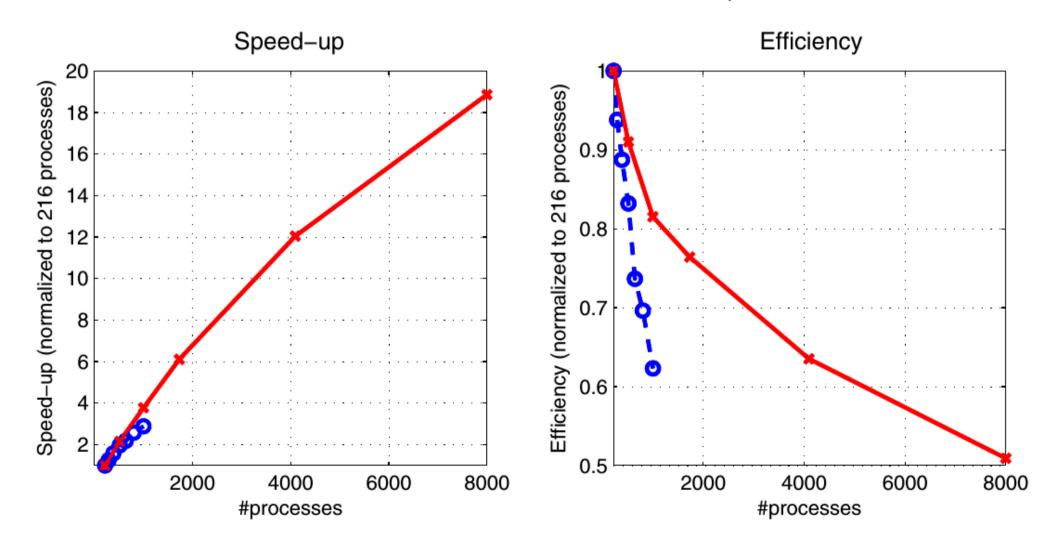
From Hager & Wellein (2011)

Example: Scaling "MPI" vs. "Hybrid"

See, e.g., Käppeli et al. (2011) http://iopscience.iop.org/article/10.1088/0067-0049/195/2/20/pdf

Hybrid parallelization:

- → Reduces the amount of memory consumption.
- → Reduces the amount of communication required.



Hybrid parallelism with MPI and OpenMP

Recall MPI

- Provides a familiar and explicit means to use message passing on distributed memory clusters.
- Has implementations on many architectures and topologies.
- Is the de-facto standard for distributed memory communications.
- Requires that program state synchronization must be handled explicitly due to the nature of distributed memory.
- data goes to the process.
- program correctness is an issue, but not big compared to those inherent to OpenMP.

OpenMP

- Allows for implicit intra-node communication, which is a shared memory paradigm.
- Provides for efficient utilization of shared memory SMP systems.
- Facilitates relatively easy threaded programming.
- Does not incur the overhead of message passing, since communication among threads is implicit.
- Is the de-facto standard, and is supported by most major compilers (Intel, IBM, gcc, etc).
- The process goes to the data program correctness is an issue since all threads can update shared memory locations.

The best from both worlds

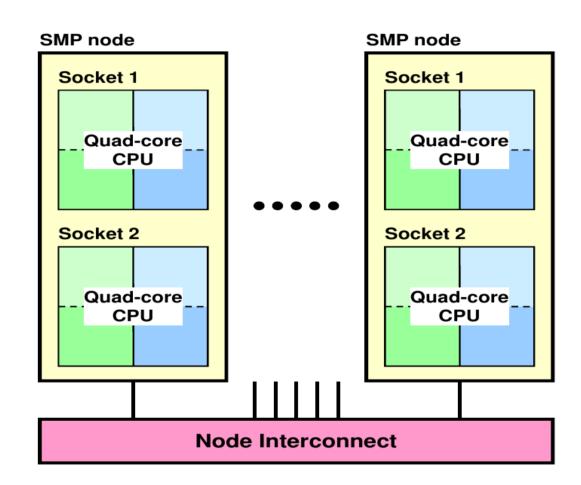
- MPI allows for inter-node communication.
- MPI facilitates efficient inter-node reductions and sending of complex data structures.
- Program synchronization is explicit.
- A common execution scenario: a single MPI process is launched on each SMP node in the cluster.
- Each process spawns *N* threads on each SMP node.
- At some global sync point, the master thread on each SMP communicate with one another.
- The threads belonging to each process continue until another sync point or completion.

Memory consumption & mapping

- Memory consumption MPI & OpenMP with n threads per MPI process:
 - → Duplicated data may be reduced by factor n.
- How many threads per MPI process?
 SMP node = with m sockets (NUMA domains) and n cores/socket
- How many threads (i.e., cores) per MPI process?
 - → Too few threads, too much memory consumption
- Optimum:
 - \rightarrow somewhere between 1 and m x n threads per MPI process.
- Typical optima:
 - → 1 MPI process per socket.
 - → 2 MPI processes per socket.
 - → Seldom: 1 MPI process per whole SMP node.

A node

- Which programming model is fastest?
- MPI everywhere?
- Fully hybridMPI & OpenMP?
- Something between?(Mixed model)



Mapping (2)

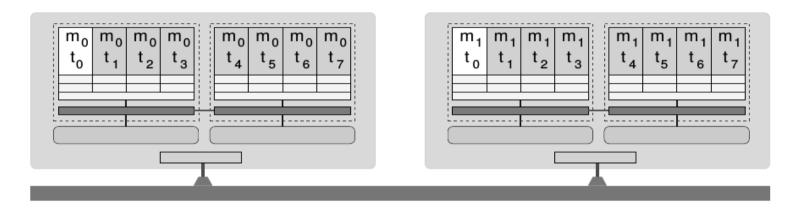


Figure 11.3: Mapping a single MPI process with eight threads to each node.

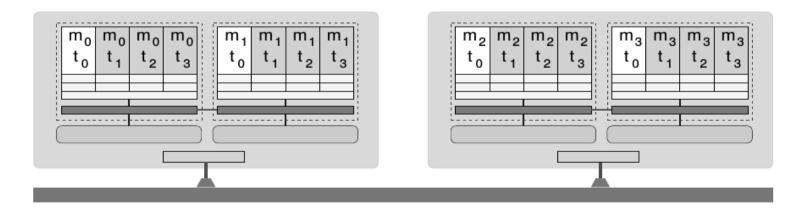


Figure 11.4: Mapping a single MPI process with four threads to each socket (L3 group or locality domain).

From Hager & Wellein (2011)

Mapping (3)

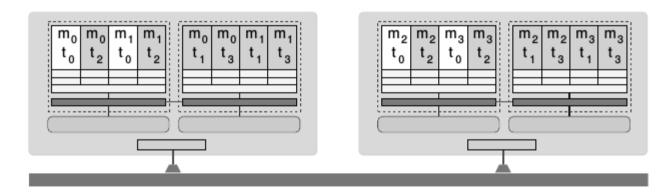


Figure 11.5: Mapping two MPI processes to each node and implementing a round-robin thread distribution.

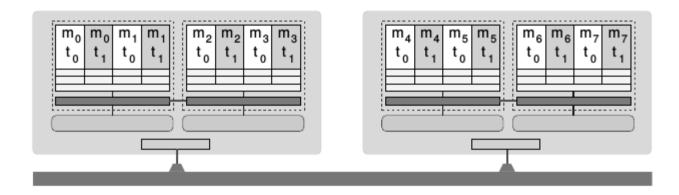


Figure 11.6: Mapping two MPI processes with two threads each to a single socket.

From Hager & Wellein (2011)

Opportunities

Algorithmic opportunities due to larger physical domains inside of each MPI process:

- → If MPI domain decomposition is based on physical zones: Nested Parallelism Outer loop with MPI / inner loop with OpenMP.
- → Load-Balancing: Using OpenMP dynamic and guided work sharing
- → Memory consumption: Significantly reduction of replicated data on MPI level.
- → Reduced MPI scaling problems: Significantly reduced number of MPI processes
- → Opportunities, if MPI speed-up is limited due to algorithmic problem
- → Significantly reduced number of MPI processes.

Basic MPI/OpenMP programming models

- The basic idea of a hybrid OpenMP/MPI programming model is to allow any MPI process to spawn a team of OpenMP threads in the same way as the master thread does in a pure OpenMP program.
- Inserting OpenMP compiler directives into an existing MPI code is a straightforward way to build a first hybrid parallel program.
- Following the guidelines of good OpenMP programming, compute intensive loop constructs are the primary targets for OpenMP parallelization in a naive hybrid code.
- Before launching the MPI processes one has to specify the maximum number of OpenMP threads per MPI process in the same way as for a pure OpenMP program.
- At execution time each MPI process activates a team of threads (being the master thread itself) whenever it encounters an OpenMP parallel region.
- There is no automatic synchronization between the MPI processes for switching from pure MPI to hybrid execution, i.e., at a given time some MPI processes may run in completely different OpenMP parallel regions, while other processes are in a pure MPI part of the program.
- Synchronization between MPI processes is still restricted to the use of appropriate MPI calls.

A common way to implement hybrid paralleism

Fortran C/C++

```
include 'mpif.h'
program hybsimp
call MPI Init(ierr)
call MPI Comm rank (...,irank,ierr)
call MPI Comm size (...,isize,ierr)
! Setup shared mem, comp. & Comm
!$OMP parallel do
  do i=1,n
    <work>
  enddo
! compute & communicate
call MPI Finalize(ierr)
end
```

```
#include <mpi.h>
int main(int argc, char **argv){
  int rank, size, ierr, i;

ierr= MPI_Init(&argc,&argv[]);
  ierr= MPI_Comm_rank (...,&rank);
  ierr= MPI_Comm_size (...,&size);

//Setup shared mem, compute & Comm

#pragma omp parallel for
  for(i=0; i<n; i++){
      <work>
    }

// compute & communicate

ierr= MPI_Finalize();
```

Example: "hello world hybrid"

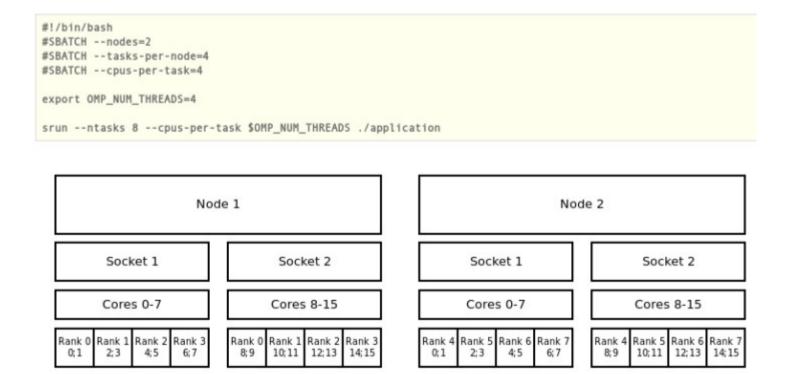
- 1. go to OSM_Lab/HPC_day4/code_day4/hybrid:
- > cd OSM_Lab/HPC_day4/code_day4/hybrid
- 2. Have a look at the code
- > vi 1a.hello_world_hybrid.cpp
- 3. compile by typing:
- > make
- 4. Experiment with different numbers of threads/MPI Processes
- > export OMP_NUM_THREADS=4
- > mpirun -np 2 ./1a.hello_world_hybrid.exec

Example

```
MPI
#include <stdio.h>
#include "mpi.h"
#include <omp.h>
int main(int argc, char *argv[]) {
 int numprocs, rank, namelen;
 int iam = \theta, np = 1;
                                                                    OpenMP
 mPI Init(&argc, &argv);
 MPI Comm size(MPI COMM WORLD, &numprocs);
 MPI Comm rank(MPI COMM WORLD, &rank):
  #pragma omp parallel default(shared) private(iam, np)
   omp get num threads();
    iam = omp get thread num();
    printf("Hello from thread %d out of %d from process %d out of %d\n"
           iam np. rank, numprocs);
 MPI Finalize();
```

Slurm with Hybrid Jobs

In the illustration below the default binding of a Hybrid-job is shown. In which 8 global ranks are distributed onto 2 nodes with 16 cores each. Each rank has 4 cores assigned to it.



Example 2: Slurm on Midway

- 1. go to OSM_Lab/HPC_day4/code_day4/hybrid:
- > cd OSM_Lab/HPC_day4/code_day4/hybrid
- 2. Have a look at the code
- > vi submit_hybrid_midway.sh
- 3. compile by typing:
- > make
- 4. Experiment with different numbers of nodes/threads/MPI Processes and look at the output.
- > sbatch submit_hybrid_midway.sh

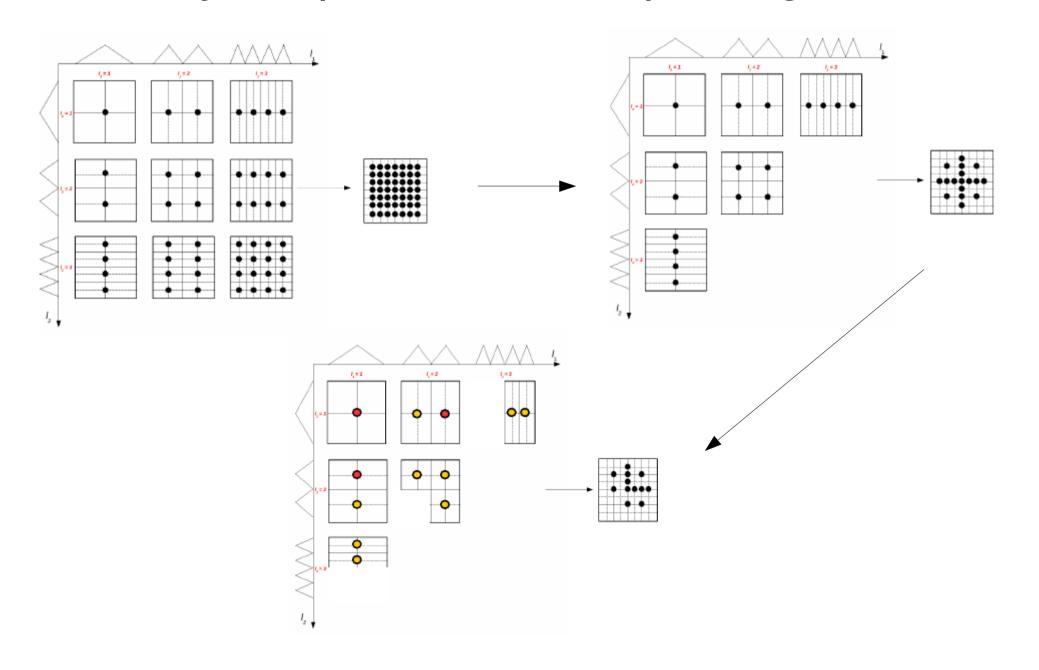
<u>Slurm – Hybrid</u>

```
#!/bin/bash
# a sample job submission script to submit a hybrid MPI/OpenMP job to the sandyb
# partition on Midway1 please change the --partition option if you want to use
# another partition on Midwayl
# set the job name to hello-hybrid
#SBATCH -- job-name=hello-hybrid
# send output to hello-hybrid.out
#SBATCH --output=hello-hybrid.out
# this job requests 4 MPI processes
#SBATCH --ntasks=4
# and request 8 cpus per task for OpenMP threads
#SBATCH --cpus-per-task=8
# this job will run in the sandyb partition on Midwayl
#SBATCH --partition=sandyb
# load the openmpi default module
module load openmpi
# set OMP NUM THREADS to the number of --cpus-per-task we asked for
export OMP NUM THREADS=$SLURM CPUS PER TASK
# Run the process with mpirun. Notice -n is not required. mpirun will
# automatically figure out how many processes to run from the slurm options
mpirun ./la.hello world hybrid.exec
```

Putting things together: Time Iteration, Adaptive Sparse Grids, HPC



Hybrid parallelism in Sparse grids



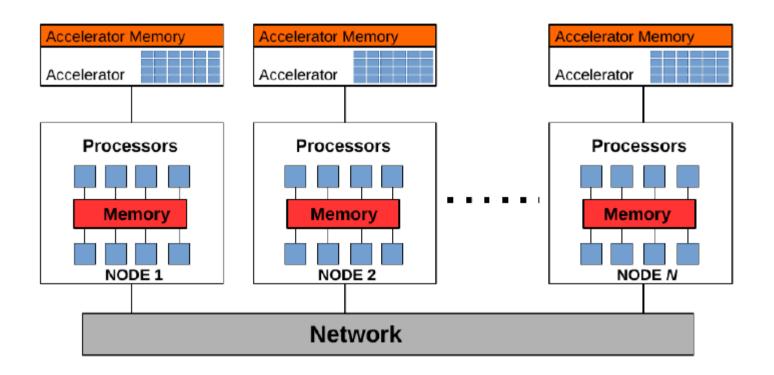
<u> Algorithm for time iteration & SG</u>

Scheidegger et al. (2017)

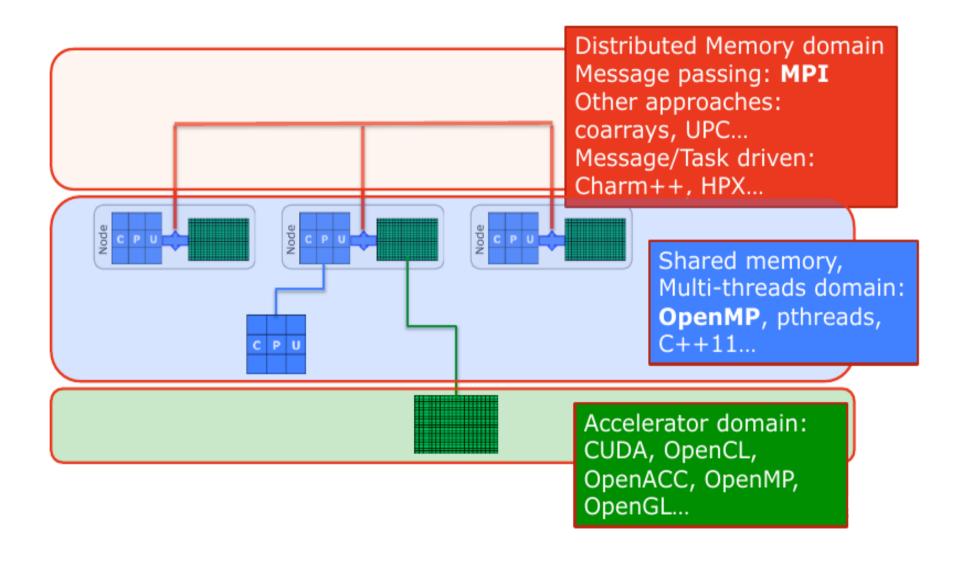
```
Data: Initial guess p_{next} = (p_{next}(1), \dots, p_{next}(N_s = 16)) for next period's policy function. Approximation accuracy \bar{\eta}. Maximal
        refinement level L_{max}. Starting refinement level L_0 \leq L_{max}. Refinement threshold \epsilon.
Result: The (approximate) equilibrium policy function p = (p(1), \dots, p(N_s = 16)).
while \eta > \bar{\eta} do
    Set z = 1.
    for z \leq N_s do
         Set l = 1, set G(z) \subset S(z) to be the level 1 grid on S(z), and set G_{old}(z) = \emptyset, G_{new}(z) = \emptyset.
         while G(z) \neq G_{old}(z) do
             for q(z) \in G(z) \setminus G_{old}(z) do
                  Compute the optimal policies p(q(z)) by evaluating (5) to (15) given next period's policy p_{next}.
                  Define the policy \tilde{p}(g((z))) by interpolating \{p(g(z))\}_{q(z) \in G_{old}(z)}.
                  if (l < L_{max} \text{ and } ||p(q(z)) - \tilde{p}(q(z))||_{\infty} > \epsilon) \text{ or } l < L_0, \text{ then }
                      Add the neighboring points (sons) of q(z) to G_{new}(z).
                  end
              end
              Set G_{old}(z) = G(z), set G = G_{old}(z) \cup G_{new}(z), set G_{new}(z) = \emptyset, and set l = l + 1.
         end
         Define the policy function p(z) as the sparse grid interpolation of \{p(g(z))\}_{g(z)\in G(z)}.
         Calculate (an approximation for) the error within a state:
         \eta(z) = ||p(z) - p_{next}(z)||. Set p_{next}(z) = p(z).
         set z = z + 1.
    end
    error: \eta = \max(\eta(1),...,\eta(N_s))
end
```

Algorithm 1: Overview of the crucial steps of the time iteration algorithm.

Recall – Today's HPC systems



Overall picture of programming models



Parallel time iteration/DP algorithm

-Our implementation:

Hybrid parallel

(MPI & Intel TBB & GPU (CUDA/THRUST)).

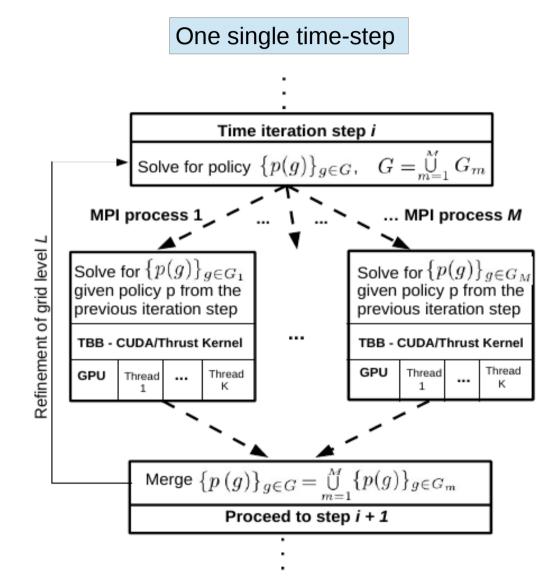
-newly generated points are distributed via MPI

Solve optimizations/ nonlinear equations locally (e.g. IPOPT (Waechter & Biegler (2006)).

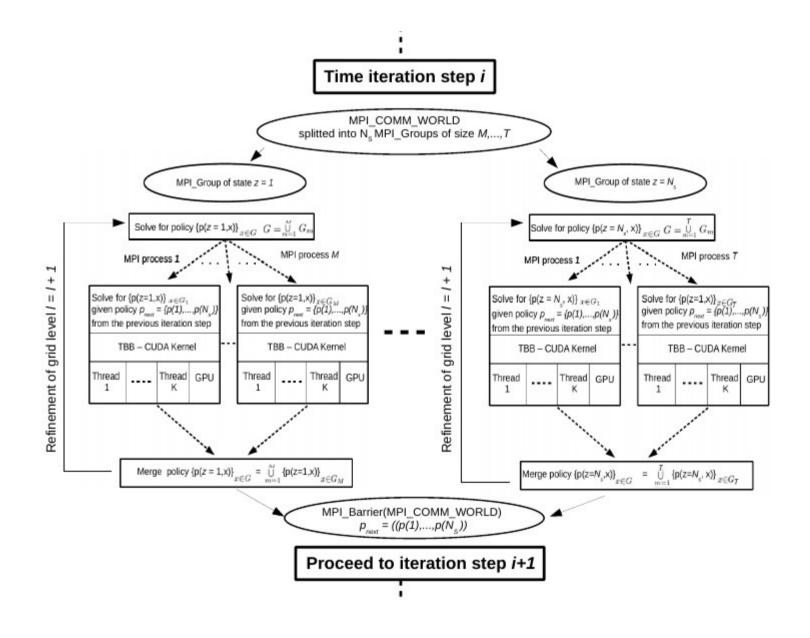
In parallel: `messy'!

- → policy from previous iteration visible on all MPI processes.
- → we have to ensure some sort of `load balancing'.
- → Now a lot better with TBB

Brumm et al. (2015), Brumm & Scheidegger (2017)

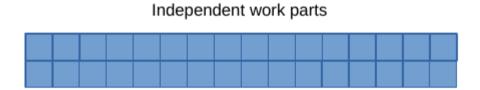


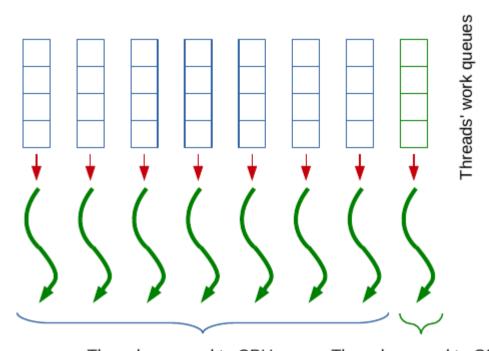
With discrete states



Intel® Threading Building Blocks (TBB)

-TBB maps different threads, similar to OpenMP.

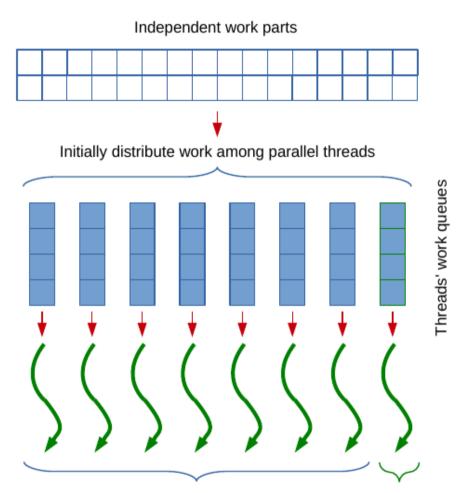




Threads mapped to CPU cores Thread mapped to GPU

Intel® Threading Building Blocks (TBB)

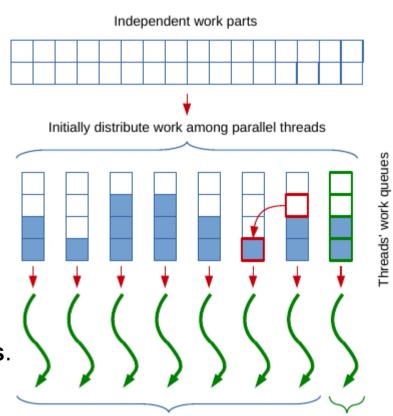
- -TBB maps different threads, similar to OpenMP.
- -Every thread is initially assigned an equal logical queue of tasks.



Threads mapped to CPU cores Thread mapped to GPU

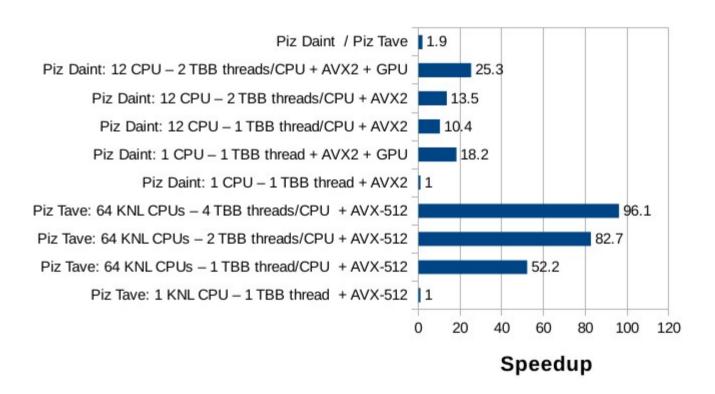
Intel® Threading Building Blocks (TBB)

- -TBB maps different threads, similar to OpenMP.
- -Every thread is initially assigned an equal logical queue of tasks.
- -However, different tasks may be processed faster or slower, due to differences between tasks and/or compute cores
- -TBB approach to work balancing: once one thread runs out of tasks, "steal" a task from another thread, which makes slower progress.
- -We map one extra thread onto GPU
- → CPU cores and GPU process interpolation tasks together.



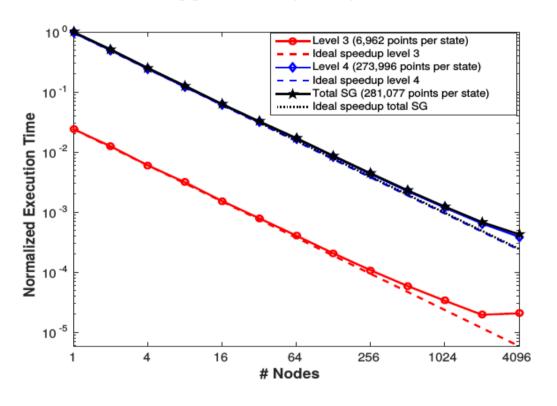
Threads mapped to CPU cores Thread mapped to GPU

<u>Strong scaling – 1 node</u>



<u>Strong scaling – intra-node</u>

Scheidegger et al. (2017)



- Annually calibrated
 OLG model.
- 16 discrete states

 (stochastic tax rates on labor and capital).
- solve this model in few hours.

Figure 6: Strong scaling on Piz Daint for an OLG model using 4 levels of grid refinements, 16 discrete states, and $16 \cdot 281,077 = 4,497,232$ points and 265,336,688 unknowns in total. "Total SG" shows the entire, normalized simulation time up to 4,096 nodes. We also show normalized execution times for the computational sub-components on different levels, e.g., for level 3 using 6.962 points. Dashed and dotted lines show the ideal speedup.

Time to soluton

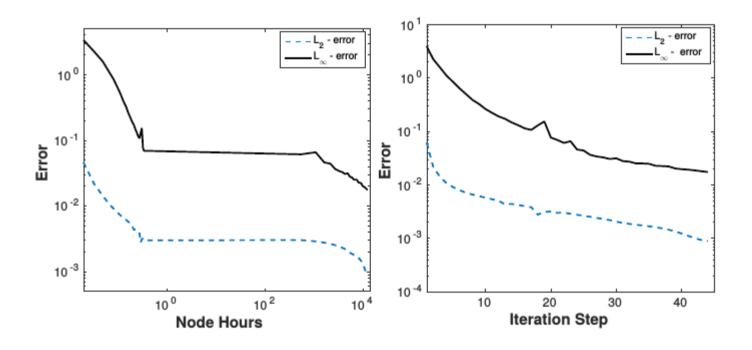


Figure 7: Comparison of the L_2 and L_{∞} -error for adaptive sparse grid solutions of the 59-dimensional OLG model as a function of compute time or iterations spent on Piz Daint.

Questions?

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