Supplementary Material: Asynchronous Stochastic Gradient Descent with Delay Compensation

A. Theorem 3.1 and Its Proof

Theorem 3.1:

Assume the loss function is L_1-Lipschitz. If $\lambda \in [0,1]$ make the following inequality holds,

$$\sum_{k=1}^{K} \frac{1}{\sigma_k^3(x, \boldsymbol{w}_t)} \geq 2\left[C_{ij}\left(\sum_{k=1}^{K}\frac{1}{\sigma_k(x,\boldsymbol{w}_t)}\right)^2 + C_{ij}' L_1^2 |\epsilon_t| \right], \tag{1}$$

where $C_{ij} = \frac{1}{1+\lambda}\left(\frac{u_i u_j \beta}{l_i l_j \sqrt{\alpha}}\right)^2$, $C_{ij}' = \frac{1}{(1+\lambda)\alpha(l_i l_j)^2}$, and the model converges to the optimal model, then the MSE of $\lambda G(\boldsymbol{w}_t)$ is smaller than the MSE of $G(\boldsymbol{w}_t)$ in approximating Hessian $H(\boldsymbol{w}_t)$.

Proof:

For simplicity, we abbreviate $\mathbb{E}_{(Y|x,w^*)}$ as $\mathbb{E}$, G_t as $G(\mathbf{w}_t)$ and H_t as $H(\mathbf{w}_t)$. First, we calculate the MSE of G_t, λG_t to approximate H_t for each element of G_t. We denote the element in the i-th row and j-th column of $G(w_t)$ as G_{ij}^t and $H(w_t)$ as $H_{ij}(t)$.

The MSE of G_{ij}^t:

$$\mathbb{E}(G_{ij}^t - \mathbb{E}H_{ij}^t)^2 = \mathbb{E}(G_{ij}^t - \mathbb{E}G_{ij}^t)^2 + (\mathbb{E}H_{ij}^t - \mathbb{E}G_{ij}^t)^2 = \mathbb{E}(G_{ij}^t)^2 - (\mathbb{E}G_{ij}^t)^2 + \epsilon_t^2 \tag{2}$$

The MSE of λg_{ij}:

$$\begin{aligned}
\mathbb{E}(\lambda G_{ij}^t - \mathbb{E}H_{ij}^t)^2 &= \lambda^2 \mathbb{E}(G_{ij}^t - \mathbb{E}G_{ij}^t)^2 + (\mathbb{E}H_{ij}^t - \lambda\mathbb{E}G_{ij}^t)^2 \\
&= \lambda^2 \mathbb{E}(G_{ij}^t)^2 - \lambda^2(\mathbb{E}G_{ij}^t)^2 + (1-\lambda)^2(\mathbb{E}G_{ij}^t)^2 + \epsilon_t^2 + 2(\lambda-1)\mathbb{E}G_{ij}^t \epsilon_t
\end{aligned} \tag{3}$$

The condition for $\mathbb{E}(G_{ij}^t - \mathbb{E}H_{ij}^t)^2 \geq \mathbb{E}(\lambda G_{ij}^t - \mathbb{E}H_{ij}^t)^2$ is

$$(1-\lambda^2)(\mathbb{E}(G_{ij}^t)^2 - (\mathbb{E}G_{ij}^t)^2) \geq 2(1-\lambda)(\mathbb{E}G_{ij}^t)^2 + 2(\lambda-1)\mathbb{E}G_{ij}^t \epsilon_t \tag{4}$$

Inequality (4) is equivalent to

$$(1+\lambda)\mathbb{E}(G_{ij}^t)^2 \geq 2[(\mathbb{E}G_{ij}^t)^2 - \mathbb{E}G_{ij}^t \epsilon_t] \tag{5}$$

Next we calculate $\mathbb{E}(G_{ij}^t)^2$, and $(\mathbb{E}G_{ij}^t)^2$ which appear in Eqn.(5). For simplicity, we denote $\sigma_k(x, \mathbf{w}_t)$ as σ_k, and $I_{[Y=k]}$

as z_k. Then we can get:

$$\mathbb{E}(g_{ij})^2 = \mathbb{E}_{(Y|x,\mathbf{w}_t)}\left(\frac{\partial}{\partial w_i}\log P(Y|x,\mathbf{w}_t)\right)^2\left(\frac{\partial}{\partial w_j}\log P(Y|x,\mathbf{w}_t)\right)^2 \tag{6}$$

$$\geq \mathbb{E}_{(Y|x,\mathbf{w}^*)}\left(\sum_{k=1}^{K}\left(-\frac{z_k}{\sigma_k}\right)\right)^4 (l_i l_j)^2$$

$$= \alpha\,(l_i l_j)^2\left(\sum_{k=1}^{K}\frac{1}{\sigma_k^3(x,\mathbf{w}_t)}\right) \tag{7}$$

$$(\mathbb{E}h_{ij})^2 = \left(\mathbb{E}_{(Y|x,\mathbf{w}^*)}\sum_{k=1}^{K}\frac{\partial\sigma_k}{\partial w_i}\left(-\frac{z_k}{\sigma_k}\right)\cdot\sum_{k=1}^{K}\frac{\partial\sigma_k}{\partial w_j}\left(-\frac{z_k}{\sigma_k}\right)\right)^2$$

$$\leq \beta^2\,(u_i u_j)^2\left(\sum_{k=1}^{K}\frac{1}{\sigma_k(x,\mathbf{w}_t)}\right)^2. \tag{8}$$

By substituting Ineq.(7) and Ineq.(8) into Ineq.(5), a sufficient condition for Ineq.(5) to be satisfied is $\sum_{k=1}^{K}\frac{1}{\sigma_k^3(x,\mathbf{w}_t)} \geq 2\left[C_{ij}\left(\sum_{k=1}^{K}\frac{1}{\sigma_k(x,\mathbf{w}_t)}\right)^2 + C_{ij}'L_1^2|\epsilon_t|\right]$ because $G_{ij}^t \leq L_1^2$. $\square$

B. Corollary 3.2 and Its Proof

Corollary 3.2: *A sufficient condition for inequality (1) is $\lambda \in [0,1]$ and $\exists k_0 \in [K]$ such that $\sigma_{k_0} \in \left[1 - \frac{K-1}{2(C_{ij}K^2 + C_{ij}'L_1^2\epsilon_t)}, 1\right]$.*

Proof:
Denote $\Delta = \frac{K-1}{2C_{ij}K^2}$ and $F(\sigma_1,...,\sigma_K) = \sum_{k=1}^{K}\frac{1}{\sigma_k^3(x,\mathbf{w}_t)} - 2C_{ij}\left(\sum_{k=1}^{K}\frac{1}{\sigma_k(x,\mathbf{w}_t)}\right)^2 - 2C_{ij}'L_1^2|\epsilon_t|$. If $\exists k_1 \in [K]$ such that $\sigma_{k_1} \in [1-\Delta, 1]$, we have for $k \neq k_1$ $\sigma_k \in [0,\Delta]$. Therefore

$$F(\sigma_1,...,\sigma_K) \geq \frac{1}{(\sigma_{k_1})^3} + \frac{K-1}{\Delta^3} - 2C_{ij}\left(\frac{1}{\sigma_{k_1}} + \frac{K-1}{\Delta}\right)^2 - 2C_{ij}'L_1^2|\epsilon_t| \tag{9}$$

$$\geq \frac{K-1}{\Delta^3} - 2C_{ij}\left(\left(\frac{K-1}{\Delta}\right)^2 + \frac{1}{\sigma_{k_1}^2} + \frac{2(K-1)}{\sigma_{k_1}\Delta}\right) - 2C_{ij}'L_1^2|\epsilon_t| \tag{10}$$

$$\geq \frac{K-1}{\Delta^3} - 2C_{ij}\left(\frac{(K-1)^2}{\Delta^2} + \frac{2K-1}{\sigma_{k_1}\Delta}\right) - 2C_{ij}'L_1^2|\epsilon_t| \tag{11}$$

$$= \frac{1}{\Delta}\left(\frac{K-1}{\Delta^2} - 2C_{ij}\left(\frac{(K-1)^2}{\Delta} + \frac{2K-1}{\sigma_{k_1}}\right)\right) - 2C_{ij}'L_1^2|\epsilon_t| \tag{12}$$

$$\geq \frac{1}{\Delta}\left(\frac{K-1}{\Delta^2} - 2C_{ij}\left(\frac{(K-1)^2 + 2K-1}{\Delta}\right)\right) - 2C_{ij}'L_1^2|\epsilon_t| \tag{13}$$

$$\geq \frac{1}{\Delta^2}\left(\frac{K-1}{\Delta} - 2C_{ij}K^2 - 2C_{ij}'L_1^2|\epsilon_t|\right) \tag{14}$$

$$= 0 \tag{15}$$

where Ineq.(11) and (13) is established since $\sigma_{k_1} > \Delta$; and Eqn.(15) is established by putting $\Delta = \frac{K-1}{2(C_{ij}K^2 + C_{ij}'L_1^2|\epsilon_t|)}$ in Eqn.(14). $\square$

C. Uniform upper bound of MSE

Lemma C.1 *Assume the loss function is L_1-Lipschitz, and the diagonalization error of Hessian is upper bounded by ϵ_D, i.e., $\|Diag(H(\boldsymbol{w}_t)) - H(\boldsymbol{w}_t)\| \le \epsilon_D$, [1] then we have, for $\forall t$,*

$$mse^t(Diag(\lambda G)) \le 4\lambda^2 V_1 + 4(1-\lambda)^2 L_1^4 + 4\epsilon_t^2 + 4\epsilon_D, \tag{16}$$

where V_1 is the upper bound of the variance of $G(\boldsymbol{w}_t)$.

Proof:

$$mse^t(Diag(\lambda G)) \tag{17}$$

$$\le \mathbb{E}\|Diag(\lambda G(w_t)) - H(w_t)\|^2 \tag{18}$$

$$\le 4\mathbb{E}\|Diag(\lambda G(w_t)) - \mathbb{E}(Diag(\lambda G(w_t)))\|^2 + 4\|\mathbb{E}(Diag(\lambda G(w_t))) - \mathbb{E}(Diag(G(w_t)))\|^2 \tag{19}$$

$$+ 4\|\mathbb{E}(Diag(G(w_t))) - \mathbb{E}(Diag(H(w_t)))\|^2 + 4\|\mathbb{E}(Diag(H(w_t))) - \mathbb{E}H(w_t)\|^2 \tag{20}$$

$$\le 4\lambda^2 V_1 + 4(1-\lambda)^2 L_1^4 + 4\epsilon_t^2 + 4\epsilon_D \tag{21}$$

D. Convergence Rate for DC-ASGD: Convex Case

DC-ASGD is a general method to compensate delay in ASGD. We first show the convergence rate for convex loss function. If the loss function $f(w)$ is convex about w, we can add a regularization term $\frac{\rho}{2}\|w\|^2$ to make the objective function $F(w) + \frac{\rho}{2}\|w\|^2$ strongly convex. Thus, we assume that the objective function is μ-strongly convex.

Theorem 4.1: (Strongly Convex) *If $f(w)$ is L_2-smooth and μ-strongly convex about w, $\nabla f(w)$ is L_3-smooth about w and the expectation of the $\|\cdot\|_2^2$ norm of the delay compensated gradient is upper bounded by a constant G. By setting the learning rate $\eta_t = \frac{1}{\mu t}$, DC-ASGD has convergence rate as*

$$\mathbb{E}F(w_t) - F(w^*) \le \frac{2L_2^2 G^2}{t\mu^4}\left(1 + 4\tau C_\lambda\right) + \frac{2G^2 L_2^2 \theta \sqrt{\tau}}{\mu^4 t \sqrt{t}} + \frac{L^3 L_2^3 \tau^2 G^3}{\mu^6 t^2},$$

where $\theta = \frac{2HKLG}{\mu}\sqrt{\frac{L_2}{\mu}\left(1 + \frac{\tau G L_3}{\mu L_2}\right)}$ and $C_\lambda = (1-\lambda)L_1^2 + \epsilon_D$, and the expectation is taking with respect to the random sampling of DC-ASGD and $\mathbb{E}_{(y|x,w^*)}$.

Proof:

We denote $g^{dc}(w_t) = g(w_t) + \lambda g(w_t) \odot g(w_t) \odot (w_{t+\tau} - w_t)$, $g^h(w_t) = g(w_t) + H_{i_t}(w_t)(w_{t+\tau} - w_t)$ and $\nabla F^h(w_t) = \nabla F(w_t) + \mathbb{E}_{i_t} H_{i_t}(w_t)(w_{t+\tau} - w_t)$. Obviously, we have $\mathbb{E}g^h(w_t) = \nabla F^h(w_t)$. By the smoothness condition, we have

$$\mathbb{E}F(w_{t+\tau+1}) - F(w^*) \tag{22}$$

$$\le F(w_{t+\tau}) - F(w^*) - \langle \nabla F(w_{t+\tau}), w_{t+\tau+1} - w_{t+\tau}\rangle + \frac{L_2}{2}\|w_{t+\tau+1} - w_{t+\tau}\|^2 \tag{23}$$

$$\le F(w_{t+\tau}) - F(w^*) - \eta_{t+\tau}\langle \nabla F(w_{t+\tau}), g^{dc}(w_t)\rangle + \frac{L_2 \eta_{t+\tau}^2 G^2}{2} \tag{24}$$

$$= F(w_{t+\tau}) - F(w^*) - \eta_{t+\tau}\langle \nabla F(w_{t+\tau}), \nabla F(w_{t+\tau})\rangle + \eta_{t+\tau}\langle \nabla F(w_{t+\tau}), \nabla F(w_{t+\tau}) - \nabla F^h(w_t)\rangle \tag{25}$$

$$+ \eta_{t+\tau}\langle \nabla F(w_{t+\tau}), \mathbb{E}g^h(w_t) - g^{dc}(w_t)\rangle + \frac{L_2 \eta_{t+\tau}^2 G^2}{2} \tag{26}$$

Since $f(w)$ is L_2-smooth and μ strongly convex, we have

$$-\langle \nabla F(w_{t+\tau}), \nabla F(w_{t+\tau})\rangle \le -\mu^2\|w_{t+\tau} - w^*\|^2 \le -\frac{2\mu^2}{L_2}(F(w_{t+\tau}) - F(w^*)). \tag{27}$$

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[1] (LeCun, 1987) demonstrated that the diagonal approximation to Hessian for neural networks is an efficient method with no much drop on accuracy

For the term $\eta_{t+\tau}\langle \nabla F(w_{t+\tau}), \nabla F(w_{t+\tau}) - \nabla F^h(w_t)\rangle$, we have

$$\eta_{t+\tau}\langle \nabla F(w_{t+\tau}), \nabla F(w_{t+\tau}) - \nabla F^h(w_t)\rangle \tag{28}$$

$$\leq \eta_{t+\tau}\|\nabla F(w_{t+\tau})\|\|\nabla F(w_{t+\tau}) - \nabla F^h(w_t)\| \tag{29}$$

$$\leq \eta_{t+\tau}G\|\nabla F(w_{t+\tau}) - \nabla F^h(w_t)\| \tag{30}$$

By the smoothness condition for $\nabla F(w)$, we have

$$\|\nabla F(w_{t+\tau}) - \nabla F^h(w_t)\| \leq \frac{L_3}{2}\|w_{t+\tau} - w_t\|^2 \leq \frac{L_3\tau G^2}{2}\sum_{j=0}^{\tau-1}\eta_{t+j}^2 \tag{31}$$

Let $\eta_t = \frac{L_2}{\mu^2 t}$, we can get $\sum_{j=1}^{\tau}\eta_{t+j}^2 \leq \frac{L_2^2}{\mu^4}\cdot\frac{\tau}{t(t+\tau)} \leq \frac{2L_2^2\tau}{\mu^4(t+\tau)^2}$.

For the term $\eta_{t+\tau}\langle \nabla F(w_{t+\tau}), \mathbb{E}g^h(w_t) - g^{dc}(w_t)\rangle$, we have

$$\langle \nabla F(w_{t+\tau}), \mathbb{E}(g^h(w_t) - g^{dc}(w_t))\rangle \tag{32}$$

$$\leq \|\nabla F(w_{t+\tau})\|\|\mathbb{E}(\lambda g(w_t)\odot g(w_t) - H(w_t))(w_{t+\tau} - w_t)\| \tag{33}$$

$$\leq G^2\tau\sum_{j=0}^{\tau-1}\eta_{t+j}(\|\mathbb{E}(\lambda g(w_t)\odot g(w_t) - g(w_t)\odot g(w_t)\| + \|g(w_t)\odot g(w_t) - Diag(H(w_t))\| + \|Diag(H(w_t)) - H(w_t)\|) \tag{34}$$

$$\leq \frac{2G^2L_2\tau}{(t+\tau)\mu^2}(C_\lambda + \epsilon_t), \tag{35}$$

where $C_\lambda = (1-\lambda)L_1^2 + \epsilon_D$.

Using Lemma F.1, $\epsilon_t \leq \theta\sqrt{\frac{1}{t}} \leq \theta\sqrt{\frac{\tau}{t+\tau}}$. Putting inequality 27 and 31 in inequality 26, we have

$$\mathbb{E}F(w_{t+\tau+1}) - F(w^*) \leq \left(1 - \frac{2}{t+\tau}\right)(\mathbb{E}F(w_t) - F(w^*)) + \frac{L_3L_2^3\tau^2G^3}{\mu^6(t+\tau)^3} \tag{36}$$

$$+ \frac{2G^2L_2^2\tau}{\mu^4(t+\tau)^2}\left(C_\lambda + \theta\sqrt{\frac{\tau}{t+\tau}}\right) + \frac{L_2^2G^2}{2(t+\tau)^2\mu^4} \tag{37}$$

We can get

$$\mathbb{E}F(w_t) - F(w^*) \leq \frac{2L_2^2G^2}{t\mu^4}(1 + 4\tau C_\lambda) + \frac{2G^2L_2^2\theta\sqrt{\tau}}{\mu^4 t\sqrt{t}} + \frac{L^3L_2^3\tau^2G^3}{\mu^6 t^2}. \tag{38}$$

by induction. □

Discussion:

(1). Following the above proof steps and using $\|\nabla F(w_{t+\tau}) - \nabla F(w_t)\| \leq L_2\|w_{t+\tau} - w_t\|$, we can get the convergence rate of ASGD is

$$\mathbb{E}F(w_t) - F(w^*) \leq \frac{2L_2^2G^2}{t\mu^4}(1 + 4\tau L_2). \tag{39}$$

Compared the convergence rate of DC-ASGD with ASGD, the extra term $\frac{2G^2L_2^2\theta\sqrt{\tau}}{\mu^4 t\sqrt{t}} + \frac{L^3L_2^3\tau^2G^3}{\mu^6 t^2}$ converge to zero faster than $\frac{2L_2^2G^2}{t\mu^4}(1 + 4\tau C_\lambda)$ in terms of the order of t. Thus, when t is large, the extra term has smaller value. We assume that t is large and the term can be neglected. Then the condition for DC-ASGD outperforming ASGD is $L_2 > C_\lambda$.

E. Convergence Rate for DC-ASGD: Nonconvex Case

Theorem 5.1: (Nonconvex Case) *Assume that Assumptions 1-4 hold. Set the learning rate*

$$\eta_t = \sqrt{\frac{2(F(w_1) - F(w^*))}{bTV^2L_2}}, \tag{40}$$

where b is the mini-batch size, and V is the upper bound of the variance of the delay-compensated gradient. If $T \geq \max\{\mathcal{O}(1/r^4), 2D_0 b L_2/V^2\}$ and delay τ is upper-bounded as below,

$$\tau \leq \min\left\{\frac{L_2 V}{C_\lambda}\sqrt{\frac{L_2 T}{2D_0 b}}, \frac{V}{C_\lambda}\sqrt{\frac{L_2 T}{2D_0 b}}, \frac{TV}{\tilde{C}}\sqrt{\frac{L_2}{bD_0}}, \frac{VL_2 T}{4\tilde{C}}\sqrt{\frac{TL_2}{2D_0 b}}\right\}. \tag{41}$$

then DC-ASGD has the following ergodic convergence rate,

$$\min_{t=\{1,\cdots,T\}}\mathbb{E}(\|\nabla F(\boldsymbol{w}_t)\|^2) \leq V\sqrt{\frac{2D_0 L_2}{bT}}, \tag{42}$$

where the expectation is taken with respect to the random sampling in SGD and the data distribution $P(Y|x, \boldsymbol{w}^*)$.

Proof:

We denote $g_m(w_t) + \lambda g_m(w_t) \odot g_m(w_t) \odot (w_{t+\tau} - w_t)$ as $g_m^{dc}(w_t)$ where $m \in \{1, \cdots, b\}$ is the index of instances in the minibatch. From the proof the Theorem 1 in ASGD (Lian et al., 2015), we can get

$$\mathbb{E}F(w_{t+\tau+1}) - F(w_{t+\tau}) \tag{43}$$

$$\leq \langle\nabla F(w_{t+\tau}), w_{t+\tau} - w_t\rangle + \frac{L_2}{2}\|w_{t+\tau+1} - w_{t+\tau}\|^2 \tag{44}$$

$$\leq -\eta_{t+\tau}\langle\nabla F(w_{t+\tau}), \sum_{m=1}^{b}\mathbb{E}g_m^{dc}(w_t)\rangle + \frac{\eta_{t+\tau}^2 L_2}{2}\mathbb{E}\left(\left\|\sum_{m=1}^{b}g_m^{dc}(w_t)\right\|^2\right) \tag{45}$$

$$\leq -\frac{b\eta_{t+\tau}}{2}\left(\|\nabla F(w_{t+\tau})\|^2 + \left\|\sum_{m=1}^{b}\mathbb{E}g_m^{dc}(w_t)\right\|^2 - \left\|\nabla F(w_{t+\tau}) - \sum_{m=1}^{b}\mathbb{E}g_m^{dc}(w_t)\right\|^2\right)$$

$$+ \frac{\eta_{t+\tau}^2 L_2}{2}\mathbb{E}\left(\left\|\sum_{m=1}^{b}g_m^{dc}(w_t)\right\|^2\right) \tag{46}$$

For the term $T_1 = \left\|\nabla F(w_{t+\tau}) - \sum_{m=1}^{b}\mathbb{E}g_m^{dc}(w_t)\right\|^2$, by using the smooth condition of g, we have

$$T_1 = \left\|\nabla F(w_{t+\tau}) - \sum_{m=1}^{b}\mathbb{E}g_m^{dc}(w_t)\right\|^2 \tag{47}$$

$$\leq \left\|\nabla F(w_{t+\tau}) - \nabla F^h(w_t) + \nabla F^h(w_t) - \sum_{m=1}^{b}\mathbb{E}g_m^{dc}(w_t)\right\|^2 \tag{48}$$

$$\leq 2\left\|\frac{L_3}{2}\|w_{t+\tau} - w_t\|^2\right\|^2 + 2\left\|\nabla F^h(w_t) - \sum_{m=1}^{b}\mathbb{E}g_m^{dc}(w_t)\right\|^2 \tag{49}$$

$$\leq (L_3^2\pi^2/2 + 2(((1-\lambda)L_1^2 + \epsilon_D)^2 + \epsilon_t^2))\|w_{t+\tau} - w_t\|^2 \tag{50}$$

Thus by following the proof of ASGD, we have

$$\mathbb{E}(T_1) \leq 4(L_3^2\pi^2/4 + ((1-\lambda)L_1^2 + \epsilon_D)^2 + \epsilon_t^2)\left(b\tau\eta_{t+\tau}^2 V^2 + \tau^2\eta_{t+\tau}^2\left\|b\mathbb{E}g_m^{dc}(w_t)\right\|^2\right). \tag{51}$$

For the term $T_2 = \mathbb{E}\left(\left\|\sum_{m=1}^{b}g_m^{dc}(w_t)\right\|^2\right)$, it has

$$\mathbb{E}(T_2) \leq bV^2 + \left\|b\mathbb{E}g_m^{dc}(w_t)\right\|^2. \tag{52}$$

By putting Ineq.(51) and Ineq.(52) in Ineq.(46), we can get

$$\mathbb{E}(F(w_{t+\tau+1}) - F(w_{t+\tau})) \tag{53}$$

$$\leq \quad -\frac{b\eta_{t+\tau}}{2}\mathbb{E}\|\nabla F(w_{t+\tau})\|^2 + \left(\frac{\eta_{t+\tau}^2 L_2}{2} - \frac{\eta_{t+\tau}}{2b}\right)\mathbb{E}\left(\left\|b\mathbb{E}g_m^{dc}(w_t)\right\|^2\right)$$

$$+ \left(\frac{\eta_{t+\tau}^2 bL_2}{2} + (L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + \epsilon_t^2)b^2\tau\eta_{t+\tau}^3\right)V^2 \tag{54}$$

$$+ (L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + \epsilon_t^2)b\tau^2\eta_{t+\tau}^3\mathbb{E}\left(\left\|b\mathbb{E}g_m^{dc}(w_t)\right\|^2\right) \tag{55}$$

Summarizing the Ineq.(55) from $t = 1$ to $t + \tau = T$, we have

$$\mathbb{E}F(w_{T+1}) - F(w_1) \tag{56}$$

$$\leq -\frac{b}{2}\sum_{t=1}^{T}\eta_t\mathbb{E}\|\nabla F(w_t)\|^2 + \sum_{t=1}^{T}\left(\frac{\eta_{t+\tau}^2 bL_2}{2} + (L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + \epsilon_t^2)b^2\tau\eta_{t+\tau}^3\right)V^2 \tag{57}$$

$$+ \sum_{t=1}^{T}\left(\frac{\eta_t^2 L_2}{2} + (L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + \epsilon_t^2)b\tau^2\eta_t^3 - \frac{\eta_t}{2b}\right)\mathbb{E}\left\|b\mathbb{E}g_m^{dc}(w_{\max\{t-\tau,1\}})\right\|^2. \tag{58}$$

By Lemma F.1 and under our assumptions, we have when $t > T_0$, w_t will goes into a strongly convex neighbourhood of some local optimal w_{loc}. Thus, $\epsilon_t \leq \epsilon_{nc} + \theta\sqrt{1/(t - T_0)}$, when $t > T_0$ and $\epsilon_t < \max_{s \in 1, \cdots, T_0} \epsilon_s$ when $t < T_0$.

Let $\eta_t = \sqrt{\frac{2(F(w_1) - F(w^*))}{bTV^2 L_2}}$. It follows that

$$\sum_{t=1}^{T}\frac{\eta_t L_2}{2} + (L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + \epsilon_t^2)b\tau^2\eta_t^2 \tag{59}$$

$$\leq \sum_{t=1}^{T}\left\{\frac{\eta_t L_2}{2} + (L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + 2\epsilon_{nc}^2)b\tau^2\eta_t^2\right\} + 2b\tau^2\eta_t^2(4T_0\max_{s \in 1, \cdots, T_0}(\epsilon_s)^2 + 4\theta^2\log(T - T_0)) \tag{60}$$

We ignore the $\log(T - T_0)$ term and regards $\tilde{C}^2 = 4T_0\max_{s \in 1, \cdots, T_0}(\epsilon_s)^2 + 4\theta^2\log(T - T_0)$ as a constant, which yields

$$\sum_{t=1}^{T}\frac{\eta_t L_2}{2} + (L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + \epsilon_t^2)b\tau^2\eta_t^2 \tag{61}$$

$$\leq \sum_{t=1}^{T}\left\{\frac{\eta_t L_2}{2} + (L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + 2\epsilon_{nc}^2)b\tau^2\eta_t^2\right\} + 2\tau^2\eta_t^2 b\tilde{C}^2 \tag{62}$$

η_t should be set to make

$$\sum_{t=1}^{T}\left(\frac{\eta_t^2 L_2}{2} + (L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + 2\epsilon_{nc}^2)b\tau^2\eta_t^3 + \frac{2\tau^2\eta_t^3 b\tilde{C}^2}{T} - \frac{\eta_t}{2b}\right) \leq 0. \tag{63}$$

Then we can get

$$\frac{1}{T}\sum_{t=1}^{T}\mathbb{E}\|\nabla F(w_t)\|^2 \tag{64}$$

$$\leq \frac{2(F(w_1) - F(w^*) + Tb(\eta_t^2 L_2 + 2(L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + 2\epsilon_{nc}^2)b\tau\eta_t^3)V^2 + \frac{\eta_t^3\tilde{C}^2 4b\tau}{T}V^2}{bT\eta_t} \tag{65}$$

$$\leq \frac{2(F(w_1) - F(w^*))}{bT\eta_t} + (\eta_t L_2 + 2(L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + 2\epsilon_{nc}^2)b\tau\eta_t^2)V^2 + \frac{\eta_t^2\tilde{C}^2 4b\tau V^2}{T} \tag{66}$$

$$\tag{67}$$

We set η_t to make

$$(2(L_3^2\pi^2/2 + 2((1-\lambda)L_1^2 + \epsilon_D)^2 + 2\epsilon_{nc}^2)b\tau\eta_t^2) + \frac{\eta_t^2\tilde{C}^2 4b\tau}{T} \leq \eta_t L_2 \tag{68}$$

Thus let $\eta_t = \sqrt{\frac{2(F(w_1)-F(w^*))}{bTV^2L_2}}$,

$$\frac{1}{T}\sum_{t=1}^{T}\mathbb{E}\|\nabla F(w_t)\|^2 \leq V\sqrt{\frac{2D_0L_2}{bT}}. \tag{69}$$

And we can get the condition for T by putting η in ineq.63 and ineq.68, we can get that

$$\tau \leq \min\left\{\frac{L_2V}{C_\lambda}\sqrt{\frac{L_2T}{2D_0b}}, \frac{V}{C_\lambda}\sqrt{\frac{L_2T}{2D_0b}}, \frac{TV}{\tilde{C}}\sqrt{\frac{L_2}{bD_0}}, \frac{VL_2T}{4\tilde{C}}\sqrt{\frac{TL_2}{2D_0b}}\right\}. \tag{70}$$

F. Decreasing rate of the approximation error ϵ_t

Since ϵ_t is contained the proof of the convergence rate for DC-ASGD , in this section we will introduce a lemma which describes the approximation error ϵ_t the for both convex and nonconvex cases.

Lemma F.1 *Assume that the true label y is generated according to the distribution $\mathbb{P}(Y = k|x, w^*) = \sigma_k(x, w^*)$ and $f(x, y, \boldsymbol{w}) = -\sum_{k=1}^{K}(I_{[y=k]}\log\sigma_k(x; \boldsymbol{w}))$. If we assume that the loss function is μ-strongly convex about w. We denote $\boldsymbol{w}_t$ is the output of DC-ASGD by using the outerproduct approximation of Hessian, we have*

$$\epsilon_t = \left|\mathbb{E}_{(x,y|\boldsymbol{w}^*)}\frac{\partial^2}{\partial\boldsymbol{w}^2}f(x, y, \boldsymbol{w}_t) - \mathbb{E}_{(x,y|\boldsymbol{w}^*)}\left(\frac{\partial}{\partial\boldsymbol{w}}f(x, y, \boldsymbol{w}_t)\right)\otimes\left(\frac{\partial}{\partial\boldsymbol{w}}f(x, y, \boldsymbol{w}_t)\right)\right| \leq \theta\sqrt{\frac{1}{t}},$$

where $\theta = \frac{2HKLVL_2}{\mu^2}\sqrt{\frac{1}{\mu}(1 + \frac{L_2+\lambda L_1^2}{L_2}\tau)}$.

If we assume that the loss function is μ-strongly convex in a neighborhood of each local optimal $d(\boldsymbol{w}_{loc}, r)$, $\left|\frac{\partial^2\mathbb{P}(Y=k|x,\boldsymbol{w})}{\partial^2\boldsymbol{w}}\times\frac{1}{P(Y=k|x,w)}\right| \leq H, \forall k, x, w$, each $\sigma_k(\boldsymbol{w})$ is L-Lipschitz continuous about $\boldsymbol{w}$. We denote $\boldsymbol{w}_t$ is the output of DC-ASGD by using the outerproduct approximation of Hessian, we have

$$\epsilon_t = \left|\mathbb{E}_{(x,y|\boldsymbol{w}^*)}\frac{\partial^2}{\partial\boldsymbol{w}^2}f(x, y, \boldsymbol{w}_t) - \mathbb{E}_{(x,y|\boldsymbol{w}^*)}\left(\frac{\partial}{\partial\boldsymbol{w}}f(x, y, \boldsymbol{w}_t)\right)\otimes\left(\frac{\partial}{\partial\boldsymbol{w}}f(x, y, \boldsymbol{w}_t)\right)\right| \leq \theta\sqrt{\frac{1}{t-T_0}} + \epsilon_{nc}.$$

where $t > T_0 \geq \mathcal{O}(\frac{1}{r^8})$.

Proof:

$$\begin{aligned}
\mathbb{E}_{(y|x,\boldsymbol{w}^*)}\frac{\partial^2}{\partial\boldsymbol{w}^2}f(x, Y, \boldsymbol{w}_t) &= -\mathbb{E}_{(y|x,\boldsymbol{w}^*)}\frac{\partial^2}{\partial\boldsymbol{w}^2}\left(\sum_{k=1}^{K}(I_{[y=k]}\log\sigma_k(x; \boldsymbol{w}_t))\right)\\
&= -\mathbb{E}_{(y|x,\boldsymbol{w}^*)}\frac{\partial^2}{\partial\boldsymbol{w}^2}\log\left(\prod_{k=1}^{K}\sigma_k(x, \boldsymbol{w}_t)^{I_{[y=k]}}\right)\\
&= -\mathbb{E}_{(y|x,\boldsymbol{w}^*)}\frac{\partial^2}{\partial\boldsymbol{w}^2}\log\mathbb{P}(y|x, \boldsymbol{w}_t)\\
&= -\mathbb{E}_{(y|x,\boldsymbol{w}^*)}\frac{\frac{\partial^2}{\partial\omega^2}\mathbb{P}(y|x, \boldsymbol{w}_t)}{\mathbb{P}(y|x, \boldsymbol{w}_t)} + \mathbb{E}_{(y|x,\boldsymbol{w}^*)}\left(\frac{\frac{\partial}{\partial\omega}\mathbb{P}(y|x, \boldsymbol{w}_t)}{\mathbb{P}(y|x, \boldsymbol{w}_t)}\right)^2\\
&= -\mathbb{E}_{(y|x,\boldsymbol{w}^*)}\frac{\frac{\partial^2}{\partial\omega^2}\mathbb{P}(y|x, \boldsymbol{w}_t)}{\mathbb{P}(y|x, \boldsymbol{w}_t)} + \mathbb{E}_{(y|x,\boldsymbol{w}^*)}\left(\frac{\partial}{\partial\omega}\log\mathbb{P}(y|x, \boldsymbol{w}_t)\right)^2.\\
&= -\mathbb{E}_{(y|x,\boldsymbol{w}^*)}\frac{\frac{\partial^2}{\partial\omega^2}\mathbb{P}(y|x, \boldsymbol{w}_t)}{\mathbb{P}(y|x, \boldsymbol{w}_t)} + \mathbb{E}_{(y|x,\boldsymbol{w}^*)}\left(\frac{\partial}{\partial\omega}f(x, Y, \boldsymbol{w}_t)\right)^2. \tag{71}
\end{aligned}$$

Since $\mathbb{E}_{(y|x,\mathbf{w}_t)} \frac{\frac{\partial^2}{\partial \omega^2} \mathbb{P}(y|x,\mathbf{w}_t)}{\mathbb{P}(y|x,\mathbf{w}_t)} = 0$ by the two equivalent methods to calculating fisher information matrix (Friedman et al., 2001), we have

$$
\left| \mathbb{E}_{(y|x,\mathbf{w}^*)} \frac{\frac{\partial^2}{\partial \omega^2} \mathbb{P}(y|x,\mathbf{w}_t)}{\mathbb{P}(y|x,\mathbf{w}_t)} \right| = \left| \mathbb{E}_{(y|x,\mathbf{w}^*)} \frac{\frac{\partial^2}{\partial \omega^2} \mathbb{P}(y|x,\mathbf{w}_t)}{\mathbb{P}(y|x,\mathbf{w}_t)} - \mathbb{E}_{(y|x,\mathbf{w}_t)} \frac{\frac{\partial^2}{\partial \omega^2} \mathbb{P}(y|x,\mathbf{w}_t)}{\mathbb{P}(y|x,\mathbf{w}_t)} \right|
$$

$$
= \left| \sum_{k=1}^{K} \frac{\partial^2}{\partial \omega^2} \mathbb{P}(Y=k|X=x,\mathbf{w}_t) \times \frac{\mathbb{P}(Y=k|x,\mathbf{w}^*) - \mathbb{P}(Y=k|x,\mathbf{w}_t)}{\mathbb{P}(Y=k|x,\mathbf{w}_t)} \right| \tag{72}
$$

$$
\leq H \cdot \sum_{k=1}^{K} |\mathbb{P}(Y=k|x,\mathbf{w}^*) - \mathbb{P}(Y=k|x,\mathbf{w}_t)|
$$

$$
\leq HKL\|\mathbf{w}_t - \mathbf{w}_{loc}\| + HK \max_{k=1,\cdots,K} |\mathbb{P}(Y=k|x,\mathbf{w}_{loc}) - \mathbb{P}(Y=k|x,\mathbf{w}^*)| \tag{73}
$$

$$
\leq HKL\|\mathbf{w}_t - \mathbf{w}_{loc}\| + \epsilon_{nc}. \tag{74}
$$

For strongly convex objective functions, $\epsilon_{nc} = 0$ and $w_{loc} = w^*$. The only thing we need is to prove the convergence of DC-ASGD without using the information of ϵ_t like before. By the smoothness condition, we have

$$
\mathbb{E}F(w_{t+\tau+1}) - F(w^*) \tag{75}
$$

$$
\leq \quad F(w_{t+\tau}) - F(w^*) - \eta_{t+\tau}\langle \nabla F(w_{t+\tau}), \mathbb{E}g^{dc}(w_t)\rangle + \frac{L_2 \eta_{t+\tau}^2 V^2}{2} \tag{76}
$$

$$
= \quad F(w_{t+\tau}) - F(w^*) - \eta_{t+\tau}\langle \nabla F(w_{t+\tau}), \nabla F(w_{t+\tau})\rangle \tag{77}
$$

$$
+ \eta_{t+\tau}\langle \nabla F(w_{t+\tau}), \nabla F(w_{t+\tau}) - \mathbb{E}g^{dc}(w_t)\rangle + \frac{L_2 \eta_{t+\tau}^2 V^2}{2} \tag{78}
$$

$$
\leq \quad (1 - \frac{2\eta_{t+\tau}\mu^2}{L_2})(F(w_{t+\tau}) - F(w^*)) + \eta_{t+\tau}\|\nabla F(w_{t+\tau})\|\|\nabla F(w_{t+\tau}) - \mathbb{E}g^{dc}(w_t)\| + \frac{L_2 \eta_{t+\tau}^2 V^2}{2} \tag{79}
$$

$$
\leq \quad (1 - \frac{2\eta_{t+\tau}\mu^2}{L_2})(F(w_{t+\tau}) - F(w^*)) + \eta_{t+\tau}V \cdot (L_2 + \lambda L_1^2)\|w_{t+\tau} - w_t\| + \frac{L_2 \eta_{t+\tau}^2 V^2}{2} \tag{80}
$$

$$
\leq \quad (1 - \frac{2\eta_{t+\tau}\mu^2}{L_2})(F(w_{t+\tau}) - F(w^*)) + \eta_{t+\tau}V \cdot (L_2 + \lambda L_1^2)\|\sum_{j=1}^{\tau} \eta_{t+\tau-j}g^{dc}(w_t)\| + \frac{L_2 \eta_{t+\tau}^2 V^2}{2} \tag{81}
$$

Taking expectation to the above inequality, we can get

$$
\mathbb{E}F(w_{t+\tau+1}) - F(w^*) \quad \leq \quad (1 - \frac{2\eta_{t+\tau}\mu^2}{L_2})(\mathbb{E}F(w_{t+\tau}) - F(w^*)) + \frac{\eta_{t+\tau}^2(L_2 + \lambda L_1^2)V^2\tau}{2} + \frac{L_2\eta_{t+\tau}^2 V^2}{2} \tag{82}
$$

$$
\leq \quad (1 - \frac{2\eta_{t+\tau}\mu^2}{L_2})(\mathbb{E}F(w_{t+\tau}) - F(w^*)) + \frac{\eta_{t+\tau}^2 V^2 L_2}{2}(1 + \frac{L_2 + \lambda L_1^2}{L_2}\tau). \tag{83}
$$

Let $\eta_t = \frac{L_2}{\mu^2 t}$, we have

$$
\mathbb{E}F(w_{t+1}) - F(w^*) \leq \left(1 - \frac{2}{t}\right)(\mathbb{E}F(w_t) - F(w^*)) + \frac{V^2 L_2^2}{2\mu^4 t^2}\left(1 + \frac{L_2 + \lambda L_1^2}{L_2}\tau\right). \tag{84}
$$

We can get

$$
\mathbb{E}F(w_t) - F(w^*) \leq \frac{2L_2^2 V^2}{t\mu^4}\left(1 + \frac{L_2 + \lambda L_1^2}{L_2}\tau\right). \tag{85}
$$

by induction. Then we can get

$$
\|w_t - w^*\|^2 \leq \frac{4L_2^2 V^2}{t\mu^5}\left(1 + \frac{L_2 + \lambda L_1^2}{L_2}\tau\right). \tag{86}
$$

By putting Ineq.86 into Ineq.73, we can get the result in the theorem.

For nonconvex case, if $\mathbf{w}_t \in \mathcal{B}(\mathbf{w}_{loc}, r)$, we have $\mathbb{E}(\mathbf{w}_t - \mathbf{w}_{loc}) \leq \frac{1}{\mu}\mathbb{E}\nabla F(\mathbf{w}_t)$ under the assumptions. Next we will prove that, for nonconvex loss function $f(x,y,\mathbf{w}_t)$, DC-ASGD has ergodic convergence rate. $\min_{t=1,\cdots,T} \mathbb{E}\|\frac{\partial}{\partial \mathbf{w}_t}F(x,y,\mathbf{w}_t)\|^2 = \mathcal{O}(1/\sqrt{T})$, where the expectation is taking with respect to the stochastic sampling.
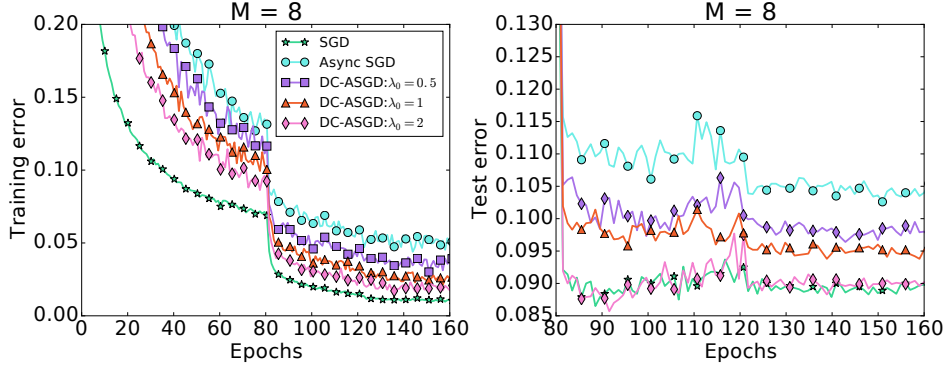
Figure 1. Error rates of the global model with Different λ_0 w.r.t. number of effective passes on CIFAR-10

Compared with the proof of ASGD (Lian et al., 2015), DC-ASGD with Hessian approximation has

$$
\begin{aligned}
T_1 &= \|\nabla F(w_{t+\tau}) - \mathbb{E}g^{dc}(w_t)\|^2 & (87) \\
&= \|\nabla F(w_{t+\tau}) - \nabla F(w_t) - \lambda \mathbb{E}g(w_t) \odot g(w_t) \cdot (w_{t+\tau} - w_t)\|^2 & (88) \\
&\leq 2\|\nabla F(w_{t+\tau}) - \nabla F(w_t)\|^2 + 2\|\lambda \mathbb{E}g(w_t) \odot g(w_t) \cdot (w_{t+\tau} - w_t)\|^2 & (89) \\
&\leq 2(L_2^2 + \lambda^2 L_1^4)\|w_{t+\tau} - w_t\|^2, & (90)
\end{aligned}
$$

since L_1 is the upper bound of $\nabla f(w)$ and L_2 is the smooth coefficient of $f(w)$. Suppose that $\eta = \sqrt{\frac{2D_0}{bTV^2L_2}}$ and τ is upper bounded as Theorem 5.1,

$$
\min_{t=1,\cdots,T} \mathbb{E}\|\nabla F(w_t)\|^2 \leq \frac{1}{T}\sum_{t=1}^{T}\mathbb{E}\|\nabla F(w_t)\|^2 \leq \mathcal{O}(\frac{1}{T^{1/2}}). \tag{91}
$$

Referring to a recent work of Lee *et.al* (Lee et al., 2016), GD with a random initialization and sufficiently small constant step size converges to a local minimizer almost surely under the assumptions in Theorem 1.2. Thus, the assumption that $F(w)$ is μ-strongly convex in the r-neighborhood of arbitrary local minimum w_{loc} is easily to be satisfied with probability one. By the L_1-Lipschitz assumption, we have $P(Y = k|x, w_t) - P(Y = k|x, w_{loc}) \leq L_1\|w_t - w_{loc}\|$. By the L_2-smooth assumption, we have $L_2\|w_t - w_{loc}\|^2 \geq \langle \nabla F(w_t), w_t - w_{loc}\rangle$. Thus for $w_t \in \mathcal{B}(w_{loc}, r)$, we have $\|\nabla F(w_t)\| \leq L_2\|w_t - w_{loc}\| \leq L_2 r$. By the continuously twice differential assumption, we can assume that $\|\nabla F(w_t)\| \leq L_2\|w_t - w_{loc}\| \leq L_2 r$ for $w_t \in \mathcal{B}(w_{loc}, r)$ and $\|\nabla F(w_t)\| \leq L_2\|w_t - w_{loc}\| > L_2 r$ for $w_t \notin \mathcal{B}(w_{loc}, r)$ without loss of generality [2]. Therefore $\min_{t=1,\cdots,T}\mathbb{E}\|\nabla F(w_t)\|^2 \leq L_2^2 r^2$ is a sufficient condition for $\mathbb{E}\|w_T - w_{loc}\| \leq r$.

$$
\min_{t=1,\cdots,T_0}\mathbb{E}\|\nabla F(w_t)\|^2 \leq \mathcal{O}(\frac{1}{T_0^{1/2}}) \leq r^2. \tag{92}
$$

We have $T_0 \geq \mathcal{O}\left(\frac{1}{r^4}\right)$.

Thus we have finished the proof for nonconvex case.

G. Experimental Results on the Influence of λ

In this section, we show how the parameter λ affect our DC-ASGD algorithm. We compare the performance of respectively sequential SGD, ASGD and DC-ASGD-a with different value of initial λ_0[3]. The results are given in Figure 1. This experiment reflects to the discussion in Section 5, too large value of this parameter ($\lambda_0 > 2$ in this setting) will introduce large variance and lead to a wrong gradient direction, meanwhile too small will make the compensation influence nearly disappear. As λ decreasing, DC-ASGD will gradually degrade to ASGD. A proper λ will lead to significant better accuracy.

---

[2]We can choose r small enough to make it satisfied.

[3]We also compare different λ_0 for DC-ASGD-c and the results are very similar to DC-ASGD-a.

H. Large Mini-batch Synchronous SGD with Delay-Compensated Gradient

In this section, we discuss how delay-compensated gradient can be used in synchronous SGD. The effective mini-batch size in SSGD is usually enlarged M times comparing with sequential SGD. A learning rate scaling trick is commonly used to overcome the influence of large mini-batch size in SSGD (Goyal et al., 2017): when the mini-batch size is multiplied by M, multiply the learning rate by M. For sequential mini-batch SGD with learning rate η we have:

$$\mathbf{w}_{t+M} = \mathbf{w}_t - \eta \sum_{j<M} g(\mathbf{w}_{t+j}, z_{t+j}), \tag{93}$$

where z_{t+j} is the $t+j$-th minibatch.

On the other hand, taking one step with M times large mini-batch size and learning rate $\hat{\eta} = M\eta$ in synchronous SGD yields:

$$\hat{\mathbf{w}}_{t+1} = \mathbf{w}_t - \hat{\eta}\frac{1}{M} \sum_{j<M} g(\mathbf{w}_t, z_t^j), \tag{94}$$

where z_t^j is the t-th minibatch on local machine j.

Assume that $z_{t+j} = z_t^j$. The assumption $g(\mathbf{w}_{t+j}, z_{t+j}) \approx g(\mathbf{w}_t, z_t^j)$ was made in synchronous SGD(Goyal et al., 2017). However, it often may not hold.

If we denote $\tilde{\mathbf{w}}_{t+1}^j = \mathbf{w}_t - \hat{\eta}\frac{1}{M}g(\mathbf{w}_t, z_t^j), j \in [M]$, we can use Eq.(5) in the main paper to compensate this assumption and apply delay-compensated gradient to update Eq.94 with:

$$g(\mathbf{w}_{t+j}, z_{t+j}) \approx g(\mathbf{w}_t, z_t^j) + \lambda g(\mathbf{w}_t, z_t^j) \odot g(\mathbf{w}_t, z_t^j) \odot (\tilde{\mathbf{w}}_{t+j} - \mathbf{w}_t)), j < M. \tag{95}$$

We have $\mathbf{w}_{t+1} = \tilde{\mathbf{w}}_{t+1}$. For $j > 1$, we need to design an order to make $\tilde{\mathbf{w}}_{t+j} \approx \mathbf{w}_{t+j}$. Choosing $\mathbf{w}_{t+j}$ according to the increasing order of $\|\tilde{\mathbf{w}}_{t+j} - \mathbf{w}_t\|^2$ can be used since the smaller distance with $\mathbf{w}_t$ will induce more accurate approximation by using Taylor expansion.

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