

AMS526: Numerical Analysis I  
(Numerical Linear Algebra)  
Lecture 7: Sensitivity of Linear Systems

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# Outline

- 1 Condition Number of a Matrix
- 2 Perturbing Right-hand Side
- 3 Perturbing Coefficient Matrix
- 4 Putting All Together

## Condition Number of Matrix

- Consider  $f(x) = Ax$ , with  $A \in \mathbb{R}^{m \times n}$

$$\kappa = \frac{\|J\|}{\|f(x)\|/\|x\|} = \frac{\|A\|\|x\|}{\|Ax\|}$$

- If  $A$  is square and nonsingular, since  $\|x\|/\|Ax\| \leq \|A^{-1}\|$

$$\kappa \leq \|A\|\|A^{-1}\|$$

- We define *condition number of matrix  $A$*  as

$$\kappa(A) = \|A\|\|A^{-1}\|$$

- It is the upper bound of the condition number of  $f(x) = Ax$  for any  $x$
- For any induced matrix norm,  $\kappa(I) = 1$  and  $\kappa(A) \geq 1$
- Note about the distinction between the condition number of a *problem* (the map  $f(x)$ ) and the condition number of a *problem instance* (the evaluation of  $f(x)$  for specific  $x$ )

## Geometric Interpretation of Condition Number

- Another way to interpret  $\kappa(A)$  is

$$\kappa(A) = \sup_{\delta x, x} \frac{\|\delta f\|/\|\delta x\|}{\|f(x)\|/\|x\|} = \frac{\sup_{\delta x} \|A\delta x\|/\|\delta x\|}{\inf_x \|Ax\|/\|x\|}$$

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- Question: For what  $x$  and  $\delta x$  is the equality achieved?  
Answer: When  $x$  is in direction of minimum magnification, and  $\delta x$  is in direction of maximum magnification
- Define *maximum magnification* of  $A$  as

$$\text{maxmag}(A) = \max_{\|x\|=1} \|Ax\|$$

and *minimum magnification* of  $A$  as

$$\text{minmag}(A) = \min_{\|x\|=1} \|Ax\|$$

- Then condition number of matrix is  $\kappa(A) = \text{maxmag}(A)/\text{minmag}(A)$
- For 2-norm,  $\kappa(A) = \sigma_1/\sigma_n$ , the ratio of largest and smallest singular values (in later sections)

## Example of Ill-Conditioned Matrix

### Example

Let  $A = \begin{bmatrix} 1000 & 999 \\ 999 & 998 \end{bmatrix}$ . It is easy to verify that

$$A^{-1} = \begin{bmatrix} -998 & 999 \\ 999 & -1000 \end{bmatrix}. \text{ So}$$

$$\kappa_{\infty}(A) = \kappa_1(A) = 1999^2 = 3.996 \times 10^6.$$

## Example of Ill-Conditioned Matrix

### Example

A famous example is Hilbert matrix, defined by  $h_{ij} = 1/(i + j - 1)$ ,  $1 \leq i, j \leq n$ . The matrix is ill-conditioned for even quite small  $n$ . For  $n \leq 4$ , we have

$$H_4 = \begin{bmatrix} 1 & 1/2 & 1/3 & 1/4 \\ 1/2 & 1/3 & 1/4 & 1/5 \\ 1/3 & 1/4 & 1/5 & 1/6 \\ 1/4 & 1/5 & 1/6 & 1/7 \end{bmatrix},$$

with condition number  $\kappa_2(H_4) \approx 1.6 \times 10^4$ , and  $\kappa_2(H_8) \approx 1.5 \times 10^{10}$ .

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### Theorem

*Let  $A$  be nonsingular, and let  $x$  and  $\hat{x} = x + \delta x$  be the solutions of  $Ax = b$  and  $A\hat{x} = b + \delta b$ , respectively. Then*

$$\frac{\|\delta x\|}{\|x\|} \leq \kappa(A) \frac{\|\delta b\|}{\|b\|},$$

*and there exists  $\|b\|$  and  $\|\delta b\|$  for which the equality holds.*

- Question: For what  $b$  and  $\delta b$  is the equality achieved?

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and there exists  $\|b\|$  and  $\|\delta b\|$  for which the equality holds.

- Question: For what  $b$  and  $\delta b$  is the equality achieved?

Answer: When  $b$  is in direction of *minimum* magnification of  $A^{-1}$ , and  $\delta b$  is in direction of *maximum* magnification of  $A^{-1}$ .

In 2-norm, when  $b$  is in direction of *maximum* magnification of  $A^T$ , and  $\delta b$  is in direction of *minimum* magnification of  $A^T$ .

# Singular and Nearly Singular Linear System

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# Singular and Nearly Singular Linear System

- Question: What is condition number of  $Ax$  if  $A$  is singular?  
Answer:  $\infty$ .
- We say a matrix is *nearly singular* if its condition number is very large
- In other words, columns of  $A$  are nearly linearly dependent
- If  $A$  is nearly singular, for matrix-vector multiplication,  $Ax$ , error is large if  $x$  is nearly in null space of  $A$
- If  $A$  is nearly singular, for linear system  $Ax = b$ , error is large if  $b$  is NOT nearly in null space of  $A^T$
- Therefore, ill-conditioning (near singularity) has a much bigger impact on solving linear system than matrix-vector multiplication!

# Ill Conditioning Caused by Poor Scaling

- Some matrices are ill conditioned simply because they are out of scale.

## Theorem

*Let  $A \in \mathbb{R}^{n \times n}$  be any nonsingular matrix, and let  $a_k$ ,  $1 \leq k \leq n$  denote the  $k$ th column of  $A$ . Then for any  $i$  and  $j$  with  $1 \leq i, j \leq n$ ,*

$$\kappa_p(A) \geq \|a_i\|_p / \|a_j\|_p.$$

- This theorem indicates that poor scaling inevitably leads to ill conditioning
- A *necessary* condition for a matrix to be well conditioned is that all of its rows and columns are of roughly the same magnitude.

## Estimating Condition Number

- We would like to estimate  $\kappa_1(A) = \|A\|_1 \|A^{-1}\|_1$  without computing  $A^{-1}$ , but allow LU factorization of  $A$
- For any vector  $w \in \mathbb{R}^n$  and  $\|w\|_1 = 1$ , we have lower bound

$$\kappa_1(A) \geq \|A\|_1 \|A^{-1}w\|_1$$

- If  $w$  has a significant component in direction near maximum magnification by  $A^{-1}$ , then

$$\kappa_1(A) \approx \|A\|_1 \|A^{-1}w\|_1$$

- Note statement on p. 132 of textbook “Actually any  $w$  chosen at random is likely to have a significant component in the direction of maximum magnification by  $A^{-1}$ ” is unjustified for large  $n$  in 1-norm
- Good estimators conduct systematic searches for  $w$  that approximately maximizes  $\|A^{-1}w\|_1$

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# Non-singularity of Perturbed Matrix

## Theorem

*If  $A$  is nonsingular and*

$$\|\delta A\|/\|A\| < 1/\kappa(A),$$

*then  $A + \delta A$  is nonsingular.*

# Non-singularity of Perturbed Matrix

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*If  $A$  is nonsingular and*

$$\|\delta A\|/\|A\| < 1/\kappa(A),$$

*then  $A + \delta A$  is nonsingular.*

## Proof.

$\|\delta A\|/\|A\| < 1/\kappa(A)$  is equivalent to  $\|\delta A\|\|A^{-1}\| < 1$ . Suppose  $A + \delta A$  is singular, then  $\exists y \neq 0$  such that  $(A + \delta A)y = 0$ , and  $y = -A^{-1}\delta A y$ .

Therefore,  $\|y\| \leq \|A^{-1}\|\|\delta A\|\|y\|$ , or  $\|A^{-1}\|\|\delta A\| \geq 1$ . □

- If  $A + \delta A$  is the singular matrix closest to  $A$ , in the sense that  $\|\delta A\|_2$  is as small as possible, then  $\|\delta A\|_2/\|A\|_2 = 1/\kappa_2(A)$

## Linear System with Perturbed Matrix

- Suppose  $Ax = b$  and  $\hat{A}\hat{x} = b$  where  $\hat{A} = A + \delta A$ . Let  $\delta x = \hat{x} - x$  and  $\hat{x} = x + \delta x$ .
- We would like to bound  $\|\delta x\|/\|x\|$ , but first we bound  $\|\delta x\|/\|\hat{x}\|$

### Theorem

If  $A$  is nonsingular, and let  $b \neq 0$ . Then

$$\frac{\|\delta x\|}{\|\hat{x}\|} \leq \kappa(A) \frac{\|\delta A\|}{\|A\|}.$$

### Proof.

Rewrite  $(A + \delta A)\hat{x} = b$  as  $Ax + A\delta x + \delta A\hat{x} = b$ , where  $Ax = b$ . Therefore,

$$\|\delta x\| \leq \|A^{-1}\| \|\delta A\| \|\hat{x}\|.$$

Therefore,

$$\frac{\|\delta x\|}{\|\hat{x}\|} \leq \|A^{-1}\| \|\delta A\| = \kappa(A) \frac{\|\delta A\|}{\|A\|}.$$

## Linear System with Perturbed Matrix Continued

- $Ax = b$  and  $\hat{A}\hat{x} = b$  where  $\hat{A} = A + \delta A$ . Let  $\delta x = \hat{x} - x$  and  $\hat{x} = x + \delta x$ .

### Theorem

If  $A$  is nonsingular and  $\|\delta A\|/\|A\| < 1/\kappa(A)$ , and let  $b \neq 0$ . Then

$$\frac{\|\delta x\|}{\|x\|} \leq \frac{\kappa(A)\|\delta A\|/\|A\|}{1 - \kappa(A)\|\delta A\|/\|A\|}.$$

### Proof.

$\|\delta x\| \leq \|A^{-1}\| \|\delta A\| \|\hat{x}\| \leq \|A^{-1}\| \|\delta A\| (\|x\| + \|\delta x\|)$ . Therefore,

$$(1 - \|A^{-1}\| \|\delta A\|) \delta x \leq \|A^{-1}\| \|\delta A\| \|x\|,$$

where  $\|A^{-1}\| \|\delta A\| = \kappa(A) \|\delta A\|/\|A\|$ . □

We typically expect  $\kappa(A) \|\delta A\| \ll \|A\|$ , so the denominator is close to 1.

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## Perturbed RHS and Matrix

- Suppose  $Ax = b$  and  $(A + \delta A)(x + \delta x) = (b + \delta b)$ , where  $\hat{A} = A + \delta A$ ,  $\hat{b} = b + \delta b$  and  $\hat{x} = x + \delta x$ .

### Theorem

Let  $A$  be nonsingular, and suppose  $\hat{x} \neq 0$  and  $\hat{b} \neq 0$ . Then

$$\frac{\|\delta x\|}{\|\hat{x}\|} \leq \kappa(A) \left( \frac{\|\delta A\|}{\|A\|} + \frac{\|\delta b\|}{\|\hat{b}\|} + \frac{\|\delta A\|}{\|A\|} \frac{\|\delta b\|}{\|\hat{b}\|} \right) \approx \kappa(A) \left( \frac{\|\delta A\|}{\|A\|} + \frac{\|\delta b\|}{\|\hat{b}\|} \right).$$

### Theorem

If  $A$  is nonsingular and  $\|\delta A\|/\|A\| < 1/\kappa(A)$ , and let  $b \neq 0$ , then

$$\frac{\|\delta x\|}{\|x\|} \lesssim \frac{\kappa(A)(\|\delta A\|/\|A\| + \|\delta b\|/\|b\|)}{1 - \kappa(A)\|\delta A\|/\|A\|}.$$

Roughly speaking,  $\kappa(A)$  determines loss of digits of accuracy in  $x$  in addition to loss of digits of accuracy in perturbations in  $A$  and  $b$

# A Posteriori Error Analysis Using Residual

- Suppose  $\hat{x}$  is a computed solution of  $Ax = b$ , and residual  $\hat{r} = b - A\hat{x}$ . How to bound error in  $x - \hat{x}$ ?

## Theorem

Let  $A$  be nonsingular, let  $b \neq 0$ . Then

$$\frac{\|\delta x\|}{\|x\|} \leq \kappa(A) \frac{\|\hat{r}\|}{\|b\|}.$$

- If the residual is tiny and  $A$  is well conditioned, then  $\hat{x}$  is an accurate approximation to  $x$ .
- For a *posteriori* error bound, one needs to estimate  $\|\hat{r}\|$  and  $\kappa(A)$