

Mango24R2 Linux

기본 교육

CQZ. TECHNOLOGY

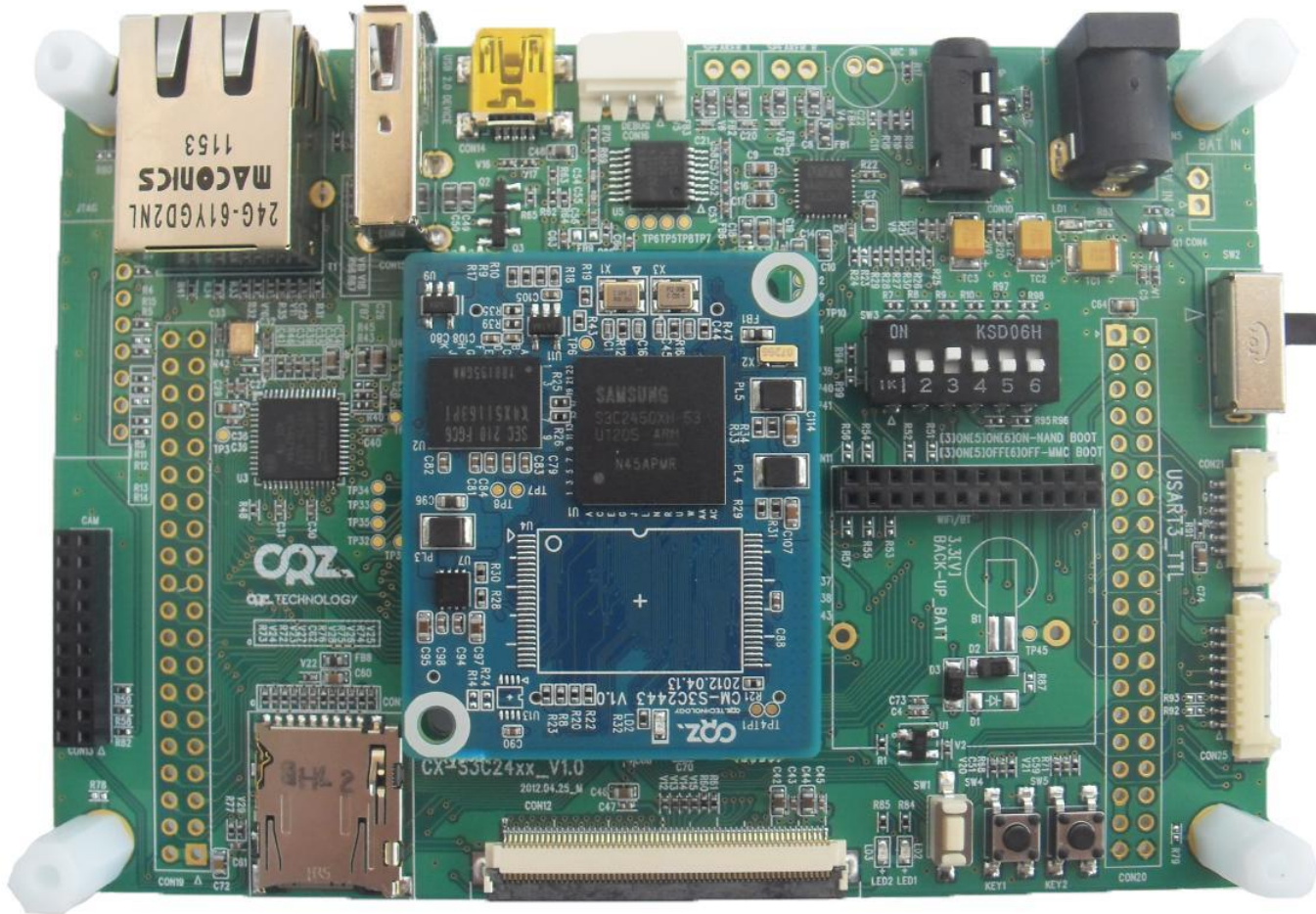
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1. 하드웨어 사양

- ◆ Hardware Specification
- ◆ Block Diagram
- ◆ 부품 배치
- ◆ Boot mode

1. 하드웨어 사양



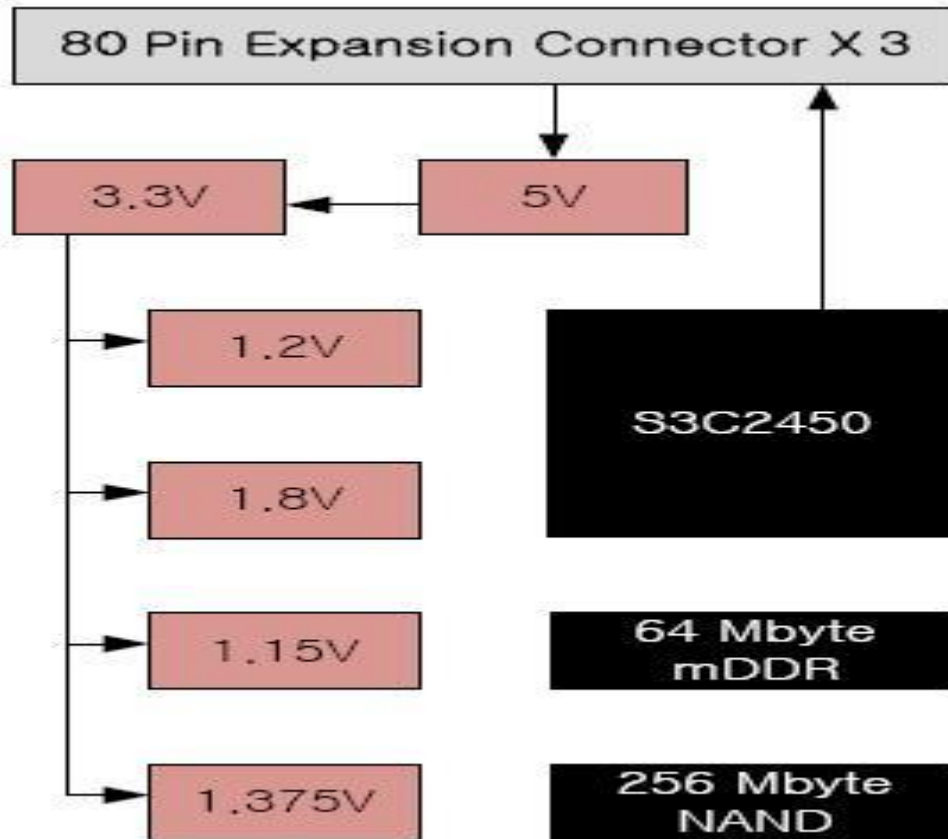
1. 하드웨어 사양

◆ Hardware Specification

Processor	ARM926EJ Samsung S3C2450 533Mhz
RAM	Mobile DDR 64MB
Flash	SLC NAND Flash 256MB
Display	7" 800x480 with touch
Audio	Wolfson WM8960 with 1W Stereo Speaker Amplifier
USB Host 1.1	1 Port (Full Speed)
USB Device 2.0	1 Port
SD	SD/MMC Port0 (WiFi/BT) SD/MMC Port1 (SD Boot)
WiFi/BT	SDIO 0 Channel 802.11B,G,N
Camera	1Port 1.3M Pixel Camera
UART	UART0 UART1 (Debug) UART2 (Expansion) UART3(GPS)
Sensor Interface	I2C 0 Port (3-Axis,Gyro,Light,Remocon etc)
Ethernet	SMSC LAN9220 10/100Mps Ethernet Constroller
Power	DC-JACK 5V, 1A
Button	Reset :1 , Button : 2
Boot Switch	1
LED indicator	2
Expansion Connector (80x2)	EBI,UART,I2C GPIO etc

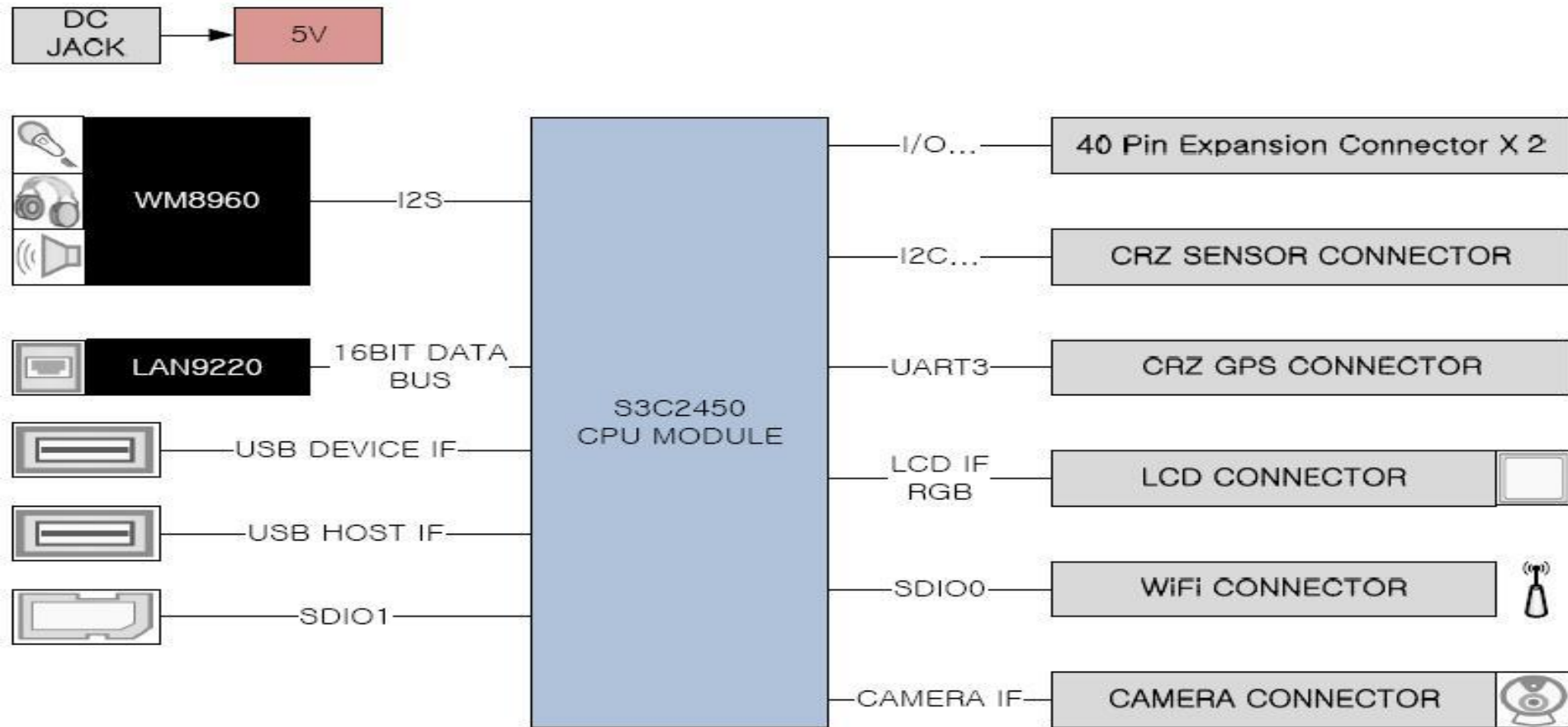
1. 하드웨어 사양

◆ CM S3C2450 CPU Module Block Diagram

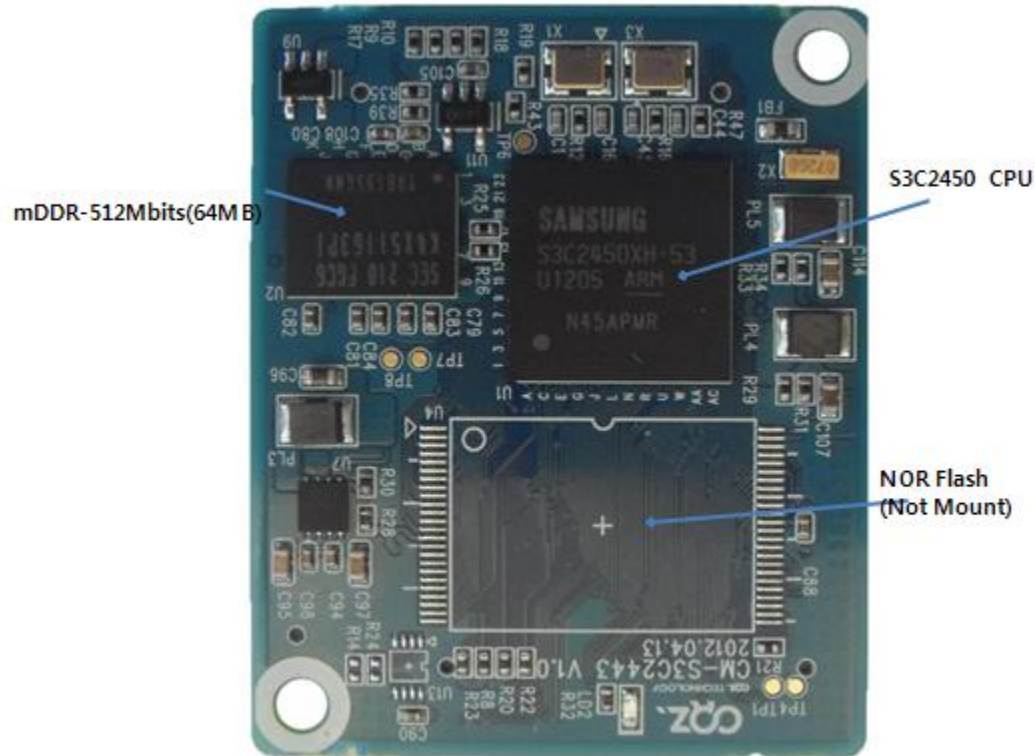


1. 하드웨어 사양

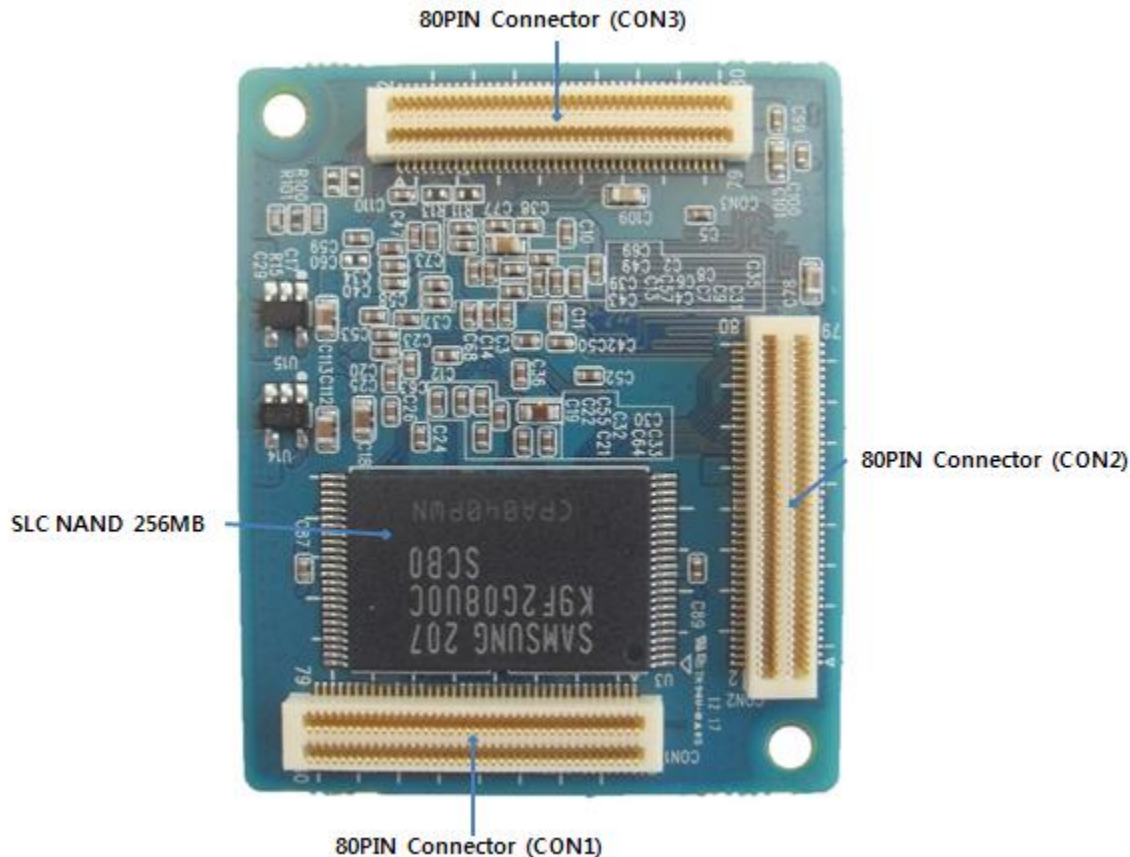
◆ CX S3C2450 Base Board Block Diagram



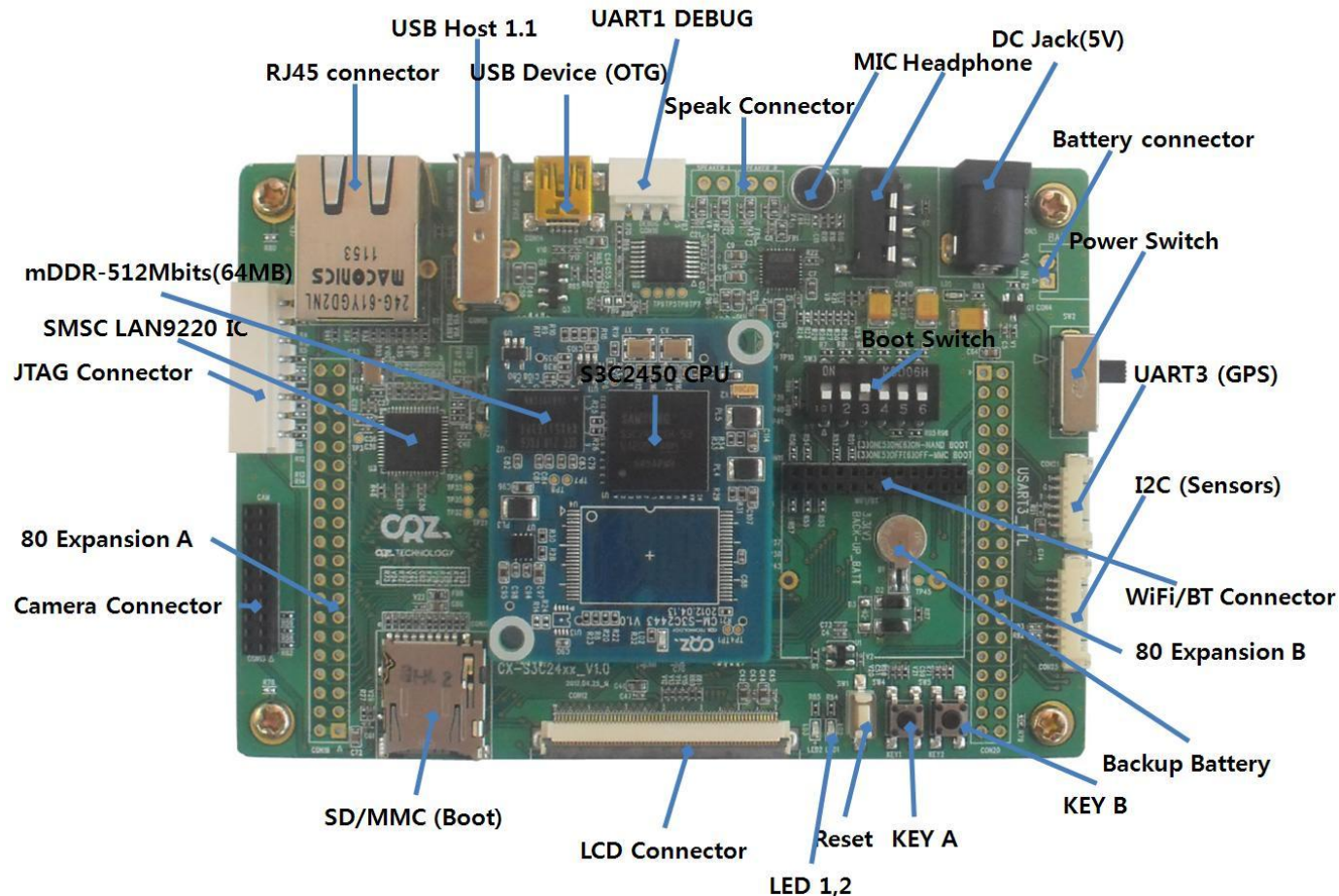
1. 하드웨어 사양 (CPU Module)



1. 하드웨어 사양(CPU Module)

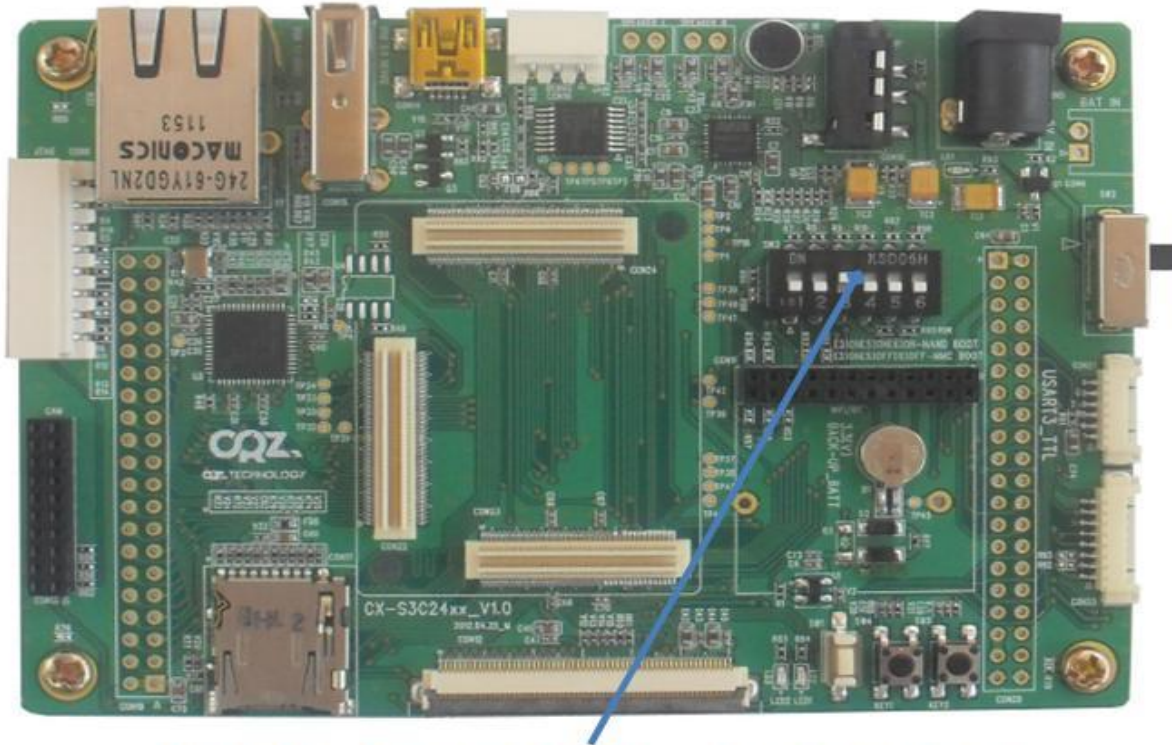


1. 하드웨어 사양



1. 하드웨어 사양

◆ BOOT MODE



[3] ON [5] ON [6] ON -> NAND BOOT
[3] ON [5] OFF [6] OFF -> MMC BOOT

2. 빌드 환경 구축(우분투 12.04 64bit 기준)

- ◆ GCC Setting
- ◆ Toolchain Install
- ◆ Package install
- ◆ TFTP 설정

2. 빌드 환경 구축

◆ GCC Setting

Install



```
$ sudo apt-get install gcc-4.5 g++-4.5 build-essential gcc-4.5-multilib g++-4.5-multilib  
$ sudo apt-get install gcc-4.5 g++-4.4 build-essential gcc-4.4-multilib g++-4.4-multilib
```

Setting

```
$ sudo update-alternatives --install /usr/bin/gcc gcc /usr/bin/gcc-4.6 40 W  
--slave /usr/bin/g++ g++ /usr/bin/g++-4.6
```

```
$ sudo update-alternatives --install /usr/bin/gcc gcc /usr/bin/gcc-4.5 60 W  
--slave /usr/bin/g++ g++ /usr/bin/g++-4.5
```

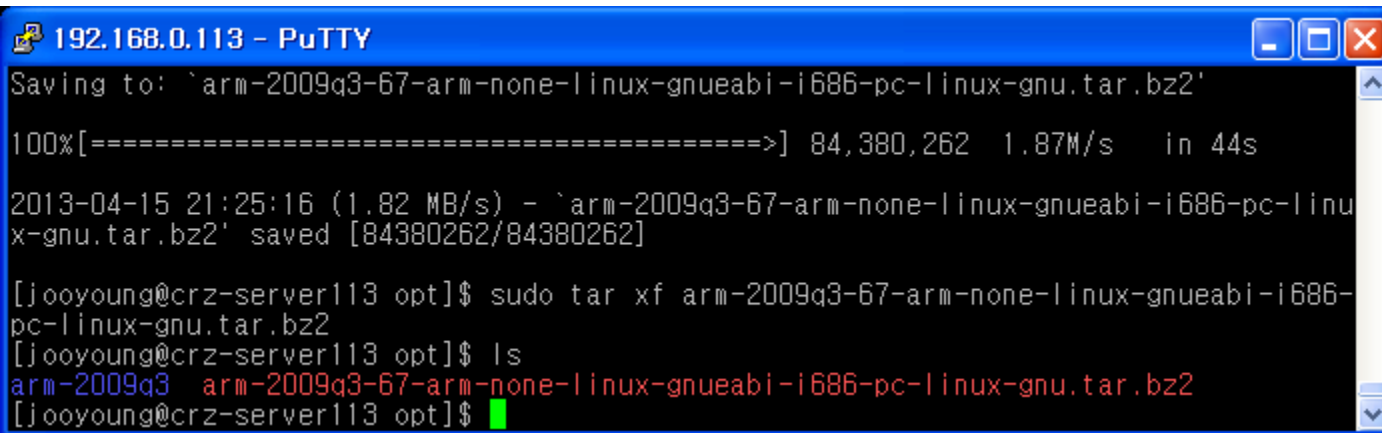
```
$ sudo update-alternatives --install /usr/bin/gcc gcc /usr/bin/gcc-4.4 80 W  
--slave /usr/bin/g++ g++ /usr/bin/g++-4.4
```

```
$ sudo update-alternatives --config gcc
```

2. 빌드 환경 구축

◆ Toolchain Install

```
$ cd /opt  
$ sudo wget http://crztech.iptime.org:8080/Release/Toolchain/arm-2009q3-67-arm-none-linux-gnueabi-i686-pc-linux-gnu.tar.bz2  
$ sudo tar xvf arm-2009q3-67-arm-none-linux-gnueabi-i686-pc-linux-gnu.tar.bz2
```



```
192.168.0.113 - PuTTY  
Saving to: 'arm-2009q3-67-arm-none-linux-gnueabi-i686-pc-linux-gnu.tar.bz2'  
100%[=====>] 84,380,262 1.87M/s in 44s  
2013-04-15 21:25:16 (1.82 MB/s) - 'arm-2009q3-67-arm-none-linux-gnueabi-i686-pc-linux-gnu.tar.bz2' saved [84380262/84380262]  
[jooyoung@crz-server113 opt]$ sudo tar xf arm-2009q3-67-arm-none-linux-gnueabi-i686-pc-linux-gnu.tar.bz2  
[jooyoung@crz-server113 opt]$ ls  
arm-2009q3 arm-2009q3-67-arm-none-linux-gnueabi-i686-pc-linux-gnu.tar.bz2  
[jooyoung@crz-server113 opt]$
```


2. 빌드 환경 구축

◆ Package install

```
$ sudo apt-get install git-core gnupg flex bison gperf build-essential  
$ sudo apt-get install zip curl libc6-dev x11proto-core-dev  
$ sudo apt-get install libx11-dev:i386 libreadline6-dev:i386 libgl1-mesa-dev:i386  
$ sudo apt-get install g++-multilib mingw32 openjdk-6-jdk tofrodos python-markdown  
$ sudo apt-get install libxml2-utils xsltproc zlib1g-dev:i386  
$ sudo apt-get install gcc-multilib  
$ sudo apt-get install libc6-dev-i386  
$ sudo apt-get install ia32-libs  
$ sudo apt-get install lib32z-dev  
$ sudo apt-get install libusb-dev:i386  
$ sudo apt-get install git-core bison flex g++ gettext texinfo  
$ sudo apt-get install automake  
  
$ sudo apt-get install libncurses5-dev
```

2. 빌드 환경 구축



◆ TFTP 설정

```
$ sudo apt-get install xinetd tftp tftpd  
$ sudo mkdir /home/tftp  
$ sudo chmod 777 /home/tftp/  
$ sudo vi /etc/xinetd.d/tftp
```

```
service tftp  
{  
  protocol      = udp  
  port          = 69  
  socket_type   = dgram  
  wait         = yes  
  user          = nobody  
  server        = /usr/sbin/in.tftpd  
  server_args   = /home/tftp  
  disable       = no  
}
```

```
$ sudo /etc/init.d/xinetd restart
```

동영상 : <http://youtu.be/WMfb-rPiexE>

3. 컴파일 방법

- ◆ Mango24R2 source Download & install
- ◆ Uboot build
- ◆ Kernel build
- ◆ Buildroot build

3. 컴파일 방법

◆ Download & install

```
$ wget  
http://crztech.iptime.org:8080/Release/mango24R2\_S3C2450/linux/m2450\_kernel  
3.0.22\_mrvl8787\_Qt\_130418\_Rel/m2450\_kernel3.0.22\_mrvl8787\_Qt\_130418.tgz  
$ tar xf m2450_kernel3.0.22_mrvl8787_Qt_130418.tgz  
$ cd m2450_kernel3.0.22_mrvl8787_Qt_130418/
```

3. 컴파일 방법



◆ Uboot build

```
$ ./build_uboot clean  
$ ./build_uboot config  
$ ./build_uboot
```

동영상 :

<http://youtu.be/4-hhIU9RmDA>

```
CPU_JOB_NUM=$(grep processor /proc/cpuinfo | awk '{field=$NF};END{print field+2}')  
START_TIME=`date +%s`  
  
case "$1" in  
clean)  
    echo make -j$CPU_JOB_NUM mrproper  
    make -j$CPU_JOB_NUM mrproper  
    ;;  
config)  
    echo make -j$CPU_JOB_NUM mango2450_config  
    make -j$CPU_JOB_NUM mango2450_config  
    ;;  
all|*)  
    echo make -j$CPU_JOB_NUM  
    make -j$CPU_JOB_NUM  
    if [ $? != 0 ] ; then  
        exit 1  
    fi  
    if [ "$2" ] ; then  
        INSTALL_BINDIR=$2  
    fi  
    if [ $INSTALL_BINDIR ] ; then  
        echo cp -a $UBOOT_IMAGE $INSTALL_BINDIR/$UBOOT_IMAGE  
        cp -a $UBOOT_IMAGE $INSTALL_BINDIR/$UBOOT_IMAGE  
    fi  
    ;;  
esac
```

3. 컴파일 방법

◆ Kernel build

```
$ ./build_kernel defconfig mango2450_defconfig
```

```
$ ./build_kernel
```

◆ 동영상 : <http://youtu.be/ULvpT5SVPvc>



3. 컴파일 방법

◆ Buildroot build



\$./build_rootFS.sh

동영상

<http://youtu.be/-vJparL4Os4>

```
#!/bin/bash

CONFIG_FILE=mango2450_config

{

START_TIME=`date +%s`

#mkdir -p ../image

echo "Copy config file"
cp $CONFIG_FILE .config

echo "Build buildroot"
make

echo "Copy build image"
cp -f ./output/images/rootfs.tar ../image/

END_TIME=`date +%s`
echo "Total compile time is $(((END_TIME-START_TIME)/60)) minutes
$(((END_TIME-START_TIME)%60)) seconds"

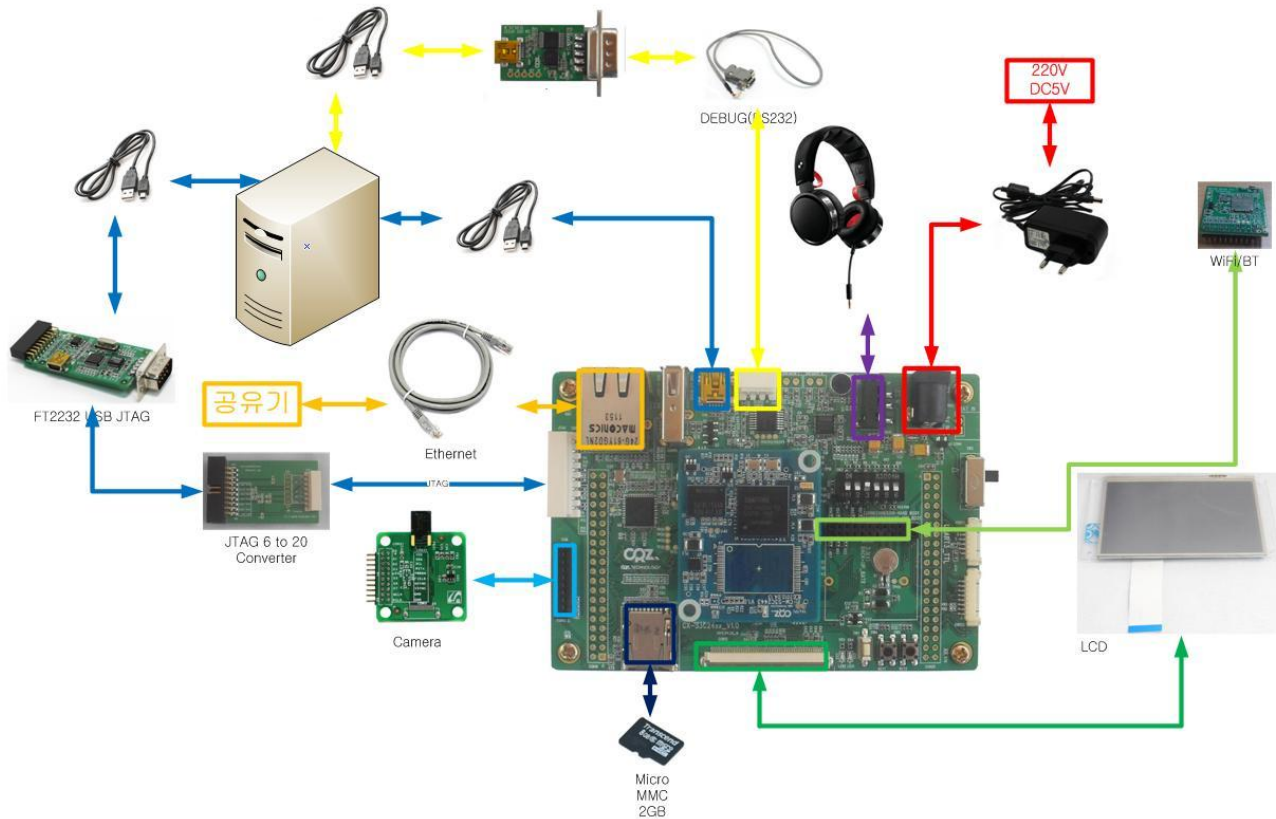
} 2>&1 |tee build.out
```

4. 보드에 Write하는 방법

- ◆ 연결도
- ◆ SD writer
- ◆ Openocd JTAG Connect and U-boot 실행
- ◆ DNW NAND U-boot How to Fusing
- ◆ DNW NAND zImage How to Fusing
- ◆ TFTP NAND Uboot How to Fusing
- ◆ TFTP NAND zImage How to Fusing
- ◆ SD Rootfs writer
- ◆ Mango24r2 board에 rootfs writer

4. 보드에 Write하는 방법

◆ 연결도



4. 보드에 Write하는 방법



◆ SD writer

Linux PC 에 SD카드 삽입

```
$ cd image/
```

```
bl1.bin          mkbl1  rootfs.tar          sdwriter      u-boot.bin  
m24r2_signature  rootfs  rootfs_nand_writer.sh sdwriter_sdhc  zImage
```

```
$ sudo fdisk -l
```

Device	Boot	Start	End	Blocks	Id	System
/dev/sdb1		2048	13441021	6719487	83	Linux
/dev/sdb2		13441022	15538173	1048576	83	Linux

```
$ sudo ./sdwriter_sdhc sdb 24 all
```

MMC Boot mode [3]ON 나머지 OFF

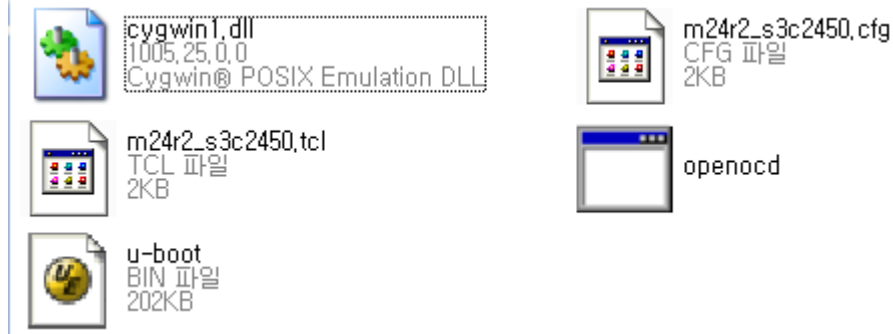
동영상 <http://youtu.be/8sqJRSqG7a4>

4. 보드에 Write하는 방법

◆ Openocd JTAG Connect and U-boot 실행



참고 및 소스다운로드 : <http://cafe.naver.com/embeddedcrazyboys/19583>



MMC Boot mode [3]ON 나머지 OFF

동영상 : <http://youtu.be/MiIBuyF58Mo>

Dos Command 창 open
>openocd.exe -f m24r2_s3c2450.cfg
Dos Command 창 open
>telnet localhost 4444

Open On-Chip Debugger
>script m24r2_s3c2450.tcl

4. 보드에 Write하는 방법(USB : 32bit OS Only)

◆ DNW NAND U-boot How to Fusing



SDboot 나 Openocd를 이용한 Uboot 중 boot mode 에서 입력

```
# nand scrub
```

```
# nand erase 0 40000
```

```
# dnw c0000000
```

Uboot.bin 올림

```
# nand write c0000000 0 40000
```

◆ 동영상 강좌 : http://youtu.be/gjwMFJ-w_30

4. 보드에 Write하는 방법(USB : 32bit OS Only)

◆ DNW NAND zImage How to Fusing



NAND Boot mode [3]ON [5]ON [6]ON

nand erase 80000 480000

dnw c0008000

zImage 올림

nand write c0008000 80000 480000

◆ 동영상 : http://youtu.be/U_yUBV8kVtE

4. 보드에 Write하는 방법(TFTP)

◆ TFTP NAND Uboot How to Fusing



Linux PC

```
$ cp -rf image/ /home/tftp/mango24r2_image/  
$ ifconfig
```

SDboot 나 Openocd를 이용한 Uboot 중 boot mode 에서 입력

```
# setenv ipaddr "192.168.50.10"; setenv gatewayip "192.168.50.1";setenv serverip "192.168.50.5"  
# saveenv  
# tftp c0000000 mango24r2_image/u-boot.bin  
# nand erase 0x0 0x40000  
# nand write 0xc0000000 0x0 0x40000
```

◆ 동영상 : <http://youtu.be/YjIpiGw3R88>

4. 보드에 Write하는 방법(TFTP)

◆ TFTP NAND zImage How to Fusing NAND Boot mode [3]ON [5]ON [6]ON



```
# setenv ipaddr "192.168.50.10"; setenv gatewayip "192.168.50.1";setenv serverip "192.168.50.5"  
# saveenv
```

```
# tftp c0008000 mango24r2_image/zImage  
# nand erase 0x80000 0x480000  
# nand write 0xc0008000 0x80000 0x480000
```

◆ 동영상 : http://youtu.be/Ao-r_zifdtc

4. 보드에 Write하는 방법

◆ Mango24r2 board에 rootfs writer



Boot Mord Setting

```
# setenv bootargs 'noinitrd console=ttySAC1,115200 rw root=/dev/mmcblk0p2 rootfstype=ext4 rootwait'  
# Saveenv  
# boot
```

Rootfs NAND writer

```
# ./rootfs_nand_writer.sh
```

실행 완료 후 reboot를 하면 이상
NAND에 설치 완료

*bootargs은 reboot를 하면 초기값으
로 변경되어 reboot만 하면 됩니다.

```
flash_erase /dev/mtd2 0 0  
ubiattach /dev/ubi_ctrl -m 2  
ubimkvol /dev/ubi0 -N rootfs -m  
mkdir /mnt/nand  
mount -t ubifs ubi0:rootfs /mnt/nand  
cd /root  
tar xvf rootfs.tar -C /mnt/nand  
umount /mnt/nand
```