

The status of the drive is reported back in registers 2100h~2110h (48449~48465 decimal). The six most recent faults are found in P11.04~P11.09 (0B04h~0B09h, 42821~42826 decimal). See Chapter 5 for more detailed explanations of these registers.

|                        | GS4 Status Addresses (Read Only) |   |   |      |                |       |  |  |  |  |
|------------------------|----------------------------------|---|---|------|----------------|-------|--|--|--|--|
| Description            |                                  | Range   |   |      | Modbus Address |       |  |  |  |  |
| Descripti              |                                  | nunge   |   | Hex  | Dec            | Octal |  |  |  |  |
| Status<br>Monitor<br>1 | Fault Codes                      | 0: No Error 1: Overcurrent during Accel (ocA) 2: Overcurrent during Decel (ocd) 3: Overcurrent during normal speed (ocn) 4: Ground Fault (GFF) 5: IGBT short circuit (occ) 6: Overcurrent during Stop (ocS) 7: Overvoltage during Accel (ovA) 8: Overvoltage during Decel (ovd) 9: Overvoltage during Decel (ovd) 9: Overvoltage during Stop (ovS) 11: Low voltage during Stop (ovS) 11: Low voltage during Accel (LvA) 12: Low voltage during Decel (Lvd) 13: Low voltage during Decel (Lvd) 13: Low voltage during Stop (LvS) 15: Input phase loss (OrP) 16: IGBT Overheat 1 (oH1) 17: Cap Overheat 2 (oH2) 18: Thermister 1 open (tH1o) 19: Thermister 2 open (tH2o) 20: Power Reset Off (PWR) 21: Overload (oL) (150% 1Min, Inverter) 22: Motor1 Thermal Overload (EoL1) 23: Motor2 Thermal Overload (EoL2) 24: Motor Overheat-PTC (oH3) 25: reserved 26: Over Torque 1 (ot1) 27: Over Torque 2 (ot2) 28: Under current (uc) 29: reserved 30: EEPROM write error (cF1) 31: EEPROM read error (cF2) 32: reserved 33: U phase current sensor detection error (cd1) 34: V phase current sensor detection error (cd2) 35: W phase current sensor detection error (cd3) 36: CC Hardware Logic error 0 (Hd0) 37: OC Hardware Logic error 1 (Hd1) 38: OV Hardware Logic error 2 (Hd2) 39: OCC Hardware Logic error 3 (Hd3) | 40: Motor auto tune error (AuE) 41: PID Feedback loss (AFE) 42~47: reserved 48: Analog input signal loss (ACE) 49: External Fault (EF) 50: Emergency Stop (EF1) 51: Base Block (bb) 52: Password Error (Pcod) 53: Software Code lock (ccod) 54: PC Command error (CE1) 55: PC Address error (CE2) 56: PC Data error (CE3) 57: PC Slave error (CE4) 58: PC Communication Time Out (CE10) 59: PC Keypad Time out (CP10) 60: Braking Transistor Fault (bf) 61: Y-Delta connection Error (ydc) 62: Decel Energy Backup Error (dEb) 63: Over Slip Error (oSL) 64: Electromagnet switch error (ryF) 65~71: reserved 72: STO Loss1 (STL1)     STO1~SCM1 internal hardware detect error 73: ES1 Emergency Stop (S1) 74: In Fire Mode (Fire) 75: reserved 76: Safety Torque Off function active (STO) 77: STO Loss2 (STL2)     STO2~SCM2 internal hardware detect error 78: STO Loss3 (STL3) —     STO1~SCM1 and STO2~SCM2 internal hardware detect error 78: STO Loss3 (STL3) —     STO1~SCM1 and STO2~SCM2 internal hardware detect error 79: U Phase Short (Voc) 81: W Phase Short (Woc) 82: U Phase Loss (UPHL) 83: V Phase Loss (UPHL) 84: W Phase Loss (WPHL) 85-89: reserved 90: PLC Force Stop (FStp) 91~98: reserved 99: CPU Command error (TRAP) 100~110: reserved 111: reserved | 2100 | 48449          | 20400 |  |  |  |  |

| Name       | Туре  | Start value | Function   |
|------------|-------|-------------|--|
| ConfigAxis | WORD  | 16#003F     | Assignment of the drive control word (drive parameter r2090).  The start value 16#003F sets bits 1 to 6 to TRUE:  Bit 1: OFF2 Bit 2: OFF3 Bit 3: Enable operation Bit 4: Enable ramp-function generator Bit 5: Continue ramp-function generator Bit 6: Enable speed setpoint |
| HWIDSTW    | HW_IO | 0           | Hardware ID setpoint value (see section Telegram slot)   |
| HWIDZSW    | HW_IO | 0           | Hardware ID actual value (see section Telegram slot)   |

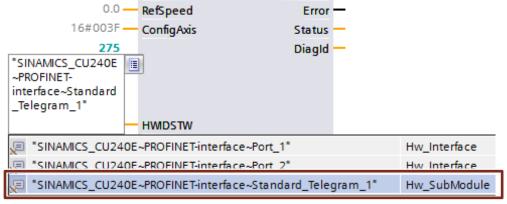
Table 3-6: "SINA\_SPEED" output parameter

| Name        | Туре | Start value | Function   |
|-------------|------|-------------|--|
| AxisEnabled | BOOL | FALSE       | Drive operation is enabled   |
| Lockout     | BOOL | FALSE       | On-inhibit of the drive is active  |
| ActVelocity | REAL | 0.0         | Actual speed of the drive  |
| Error       | BOOL | FALSE       | Drive fault active   |
| Status      | WORD | 0           | Display of status values: 16#7002: No fault 16#8401: Drive fault active 16#8402: On-inhibit active 16#8600: DPRD_DAT error 16#8601: DPWR_DAT error |
| Diagld      | WORD | 0           | Expanded communication fault (error when calling up a command)   |

## **Telegram slot**

The block inputs HWIDSTW and HWIDZSW must reference to the hardware ID of the standard telegram.

Figure 3-3: Supply of the telegram slot



When using a PROFINET connection between the SIMATIC controller and the SINAMICS G120 drive, the same hardware ID must be configured for block inputs HWIDSTW and HWIDZSW.