

# MATH1023/MATH1062 Calculas

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## 1 Week1

### 1.1 Differential Equation

1. **Differential Equation(DE)**: A differential equation (DE) is a mathematical equation that relates some **function with its derivatives**
2. **Order**: The order of a differential equation equals to a **highest derivative** occuring in it.
  - $\frac{dy}{dx} = -ky$  has order **1**
  - $\frac{dy}{dx} = y^{18} + \frac{d^5y}{dx^2}y + x^2$  has order **5**
3. **Standard Form**: The standard form of a **first-order differential equation** is

$$\frac{dy}{dx} = f(x, y)$$

4. **General Solution**: A **general solution** is a solution incoporating all constants of integration.
5. **Initial Condition**: An initial condition is a pair  $(x_0, y_0)$  such that  $y(x_0) = y_0$

## 2 Week2

### 2.1 Direction Field

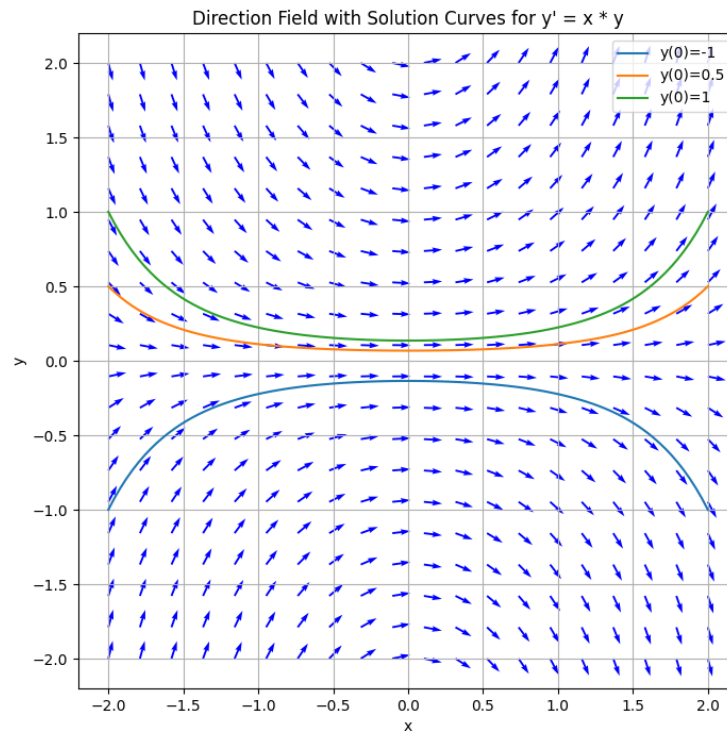
1. **Definition**: A direction field of a DE

$$y' = f(x, y)$$

consists of a grid of short line segments with slope  $f(a, b)$  drawn at points  $(a, b)$ . So the line segment at  $(a, b)$  is **tangent** to any solution passing through  $(a, b)$

2. **Example:** Draw some solution curves on the given direction field for the DE:

$$y' = xy$$



## 2.2 Separable equations

1. **Definition:** A first-order DE  $y' = f(x, y)$  is called **separable** if there are functions  $g(x)$  and  $h(y)$  such that  $f(x, y) = g(x)h(y)$ , so a separable DE can be written

$$y' = g(x)h(y)$$

2. **Goal:** We want to find a method for solving separable DEs
3. **Method:** We can solve a separable DE:

$$\frac{dy}{dx} = g(x)h(y)$$

by separating variables.

Dividing both sides by  $h(y)$  gives

$$\frac{1}{h(y)} \frac{dy}{dx} = g(x)$$

Integrating both sides gives:

$$\int \frac{1}{h(y)} dy = \int g(x) dx$$

If we can find antiderivatives  $H(y)$  for  $\frac{1}{h(y)}$  and  $G(x)$  for  $g(x)$ , then we have

$$H(y) = G(x) + C$$

### 3 Week3

#### 3.1 Modelling Population Growth

1. **Constant Growth:** This occurs when the population  $x$  increases at a constant rate. The DE is

$$\frac{dx}{dt} = k$$

where  $k$  is constant

2. **Exponential Growth:** The exponential growth model assumes the growth rate is proportional to the size of the population.

The general form of a DE modelling exponential growth is

$$\frac{dx}{dt} = kx$$

where  $k$  is constant

3. **Logistic Growth:** Exponential growth is **not** a realistic growth model for all values of  $t$ . **A small animal population** with unlimited resources of food and space **may show exponential growth initially**

As the population gets larger there will be food shortages, overcrowding, and other factors that **slow down the growth rate**.

**The growth rate  $k$  should decrease as the population  $x$  increases.**

Since  $k$  is no longer constant, we write  $k = g(x)$ , so the DE becomes

$$\frac{dx}{dt} = g(x)x$$

A small population can grow exponentially, so we want  $g(x) \approx k$  when  $x \approx 0$ . But as  $x$  increases  $g(x)$  should decrease.

The simplest formula with this behaviour is

$$g(x) = k - ax$$

So the DE becomes

$$\frac{dx}{dt} = (k - ax)x$$

We introduce a new constant  $b = \frac{k}{a}$  so

$$(k - ax)x = ax\left(\frac{k}{a} - x\right) = ax(b - x)$$

Let  $\frac{b}{a} = b$ , the logistic DE is then given by

$$\frac{dx}{dt} = ax(b - x)$$

## 4 week4

### 4.1 First-order linear DEs

1. **First-order linear differential equation:** A first-order linear differential equation is a DE of the form:

$$\frac{dy}{dx} + p(x)y = q(x)$$

$\frac{dy}{dx}$  and  $y$  occur only linearly

2. **How to solve first-order linear DEs ?:** The idea is multiplying the DE by a function  $r(x)$  give:

$$r(x)\frac{dy}{dx} + r(x)p(x)y = r(x)q(x)$$

If we can find  $r(x)$  such that:

$$r(x)\frac{dy}{dx} + r(x)p(x)y = \frac{d}{dx}(r(x)y(x))$$

then the DE becomes:

$$\frac{d}{dx}(r(x)y(x)) = r(x)q(x)$$

Integrating with respect to  $x$  gives:

$$\begin{aligned} \int \frac{d}{dx}(r(x)y(x))dx &= \int r(x)q(x)dx \\ &\rightarrow \\ r(x)y(x) &= \int r(x)q(x)dx + C \end{aligned}$$

so the general solution is

$$y = \frac{1}{r(x)} \left[ \int r(x)q(x)dx + C \right]$$

3. **Integrating factor:** The function

$$r(x) = e^{\int p(x)dx}$$

is an integrating factor for the first-order linear DE

$$\frac{dy}{dx} + p(x)y = q(x)$$

4. **General Solution** the general solution of the DE is

$$y = \frac{1}{r(x)} \left[ \int r(x)q(x)dx + C \right]$$

## 5 week5

### 5.1 Higher order differential equations

Higher order DEs involve higher order derivatives. For example, the DE:

$$\frac{d^2y}{dx^2} + f(x, y)\frac{dy}{dx} = g(x, y)$$

is a second-order differential equation.

1. Solving higher-order DEs is harder.
2. The general solution of a second-order DE has 2 degrees of freedom, so needs two initial conditions.
3. The general solution of an nth-order DE has n degrees of freedom, so needs n initial conditions.

### 5.2 Second-order linear DEs with constant coefficients

1. **Definition** A second-order linear differential equation is a DE that can be expressed in the form:

$$\frac{d^2y}{dx^2} + f_1(x)\frac{dy}{dx} + f_0(x)y = g(x)$$

The DE is linear in  $y$  and its derivatives.

#### 2. homogeneous/inhomogeneous

- The DE is homogeneous if  $g(x) = 0$
- The DE is inhomogeneous if  $g(x) \neq 0$

If  $g(x) = 0, f_0(x) = a, f_1(x) = b$  for  $a, b \in \mathbb{R}$ , then we have a homogeneous second-order linear differential equation with constant coefficient:

$$\frac{d^2y}{dx^2} + a\frac{dy}{dx} + by = 0$$

3. Solve the above DE :

$$\frac{d^2y}{dx^2} + a\frac{dy}{dx} + by = 0$$

- **Observation 1:**  $y$  is a linear combination of its first two derivatives, so we try:

$$y(x) = e^{mx}$$

We have

$$\frac{dy}{dx} = me^{mx}, \frac{d^2y}{dx^2} = m^2e^{mx}$$

- **Observation 2:** Find  $m$  such that  $y = Ce^{mx}$  satisfies the DE

$$\frac{d^2y}{dx^2} + a\frac{dy}{dx} + by = 0$$

substituting  $y$  and its derivatives we get:

$$\begin{aligned} Cm^2e^{mx} + aCme^{mx} + bCe^{mx} &= 0 \\ \Rightarrow Ce^{mx}(m^2 + am + b) &= 0 \\ \Rightarrow m &= \frac{-a \pm \sqrt{a^2 - 4b}}{2} \end{aligned}$$

So we have 2 solutions

$$m_1 = \frac{-a + \sqrt{a^2 - 4b}}{2}, m_2 = \frac{-a - \sqrt{a^2 - 4b}}{2}$$

- **Observation 3:** Show that if  $m = m_1, m_2$  are solutions of  $m^2 + am + b = 0$ , then  $y = C_1e^{m_1x} + C_2e^{m_2x}$ , satisfies the DE

$$\frac{d^2y}{dx^2} + a\frac{dy}{dx} + by = 0$$

we have

$$\begin{aligned} y &= C_1e^{m_1x} + C_2e^{m_2x} \\ \Rightarrow \frac{dy}{dx} &= m_1C_1e^{m_1x} + m_2C_2e^{m_2x} \\ \Rightarrow \frac{d^2y}{dx^2} &= m_1^2C_1e^{m_1x} + m_2^2C_2e^{m_2x} \end{aligned}$$

substituting into the DE we get

$$\begin{aligned} \Rightarrow \frac{d^2y}{dx^2} &= m_1^2C_1e^{m_1x} + m_2^2C_2e^{m_2x} \\ \Rightarrow \frac{d^2y}{dx^2} &= m_1^2C_1e^{m_1x} + m_2^2C_2e^{m_2x} \end{aligned}$$

substituting into the DE we get

$$\begin{aligned}\frac{d^2y}{dx^2} + a\frac{dy}{dx} + by &= m_1^2 C_1 e^{m_1 x} + m_2^2 C_2 e^{m_2 x} + a(m_1 C_1 e^{m_1 x} + m_2 C_2 e^{m_2 x}) + b(C_1 e^{m_1 x} + C_2 e^{m_2 x}) \\ &= C_1 e^{m_1 x} (m_1^2 + am_1 + b) + C_2 e^{m_2 x} (m_2^2 + am_2 + b) \\ &= 0\end{aligned}$$

- **formal solution:** We now have a good candidate for a general solution of the DE:

$$y = C_1 e^{m_1 x} + C_2 e^{m_2 x}$$

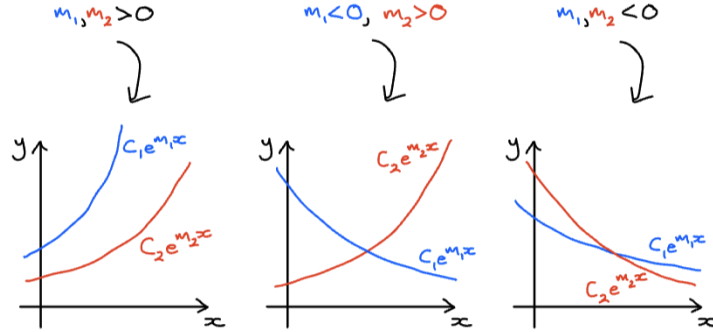
Where  $m_1 = \frac{-a + \sqrt{a^2 - 4b}}{2}, m_2 = \frac{-a - \sqrt{a^2 - 4b}}{2}$  are solutions of  $m^2 + am + b = 0$ . We have 3 cases to consider:

- **Case 1:** For  $a^2 > 4b$  we have 2 distinct real solutions

$$m_1 \neq m_2, m_1, m_2 \in \mathbb{R}$$

The general solution is

$$y = C_1 e^{m_1 x} + C_2 e^{m_2 x}$$



- **Case 2:** For  $a^2 < 4b$  we have 2 distinct complex solutions:

$$m_1, m_2 = \frac{-a \pm \sqrt{a^2 - 4b}}{2} = \frac{-a \pm 2ik}{2} = -\frac{a}{2} \pm ik$$

$$\text{where } k = \frac{1}{2}\sqrt{4b - a^2} > 0$$

Using Euler's formula:

$$e^{ikx} = \cos(kx) + i\sin(kx)$$

We have

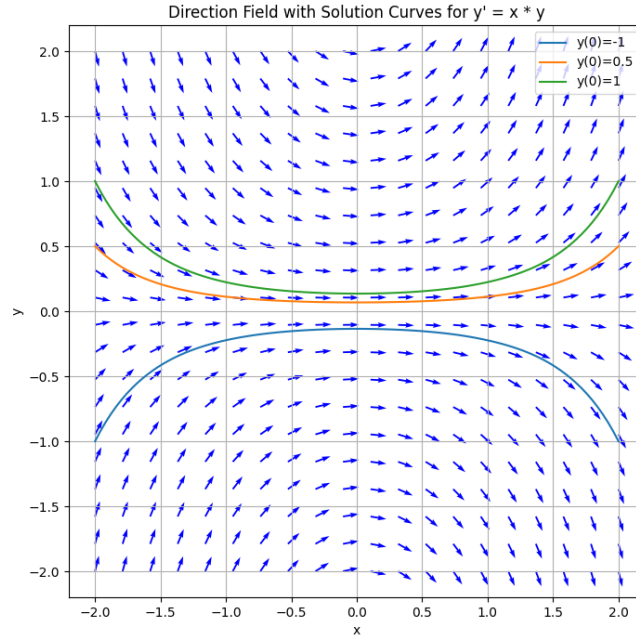
$$\begin{aligned}y &= C_1 e^{m_1 x} + C_2 e^{m_2 x} \\ &= C_1 e^{(-\frac{a}{2} + ik)x} + C_2 e^{(-\frac{a}{2} - ik)x} \\ &= e^{-\frac{a}{2}x} (C_1 e^{ikx} + C_2 e^{-ikx})\end{aligned}$$

$$= e^{-\frac{a}{2}x} (C_1 (\cos(kx) + i \sin(kx)) + C_2 (\cos(kx) - i \sin(kx)))$$

$$= e^{-\frac{a}{2}x} ((C_1 + C_2) \cos(kx) + i (C_1 - C_2) \sin(kx))$$

$$= e^{-\frac{a}{2}x} (D_1 \cos(kx) + D_2 \sin(kx))$$

So the general solution is:  $y = e^{-\frac{a}{2}x} (D_1 \cos(kx) + D_2 \sin(kx))$



– **Case 3:** For  $a^2 = 4b$  we have 1 real solution:

$$m_1 = m_2 = \frac{-a \pm \sqrt{a^2 - 4b}}{2} = -\frac{a}{2}$$

Our solution becomes

$$y = C_1 e^{-\frac{a}{2}x} + C_2 e^{-\frac{a}{2}x}$$

$$= (C_1 + C_2) e^{-\frac{a}{2}x}$$

$$= D e^{-\frac{a}{2}x}$$

Here,  $D$  is a constant ( $D = C_1 + C_2$ ), which means we only have 1 degree of freedom, so this is not a general solution.



We look for a general solution of the form

$$y = f(x)e^{-\frac{a}{2}x}$$

Substituting  $y$  and its derivatives into the differential equation (DE)

$$\frac{d^2y}{dx^2} + a\frac{dy}{dx} + by = 0$$

gives

$$e^{-\frac{a}{2}x} \left( f''(x) + \frac{1}{4}(4b - a^2)f(x) \right) = 0 \quad (\text{exercise})$$

Since  $e^{-\frac{a}{2}x} \neq 0$ ,

$$f''(x) = \frac{1}{4}(a^2 - 4b)f(x) = 0$$

which implies

$$f'(x) = C_2$$

$$f(x) = C_2x + C_1$$

Hence, the general solution is

$$y = (C_1 + C_2x)e^{-\frac{a}{2}x}$$