

**COMP2022**  
**Models of Computation**  
**Intro to Computational Complexity**  
**P vs NP**  
**Sipser Chapter 7**

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# Agenda

Investigate the time (= number of steps) taken by TMs to solve problems.

- What is time complexity?
- What is the **P** vs **NP** problem?

Recall that a **polynomial** (with integer coefficients) in the variable  $n$  is an expression of the form

$$\sum_{i=0}^k a_i n^i$$

where each  $a_i$  is an integer and  $k \in \mathbb{Z}_0^+$ .

e.g.,  $2n^3 - 3n + 1$  is a polynomial.

# What is a step?

What counts as a step for pseudocode?<sup>1</sup>

- assignments  $a = 42$
- comparisons  $i < j$
- Boolean formulas  $(p \& q) \& q$
- mathematical operations  $a = 42x + y$

What counts as a step for Turing machines?

- A single transition counts as a step.
- The number of steps of a run on a given input is computed by the simulator <http://morphett.info/turing/>



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<sup>1</sup>This is how we do it in COMP2x23.

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You: So for each length  $n$  we look at the largest number of steps amongst all inputs of length  $n$ .

Me: Right! This is a function  $f(n)$ , called the **time complexity of the algorithm/TM**

$f(n)$  = the largest number of steps taken by the algorithm/TM  
on any input of length  $n$ .

We say that the algorithm/TM **runs in time  $f(n)$** .

If  $f(n) = O(p(n))$  for some polynomial  $p$ , then we say that the  
algorithm/TM **runs in polynomial time**

For instance,  $M$  has time complexity  $n \log n$  then  $M$  runs in  
polynomial time (since  $n \log n = O(n^2)$ ).

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```
1 def my_fun(array A of integers):
2     n = size(A)
3     for i = 1 to n-1:
4         for j = i+1 to n:
5             if A[i] > A[j] then swap A[i] with A[j]
6     return A
```

---

- On arrays of size  $n$ , line 5 is executed  $(n-1) + (n-2) + \dots + 2 + 1 = n(n-1)/2$  steps.
- So, the time complexity of this algorithm is  $\Theta(n^2)$ , i.e., quadratic.<sup>2</sup>
- We call it a *quadratic-time algorithm*

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<sup>2</sup>Recall that a function  $f$  is  $\Theta(g)$ , read "Big-Theta  $g$ ", if there are constants  $c, d, e$  such that  $cg(n) \leq f(n) \leq dg(n)$  for all  $n > e$ .

This TM  $M$  decides the language  $L = \{0^n 1^n : n \geq 1\}$

The time complexity of  $M$  is  $\Theta(n^2)$  (Tutorial).

# The most important class of languages

## Definition

Define **P** to be the collection of languages  $L$  that are decidable in polynomial time on **deterministic** TMs.

- Read "P" or "P Time" or "Poly Time" or "Polynomial Time" or "Deterministic Polynomial Time".
- **P** includes all the languages decided by linear-time algorithms, and quadratic-time algorithms, and cubic-time algorithms, etc.
- **P** is robust to certain changes in the model, notably multiple tapes.

**P** roughly corresponds to the problems that can be realistically solved on a computer.

# Examples of languages in P

- Every regular language. Why?
- Every context-free language. Why?
- Some of the problems studied in this course, *e.g.*, DFA membership, RE membership, DFA equivalence, CFG membership, CFG emptiness
- Most of the problems studied in
  - COMP2123:Data Structures and Algorithms
  - COMP3027:Algorithm Design

# Self-test

The halting-problem is not in  $\mathbf{P}$  because...

1. It is recognisable, and some recognisable languages are in  $\mathbf{P}$ .
2. It is not decidable, but every language in  $\mathbf{P}$  is decidable.
3. Actually, it is in  $\mathbf{P}$ , and the statement above is wrong!



We saw that automata had deterministic and nondeterministic versions. Turing machines do too!

# Non-Deterministic TMs

The type of the transition function of a non-deterministic TM  $N$  becomes:

$$\delta : Q \times \Gamma \rightarrow P(\Gamma \times \{L, R, S\} \times Q)$$

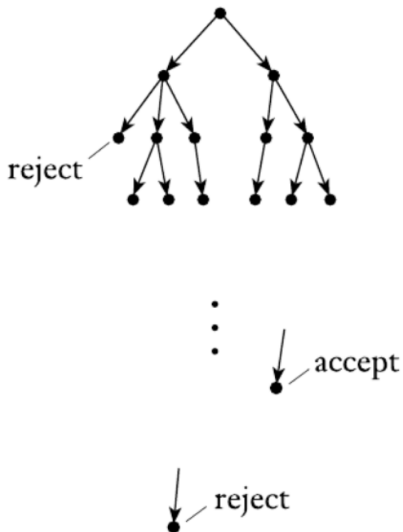
E.g.,  $(a', L, q') \in \delta(q, a)$  means "if  $N$  is in state  $q$  and reads symbol  $a$  under the head, one of its possible transitions is to write  $a'$ , change to state  $q'$ , and move the head one cell to the left".

A computation of  $N$  on an input  $u$  is a tree, called the **computation tree**

## Deterministic



## Nondeterministic



What does it mean for a NTM to accept an input?

### **Definition**

A NTM  $N$  accepts input  $u$  if some branch of the computation tree of  $u$  has an accepting configuration.

So, if no branch of the tree has an accepting configuration (because each rejects or diverges) then  $N$  does not accept  $u$ .

## Theorem

*Every non-deterministic TM  $N$  has an equivalent deterministic TM  $D$ .*

The idea is that  $D$  will "search the computation tree of  $N$ ".

High-level description of TM  $D$ :

- $D$  does a breadth-first search of  $N$ 's computation tree on given input.
- If it finds  $q_{\text{accept}}$  it accepts, otherwise it diverges.

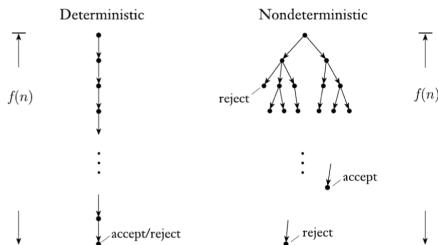
Suppose  $D$  were to use a **depth-first search (DFS)** instead.  
Would this work?

1. Yes, because we know that BFS and DFS both end up traversing the whole tree.
2. No:  $D$  might reach an accepting configuration even if  $N$  can't.
3. No:  $D$  might reach a rejecting configuration even if  $N$  can't.
4. No:  $D$  might not reach an accepting configuration even if  $N$  can.
5. No:  $D$  might not reach a rejecting configuration even if  $N$  can.

# What is time complexity for NTMs?

## Definition

1. An NTM  $N$  is a **decider** if on every input, every branch of its computation tree halts.
2. The **time-complexity** of  $N$  is the the function  $f : \mathbb{N} \rightarrow \mathbb{N}$  where  $f(n)$  is the maximum number of steps that  $N$  uses on any branch of its computation on any input of length  $n$ .
3. If  $f(n) = O(p(n))$  for some polynomial  $p$  then  $N$  **runs in polynomial time**



# The second most important class of languages

## Definition

Define **NP** to be the collection of languages  $L$  that are decidable in polynomial time on **nondeterministic** Turing machines.

- read "NP" or "Nondeterministic Polynomial time"
- It does not stand for "Not Polynomial"

What languages are in **NP**?

- all languages that are in **P**. Why?

What other languages are in **NP**?



# Graphs (AK)

A **graph**  $G$  is a pair  $(V, E)$  where  $V$  is a set of *vertices* and  $E \subseteq V \times V$  is a set of *edges*.

Example:

- A vertex represents a city
- An edge represents a two-way road between two cities

A non-empty graph is called a **clique** (aka "completely connected") if every pair of different nodes is connected by an edge.

# CLIQUE is in NP

The CLIQUE problem:

**Input:** Graph  $(V, E)$  and  $K \in \mathbb{Z}^+$

**Output:** "Yes" if the graph contains  $K$  vertices that form a clique, and "No" otherwise.

To show that CLIQUE is in **NP**, we only need to give a polynomial time NTM that decides it.

Here is a high-level description of such a TM:

On input  $(V, E), K$ :

1. Nondeterministically select a subset  $C \subseteq V$  of  $K$  vertices.
2. Test whether every pair of different nodes in  $C$  is connected by an edge.
3. If yes, accept; else reject

# The most(?) important unsolved problem in computer science

We know that every problem in  $P$  is also in  $NP$ , i.e.,  $P \subseteq NP$

However, we don't know if these are equal:

Is  $P$  equal to  $NP$ ?

You: Ok, so we know that every language in **P** is also in **NP**, but we don't know the reverse.

Me: Right. Do you think CLIQUE is in **P**?

You: Ok, so we know that every language in **P** is also in **NP**, but we don't know the reverse.

Me: Right. Do you think CLIQUE is in **P**?

You: I can't think of a faster way than checking all sets of vertices of size  $K$ , and there are about  $|V|^K$  such sets, which is exponential in  $K$

Me: Right. In fact, if we could show that CLIQUE was in **P** we would be able to conclude that **P** = **NP**.

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You: (mind-blown emoji)

Me: And there are lots of problems like this. They are called **NP**-complete, and are in some sense the "hardest" problems in **NP**.

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You: Where can I learn more about **NP**-completeness?

Me: COMP3027:Algorithm Design