

Important Ideas and Useful Facts:

- (i) **Eigenvalues and eigenvectors:** Let M be a square matrix, \mathbf{x} a nonzero column vector and λ a scalar such that

$$M\mathbf{x} = \lambda\mathbf{x}.$$

Then λ is called an *eigenvalue* of M and \mathbf{x} is called an *eigenvector* of M associated with or corresponding to the eigenvalue λ .

- (ii) **The eigenspace of a matrix:** The *eigenspace* of a square matrix M associated with an eigenvalue λ is the collection

$$\left\{ \mathbf{v} \mid M\mathbf{v} = \lambda\mathbf{v} \right\} = \left\{ \mathbf{v} \mid (\lambda I - M)\mathbf{v} = \mathbf{0} \right\}$$

comprising all of the eigenvectors of M associated with λ and the zero vector (which is never an eigenvector).

- (iii) **Description of eigenvalues in terms of determinants:** A scalar λ is an eigenvalue of a square matrix M if and only if

$$\det(\lambda I - M) = 0.$$

- (iv) **The characteristic polynomial of a square matrix:** The expression $\det(\lambda I - M)$ is always a polynomial in λ and is called the *characteristic polynomial* of M . Thus the eigenvalues of a square matrix are precisely the roots of its characteristic polynomial.

- (v) **Finding eigenspaces:** Finding the eigenspace corresponding to the eigenvalue λ of a matrix M is equivalent to solving the homogeneous system with coefficient matrix $\lambda I - M$. After the eigenspace has been found, substituting particular values of the parameters yields particular eigenvectors.

- (vi) **Eigenvalues of a triangular matrix:** The eigenvalues of a triangular matrix are simply the diagonal entries.

- (vii) **The Cayley-Hamilton Theorem:** Every square matrix M is the root of its own characteristic polynomial, that is,

$$\chi(M) = 0,$$

where $\chi(\lambda) = \det(\lambda I - M)$ denotes the characteristic polynomial, $\chi(M)$ is the result of evaluating the matrix expression obtained from $\chi(\lambda)$ by substituting M for the indeterminate λ and I for the constant 1, and 0 denotes the zero matrix.

(viii) **Reflection matrices:** A *reflection matrix* in the real plane has the form

$$M = \begin{bmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{bmatrix}$$

for some real θ , and corresponds to reflection in the plane through a line through the origin making an angle θ with the positive x -axis. The eigenvalues of M are ± 1 . The eigenspace corresponding to 1 is the line of reflection. The eigenspace corresponding to -1 is the line through the origin perpendicular to the line of reflection.

(ix) **Rotation matrices:** A *rotation matrix* in the real plane has the form

$$M = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

for some real θ , and corresponds to rotation in the plane anticlockwise through an angle θ about the origin. The eigenvalues of M are the complex numbers

$$e^{i\theta} = \cos \theta \pm i \sin \theta$$

where $i = \sqrt{-1}$. The eigenvalues are real if and only if θ is an integer multiple of π , in which case all nonzero vectors are eigenvectors, corresponding to eigenvalue 1 if the integer multiple is even, and corresponding to -1 if the integer multiple is odd.

Questions labelled with an asterisk are suitable for students aiming for a distinction or higher.

Tutorial Exercises:

1. Find eigenvalues and eigenspaces for the following matrices, working over \mathbb{R} :

$$(a) \quad A = \begin{bmatrix} 2 & 0 \\ 1 & 1 \end{bmatrix} \quad (b) \quad B = \begin{bmatrix} 1 & 1 \\ -2 & 4 \end{bmatrix} \quad (c) \quad C = \begin{bmatrix} 1 & 1 \\ -1 & 3 \end{bmatrix}$$

2. Find eigenvalues and eigenspaces for the following matrices, working over \mathbb{R} :

$$(a) \quad A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & -1 \\ 0 & 0 & 3 \end{bmatrix} \quad (b) \quad B = \begin{bmatrix} 0 & 1 & 0 \\ -2 & 3 & 0 \\ 0 & 0 & 2 \end{bmatrix} \quad (c)^* \quad C = \begin{bmatrix} -7 & -2 & 6 \\ -2 & 1 & 2 \\ -10 & -2 & 9 \end{bmatrix}$$

3. Let A be a square matrix over a field F with eigenvalue λ . Prove the following implications:

$$(a) \quad A^2 = 0 \Rightarrow \lambda = 0 \quad (b) \quad A^2 = A \Rightarrow (\lambda = 0 \text{ or } \lambda = 1) \\ (c) \quad A^2 = I \Rightarrow (\lambda = 1 \text{ or } \lambda = -1)$$

4. Consider the group G of symmetries of a regular hexagon, generated by a rotation α one sixth of a turn and a reflection β .

- (a) Write out all of the elements of G as simply as possible. What happens if you reverse the order of the generators in each of the expressions that you found?
 (b) Evaluate $\beta\alpha^5\beta^5\alpha^{-3}\beta^{-3}\alpha^8\beta$ as simply as possible.
 (c)* Find a rotation matrix A and a reflection matrix B that together generate a group H in a one-one correspondence to G . Explain why matrix multiplication in H corresponds to composition of symmetries in G under this correspondence (thus exhibiting an *isomorphism* between H and G).

- 5.* Consider the permutations $\alpha = (1 \ 2 \ 3 \ 4 \ 5 \ 6)$ and $\beta = (1 \ 6)(2 \ 5)(3 \ 4)$. Verify that $\alpha^6 = \beta^2 = 1$ and $\beta^{-1}\alpha\beta = \alpha^{-1}$. Write out all permutations in $\langle\alpha, \beta\rangle$ using cycle notation. Find all $\gamma \in \text{Sym}(6)$ such that $\gamma^{-1}\alpha\gamma = \alpha^{-1}$. What do you notice?

6.* Consider the matrix $M = \begin{bmatrix} 2 & 2 & 4 \\ 2 & 5 & 8 \\ -1 & -2 & -3 \end{bmatrix}$.

- (a) Verify directly that $M^2 = 3M - 2I$ and that

$$\chi(\lambda) = \det(\lambda I - M) = (\lambda - 1)^2(\lambda - 2) = \lambda^3 - 4\lambda^2 + 5\lambda - 2.$$

- (b) What conclusion follows from the second part of (a) and the Cayley-Hamilton Theorem? How is this conclusion reconciled with the first part of (a)?
 (c) Prove by induction that, for all positive integers k ,

$$M^k = (2^k - 1)M + (2 - 2^k)I.$$

Now deduce this formula for all integers k .

- (d) Evaluate M^5 , M^{-1} and M^{-5} .

Further Exercises:

7. Consider the matrices

$$A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}, \quad B = \begin{bmatrix} \cos 2\phi & \sin 2\phi \\ \sin 2\phi & -\cos 2\phi \end{bmatrix}, \quad C = \begin{bmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{bmatrix}$$

for some $\theta, \phi \in \mathbb{R}$. Describe each of the following as simply as possible:

- | | | | | |
|-----------|-----------|--------------|-------------|-----------|
| (a) A^2 | (b) B^2 | (c) A^{-3} | (d) AB | (e) AC |
| (f) BA | (g) BC | (h) ABA | (i) BA^2B | (j) BAC |

8. Suppose that $M = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$. Verify that the characteristic polynomial of M is

$$\chi(\lambda) = \lambda^2 - (a + d)\lambda + ad - bc.$$

Now also verify that

$$M^2 - (a + d)M + (ad - bc)I = 0.$$

This verifies the Cayley-Hamilton Theorem directly for 2×2 matrices.

9. Let λ be an eigenvalue of a matrix M .

- (a) Show that λ^k is an eigenvalue of M^k for all positive integers k .
(b) Show that if M is invertible then λ is nonzero and λ^{-1} is an eigenvalue of M^{-1} .

- 10.* Working over \mathbb{C} , find the eigenspaces of a rotation matrix.

- 11.* Let A be a square matrix. Denote by A_{ij} the square matrix that results by deleting the i th row and j th column of A . Define the *adjugate matrix* $\text{adj} A$ to be the square matrix, of the same size as A , whose (j, i) -entry is $(-1)^{i+j} \det A_{ij}$. Quoting results about determinants, verify that

$$A(\text{adj} A) = (\text{adj} A)A = (\det A)I.$$

This proves that A is invertible if and only if $\det A \neq 0$, in which case $A^{-1} = \frac{1}{\det A} \text{adj} A$.

- 12.* Use the adjugate matrix to verify the following fact, known as *Cramer's Rule*: if M is an invertible $n \times n$ matrix and \mathbf{c} a column vector, then the equation $M\mathbf{x} = \mathbf{c}$ has a unique solution \mathbf{x} whose i th entry is

$$x_i = \frac{\det M_i}{\det M}$$

where M_i is the matrix obtained by replacing the i th column of M by \mathbf{c} . Use Cramer's Rule to solve the following system of equations:

$$\begin{array}{rrcr} 2x & + & 3y & + & 4z & = & -4 \\ 5x & + & 5y & + & 6z & = & -3 \\ 3x & + & y & + & 2z & = & -1 \end{array}$$