

# Linear Transformations on Cartesian Products

Recall: For a field  $F$  and natural number  $n \geq 0$ , the Cartesian power  $F^n$  is given by

$$F^n: \left\{ (a_1, a_2, \dots, a_n) \mid a_i \in F \right\}$$

We defined a linear map  $L: F^n \rightarrow F^m$  by

$$\textcircled{1} L(\underline{v} + \underline{w}) = L(\underline{v}) + L(\underline{w})$$

$$\textcircled{2} L(\lambda \underline{v}) = \lambda L(\underline{v}).$$

for all  $\underline{v}, \underline{w} \in F^n$ ,  $\lambda \in F$ .

• Examples:  $\textcircled{1} L_\theta: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$L_\theta(x, y) = (x \cos \theta - y \sin \theta, x \sin \theta + y \cos \theta)$$

— Rotation anticlockwise by angle  $\theta$

$$(2) S_{\theta}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$S_{\theta}(x, y) = (x \cos \theta + y \sin \theta, x \sin \theta - y \cos \theta)$$

- Reflection

- Importantly, we can represent these maps via matrices:

$$(1) L_{\theta}(x, y) = (x', y') \Leftrightarrow \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x' \\ y' \end{bmatrix}$$

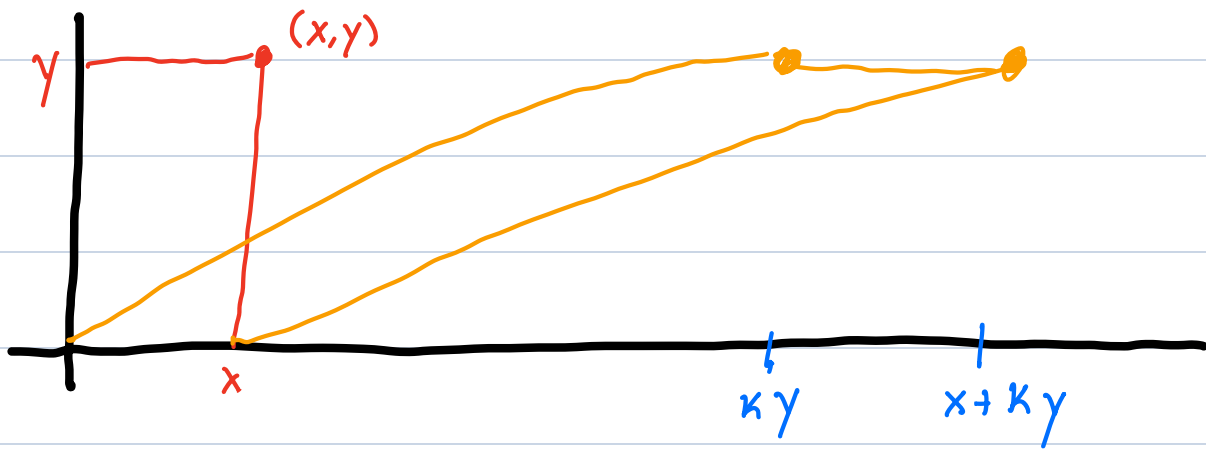
$$(1) S_{\theta}(x, y) = (x', y') \Leftrightarrow \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x' \\ y' \end{bmatrix}$$

### Example: Shear Transformations

Fix  $k \in \mathbb{R}$ . Define  $L: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by

$$L(x, y) = (x + ky, y)$$

- Geometrically:  $L$  fixes the  $y$ -coordinate, and shifts points horizontally by factor  $k$ .



• Put  $M = \begin{pmatrix} 1 & k \\ 0 & 1 \end{pmatrix}$ , shear matrix

$$\Rightarrow M \begin{bmatrix} x \\ y \end{bmatrix} = \begin{pmatrix} 1 & k \\ 0 & 1 \end{pmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x+ky \\ y \end{bmatrix}$$

So,  $M$  represents  $L$ .

**Example:** Let  $L: \mathbb{R}^3 \rightarrow \mathbb{R}^4$ , where

$$L(x, y, z) = (x+y+z, x-y-z, y+z, x-z)$$

Can compute:

$$L(1, 1, 2) = (4, -2, 3, -1)$$

$$L(0, 0, 1) = (1, -1, 1, -1)$$

$$L(0, 0, 0) = (0, 0, 0, 0)$$

In fact,  $L$  is a linear transformation (check this!)

Put  $M = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \\ 0 & 1 & 1 \\ 1 & 0 & -1 \end{pmatrix}$ . Then

$$M \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \\ 0 & 1 & 1 \\ 1 & 0 & -1 \end{pmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x+y+z \\ x-y-z \\ y+z \\ x-z \end{bmatrix}$$

• So,  $M$  represents  $L$ .

• This pattern of representing linear transformations by matrices is universal.

• **Theorem** Let  $L: F^m \rightarrow F^n$  be any map. Then  $L$  is a linear transformation iff there is an  $n \times m$  matrix  $M$  such that, for all  $(a_1, \dots, a_m) \in F^m$   
 $(b_1, \dots, b_n) \in F^n$ ,

$$L(a_1, \dots, a_m) = (b_1, \dots, b_n) \Leftrightarrow M \cdot \begin{bmatrix} a_1 \\ \vdots \\ a_m \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$



**Theorem** Let  $L: F^m \rightarrow F^n$  be any map. Then  $L$  is a linear transformation iff there is an  $n \times m$  matrix  $M$  such that, for all  $(a_1, \dots, a_m) \in F^m$   
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$$L(a_1, \dots, a_m) = (b_1, \dots, b_n) \text{ iff}$$

$$M \cdot \begin{bmatrix} a_1 \\ \vdots \\ a_m \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$

- We say  $M$  represents  $L$ .

Proof

$\Leftarrow$  Suppose we have an  $n \times m$  matrix  $M$  such that  
 $\otimes L(a_1, \dots, a_m) = (b_1, \dots, b_n) \text{ iff } M \cdot \begin{bmatrix} a_1 \\ \vdots \\ a_m \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}.$

We need to show that  $L$  is linear:

If  $L(\lambda(a_1, \dots, a_m) + \lambda'(a'_1, \dots, a'_m)) = (b_1, \dots, b_n)$ ,  
then want to show:  $\lambda L(a_1, \dots, a_m) + \lambda' L(a'_1, \dots, a'_m) = (b_1, \dots, b_n)$

By  $\otimes$ ,  $L(\lambda(a_1, \dots, a_m) + \lambda'(a'_1, \dots, a'_m)) = (b_1, \dots, b_n)$

$$\Rightarrow M(\lambda \begin{bmatrix} a_1 \\ \vdots \\ a_m \end{bmatrix} + \lambda' \begin{bmatrix} a'_1 \\ \vdots \\ a'_m \end{bmatrix}) = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}.$$

$$\Rightarrow = \lambda \underbrace{M \begin{bmatrix} a_1 \\ \vdots \\ a_m \end{bmatrix}} + \lambda' \underbrace{M \begin{bmatrix} a'_1 \\ \vdots \\ a'_m \end{bmatrix}} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$

By  $\otimes$ ,  $= L(a_1, \dots, a_m) = L(a'_1, \dots, a'_m).$

$$\Rightarrow \lambda L(a_1, \dots, a_m) + \lambda' L(a'_1, \dots, a'_m) = (b_1, \dots, b_n).$$

$\Rightarrow L$  is linear.



$\Rightarrow$  Suppose that  $L$  is linear. We need to construct a matrix  $M$  that represents  $L$ .

Write  $\underline{e}_j := (0, 0, \dots, 0, \overset{j\text{th place}}{\downarrow} 1, 0, 0, \dots, 0)$

So, for example

$$\underline{e}_1 = (1, 0, 0, \dots, 0)$$

$$\underline{e}_2 = (0, 1, 0, \dots, 0)$$

$$\underline{e}_3 = (0, 0, 1, 0, \dots, 0).$$

etc.

- We call  $\underline{e}_j$  a **standard basis vector**, and the collection  $\{\underline{e}_1, \underline{e}_2, \dots, \underline{e}_m\}$  the **standard basis** of  $F^m$ .

(We will discuss general notion of basis later...)

- For  $j=1, \dots, m$ , we know  $L(\underline{e}_j) \in F^n$ .

Write

$$L(\underline{e}_j) = (c_{1j}, c_{2j}, c_{3j}, \dots, c_{nj})$$

for some  $c_{1j}, c_{2j}, \dots, c_{nj} \in F$ .

$\uparrow$  Notice: putting index  $j$  in second position!

- Define a matrix with this data.

Put

$$M = \begin{pmatrix} c_{11} & c_{12} & \dots & c_{1m} \\ c_{21} & c_{22} & \dots & c_{2m} \\ c_{31} & c_{32} & \dots & c_{3m} \\ \vdots & \vdots & \ddots & \vdots \\ c_{n1} & c_{n2} & \dots & c_{nm} \end{pmatrix}$$

$n \times m$   $\leftarrow$

so the  $j^{\text{th}}$  column of  $M$  is  $\begin{bmatrix} c_{1j} \\ c_{2j} \\ \vdots \\ c_{nj} \end{bmatrix} \longleftrightarrow L(\underline{e}_j)$

• We now check that  $M$  represents  $L$ : first, note  $(a_1, \dots, a_m) = a_1 \underline{e}_1 + a_2 \underline{e}_2 + \dots + a_m \underline{e}_m$ .

so that by linearity

$$\begin{aligned} L(a_1, \dots, a_m) &= L(a_1 \underline{e}_1 + a_2 \underline{e}_2 + \dots + a_m \underline{e}_m) \\ &= a_1 L(\underline{e}_1) + a_2 L(\underline{e}_2) + \dots + a_m L(\underline{e}_m). \end{aligned}$$

$$= a_1 (c_{11}, c_{21}, \dots, c_{n1}) + a_2 (c_{12}, c_{22}, \dots, c_{n2})$$

$$+ \dots + a_m (c_{1m}, c_{2m}, \dots, c_{nm})$$

$$= \begin{pmatrix} a_1 c_{11} + a_2 c_{12} + \dots + a_m c_{1m}, a_1 c_{21} + a_2 c_{22} + \dots + a_m c_{2m}, \\ \dots, a_1 c_{n1} + a_2 c_{n2} + \dots + a_m c_{nm} \end{pmatrix}.$$

So,  $L(a_1, \dots, a_m) = (b_1, \dots, b_n)$  iff

$$\begin{cases} c_{11}a_1 + c_{12}a_2 + \dots + c_{1m}a_m = b_1 \\ c_{21}a_1 + c_{22}a_2 + \dots + c_{2m}a_m = b_2 \\ \vdots \\ c_{n1}a_1 + c_{n2}a_2 + \dots + c_{nm}a_m = b_n \end{cases}$$

But this system of equations is precisely

$$\begin{pmatrix} c_{11} & \dots & c_{1m} \\ c_{21} & & \vdots \\ \vdots & & \vdots \\ c_{n1} & \dots & c_{nm} \end{pmatrix} \begin{pmatrix} a_1 \\ \vdots \\ a_m \end{pmatrix} = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

$$\Rightarrow M \begin{bmatrix} a_1 \\ \vdots \\ a_m \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}.$$



• **Observation:** This proof gives a recipe for finding the matrix  $M$  which represents a linear transformation  $L: F^m \rightarrow F^n$

•  $L: F^m \rightarrow F^n$  then the  $j^{\text{th}}$  column of the  $n \times m$  matrix  $M$  corresponds to  $L(\underline{e}_j)$ .

• **Example:**  $L: \mathbb{R}^4 \rightarrow \mathbb{R}^3$  where

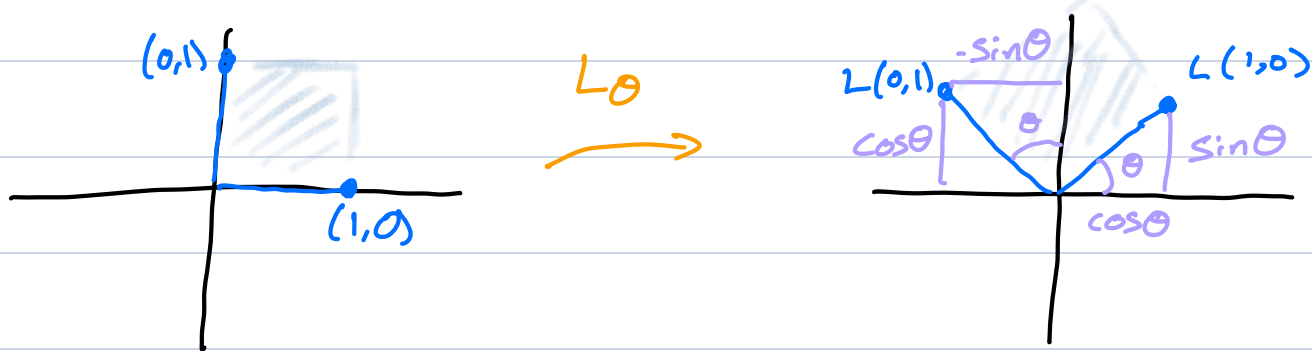
$$L(x, y, z, w) = (5x + 2y - z + 3w, x - y + 2z, x + y - 4w).$$

Find  $M$ .

- $L(1, 0, 0, 0) = (5, 1, 1)$
- $L(0, 1, 0, 0) = (2, -1, 1)$
- $L(0, 0, 1, 0) = (-1, 2, 0)$
- $L(0, 0, 0, 1) = (3, 0, -4)$

$$\Rightarrow M = \begin{pmatrix} 5 & 2 & -1 & 3 \\ 1 & -1 & 2 & 0 \\ 1 & 1 & 0 & -4 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} 5x + 2y - z + 3w \\ \vdots \\ \vdots \end{pmatrix}$$

• Example: Rotation matrices in  $\mathbb{R}^2$

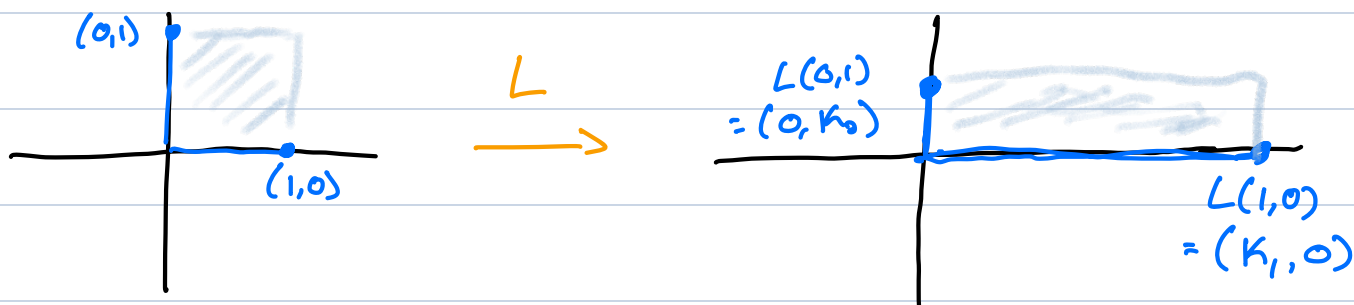


$$L_\theta(1,0) = (\cos\theta, \sin\theta)$$
$$L_\theta(0,1) = (-\sin\theta, \cos\theta)$$

$$\Rightarrow M = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}, \text{ as expected.}$$

• Example: Scaling in  $\mathbb{R}^2$ :

$L: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by scaling the x-axis  
by factor  $k_1$ , and the y-axis  
by factor  $k_2$ :



$$L(1,0) = (k_1, 0)$$

$$L(0,1) = (0, k_2)$$

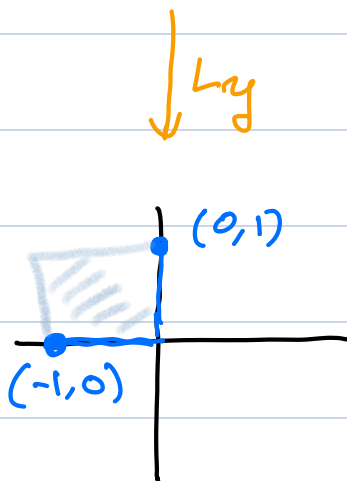
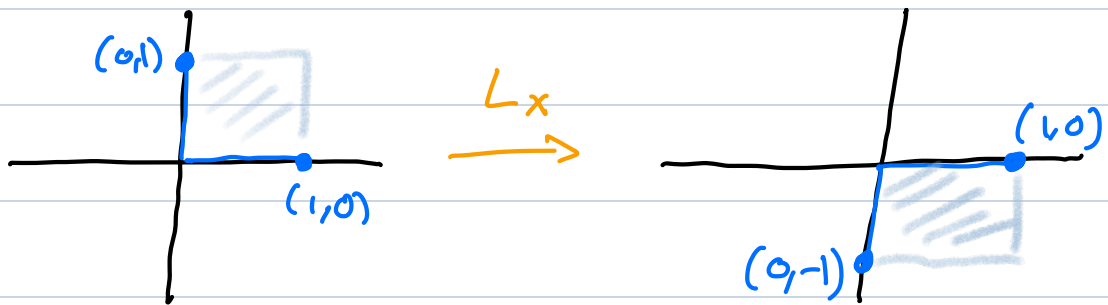
$$\Rightarrow M = \begin{pmatrix} k_1 & 0 \\ 0 & k_2 \end{pmatrix} \text{ represents } L.$$

• **Exercise:** Axis Reflection in  $\mathbb{R}^2$ :

Find matrices representing

$L_x$ : reflect across x-axis

$L_y$ : reflect across y-axis



•  $L_x$  is represented by

$$M_x = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

•  $L_y$  is represented by

$$M_y = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}.$$

• Notice: "negative scaling"  $\leftrightarrow$  reflect + scale.