CS 446/ECE 449: Machine Learning

Lecture 6: Kernel Methods

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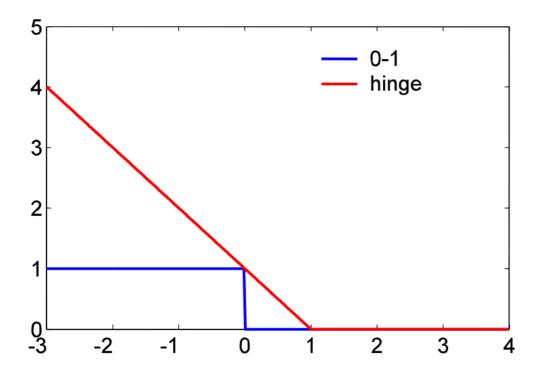
Recap: Support Vector Machine

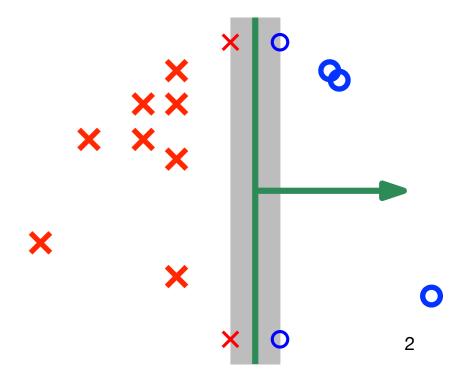
Max-margin principle: (Vapink' 82): choose w that maximizes the margin (distance to the closest data point)

Support vector machines:

Support vector machines:
$$\min_{w \in \mathbb{R}^d} \sum_{i \in [n]} \mathcal{C}_{\text{hinge}}(y^{(i)} \cdot w^{\mathsf{T}} x^{(i)}) + \frac{\lambda}{2} \|w\|_2^2,$$
 where $\mathcal{C}_{\text{hinge}}(t) := \max\{0, 1 \mid t\}$ is called the hinge-loss
$$l_2 \text{ regularization of } w$$

Hinge loss





Recap: Support Vector Machine

Comparisons:

- E: supervised
- T: linear prediction
- P: zero-one, hinge, logistic, squared

Regularized linear regression (Ridge regression):
$$\min_{w \in \mathbb{R}^d} \sum_{i \in [n]} (y^{(i)} - w^{\mathsf{T}} x^{(i)})^2 + \frac{\lambda}{2} ||w||_2^2,$$

Regularized logistic regression:

$$\min_{w \in \mathbb{R}^d} \sum_{i \in [n]} \ell_{\log}(y^{(i)} \cdot w^{\mathsf{T}} x^{(i)}) + \frac{\lambda}{2} ||w||_2^2,$$

Support vector machines:

$$\min_{w \in \mathbb{R}^d} \sum_{i \in [n]} \mathcal{\ell}_{\text{hinge}}(y^{(i)} \cdot w^{\mathsf{T}} x^{(i)}) + \frac{\lambda}{2} \|w\|_2^2,$$

Lecture Today

- Support Vector Machine (dual)
- Kernel Method

Recall: given a linearly separable data for binary classification, our objective function of optimizing (hard-margin) SVM looks like follows:

$$\min_{w \in \mathbb{R}^d} \frac{1}{2} ||w||_2^2, \quad \text{s.t.} \quad y^{(i)} w^{\mathsf{T}} x^{(i)} \ge 1, \ \forall i \in [n]$$

Note:

- This is an instance of the so-called "Quadratic Program", which belongs to convex problems
- Every convex program has a corresponding dual program
 - Clarifies the role of support vectors
 - Leads to a nice nonlinear approach: "kernel trick"
 - Gives another choice for optimization algorithms to solve for SVMs

Recall: given a linearly separable data for binary classification, our objective function of optimizing (hard-margin) SVM looks like follows:

$$\min_{w \in \mathbb{R}^d} \frac{1}{2} ||w||_2^2$$
s.t.
$$y^{(i)} w^{\mathsf{T}} x^{(i)} \ge 1, \ \forall i \in [n]$$

How to obtain the corresponding dual program?

Key idea: introduce a dual variable $\alpha_i \geq 0$ for each of the constraint

- Interpretation of α_i : the "price" to pay if the corresponding constraint is violated
- With the dual variables, we can equivalently transform a constrained opt. to an unconstrained one

Recall: given a linearly separable data for binary classification, our objective function of optimizing (hard-margin) SVM looks like follows:

$$\min_{w \in \mathbb{R}^{d}} \quad \frac{1}{2} \|w\|_{2}^{2}$$
s.t. $y^{(i)}w^{T}x^{(i)} \ge 1, \ \forall i \in [n]$

$$\min_{w \in \mathbb{R}^{d}} \max_{\alpha \in \mathbb{R}^{n}_{+}} \quad \frac{1}{2} \|w\|_{2}^{2} + \sum_{i \in [n]} \alpha_{i} \left(1 - y^{(i)}w^{T}x^{(i)}\right)$$

Claim: the optimal solutions of these two problems are the same (why?)

Recall: given a linearly separable data for binary classification, our objective function of optimizing (hard-margin) SVM looks like follows:

$$\min_{w \in \mathbb{R}^{d}} \quad \frac{1}{2} \|w\|_{2}^{2}$$
s.t. $y^{(i)}w^{T}x^{(i)} \ge 1, \forall i \in [n]$

$$\min_{w \in \mathbb{R}^{d}} \max_{\alpha \in \mathbb{R}^{n}_{+}} \quad \frac{1}{2} \|w\|_{2}^{2} + \sum_{i \in [n]} \alpha_{i} \left(1 - y^{(i)}w^{T}x^{(i)}\right)$$

Let's consider two cases:

- If the *i*-th constraint holds, i.e., $1 y^{(i)} w^{\top} x^{(i)} \le 0$, then $\alpha_i^* = 0$
- If the *i*-th constraint is violated, i.e., $1 y^{(i)} w^{\top} x^{(i)} > 0$, then $\alpha_i^* \to \infty$

The Lagrangian $\mathcal{L}(w, \alpha)$:

$$\min_{w \in \mathbb{R}^d} \max_{\alpha \in \mathbb{R}^n_+} \quad \mathcal{L}(w, \alpha) := \frac{1}{2} \|w\|_2^2 + \sum_{i \in [n]} \alpha_i \left(1 - y^{(i)} w^{\mathsf{T}} x^{(i)}\right)$$

The dual variables α_i are also called the Lagrange multipliers

In general, for an arbitrary function f(x, y), we have the following relationship holds, known as "weak duality":

$$\min_{x} \max_{y} f(x, y) \ge \max_{y} \min_{x} f(x, y)$$

Can understand this inequality from a game-theoretic perspective:

- There are two players x, y for a one-shot, zero-sum game, with payoff f(x, y)
- Player *x* would like to minimize the payoff
- Player y would like to maximize the payoff
- LHS = Player x goes first then player y
- The minimax inequality holds due to "second-mover advantage"

The Lagrangian $\mathcal{L}(w, \alpha)$:

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$$\min_{x} \max_{y} f(x, y) \ge \max_{y} \min_{x} f(x, y)$$

For convex problems with affine constraints, "strong duality" holds:

$$\min_{x} \max_{y} f(x, y) = \max_{y} \min_{x} f(x, y)$$

Hence,

$$\min_{w \in \mathbb{R}^d} \max_{\alpha \in \mathbb{R}^n_+} \mathcal{L}(w, \alpha) = \max_{\alpha \in \mathbb{R}^n_+} \min_{w \in \mathbb{R}^d} \mathcal{L}(w, \alpha)$$

The Lagrangian $\mathcal{L}(w, \alpha)$:

$$\min_{w \in \mathbb{R}^d} \max_{\alpha \in \mathbb{R}^n_+} \quad \mathcal{L}(w, \alpha) := \frac{1}{2} \|w\|_2^2 + \sum_{i \in [n]} \alpha_i \left(1 - y^{(i)} w^\mathsf{T} x^{(i)}\right)$$

The dual variables α_i are also called the Lagrange multipliers. We can then define the following primal and dual problems:

Primal problem:
$$P(w) := \max_{\alpha \in \mathbb{R}^n_+} \mathscr{L}(w, \alpha)$$

_ Dual problem:
$$D(\alpha) := \min_{w \in \mathbb{R}^d} \mathcal{L}(w, \alpha)$$

By strong duality, we have

$$\min_{w \in \mathbb{R}^d} P(w) = \max_{\alpha \in \mathbb{R}^n_+} D(\alpha)$$

The dual problem $D(\alpha)$:

$$\min_{w \in \mathbb{R}^d} \frac{1}{2} \|w\|_2^2 + \sum_{i \in [n]} \alpha_i \left(1 - y^{(i)} w^{\mathsf{T}} x^{(i)}\right)$$

For any fixed $\alpha \in \mathbb{R}^n_+$, we can first solve the internal optimization problem w.r.t. w, which is an unconstrained quadratic problem.

Setting the gradient to 0:

$$\nabla_{w} \left(\frac{1}{2} \|w\|_{2}^{2} + \sum_{i \in [n]} \alpha_{i} \left(1 - y^{(i)} w^{\mathsf{T}} x^{(i)} \right) \right) = 0$$

we have

$$w = \sum_{i \in [n]} \alpha_i y^{(i)} x^{(i)}$$

The dual problem $D(\alpha)$:

$$D(\alpha) = \min_{w \in \mathbb{R}^d} \frac{1}{2} ||w||_2^2 + \sum_{i \in [n]} \alpha_i \left(1 - y^{(i)} w^{\mathsf{T}} x^{(i)} \right)$$

Plugging $w = \sum_{i \in [n]} \alpha_i y^{(i)} x^{(i)}$ into the above dual problem, we have

$$D(\alpha) = \sum_{i \in [n]} \alpha_i - \frac{1}{2} \sum_{i,j \in [n]} \alpha_i \alpha_j y^{(i)} y^{(j)} x^{(i)\top} x^{(j)}$$
$$= \mathbf{1}_n^{\top} \alpha - \frac{1}{2} \alpha^{\top} K \alpha$$

where $\mathbf{1}_n \in \mathbb{R}^n$ is a all-one vector of dim-n, and $K \in \mathbb{R}^{n \times n}$ with $K_{ij} := \left(y^{(i)} x^{(i)}\right)^{\top} \left(y^{(j)} x^{(j)}\right)$.

The dual problem $D(\alpha)$:

$$\max_{\alpha \in \mathbb{R}^n_+} D(\alpha) = \sum_{i \in [n]} \alpha_i - \frac{1}{2} \sum_{i,j \in [n]} \alpha_i \alpha_j y^{(i)} y^{(j)} x^{(i)\top} x^{(j)} = \mathbf{1}_n^\top \alpha - \frac{1}{2} \alpha^\top K \alpha$$

Note:

- The dual optimization problem w.r.t. α is still a quadratic program
- In the primal problem P(w), $w \in \mathbb{R}^d$ is the optimization variable
- In the dual problem $D(\alpha)$, $\alpha \in \mathbb{R}^n_+$ is the optimization variable
- Both the primal and the dual problems have affine constraints
- Similar to the primal problem, we can use off-the-shelf convex solvers to find the optimal α^*

Once we have the optimal α^* , we can recover the optimal w^* with

$$w^* = \sum_{i \in [n]} \alpha_i^* y^{(i)} x^{(i)}$$

The dual problem $D(\alpha)$:

$$\max_{\alpha \in \mathbb{R}^n_+} D(\alpha) = \sum_{i \in [n]} \alpha_i - \frac{1}{2} \sum_{i,j \in [n]} \alpha_i \alpha_j y^{(i)} y^{(j)} x^{(i)\top} x^{(j)} = \mathbf{1}_n^{\top} \alpha - \frac{1}{2} \alpha^{\top} K \alpha$$

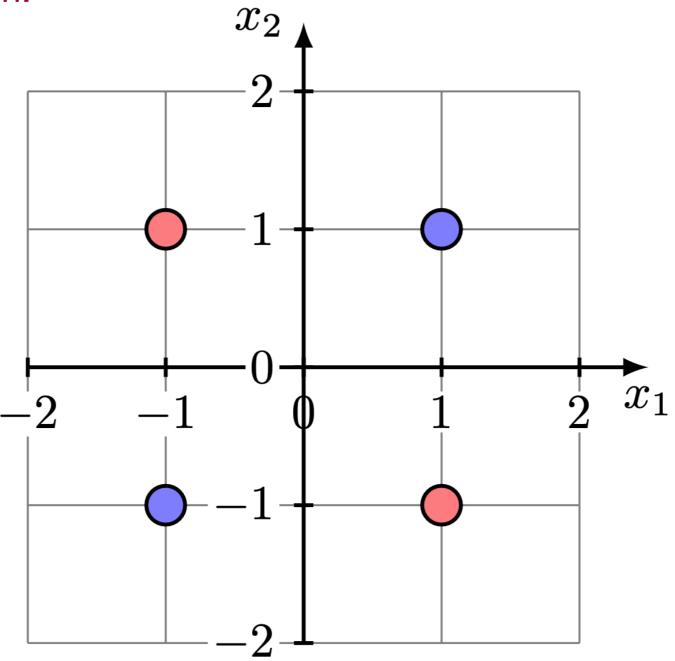
Once we have the optimal α^* , we can recover the optimal w^* with

$$w^* = \sum_{i \in [n]} \alpha_i^* y^{(i)} x^{(i)}$$

- The optimal normal vector w^* is a linear combination of $y^{(i)}x^{(i)}$
- Only the ones with $\alpha_i^* > 0$ contributes to w^*
- The point $y^{(i)}x^{(i)}$ with $\alpha_i^*>0$ are called support vectors
- In fact, with $\alpha_i^* > 0$, we must have $y^{(i)}w^\top x^{(i)} = 1$ (due to the so-called **complementary slackness** condition), which coincides with our geometric definition of support vectors as well.
- Dual solutions and support vectors are not necessarily unique (even if the primal solution is unique)

But, the dual problem formulation is still a hard-margin linear SVM

The XOR problem:



Think: not possible to perfectly classify the XOR problem with linear predictors

Key idea: feature mapping/lifting

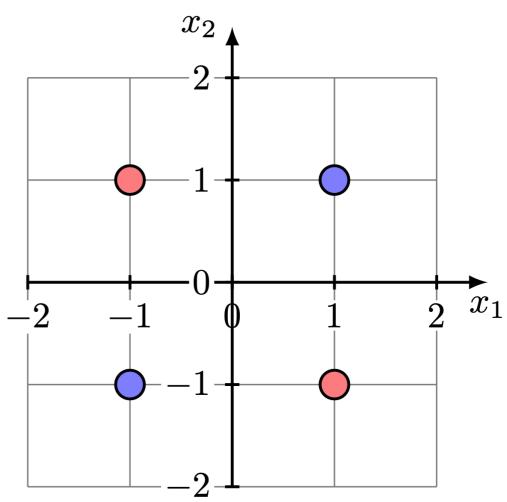
$$\phi : \mathbb{R}^2 \to \mathbb{R}^3$$
 $(x_1, x_2) \to (x_1, x_2, x_1 x_2)$

Under this feature map $\phi(\cdot)$, the XOR problem becomes:

Finding a linear classifier $w \in \mathbb{R}^3$ that correctly predicts the following 4 points:

- -(1,1,1)
- -(1,-1,-1)
- -(-1,1,-1)
- -(-1,-1,1)

One potential solution: $w^* = (0,0,1)$



Key idea: feature map $\phi(\,\cdot\,):\mathbb{R}^d o \mathbb{R}^p$

The primal optimization problem of hard-margin SVM under ϕ :

$$\min_{w \in \mathbb{R}^d} \frac{1}{2} ||w||_2^2
\text{s.t.} y^{(i)} w^{\mathsf{T}} \phi(x^{(i)}) \ge 1, \ \forall i \in [n]$$

Now the search space has p dimensions, and potentially $p \gg d$. In the case of $p = \infty$, we cannot solve the primal explicitly. How about the dual?

$$\begin{aligned} \max_{\alpha \in \mathbb{R}^n_+} D(\alpha) &= \sum_{i \in [n]} \alpha_i - \frac{1}{2} \sum_{i,j \in [n]} \alpha_i \alpha_j y^{(i)} y^{(j)} \phi(x^{(i)})^\top \phi(x^{(j)}) \\ &= \mathbf{1}_n^\top \alpha - \frac{1}{2} \alpha^\top K \alpha \end{aligned}$$

where $\mathbf{1}_n \in \mathbb{R}^n$ is a all-one vector of dim-n, and $K \in \mathbb{R}^{n \times n}$ with $K_{ii} := \left(y^{(i)}\phi(x^{(i)})\right)^{\top} \left(y^{(j)}\phi(x^{(j)})\right)$.

Key idea: feature map $\phi(\,\cdot\,):\mathbb{R}^d\to\mathbb{R}^p$

Dual form of hard-margin SVM under the feature map ϕ :

$$\max_{\alpha \in \mathbb{R}^n_+} D(\alpha) = \sum_{i \in [n]} \alpha_i - \frac{1}{2} \sum_{i,j \in [n]} \alpha_i \alpha_j y^{(i)} y^{(j)} \phi(x^{(i)})^\top \phi(x^{(j)})$$
$$= \mathbf{1}_n^\top \alpha - \frac{1}{2} \alpha^\top K \alpha$$

- The dual form never needs $\phi(x) \in \mathbb{R}^p$ explicitly, but only $\phi(x)^{\mathsf{T}}\phi(x') \in \mathbb{R}$
- Kernel trick: replace every $\phi(x)^{T}\phi(x')$ with kernel evaluation k(x, x')
- Sometimes, k(x, x') is much cheaper than $\phi(x)^{\mathsf{T}}\phi(x')$
- The idea started with SVM, but appears in many other linear models as well
- Downside: we need to explicitly maintain the kernel matrix $K \in \mathbb{R}^{n \times n}$, which could be expensive if n is large

Key idea: feature map $\phi(\,\cdot\,):\mathbb{R}^d \to \mathbb{R}^p$

Kernel example: affine features $\phi: \mathbb{R}^d \to \mathbb{R}^{d+1}$ with

$$\phi(x) = (1, x_1, ..., x_d)$$

Kernel form:

$$k(x, x') = \phi(x)^{\mathsf{T}} \phi(x') = 1 + x^{\mathsf{T}} x'$$

Key idea: feature map $\phi(\,\cdot\,):\mathbb{R}^d o\mathbb{R}^p$

Kernel example: quadratic features $\phi:\mathbb{R}^d o \mathbb{R}^p$ with

HW1:
$$\phi(x) = ?$$

Kernel form:

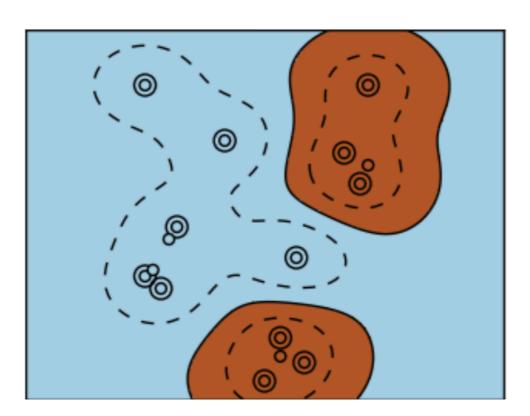
$$k(x, x') = \phi(x)^{\mathsf{T}} \phi(x') = (1 + x^{\mathsf{T}} x')^2$$

Radial Basis Function kernel (RBF kernel, Gaussian kernel):

For any $\sigma > 0$, there is an infinite-dim feature map $\phi : \mathbb{R}^d \to \mathbb{R}^\infty$ such that

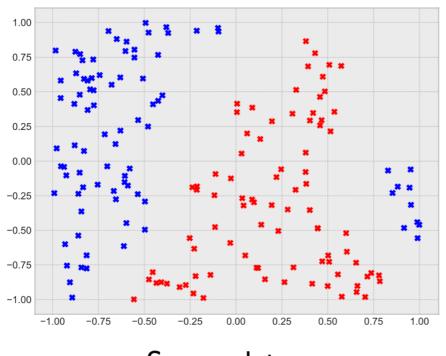
$$k(x, x') = \phi(x)^{\mathsf{T}} \phi(x') = \exp\left(-\frac{\|x - x'\|_2^2}{2\sigma^2}\right)$$

Note: despite the infinite-dim expansion, the kernel evaluation could be computed in O(d) time

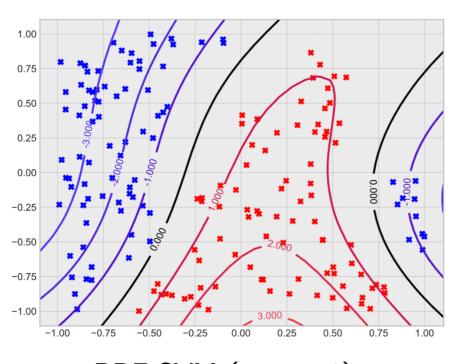


Intuition: kernel computes the similarity between data points

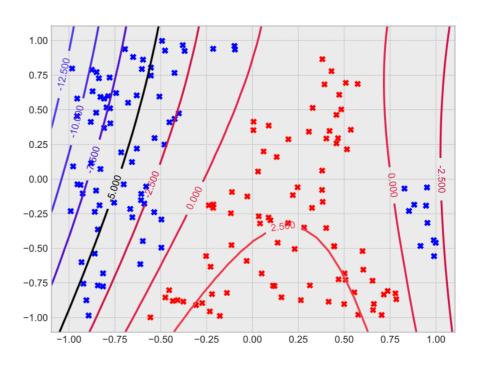
Radial Basis Function kernel (RBF kernel, Gaussian kernel):



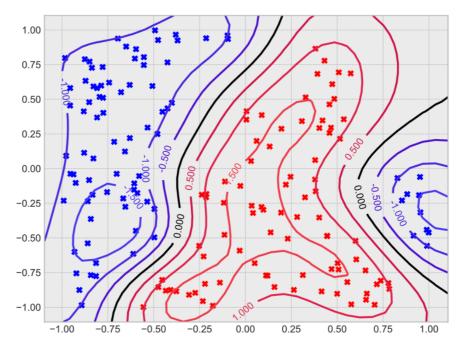
Source data.



RBF SVM ($\sigma = 1$).



Quadratic SVM.



RBF SVM ($\sigma = 0.1$).

Next Time

- Decision Trees
- Random Forests