Propeller Loader

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# Introduction

The Propeller Loader, propeller-load, is a command line program you use to load programs generated by the PropGCC toolchain into a Propeller board over a serial connection from a PC running Windows, Mac OS x, or Linux. It can also load Spin binary programs generated by programs like the Propeller Tool or BST.

# Options

## -b <type> Select target board

Use this option to select the target board type. This determines which board configuration file is used. If this option is not specified, the value of the environment variable *PROPELLER\_LOAD\_BOARD* is used. If that environment variable is not defined, the “default” board type is used. The configuration file for the selected board type is located by first looking in

* the directory containing the file being loaded
* the directory given in the environment variable *PROPELLER\_LOAD\_PATH*
* the directory containing the propeller-load program
* the directory /opt/parallax/propeller-load

Example

-b c3

This will select the *c3.cfg* board configuration file.

## -D <var>=<value> Define a board configuration variable

Use this option to define or redefine a configuration variable. The loader will use values set using the –D option instead of the corresponding values from the selected board configuration file. The –D option can also be used to define new variables that are not in the board configuration file. This could be useful if the program being loaded makes use of the values of these additional variables through the loader’s variable patching facility.

Example

-D baudrate=9600

This will use 9600 as the baud rate overriding the value for *baudrate* in the selected configuration file.

## -e Write the program into EEPROM

Use this option to write the program being loaded to EEPROM. This option works differently depending on the type of program being loaded.

If a COG or LMM program is being loaded, the entire program is written to the EEPROM.

If an XMM program is being loaded, only a loader is written to EEPROM. The program itself is written to external memory. This requires that the external memory be non-volatile. In other words, it must be flash memory.

## -f Write a file to the SD card

Use this option to write a file to an SD card inserted in the target board. If this option is given then no program is loaded. The only action is to write a file to the SD card.

Example

-f myprog.pex

## -I <path> Add a directory to the include path

Use this option to add a directory to the include path. This is the path that the loader uses to locate board configuration files. The directories specified using the –I option will be searched before the standard directories.

Example

-I foo/bar

## -l Write a program to the SD card and use the SD loader

Use this option to load code that can load the program *autorun.pex* from the root directory on the SD card into external memory. If a filename is given in the command, that file will be written to the SD card as *autorun.pex.* It should be an XMM program.

Examples

-l

Load code to load the program *autorun.pex* which should already be on the SD card

-l myprog.elf

Write the program myprog.elf to the SD card as *autorun.pex* and load code to load it from the SD card.

## –P List available serial ports

Use this option to list all serial ports. Not all of the ports listed will necessarily be connected to boards containing Propeller chips.

## -p <port> Select serial port

Use this option to select the serial port that is connected to the Propeller board you wish to load. If this option is not specified and the environment variable *PROPELLER\_LOAD\_PORT* is defined, it’s value is used. If it is not defined, the loader will search for ports attached to a Propeller board. The first one found is used.

## -q Quit on the exit sequence

Use this option to cause propeller-load to exit terminal mode when it receives the byte sequence (0xff, 0x00, status) from the target board. This is primarily intended for use in automated test scripts.

## -r Run the program after loading

Use this option to start the program running after loading has completed.

## –S or –S<n> Slow down the loader by adding a delay

Use this option to introduce a time delay during the initial phase of loading that uses the Propeller boot protocol. If *<n>* is not given, a delay of 5ms is used. The *<n>* must be immediately adjacent to the –S with no intervening space.

Examples

-S

This will cause a delay of 5ms to be used.

-S12

This will cause a delay of 12ms to be used.

## -s Write a spin .binary file for use with the Propeller Tool

Use this option to write a Spin .binary file for use with the Propeller Tool or any other loader that can handle the Spin binary format.

Example

-s myprog.elf

This will write myprog.binary.

## -t or –t<baud> Enter terminal mode after running the program

Use this option to cause the loader to enter a simple terminal emulator after loading is complete. If *<baud>* is given the baud rate is changed to this value before entering terminal mode. The *<baud>* must be immediately adjacent to the –t with no intervening space.

## -v Verbose output

Use this option to produce more verbose progress information.

## -x Write a .pex binary file for use with the SD loader or SD cache

Use this option to write a Propeller executable file (.pex). This file can then be transferred to an SD card to be run using either the –z or –l option.

Example

-x myprog.elf

This will read the program myprog.elf and write myprog.pex.

## -z Write a program to the sd card and use the SD cache

Use this option to load code that can run the program *autorun.pex* from the root directory on the SD card. If a filename is given in the command, that file will be written to the SD card as *autorun.pex.* It should be an XMM program.

Examples

-z

Load code to run the program *autorun.pex* which should already be on the SD card

-z myprog.elf

Write the program myprog.elf to the SD card as *autorun.pex* and load code to run it from the SD card.

## -? Display a usage message and exit

Use this option or just invoke propeller-load with no parameters to display a short usage message.

<name> elf or spin binary file to load

Target board type can be either a single identifier like 'propboe' in which case the subtype

defaults to 'default' or it can be of the form <type>:<subtype> like 'c3:ram'.

Variables that can be set with -D are:

* clkfreq
* clkmode
* baudrate
* reset
* rxpin
* txpin
* tvpin
* cache-driver
* cache-size
* cache-param1
* cache-param2
* sd-driver
* sdspi-do
* sdspi-clk
* sdspi-di
* sdspi-cs
* sdspi-clr
* sdspi-inc
* sdspi-start
* sdspi-width
* spdspi-addr
* sdspi-config1
* sdspi-config2
* eeprom-first

# Expressions

Value expressions for -D can include:

* rcfast
* rcslow
* xinput
* xtal1
* xtal2
* xtal3
* pll1x
* pll2x
* pll4x
* pll8x
* pll16x
* k
* m
* mhz
* true
* false

an integer or two operands with a binary operator + - \* / % & | or unary + or -

all operators have the same precedence

# Variable Patching

int \_cfg\_baudrate = -1;