

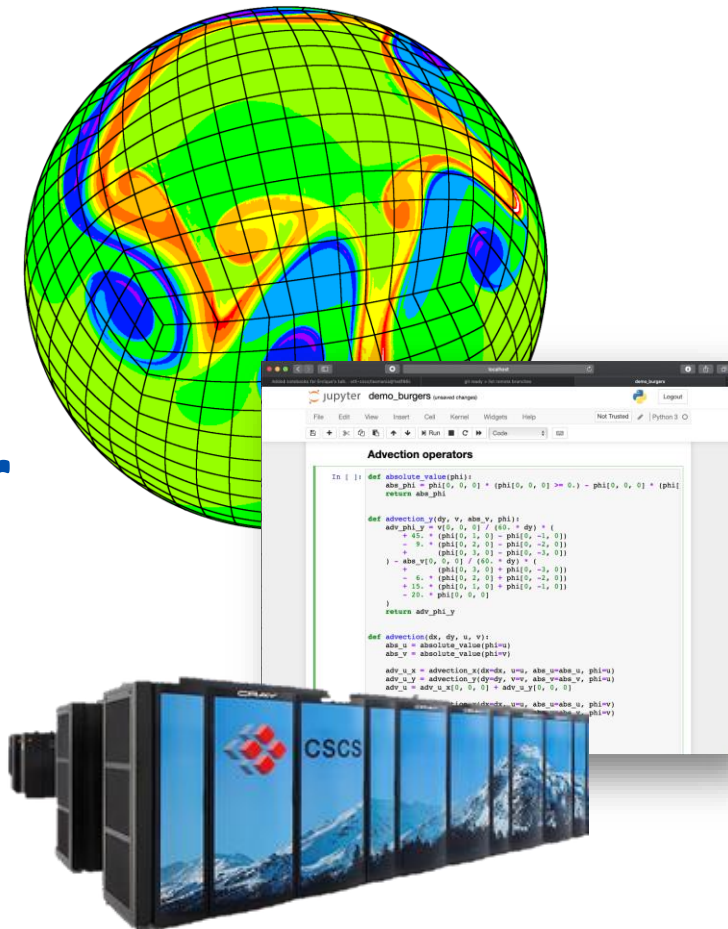
# High Performance Computing for Weather and Climate (HPC4WC)

Content: Pace: A model in Python

Lecturer: Tobias Wicky

Block course 701-1270-00L

Summer 2022



# Learning Goal

- See the DSL approach in action
- See some of the concepts we've learned applied in a real code

# Who are we?



Oliver  
Fuhrer



Johann  
Dahm



Florian  
Deconinck



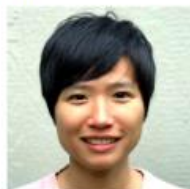
Oliver  
Elbert



Jeremy  
McGibbon



Tobias  
Wicky



Elynn Wu

## Collaborators



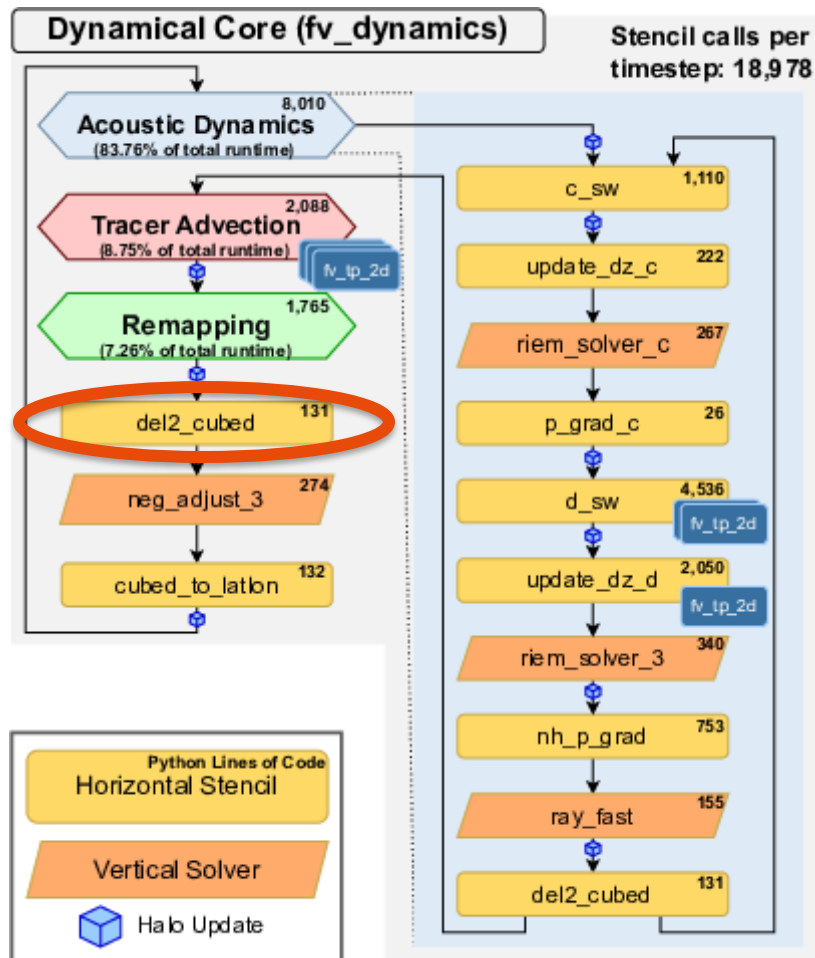
# Pace: Python based FV3

## GFDL Finite-Volume Cubed-Sphere Dynamical Core (FV3)

Finite volume transport on a cubed sphere  
grid

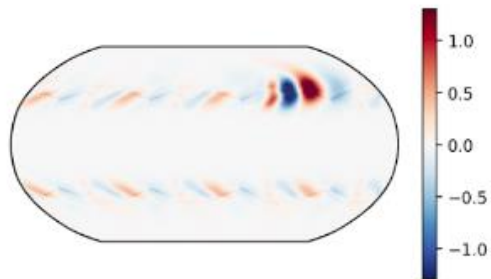


- Integrated into several models, including
  - Operational weather models (Global Forecast System)
  - Next Generation Global Prediction System

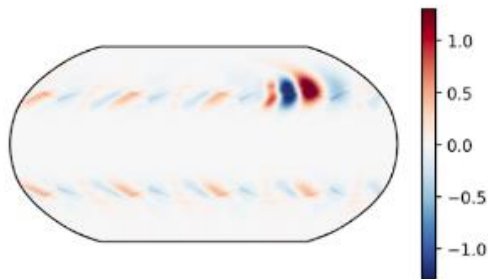


# Validation

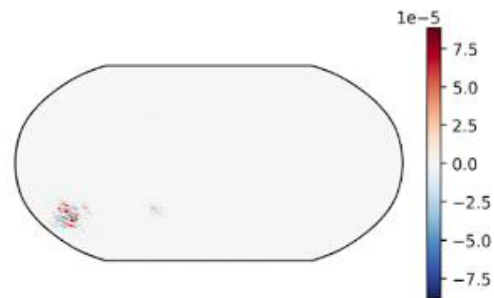
Fortran



GT4Py

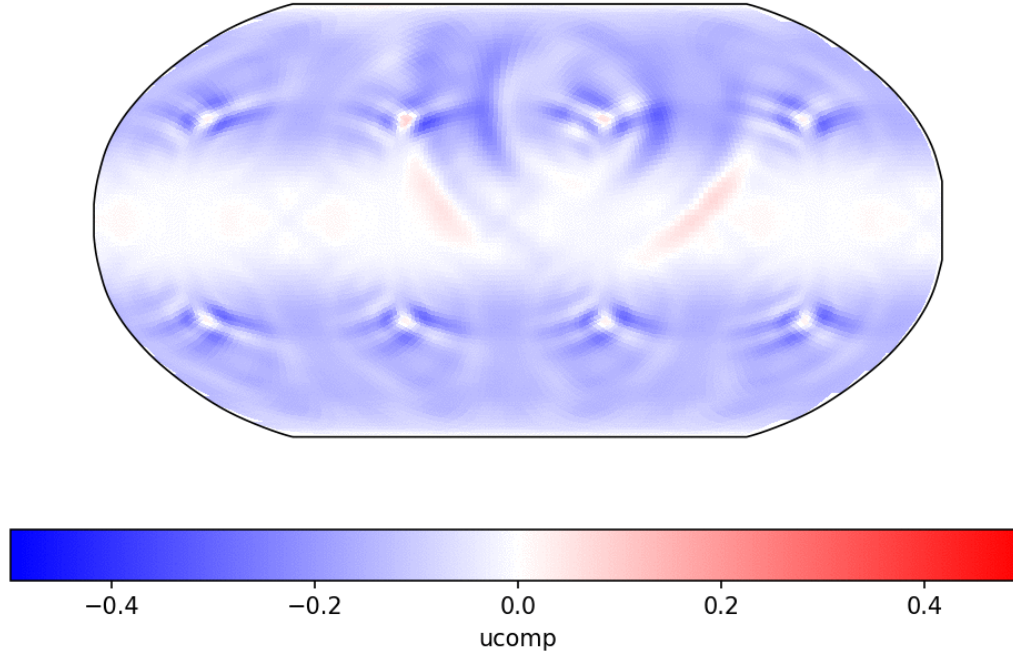


Difference













# Validation

Diff from init with heat source fix c48 6ranks: ucomp, z=40, t=6hr



Generated on 06/01/22 20:10:45

# Physical Parametrizations

	Microphysics	PBL & Turbulence	Sea-Ice	Shallow Convection	LSM	Radiation
Authors	 Mikael	 Chris Kung (NASA)	 Vera  Nadja  Nicolai	 Mikael  Chenwei  Langwen	 Safira	 Andrew
Scheme	GFDL Cloud Microphysics Scheme	GFS scale-aware EDMF PBL and Free Atmospheric Turbulence Scheme	GFS Sea Ice Scheme	GFS SAS-based Mass-Flux Scheme for Shallow convection	GFS Noah Land Surface Model	GFS RRTMG

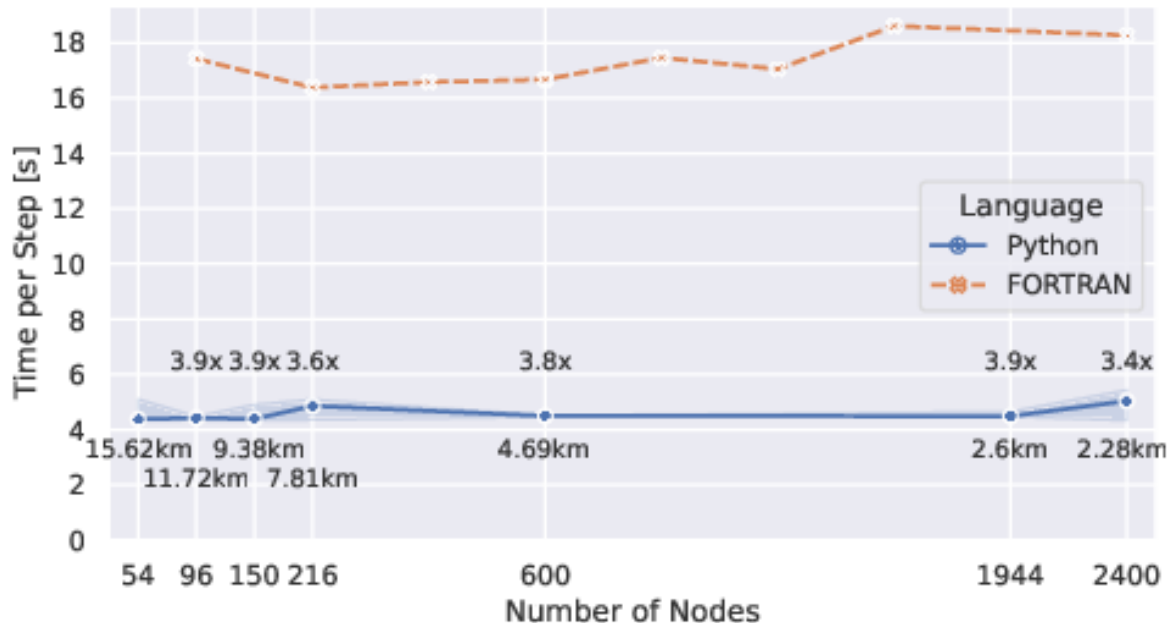
# The Pace Model

Full program optimization

DSL coverage of all main numerical computation

Custom code for halo updates

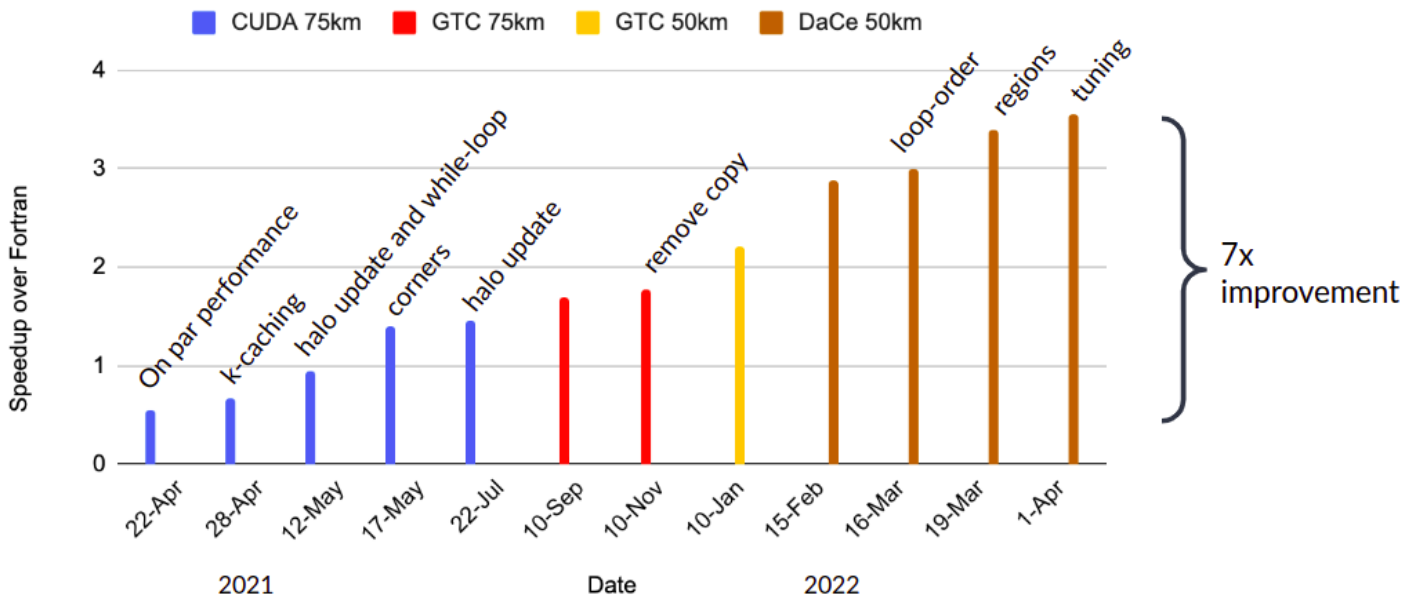
New DSL concepts for FV3-specific motifs





# The Pace Model

GPU Performance - 6 Node



# Why did you torture us for 4 days?

DSL still uses these concepts under the hood

```
def visit_Stencil(self, node: oir.Stencil, **kwargs: Any) -> oir.Stencil:
    write_before_read_tmps = {
        symbol
        for symbol, value in kwargs["syntable"].items()
        if isinstance(value, oir.Temporary)
    }
    horizontal_executions = node.iter_tree().if_isinstance(oir.HorizontalExecution)

    for horizontal_execution in horizontal_executions:
        accesses = AccessCollector.apply(horizontal_execution)
        offsets = accesses.offsets()
        ordered_accesses = accesses.ordered_accesses()

        def write_before_read(tmp: str) -> bool:
            if tmp not in offsets:
                return True
            if offsets[tmp] != {(0, 0, 0)}:
                return False
            return next(
                o.is_write and o.horizontal_mask is None
                for o in ordered_accesses
                if o.field == tmp
            )

        write_before_read_tmps = {
            tmp for tmp in write_before_read_tmps if write_before_read(tmp)
        }

    return super().visit_Stencil(node, tmps_to_replace=write_before_read_tmps, **kwargs)
```

# Why did you torture us for 4 days?

There are things that we still need to do manually:

E.g. Halo updates

```
)  
  
# Post recv MPI order  
with self._timer.clock("Irecv"):  
    self._recv_requests = []  
    for to_rank, transformer in self._transformers.items():  
        self._recv_requests.append(  
            self._comm.comm.Irecv(  
                transformer.get_unpack_buffer().array,  
                source=to_rank,  
                tag=self._tag,  
            )  
        )  
    )
```

```
# Pack quantities halo points data into buffers | FlorianDeco  
with self._timer.clock("pack"):  
    for transformer in self._transformers.values():  
        transformer.async_pack(quantities_x, quantities_y)
```

# What does Python bring us?

```
class Physics:
```

```
...
```

```
    prepare_microphysics(physics_state)
```

```
    microph_state = physics_state.microphysics
```

```
    microphysics(microph_state)
```

**GT4Py stencil-based**

```
emulation_model = tf.keras.models.load_model("model.tf")
```

**ML-based microphysics**

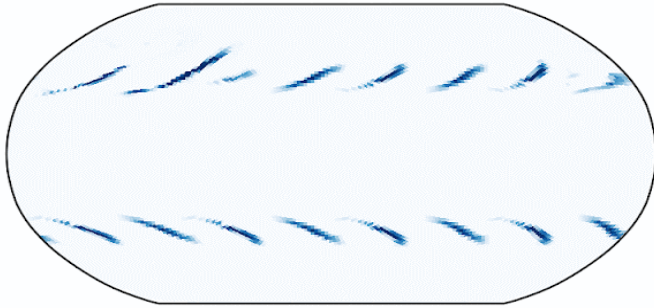
```
emulation_dict = prepare_emulation_data(physics_state.microphysics)
```

```
predictions = emulation_model(emulation_dict)
```

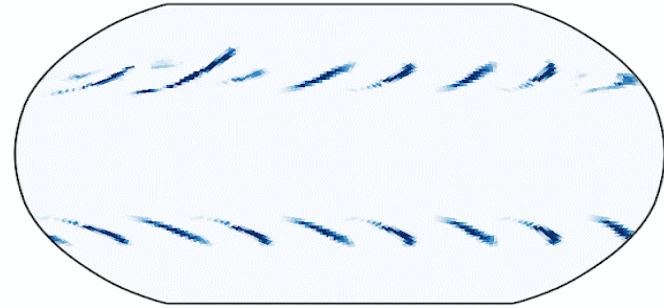
```
model_outputs = unpack_predictions(predictions, emulation_model.output_names, ...)
```

# ML-based Microphysics

Fortran liquid column sum ts=5

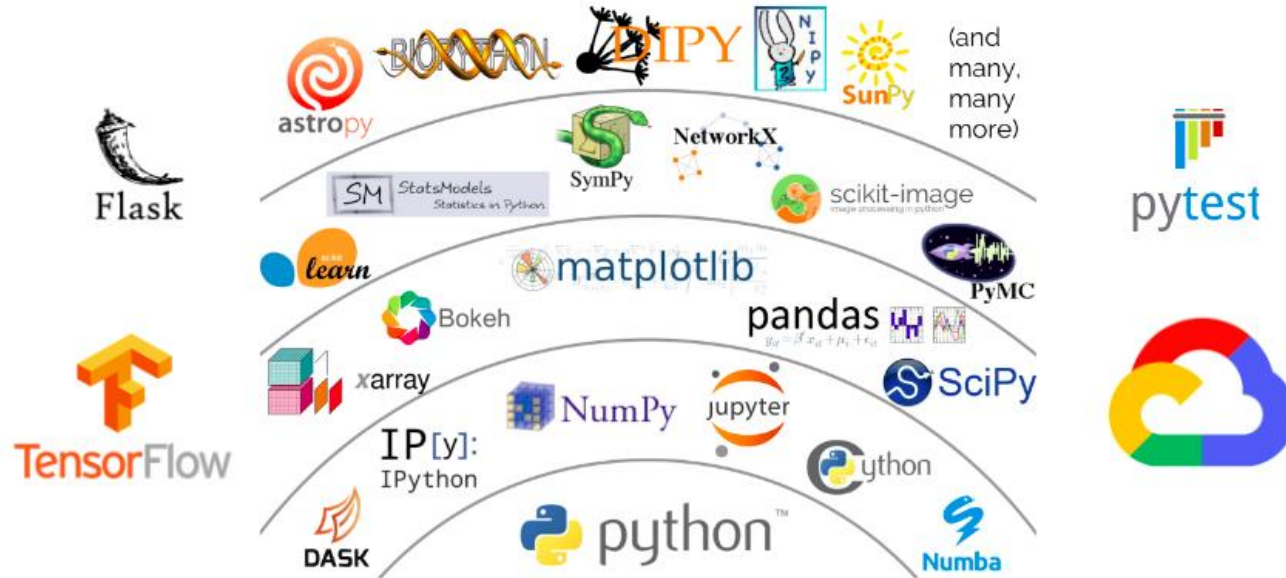


Python mph emulation liquid column sum ts=5



# Why else is Python awesome?

The rich python ecosystem is valuable – new options for development



Credit: Jake VanderPlas, "The Unexpected Effectiveness of Python in Science",  
PyCon 2017

# Why else is Python awesome?

Testing is WAY easier!

```
def test_temporaries_are_deterministic():
    """
    This is a precursor test to the next one, ensuring that two
    identically-initialized dycores called on identically-initialized
    states produce identical temporaries.

    This will fail if there is non-determinism in the initialization,
    for example from using `empty` instead of `zeros` to initialize data.
    """
    dycore1, state1, timer1 = setup_dycore()
    dycore2, state2, timer2 = setup_dycore()

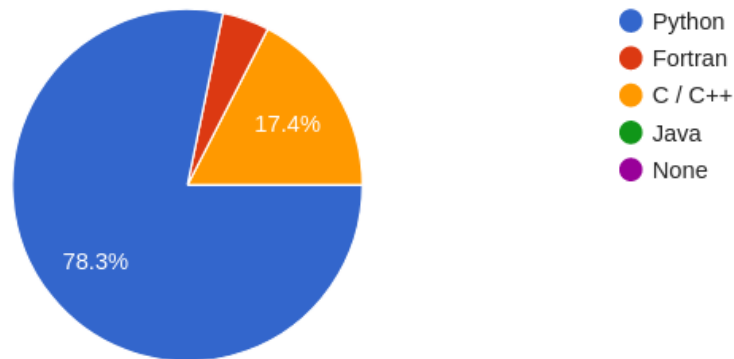
    dycore1.step_dynamics(state1, timer1)
    first_temporaries = copy_temporaries(dycore1, max_depth=10)
    assert len(first_temporaries) > 0
    dycore2.step_dynamics(state2, timer2)
    second_temporaries = copy_temporaries(dycore2, max_depth=10)
    assert_same_temporaries(second_temporaries, first_temporaries)
```

# Why else is Python awesome?

You!

What is the programming language you feel most comfortable in?

23 responses





# Are we seeing what DSLs promise?

## Overarching Goals (The 3 P's)

- **Productivity**  
Easy to implement.  
Easy to **read**.  
Easy to **maintain**.
- **Performance**  
Is **fast**.
- **Portability**  
Single **hardware-agnostic** application code.  
Runs efficiently on **different hardware** targets.

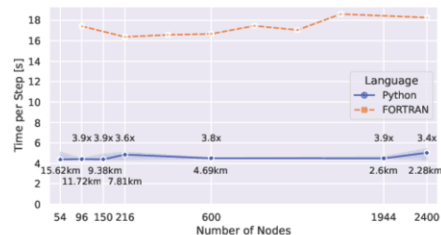
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High-Level Programming 6

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High-Level Programming 13

```
stencil_config:  
  backend: numpy  
  rebuild: false  
  validate_args: true  
  format_source: false  
  device_sync: true  
initialization:  
  type: baroclinic  
performance_config:  
  performance_mode: false  
  experiment_name: c12_baroclinic  
comm_config:  
  type: read  
  config:  
    path: comm  
    rank: 0  
  nx_tile: 12
```