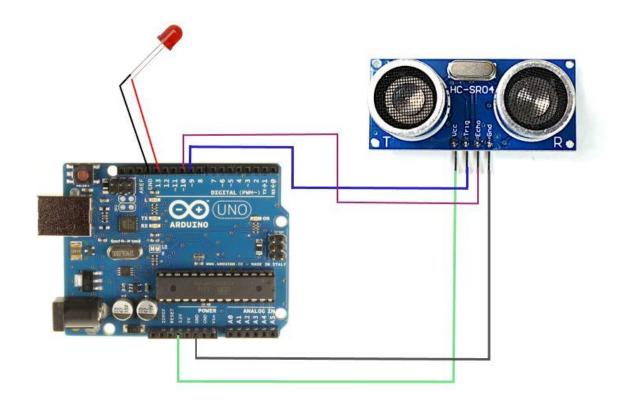
Circuit:



Code:

```
// Define pins
const int trigPin = 9;
const int echoPin = 10;
const int ledPin = 13;

// Define variables
long duration;
int distance;
int blinkInterval;

void setup() {
    // Initialize pins
    pinMode(trigPin, OUTPUT);
    pinMode(echoPin, INPUT);
    pinMode(ledPin, OUTPUT);

    // Serial communication for debugging
    Serial.begin(9600);
}
```

```
void loop() {
 // Send a pulse to the ultrasonic sensor
 digitalWrite(trigPin, LOW);
 delayMicroseconds(2);
 digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 duration = pulseIn(echoPin, HIGH);
 // Calculate distance in centimeters
 distance = duration / 58;
 // Set blink interval based on distance
 if (distance < 10) {</pre>
   blinkInterval = 100;
 } else if (distance < 20) {</pre>
   blinkInterval = 200;
 } else if (distance < 30) {</pre>
   blinkInterval = 300;
 } else {
    blinkInterval = 500;
 // Blink the LED at the appropriate interval
 digitalWrite(ledPin, HIGH);
 delay(blinkInterval);
 digitalWrite(ledPin, LOW);
 delay(blinkInterval);
 // Print distance for debugging
 Serial.print("Distance: ");
 Serial.print(distance);
 Serial.println(" cm");
```

About:

In this project if an object is present in front of the ultrasound sensor the led light will start blinking if the object come towards they sensor the led will blink with less delay