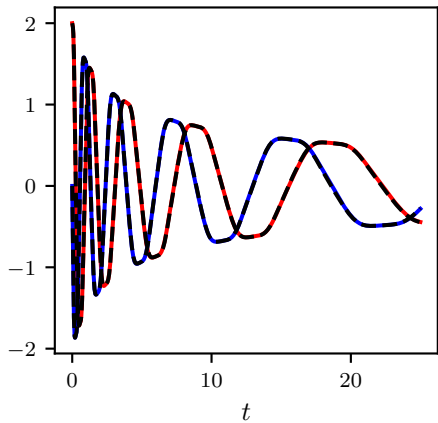
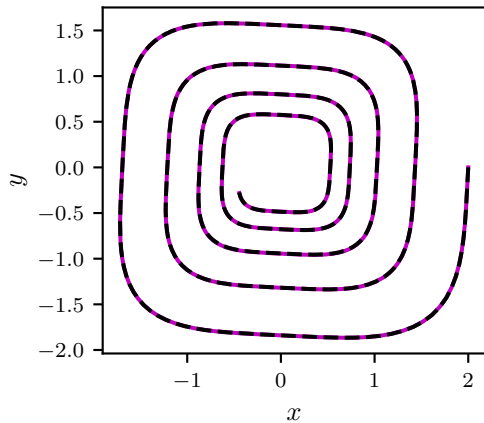


Trajectories



Phase Portrait



— x — y - - - learned model — (x, y)