# Convex optimization exercise sheet

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### Notation

For a linear operator A, its adjoint is  $A^*$  and its Moore-Penrose pseudoinverse is  $A^{\dagger}$ .  $\mathcal{X}$  and  $\mathcal{Y}$  are two Hilbert spaces.

### 1 Convexity

**Exercise 1.1** (Pointwise sup preserves convexity). Let  $(f_i)_I$  be a family of convex functions (not necessarily countable). Show that  $x \mapsto \sup_{i \in I} f_i(x)$  is convex.

**Exercise 1.2** (Precomposition by linear operator preserves convexity). Let  $f: \mathcal{X} \to \mathbb{R}$  be a convex function and  $A: \mathcal{X} \to \mathcal{Y}$  a linear operator. Show that  $f(A\cdot)$  is convex (on  $\mathcal{Y}$ ).

Exercise 1.3 (Misconceptions on existence of minima). Provide an example of convex function which does not admit a minimizer.

What if the function is continuous and lower bounded?

## 2 Least squares

#### 2.1 From a linear algebra perspective

**Exercise 2.1.** Let  $A \in \mathbb{R}^{n \times d}$ . Show that  $\operatorname{Ker} A = \operatorname{Ker} A^*A$ .

**Exercise 2.2.** Show that there always exist a solution to  $A^*Ax = A^*b$ .

Show that this no longer holds in the infinite dimensional space (when A is a bounded linear operator between infinite dimensional Hilbert spaces.)

**Exercise 2.3.** Let  $A \in \mathbb{R}^{n \times d}$ ,  $b \in \mathbb{R}^n$ . Show that solving Ordinary Least Squares:

$$\min \frac{1}{2} ||Ax - b||^2 ,$$

amounts to solving  $A^*Ax = A^*b$  (aka the normal equations).

Show that the set of solutions is:

$$(A^*A)^{\dagger}A^*b + \operatorname{Ker} A$$
.

#### 2.2 Gradient descent on least squares

**Exercise 2.4** (Gradient descent on isotropic parabola). Let  $A \in \mathbb{R}^{n \times d}$  be such that its condition number<sup>1</sup>  $\kappa(A)$  is equal to 1. Show that gradient descent with stepsize 1/L converges in a single iteration for the problem  $\min \frac{1}{2} ||Ax - b||^2$ .

<sup>&</sup>lt;sup>1</sup>i.e. the ratio between the largest and the smallest eigenvalues of  $A^*A$ .

#### 3 Gradient

Exercise 3.1. Provide an example of setting where the gradient is not equal to the vector of partial derivatives.

**Exercise 3.2.** Let  $f: \mathcal{X} \to \mathbb{R}$  and  $\theta: \mathbb{R}_+ \to \mathcal{X}$  be differentiable. Show that

$$\frac{d}{dt}f(\theta(t)) = \langle \nabla f(\theta(t)), \dot{\theta}(t) \rangle .$$

Exercise 3.3. Show that the gradient of a function is orthogonal to the level lines of that function.

**Exercise 3.4.** Let  $A \in \mathbb{R}^{n \times d}$ ,  $f : \mathbb{R}^n \to \mathbb{R}$  and  $g : \mathbb{R}^d \to \mathbb{R}$  defined as g(x) = f(Ax) for all  $x \in \mathbb{R}^d$ . Show that

$$\nabla g(x) = A^* \nabla f(Ax) ,$$
  
$$\nabla^2 g(x) = A^* \nabla^2 f(Ax) A .$$

**Exercise 3.5** (Polyak-Lojasiewicz inequality). Let f be a  $\mu$ -strongly-convex and differentiable function. Let  $x^* = \operatorname{argmin} f(x)$ . Show that f satisfies the Polyak-Lojasiewicz inequality:

$$\mu(f(x) - f(x^*)) \le \frac{1}{2} \|\nabla f(x)\|^2 . \tag{1}$$

Provide an example of function which is not strongly convex, but satisfies the inequality.

**Exercise 3.6.** Provide an example of matrix  $A \in \mathbb{R}^{n \times d}$  such that the gradient of  $x \mapsto \frac{1}{2}x^{\top}Ax$  is not equal to Ax.

### 4 Convexity inequalities

**Exercise 4.1.** Let f be a convex and Gateaux-differentiable function. Let L > 0. Show that the following properties are equivalent:

- 1.  $\forall x, y, \|\nabla f(x) \nabla f(y)\| \le L\|x y\|$
- 2.  $\forall x, y, f(x) \le f(y) + \langle \nabla f(y), x y \rangle + \frac{L}{2} ||x y||^2$
- 3.  $\forall x, y, \frac{1}{L} \|\nabla f(x) \nabla f(y)\| \le \langle x y, \nabla f(x) \nabla f(y) \rangle$

Note: 2 is known as the descent lemma; 3 is known as the Baillon-Haddad theorem, or cocoercivity of the gradient.

**Exercise 4.2.** Let f be a L-smooth  $\mu$ -strongly convex function. Show that for any x, y, y

$$\frac{\mu L}{\mu + L} \|x - y\|^2 + \frac{1}{L + \mu} \|\nabla f(x) - \nabla f(y)\|^2 \le \langle x - y, \nabla f(x) - \nabla f(y) \rangle.$$

## 5 Around fixed point schemes

**Exercise 5.1.** Let  $T: \mathcal{X} \to \mathcal{X}$  be a linear operator which is q-contractive, meaning that for all  $x \in \mathcal{X}$ ,

$$||Tx|| \leq q||x||$$
.

Show that T admits at most one fixed point.

Show that the sequence defined by  $x_0 \in \mathcal{X}$ ,  $x_{k+1} = Tx_k$  converges, and that the limit is a fixed point. Show that, denoting  $x^*$  this fixed point, the sequence  $x_k$  converges to  $x^*$  at linear speed.

**Exercise 5.2.** Show that the results of the above exercise do not hold when q = 1.

## 6 Constrained optimization

**Exercise 6.1.** Show that the indicator function  $\iota_C$  is convex (resp. lower semicontinuous, resp. proper) if C is convex (resp. closer, resp. nonempty).

**Exercise 6.2** (Global optimality condition for constrained convex optimisation). Let  $f: \mathbb{R}^d \to \mathbb{R}$  be a convex differentiable function, let C be a convex subset of  $\mathbb{R}^d$ . Show that  $x^* \in \operatorname{argmin}_{x \in C} f(x)$  if and only if

$$\forall x \in \mathbb{R}^d, \langle \nabla f(x^*), x - x^* \rangle \ge 0$$
.